











INA333

SBOS445C - JULY 2008-REVISED DECEMBER 2015

# INA333 Micro-Power (50µA), Zerø-Drift, Rail-to-Rail Out Instrumentation Amplifier

#### 1 Features

Low Offset Voltage: 25 μV (Maximum), G ≥ 100

Low Drift: 0.1 μV/°C, G ≥ 100
 Low Noise: 50 nV/√Hz, G ≥ 100

High CMRR: 100 dB (Minimum), G ≥ 10
 Low Input Bias Current: 200 pA (Maximum)

Supply Range: 1.8 V to 5.5 V

Input Voltage: (V–) +0.1 V to (V+) –0.1 V

• Output Range: (V-) +0.05 V to (V+) -0.05 V

Low Quiescent Current: 50 μA

Operating Temperature: –40°C to +125°C

RFI Filtered Inputs

8-Pin VSSOP and 8-Pin WSON Packages

# 2 Applications

- Bridge Amplifiers
- ECG Amplifiers
- Pressure Sensors
- Medical Instrumentation
- Portable Instrumentation
- · Weigh Scales
- Thermocouple Amplifiers
- RTD Sensor Amplifiers
- Data Acquisition

#### 3 Description

The INA333 device is a low-power, precision instrumentation amplifier offering excellent accuracy. The versatile 3-operational amplifier design, small size, and low power make it ideal for a wide range of portable applications.

A single external resistor sets any gain from 1 to 1000. The INA333 is designed to use an industry-standard gain equation:  $G = 1 + (100 \text{ k}\Omega / R_G)$ .

The INA333 device provides very low offset voltage (25 µV, G ≥ 100), excellent offset voltage drift (0.1 µV/°C, G ≥ 100), and high common-mode rejection (100 dB at G ≥ 10). It operates with power supplies as low as 1.8 V (±0.9 V) and quiescent current is only 50 µA, making it ideal for battery-operated systems. Using autocalibration techniques to ensure excellent precision over the extended industrial temperature range, the INA333 device also offers exceptionally low noise density (50 nV/ $\sqrt{\text{Hz}}$ ) that extends down to DC.

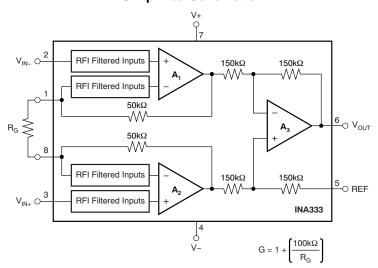
The INA333 device is available in both 8-pin VSSOP and WSON surface-mount packages and is specified over the  $T_A = -40$ °C to +125°C temperature range.

# **Device Information**(1)

PART NUMBER		PACKAGE	BODY SIZE (NOM)		
	INIAGOG	VSSOP (8)	3.00 mm × 3.00 mm		
	INA333	WSON (8)	3.00 mm × 3.00 mm		

 For all available packages, see the orderable addendum at the end of the data sheet.

#### **Simplified Schematic**





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# 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

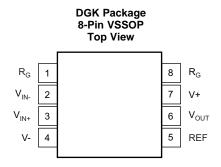
#### Changes from Revision B (October 2008) to Revision C

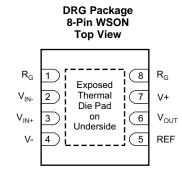
**Page** 

Added ESD Ratings table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and 



# 5 Pin Configuration and Functions





#### **Pin Functions**

PIN		1/0	DESCRIPTION
NAME	NO.	1/0	DESCRIPTION
REF	5	1	Reference input. This pin must be driven by low impedance or connected to ground.
RG	1, 8	_	Gain setting pins. For gains greater than 1, place a gain resistor between pins 1 and 8.
V <sup>+</sup>	7	_	Positive supply
V-	4	_	Negative supply
VIN+	3	- 1	Positive input
VIN-	2	- 1	Negative input
VOUT	6	0	Output

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#### 6 Specifications

#### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) (1)

	MIN	MAX	UNIT
Supply voltage	7		V
Analog input voltage <sup>(2)</sup>	(V-) - 0.3	(V+) + 0.3	V
Output short-circuit (3)	Continuous		
Operating temperature, T <sub>A</sub>	-40	150	°C
Junction temperature, T <sub>J</sub>		150	°C
Storage temperature, T <sub>stg</sub>	-65	150	°C

- (1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) Input pins are diode-clamped to the power-supply rails. Input signals that can swing more than 0.3 V beyond the supply rails should be current limited to 10 mA or less.
- (3) Short-circuit to ground.

