

## ADC344x Quad-Channel, 14-Bit, 25-MSPS to 125-MSPS, Analog-to-Digital Converters

### 1 Features

- Quad Channel
- 14-Bit Resolution
- Single Supply: 1.8 V
- Serial LVDS Interface
- Flexible Input Clock Buffer With Divide-by-1, -2, -4
- SNR = 72.4 dBFS, SFDR = 87 dBc at  $f_{IN} = 70$  MHz
- Ultra-Low Power Consumption:
  - 98 mW/Ch at 125 MSPS
- Channel Isolation: 105 dB
- Internal Dither and Chopper
- Support for Multi-Chip Synchronization
- Pin-to-Pin Compatible With 12-Bit Version
- Package: VQFN-56 (8 mm × 8 mm)

### 2 Applications

- Multi-Carrier, Multi-Mode Cellular Base Stations
- Radar and Smart Antenna Arrays
- Munitions Guidance
- Motor Control Feedback
- Network and Vector Analyzers
- Communications Test Equipment
- Nondestructive Testing
- Microwave Receivers
- Software-Defined Radios (SDRs)
- Quadrature and Diversity Radio Receivers

### 3 Description

The ADC344x devices are a high-linearity, ultra-low power, quad-channel, 14-bit, 25-MSPS to 125-MSPS, analog-to-digital converter (ADC) family. The devices are designed specifically to support demanding, high input frequency signals with large dynamic range requirements. An input clock divider allows more flexibility for system clock architecture design while the SYSREF input enables complete system synchronization.

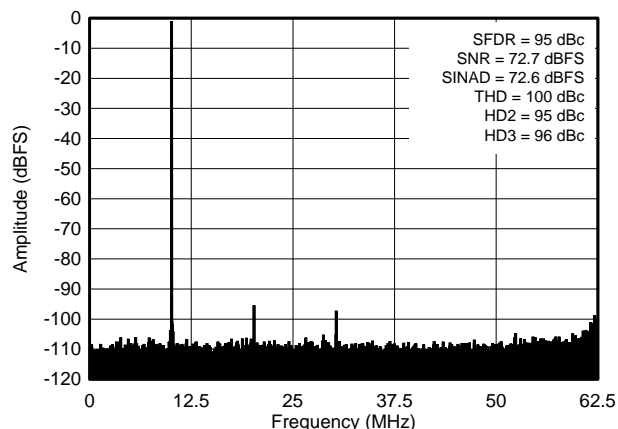
The ADC344x family supports serial low-voltage differential signaling (LVDS) to reduce the number of interface lines, thus allowing for high system integration density. The serial LVDS interface is two-wire, where each ADC data are serialized and output over two LVDS pairs. Optionally, a one-wire serial LVDS interface is available. An internal phase-locked loop (PLL) multiplies the incoming ADC sampling clock to derive the bit clock that is used to serialize the 14-bit output data from each channel. In addition to the serial data streams, the frame and bit clocks are transmitted as LVDS outputs.

#### Device Information

PART NUMBER	PACKAGE	BODY SIZE (NOM)
ADC344x	VQFN (56)	8.00 mm × 8.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Spectrum at 10 MHz



## Table of Contents

<b>1</b>	<b>Features</b> .....	<b>1</b>	7.20	Typical Characteristics: Contour .....	<b>44</b>
<b>2</b>	<b>Applications</b> .....	<b>1</b>	<b>8</b>	<b>Parameter Measurement Information</b> .....	<b>44</b>
<b>3</b>	<b>Description</b> .....	<b>1</b>	8.1	Timing Diagrams .....	<b>44</b>
<b>4</b>	<b>Revision History</b> .....	<b>2</b>	<b>9</b>	<b>Detailed Description</b> .....	<b>47</b>
<b>5</b>	<b>Device Comparison Table</b> .....	<b>4</b>	9.1	Overview .....	<b>47</b>
<b>6</b>	<b>Pin Configuration and Functions</b> .....	<b>4</b>	9.2	Functional Block Diagram .....	<b>47</b>
<b>7</b>	<b>Specifications</b> .....	<b>6</b>	9.3	Feature Description .....	<b>48</b>
7.1	Absolute Maximum Ratings .....	<b>6</b>	9.4	Device Functional Modes .....	<b>53</b>
7.2	ESD Ratings .....	<b>6</b>	9.5	Programming .....	<b>54</b>
7.3	Recommended Operating Conditions .....	<b>6</b>	9.6	Register Maps .....	<b>59</b>
7.4	Thermal Information .....	<b>7</b>	<b>10</b>	<b>Applications and Implementation</b> .....	<b>74</b>
7.5	Electrical Characteristics: General .....	<b>7</b>	10.1	Application Information .....	<b>74</b>
7.6	Electrical Characteristics: ADC3441, ADC3442 .....	<b>8</b>	10.2	Typical Applications .....	<b>75</b>
7.7	Electrical Characteristics: ADC3443, ADC3444 .....	<b>8</b>	<b>11</b>	<b>Power Supply Recommendations</b> .....	<b>77</b>
7.8	AC Performance: ADC3441 .....	<b>9</b>	<b>12</b>	<b>Layout</b> .....	<b>78</b>
7.9	AC Performance: ADC3442 .....	<b>11</b>	12.1	Layout Guidelines .....	<b>78</b>
7.10	AC Performance: ADC3443 .....	<b>13</b>	12.2	Layout Example .....	<b>78</b>
7.11	AC Performance: ADC3444 .....	<b>15</b>	<b>13</b>	<b>Device and Documentation Support</b> .....	<b>79</b>
7.12	Digital Characteristics .....	<b>17</b>	13.1	Related Links .....	<b>79</b>
7.13	Timing Requirements: General .....	<b>17</b>	13.2	Receiving Notification of Documentation Updates .....	<b>79</b>
7.14	Timing Requirements: LVDS Output .....	<b>18</b>	13.3	Community Resources .....	<b>79</b>
7.15	Typical Characteristics: ADC3441 .....	<b>19</b>	13.4	Trademarks .....	<b>79</b>
7.16	Typical Characteristics: ADC3442 .....	<b>25</b>	13.5	Electrostatic Discharge Caution .....	<b>79</b>
7.17	Typical Characteristics: ADC3443 .....	<b>31</b>	13.6	Glossary .....	<b>79</b>
7.18	Typical Characteristics: ADC3444 .....	<b>37</b>	<b>14</b>	<b>Mechanical, Packaging, and Orderable Information</b> .....	<b>79</b>
7.19	Typical Characteristics: Common .....	<b>43</b>			

## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision A (October 2015) to Revision B	Page
• Added description for availability of one-wire serial LVDS interface in <i>Description</i> section .....	<b>1</b>
• Changed <i>Spectrum at 10 MHz</i> figure to show conditions within curve .....	<b>1</b>
• Changed description of AVDD, DVDD, and GND pins and added <i>active high</i> to description of PDN pin in <i>Pin Functions</i> table .....	<b>5</b>
• Deleted <i>maximum</i> from parameter description in <i>Recommended Operating Conditions</i> table .....	<b>6</b>
• Changed Digital Outputs, $R_{LOAD}$ parameter description in <i>Recommended Operating Conditions</i> table .....	<b>6</b>
• Changed conditions of all <i>Electrical Characteristics</i> and <i>AC Performance</i> tables .....	<b>7</b>
• Added minimum and maximum specifications to Analog Input, $V_{OC(VCM)}$ parameter in <i>Electrical Characteristics: General</i> table .....	<b>7</b>
• Changed description of Analog Input, <i>Analog input bandwidth</i> parameter in <i>Electrical Characteristics: General</i> table .....	<b>7</b>
• Deleted footnote 1 from <i>Electrical Characteristics: General</i> table .....	<b>7</b>
• Added DC Accuracy, $E_G$ parameter with its test conditions and footnote 3 to <i>Electrical Characteristics: General</i> table .....	<b>7</b>
• Deleted $E_{G(REF)}$ and $E_{G(CHAN)}$ from DC Accuracy in <i>Electrical Characteristics: General</i> table .....	<b>7</b>
• Changed DC Accuracy, $\alpha_{(EGCHAN)}$ to $\alpha_{EG}$ and updated its parameter in <i>Electrical Characteristics: General</i> table .....	<b>7</b>
• Changed Channel-to-Channel Isolation, <i>Crosstalk</i> parameter in <i>Electrical Characteristics: General</i> table: changed test conditions, added footnote 2 .....	<b>7</b>
• Changed test conditions for IMD3 parameter in <i>AC Performance: ADC3441</i> table .....	<b>10</b>
• Added INL and DNL rows to all <i>AC Performance</i> tables .....	<b>10</b>
• Changed <i>Digital Inputs (SYSREFP, SYSREFM)</i> subsection in <i>Digital Characteristics</i> table, added footnote 2 .....	<b>17</b>

**Revision History (continued)**

• Changed specifications of Digital Outputs (LVDS Interface), $V_{OCM}$ parameter in <i>Digital Characteristics</i> table.....	17
• Changed <i>rising</i> to <i>falling</i> in description of <i>SYSREF reference time</i> parameter in <i>Timing Requirements: General</i> table ...	17
• Changed <i>Typical Characteristics</i> sections: added <i>dither on</i> to all section condition statements, changed <i>Non 23</i> to <i>excluding HD2, HD3</i> .....	19
• Added INL and DNL plots in <a href="#">Typical Characteristics: ADC3441</a> section .....	24
• Changed conditions of <a href="#">Figure 34</a> , <a href="#">Figure 35</a> .....	25
• Added INL and DNL plots in <a href="#">Typical Characteristics: ADC3442</a> section .....	30
• Changed conditions of <a href="#">Figure 67</a> , <a href="#">Figure 68</a> .....	31
• Added INL and DNL plots in <a href="#">Typical Characteristics: ADC3443</a> section .....	36
• Changed conditions of <a href="#">Figure 100</a> , <a href="#">Figure 101</a> .....	37
• Added INL and DNL plots in <a href="#">Typical Characteristics: ADC3444</a> section. ....	42
• Changed conditions of <a href="#">Figure 134</a> .....	43
• Added <a href="#">Figure 141</a> to <i>Timing Diagrams</i> section .....	44
• Added <i>Using the SYSREF Input</i> section .....	50
• Changed the description about synchronization of the phase of the divided clock in each device to the common sampling clock in <a href="#">Using the SYSREF Input</a> section. ....	50
• Added <i>ADC3441 Power-Up Requirements</i> section, deleted the <i>Register Initialization</i> section.....	57
• Added last sentence to <i>Detailed Design Procedure</i> section of first typical application.....	75
• Added <i>Chopper On</i> to caption of <a href="#">Figure 198</a> .....	75
• Added <i>Chopper Off</i> to caption of <a href="#">Figure 200</a> .....	76
• Changed the caption of <a href="#">Figure 202</a> from <i>FFT for 450-MHz Input Signal (Dither On)</i> to <i>FFT for 450-MHz Input Signal (Chopper Off, Dither On)</i> .....	77

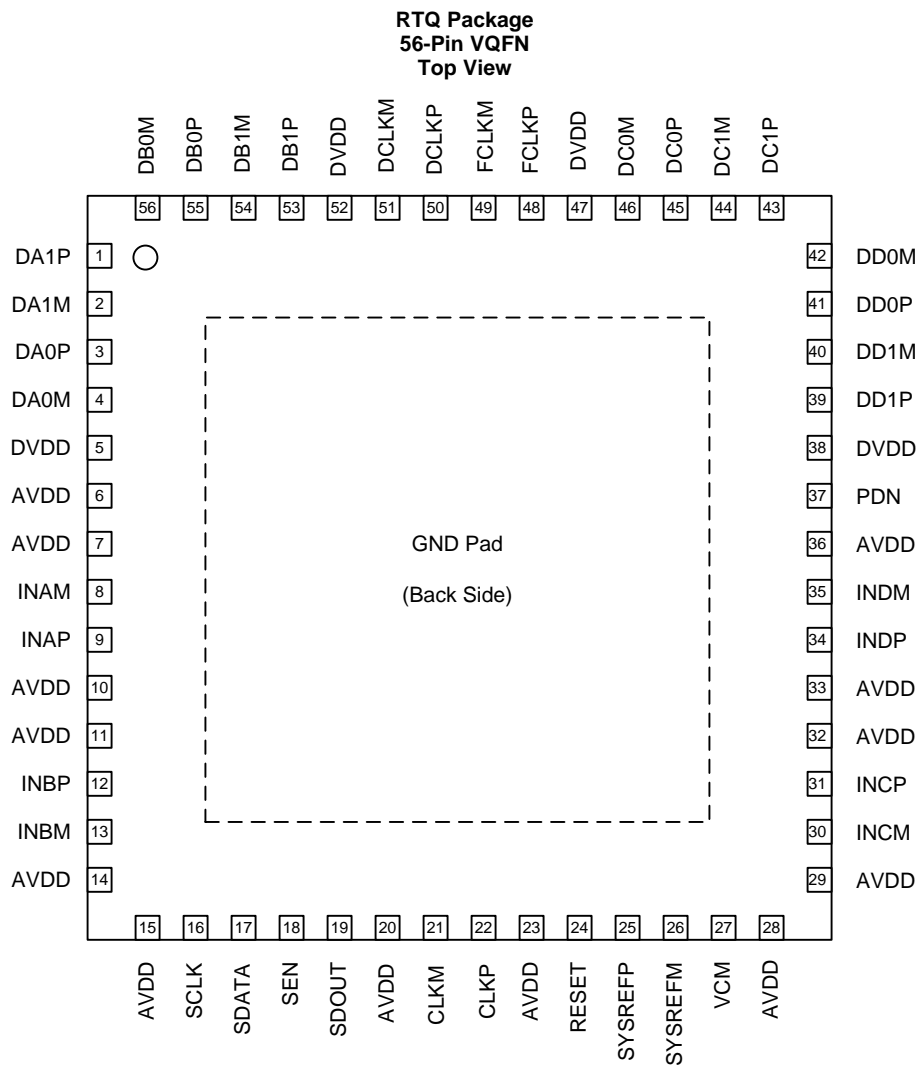
**Changes from Original (July 2014) to Revision A**
**Page**

• Released to production.....	1
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## 5 Device Comparison Table

INTERFACE	RESOLUTION (Bits)	25 MSPS	50 MSPS	80 MSPS	125 MSPS	160 MSPS
Serial LVDS	12	<a href="#">ADC3421</a>	<a href="#">ADC3422</a>	<a href="#">ADC3423</a>	<a href="#">ADC3424</a>	—
	14	<a href="#">ADC3441</a>	<a href="#">ADC3442</a>	<a href="#">ADC3443</a>	<a href="#">ADC3444</a>	—
JESD204B	12	—	<a href="#">ADC34J22</a>	<a href="#">ADC34J23</a>	<a href="#">ADC34J24</a>	<a href="#">ADC34J25</a>
	14	—	<a href="#">ADC34J42</a>	<a href="#">ADC34J43</a>	<a href="#">ADC34J44</a>	<a href="#">ADC34J45</a>

## 6 Pin Configuration and Functions



### Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
AVDD	6, 7, 10, 11, 14, 15, 20, 23, 28, 29, 32, 33, 36	I	Analog 1.8-V power supply, decoupled with capacitors
CLKM	21	I	Negative differential clock input for the ADC
CLKP	22	I	Positive differential clock input for the ADC
DA0M	4	O	Negative serial LVDS output for wire-0 of channel A
DA0P	3	O	Positive serial LVDS output for wire-0 of channel A
DA1M	2	O	Negative serial LVDS output for wire-1 of channel A
DA1P	1	O	Positive serial LVDS output for wire-1 of channel A
DB0M	56	O	Negative serial LVDS output for wire-0 of channel B
DB0P	55	O	Positive serial LVDS output for wire-0 of channel B
DB1M	54	O	Negative serial LVDS output for wire-1 of channel B
DB1P	53	O	Positive serial LVDS output for wire-1 of channel B
DC0M	46	O	Negative serial LVDS output for wire-0 of channel C
DC0P	45	O	Positive serial LVDS output for wire-0 of channel C
DC1M	44	O	Negative serial LVDS output for wire-1 of channel C
DC1P	43	O	Positive serial LVDS output for wire-1 of channel C
DD0M	42	O	Negative serial LVDS output for wire-0 of channel D
DD0P	41	O	Positive serial LVDS output for wire-0 of channel D
DD1M	40	O	Negative serial LVDS output for wire-1 of channel D
DD1P	39	O	Positive serial LVDS output for wire-1 of channel D
DCLKM	51	O	Negative bit clock output
DCLKP	50	O	Positive bit clock output
DVDD	5, 38, 47, 52	I	Digital 1.8-V power supply, decoupled with capacitors
FCLKM	49	O	Negative frame clock output
FCLKP	48	O	Positive frame clock output
GND	PowerPAD™	I	Ground, 0 V. Connect to the printed circuit board (PCB) ground plane.
INAM	8	I	Negative differential analog input for channel A
INAP	9	I	Positive differential analog input for channel A
INBM	13	I	Negative differential analog input for channel B
INBP	12	I	Positive differential analog input for channel B
INCM	30	I	Negative differential analog input for channel C
INCP	31	I	Positive differential analog input for channel C
INDM	35	I	Negative differential analog input for channel D
INDP	34	I	Positive differential analog input for channel D
PDN	37	I	Power-down control; active high. This pin may be configured through the SPI. This pin has an internal 150-kΩ pulldown resistor.
RESET	24	I	Hardware reset; active high. This pin has an internal 150-kΩ pulldown resistor.
SCLK	16	I	Serial interface clock input. This pin has an internal 150-kΩ pulldown resistor.
SDATA	17	I	Serial interface data input. This pin has an internal 150-kΩ pulldown resistor.
SDOUT	19	O	Serial interface data output
SEN	18	I	Serial interface enable; active low. This pin has an internal 150-kΩ pullup resistor to AVDD.
SYSREFM	26	I	Negative external SYSREF input
SYSREFP	25	I	Positive external SYSREF input
VCM	27	O	Common-mode voltage for analog inputs

## 7 Specifications

### 7.1 Absolute Maximum Ratings

 over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
Analog supply voltage range, AVDD		-0.3	2.1	V
Digital supply voltage range, DVDD		-0.3	2.1	V
Voltage applied to input pins	INAP, INBP, INAM, INBM	-0.3	min (1.9, AVDD + 0.3)	V
	CLKP, CLKM	-0.3	AVDD + 0.3	
	SYSREFP, SYSREFM	-0.3	AVDD + 0.3	
	SCLK, SEN, SDATA, RESET, PDN	-0.3	3.9	
Temperature	Operating free-air, T <sub>A</sub>	-40	85	°C
	Operating junction, T <sub>J</sub>		125	
	Storage, T <sub>stg</sub>	-65	150	

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 7.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

 over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	NOM	MAX	UNIT
<b>SUPPLIES</b>					
AVDD	Analog supply voltage range	1.7	1.8	1.9	V
DVDD	Digital supply voltage range	1.7	1.8	1.9	V
<b>ANALOG INPUT</b>					
V <sub>ID</sub>	Differential input voltage	For input frequencies < 450 MHz		2	V <sub>PP</sub>
		For input frequencies < 600 MHz		1	
V <sub>IC</sub>	Input common-mode voltage	VCM ± 0.025			V
<b>CLOCK INPUT</b>					
	Input clock frequency	Sampling clock frequency	15 <sup>(2)</sup>	125 <sup>(3)</sup>	MSPS
	Input clock amplitude (differential)	Sine wave, ac-coupled	0.2	1.5	V <sub>PP</sub>
		LPECL, ac-coupled		1.6	
		LVDS, ac-coupled		0.7	
	Input clock duty cycle	35%	50%	65%	
	Input clock common-mode voltage	0.95			V
<b>DIGITAL OUTPUTS</b>					
C <sub>LOAD</sub>	External load capacitance from each output pin to GND	3.3			pF
R <sub>LOAD</sub>	Differential load resistance to be placed across the positive and negative pins of the LVDS output pair	100			Ω

- (1) After power-up, only use the RESET pin to reset the device for the first time; see the [Register Initialization](#) section for details.  
 (2) See [Table 3](#) for details.  
 (3) With the clock divider enabled by default for divide-by-1. Maximum sampling clock frequency for the divide-by-4 option is 500 MSPS.

## 7.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		ADC344x	
		RTQ (VQFN)	
		56 PINS	
Symbol	Description	Value	Unit
$R_{\theta JA}$	Junction-to-ambient thermal resistance	25.3	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	9.5	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	3.4	°C/W
$\psi_{JT}$	Junction-to-top characterization parameter	0.2	°C/W
$\psi_{JB}$	Junction-to-board characterization parameter	3.3	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	0.5	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 7.5 Electrical Characteristics: General

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>ANALOG INPUT</b>					
	Differential input full-scale		2.0		$V_{PP}$
$r_i$	Input resistance	Differential at dc	6.6		k $\Omega$
$c_i$	Input capacitance	Differential at dc	3.7		pF
$V_{OC(VCM)}$	VCM common-mode voltage output	0.8	0.95	1.1	V
	VCM output current capability		10		mA
	Input common-mode current	Per analog input pin	1.5		$\mu$ A/MSPS
	Analog input bandwidth (–3-dB point)	50- $\Omega$ differential source driving 50- $\Omega$ termination across INP and INM	540		MHz
<b>DC ACCURACY</b>					
$E_O$	Offset error		–25	25	mV
$\alpha_{EO}$	Temperature coefficient of offset error		$\pm 0.024$		mV/°C
$E_G$	Overall dc gain error of a channel	ADC3441	–2	2	%FS
		ADC3442, ADC3443, ADC3444	–2.5	2.5	
$\alpha_{EG}$	Temperature coefficient of overall gain error		0.005		$\Delta$ %FS/°C
<b>CHANNEL-TO-CHANNEL ISOLATION</b>					
Crosstalk <sup>(1)(2)</sup>	$f_{IN} = 10$ MHz	Between near channels	105		dB
		Between far channels	105		
	$f_{IN} = 100$ MHz	Between near channels	95		
		Between far channels	105		
	$f_{IN} = 200$ MHz	Between near channels	94		
		Between far channels	105		
	$f_{IN} = 230$ MHz	Between near channels	92		
		Between far channels	105		
	$f_{IN} = 300$ MHz	Between near channels	85		
		Between far channels	105		

(1) Crosstalk is measured with a –1-dBFS input signal on the aggressor channel and no input on the victim channel.

(2) Channels A and B are near to each other but far from channels C and D. Similarly, channels C and D are near to each other but far from channels A and B; see the [Pin Configuration and Functions](#) section for more information.

## 7.6 Electrical Characteristics: ADC3441, ADC3442

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER	ADC3441			ADC3442			UNIT
	MIN	TYP	MAX	MIN	TYP	MAX	
ADC clock frequency			25			50	MSPS
Resolution	14			14			Bits
1.8-V analog supply current		54	74		71	97	mA
1.8-V digital supply current		45	67		56	83	mA
Total power dissipation		177	215		228	277	mW
Global power-down dissipation		5	17		5	17	mW
Standby power-down dissipation		34	103		35	103	mW

## 7.7 Electrical Characteristics: ADC3443, ADC3444

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER	ADC3443			ADC3444			UNIT
	MIN	TYP	MAX	MIN	TYP	MAX	
ADC clock frequency			80			125	MSPS
Resolution	14			14			Bits
1.8-V analog supply current		92	125		119	162	mA
1.8-V digital supply current		68	101		98	145	mA
Total power dissipation		288	350		391	475	mW
Global power-down dissipation		5	17		5	17	mW
Standby power-down dissipation		40	103		43	103	mW



## 7.8 AC Performance: ADC3441

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER		TEST CONDITIONS	ADC3441 (f <sub>S</sub> = 25 MSPS)						UNIT
			DITHER ON			DITHER OFF			
			MIN	TYP	MAX	MIN	TYP	MAX	
SNR	Signal-to-noise ratio (from 1-MHz offset)	f <sub>IN</sub> = 10 MHz	73.1			73.5			dBFS
		f <sub>IN</sub> = 20 MHz	70.9	72.9		73.4			
		f <sub>IN</sub> = 70 MHz	72.5			73			
		f <sub>IN</sub> = 100 MHz	72.4			72.7			
		f <sub>IN</sub> = 170 MHz	71.4			71.7			
		f <sub>IN</sub> = 230 MHz	70.3			70.5			
	Signal-to-noise ratio (full Nyquist band)	f <sub>IN</sub> = 10 MHz	72.4			72.9			
		f <sub>IN</sub> = 20 MHz	72.2			72.7			
		f <sub>IN</sub> = 70 MHz	71.9			72.4			
		f <sub>IN</sub> = 100 MHz	71.7			72.0			
		f <sub>IN</sub> = 170 MHz	70.9			71.1			
		f <sub>IN</sub> = 230 MHz	69.7			69.9			
NSD <sup>(1)</sup>	Noise spectral density (averaged across Nyquist zone)	f <sub>IN</sub> = 10 MHz	–143.7			–144.1			dBFS/Hz
		f <sub>IN</sub> = 20 MHz	–143.5	–141.5		–143.9			
		f <sub>IN</sub> = 70 MHz	–143.1			–143.6			
		f <sub>IN</sub> = 100 MHz	–143.0			–143.3			
		f <sub>IN</sub> = 170 MHz	–142.0			–142.3			
		f <sub>IN</sub> = 230 MHz	–140.9			–141.1			
SINAD <sup>(1)</sup>	Signal-to-noise and distortion ratio	f <sub>IN</sub> = 10 MHz	73.1			73.4			dBFS
		f <sub>IN</sub> = 20 MHz	69.9	72.9		73.2			
		f <sub>IN</sub> = 70 MHz	71.7			71.9			
		f <sub>IN</sub> = 100 MHz	72.6			72.8			
		f <sub>IN</sub> = 170 MHz	71.2			71.4			
		f <sub>IN</sub> = 230 MHz	69.9			70.1			
ENOB <sup>(1)</sup>	Effective number of bits	f <sub>IN</sub> = 10 MHz	11.9			11.9			Bits
		f <sub>IN</sub> = 20 MHz	11.3	11.8		11.8			
		f <sub>IN</sub> = 70 MHz	11.7			11.8			
		f <sub>IN</sub> = 100 MHz	11.8			11.8			
		f <sub>IN</sub> = 170 MHz	11.5			11.6			
		f <sub>IN</sub> = 230 MHz	11.3			11.4			
SFDR	Spurious-free dynamic range	f <sub>IN</sub> = 10 MHz	91			89			dBc
		f <sub>IN</sub> = 20 MHz	82	91		85			
		f <sub>IN</sub> = 70 MHz	92			87			
		f <sub>IN</sub> = 100 MHz	85			82			
		f <sub>IN</sub> = 170 MHz	86			85			
		f <sub>IN</sub> = 230 MHz	81			81			

(1) Reported from a 1-MHz offset.

**AC Performance: ADC3441 (continued)**

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER	TEST CONDITIONS	ADC3441 (f <sub>S</sub> = 25 MSPS)						UNIT
		DITHER ON			DITHER OFF			
		MIN	TYP	MAX	MIN	TYP	MAX	
HD2	Second-order harmonic distortion	f <sub>IN</sub> = 10 MHz		92		93		dBc
		f <sub>IN</sub> = 20 MHz	82	92		91		
		f <sub>IN</sub> = 70 MHz		92		91		
		f <sub>IN</sub> = 100 MHz		96		94		
		f <sub>IN</sub> = 170 MHz		86		85		
		f <sub>IN</sub> = 230 MHz		84		84		
HD3	Third-order harmonic distortion	f <sub>IN</sub> = 10 MHz		96		90		dBc
		f <sub>IN</sub> = 20 MHz	82	93		89		
		f <sub>IN</sub> = 70 MHz		93		88		
		f <sub>IN</sub> = 100 MHz		85		82		
		f <sub>IN</sub> = 170 MHz		89		89		
		f <sub>IN</sub> = 230 MHz		82		82		
Non HD2, HD3	Spurious-free dynamic range (excluding HD2, HD3)	f <sub>IN</sub> = 10 MHz		100		93		dBc
		f <sub>IN</sub> = 20 MHz	87	97		92		
		f <sub>IN</sub> = 70 MHz		97		92		
		f <sub>IN</sub> = 100 MHz		97		94		
		f <sub>IN</sub> = 170 MHz		92		90		
		f <sub>IN</sub> = 230 MHz		98		92		
THD	Total harmonic distortion	f <sub>IN</sub> = 10 MHz		90		86		dBc
		f <sub>IN</sub> = 20 MHz	79	90		85		
		f <sub>IN</sub> = 70 MHz		90		85		
		f <sub>IN</sub> = 100 MHz		84		80		
		f <sub>IN</sub> = 170 MHz		84		83		
		f <sub>IN</sub> = 230 MHz		80		80		
IMD3	Two-tone, third-order intermodulation distortion	f <sub>IN1</sub> = 45 MHz, f <sub>IN2</sub> = 50 MHz, each tone at –7 dBFS		–97		–97		dBFS
		f <sub>IN1</sub> = 185 MHz, f <sub>IN2</sub> = 190 MHz, each tone at –7 dBFS		–88		–88		
INL	Integral nonlinearity	f <sub>IN</sub> = 20 MHz		±0.75	±3	±0.75		LSBs
DNL	Differential nonlinearity	f <sub>IN</sub> = 20 MHz	–0.95	±0.6		±0.6		LSBs

## 7.9 AC Performance: ADC3442

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER		TEST CONDITIONS	ADC3442 (f <sub>S</sub> = 50 MSPS)						UNIT
			DITHER ON			DITHER OFF			
			MIN	TYP	MAX	MIN	TYP	MAX	
SNR	Signal-to-noise ratio (from 1-MHz offset)	f <sub>IN</sub> = 10 MHz	73.1			73.5			dBFS
		f <sub>IN</sub> = 20 MHz	70.7	72.9		73.3			
		f <sub>IN</sub> = 70 MHz	72.7			73.1			
		f <sub>IN</sub> = 100 MHz	71.9			72.6			
		f <sub>IN</sub> = 170 MHz	71.5			71.8			
		f <sub>IN</sub> = 230 MHz	70.4			70.8			
	Signal-to-noise ratio (full Nyquist band)	f <sub>IN</sub> = 10 MHz	72.5			72.9			
		f <sub>IN</sub> = 20 MHz	72.3			72.7			
		f <sub>IN</sub> = 70 MHz	71.9			72.3			
		f <sub>IN</sub> = 100 MHz	71.3			72.1			
		f <sub>IN</sub> = 170 MHz	71.0			71.2			
		f <sub>IN</sub> = 230 MHz	69.8			70.2			
NSD <sup>(1)</sup>	Noise spectral density (averaged across Nyquist zone)	f <sub>IN</sub> = 10 MHz	–146.9			–147.3			dBFS/Hz
		f <sub>IN</sub> = 20 MHz	–146.7	–144.5		–146.9			
		f <sub>IN</sub> = 70 MHz	–146.5			–146.9			
		f <sub>IN</sub> = 100 MHz	–145.7			–146.4			
		f <sub>IN</sub> = 170 MHz	–145.3			–145.6			
		f <sub>IN</sub> = 230 MHz	–144.2			–144.6			
SINAD <sup>(1)</sup>	Signal-to-noise and distortion ratio	f <sub>IN</sub> = 10 MHz	73			73.4			dBFS
		f <sub>IN</sub> = 20 MHz	69.7	72.2		72.7			
		f <sub>IN</sub> = 70 MHz	72.2			72.7			
		f <sub>IN</sub> = 100 MHz	72.1			73.2			
		f <sub>IN</sub> = 170 MHz	71.4			71.8			
		f <sub>IN</sub> = 230 MHz	69.8			70.1			
ENOB <sup>(1)</sup>	Effective number of bits	f <sub>IN</sub> = 10 MHz	11.9			11.9			Bits
		f <sub>IN</sub> = 20 MHz	11.3	11.8		11.8			
		f <sub>IN</sub> = 70 MHz	11.8			11.8			
		f <sub>IN</sub> = 100 MHz	11.7			11.9			
		f <sub>IN</sub> = 170 MHz	11.6			11.6			
		f <sub>IN</sub> = 230 MHz	11.4			11.4			
SFDR	Spurious-free dynamic range	f <sub>IN</sub> = 10 MHz	90			90			dBc
		f <sub>IN</sub> = 20 MHz	82	92		90			
		f <sub>IN</sub> = 70 MHz	92			90			
		f <sub>IN</sub> = 100 MHz	87			87			
		f <sub>IN</sub> = 170 MHz	86			84			
		f <sub>IN</sub> = 230 MHz	83			82			

(1) Reported from a 1-MHz offset.

**AC Performance: ADC3442 (continued)**

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER	TEST CONDITIONS	ADC3442 (f <sub>S</sub> = 50 MSPS)						UNIT
		DITHER ON			DITHER OFF			
		MIN	TYP	MAX	MIN	TYP	MAX	
HD2	Second-order harmonic distortion	f <sub>IN</sub> = 10 MHz		95		92		dBc
		f <sub>IN</sub> = 20 MHz	83	99		94		
		f <sub>IN</sub> = 70 MHz		93		91		
		f <sub>IN</sub> = 100 MHz		92		92		
		f <sub>IN</sub> = 170 MHz		87		85		
		f <sub>IN</sub> = 230 MHz		85		83		
HD3	Third-order harmonic distortion	f <sub>IN</sub> = 10 MHz		90		92		dBc
		f <sub>IN</sub> = 20 MHz	82	94		91		
		f <sub>IN</sub> = 70 MHz		94		91		
		f <sub>IN</sub> = 100 MHz		87		87		
		f <sub>IN</sub> = 170 MHz		88		89		
		f <sub>IN</sub> = 230 MHz		83		88		
Non HD2, HD3	Spurious-free dynamic range (excluding HD2, HD3)	f <sub>IN</sub> = 10 MHz		99		95		dBc
		f <sub>IN</sub> = 20 MHz	87	99		93		
		f <sub>IN</sub> = 70 MHz		99		93		
		f <sub>IN</sub> = 100 MHz		92		94		
		f <sub>IN</sub> = 170 MHz		97		89		
		f <sub>IN</sub> = 230 MHz		97		91		
THD	Total harmonic distortion	f <sub>IN</sub> = 10 MHz		89		87		dBc
		f <sub>IN</sub> = 20 MHz	79	90		87		
		f <sub>IN</sub> = 70 MHz		90		87		
		f <sub>IN</sub> = 100 MHz		86		85		
		f <sub>IN</sub> = 170 MHz		85		83		
		f <sub>IN</sub> = 230 MHz		81		81		
IMD3	Two-tone, third-order intermodulation distortion	f <sub>IN1</sub> = 45 MHz, f <sub>IN2</sub> = 50 MHz		–92		–92		dBFS
		f <sub>IN1</sub> = 185 MHz, f <sub>IN2</sub> = 190 MHz		–87		–87		
INL	Integral nonlinearity	f <sub>IN</sub> = 20 MHz		±0.8	±3	±0.8		LSBs
DNL	Differential nonlinearity	f <sub>IN</sub> = 20 MHz	–0.95	±0.6		±0.6		LSBs

## 7.10 AC Performance: ADC3443

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER		TEST CONDITIONS	ADC3443 (f <sub>S</sub> = 80 MSPS)						UNIT
			DITHER ON			DITHER OFF			
			MIN	TYP	MAX	MIN	TYP	MAX	
SNR	Signal-to-noise ratio (from 1-MHz offset)	f <sub>IN</sub> = 10 MHz	72.9			73.2			dBFS
		f <sub>IN</sub> = 70 MHz	70.7	72.8	73.1				
		f <sub>IN</sub> = 100 MHz	72.5			72.9			
		f <sub>IN</sub> = 170 MHz	72.1			72.4			
		f <sub>IN</sub> = 230 MHz	71.4			71.7			
	Signal-to-noise ratio (full Nyquist band)	f <sub>IN</sub> = 10 MHz	72.5			72.8			
		f <sub>IN</sub> = 70 MHz	72.4			72.8			
		f <sub>IN</sub> = 100 MHz	72.1			72.6			
		f <sub>IN</sub> = 170 MHz	71.7			72.0			
		f <sub>IN</sub> = 230 MHz	71.1			71.4			
NSD <sup>(1)</sup>	Noise spectral density (averaged across Nyquist zone)	f <sub>IN</sub> = 10 MHz	–148.8			–149.1			dBFS/Hz
		f <sub>IN</sub> = 70 MHz	–148.7	–146.6	–149.0				
		f <sub>IN</sub> = 100 MHz	–148.4			–148.8			
		f <sub>IN</sub> = 170 MHz	–148.0			–148.3			
		f <sub>IN</sub> = 230 MHz	–147.3			–147.6			
SINAD <sup>(1)</sup>	Signal-to-noise and distortion ratio	f <sub>IN</sub> = 10 MHz	72.8			73.2			dBFS
		f <sub>IN</sub> = 70 MHz	69.7	72.2	72.4				
		f <sub>IN</sub> = 100 MHz	72.7			73			
		f <sub>IN</sub> = 170 MHz	71.9			72.2			
		f <sub>IN</sub> = 230 MHz	71.2			71.4			
ENOB <sup>(1)</sup>	Effective number of bits	f <sub>IN</sub> = 10 MHz	11.8			11.9			Bits
		f <sub>IN</sub> = 70 MHz	11.3	11.8	11.8				
		f <sub>IN</sub> = 100 MHz	11.8			11.8			
		f <sub>IN</sub> = 170 MHz	11.7			11.7			
		f <sub>IN</sub> = 230 MHz	11.5			11.6			
SFDR	Spurious-free dynamic range	f <sub>IN</sub> = 10 MHz	89			89			dBc
		f <sub>IN</sub> = 70 MHz	81	90	89				
		f <sub>IN</sub> = 100 MHz	92			92			
		f <sub>IN</sub> = 170 MHz	88			86			
		f <sub>IN</sub> = 230 MHz	86			84			

(1) Reported from a 1-MHz offset.

**AC Performance: ADC3443 (continued)**

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER	TEST CONDITIONS	ADC3443 (f <sub>S</sub> = 80 MSPS)						UNIT
		DITHER ON			DITHER OFF			
		MIN	TYP	MAX	MIN	TYP	MAX	
HD2	Second-order harmonic distortion	f <sub>IN</sub> = 10 MHz		94			91	dBc
		f <sub>IN</sub> = 70 MHz	81	96			91	
		f <sub>IN</sub> = 100 MHz		97			94	
		f <sub>IN</sub> = 170 MHz		88			86	
		f <sub>IN</sub> = 230 MHz		87			85	
HD3	Third-order harmonic distortion	f <sub>IN</sub> = 10 MHz		89			90	dBc
		f <sub>IN</sub> = 70 MHz	81	91			90	
		f <sub>IN</sub> = 100 MHz		94			100	
		f <sub>IN</sub> = 170 MHz		95			93	
		f <sub>IN</sub> = 230 MHz		87			87	
Non HD2, HD3	Spurious-free dynamic range (excluding HD2, HD3)	f <sub>IN</sub> = 10 MHz		100			95	dBc
		f <sub>IN</sub> = 70 MHz	86	98			94	
		f <sub>IN</sub> = 100 MHz		95			94	
		f <sub>IN</sub> = 170 MHz		95			94	
		f <sub>IN</sub> = 230 MHz		94			92	
THD	Total harmonic distortion	f <sub>IN</sub> = 10 MHz		88			86	dBc
		f <sub>IN</sub> = 70 MHz	78	89			87	
		f <sub>IN</sub> = 100 MHz		91			90	
		f <sub>IN</sub> = 170 MHz		87			84	
		f <sub>IN</sub> = 230 MHz		84			82	
IMD3	Two-tone, third-order intermodulation distortion	f <sub>IN1</sub> = 45 MHz, f <sub>IN2</sub> = 50 MHz		–98			–98	dBFS
		f <sub>IN1</sub> = 185 MHz, f <sub>IN2</sub> = 190 MHz		–88			–88	
INL	Integral nonlinearity	f <sub>IN</sub> = 70 MHz		±0.8	±3		±0.8	LSBs
DNL	Differential nonlinearity	f <sub>IN</sub> = 70 MHz	–0.95	±0.7			±0.7	LSBs

## 7.11 AC Performance: ADC3444

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER		TEST CONDITIONS	ADC3444 (f <sub>S</sub> = 125 MSPS)						UNIT
			DITHER ON			DITHER OFF			
			MIN	TYP	MAX	MIN	TYP	MAX	
SNR	Signal-to-noise ratio (from 1-MHz offset)	f <sub>IN</sub> = 10 MHz	72.6			73			dBFS
		f <sub>IN</sub> = 70 MHz	70.2	72.5	72.9				
		f <sub>IN</sub> = 100 MHz	72.2			72.7			
		f <sub>IN</sub> = 170 MHz	71.7			72.3			
		f <sub>IN</sub> = 230 MHz	70.8			71.7			
	Signal-to-noise ratio (full Nyquist band)	f <sub>IN</sub> = 10 MHz	72.4			72.8			
		f <sub>IN</sub> = 70 MHz	72.3			72.7			
		f <sub>IN</sub> = 100 MHz	72.1			72.5			
		f <sub>IN</sub> = 170 MHz	71.5			72.1			
		f <sub>IN</sub> = 230 MHz	70.6			71.5			
NSD <sup>(1)</sup>	Noise spectral density (averaged across Nyquist zone)	f <sub>IN</sub> = 10 MHz	–150.4			–150.9			dBFS/Hz
		f <sub>IN</sub> = 70 MHz	–150.4	–148.1	–150.8				
		f <sub>IN</sub> = 100 MHz	–150.1			–150.5			
		f <sub>IN</sub> = 170 MHz	–149.5			–150.2			
		f <sub>IN</sub> = 230 MHz	–148.7			–149.6			
SINAD <sup>(1)</sup>	Signal-to-noise and distortion ratio	f <sub>IN</sub> = 10 MHz	72.6			72.9			dBFS
		f <sub>IN</sub> = 70 MHz	69.3	72.3	72.7				
		f <sub>IN</sub> = 100 MHz	72.3			72.7			
		f <sub>IN</sub> = 170 MHz	71.5			72			
		f <sub>IN</sub> = 230 MHz	69.9			70.6			
ENOB <sup>(1)</sup>	Effective number of bits	f <sub>IN</sub> = 10 MHz	11.8			11.8			Bits
		f <sub>IN</sub> = 70 MHz	11.2	11.8	11.8				
		f <sub>IN</sub> = 100 MHz	11.7			11.8			
		f <sub>IN</sub> = 170 MHz	11.6			11.7			
		f <sub>IN</sub> = 230 MHz	11.4			11.6			
SFDR	Spurious-free dynamic range	f <sub>IN</sub> = 10 MHz	92			87			dBc
		f <sub>IN</sub> = 70 MHz	80	93	88				
		f <sub>IN</sub> = 100 MHz	89			89			
		f <sub>IN</sub> = 170 MHz	86			84			
		f <sub>IN</sub> = 230 MHz	82			82			

(1) Reported from a 1-MHz offset.

**AC Performance: ADC3444 (continued)**

at maximum sampling rate, 50% clock duty cycle, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); typical values are specified at an ambient temperature of 25°C; minimum and maximum values are specified over an ambient temperature range of –40°C to +85°C

PARAMETER	TEST CONDITIONS	ADC3444 (f <sub>S</sub> = 125 MSPS)						UNIT
		DITHER ON			DITHER OFF			
		MIN	TYP	MAX	MIN	TYP	MAX	
HD2	Second-order harmonic distortion	f <sub>IN</sub> = 10 MHz		93			93	dBc
		f <sub>IN</sub> = 70 MHz	80	94			91	
		f <sub>IN</sub> = 100 MHz		90			90	
		f <sub>IN</sub> = 170 MHz		86			85	
		f <sub>IN</sub> = 230 MHz		81			80	
HD3	Third-order harmonic distortion	f <sub>IN</sub> = 10 MHz		96			88	dBc
		f <sub>IN</sub> = 70 MHz	81	95			89	
		f <sub>IN</sub> = 100 MHz		95			89	
		f <sub>IN</sub> = 170 MHz		93			87	
		f <sub>IN</sub> = 230 MHz		87			86	
Non HD2, HD3	Spurious-free dynamic range (excluding HD2, HD3)	f <sub>IN</sub> = 10 MHz		100			93	dBc
		f <sub>IN</sub> = 70 MHz	86	99			94	
		f <sub>IN</sub> = 100 MHz		94			92	
		f <sub>IN</sub> = 170 MHz		96			93	
		f <sub>IN</sub> = 230 MHz		94			90	
THD	Total harmonic distortion	f <sub>IN</sub> = 10 MHz		91			85	dBc
		f <sub>IN</sub> = 70 MHz	77	91			85	
		f <sub>IN</sub> = 100 MHz		88			86	
		f <sub>IN</sub> = 170 MHz		85			82	
		f <sub>IN</sub> = 230 MHz		80			78	
IMD3	Two-tone, third-order intermodulation distortion	f <sub>IN1</sub> = 45 MHz, f <sub>IN2</sub> = 50 MHz		–97			–97	dBFS
		f <sub>IN1</sub> = 185 MHz, f <sub>IN2</sub> = 190 MHz		–87			–87	
INL	Integral nonlinearity	f <sub>IN</sub> = 70 MHz		±0.75	±3		±0.75	LSBs
DNL	Differential nonlinearity	f <sub>IN</sub> = 70 MHz	–0.95	±0.7			±0.7	LSBs



## 7.12 Digital Characteristics

the dc specifications refer to the condition where the digital outputs are not switching, but are permanently at a valid logic level 0 or 1; AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>DIGITAL INPUTS (RESET, SCLK, SDATA, SEN, PDN)</b>						
V <sub>IH</sub>	High-level input voltage	All digital inputs support 1.8-V and 3.3-V CMOS logic levels	1.3			V
V <sub>IL</sub>	Low-level input voltage				0.4	V
I <sub>IH</sub>	High-level input current	RESET, SDATA, SCLK, PDN	V <sub>HIGH</sub> = 1.8 V		10	μA
		SEN <sup>(1)</sup>	V <sub>HIGH</sub> = 1.8 V		0	
I <sub>IL</sub>	Low-level input current	RESET, SDATA, SCLK, PDN	V <sub>LOW</sub> = 0 V		0	μA
		SEN	V <sub>LOW</sub> = 0 V		10	
<b>DIGITAL INPUTS (SYSREFP, SYSREFM)</b>						
Differential swing			0.2	0.8	1.0	V
Common-mode voltage for SYSREF <sup>(2)</sup>			0.9			V
<b>DIGITAL OUTPUTS (CMOS Interface, SDOOUT)</b>						
V <sub>OH</sub>	High-level output voltage		DVDD – 0.1	DVDD		V
V <sub>OL</sub>	Low-level output voltage			0	0.1	V
<b>DIGITAL OUTPUTS (LVDS Interface)</b>						
V <sub>ODH</sub>	High-level output differential voltage	With an external 100-Ω termination	280	350	–280	mV
V <sub>ODL</sub>	Low-level output differential voltage	With an external 100-Ω termination	–460	–350	–460	mV
V <sub>OCM</sub>	Output common-mode voltage		0.9	1.05	1.2	V

- (1) SEN has an internal 150-kΩ pullup resistor to AVDD. SPI pins (SEN, SCLK, SDATA) may be driven by 1.8 V or 3.3 V CMOS buffers.  
(2) SYSREF is internally biased to 0.9 V.

## 7.13 Timing Requirements: General

typical values are at T<sub>A</sub> = 25°C, AVDD = DVDD = 1.8 V, and –1-dBFS differential input (unless otherwise noted); minimum and maximum values are across the full temperature range: T<sub>MIN</sub> = –40°C to T<sub>MAX</sub> = +85°C

		MIN	TYP	MAX	UNIT	
t <sub>A</sub>	Aperture delay	1.24	1.44	1.64	ns	
Aperture delay matching between two channels of the same device		±70			ps	
Variation of aperture delay between two devices at the same temperature and supply voltage		±150			ps	
t <sub>J</sub>	Aperture jitter	130			f <sub>S</sub> rms	
Wake-up time		Time to valid data after exiting standby power-down mode		35	200	μs
		Time to valid data after exiting global power-down mode (in this mode, both channels power down)		85	450	μs
ADC latency <sup>(1)</sup>		2-wire mode (default)		9		Clock cycles
		1-wire mode		8		Clock cycles
t <sub>SU_SYSREF</sub>	SYSREF reference time	Setup time for SYSREF referenced to input clock falling edge		1000		ps
t <sub>H_SYSREF</sub>		Hold time for SYSREF referenced to input clock falling edge		100		ps

- (1) Overall latency = ADC latency + t<sub>PDI</sub>; see [Figure 141](#).

## 7.14 Timing Requirements: LVDS Output

typical values are at 25°C, AVDD = DVDD = 1.8 V, –1-dBFS differential input, 7x serialization (2-wire mode), C<sub>LOAD</sub> = 3.3 pF<sup>(1)</sup>, and R<sub>LOAD</sub> = 100 Ω<sup>(2)</sup> (unless otherwise noted); minimum and maximum values are across the full temperature range: T<sub>MIN</sub> = –40°C to T<sub>MAX</sub> = +85°C<sup>(3)(4)</sup>

		MIN	TYP	MAX	UNIT		
t <sub>SU</sub>	Data setup time: data valid to zero-crossing of differential output clock (CLKOUTP – CLKOUTM) <sup>(5)</sup>	0.36	0.42		ns		
t <sub>HO</sub>	Data hold time: zero-crossing of differential output clock (CLKOUTP – CLKOUTM) to data becoming invalid <sup>(5)</sup>	0.36	0.47		ns		
	LVDS bit clock duty cycle: duty cycle of differential clock (CLKOUTP – CLKOUTM)	49%					
t <sub>PDI</sub>	Clock propagation delay: input clock falling edge cross-over to frame clock rising edge cross-over 15 MSPS < sampling frequency < 125 MSPS	1-wire mode		2.7	4.5	6.5	ns
		2-wire mode		0.44 × t <sub>S</sub> + t <sub>DELAY</sub>			ns
t <sub>DELAY</sub>	Delay time	3	4.5	5.9		ns	
t <sub>FALL</sub> , t <sub>RISE</sub>	Data fall time, data rise time: rise time measured from –100 mV to 100 mV, 15 MSPS ≤ Sampling frequency ≤ 125 MSPS	0.11				ns	
t <sub>CLKRISE</sub> , t <sub>CLKFALL</sub>	Output clock rise time, output clock fall time: rise time measured from –100 mV to 100 mV, 15 MSPS ≤ Sampling frequency ≤ 125 MSPS	0.11				ns	

- (1) C<sub>LOAD</sub> is the effective external single-ended load capacitance between each output pin and ground
- (2) R<sub>LOAD</sub> is the differential load resistance between the LVDS output pair.
- (3) Measurements are done with a transmission line of a 100-Ω characteristic impedance between the device and load. Setup and hold time specifications take into account the effect of jitter on the output data and clock.
- (4) Timing parameters are ensured by design and characterization and are not tested in production.
- (5) Data valid refers to a logic high of +100 mV and a logic low of –100 mV.

**Table 1. LVDS Timings at Lower Sampling Frequencies: 7x Serialization (2-Wire Mode)**

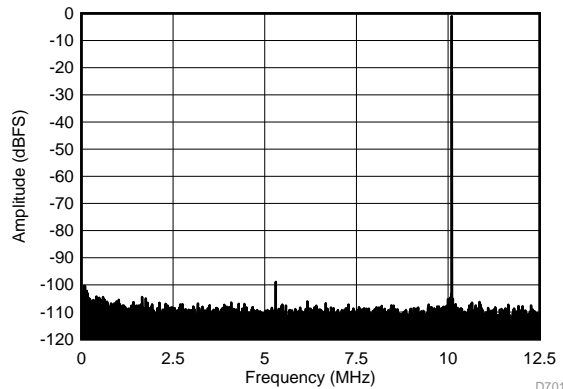
SAMPLING FREQUENCY (MSPS)	SETUP TIME (t <sub>SU</sub> , ns)			HOLD TIME (t <sub>HO</sub> , ns)		
	MIN	TYP	MAX	MIN	TYP	MAX
25	2.27	2.6		2.41	2.6	
40	1.44	1.6		1.51	1.7	
50	1.2	1.32		1.24	1.4	
60	0.95	1.04		0.97	1.09	
80	0.68	0.75		0.72	0.81	
100	0.5	0.57		0.53	0.62	

**Table 2. LVDS Timings at Lower Sampling Frequencies: 14x Serialization (1-Wire Mode)**

SAMPLING FREQUENCY (MSPS)	SETUP TIME (t <sub>SU</sub> , ns)			HOLD TIME (t <sub>HO</sub> , ns)		
	MIN	TYP	MAX	MIN	TYP	MAX
25	1.1	1.24		1.19	1.34	
40	0.66	0.72		0.74	0.82	
50	0.48	0.55		0.54	0.64	
60	0.35	0.41		0.42	0.51	
80	0.17	0.24		0.3	0.38	

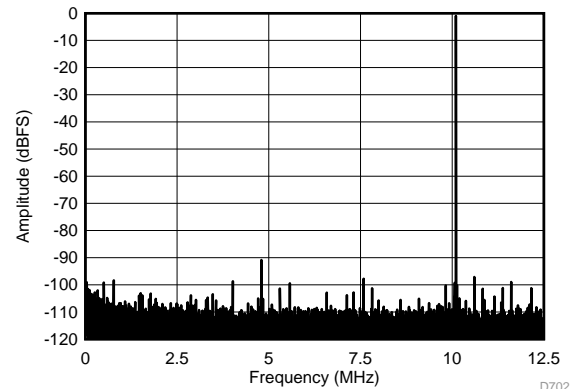
### 7.15 Typical Characteristics: ADC3441

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 25 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2-V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)



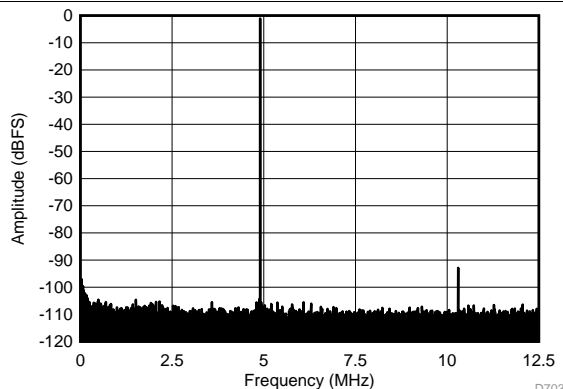
SFDR = 98 dBc, SNR = 73.1 dBFS, SINAD = 73 dBFS,  
THD = 97 dBc, HD2 = 110.0 dBc,  
HD3 = 98 dBc, SFDR = 100 dBc (excluding HD2, HD3)

**Figure 1. FFT for 10-MHz Input Signal (Dither On)**



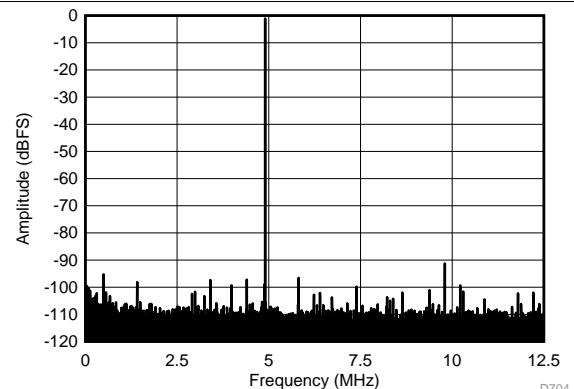
SFDR = 90 dBc, SNR = 73.5 dBFS, SINAD = 73.2 dBFS,  
THD = 88 dBc, HD2 = 90 dBc,  
HD3 = 100 dBc, SFDR = 92 dBc (excluding HD2, HD3)

**Figure 2. FFT for 10-MHz Input Signal (Dither Off)**



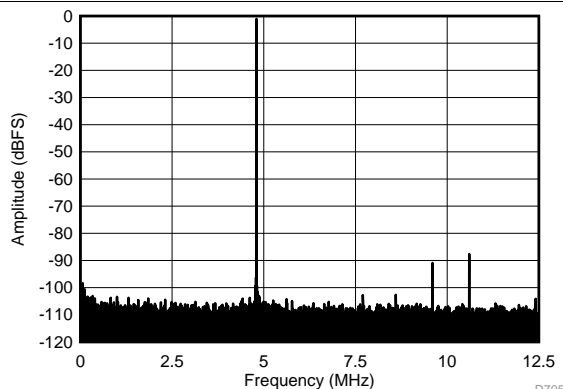
SFDR = 92 dBc, SNR = 72.5 dBFS, SINAD = 72.3 dBFS,  
THD = 91 dBc, HD2 = 108 dBc,  
HD3 = 92 dBc, SFDR = 101 dBc (excluding HD2, HD3)

**Figure 3. FFT for 70-MHz Input Signal (Dither On)**



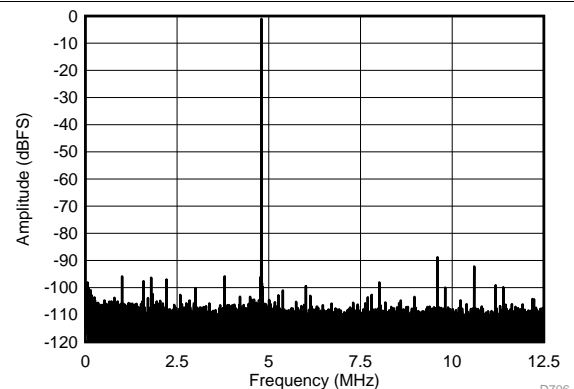
SFDR = 90 dBc, SNR = 72.9 dBFS, SINAD = 72.7 dBFS,  
THD = 89 dBc, HD2 = 90 dBc,  
HD3 = 101 dBc, SFDR = 93 dBc (excluding HD2, HD3)

**Figure 4. FFT for 70-MHz Input Signal (Dither Off)**



SFDR = 87 dBc, SNR = 71.5 dBFS, SINAD = 71.1 dBFS,  
THD = 85 dBc, HD2 = 90 dBc,  
HD3 = 87 dBc, SFDR = 100 dBc (excluding HD2, HD3)

**Figure 5. FFT for 170-MHz Input Signal (Dither On)**

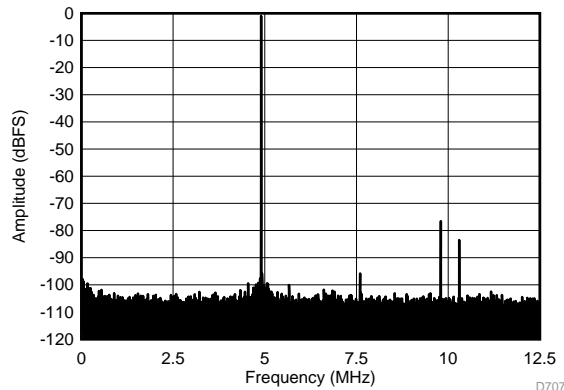


SFDR = 88 dBc, SNR = 71.7 dBFS, SINAD = 71.4 dBFS,  
THD = 85 dBc, HD2 = 88 dBc,  
HD3 = 91 dBc, SFDR = 93 dBc (excluding HD2, HD3)

**Figure 6. FFT for 170-MHz Input Signal (Dither Off)**

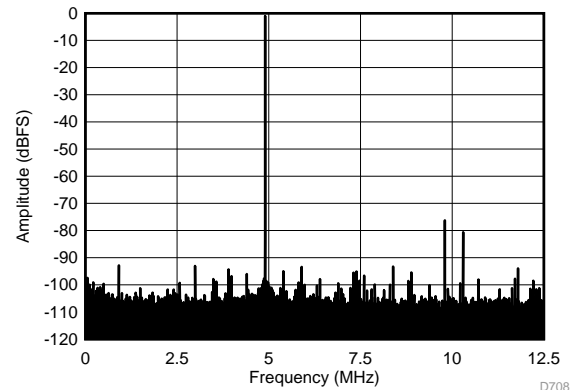
### Typical Characteristics: ADC3441 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 25 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)



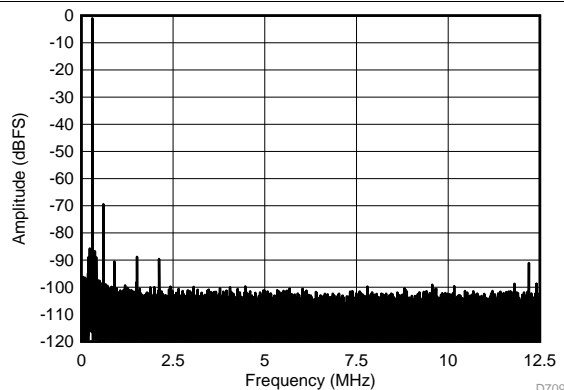
SFDR = 76 dBc, SNR = 69.4 dBFS, SINAD = 68.8 dBFS,  
THD = 75 dBc, HD2 = 76 dBc,  
HD3 = 83 dBc, SFDR = 96 dBc (excluding HD2, HD3)

Figure 7. FFT for 270-MHz Input Signal (Dither On)



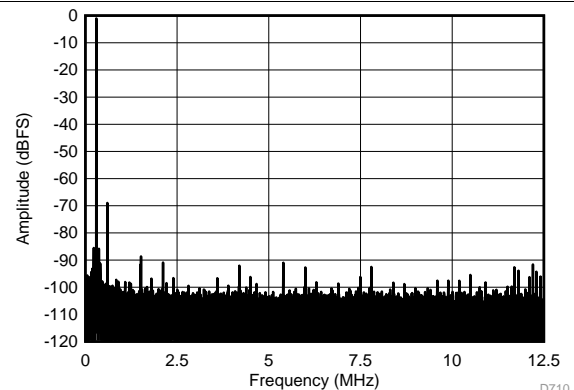
SFDR = 75 dBc, SNR = 69.6 dBFS, SINAD = 68.6 dBFS,  
THD = 74 dBc, HD2 = 75 dBc,  
HD3 = 80 dBc, SFDR = 91 dBc (excluding HD2, HD3)

Figure 8. FFT for 270-MHz Input Signal (Dither Off)



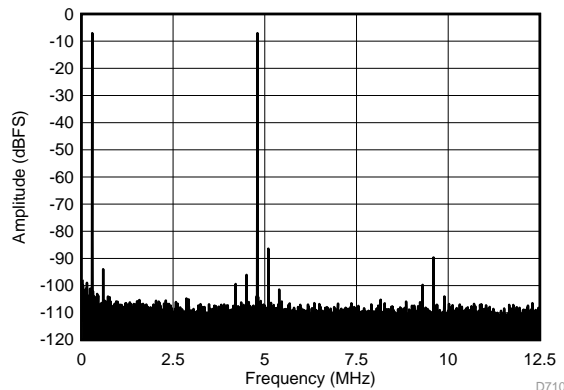
SFDR = 68 dBc, SNR = 66.7 dBFS, SINAD = 66.5 dBFS,  
THD = 92 dBc, HD2 = 68 dBc,  
HD3 = 90 dBc, SFDR = 91 dBc (excluding HD2, HD3)

Figure 9. FFT for 450-MHz Input Signal (Dither On)



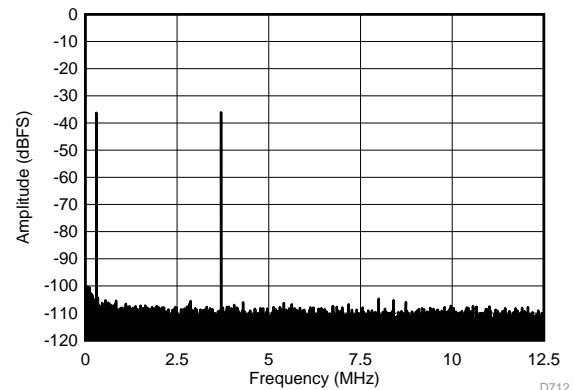
SFDR = 66 dBc, SNR = 66.8 dBFS, SINAD = 66.5 dBFS,  
THD = 88 dBc, HD2 = 66 dBc,  
HD3 = 97 dBc, SFDR = 90 dBc (excluding HD2, HD3)

Figure 10. FFT for 450-MHz Input Signal (Dither Off)



$f_{IN1} = 46.3\text{ MHz}$ ,  $f_{IN2} = 50.3\text{ MHz}$ , IMD3 = 86 dBFS,  
each tone at -7 dBFS

Figure 11. FFT for Two-Tone Input Signal  
(-7 dBFS at 46 MHz and 50 MHz)



$f_{IN1} = 46.3\text{ MHz}$ ,  $f_{IN2} = 50.3\text{ MHz}$ , IMD3 = 105 dBFS,  
each tone at -36 dBFS

Figure 12. FFT for Two-Tone Input Signal  
(-36 dBFS at 46 MHz and 50 MHz)

### Typical Characteristics: ADC3441 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 25 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2 \cdot V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)

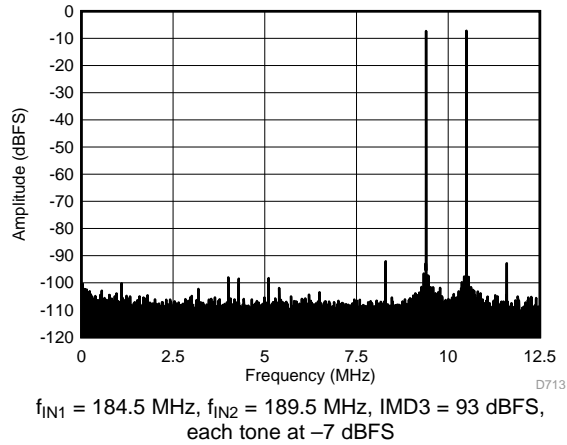


Figure 13. FFT for Two-Tone Input Signal  
( $-7 \text{ dBFS}$  at 185 MHz and 190 MHz)

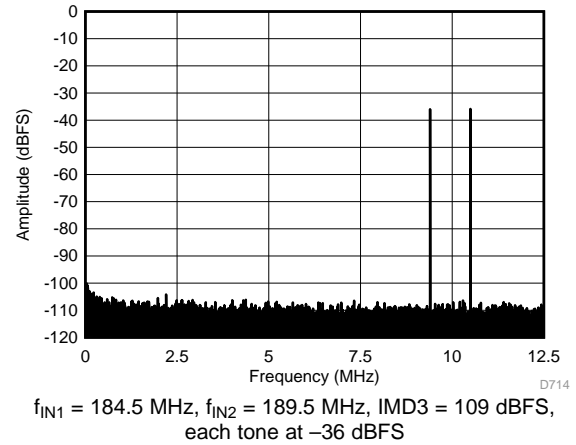


Figure 14. FFT for Two-Tone Input Signal  
( $-36 \text{ dBFS}$  at 185 MHz and 190 MHz)

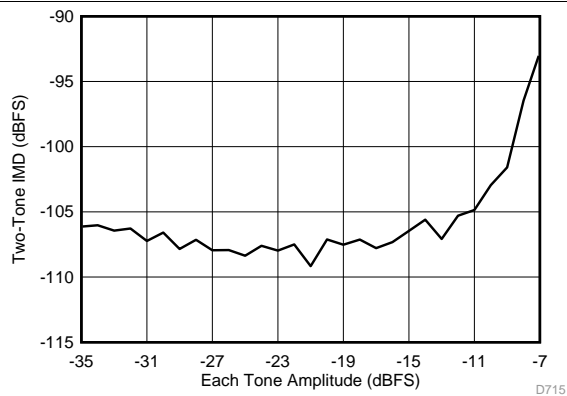


Figure 15. Intermodulation Distortion vs Input Amplitude  
(46 MHz and 50 MHz)

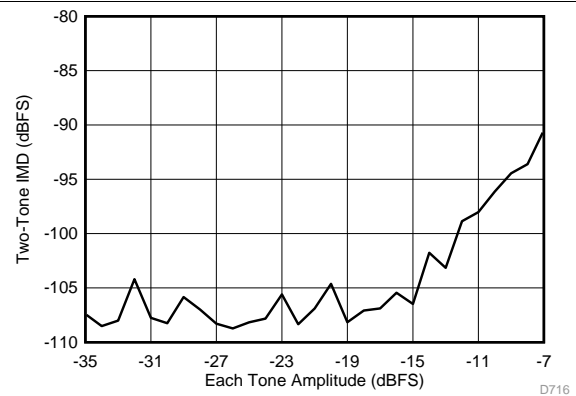


Figure 16. Intermodulation Distortion vs Input Amplitude  
(185 MHz and 190 MHz)

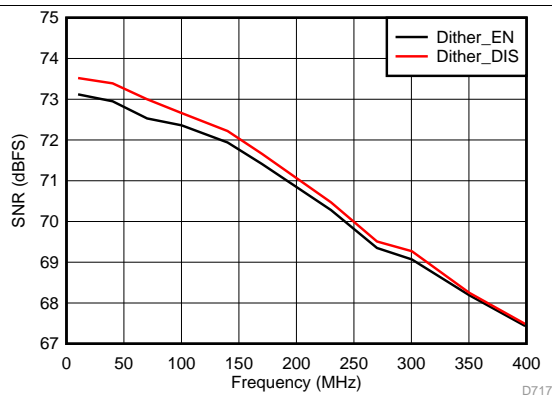


Figure 17. Signal-to-Noise Ratio vs Input Frequency

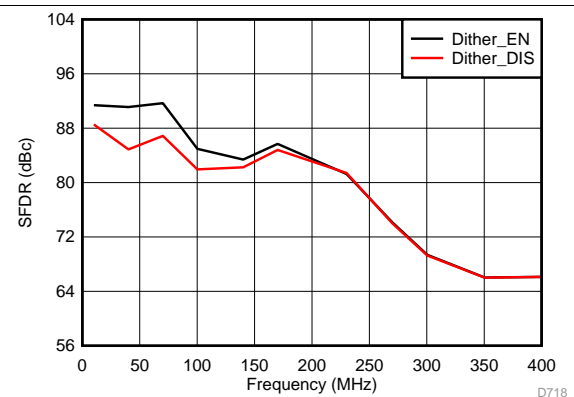


Figure 18. Spurious-Free Dynamic Range vs  
Input Frequency

### Typical Characteristics: ADC3441 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 25 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2 \cdot V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

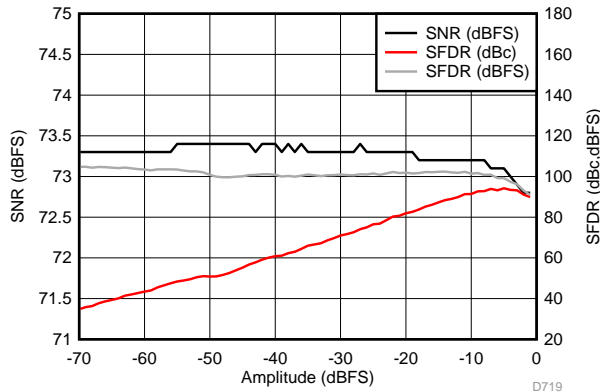


Figure 19. Performance vs Input Amplitude (30 MHz)

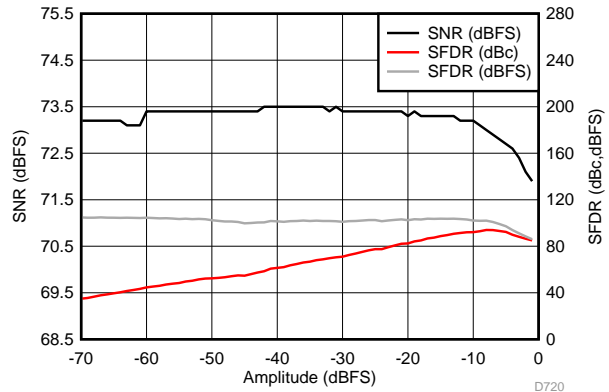


Figure 20. Performance vs Input Amplitude (170 MHz)

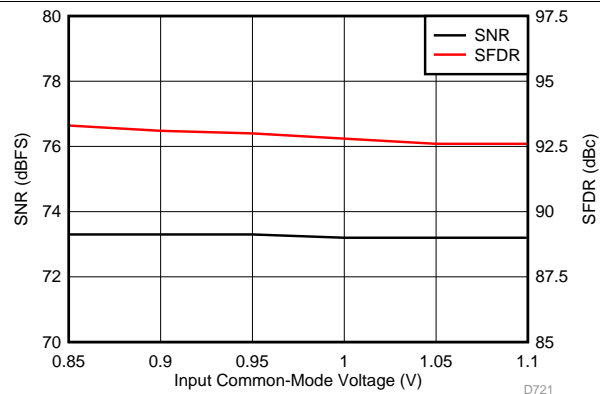


Figure 21. Performance vs Input Common-Mode Voltage (30 MHz)

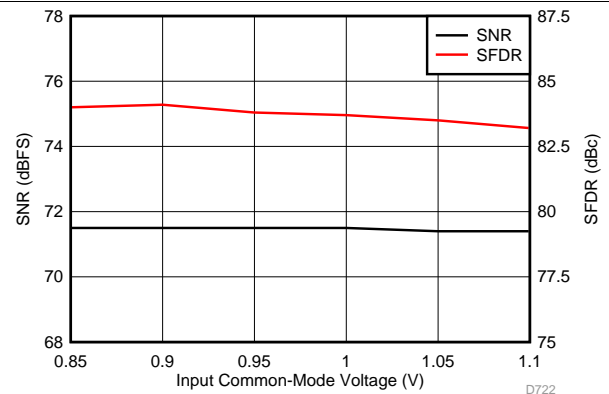


Figure 22. Performance vs Input Common-Mode Voltage (170 MHz)

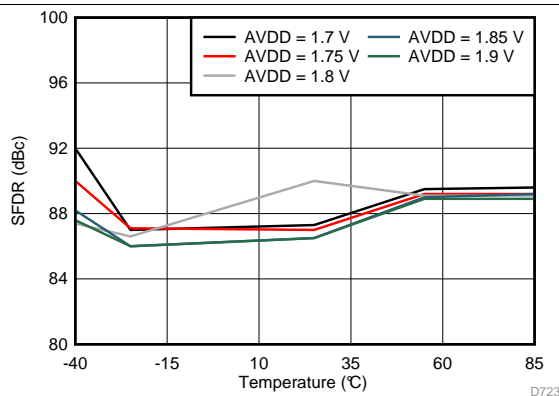


Figure 23. Spurious-Free Dynamic Range vs AVDD Supply and Temperature (30 MHz)