#### 6.2 ESD Ratings

			VALUE	UNIT
		Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 (1)	±4000	
V <sub>(ESD)</sub>	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 (2)	±1000	V
		Machine model (MM)	±200	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

#### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
VS	Supply voltage	1.8	5.5	V
	Specified temperature	-40	125	°C

#### 6.4 Thermal Information

		INA		
	THERMAL METRIC <sup>(1)</sup>	DGK (VSSOP)	DRG (WSON)	UNIT
		8 PINS	8 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	169.5	60	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	62.7	60	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	90.3	50	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	7.6	_	°C/W
$\psi_{JB}$	Junction-to-board characterization parameter	88.7	_	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance		6	°C/W

 For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

Product Folder Links: INA333



#### 6.5 Electrical Characteristics

for  $V_S$  = 1.8 V to 5.5 V at  $T_A$  = 25°C,  $R_L$  = 10 k $\Omega$ ,  $V_{REF}$  =  $V_S$  / 2, and G = 1 (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
NPUT <sup>(</sup>	1)					
V <sub>OSI</sub>	Offset voltage, RTI <sup>(2)</sup>			±10 ±25/G	±25 ±75/G	μV
	vs temperature	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$			±0.1 ±0.5 / G	μV/°C
PSR	vs power supply	$1.8 \text{ V} \le \text{V}_{\text{S}} \le 5.5 \text{ V}$		±1 ±5/G	±5 ±15/G	μV/V
	Long-term stability			See (3)		
	Turnon time to specified $V_{\text{OSI}}$	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$	See <i>Typ</i>	ical Characteristi	cs	
	Impedance					
Z <sub>IN</sub>	Differential			100    3		GΩ    pF
Z <sub>IN</sub>	Common-mode			100    3		GΩ    pF
V <sub>CM</sub>	Common-mode voltage range	V <sub>O</sub> = 0 V	(V-) + 0.1		(V+) - 0.1	V
	Common-mode rejection	DC to 60 Hz				
	G = 1	$V_{CM} = (V-) + 0.1 V$ to $(V+) - 0.1 V$	80	90		dB
CMR	G = 10	V <sub>CM</sub> = (V-) + 0.1 V to (V+) - 0.1 V	100	110		dB
	G = 100	V <sub>CM</sub> = (V-) + 0.1 V to (V+) - 0.1 V	100	115		dB
	G = 1000	$V_{CM} = (V-) + 0.1 V$ to $(V+) - 0.1 V$	100	115		dB
INPUT	BIAS CURRENT				-	
ı	Input bias current			±70	±200	pA
В	vs temperature	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	Se	ee Figure 26		pA/°C
ı	Input offset current			±50	±200	pA
vs temperature		$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$	Se	ee Figure 28		pA/°C
INPUT	VOLTAGE NOISE					
		G = 100, $R_S = 0 \Omega$ , $f = 10 Hz$		50		nV/√Hz
	La de Maria de La de Carta de	G = 100, $R_S = 0 \Omega$ , $f = 100 Hz$		50		nV/√Hz
e <sub>NI</sub>	Input voltage noise	G = 100, $R_S = 0 \Omega$ , $f = 1 \text{ kHz}$		50		nV/√Hz
		G = 100, $R_S = 0 \Omega$ , $f = 0.1 Hz$ to 10 Hz		1		$\mu V_{PP}$
		f = 10 Hz		100		fA/√ <del>Hz</del>
i <sub>N</sub>	Input current noise	f = 0.1 Hz to 10 Hz		2		pA <sub>PP</sub>
GAIN		1				
G	Gain equation		1	+ (100 kΩ/R <sub>G</sub> )		V/V
	Range of gain		1		1000	V/V
		$V_S = 5.5 \text{ V}, (V-) + 100 \text{ mV}$ $\leq V_O \leq (V+) - 100 \text{ mV}$				
		G = 1		±0.01%	±0.1%	
	Gain error	G = 10		±0.05%	±0.25%	
		G = 100		±0.07%	±0.25%	
		G = 1000		±0.25%	±0.5%	
	Gain vs temperature, G = 1	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±1	±5	ppm/°C
	Gain vs temperature, G > 1 <sup>(4)</sup>	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±15	±50	ppm/°C
	Gain nonlinearity	$V_S = 5.5 \text{ V}, (V-) + 100 \text{ mV}$ $\leq V_O \leq (V+) - 100 \text{ mV}$				
	Gain nonlinearity, G = 1 to 1000	$R_L = 10 \text{ k}\Omega$		10		ppm
OUTPU	• • • • • • • • • • • • • • • • • • • •					
	Output voltage swing from rail	$V_S = 5.5 \text{ V}, R_L = 10 \text{ k}\Omega$		See Figure 29	50	mV
	Capacitive load drive	0 010 1, 112 10 101		500	33	pF
				000		Ρ'