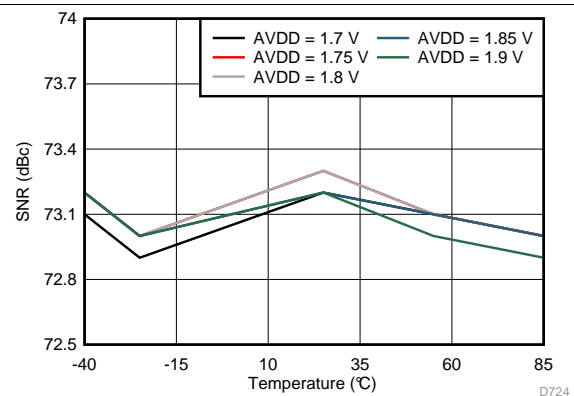


Figure 24. Signal-to-Noise Ratio vs AVDD Supply and Temperature (30 MHz)

Typical Characteristics: ADC3441 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 25 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input, 2- $V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

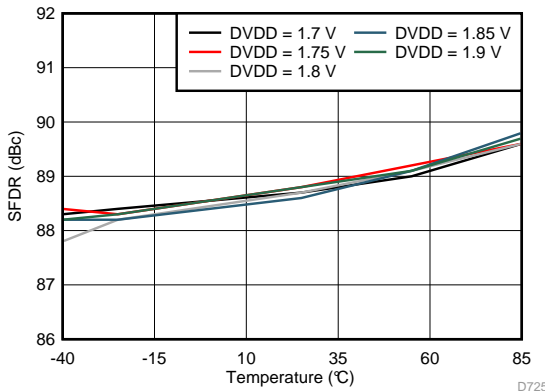


Figure 25. Spurious-Free Dynamic Range vs DVDD Supply and Temperature (30 MHz)

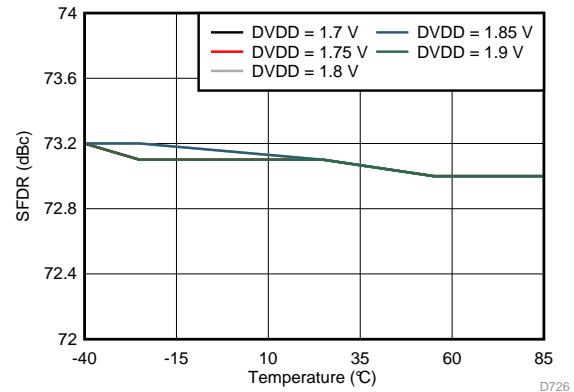


Figure 26. Signal-to-Noise Ratio vs DVDD Supply and Temperature (30 MHz)

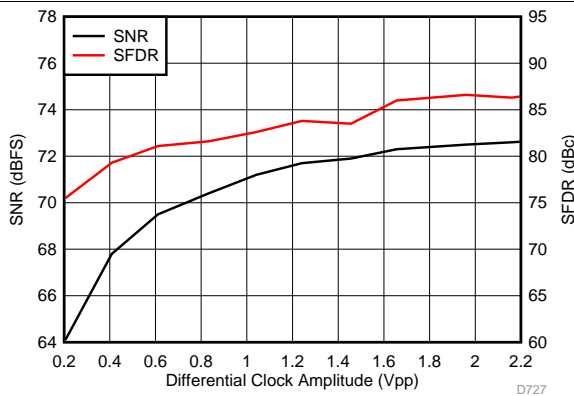


Figure 27. Performance vs Clock Amplitude (40 MHz)

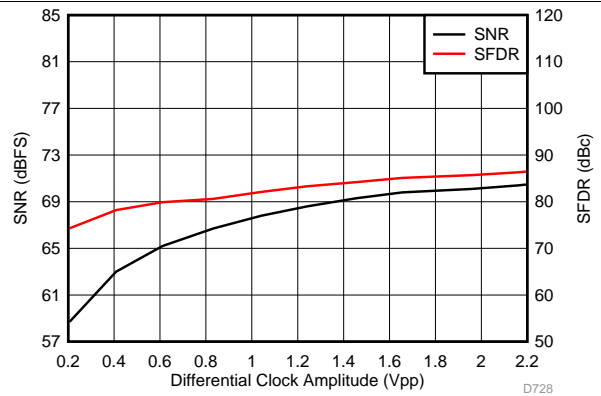


Figure 28. Performance vs Clock Amplitude (150 MHz)

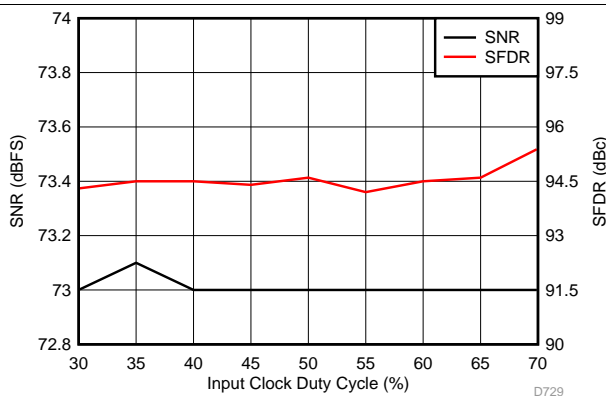


Figure 29. Performance vs Clock Duty Cycle (30 MHz)

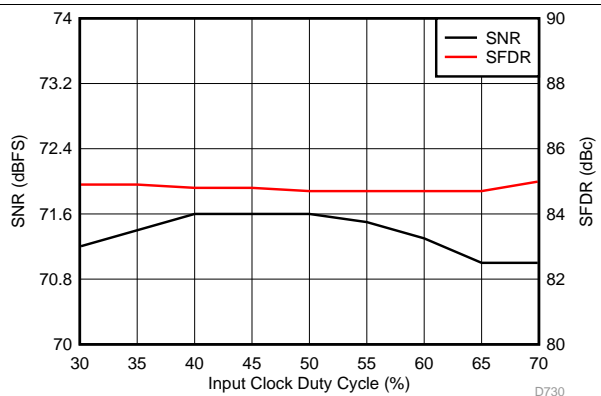


Figure 30. Performance vs Clock Duty Cycle (150 MHz)

### Typical Characteristics: ADC3441 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 25 MSPS, 50% clock duty cycle,  $AV_{DD} = 1.8\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $-1\text{-dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

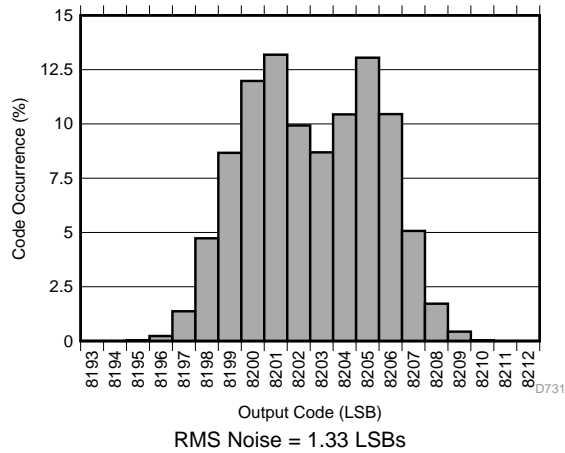


Figure 31. Idle Channel Histogram

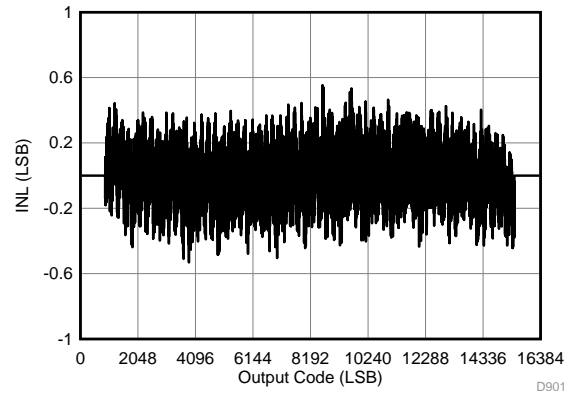


Figure 32. Integral Nonlinearity for 20-MHz Input

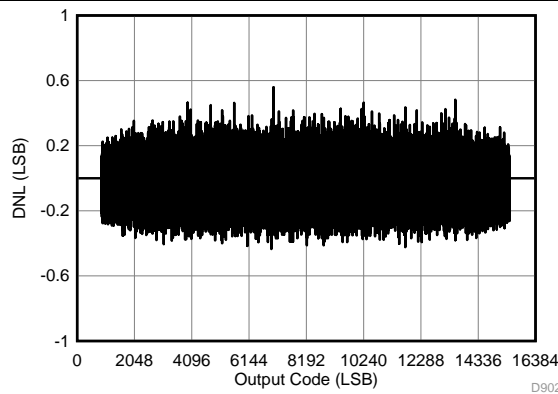
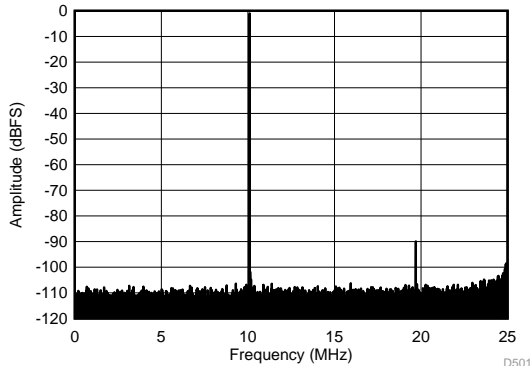


Figure 33. Differential Nonlinearity for 20-MHz Input



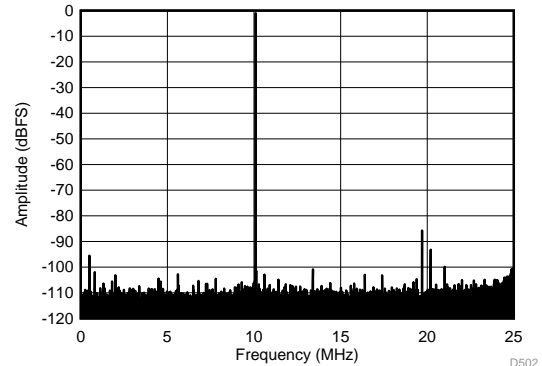
## 7.16 Typical Characteristics: ADC3442

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 50 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input, 2- $V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)



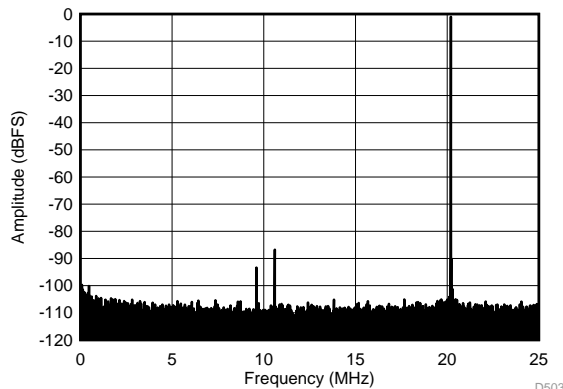
SFDR = 89 dBc, SNR = 73.1 dBFS, SINAD = 73 dBFS,  
THD = 89 dBc, HD2 = 111 dBc,  
HD3 = 89 dBc, SFDR = 100 dBc (excluding HD2, HD3)

**Figure 34. FFT for 10-MHz Input Signal  
(Chopper On, Dither On)**



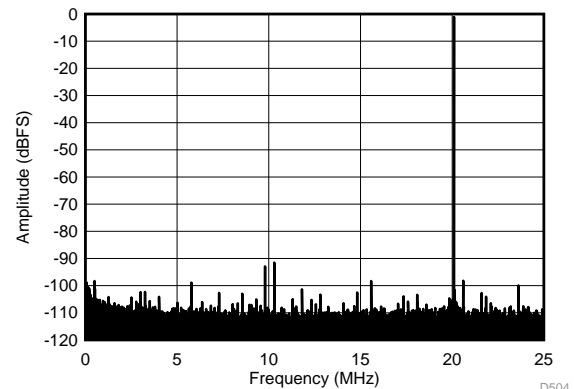
SFDR = 85 dBc, SNR = 73.5 dBFS, SINAD = 73.3 dBFS,  
THD = 84 dBc, HD2 = 92 dBc,  
HD3 = 85 dBc, SFDR = 96 dBc (excluding HD2, HD3)

**Figure 35. FFT for 10-MHz Input Signal  
(Chopper On, Dither Off)**



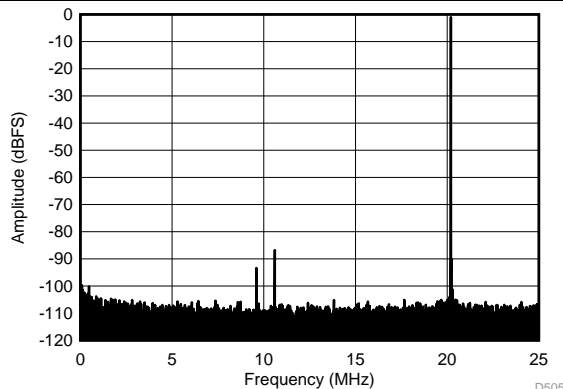
SFDR = 86 dBc, SNR = 72.7 dBFS, SINAD = 72.5 dBFS,  
THD = 85 dBc, HD2 = 92 dBc,  
HD3 = 86 dBc, SFDR = 100 dBc (excluding HD2, HD3)

**Figure 36. FFT for 70-MHz Input Signal (Dither On)**



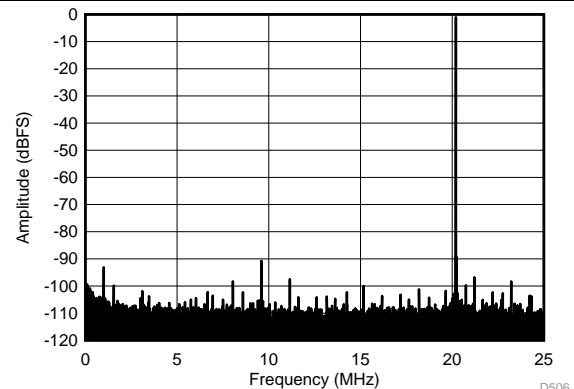
SFDR = 90 dBc, SNR = 73.1 dBFS, SINAD = 73 dBFS,  
THD = 88 dBc, HD2 = 92 dBc,  
HD3 = 90 dBc, SFDR = 95 dBc (excluding HD2, HD3)

**Figure 37. FFT for 70-MHz Input Signal (Dither Off)**



SFDR = 86 dBc, SNR = 71.6 dBFS, SINAD = 71.4 dBFS,  
THD = 85 dBc, HD2 = 92 dBc,  
HD3 = 86 dBc, SFDR = 99 dBc (excluding HD2, HD3)

**Figure 38. FFT for 170-MHz Input Signal (Dither On)**

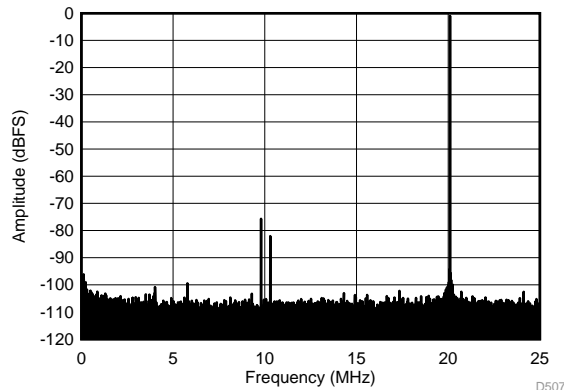


SFDR = 90 dBc, SNR = 71.8 dBFS, SINAD = 71.6 dBFS,  
THD = 87 dBc, HD2 = 90 dBc,  
HD3 = 108 dBc, SFDR = 93 dBc (excluding HD2, HD3)

**Figure 39. FFT for 170-MHz Input Signal (Dither Off)**

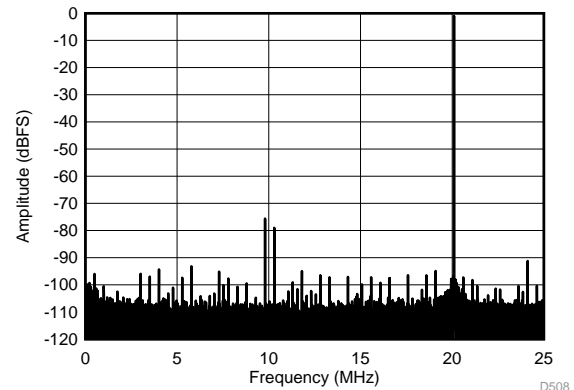
### Typical Characteristics: ADC3442 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 50 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, –1-dBFS differential input,  $2 \cdot V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)



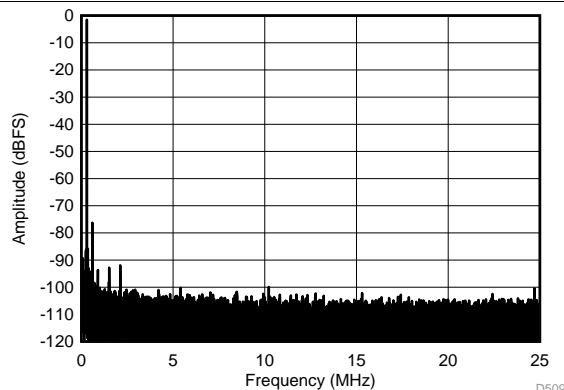
SFDR = 75 dBc, SNR = 70.3 dBFS, SINAD = 69.1 dBFS,  
THD = 74 dBc, HD2 = -75 dBc,  
HD3 = 81 dBc, SFDR = 95 dBc (excluding HD2, HD3)

Figure 40. FFT for 270-MHz Input Signal (Dither On)



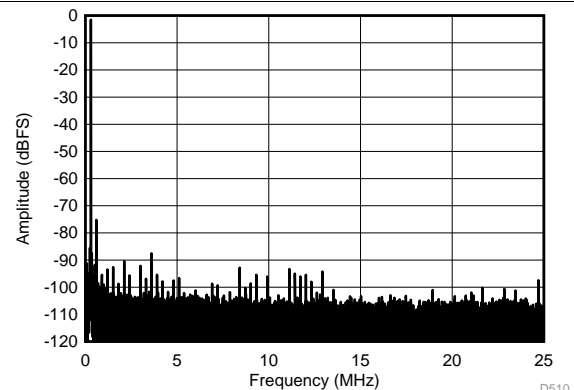
SFDR = 75 dBc, SNR = 70.6 dBFS, SINAD = 69.6 dBFS,  
THD = 73 dBc, HD2 = 75 dBc,  
HD3 = 78 dBc, SFDR = 91 dBc (excluding HD2, HD3)

Figure 41. FFT for 270-MHz Input Signal (Dither Off)



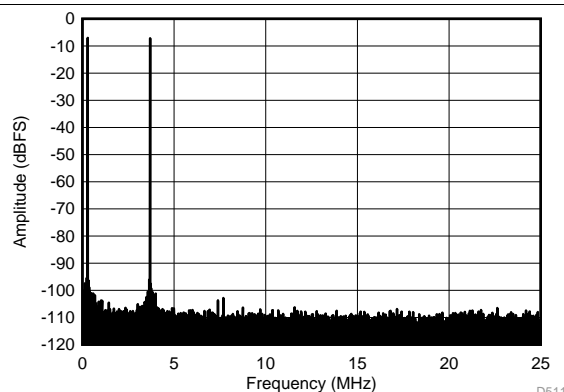
SFDR = 68 dBc, SNR = 68.2 dBFS, SINAD = 68 dBFS,  
THD = 86 dBc, HD2 = 68 dBc, HD3 = 87 dBc

Figure 42. FFT for 450-MHz Input Signal (Dither On)



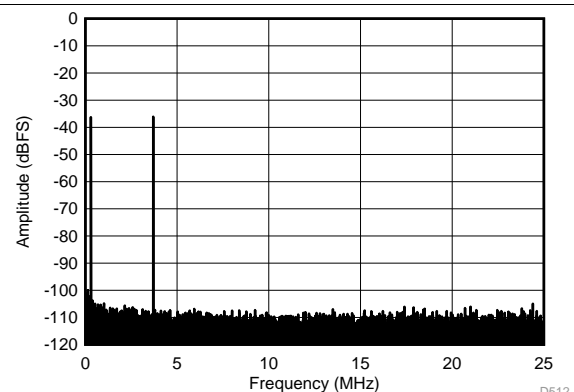
SFDR = 68 dBc, SNR = 68.5 dBFS, SINAD = 68.3 dBFS,  
THD = 86 dBc, HD2 = 68 dBc, HD3 = 90 dBc

Figure 43. FFT for 450-MHz Input Signal (Dither Off)



$f_{IN1} = 46.3 \text{ MHz}$ ,  $f_{IN2} = 50.3 \text{ MHz}$ , IMD3 = 102 dBFS,  
each tone at -7 dBFS

Figure 44. FFT for Two-Tone Input Signal  
(–7 dBFS at 46 MHz and 50 MHz)



$f_{IN1} = 46.3 \text{ MHz}$ ,  $f_{IN2} = 50.3 \text{ MHz}$ , IMD3 = 110 dBFS,  
each tone at -36 dBFS

Figure 45. FFT for Two-Tone Input Signal  
(–36 dBFS at 46 MHz and 50 MHz)

### Typical Characteristics: ADC3442 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 50 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)

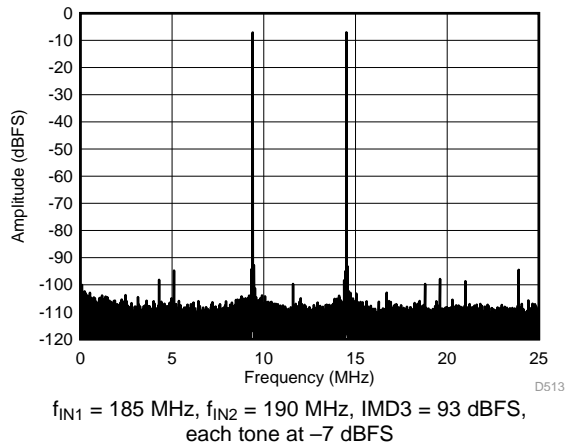


Figure 46. FFT for Two-Tone Input Signal (-7 dBFS at 185 MHz and 190 MHz)

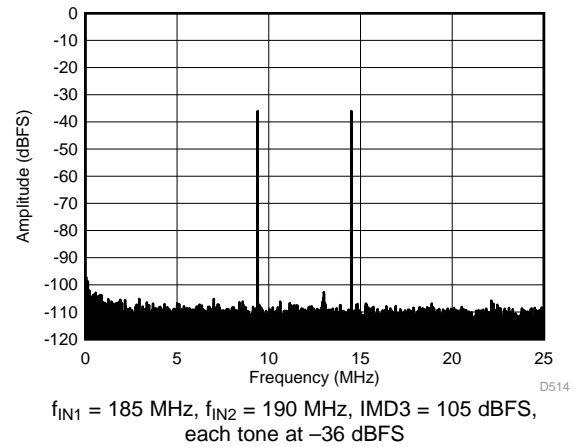


Figure 47. FFT for Two-Tone Input Signal (-36 dBFS at 185 MHz and 190 MHz)

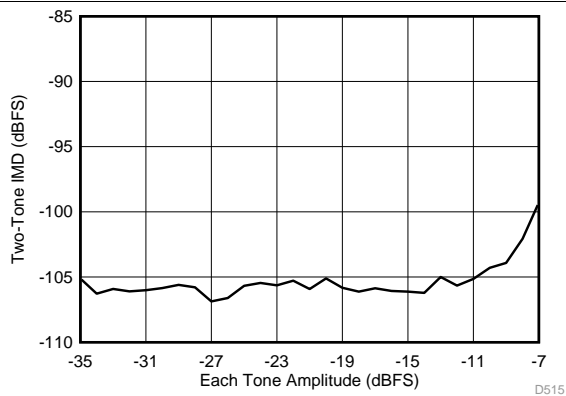


Figure 48. Intermodulation Distortion vs Input Amplitude (46 MHz and 50 MHz)

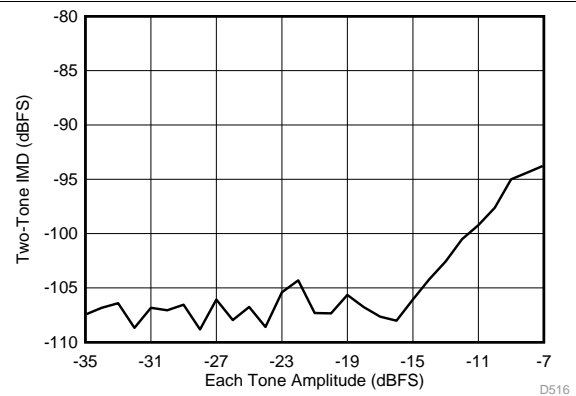


Figure 49. Intermodulation Distortion vs Input Amplitude (185 MHz and 190 MHz)

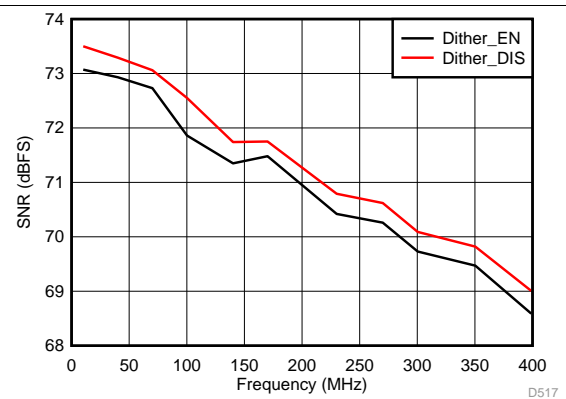


Figure 50. Signal-to-Noise Ratio vs Input Frequency

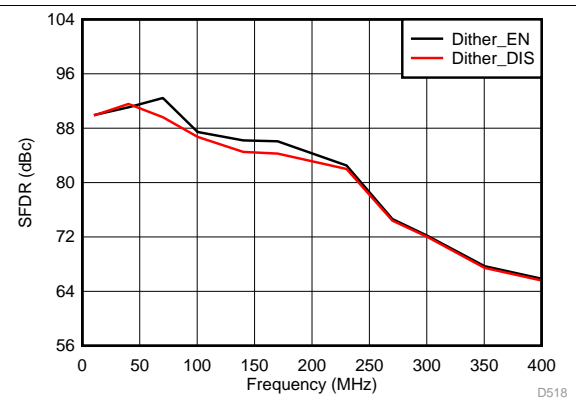


Figure 51. Spurious-Free Dynamic Range vs Input Frequency

### Typical Characteristics: ADC3442 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 50 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)

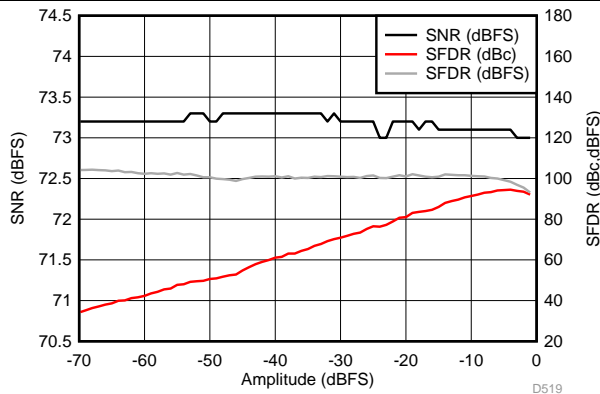


Figure 52. Performance vs Input Amplitude (30 MHz)

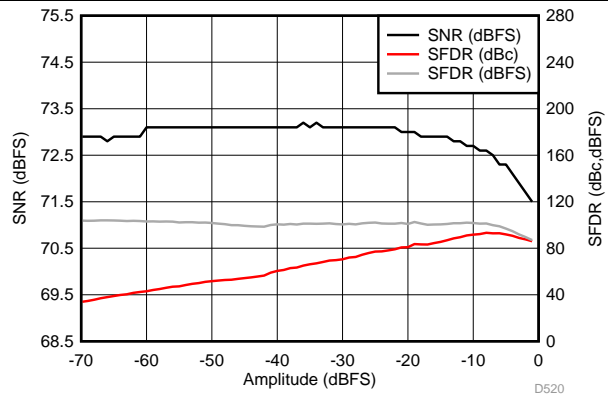


Figure 53. Performance vs Input Amplitude (170 MHz)

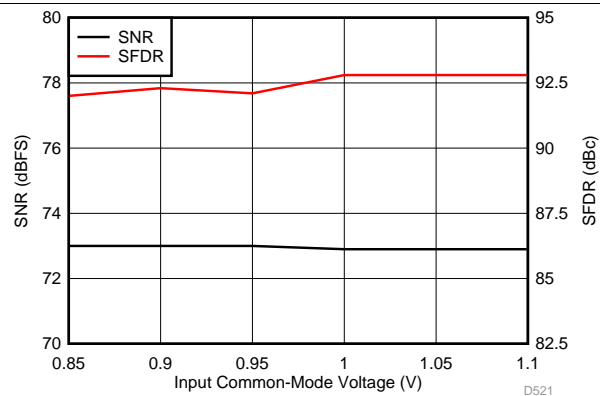


Figure 54. Performance vs Input Common-Mode Voltage (30 MHz)

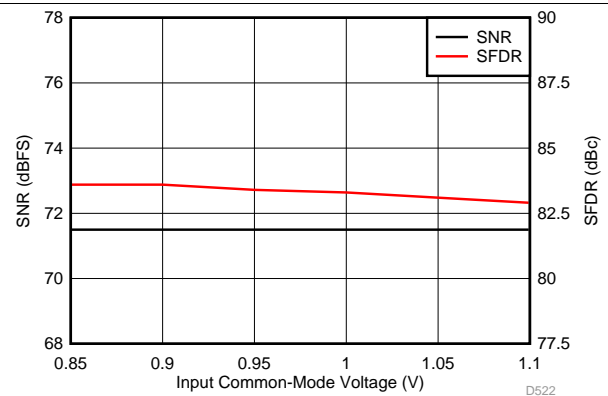


Figure 55. Performance vs Input Common-Mode Voltage (170 MHz)

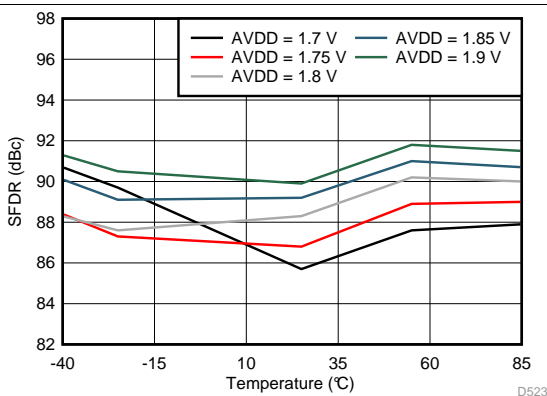


Figure 56. Spurious-Free Dynamic Range vs AVDD Supply and Temperature (30 MHz)

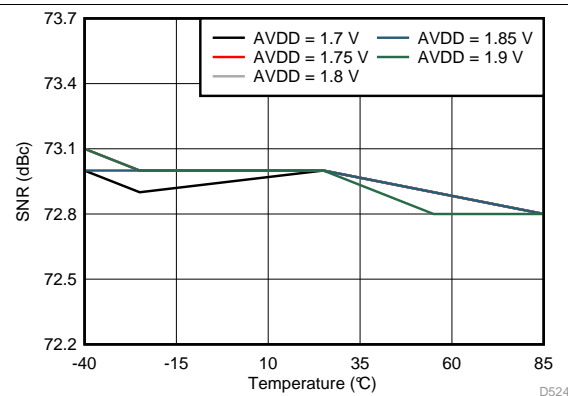


Figure 57. Signal-to-Noise Ratio vs AVDD Supply and Temperature (30 MHz)

Typical Characteristics: ADC3442 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 50 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2\cdot V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

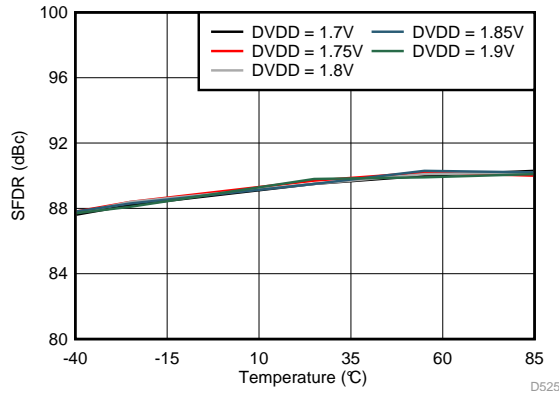


Figure 58. Spurious-Free Dynamic Range vs DVDD Supply and Temperature (30 MHz)

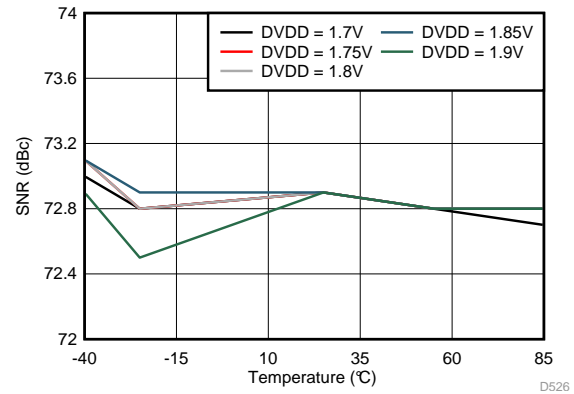


Figure 59. Signal-to-Noise Ratio vs DVDD Supply and Temperature (30 MHz)

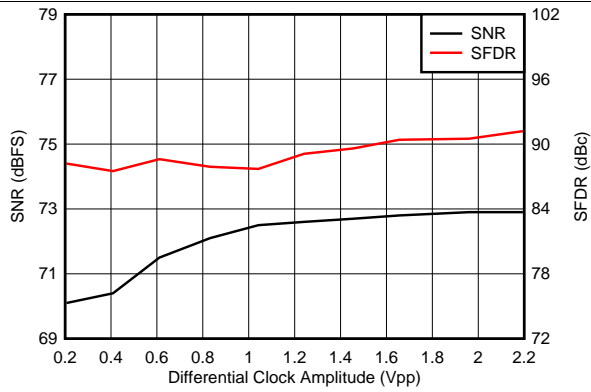


Figure 60. Performance vs Clock Amplitude (40 MHz)

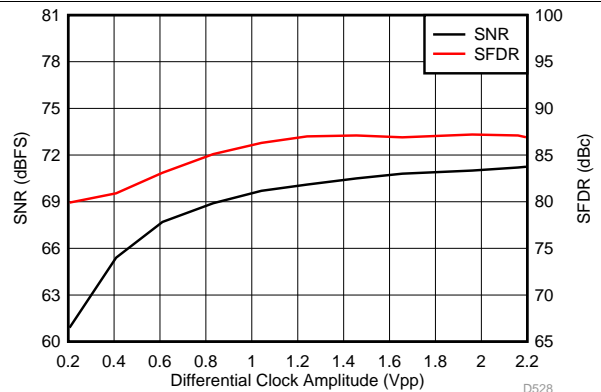


Figure 61. Performance vs Clock Amplitude (150 MHz)

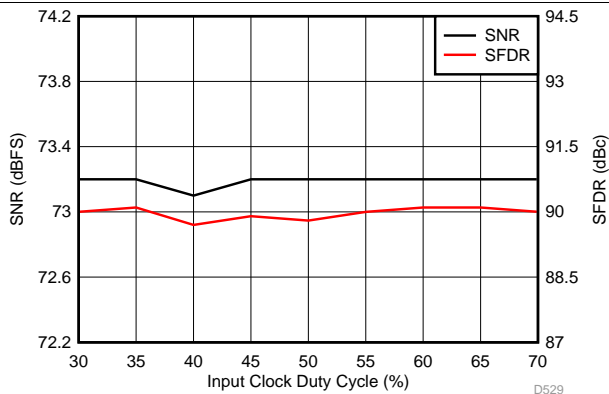


Figure 62. Performance vs Clock Duty Cycle (30 MHz)

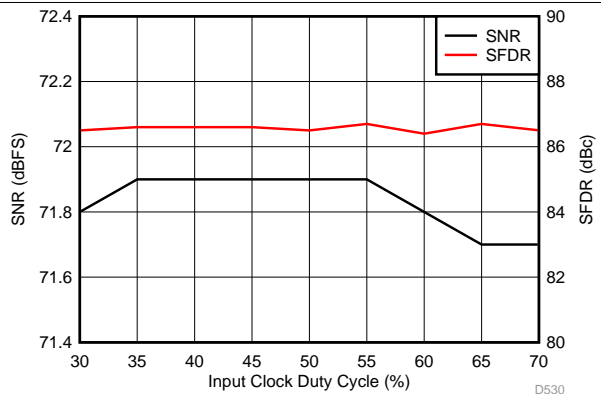


Figure 63. Performance vs Clock Duty Cycle (150 MHz)

### Typical Characteristics: ADC3442 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 50 MSPS, 50% clock duty cycle,  $AV_{DD} = 1.8\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $-1\text{-dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

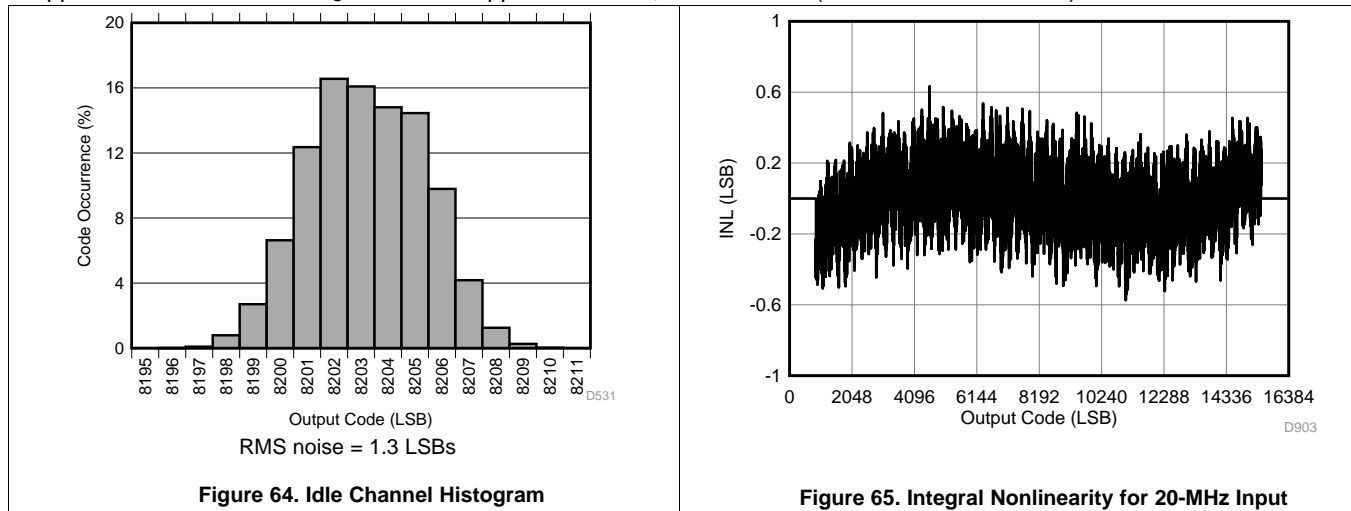


Figure 64. Idle Channel Histogram

Figure 65. Integral Nonlinearity for 20-MHz Input

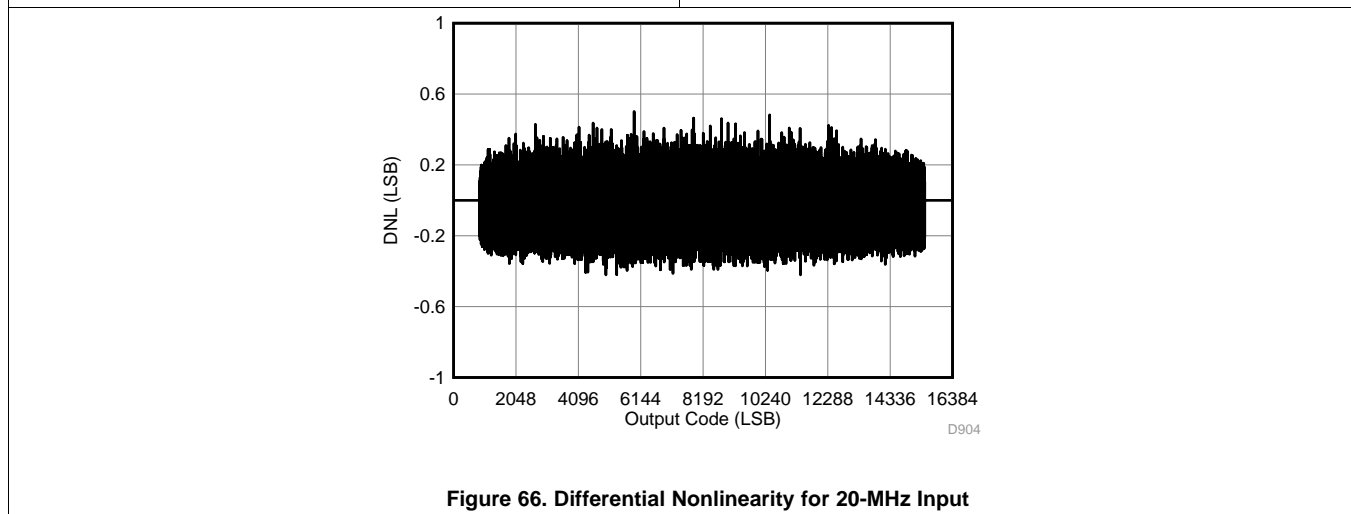
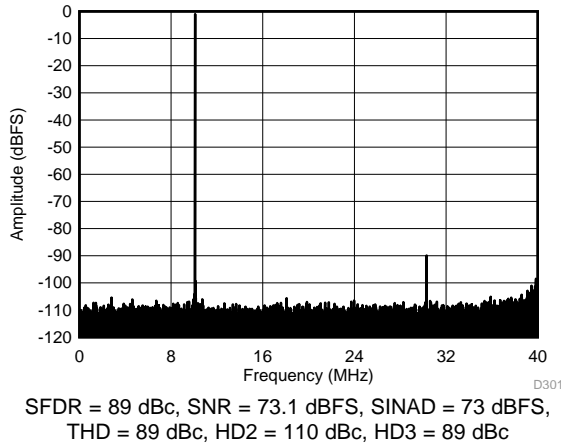


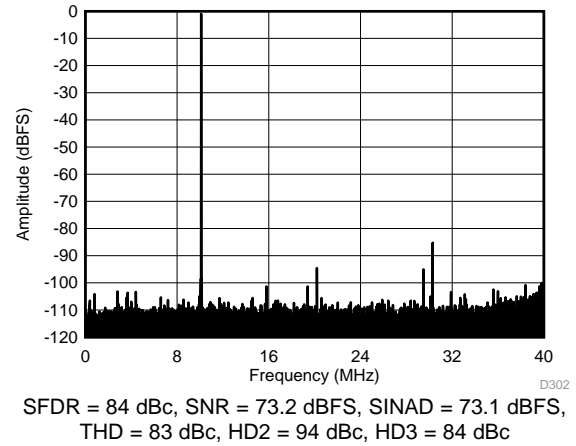
Figure 66. Differential Nonlinearity for 20-MHz Input

### 7.17 Typical Characteristics: ADC3443

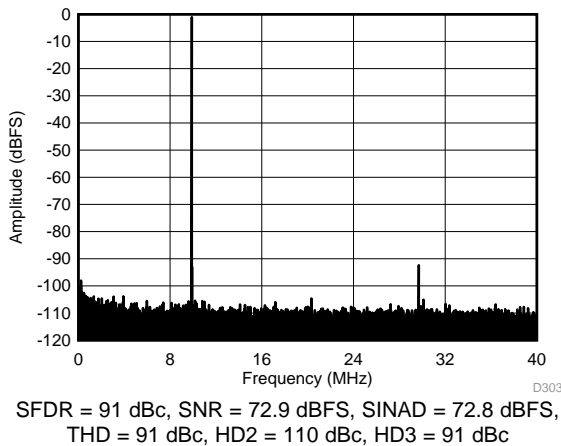
typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 80 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input, 2- $V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)



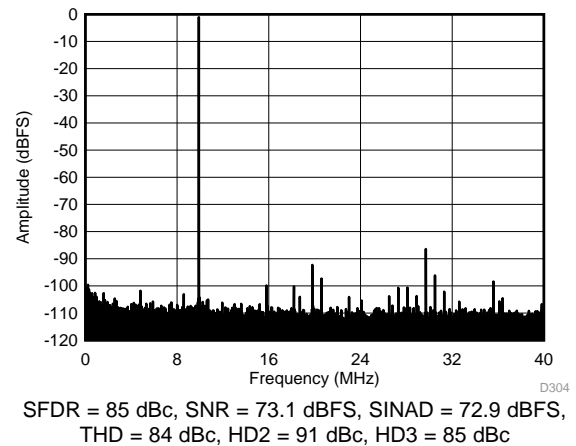
**Figure 67. FFT for 10-MHz Input Signal (Chopper On, Dither On)**



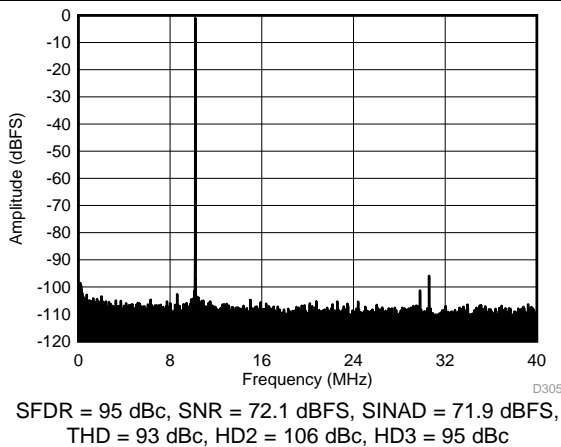
**Figure 68. FFT for 10-MHz Input Signal (Chopper On, Dither Off)**



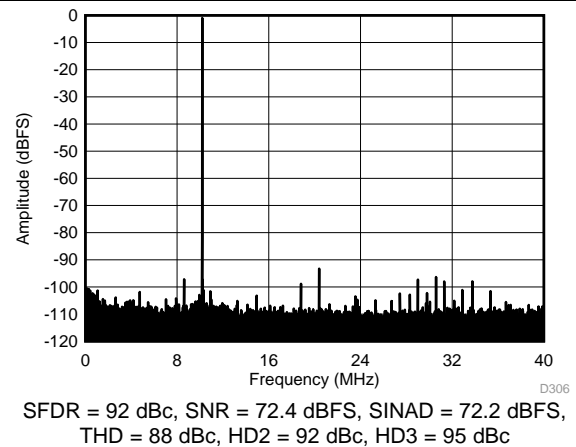
**Figure 69. FFT for 70-MHz Input Signal (Dither On)**



**Figure 70. FFT for 70-MHz Input Signal (Dither Off)**



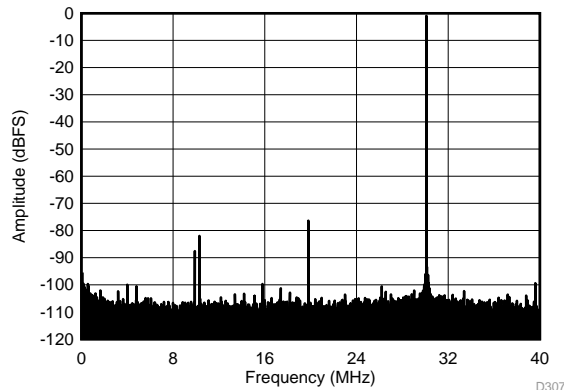
**Figure 71. FFT for 170-MHz Input Signal (Dither On)**



**Figure 72. FFT for 170-MHz Input Signal (Dither Off)**

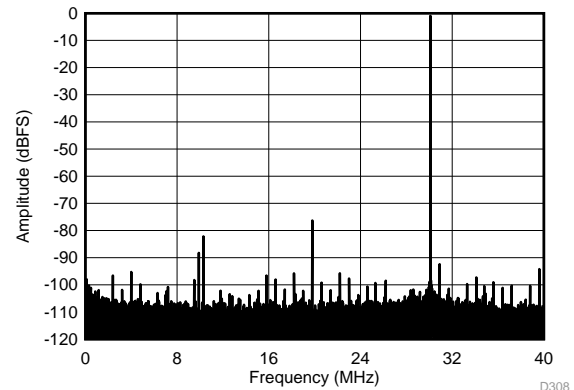
### Typical Characteristics: ADC3443 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 80 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2 \cdot V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)



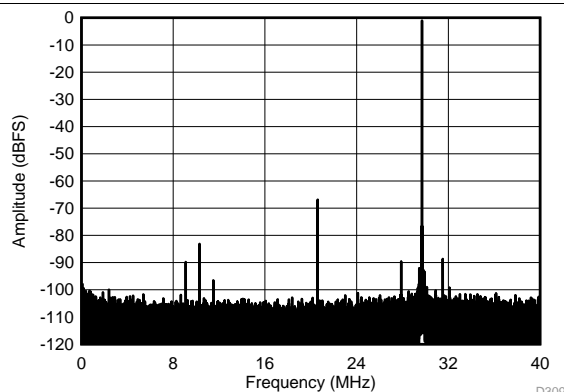
SFDR = 75 dBc, SNR = 70.5 dBFS, SINAD = 69.6 dBFS, THD = 74 dBc, HD2 = 75 dBc, HD3 = 81 dBc

Figure 73. FFT for 270-MHz Input Signal (Dither On)



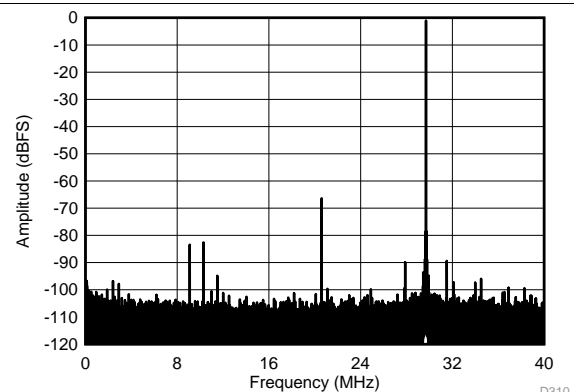
SFDR = 75 dBc, SNR = 71 dBFS, SINAD = 69.7 dBFS, THD = 74 dBc, HD2 = 75 dBc, HD3 = 81 dBc

Figure 74. FFT for 270-MHz Input Signal (Dither Off)



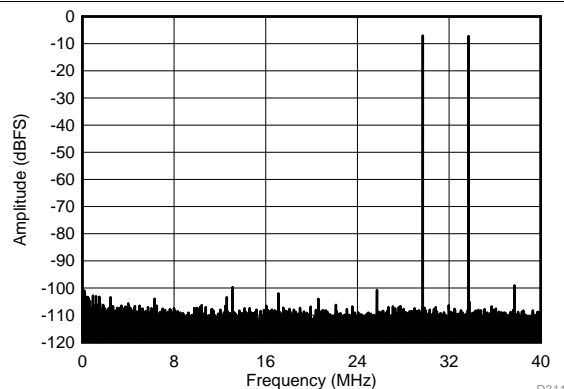
SFDR = 66 dBc, SNR = 68.4 dBFS, SINAD = 64.6 dBFS, THD = 66 dBc, HD2 = 66 dBc, HD3 = 89 dBc

Figure 75. FFT for 450-MHz Input Signal (Dither On)



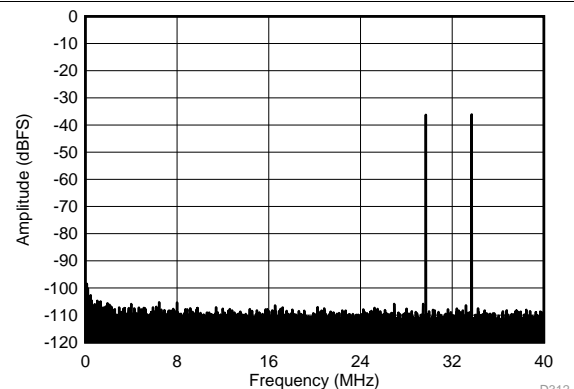
SFDR = 65 dBc, SNR = 68.7 dBFS, SINAD = 64.4 dBFS, THD = 65 dBc, HD2 = 65 dBc, HD3 = 82 dBc

Figure 76. FFT for 450-MHz Input Signal (Dither Off)



$f_{IN1} = 46 \text{ MHz}$ ,  $f_{IN2} = 50 \text{ MHz}$ , IMD3 = 99 dBFS, each tone at -7 dBFS

Figure 77. FFT for Two-Tone Input Signal (-7 dBFS at 46 MHz and 50 MHz)



$f_{IN1} = 46 \text{ MHz}$ ,  $f_{IN2} = 50 \text{ MHz}$ , IMD3 = 105 dBFS, each tone at -36 dBFS

Figure 78. FFT for Two-Tone Input Signal (-36 dBFS at 46 MHz and 50 MHz)



Typical Characteristics: ADC3443 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 80 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2 \cdot V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)

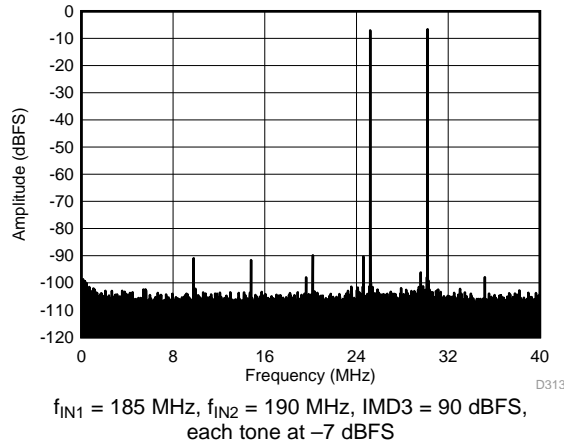


Figure 79. FFT FOR Two-Tone Input Signal (-7 dBFS at 185 MHz and 190 MHz)

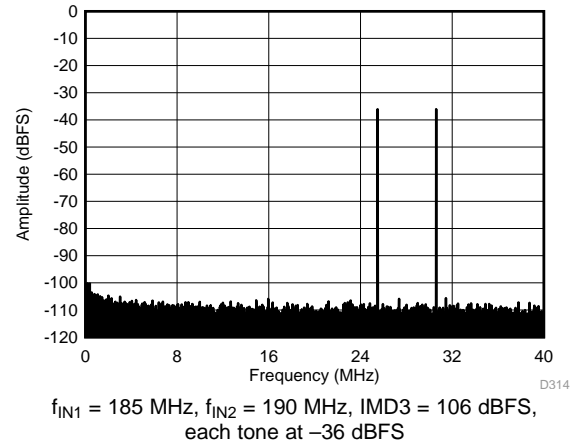


Figure 80. FFT FOR Two-Tone Input Signal (-36 dBFS at 185 MHz and 190 MHz)

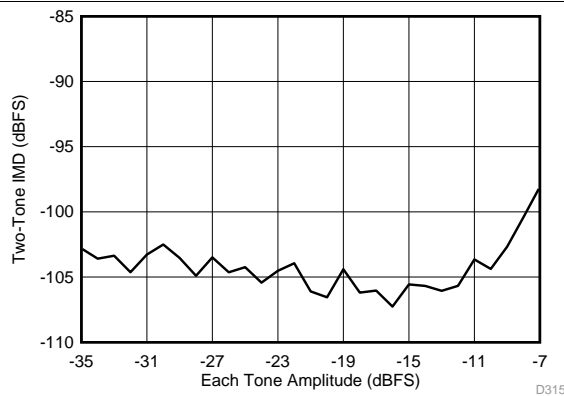


Figure 81. Intermodulation Distortion vs Input Amplitude (46 MHz and 50 MHz)

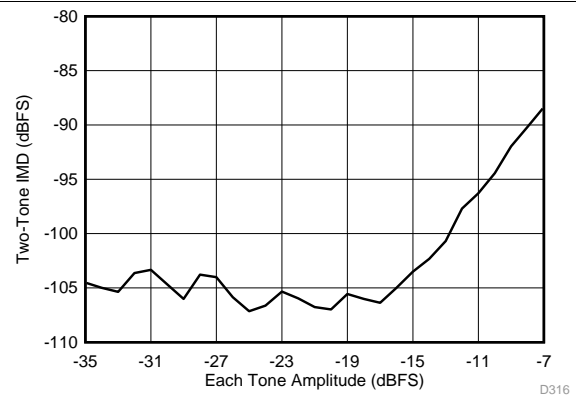


Figure 82. Intermodulation Distortion vs Input Amplitude (185 MHz and 190 MHz)

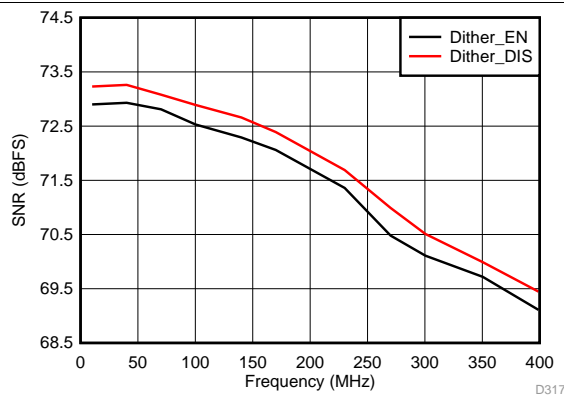


Figure 83. Signal-to-Noise Ratio vs Input Frequency

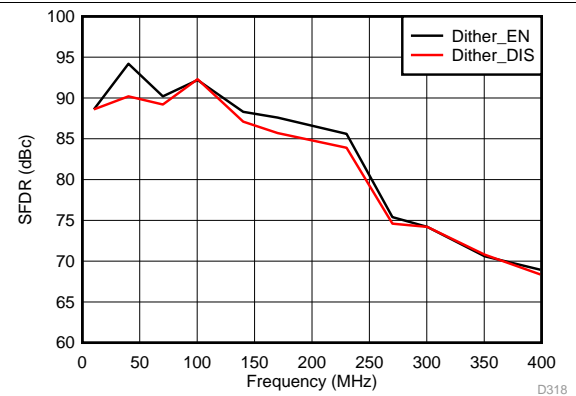


Figure 84. Spurious-Free Dynamic Range vs Input Frequency

### Typical Characteristics: ADC3443 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 80 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

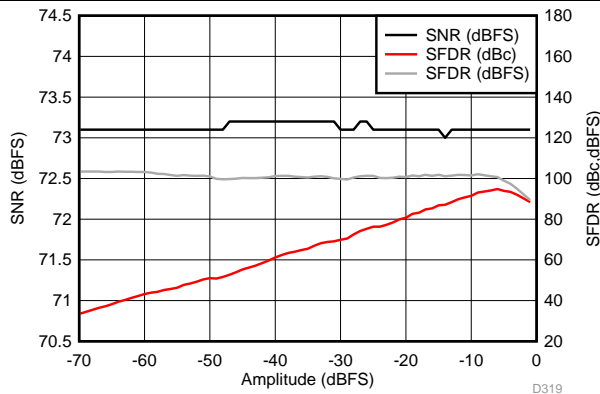


Figure 85. Performance vs Input Amplitude (30 MHz)

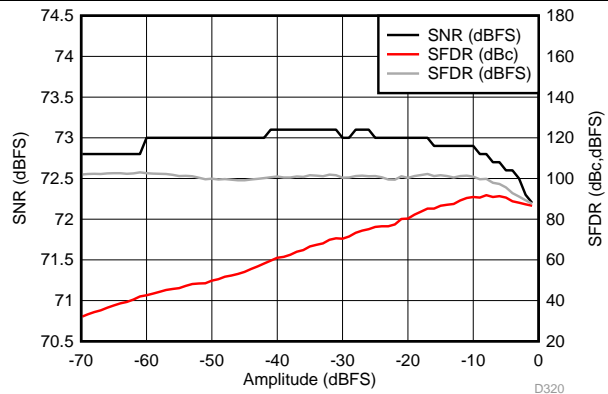


Figure 86. Performance vs Input Amplitude (170 MHz)

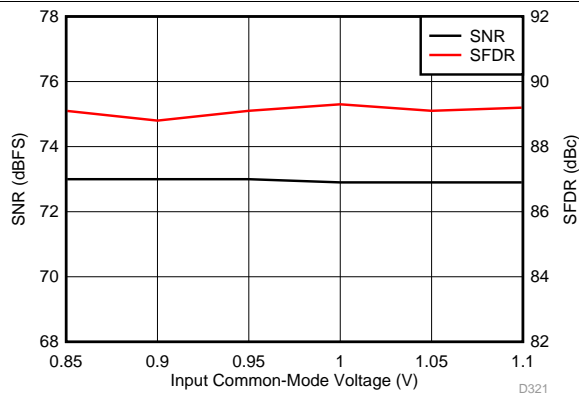


Figure 87. Performance vs Input Common-Mode Voltage (30 MHz)

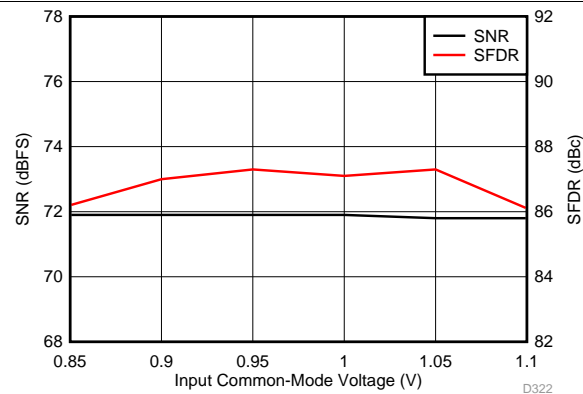


Figure 88. Performance vs Input Common-Mode Voltage (170 MHz)

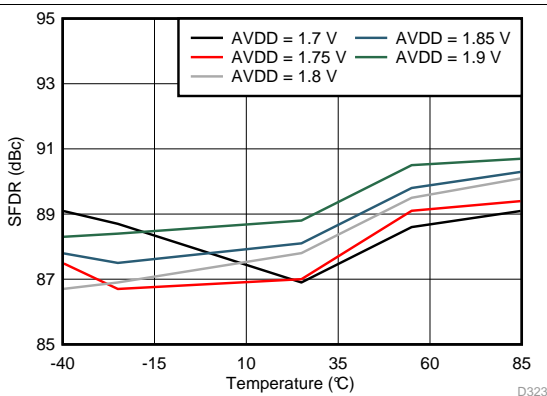


Figure 89. Spurious-Free Dynamic Range vs AVDD Supply and Temperature (170 MHz)

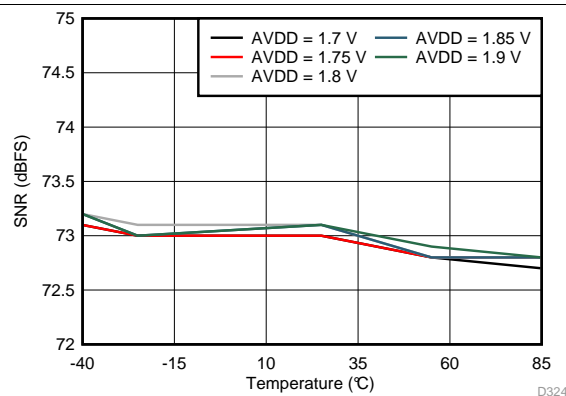


Figure 90. Signal-to-Noise Ratio vs AVDD Supply and Temperature (170 MHz)

Typical Characteristics: ADC3443 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 80 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input, 2- $V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)

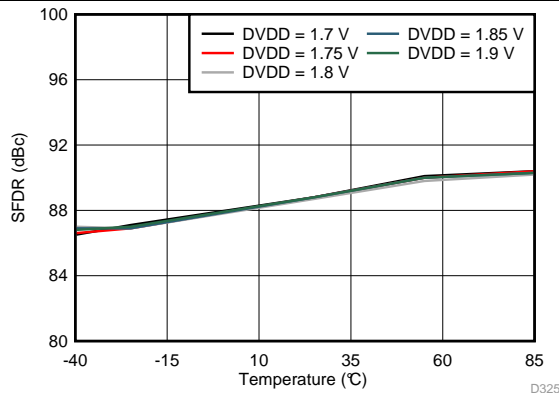


Figure 91. Spurious-Free Dynamic Range vs DVDD Supply and Temperature (170 MHz)

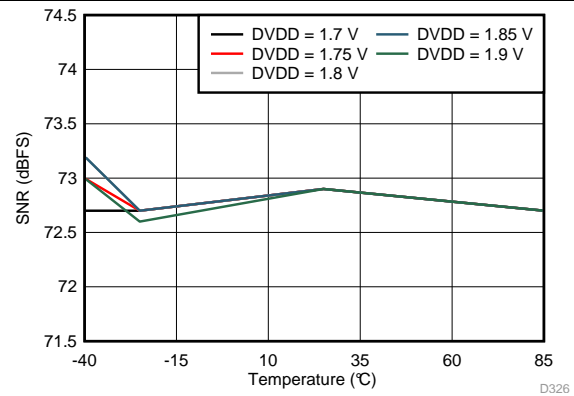


Figure 92. Signal-to-Noise Ratio vs DVDD Supply and Temperature (170 MHz)

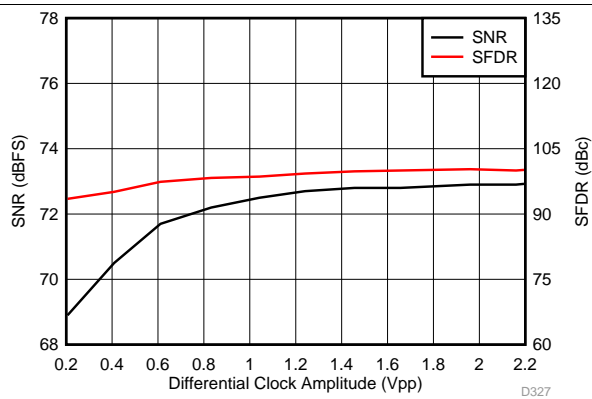


Figure 93. Performance vs Clock Amplitude (40 MHz)

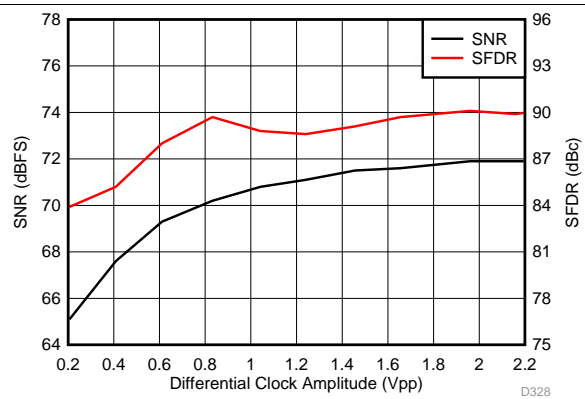


Figure 94. Performance vs Clock Amplitude (150 MHz)

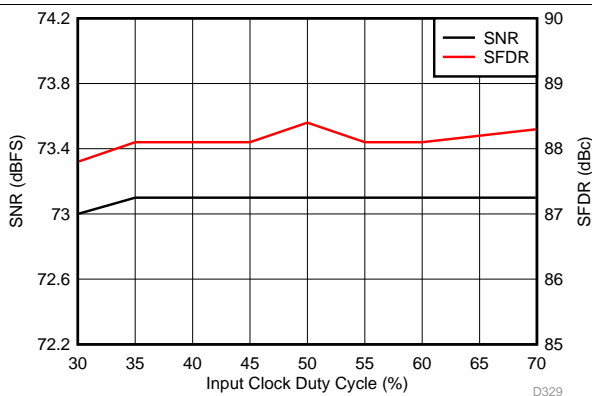


Figure 95. Performance vs Clock Duty Cycle (30 MHz)

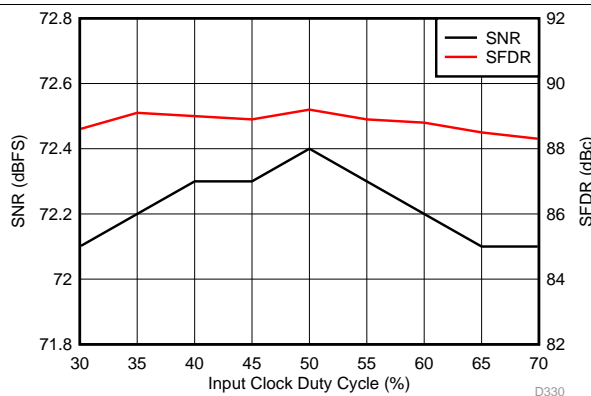


Figure 96. Performance vs Clock Duty Cycle (150 MHz)

### Typical Characteristics: ADC3443 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 80 MSPS, 50% clock duty cycle,  $AV_{DD} = 1.8\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $-1\text{-dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

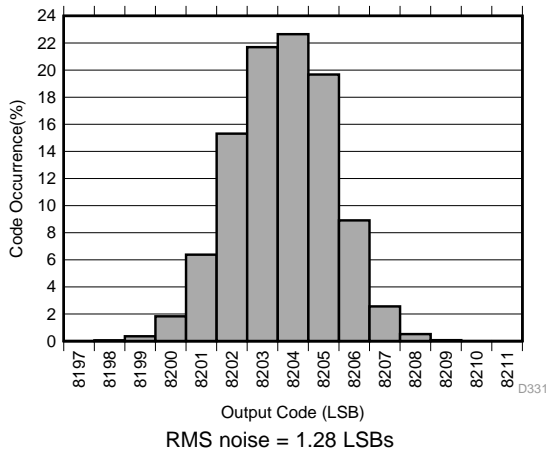


Figure 97. Idle Channel Histogram

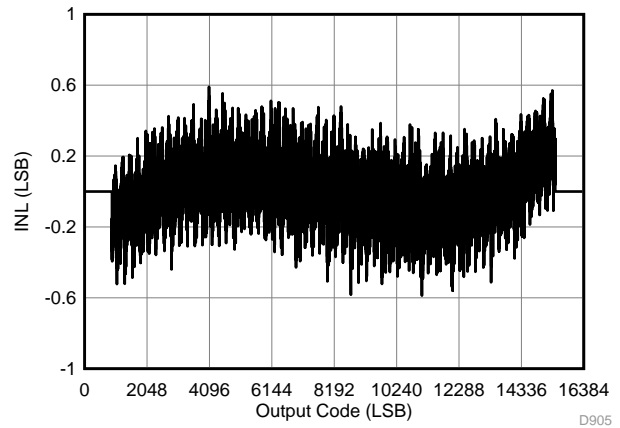


Figure 98. Integral Nonlinearity for 70-MHz Input

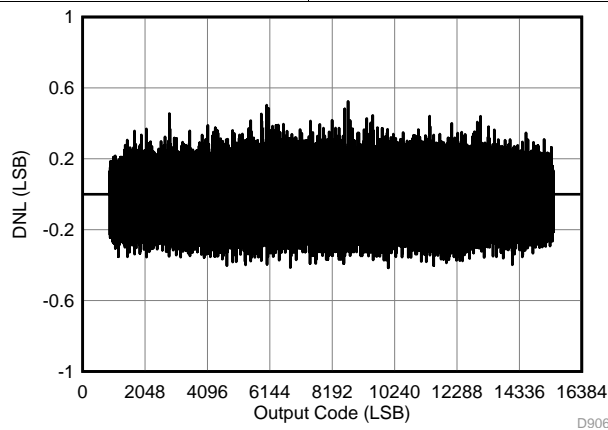
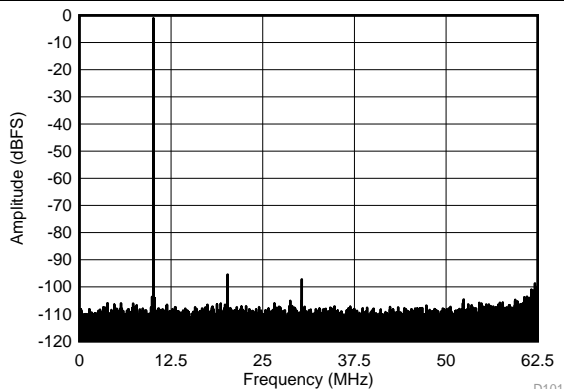


Figure 99. Differential Nonlinearity for 70-MHz Input

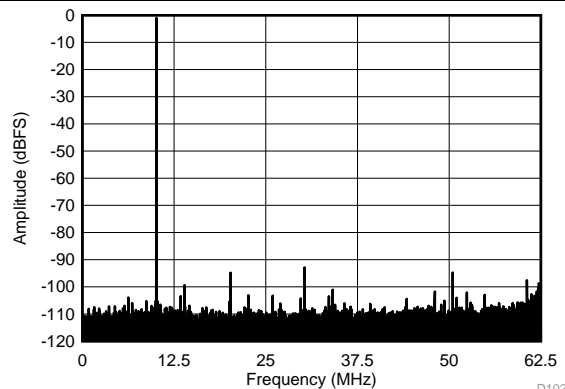
### 7.18 Typical Characteristics: ADC3444

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 125 MSPS, 50% clock duty cycle,  $AV_{DD} = 1.8\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $-1\text{ dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)



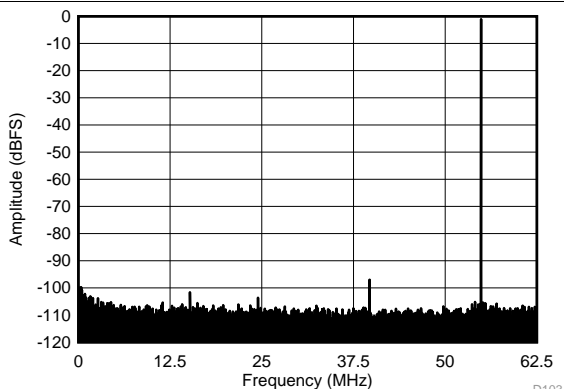
SFDR = 95 dBc, SNR = 72.7 dBFS, SINAD = 72.6 dBFS, THD = 100 dBc, HD2 = 95 dBc, HD3 = 96 dBc