Total  $V_{OS}$ , referred-to-input =  $(V_{OSI})$  +  $(V_{OSO} / G)$ RTI = Referred-to-input

<sup>300-</sup>hour life test at  $150^{\circ}\text{C}$  demonstrated randomly distributed variation of approximately 1  $\mu\text{V}$ 

Does not include effects of external resistor R<sub>G</sub>



# **Electrical Characteristics (continued)**

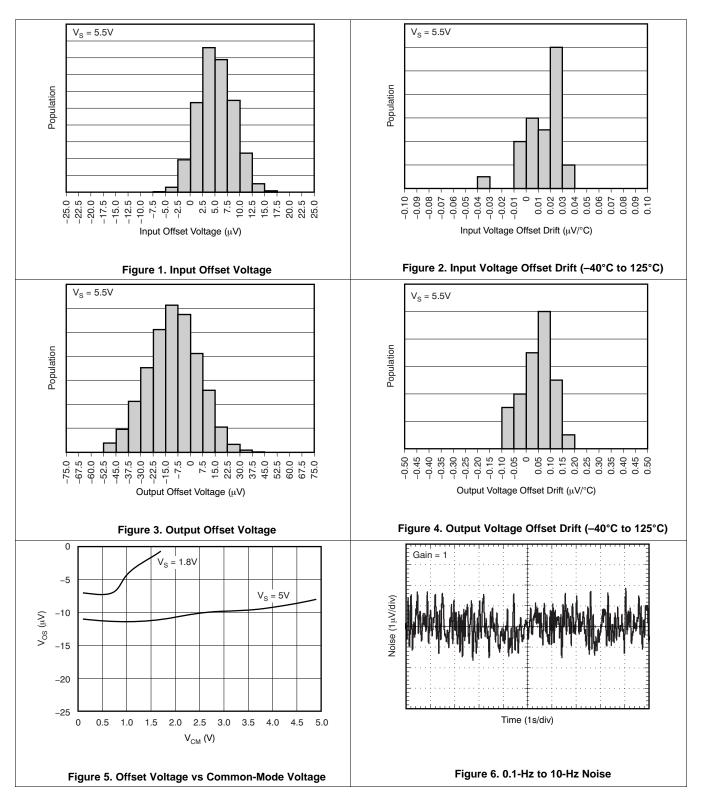
for  $V_S$  = 1.8 V to 5.5 V at  $T_A$  = 25°C,  $R_L$  = 10 k $\Omega$ ,  $V_{REF}$  =  $V_S$  / 2, and G = 1 (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
FREQ	UENCY RESPONSE					
		G = 1		150		kHz
	Dondwidth 2dD	G = 10		35		kHz
	Bandwidth, -3dB	G = 100		3.5		kHz
		G = 1000		350		Hz
CD	01	V <sub>S</sub> = 5 V, V <sub>O</sub> = 4-V step, G = 1		0.16		V/µs
SR	Slew rate	V <sub>S</sub> = 5 V, V <sub>O</sub> = 4-V step, G = 100		0.05		V/µs
	Cattling time a 45 0 040/	V <sub>STEP</sub> = 4 V, G = 1		50		μs
t <sub>S</sub>	Settling time to 0.01%	V <sub>STEP</sub> = 4 V, G = 100		400		μs
	O-Min - tim - t - 0.0040/	V <sub>STEP</sub> = 4 V, G = 1		60		μs
t <sub>S</sub>	Settling time to 0.001%	V <sub>STEP</sub> = 4 V, G = 100		500		μs
	Overload recovery	50% overdrive		75		μs
REFE	RENCE INPUT					
	R <sub>IN</sub>			300		kΩ
	Voltage range		V-		V+	V
POWE	ER SUPPLY					
	V-14	Single voltage range	+1.8		+5.5	V
	Voltage range	Dual voltage range	±0.9		±2.75	V
	Quiescent current	V <sub>IN</sub> = V <sub>S</sub> / 2		50	75	μA
IQ	vs temperature	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$			80	μA
TEMP	ERATURE RANGE					
	Specified temperature range		-40		125	°C
	Operating temperature range		-40		150	°C