**Figure 100. FFT for 10-MHz Input Signal (Chopper On, Dither On)**



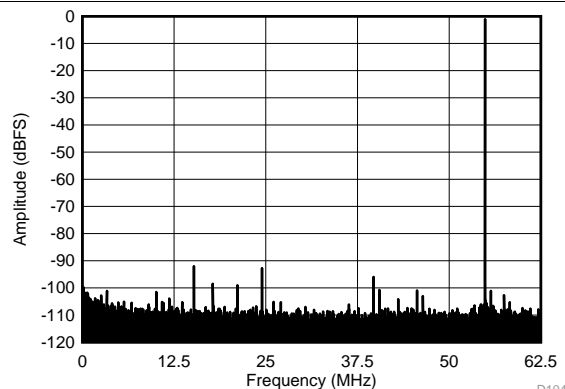
SFDR = 91.8 dBc, SNR = 73.1 dBFS, SINAD = 73 dBFS, THD = 87 dBc, HD2 = 94 dBc, HD3 = 92 dBc

**Figure 101. FFT for 10-MHz Input Signal (Chopper On, Dither Off)**



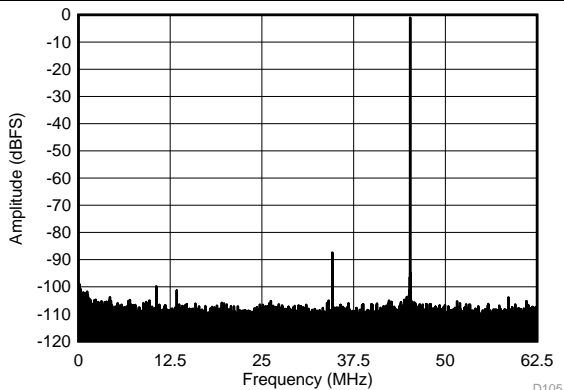
SFDR = 96 dBc, SNR = 72.5 dBFS, SINAD = 72.4 dBFS, THD = 94 dBc, HD2 = 101 dBc, HD3 = 96 dBc

**Figure 102. FFT for 70-MHz Input Signal (Dither On)**



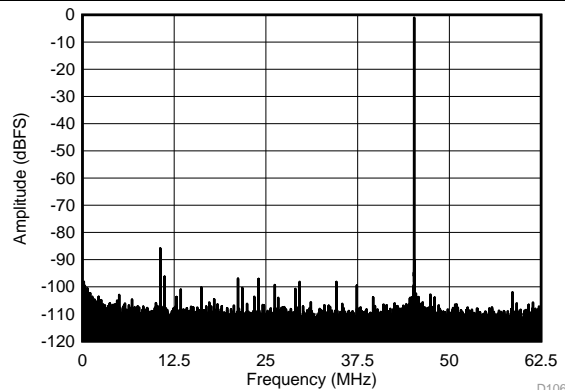
SFDR = 91 dBc, SNR = 73 dBFS, SINAD = 72.8 dBFS, THD = 87 dBc, HD2 = 91 dBc, HD3 = 95 dBc

**Figure 103. FFT for 70-MHz Input Signal (Dither Off)**



SFDR = 86 dBc, SNR = 71.7 dBFS, SINAD = 71.6 dBFS, THD = 93 dBc, HD2 = 86 dBc, HD3 = 99 dBc

**Figure 104. FFT for 170-MHz Input Signal (Dither On)**

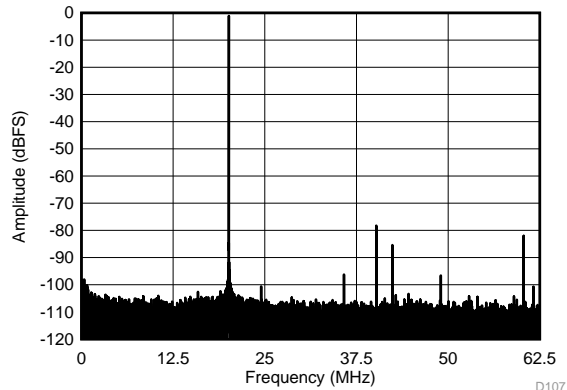


SFDR = 85 dBc, SNR = 72.3 dBFS, SINAD = 72.1 dBFS, THD = 87 dBc, HD2 = 97 dBc, HD3 = 85 dBc

**Figure 105. FFT for 170-MHz Input Signal (Dither Off)**

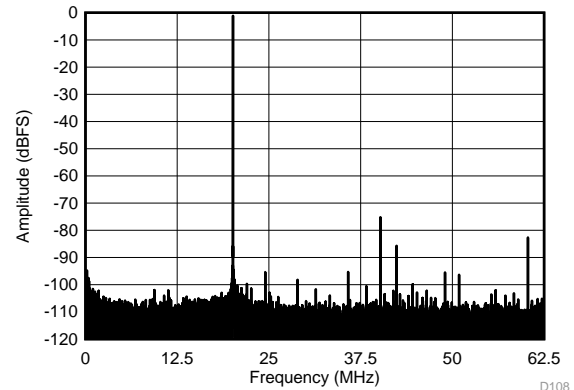
### Typical Characteristics: ADC3444 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 125 MSPS, 50% clock duty cycle,  $AVDD = 1.8\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $-1\text{-dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when chopper is enabled, and dither on (unless otherwise noted)



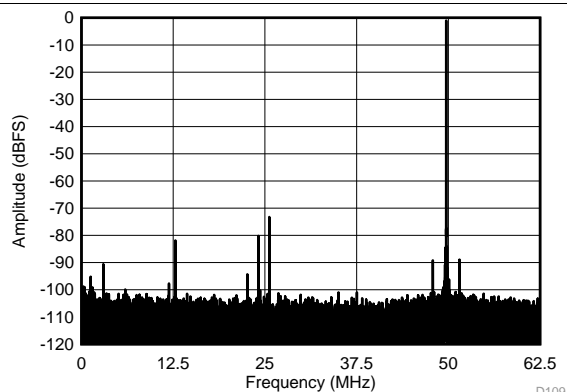
SFDR = 77 dBc, SNR = 70.4 dBFS, SINAD = 69.6 dBFS, THD = 75 dBc, HD2 = 77 dBc, HD3 = 81 dBc

Figure 106. FFT for 270-MHz Input Signal (Dither On)



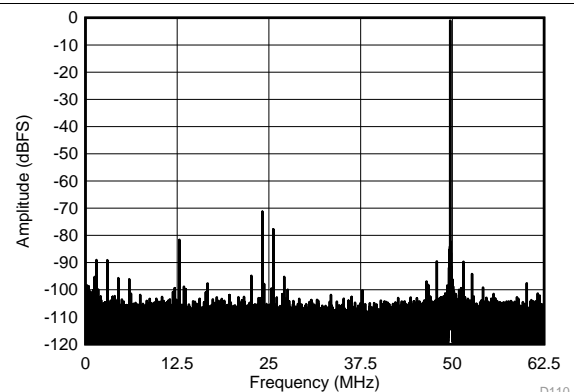
SFDR = 74 dBc, SNR = 71 dBFS, SINAD = 70.1 dBFS, THD = 75 dBc, HD2 = 76 dBc, HD3 = 82 dBc

Figure 107. FFT for 270-MHz Input Signal (Dither Off)



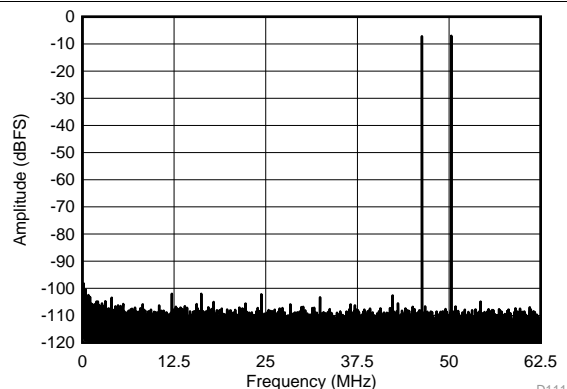
SFDR = 72 dBc, SNR = 68.2 dBFS, SINAD = 67.3 dBFS, THD = 74 dBc, HD2 = 72 dBc, HD3 = 79 dBc

Figure 108. FFT for 450-MHz Input Signal (Dither On)



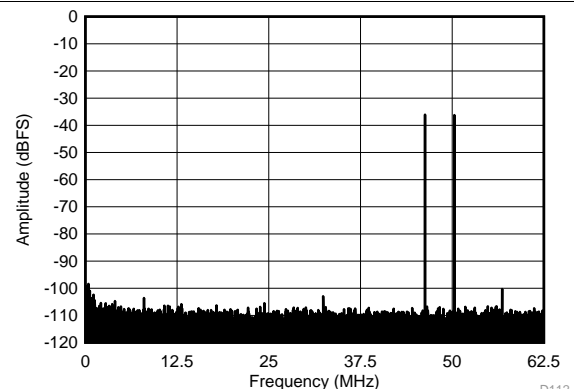
SFDR = 70 dBc, SNR = 68.9 dBFS, SINAD = 67.6 dBFS, THD = 73 dBc, HD2 = 77 dBc, HD3 = 70 dBc

Figure 109. FFT for 450-MHz Input Signal (Dither Off)



$f_{IN1} = 46\text{ MHz}$ ,  $f_{IN2} = 50\text{ MHz}$ , IMD3 = 102 dBFS, each tone at  $-7\text{ dBFS}$

Figure 110. FFT for Two-Tone Input Signal ( $-7\text{ dBFS}$  at 46 MHz and 50 MHz)



$f_{IN1} = 46\text{ MHz}$ ,  $f_{IN2} = 50\text{ MHz}$ , IMD3 = 100 dBFS, each tone at  $-36\text{ dBFS}$

Figure 111. FFT for Two-Tone Input Signal ( $-36\text{ dBFS}$  at 46 MHz and 50 MHz)

Typical Characteristics: ADC3444 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 125 MSPS, 50% clock duty cycle,  $AVDD = 1.8\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $-1\text{ dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

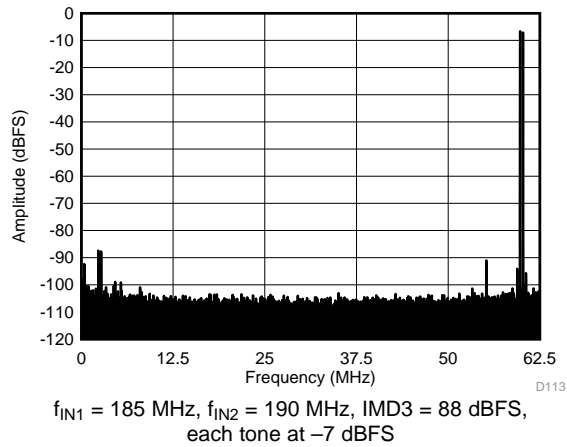


Figure 112. FFT for Two-Tone Input Signal  
( $-7\text{ dBFS}$  at 185 MHz and 190 MHz)

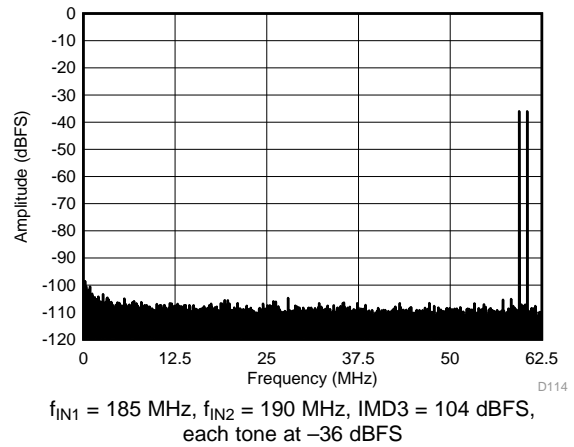


Figure 113. FFT for Two-Tone Input Signal  
( $-36\text{ dBFS}$  at 185 MHz and 190 MHz)

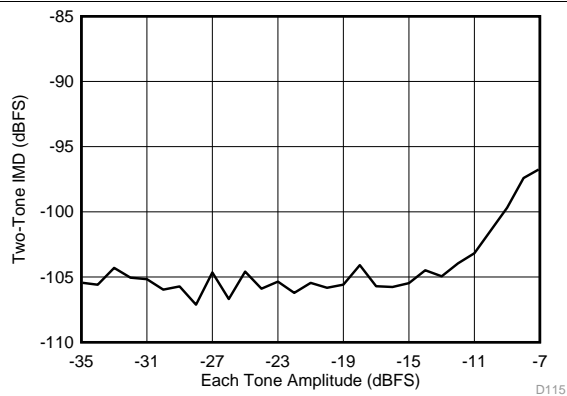


Figure 114. Intermodulation Distortion vs Input Amplitude  
(46 MHz and 50 MHz)

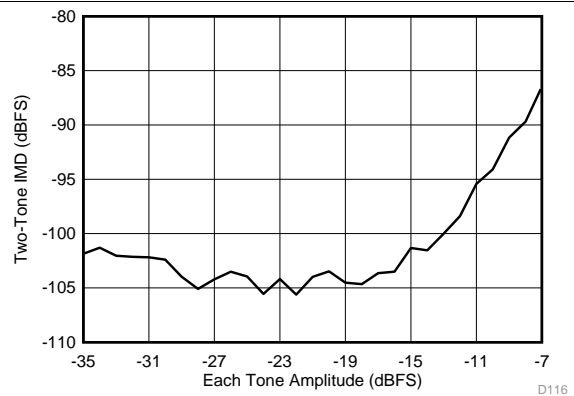


Figure 115. Intermodulation Distortion vs Input Amplitude  
(185 MHz and 190 MHz)

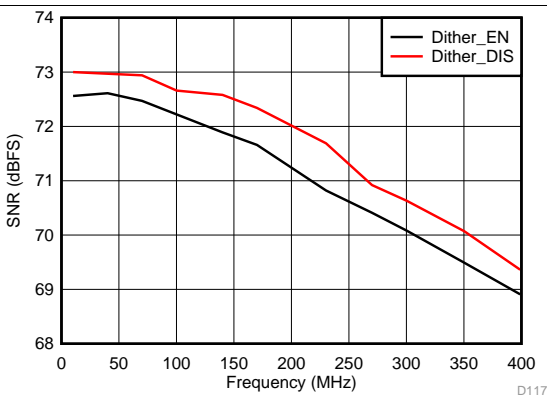


Figure 116. Signal-to-Noise Ratio vs Input Frequency

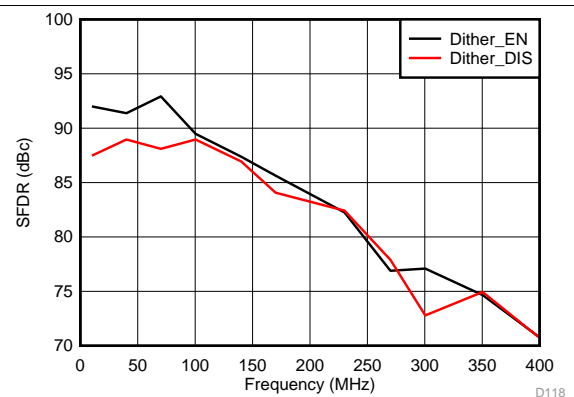
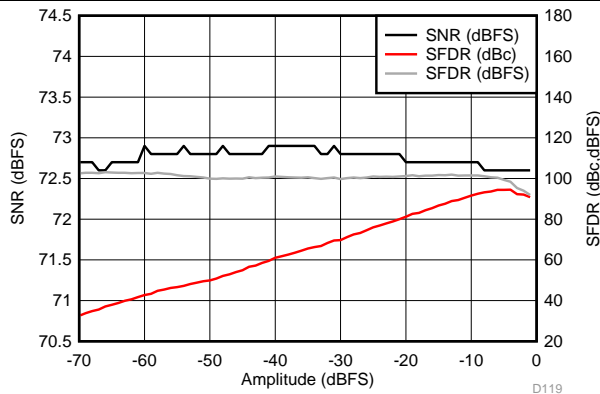


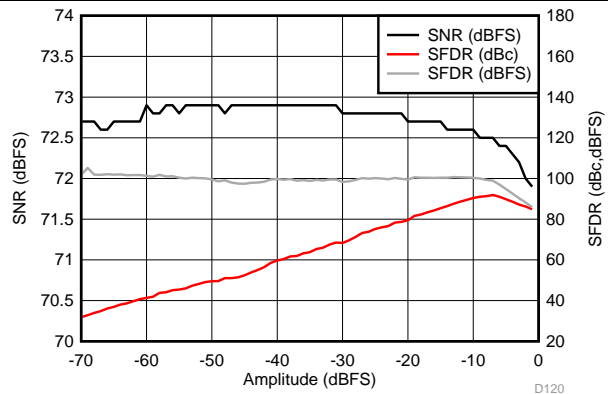
Figure 117. Spurious-Free Dynamic Range vs  
Input Frequency

**Typical Characteristics: ADC3444 (continued)**

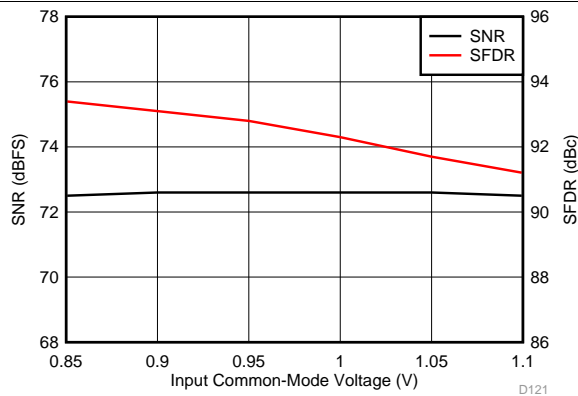
typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 125 MSPS, 50% clock duty cycle,  $AVDD = 1.8\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $-1\text{ dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)



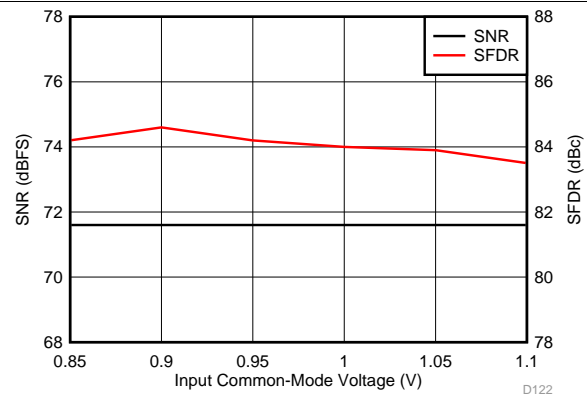
**Figure 118. Performance vs Input Amplitude (30 MHz)**



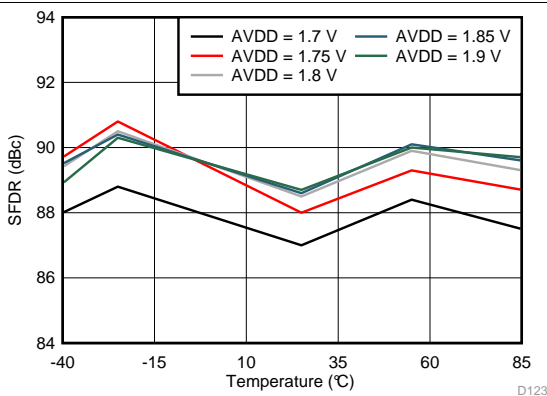
**Figure 119. Performance vs Input Amplitude (170 MHz)**



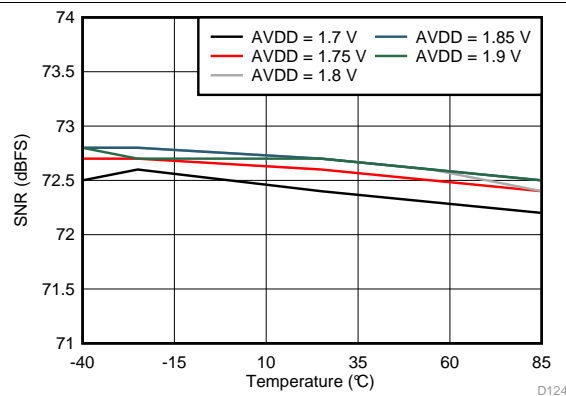
**Figure 120. Performance vs Input Common-Mode Voltage (30 MHz)**



**Figure 121. Performance vs Input Common-Mode Voltage (170 MHz)**



**Figure 122. Spurious-Free Dynamic Range vs AVDD Supply and Temperature (170 MHz)**



**Figure 123. Signal-to-Noise Ratio vs AVDD Supply and Temperature (170 MHz)**



Typical Characteristics: ADC3444 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 125 MSPS, 50% clock duty cycle, AVDD = 1.8 V, DVDD = 1.8 V, -1-dBFS differential input,  $2 \cdot V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

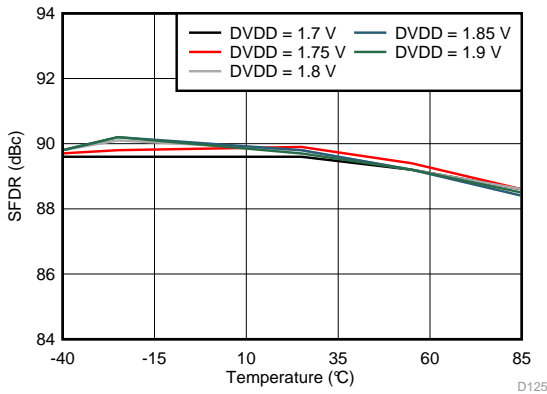


Figure 124. Spurious-Free Dynamic Range vs DVDD Supply and Temperature (170 MHz)

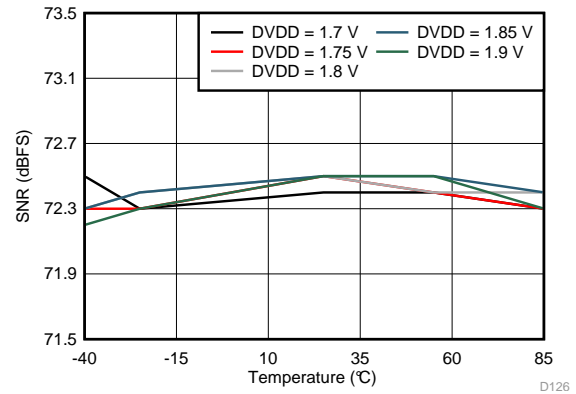


Figure 125. Signal-to-Noise Ratio vs DVDD Supply and Temperature (170 MHz)

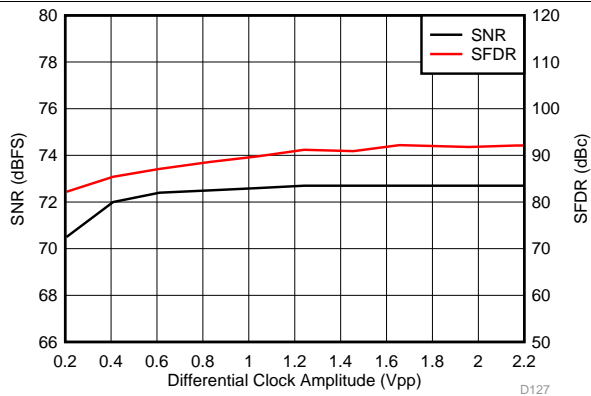


Figure 126. Performance vs Clock Amplitude (40 MHz)

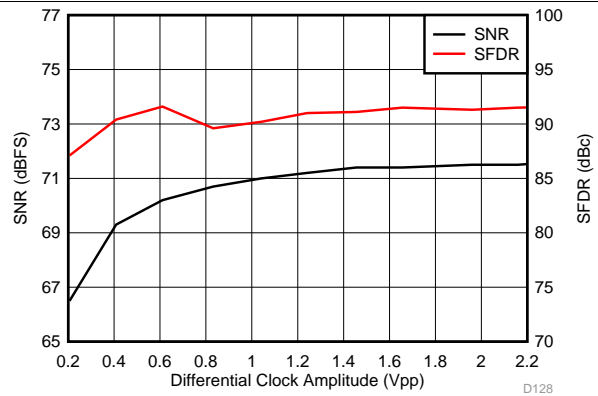


Figure 127. Performance vs Clock Amplitude (150 MHz)

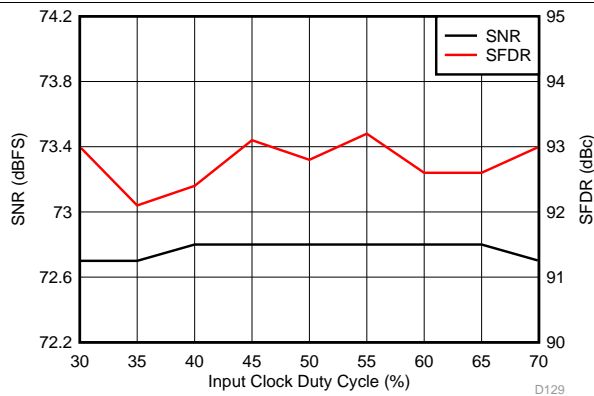


Figure 128. Performance vs Clock Duty Cycle (30 MHz)

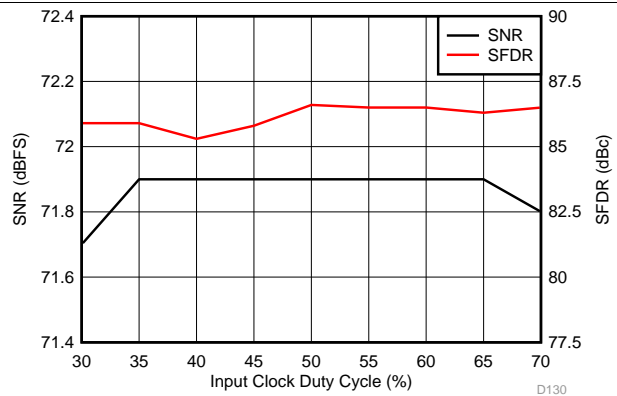


Figure 129. Performance vs Clock Duty Cycle (150 MHz)

### Typical Characteristics: ADC3444 (continued)

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 125 MSPS, 50% clock duty cycle,  $AV_{DD} = 1.8\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $-1\text{-dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)

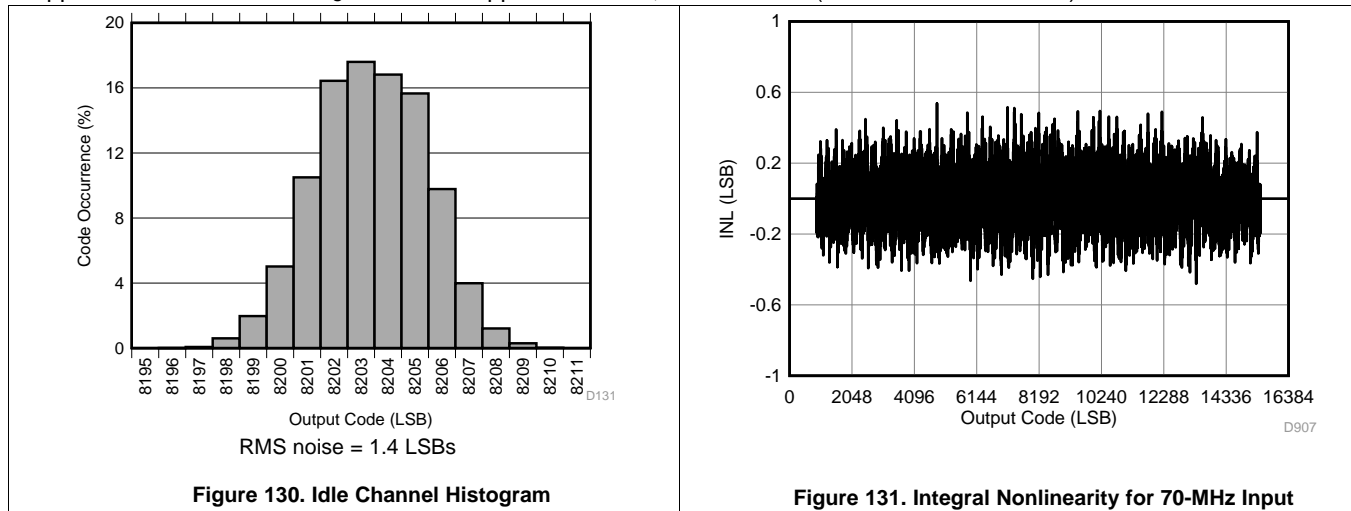


Figure 130. Idle Channel Histogram

Figure 131. Integral Nonlinearity for 70-MHz Input

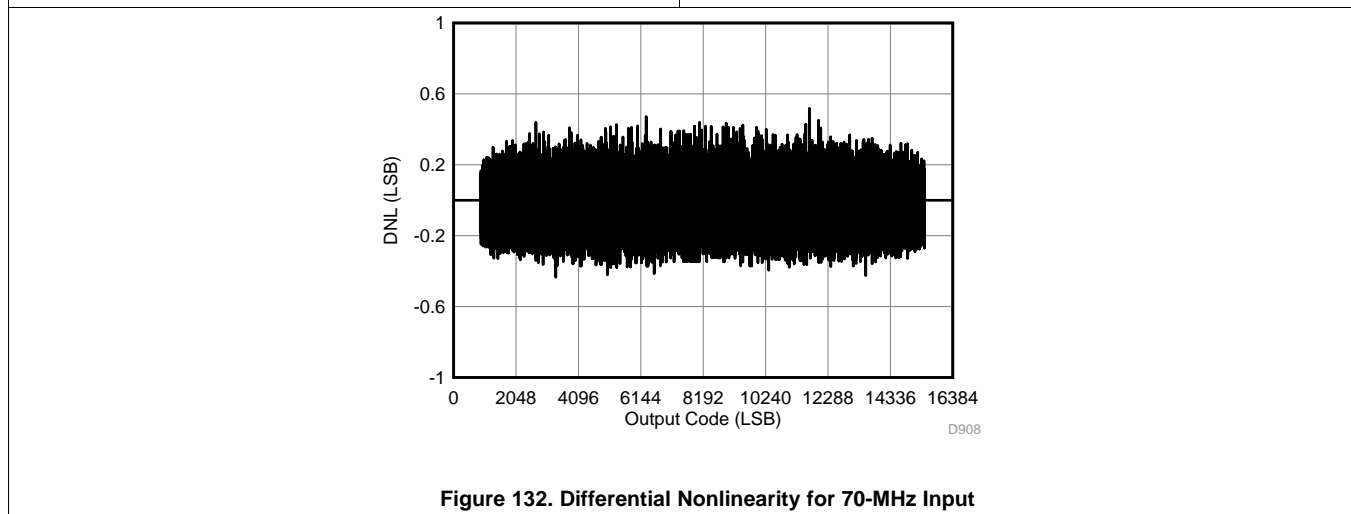
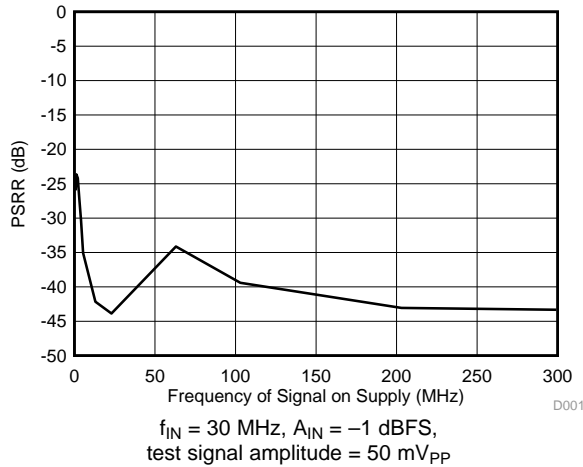


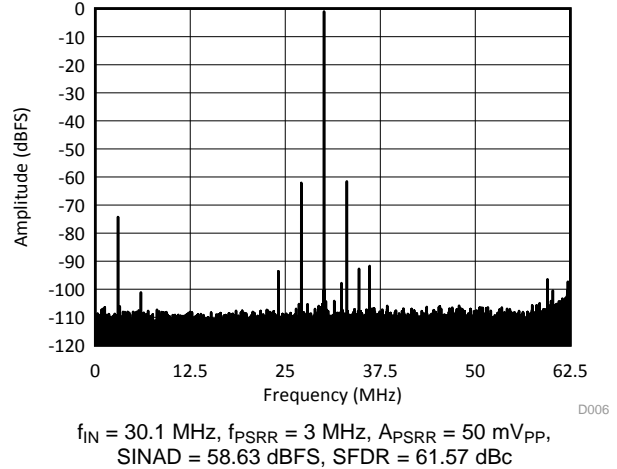
Figure 132. Differential Nonlinearity for 70-MHz Input

### 7.19 Typical Characteristics: Common

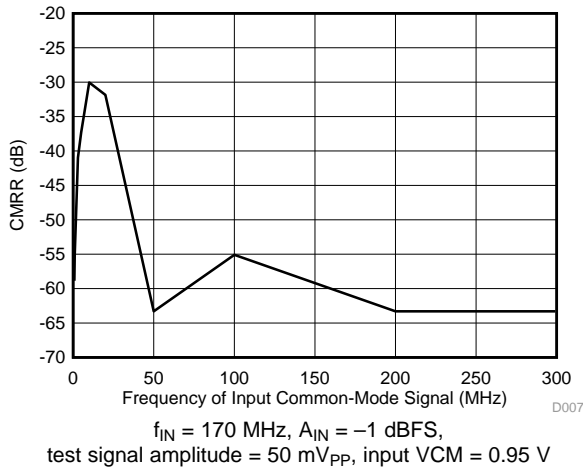
typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 125 MSPS, 50% clock duty cycle,  $AVDD = 1.8\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $-1\text{ dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_S / 2$  when chopper is enabled, and dither on (unless otherwise noted)



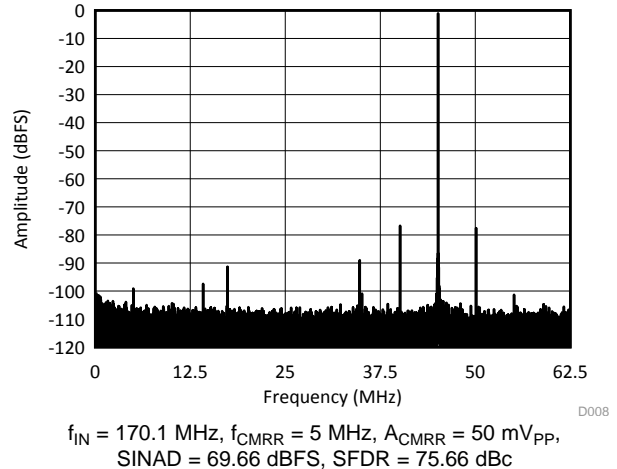
**Figure 133. Power-Supply Rejection Ratio vs Test Signal Frequency**



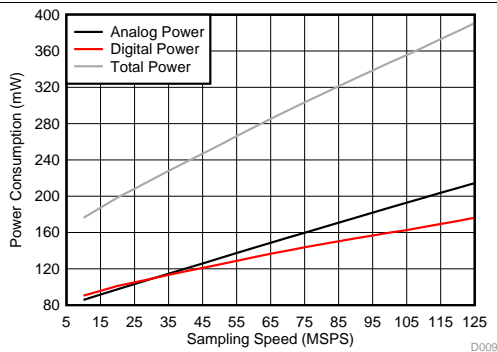
**Figure 134. Power-Supply Rejection Ratio Spectrum (Chopper On)**



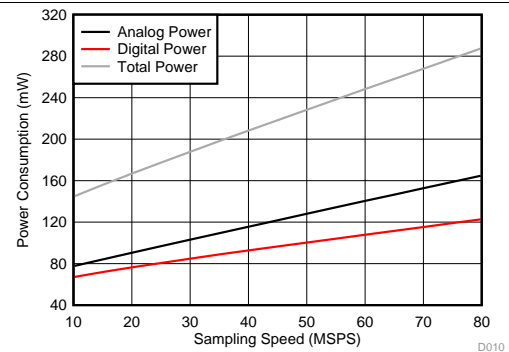
**Figure 135. Common-Mode Rejection Ratio vs Test Signal Frequency**



**Figure 136. Common-Mode Rejection Ratio Spectrum (Chopper On)**



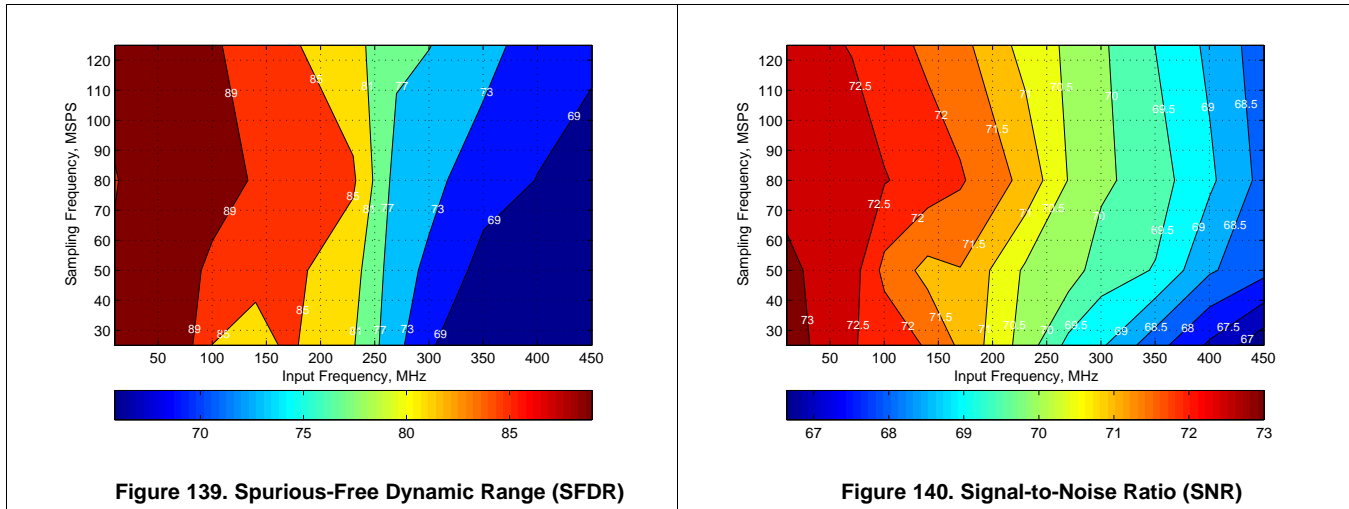
**Figure 137. Power vs Sampling Frequency (Two-Wire Mode)**



**Figure 138. Power vs Sampling Frequency (One-Wire Mode)**

## 7.20 Typical Characteristics: Contour

typical values are at  $T_A = 25^\circ\text{C}$ , ADC sampling rate = 125 MSPS, 50% clock duty cycle,  $AV_{DD} = 1.8\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $-1\text{ dBFS}$  differential input,  $2\text{-}V_{PP}$  full-scale, 32k-point FFT, chopper disabled, SNR reported with a 1-MHz offset from dc when chopper is disabled and from  $f_s / 2$  when is chopper enabled, and dither on (unless otherwise noted)



## 8 Parameter Measurement Information

### 8.1 Timing Diagrams

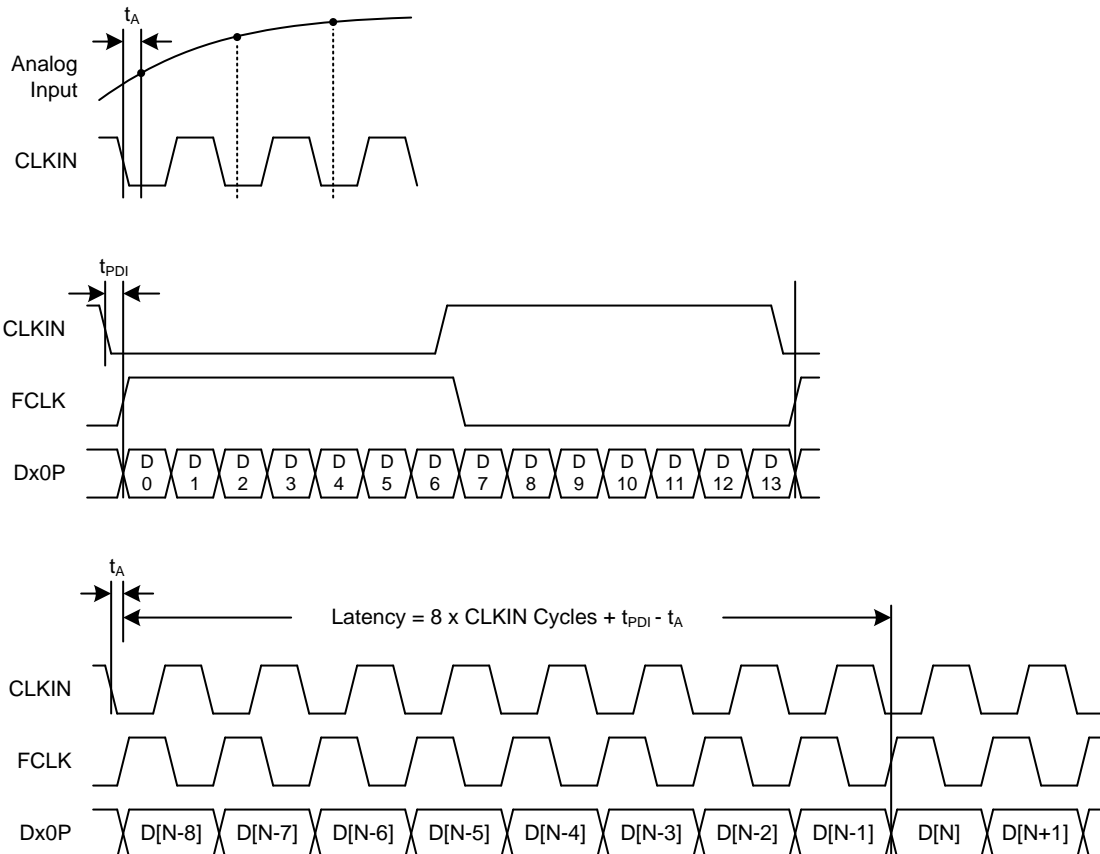
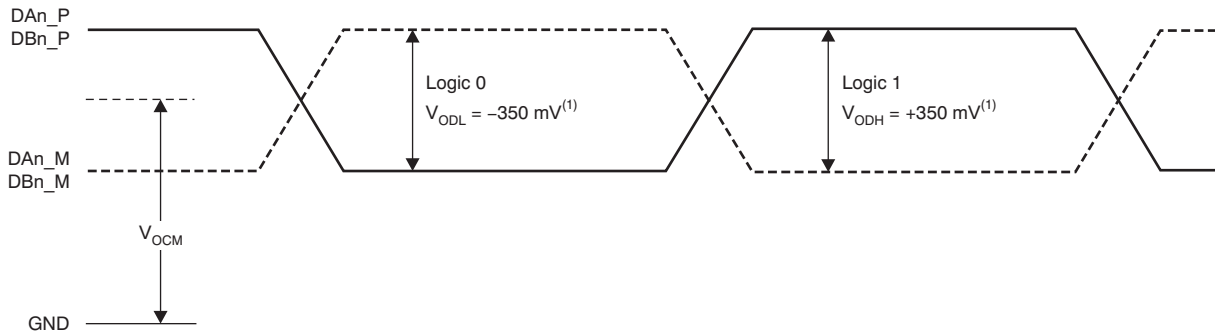


Figure 141. Latency Timing Diagram

Timing Diagrams (continued)



(1) With an external 100-Ω termination.

Figure 142. Serial LVDS Output Voltage Levels

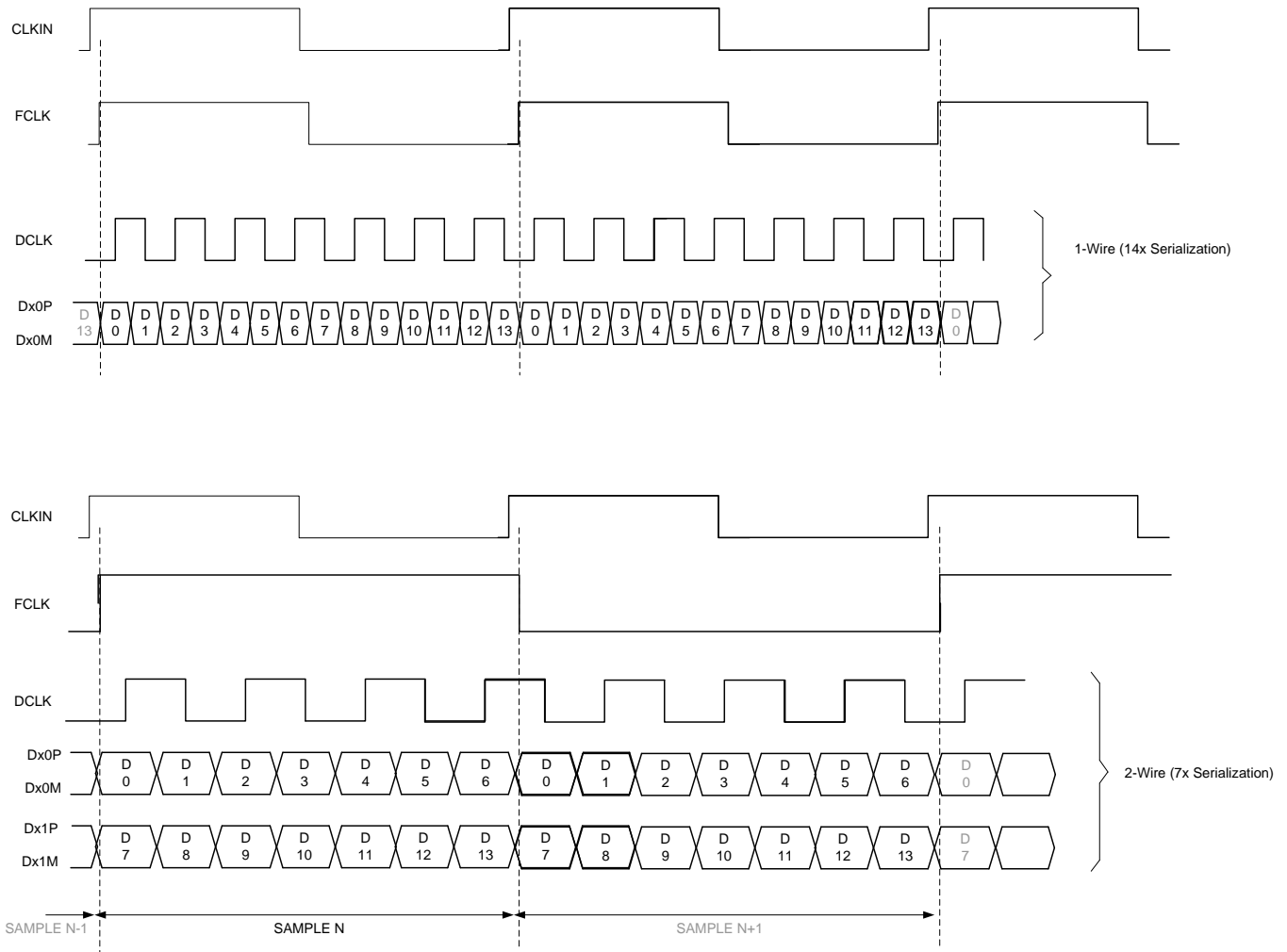
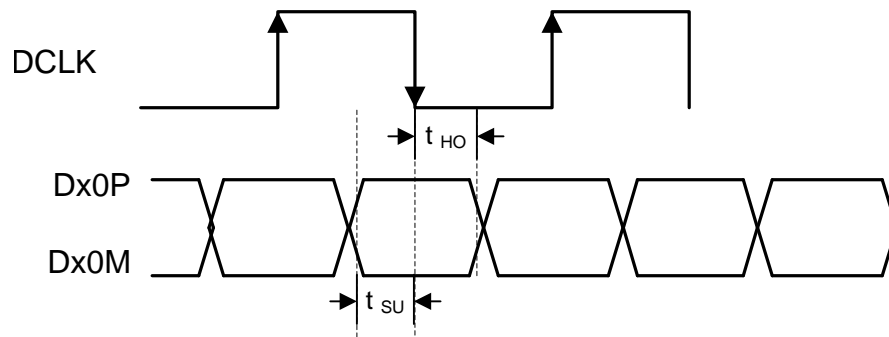


Figure 143. Output Timing Diagram

**Timing Diagrams (continued)**



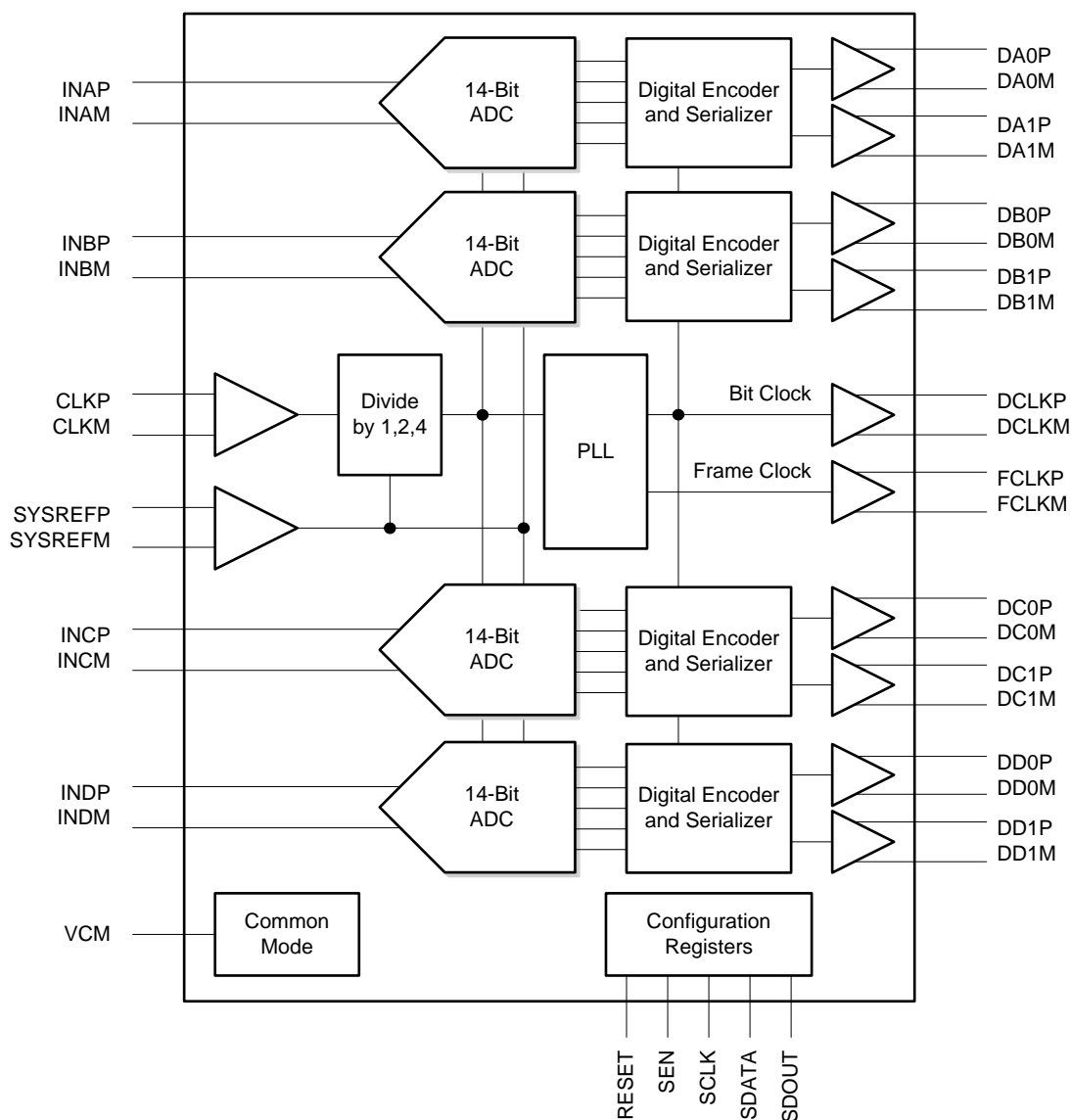
**Figure 144. Setup and Hold Time**

## 9 Detailed Description

### 9.1 Overview

The ADC344x devices are a high-linearity, ultra-low power, quad-channel, 14-bit, 25-MSPS to 125-MSPS, analog-to-digital converter (ADC) family. The devices are designed specifically to support demanding, high input frequency signals with large dynamic range requirements. An input clock divider allows more flexibility for system clock architecture design while the SYSREF input enables complete system synchronization. The ADC344x family supports serial LVDS interface in order to reduce the number of interface lines, thus allowing for high system integration density. The serial LVDS interface is two-wire, where each ADC data are serialized and output over two LVDS pairs. An internal phase-locked loop (PLL) multiplies the incoming ADC sampling clock to derive the bit clock that is used to serialize the 14-bit output data from each channel. In addition to the serial data streams, the frame and bit clocks are also transmitted as LVDS outputs.

### 9.2 Functional Block Diagram



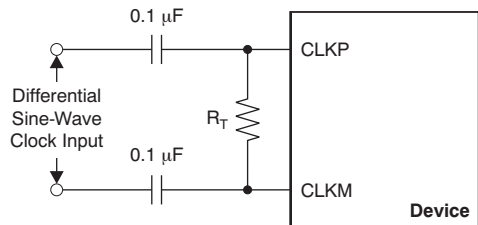
## 9.3 Feature Description

### 9.3.1 Analog Inputs

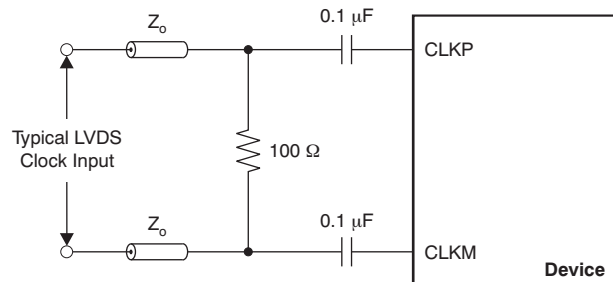
The ADC344x analog signal inputs are designed to be driven differentially. Each input pin (INP, INM) must swing symmetrically between  $(V_{CM} + 0.5\text{ V})$  and  $(V_{CM} - 0.5\text{ V})$ , resulting in a  $2\text{-}V_{PP}$  (default) differential input swing. The input sampling circuit has a 3-dB bandwidth that extends up to 540 MHz (50- $\Omega$  source driving 50- $\Omega$  termination between INP and INM).

### 9.3.2 Clock Input

The device clock inputs may be driven differentially (sine, LVPECL, or LVDS) or single-ended (LVCMOS), with little or no difference in performance between them. The common-mode voltage of the clock inputs is set to 0.95 V using internal 5-k $\Omega$  resistors. The ADC344x self-bias clock inputs may be driven by the transformer-coupled, sine-wave clock source or by the ac-coupled, LVPECL and LVDS clock sources, as shown in Figure 145, Figure 146, and Figure 147. See Figure 148 for details regarding the internal clock buffer.

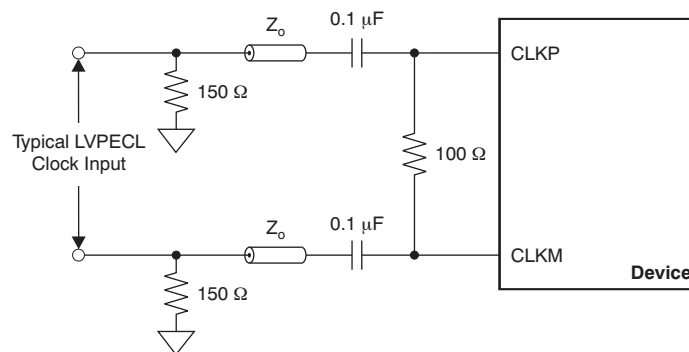


NOTE:  $R_T$  = termination resistor, if necessary.



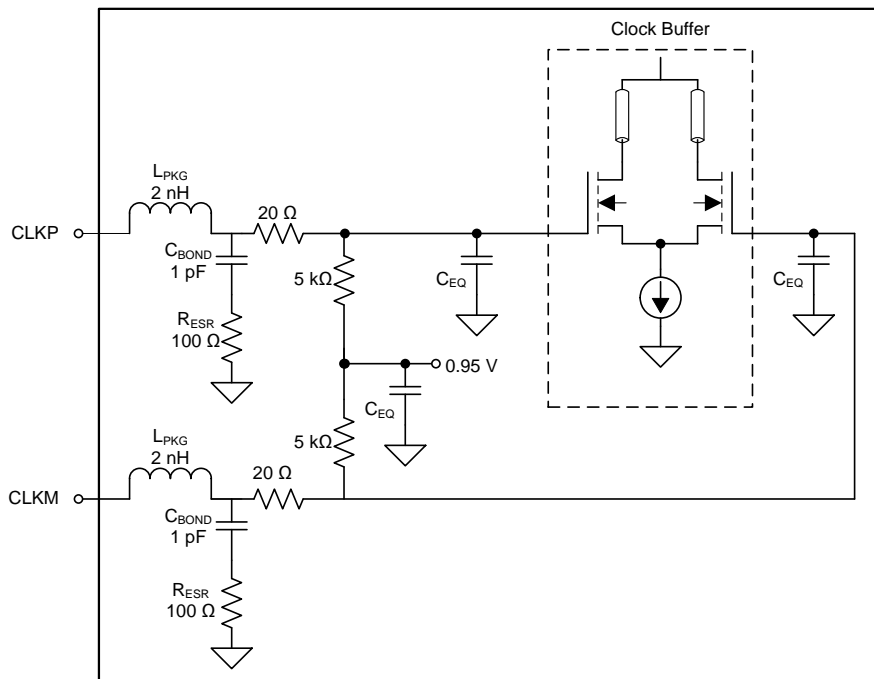
**Figure 145. Differential Sine-Wave Clock Driving Circuit**

**Figure 146. LVDS Clock Driving Circuit**



**Figure 147. LVPECL Clock Driving Circuit**

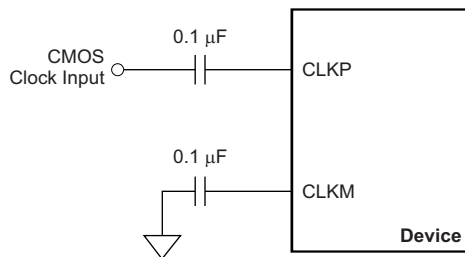




NOTE:  $C_{EQ}$  is 1 pF to 3 pF and is the equivalent input capacitance of the clock buffer.

**Figure 148. Internal Clock Buffer**

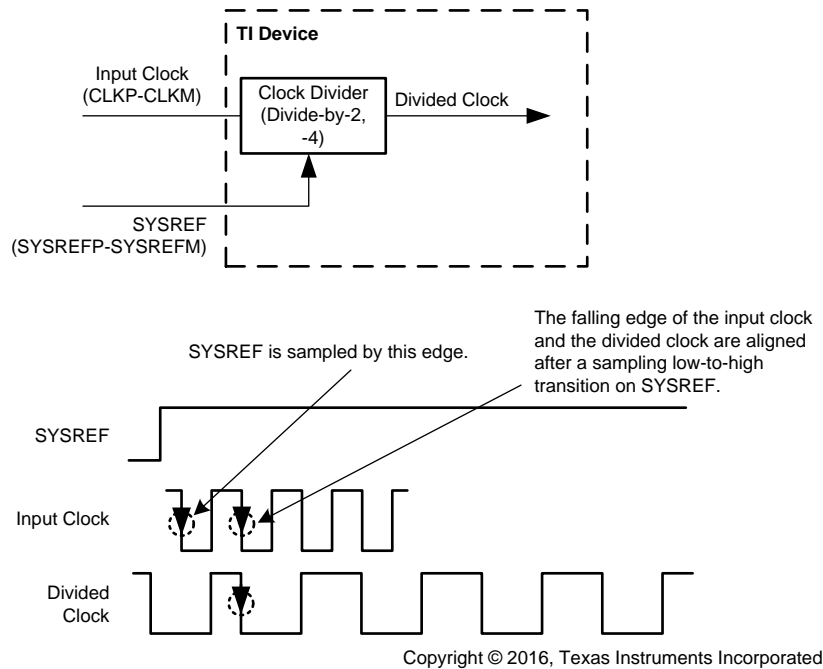
A single-ended CMOS clock may be ac-coupled to the CLKP input, with CLKM connected to ground with a 0.1- $\mu$ F capacitor, as shown in Figure 149. However, for best performance the clock inputs must be driven differentially, thereby reducing susceptibility to common-mode noise. For high input frequency sampling, TI recommends using a clock source with low jitter. Band-pass filtering of the clock source may help reduce the effects of jitter. There is no change in performance with a non-50% duty cycle clock input.



**Figure 149. Single-Ended Clock Driving Circuit**

### 9.3.2.1 Using the SYSREF Input

The ADC344x has a SYSREF input pin that can be used when the clock-divider feature is used. A logic low-to-high transition on the SYSREF pin aligns the falling edge of the divided clock with the next falling edge of the input clock, essentially resetting the phase of the divided clock, as shown in [Figure 150](#). When multiple ADC344x devices are onboard and the clock divider option is used, the phase of the divided clock among the devices may not be the same. The phase of the divided clock in each device can be synchronized to the common sampling clock by using the SYSREF pins. SYSREF can be applied as mono-shot or periodic waveform. When applied as periodic waveform, its period must be an integer multiple of the period of the divided clock. When not used, the SYSREFP and SYSREFM pins can be connected to AVDD and GND, respectively. Alternatively, the SYSREF buffer inside the device can be powered down using the PDN SYSREF register bit.



**Figure 150. Using SYSREF for Synchronization**

### 9.3.2.2 SNR and Clock Jitter

The signal-to-noise ratio of the ADC is limited by three different factors, as shown in [Equation 1](#). Quantization noise (typically 86 dB for a 14-bit ADC) and thermal noise limit SNR at low input frequencies while the clock jitter sets SNR for higher input frequencies.

$$SNR_{ADC}[dBc] = -20 \cdot \log \sqrt{\left(10^{\frac{SNR_{Quantization\ Noise}}{20}}\right)^2 + \left(10^{\frac{SNR_{Thermal\ Noise}}{20}}\right)^2 + \left(10^{\frac{SNR_{Jitter}}{20}}\right)^2} \quad (1)$$

The SNR limitation resulting from sample clock jitter may be calculated with [Equation 2](#).

$$SNR_{Jitter}[dBc] = -20 \cdot \log(2\pi \cdot f_{in} \cdot T_{Jitter}) \quad (2)$$

The total clock jitter ( $T_{Jitter}$ ) has two components: the internal aperture jitter (130 fs for the device) which is set by the noise of the clock input buffer and the external clock.  $T_{Jitter}$  may be calculated with [Equation 3](#).

$$T_{Jitter} = \sqrt{(T_{Jitter,Ext.Clock\_Input})^2 + (T_{Aperture\_ADC})^2} \quad (3)$$

External clock jitter may be minimized by using high-quality clock sources and jitter cleaners as well as band-pass filters at the clock input while a faster clock slew rate improves the ADC aperture jitter. The devices have a typical thermal noise of 72.7 dBFS and internal aperture jitter of 130 fs. The SNR, depending on the amount of external jitter for different input frequencies, is shown in Figure 151.

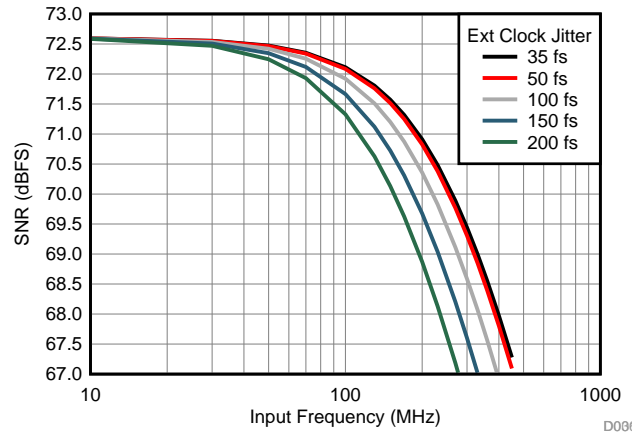


Figure 151. SNR vs Frequency for Different Clock Jitter

### 9.3.3 Digital Output Interface

The devices offer two different output format options, thus making interfacing to a field-programmable gate array (FPGA) or an application-specific integrated circuit (ASIC) easy. Each option may be easily programmed using the serial interface, as shown in Table 3. The output interface options are:

- One-wire, 1x frame clock, 14x serialization with the DDR bit clock
- Two-wire, 1x frame clock, 7x serialization with the DDR bit clock.

Table 3. Interface Rates

INTERFACE OPTIONS	SERIALIZATION	RECOMMENDED SAMPLING FREQUENCY (MSPS)		BIT CLOCK FREQUENCY (MHz)	FRAME CLOCK FREQUENCY (MHz)	SERIAL DATA RATE (Mbps)
		MINIMUM	MAXIMUM			
1-wire	14x	15 <sup>(1)</sup>	—	105	15	210
		—	80	560	80	1120
2-wire (default after reset)	7x	20 <sup>(1)</sup>	—	70	10	140
		—	125	437.5	62.5	875

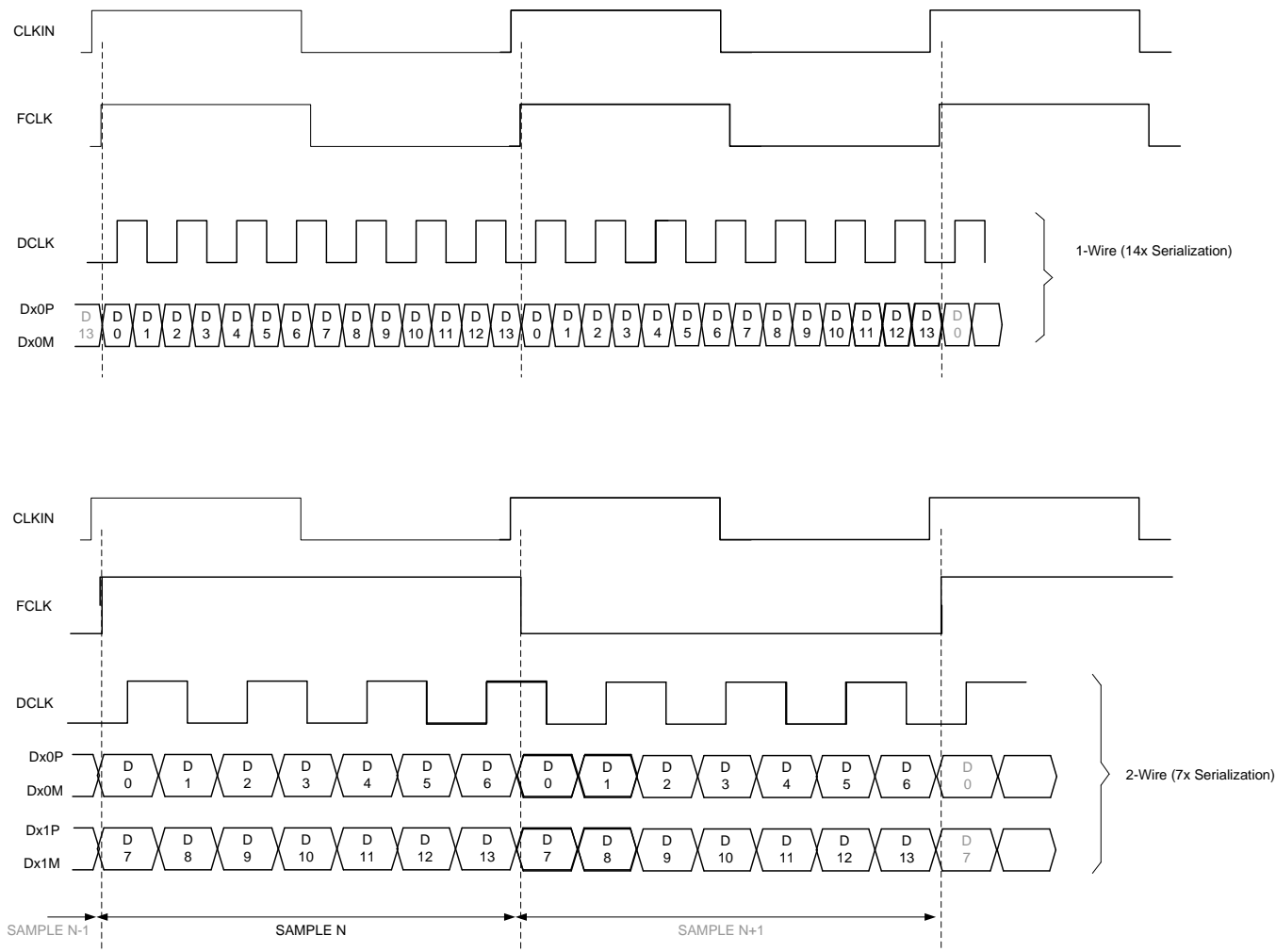
(1) Use the LOW SPEED ENABLE register bits for low speed operation; see Table 20.

### 9.3.3.1 One-Wire Interface: 14x Serialization

In this interface option, the device outputs the data of each ADC serially on a single LVDS pair (one-wire). The data are available at the rising and falling edges of the bit clock (DDR bit clock). The ADC outputs a new word at the rising edge of every frame clock, starting with the LSB. The data rate is 14x sample frequency (14x serialization).

### 9.3.3.2 Two-Wire Interface: 7x Serialization

The two-wire interface is recommended for sampling frequencies above 65 MSPS. The output data rate is 7x sample frequency because seven data bits are output every clock cycle on each differential pair. Each ADC sample is sent over the two wires with the seven MSBs on Dx1P, Dx1M and the seven LSBs on Dx0P, Dx0M, as shown in Figure 152.



**Figure 152. Output Timing Diagram**

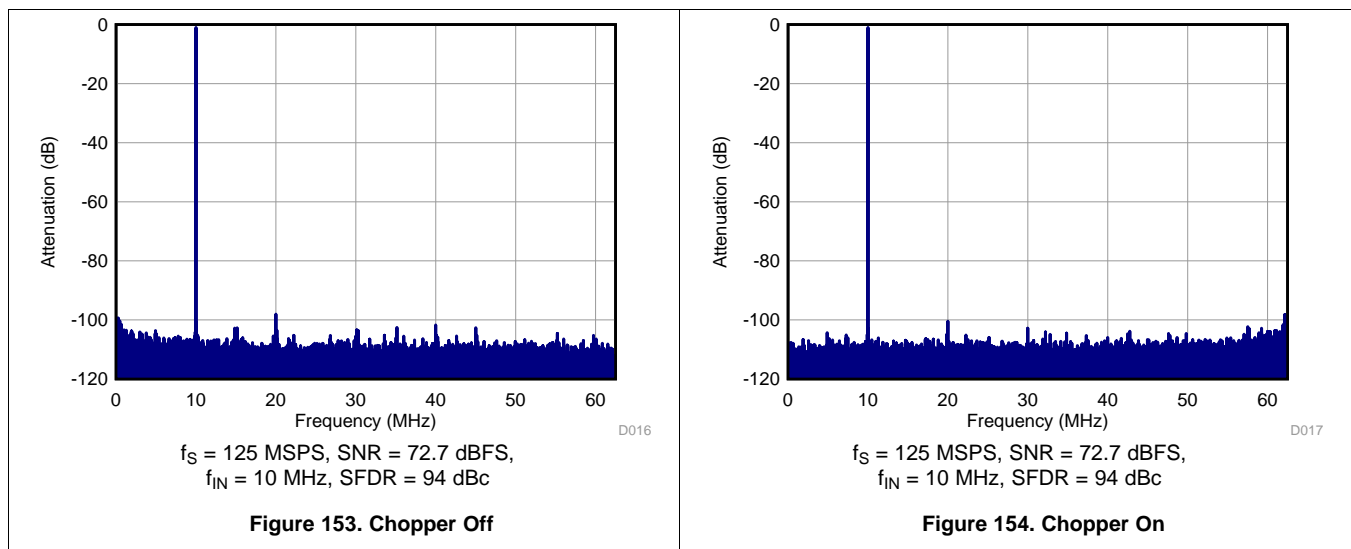
## 9.4 Device Functional Modes

### 9.4.1 Input Clock Divider

The devices are equipped with an internal divider on the clock input. The clock divider allows operation with a faster input clock, thus simplifying the system clock distribution design. The clock divider may be bypassed for operation with a 125-MHz clock while the divide-by-2 option supports a maximum input clock of 250 MHz and the divide-by-4 option provides a maximum input clock frequency of 500 MHz.

### 9.4.2 Chopper Functionality

The devices are equipped with an internal chopper front-end. Enabling the chopper function swaps the ADC noise spectrum by shifting the  $1/f$  noise from dc to  $f_S / 2$ . [Figure 153](#) shows the noise spectrum with the chopper off and [Figure 154](#) shows the noise spectrum with the chopper on. This function is especially useful in applications requiring good ac performance at low input frequencies or in dc-coupled applications. The chopper may be enabled through SPI register writes and is recommended for input frequencies below 30 MHz. The chopper function creates a spur at  $f_S / 2$  that must be filtered out digitally.