# 6.6 Typical Characteristics

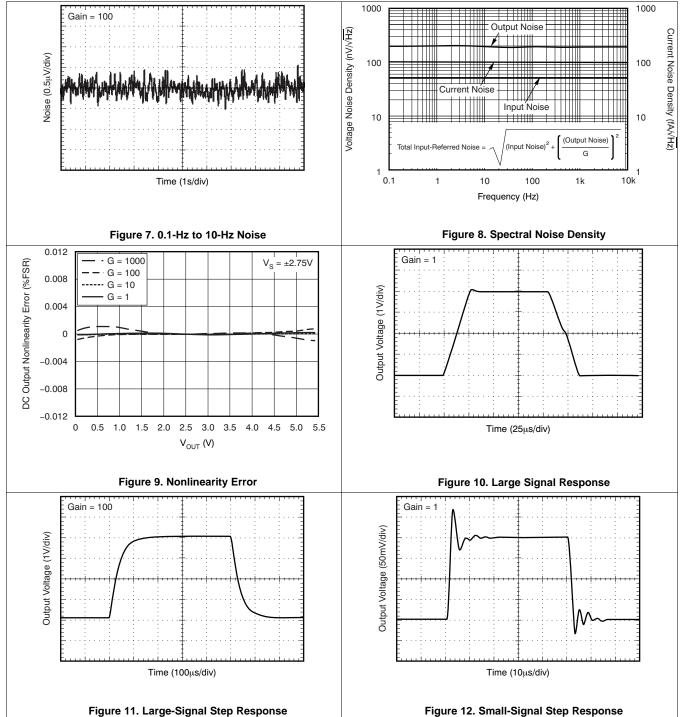
at  $T_A = 25$ °C,  $V_S = 5$  V,  $R_L = 10$  k $\Omega$ ,  $V_{REF} =$  midsupply, and G = 1 (unless otherwise noted)



# TEXAS INSTRUMENTS

# **Typical Characteristics (continued)**

at  $T_A = 25$ °C,  $V_S = 5$  V,  $R_L = 10$  k $\Omega$ ,  $V_{REF} =$  midsupply, and G = 1 (unless otherwise noted)



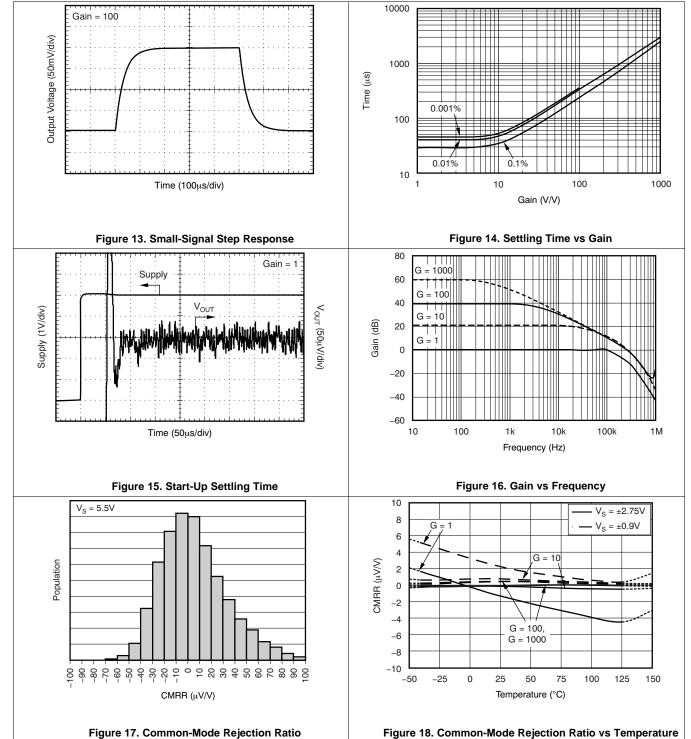
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#### **Typical Characteristics (continued)**

at  $T_A = 25$ °C,  $V_S = 5$  V,  $R_L = 10$  k $\Omega$ ,  $V_{REF} =$  midsupply, and G = 1 (unless otherwise noted)