### 9.4.3 Power-Down Control

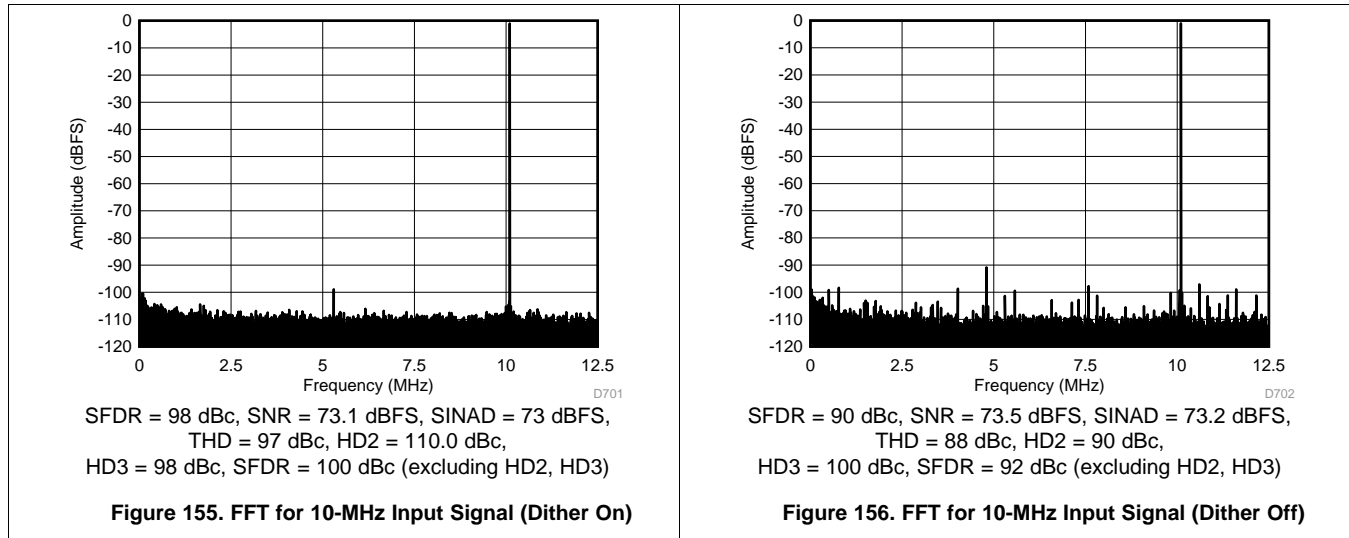
The ADC344x power-down functions may be controlled either through the parallel control pin (PDN) or through an SPI register setting (see [register 15h](#)). The PDN pin may also be configured through SPI to a global power-down or standby functionality, as shown in [Table 4](#).

**Table 4. Power-Down Modes**

FUNCTION	POWER CONSUMPTION (mW)	WAKE-UP TIME ( $\mu$ s)
Global power-down	5	85
Standby	45	35

### 9.4.4 Internal Dither Algorithm

The ADC344x family uses an internal dither algorithm to achieve high SFDR and a clean spectrum. However, the dither algorithm marginally degrades SNR, creating a trade-off between SNR and SFDR. If desired, the dither algorithm may be turned off by using the DIS DITH CHx registers bits. [Figure 155](#) and [Figure 156](#) show the effect of using dither algorithms.



### 9.4.5 Summary of Performance Mode Registers

[Table 5](#) lists the location, value, and functions of performance mode registers in the device.

**Table 5. Performance Modes**

MODE	LOCATION	FUNCTION
Special modes	Registers 139 (bit 3), 239 (bit 3), 439 (bit 3), and 539 (bit 3)	Always write 1 for best performance.
Disable dither	Registers 1 (bits 7-0), 134 (bits 5 and 3), 234 (bits 5 and 3), 434 (bits 5 and 3), and 534 (bits 5 and 3)	Disables the dither to improve SNR.
Disable chopper	Registers 122 (bit 1), 222 (bit 1), 422 (bit 1), and 522 (bit 1)	Disables the chopper (shifts the 1/f noise floor at dc).
High IF modes	Registers 11Dh (bit 1), 21Dh (bit 1), 41Dh (bit 1), 51Dh (bit 1), 308h (bits 7-6) and 608h (bits 7-6)	Improves HD3 by a couple of dB for IF > 100 MHz

## 9.5 Programming

The ADC344x device may be configured using a serial programming interface, as described in this section.

### 9.5.1 Serial Interface

The device has a set of internal registers that may be accessed by the serial interface formed by the SEN (serial interface enable), SCLK (serial interface clock), SDATA (serial interface data), and SDOUT (serial interface data output) pins. Serially shifting bits into the device is enabled when SEN is low. Serial data SDATA are latched at every SCLK rising edge when SEN is active (low). The serial data are loaded into the register at every 24th SCLK rising edge when SEN is low. When the word length exceeds a multiple of 24 bits, the excess bits are ignored. Data may be loaded in multiples of 24-bit words within a single active SEN pulse. The interface may function with SCLK frequencies from 20 MHz down to very low speeds (of a few hertz) and also with a non-50% SCLK duty cycle.

## Programming (continued)

### 9.5.1.1 Register Initialization

After power-up, the internal registers must be initialized to their default values through a hardware reset by applying a high pulse on the RESET pin (of durations greater than 10 ns), as shown in Figure 157. If required, the serial interface registers may be cleared during operation either:

1. Through a hardware reset, or
2. By applying a software reset. When using the serial interface, set the RESET bit (D0 in register address 06h) to high. This setting initializes the internal registers to the default values and then self-resets the RESET bit low. In this case, the RESET pin is kept low.

#### 9.5.1.1.1 Serial Register Write

The device internal register may be programmed with these steps:

1. Drive the SEN pin low,
2. Set the R/W bit to 0 (bit A15 of the 16-bit address),
3. Set bit A14 in the address field to 1,
4. Initiate a serial interface cycle by specifying the address of the register (A13 to A0) whose content must be written, and
5. Write the 8-bit data that are latched in on the SCLK rising edge.

Figure 157 and Table 6 show the timing requirements for the serial register write operation.

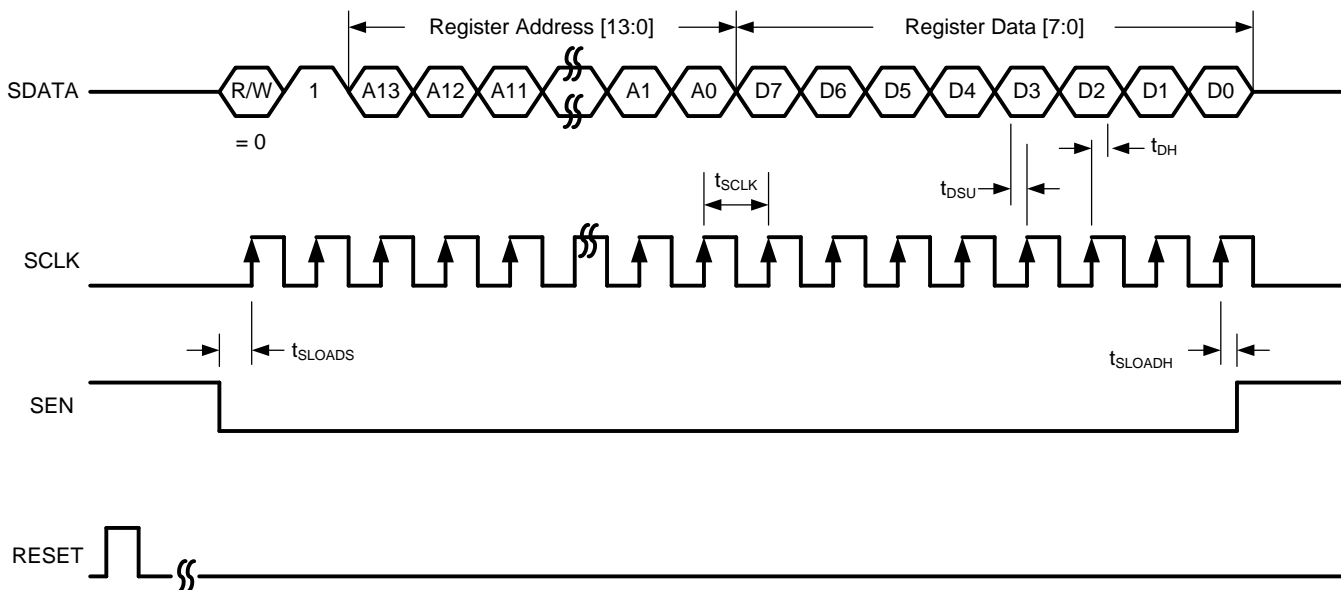


Figure 157. Serial Register Write Timing Diagram

Table 6. Serial Interface Timing<sup>(1)</sup>

		MIN	TYP	MAX	UNIT
$f_{SCLK}$	SCLK frequency (equal to $1 / t_{SCLK}$ )	> DC		20	MHz
$t_{SLOADS}$	SEN to SCLK setup time	25			ns
$t_{SLOADH}$	SCLK to SEN hold time	25			ns
$t_{DSU}$	SDIO setup time	25			ns
$t_{DH}$	SDIO hold time	25			ns

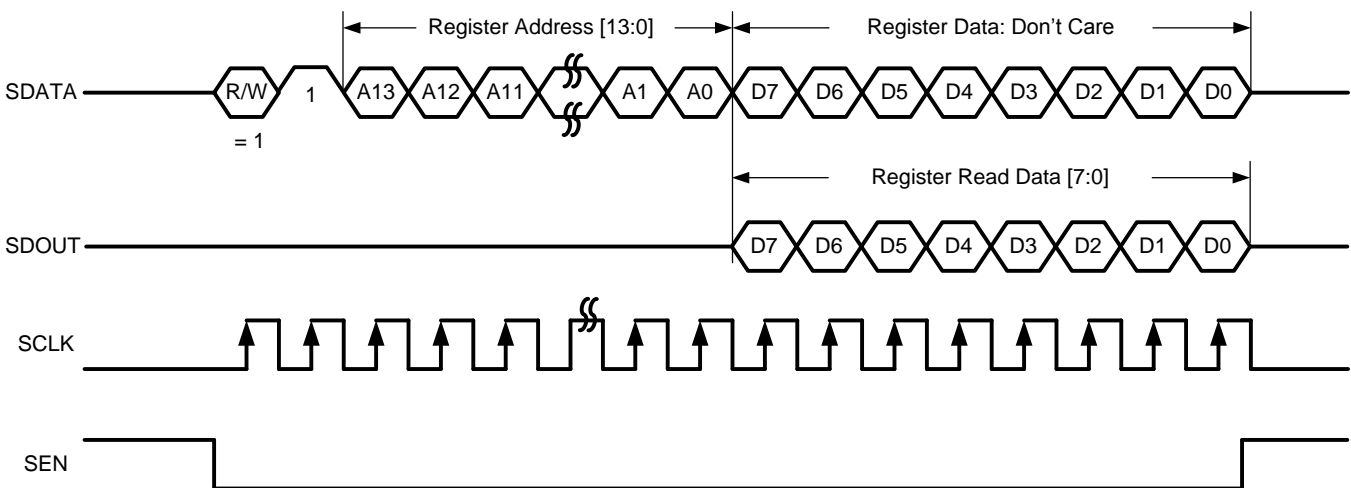
(1) Typical values are at 25°C, full temperature range is from  $T_{MIN} = -40^{\circ}\text{C}$  to  $T_{MAX} = 85^{\circ}\text{C}$ , and  $AVDD = DVDD = 1.8\text{ V}$ , unless otherwise noted.

### 9.5.1.1.2 Serial Register Readout

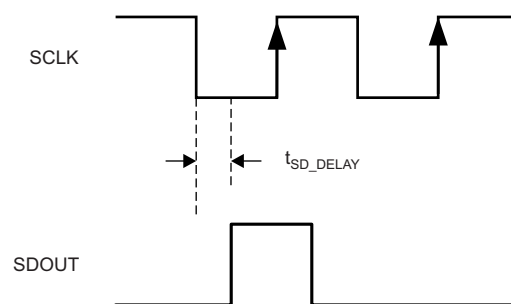
The device includes a mode where the contents of the internal registers may be read back using the SDOUT pin. This readback mode may be useful as a diagnostic check to verify the serial interface communication between the external controller and the ADC. The procedure to read the contents of the serial registers is as follows:

1. Drive the SEN pin low.
2. Set the R/W bit (A15) to 1. This setting disables any further writes to the registers.
3. Set bit A14 in the address field to 1.
4. Initiate a serial interface cycle specifying the address of the register (A13 to A0) whose content must be read.
5. The device outputs the contents (D7 to D0) of the selected register on the SDOUT pin.
6. The external controller may latch the contents at the SCLK rising edge.
7. To enable register writes, reset the R/W register bit to 0.

When READOUT is disabled, the SDOUT pin is in a high-impedance mode. If serial readout is not used, the SDOUT pin must float. [Figure 158](#) shows a timing diagram of the serial register read operation. Data appear on the SDOUT pin at the SCLK falling edge with an approximate delay ( $t_{SD\_DELAY}$ ) of 20 ns, as shown in [Figure 159](#).



**Figure 158. Serial Register Read Timing Diagram**



**Figure 159. SDOUT Timing Diagram**

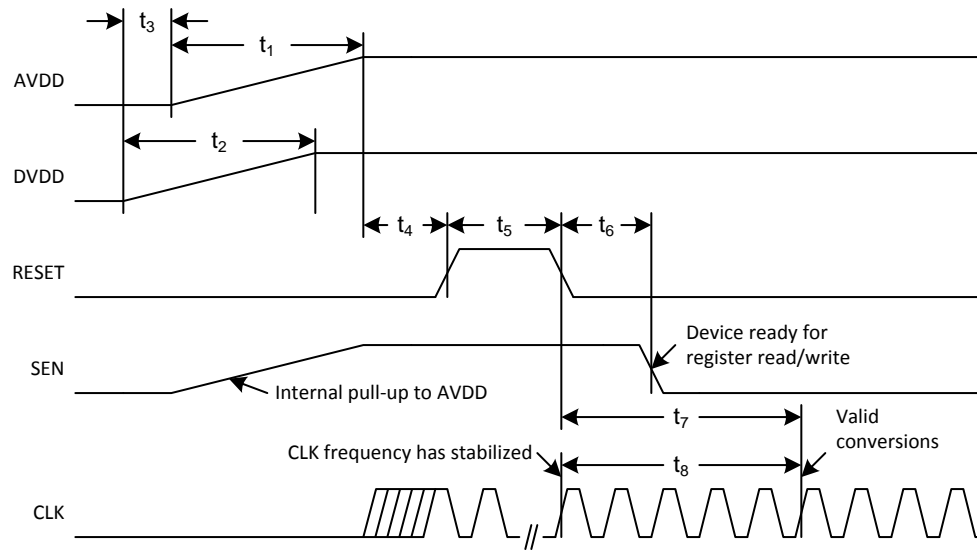


### 9.5.2 ADC3441 Power-Up Requirements

Power-up begins with the application of AVDD and DVDD. The exact sequencing and ramp rate of AVDD and DVDD are not important as long as the parameters in [Table 7](#) are met.

After power-up, the RESET pin must be pulsed high to reset the internal registers to the default values. [Figure 160](#) and [Table 7](#) show a power-up sequence.

During operation, the device registers can be restored to the default values by either pulsing the RESET pin high or by issuing a software reset via the SPI interface. A software reset can be issued by writing bit 0 of register 06h high. This bit is self-clearing.



**Figure 160. Power-Up Timing**

**Table 7. Power-Up Timing Table**

		MIN	NOM	MAX	UNIT
t <sub>1</sub>	AVDD supply power-up ramp time			10	ms
t <sub>2</sub>	DVDD supply power-up ramp time			10	ms
t <sub>3</sub>	AVDD to DVDD power-up delay	-10		10	ms
t <sub>4</sub>	Device power-up to RESET assertion	1			ms
t <sub>5</sub>	RESET assertion duration	10			ns
t <sub>6</sub>	RESET deassertion to SEN assertion	10			µs
t <sub>7</sub>	RESET deassertion to valid conversions	150			µs
t <sub>8</sub>	CLK stable frequency to valid conversions	150			µs

After the power supplies are valid, enable the sample clock. The sampling clock can be enabled before or after reset, but conversions are not valid until at least a minimum time after reset and the time that the sample clock reaches a stable frequency, as shown in [Table 7](#).

Before using samples from the device, a minimum register write sequence must be applied, as described in [Table 8](#). Apply this register write sequence after any further application of the hardware or software reset.

**Table 8. Required Register Writes after Power-up or Reset**

ADDRESS	DATA	NOTE
139h	08h	Channel A - best performance default
439h	08h	Channel B - best performance default
539h	08h	Channel C - best performance default
239h	08h	Channel D - best performance default
137h	40h	ADC core latch reset
437h	40h	
537h	40h	
237h	40h	
137h	00h	
437h	00h	
537h	00h	
237h	00h	

These register writes configure the optimal settings for ADC performance and apply a reset to the internal latches inside the ADC core that are not part of the device reset function. After the register writes of [Table 8](#) are written, any use-case-specific registers must be applied before using the conversion values.

## 9.6 Register Maps

**Table 9. Register Map Summary**

REGISTER ADDRESS, A[13:0] (Hex)	REGISTER DATA							
	7	6	5	4	3	2	1	0
Register 01h	DIS DITH CHA		DIS DITH CHB		DIS DITH CHC		DIS DITH CHD	
Register 03h	0	0	0	0	0	0	0	ODD EVEN
Register 04h	0	0	0	0	0	0	0	FLIP WIRE
Register 05h	0	0	0	0	0	0	0	1W-2W
Register 06h	0	0	0	0	0	0	TEST PATTERN EN	RESET
Register 07h	0	0	0	0	0	0	0	OVR ON LSB
Register 09h	0	0	0	0	0	0	ALIGN TEST PATTERN	DATA FORMAT
Register 0Ah	CHA TEST PATTERN				CHB TEST PATTERN			
Register 0Bh	CHC TEST PATTERN				CHD TEST PATTERN			
Register 13h	0	0	0	0	0	0	LOW SPEED ENABLE	
Register 0Eh	CUSTOM PATTERN[13:6]							
Register 0Fh	CUSTOM PATTERN[5:0]						0	0
Register 15h	CHA PDN	CHB PDN	CHC PDN	CHD PDN	STANDBY	GLOBAL PDN	0	CONFIG PDN PIN
Register 25h	LVDS SWING							
Register 27h	CLK DIV		0	0	0	0	0	0
Register 11Dh	0	0	0	0	0	0	HIGH IF MODE0	0
Register 122h	0	0	0	0	0	0	DIS CHOP CHA	0
Register 134h	0	0	DIS DITH CHA	0	DIS DITH CHA	0	0	0
Register 139h	0	0	0	0	SP1 CHA	0	0	0
Register 21Dh	0	0	0	0	0	0	HIGH IF MODE1	0
Register 222h	0	0	0	0	0	0	DIS CHOP CHD	0
Register 234h	0	0	DIS DITH CHD	0	DIS DITH CHD	0	0	0
Register 239h	0	0	0	0	SP1 CHD	0	0	0
Register 308	HIGH IF MODE <5:4>		0	0	0	0	0	0
Register 41Dh	0	0	0	0	0	0	HIGH IF MODE2	0
Register 422h	0	0	0	0	0	0	DIS CHOP CHB	0
Register 434h	0	0	DIS DITH CHB	0	DIS DITH CHB	0	0	0
Register 439h	0	0	0	0	SP1 CHB	0	0	0
Register 51Dh	0	0	0	0	0	0	HIGH IF MODE3	0
Register 522h	0	0	0	0	0	0	DIS CHOP CHC	0
Register 534h	0	0	DIS DITH CHC	0	DIS DITH CHC	0	0	0
Register 539h	0	0	0	0	SP1 CHC	0	0	0
Register 608h	HIGH IF MODE <7:6>		0	0	0	0	0	0
Register 70Ah	0	0	0	0	0	0	0	PDN SYSREF

## 9.6.1 Serial Register Description

### 9.6.1.1 Register 01h (address = 01h)

**Figure 161. Register 01h**

7	6	5	4	3	2	1	0
DIS DITH CHA		DIS DITH CHB		DIS DITH CHC		DIS DITH CHD	
R/W-0h		R/W-0h		R/W-0h		R/W-0h	

LEGEND: R/W = Read/Write; -n = value after reset

**Table 10. Register 01h Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	DIS DITH CHA	R/W	0h	These bits enable or disable the on-chip dither. Control this bit along with bits 5 and 3 of register 134h. 00 = Default 11 = Dither is disabled for channel A. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
5-4	DIS DITH CHB	R/W	0h	These bits enable or disable the on-chip dither. Control this bit along with bits 5 and 3 of register 434h. 00 = Default 11 = Dither is disabled for channel B. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
3-2	DIS DITH CHC	R/W	0h	These bits enable or disable the on-chip dither. Control this bit along with bits 5 and 3 of register 534h. 00 = Default 11 = Dither is disabled for channel B. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
1-0	DIS DITH CHD	R/W	0h	These bits enable or disable the on-chip dither. Control this bit along with bits 5 and 3 of register 234h. 00 = Default 11 = Dither is disabled for channel B. In this mode, SNR typically improves by 0.5 dB at 70 MHz.

**9.6.1.2 Register 03h (address = 03h)**
**Figure 162. Register 03h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	ODD EVEN
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 11. Register 03h Field Descriptions**

Bit	Field	Type	Reset	Description
7-1	0	W	0h	Must write 0.
0	ODD EVEN	R/W	0h	This bit selects the bit sequence on the output wires (in 2-wire mode only). 0 = Bits 0, 1, 2, and so forth appear on wire-0; bits 7, 8, 9, and so forth appear on wire-1. 1 = Bits 0, 2, 4, and so forth appear on wire-0; bits 1, 3, 5, and so forth appear on wire-1.

**9.6.1.3 Register 04h (address = 04h)**
**Figure 163. Register 04h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	FLIP WIRE
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 12. Register 04h Field Descriptions**

Bit	Field	Type	Reset	Description
7-1	0	W	0h	Must write 0.
0	FLIP WIRE	R/W	0h	This bit flips the data on the output wires. Valid only in two wire configuration. 0 = Default 1 = Data on output wires is flipped. Pin D0x becomes D1x, and vice versa.

**9.6.1.4 Register 05h (address = 05h)**
**Figure 164. Register 05h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	1W-2W
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 13. Register 05h Field Descriptions**

Bit	Field	Type	Reset	Description
7-1	0	W	0h	Must write 0.
0	1W-2W	R/W	0h	This bit transmits output data on either one or two wires. 0 = Output data are transmitted on two wires (Dx0P, Dx0M and Dx1P, Dx1M) 1 = Output data are transmitted on one wire (Dx0P, Dx0M). In this mode, the recommended $f_s$ is less than 80 MSPS.

**9.6.1.5 Register 06h (address = 06h)**
**Figure 165. Register 06h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	TEST PATTERN EN	RESET
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	R/W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 14. Register 06h Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	TEST PATTERN EN	R/W	0h	Enables test pattern selection for the digital outputs. 0 = Normal output 1 = Test pattern output enabled
0	RESET	R/W	0h	Software reset applied. This bit resets all internal registers to the default values and self-clears to 0.

**9.6.1.6 Register 07h (address = 07h)**
**Figure 166. Register 07h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	OVR ON LSB
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 15. Register 07h Field Descriptions**

Bit	Field	Type	Reset	Description
7-1	0	W	0h	Must write 0.
0	OVR ON LSB	R/W	0h	OVR information on the LSB bits. 0 = Output data bit 0 functions as the LSB of the 14-bit data 1 = Output data bit 0 carries the overrange (OVR) information.

**9.6.1.7 Register 09h (address = 09h)**
**Figure 167. Register 09h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	ALIGN TEST PATTERN	DATA FORMAT
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	R/W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 16. Register 09h Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	ALIGN TEST PATTERN	R/W	0h	This bit aligns the test patterns across the outputs of both channels. 0 = Test patterns of both channels are free running 1 = Test patterns of both channels are aligned
0	DATA FORMAT	R/W	0h	Digital output data format. 0 = Twos complement 1 = Offset binary

**9.6.1.8 Register 0Ah (address = 0Ah)**
**Figure 168. Register 0Ah**

7	6	5	4	3	2	1	0
CHA TEST PATTERN				CHB TEST PATTERN			
R/W-0h				R/W-0h			

LEGEND: R/W = Read/Write; -n = value after reset

**Table 17. Register 0Ah Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	CHA TEST PATTERN	R/W	0h	These bits control the test pattern for channel A after the TEST PATTERN EN bit is set. 0000 = Normal operation 0001 = All 0's 0010 = All 1's 0011 = Toggle pattern: data alternate between 101010101010 and 010101010101 0100 = Digital ramp: data increment by 1 LSB every clock cycle from code 0 to 16383 0101 = Custom pattern: output data are the same as programmed by the CUSTOM PATTERN register bits 0110 = Deskew pattern: data are 2AAAh 1000 = PRBS pattern: data are a sequence of pseudo random numbers 1001 = 8-point sine-wave: data are a repetitive sequence of the following eight numbers that form a sine-wave: 0, 2399, 8192, 13984, 16383, 13984, 8192, 2399. Others = Do not use
3-0	CHB TEST PATTERN	R/W	0h	These bits control the test pattern for channel B after the TEST PATTERN EN bit is set. 0000 = Normal operation 0001 = All 0's 0010 = All 1's 0011 = Toggle pattern: data alternate between 101010101010 and 010101010101 0100 = Digital ramp: data increment by 1 LSB every clock cycle from code 0 to 16383 0101 = Custom pattern: output data are the same as programmed by the CUSTOM PATTERN register bits 0110 = Deskew pattern: data are 2AAAh 1000 = PRBS pattern: data are a sequence of pseudo random numbers 1001 = 8-point sine-wave: data are a repetitive sequence of the following eight numbers that form a sine-wave: 0, 2399, 8192, 13984, 16383, 13984, 8192, 2399. Others = Do not use

**9.6.1.9 Register 0Bh (address = 0Bh)**
**Figure 169. Register 0Bh**

7	6	5	4	3	2	1	0
CHC TEST PATTERN				CHD TEST PATTERN			
R/W-0h				R/W-0h			

LEGEND: R/W = Read/Write; -n = value after reset

**Table 18. Register 0Bh Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	CHC TEST PATTERN	R/W	0h	These bits control the test pattern for channel C after the TEST PATTERN EN bit is set. 0000 = Normal operation 0001 = All 0's 0010 = All 1's 0011 = Toggle pattern: data alternate between 101010101010 and 010101010101 0100 = Digital ramp: data increment by 1 LSB every clock cycle from code 0 to 16383 0101 = Custom pattern: output data are the same as programmed by the CUSTOM PATTERN register bits 0110 = Deskew pattern: data are 2AAAh 1000 = PRBS pattern: data are a sequence of pseudo random numbers 1001 = 8-point sine-wave: data are a repetitive sequence of the following eight numbers that form a sine-wave: 0, 2399, 8192, 13984, 16383, 13984, 8192, 2399. Others = Do not use
3-0	CHD TEST PATTERN	R/W	0h	These bits control the test pattern for channel D after the TEST PATTERN EN bit is set. 0000 = Normal operation 0001 = All 0's 0010 = All 1's 0011 = Toggle pattern: data alternate between 101010101010 and 010101010101 0100 = Digital ramp: data increment by 1 LSB every clock cycle from code 0 to 16383 0101 = Custom pattern: output data are the same as programmed by the CUSTOM PATTERN register bits 0110 = Deskew pattern: data are 2AAAh 1000 = PRBS pattern: data are a sequence of pseudo random numbers 1001 = 8-point sine-wave: data are a repetitive sequence of the following eight numbers that form a sine-wave: 0, 2399, 8192, 13984, 16383, 13984, 8192, 2399. Others = Do not use



**9.6.1.10 Register 13h (address = 13h)**
**Figure 170. Register 13h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	LOW SPEED ENABLE	
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 19. Register 13h Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1-0	LOW SPEED ENABLE	R/W	0h	Enables low speed operation in 1-wire and 2-wire mode. Depending upon sampling frequency, write this bit as per <a href="#">Table 20</a> .

**Table 20. LOW SPEED ENABLE Register Settings Across  $f_s$** 

$f_s$ , MSPS		REGISTER BIT LOW SPEED ENABLE	
MIN	MAX	1-WIRE MODE	2-WIRE MODE
25	125	00	00
20	25	00	10
15	20	10	Not supported

**9.6.1.11 Register 0Eh (address = 0Eh)**
**Figure 171. Register 0Eh**

7	6	5	4	3	2	1	0
CUSTOM PATTERN[13:6]							
R/W-0h							

LEGEND: R/W = Read/Write; -n = value after reset

**Table 21. Register 0Eh Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	CUSTOM PATTERN[13:6]	R/W	0h	These bits set the 14-bit custom pattern (bits 13-6) for all channels.

**9.6.1.12 Register 0Fh (address = 0Fh)**
**Figure 172. Register 0Fh**

7	6	5	4	3	2	1	0
CUSTOM PATTERN[5:0]						0	0
R/W-0h						W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 22. Register 0Fh Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	CUSTOM PATTERN[5:0]	R/W	0h	These bits set the 14-bit custom pattern (bits 5-0) for all channels.
1-0	0	W	0h	Must write 0.

**9.6.1.13 Register 15h (address = 15h)**
**Figure 173. Register 15h**

7	6	5	4	3	2	1	0
CHA PDN	CHB PDN	CHC PDN	CHD PDN	STANDBY	GLOBAL PDN	0	CONFIG PDN PIN
W-0h	R/W-0h	R/W-0h	W-0h	R/W-0h	R/W-0h	W-0h	R/W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 23. Register 15h Field Descriptions**

Bit	Field	Type	Reset	Description
7	CHA PDN	W	0h	0 = Normal operation 1 = Power-down channel A
6	CHB PDN	R/W	0h	0 = Normal operation 1 = Power-down channel B
5	CHC PDN	R/W	0h	0 = Normal operation 1 = Power-down channel C
4	CHD PDN	W	0h	0 = Normal operation 1 = Power-down channel D
3	STANDBY	R/W	0h	ADCs of both channels enter standby. 0 = Normal operation 1 = Standby
2	GLOBAL PDN	R/W	0h	0 = Normal operation 1 = Global power-down
1	0	W	0h	Must write 0.
0	CONFIG PDN PIN	R/W	0h	This bit configures the PDN pin as either a global power-down or standby pin. 0 = Logic high voltage on PDN pin sends the device into global power-down 1 = Logic high voltage on PDN pin sends the device into standby

**9.6.1.14 Register 25h (address = 25h)**
**Figure 174. Register 25h**

7	6	5	4	3	2	1	0
LVDS SWING							
R/W-0h							

LEGEND: R/W = Read/Write; -n = value after reset

**Table 24. Register 25h Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	LVDS SWING	R/W	0h	These bits control the swing of the LVDS outputs (including the data output, bit clock, and frame clock).

**9.6.1.15 Register 27h (address = 27h)**
**Figure 175. Register 27h**

7	6	5	4	3	2	1	0
CLK DIV	0	0	0	0	0	0	0
R/W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 25. Register 27h Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	CLK DIV	R/W	0h	Internal clock divider for the input sampling clock. 00 = Divide-by-1 01 = Divide-by-1 10 = Divide-by-2 11 = Divide-by-4
5-0	0	W	0h	Must write 0.

**9.6.1.16 Register 11Dh (address = 11Dh)**
**Figure 176. Register 11Dh**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	HIGH IF MODE0	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 26. Register 11Dh Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	HIGH IF MODE0			Set the HIGH IF MODE[7:0] bits together to 1111. Improves HD3 by a couple of dB for IF > 100 MHz.
0	0	W	0h	Must write 0.

**9.6.1.17 Register 122h (address = 122h)**
**Figure 177. Register 122h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	DIS CHOP CHA	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 27. Register 122h Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	DIS CHOP CHA	R/W	0h	Disables the chopper. Set this bit to shift 1/f noise floor at dc. 0 = 1/f noise floor is centered at $f_S / 2$ (default) 1 = Chopper mechanism is disabled; 1/f noise floor is centered at dc
0	0	W	0h	Must write 0.

**9.6.1.18 Register 134h (address = 134h)**
**Figure 178. Register 134h**

7	6	5	4	3	2	1	0
0	0	DIS DITH CHA	0	DIS DITH CHA	0	0	0
W-0h	W-0h	R/W-0h	W-0h	R/W-0h	W-0h	W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 28. Register 134h Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	0	W	0h	Must write 0.
5	DIS DITH CHA	R/W	0h	Set this bit with bits 7 and 6 of register 01h. 00 = Default 11 = Dither is disabled for channel A. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
4	0	W	0h	Must write 0.
3	DIS DITH CHA	R/W	0h	Set this bit with bits 7 and 6 of register 01h. 00 = Default 11 = Dither is disabled for channel A. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
2-0	0	W	0h	Must write 0.

**9.6.1.19 Register 139h (address = 139h)**
**Figure 179. Register 139h**

7	6	5	4	3	2	1	0
0	0	0	0	SP1 CHA	0	0	0
W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h	W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 29. Register 139h Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	0	W	0h	Must write 0.
3	SP1 CHA	R/W	0h	Special mode for best performance on channel A. Always write 1 after reset.
2-0	0	W	0h	Must write 0.

**9.6.1.20 Register 21Dh (address = 21Dh)**
**Figure 180. Register 21Dh**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	HIGH IF MODE1	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 30. Register 21Dh Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	HIGH IF MODE1			Set the HIGH IF MODE[7:0] bits together to 1111. Improves HD3 by a couple of dB for IF > 100 MHz.
0	0	W	0h	Must write 0.

**9.6.1.21 Register 222h (address = 222h)**
**Figure 181. Register 222h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	DIS CHOP CHD	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 31. Register 222h Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	DIS CHOP CHD	R/W	0h	Disables the chopper. Set this bit to shift 1/f noise floor at dc. 0 = 1/f noise floor is centered at $f_S / 2$ (default) 1 = Chopper mechanism is disabled; 1/f noise floor is centered at dc
0	0	W	0h	Must write 0.

**9.6.1.22 Register 234h (address = 234h)**
**Figure 182. Register 234h**

7	6	5	4	3	2	1	0
0	0	DIS DITH CHD	0	DIS DITH CHD	0	0	0
W-0h	W-0h	R/W-0h	W-0h	R/W-0h	W-0h	W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 32. Register 234h Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	0	W	0h	Must write 0.
5	DIS DITH CHD	R/W	0h	Set this bit with bits 1 and 0 of register 01h. 00 = Default 11 = Dither is disabled for channel D. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
4	0	W	0h	Must write 0.
3	DIS DITH CHD	R/W	0h	Set this bit with bits 1 and 0 of register 01h. 00 = Default 11 = Dither is disabled for channel D. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
2-0	0	W	0h	Must write 0.

**9.6.1.23 Register 239h (address = 239h)**
**Figure 183. Register 239h**

7	6	5	4	3	2	1	0
0	0	0	0	SP1 CHD	0	0	0
W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h	W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 33. Register 239h Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	0	W	0h	Must write 0.
3	SP1 CHD	R/W	0h	Special mode for best performance on channel D. Always write 1 after reset.
2-0	0	W	0h	Must write 0.

**9.6.1.24 Register 308h (address = 308h)**
**Figure 184. Register 308h**

7	6	5	4	3	2	1	0
HIGH IF MODE<5:4>	0	0	0	0	0	0	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 34. Register 308h Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	HIGH IF MODE<5:4>	W	0h	Set the HIGH IF MODE[7:0] bits together to FFh. Improves HD3 by a couple of dB for IF > 100 MHz.
5-0	0	W	0h	Must write 0.

**9.6.1.25 Register 41Dh (address = 41Dh)**
**Figure 185. Register 41Dh**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	HIGH IF MODE2	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 35. Register 41Dh Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	HIGH IF MODE2			Set the HIGH IF MODE[7:0] bits together to FFh. Improves HD3 by a couple of dB for IF > 100 MHz.
0	0	W	0h	Must write 0.

**9.6.1.26 Register 422h (address = 422h)**
**Figure 186. Register 422h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	DIS CHOP CHB	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 36. Register 422h Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	DIS CHOP CHB	R/W	0h	Disables the chopper. Set this bit to shift 1/f noise floor at dc. 0 = 1/f noise floor is centered at $f_S / 2$ (default) 1 = Chopper mechanism is disabled; 1/f noise floor is centered at dc
0	0	W	0h	Must write 0.

**9.6.1.27 Register 434h (address = 434h)**
**Figure 187. Register 434h**

7	6	5	4	3	2	1	0
0	0	DIS DITH CHB	0	DIS DITH CHB	0	0	0
W-0h	W-0h	R/W-0h	W-0h	R/W-0h	W-0h	W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 37. Register 434h Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	0	W	0h	Must write 0.
5	DIS DITH CHB	R/W	0h	Set this bit with bits 5 and 4 of register 01h. 00 = Default 11 = Dither is disabled for channel B. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
4	0	W	0h	Must write 0.
3	DIS DITH CHB	R/W	0h	Set this bit with bits 5 and 4 of register 01h. 00 = Default 11 = Dither is disabled for channel B. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
2-0	0	W	0h	Must write 0.

**9.6.1.28 Register 439h (address = 439h)**
**Figure 188. Register 439h**

7	6	5	4	3	2	1	0
0	0	0	0	SP1 CHB	0	0	0
W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h	W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 38. Register 439h Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	0	W	0h	Must write 0.
3	SP1 CHB	R/W	0h	Special mode for best performance on channel B. Always write 1 after reset.
2-0	0	W	0h	Must write 0.

**9.6.1.29 Register 51Dh (address = 51Dh)**
**Figure 189. Register 51Dh**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	HIGH IF MODE3	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 39. Register 51Dh Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	HIGH IF MODE3			Set the HIGH IF MODE[7:0] bits together to FFh. Improves HD3 by a couple of dB for IF > 100 MHz.
0	0	W	0h	Must write 0.