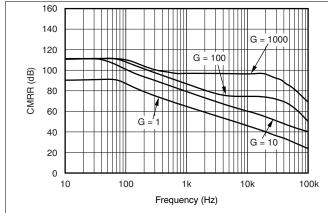


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# TEXAS INSTRUMENTS

# **Typical Characteristics (continued)**

at  $T_A = 25$ °C,  $V_S = 5$  V,  $R_L = 10$  k $\Omega$ ,  $V_{REF} =$  midsupply, and G = 1 (unless otherwise noted)



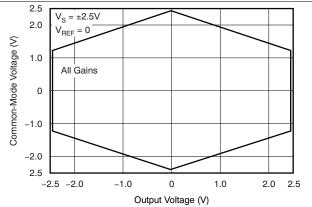
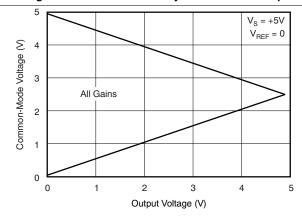


Figure 19. Common-Mode Rejection Ratio vs Frequency

Figure 20. Typical Common-Mode Range vs Output Voltage



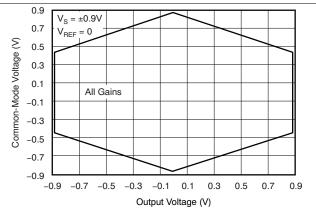
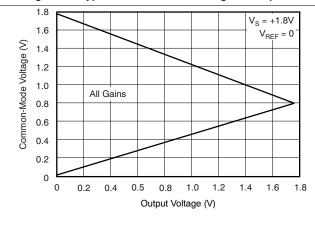


Figure 21. Typical Common-Mode Range vs Output Voltage

Figure 22. Typical Common-Mode Range vs Output Voltage



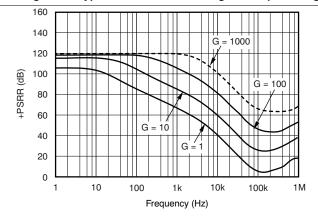


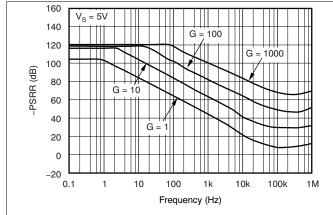
Figure 23. Typical Common-Mode Range vs Output Voltage

Figure 24. Positive Power-Supply Rejection Ratio



# **Typical Characteristics (continued)**

at  $T_A = 25$ °C,  $V_S = 5$  V,  $R_L = 10$  k $\Omega$ ,  $V_{REF} =$  midsupply, and G = 1 (unless otherwise noted)



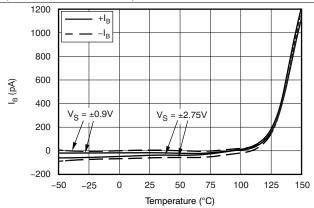
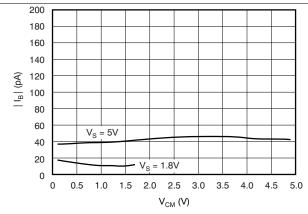