**9.6.1.30 Register 522h (address = 522h)**
**Figure 190. Register 522h**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	DIS CHOP CHC	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 40. Register 522h Field Descriptions**

Bit	Field	Type	Reset	Description
7-2	0	W	0h	Must write 0.
1	DIS CHOP CHC	R/W	0h	Disables the chopper. Set this bit to shift 1/f noise floor at dc. 0 = 1/f noise floor is centered at $f_s / 2$ (default) 1 = Chopper mechanism is disabled; 1/f noise floor is centered at dc
0	0	W	0h	Must write 0.

**9.6.1.31 Register 534h (address = 534h)**
**Figure 191. Register 534h**

7	6	5	4	3	2	1	0
0	0	DIS DITH CHC	0	DIS DITH CHC	0	0	0
W-0h	W-0h	R/W-0h	W-0h	R/W-0h	W-0h	W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 41. Register 534h Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	0	W	0h	Must write 0.
5	DIS DITH CHC	R/W	0h	Set this bit with bits 3 and 2 of register 01h. 00 = Default 11 = Dither is disabled for channel C. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
4	0	W	0h	Must write 0.
3	DIS DITH CHC	R/W	0h	Set this bit with bits 3 and 2 of register 01h. 00 = Default 11 = Dither is disabled for channel C. In this mode, SNR typically improves by 0.5 dB at 70 MHz.
2-0	0	W	0h	Must write 0.



**9.6.1.32 Register 539h (address = 539h)**
**Figure 192. Register 539h**

7	6	5	4	3	2	1	0
0	0	0	0	SP1 CHC	0	0	0
W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h	W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 42. Register 539h Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	0	W	0h	Must write 0.
3	SP1 CHC	R/W	0h	Special mode for best performance on channel C. Always write 1 after reset.
2-0	0	W	0h	Must write 0.

**9.6.1.33 Register 608h (address = 608h)**
**Figure 193. Register 608h**

7	6	5	4	3	2	1	0
HIGH IF MODE<7:6>	0	0	0	0	0	0	0
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h	W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 43. Register 608h Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	HIGH IF MODE<7:6>			Set the HIGH IF MODE[7:0] bits together to FFh. Improves HD3 by a couple of dB for IF > 100 MHz.
5-0	0	W	0h	Must write 0.

**9.6.1.34 Register 70Ah (address = 70Ah)**
**Figure 194. Register 70Ah**

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	PDN SYSREF
W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	W-0h	R/W-0h

LEGEND: R/W = Read/Write; W = Write only; -n = value after reset

**Table 44. Register 70Ah Field Descriptions**

Bit	Field	Type	Reset	Description
7-1	0	W	0h	Must write 0.
0	PDN SYSREF	R/W	0h	If the SYSREF pins are not used in the system, the SYSREF buffer must be powered down by setting this bit. 0 = Normal operation 1 = Powers down the SYSREF buffer

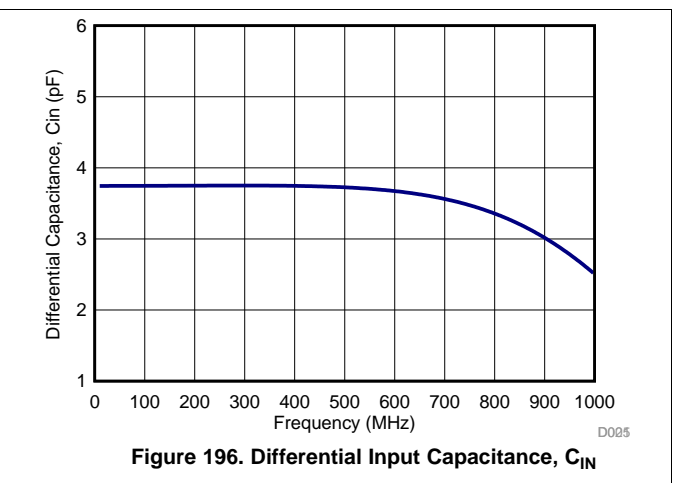
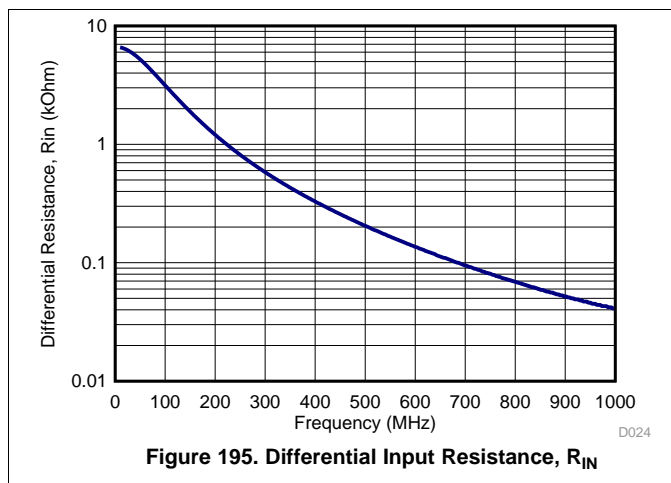
## 10 Applications and Implementation

### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 10.1 Application Information

Typical applications involving transformer-coupled circuits are discussed in this section. Transformers (such as ADT1-1WT or WBC1-1) may be used up to 250 MHz to achieve good phase and amplitude balances at ADC inputs. While designing the dc driving circuits, the ADC input impedance must be considered. [Figure 195](#) and [Figure 196](#) show the impedance ( $Z_{in} = R_{in} \parallel C_{in}$ ) across the ADC input pins.



## 10.2 Typical Applications

### 10.2.1 Driving Circuit Design: Low Input Frequencies

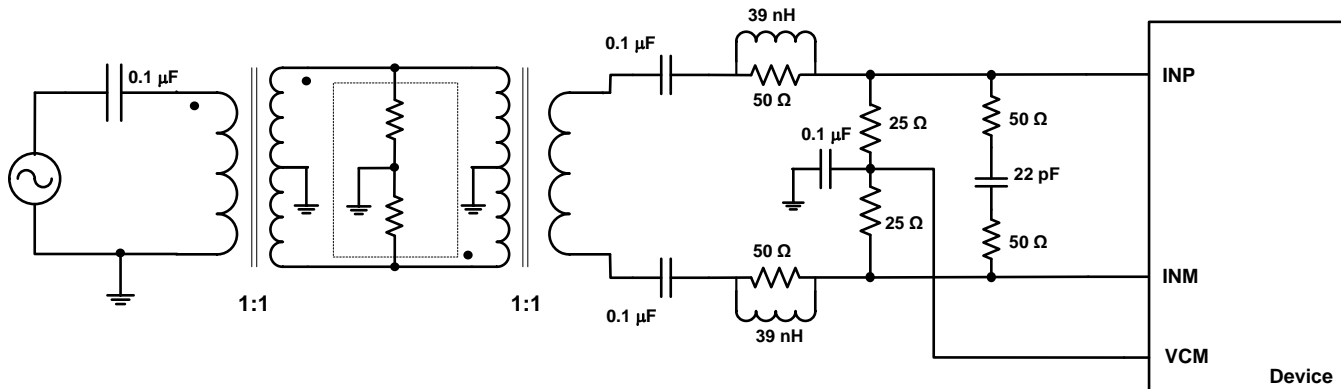


Figure 197. Driving Circuit for Low Input Frequencies

#### 10.2.1.1 Design Requirements

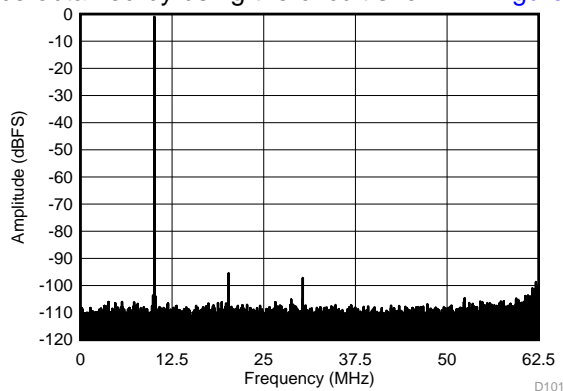
For optimum performance, the analog inputs must be driven differentially. An optional 5-Ω to 15-Ω resistor in series with each input pin may be kept to damp out ringing caused by package parasitic. The drive circuit may have to be designed to minimize the impact of kick-back noise generated by sampling switches opening and closing inside the ADC, as well as ensuring low insertion loss over the desired frequency range and matched impedance to the source.

#### 10.2.1.2 Detailed Design Procedure

A typical application involving using two back-to-back coupled transformers is shown in Figure 197. The circuit is optimized for low input frequencies. An external R-C-R filter using 50-Ω resistors and a 22-pF capacitor is used with the series inductor (39 nH), this combination helps absorb the sampling glitches. To improve phase and amplitude balance of first transformer, the termination resistors can be split between two transformers. For example, 25-Ω to 25-Ω termination across the secondary winding of the second transformer can be changed to 50-Ω to 50-Ω termination and another 50-Ω to 50-Ω resistor can be placed inside the dashed box between the transformers in Figure 197.

#### 10.2.1.3 Application Curve

Figure 198 shows the performance obtained by using the circuit shown in Figure 197.



SFDR = 95 dBc, SNR = 72.7 dBFS, SINAD = 72.6 dBFS,  
THD = 100 dBc, HD2 = 95 dBc, HD3 = 96 dBc

Figure 198. FFT for 10-MHz Input Signal  
(Chopper On, Dither On)

Typical Applications (continued)

10.2.2 Driving Circuit Design: Input Frequencies Between 100 MHz to 230 MHz

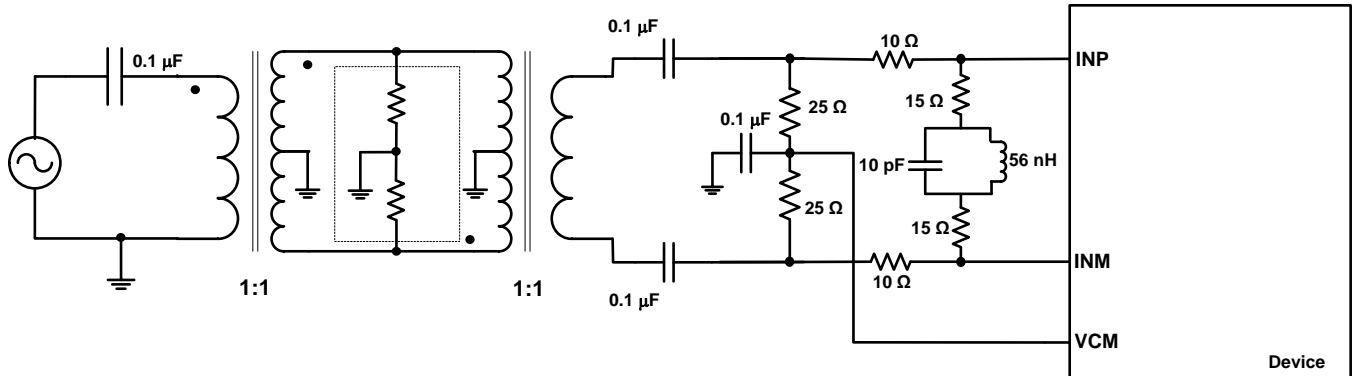


Figure 199. Driving Circuit for Mid-Range Input Frequencies ( $100 \text{ MHz} < f_{IN} < 230 \text{ MHz}$ )

10.2.2.1 Design Requirements

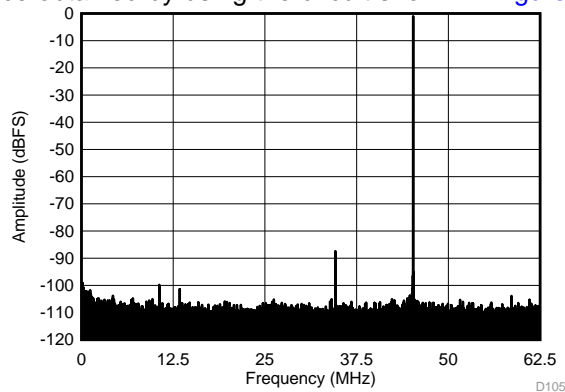
See the [Design Requirements](#) section for further details.

10.2.2.2 Detailed Design Procedure

When input frequencies are between 100 MHz to 230 MHz, an R-LC-R circuit may be used to optimize performance, as shown in [Figure 199](#).

10.2.2.3 Application Curve

[Figure 200](#) shows the performance obtained by using the circuit shown in [Figure 199](#).



SFDR = 86 dBc, SNR = 71.7 dBFS, SINAD = 71.6 dBFS,  
 THD = 93 dBc, HD2 = 86 dBc, HD3 = 99 dBc

Figure 200. FFT for 170-MHz Input Signal (Chopper Off, Dither On)

Typical Applications (continued)

10.2.3 Driving Circuit Design: Input Frequencies Greater than 230 MHz

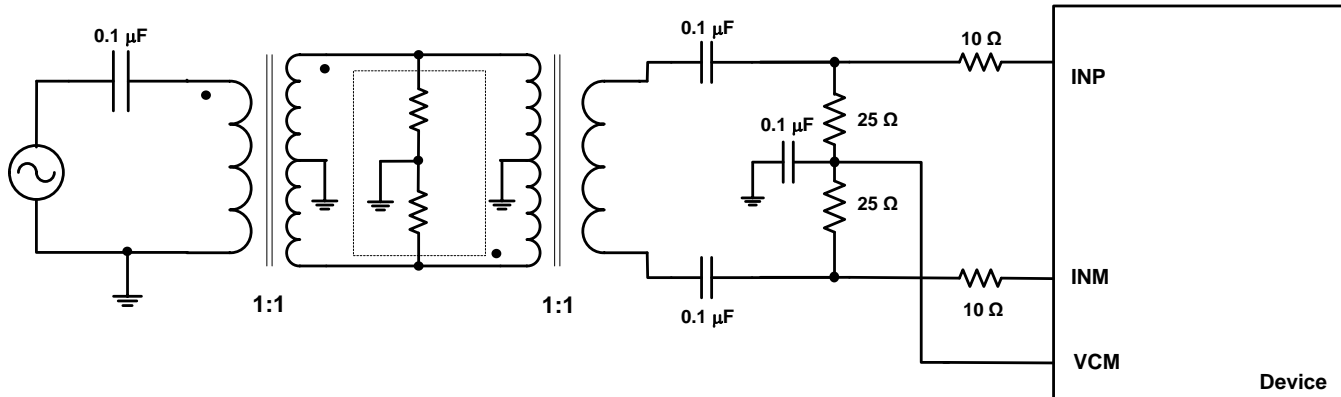


Figure 201. Driving Circuit for High Input Frequencies ( $f_{IN} > 230$  MHz)

10.2.3.1 Design Requirements

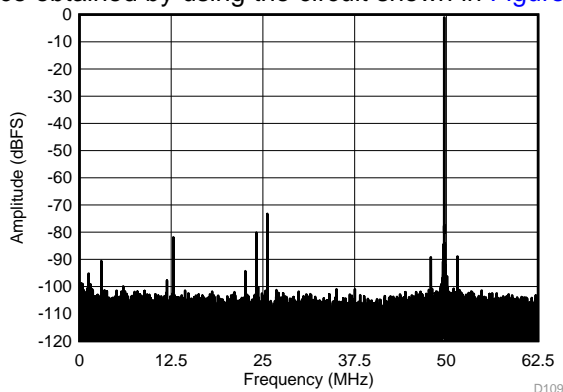
See the [Design Requirements](#) section for further details.

10.2.3.2 Detailed Design Procedure

For high input frequencies (> 230 MHz), using the R-C-R or R-LC-R circuit does not show significant improvement in performance. However, a series resistance of 10 Ω may be used as shown in [Figure 201](#).

10.2.3.3 Application Curve

[Figure 202](#) shows the performance obtained by using the circuit shown in [Figure 201](#).



SFDR = 72 dBc, SNR = 68.2 dBFS, SINAD = 67.3 dBFS,  
THD = 74 dBc, HD2 = 72 dBc, HD3 = 79 dBc

Figure 202. FFT for 450-MHz Input Signal (Chopper Off, Dither On)

11 Power Supply Recommendations

The device requires a 1.8-V nominal supply for AVDD and DVDD. There are no specific sequence power-supply requirements during device power-up. AVDD and DVDD may power up in any order. See [Figure 160](#) for other power-up requirements.

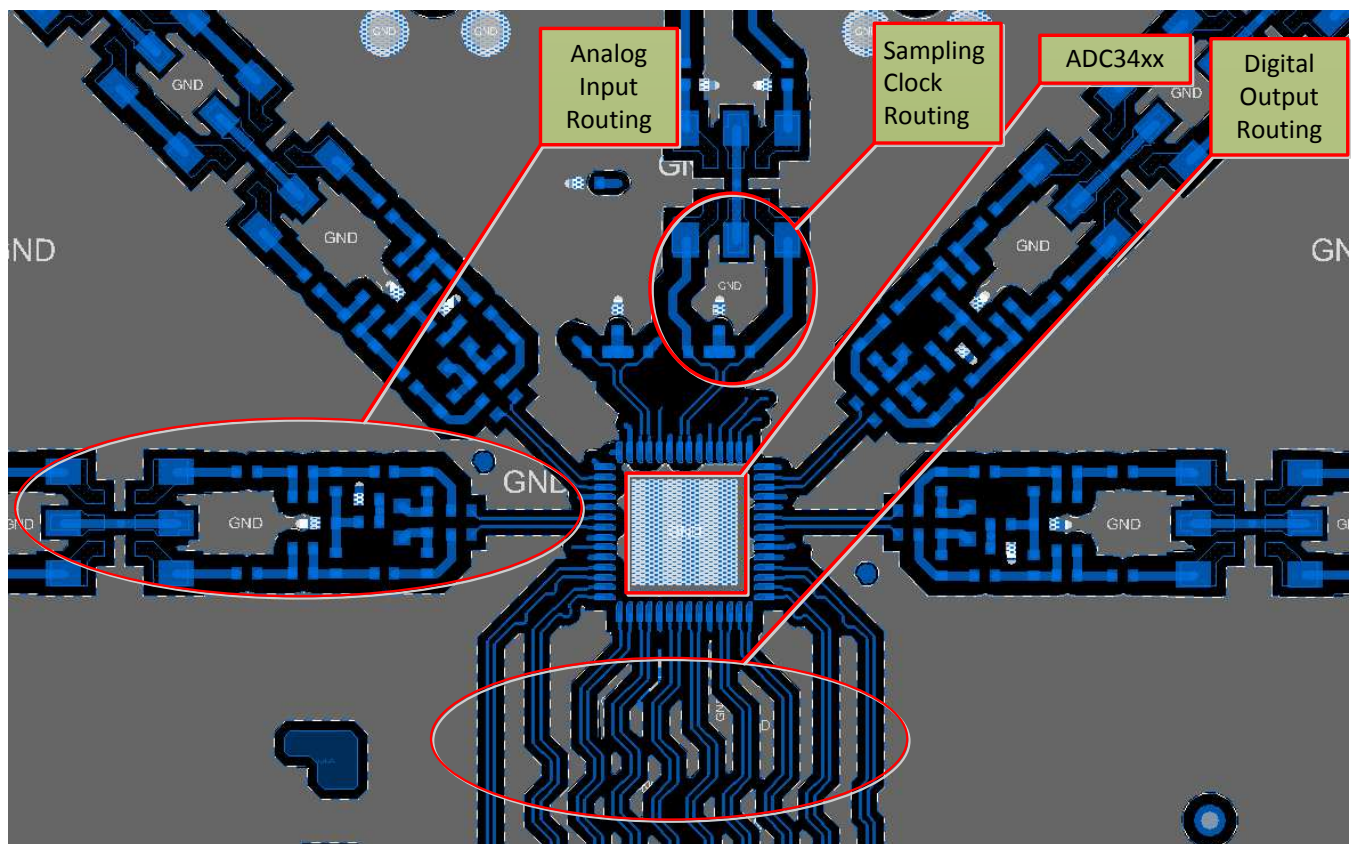
## 12 Layout

### 12.1 Layout Guidelines

The ADC344x EVM layout may be used as a reference layout to obtain the best performance. A layout diagram of the EVM top layer is provided in [Figure 203](#). Some important points to remember during laying out the board are:

1. Analog inputs are located on opposite sides of the device pin out to ensure minimum crosstalk on the package level. To minimize crosstalk onboard, the analog inputs must exit the pin out in opposite directions, as shown in the reference layout of [Figure 203](#) as much as possible.
2. In the device pin out, the sampling clock is located on a side perpendicular to the analog inputs in order to minimize coupling between them. This configuration is also maintained on the reference layout of [Figure 203](#) as much as possible.
3. Keep digital outputs away from the analog inputs. When these digital outputs exit the pin out, the digital output traces must not be kept parallel to the analog input traces because this configuration may result in coupling from digital outputs to analog inputs and degrade performance. All digital output traces to the receiver [such as a field-programmable gate array (FPGA) or an application-specific integrated circuit (ASIC)] must be matched in length to avoid skew among outputs.
4. At each power-supply pin (AVDD and DVDD), keep a 0.1- $\mu$ F decoupling capacitor close to the device. A separate decoupling capacitor group consisting of a parallel combination of 10- $\mu$ F, 1- $\mu$ F, and 0.1- $\mu$ F capacitors may be kept close to the supply source.

### 12.2 Layout Example



**Figure 203. Typical Layout of the ADC344x Board**

## 13 Device and Documentation Support

### 13.1 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to order now.

**Table 45. Related Links**

PARTS	PRODUCT FOLDER	ORDER NOW	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
ADC3441	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>
ADC3442	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>
ADC3443	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>
ADC3444	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>	<a href="#">Click here</a>

### 13.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 13.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

### 13.4 Trademarks

PowerPAD, E2E are trademarks of Texas Instruments.  
All other trademarks are the property of their respective owners.

### 13.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 13.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

**PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">ADC3441IRTQR</a>	Active	Production	QFN (RTQ)   56	2000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ3441
<a href="#">ADC3441IRTQT</a>	Active	Production	QFN (RTQ)   56	250   SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ3441
<a href="#">ADC3442IRTQR</a>	Active	Production	QFN (RTQ)   56	2000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ3442
<a href="#">ADC3442IRTQT</a>	Active	Production	QFN (RTQ)   56	250   SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ3442
<a href="#">ADC3443IRTQR</a>	Active	Production	QFN (RTQ)   56	2000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ3443
<a href="#">ADC3443IRTQT</a>	Active	Production	QFN (RTQ)   56	250   SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ3443
<a href="#">ADC3444IRTQR</a>	Active	Production	QFN (RTQ)   56	2000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ3444
<a href="#">ADC3444IRTQT</a>	Active	Production	QFN (RTQ)   56	250   SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ3444

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.



In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADC3441IRTQR	QFN	RTQ	56	2000	330.0	16.4	8.3	8.3	2.25	12.0	16.0	Q2
ADC3442IRTQR	QFN	RTQ	56	2000	330.0	16.4	8.3	8.3	2.25	12.0	16.0	Q2
ADC3443IRTQR	QFN	RTQ	56	2000	330.0	16.4	8.3	8.3	2.25	12.0	16.0	Q2
ADC3444IRTQR	QFN	RTQ	56	2000	330.0	16.4	8.3	8.3	2.25	12.0	16.0	Q2

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADC3441IRTQR	QFN	RTQ	56	2000	350.0	350.0	43.0
ADC3442IRTQR	QFN	RTQ	56	2000	350.0	350.0	43.0
ADC3443IRTQR	QFN	RTQ	56	2000	350.0	350.0	43.0
ADC3444IRTQR	QFN	RTQ	56	2000	350.0	350.0	43.0

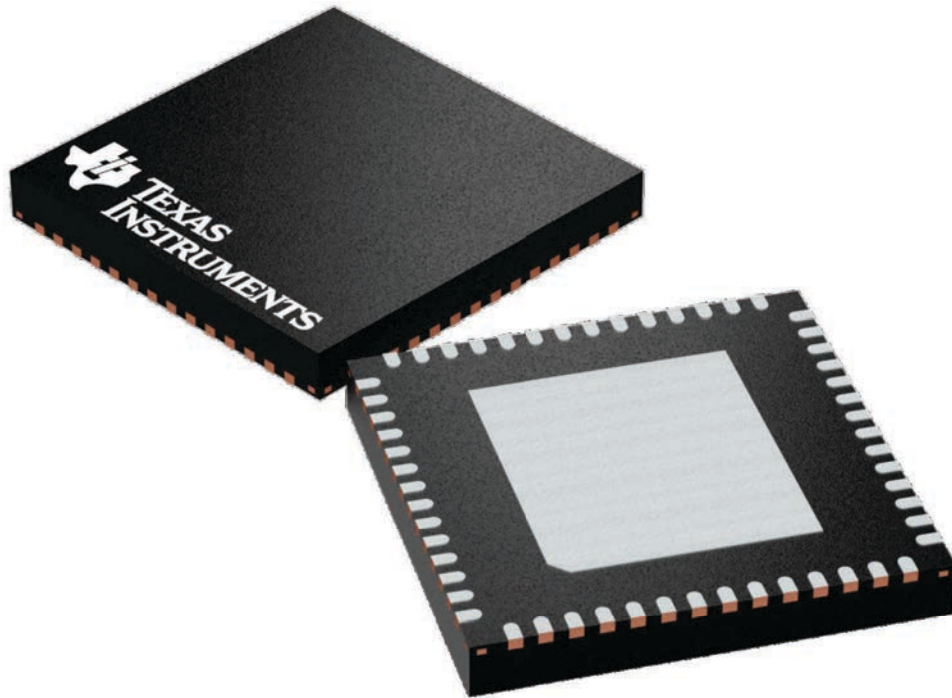
## GENERIC PACKAGE VIEW

**RTQ 56**

**VQFN - 1 mm max height**

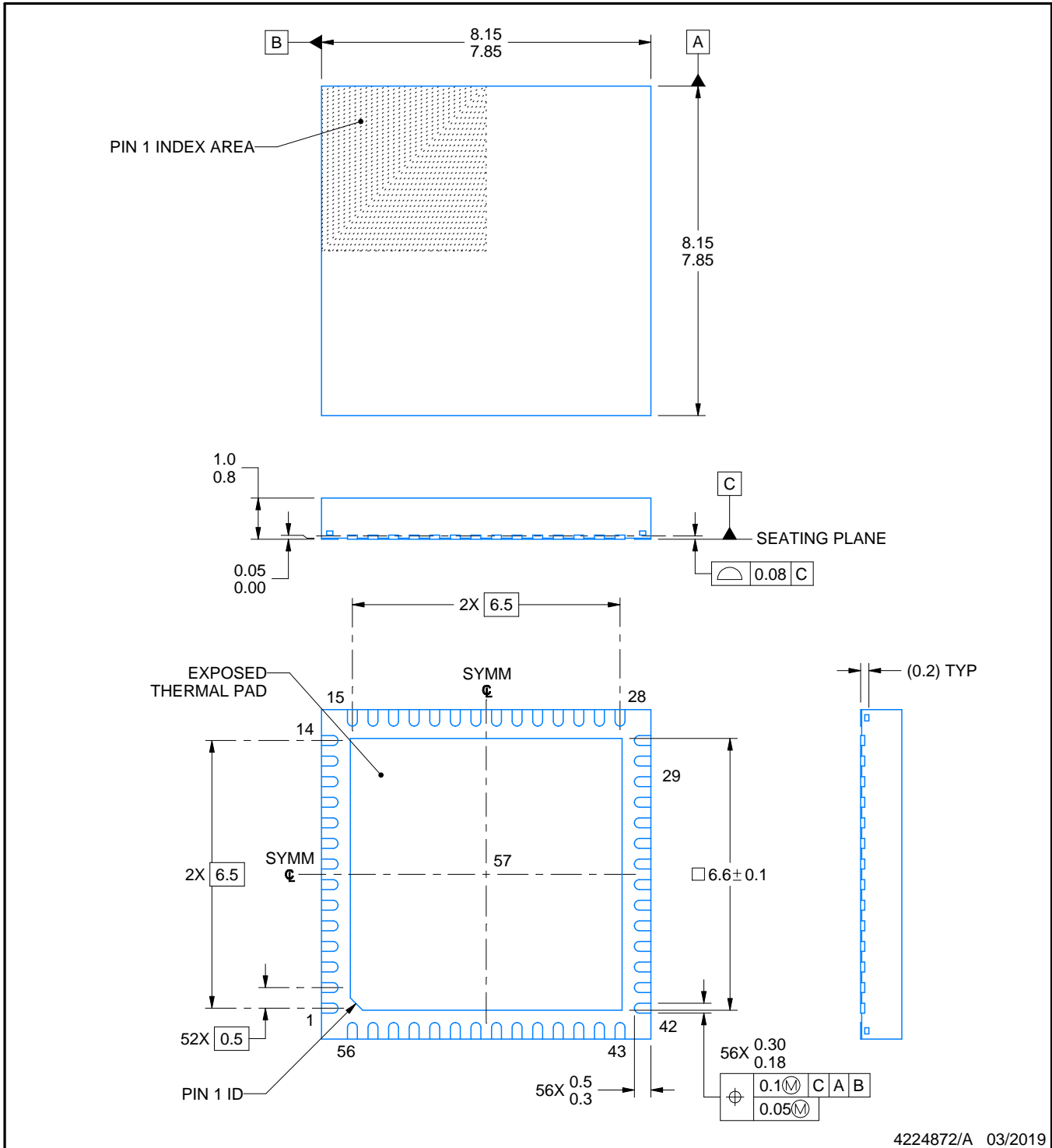
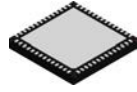
8 x 8, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

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4224872/A 03/2019

NOTES:

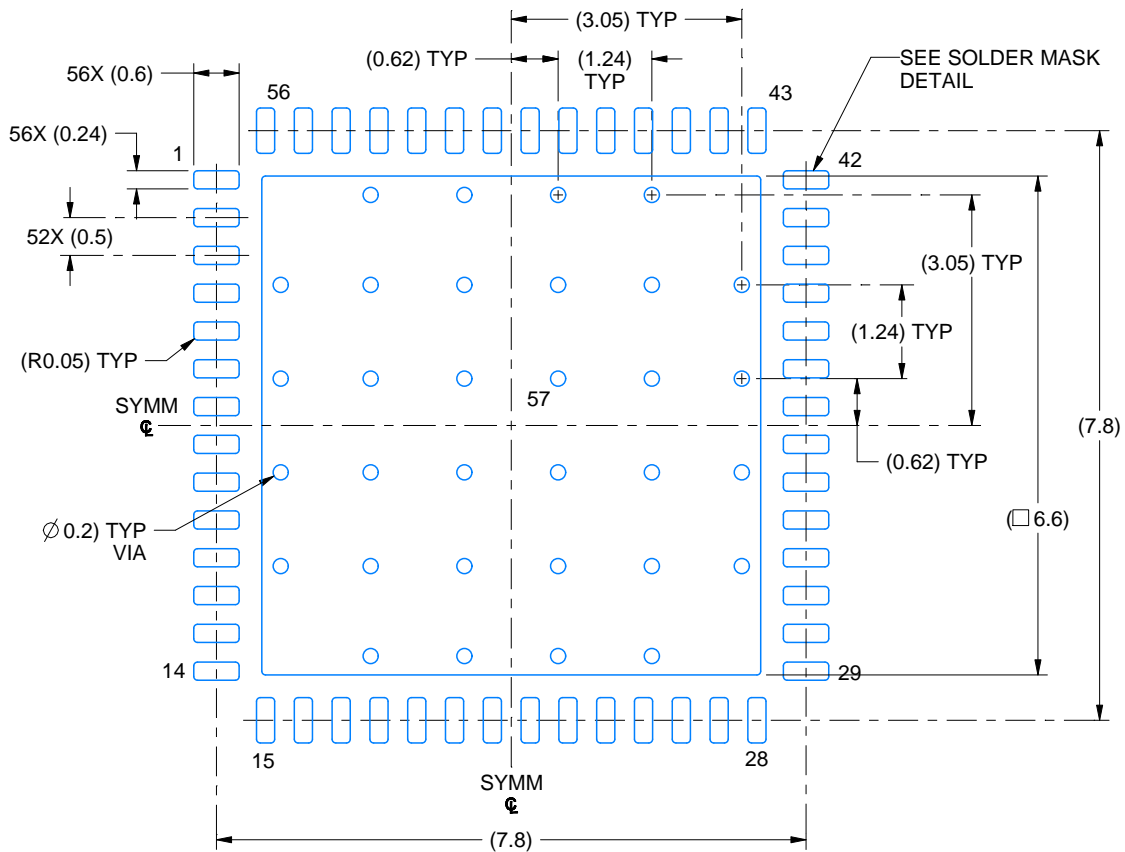
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

# EXAMPLE BOARD LAYOUT

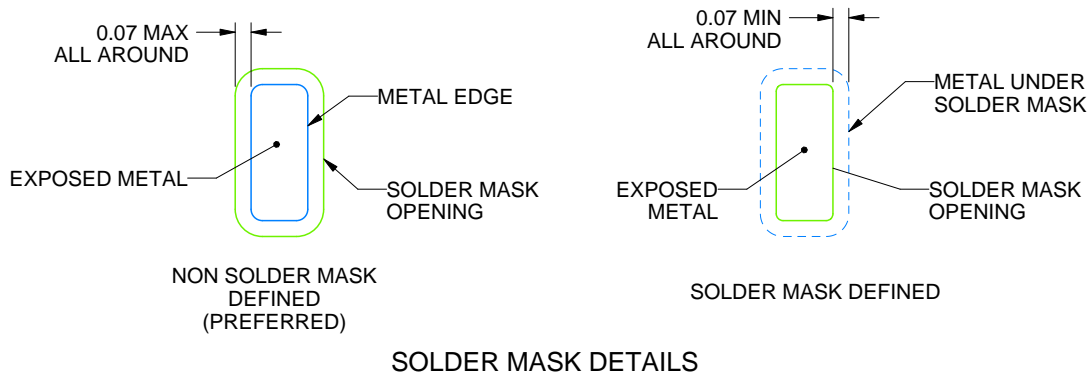
RTQ0056C

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE: 10X



4224872/A 03/2019

NOTES: (continued)

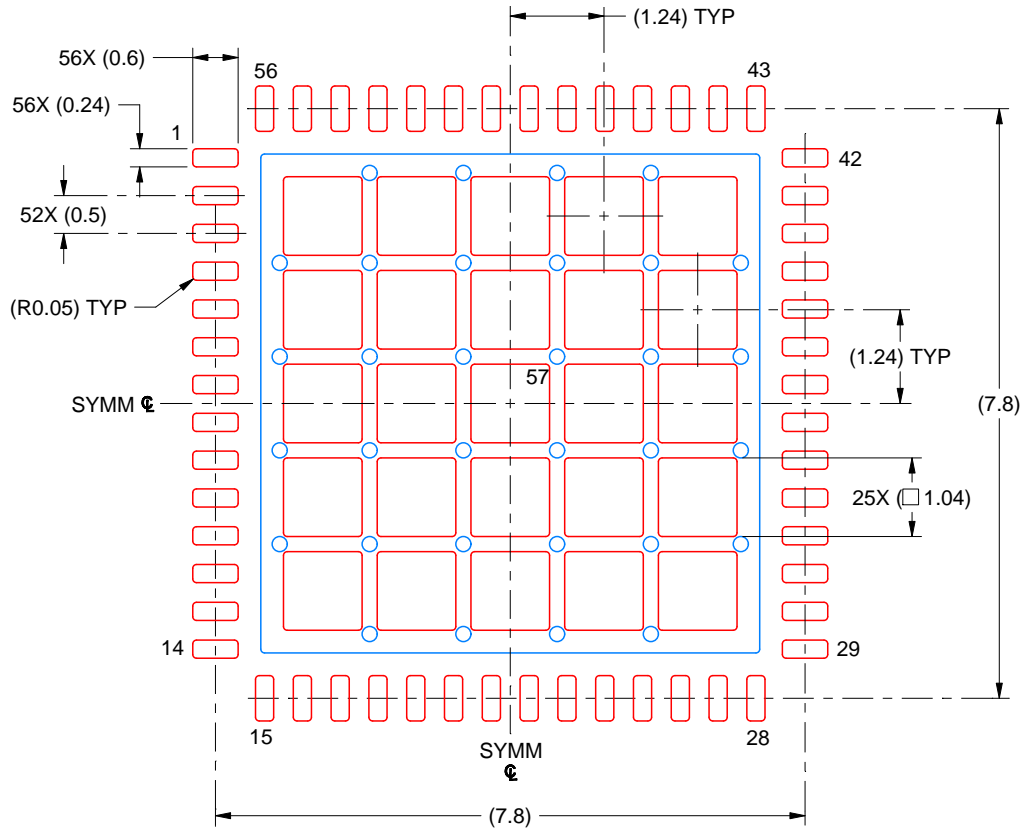
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/sl原因271](http://www.ti.com/lit/sl原因271)).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

# EXAMPLE STENCIL DESIGN

RTQ0056C

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



SOLDER PASTE EXAMPLE  
BASED ON 0.125 MM THICK STENCIL  
SCALE: 10X

EXPOSED PAD 57  
62% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE

4224872/A 03/2019

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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