Figure 25. Negative Power-Supply Rejection Ratio

Figure 26. Input Bias Current vs Temperature



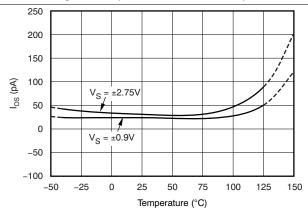


Figure 27. Input Bias Current vs Common-Mode Voltage

Figure 28. Input Offset Current vs Temperature

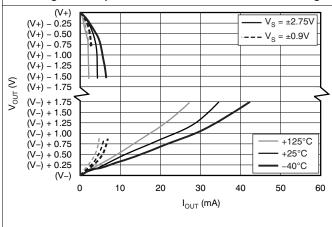


Figure 29. Output Voltage Swing vs Output Current

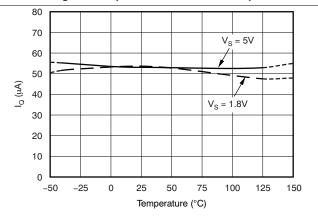
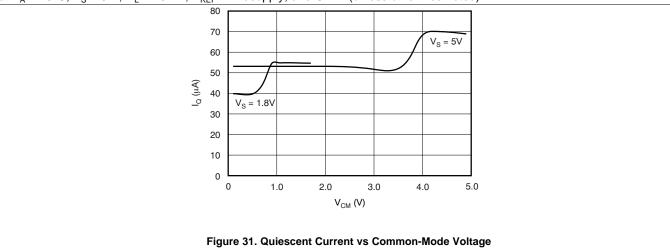


Figure 30. Quiescent Current vs Temperature



# **Typical Characteristics (continued)**

at  $T_A = 25$ °C,  $V_S = 5$  V,  $R_L = 10$  k $\Omega$ ,  $V_{REF} =$  midsupply, and G = 1 (unless otherwise noted)



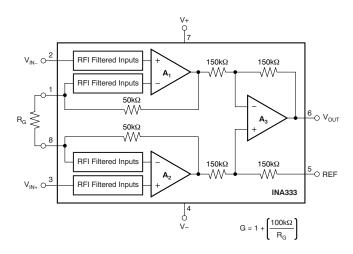


#### 7 Detailed Description

#### 7.1 Overview

The INA333 is a monolithic instrumentation amplifier (INA) based on the precision zero-drift OPA333 (operational amplifier) core. The INA333 also integrates laser-trimmed resistors to ensure excellent common-mode rejection and low gain error. The combination of the zero-drift amplifier core and the precision resistors allows this device to achieve outstanding DC precision and makes the INA333 ideal for many 3.3-V and 5-V industrial applications.

#### 7.2 Functional Block Diagram



#### 7.3 Feature Description

The INA333 is a low-power, zero-drift instrumentation amplifier offering excellent accuracy. The versatile three-operational-amplifier design and small size make the amplifiers ideal for a wide range of applications. Zero-drift chopper circuitry provides excellent DC specifications. A single external resistor sets any gain from 1 to 10,000. The INA333 is laser trimmed for very high common-mode rejection (100 dB at G  $\geq$  100). This devices operate with power supplies as low as 1.8 V, and quiescent current of 50  $\mu$ A, typically.

#### 7.4 Device Functional Modes

#### 7.4.1 Internal Offset Correction

INA333 internal operational amplifiers use an auto-calibration technique with a time-continuous 350-kHz operational amplifier in the signal path. The amplifier is zero-corrected every 8  $\mu$ s using a proprietary technique. Upon power up, the amplifier requires approximately 100  $\mu$ s to achieve specified VOS accuracy. This design has no aliasing or flicker noise.

#### 7.4.2 Input Common-Mode Range

The linear input voltage range of the input circuitry of the INA333 is from approximately 0.1 V below the positive supply voltage to 0.1 V above the negative supply. As a differential input voltage causes the output voltage to increase, however, the linear input range is limited by the output voltage swing of amplifiers A1 and A2. Thus, the linear common-mode input range is related to the output voltage of the complete amplifier. This behavior also depends on supply voltage—see Figure 20.

Input overload conditions can produce an output voltage that appears normal. For example, if an input overload condition drives both input amplifiers to the respective positive output swing limit, the difference voltage measured by the output amplifier is near zero. The output of the INA333 is near 0 V even though both inputs are overloaded.

Product Folder Links: INA333

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#### 8 Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### 8.1 Application Information

The INA333 measures small differential voltage with high common-mode voltage developed between the noninverting and inverting input. The high input impedance makes the INA333 suitable for a wide range of applications. The ability to set the reference pin to adjust the functionality of the output signal offers additional flexibility that is practical for multiple configurations.

#### 8.2 Typical Application

Figure 32 shows the basic connections required for operation of the INA333 device. Good layout practice mandates the use of bypass capacitors placed close to the device pins as shown.

The output of the INA333 device is referred to the output reference (REF) pin, which is normally grounded. This connection must be low-impedance to assure good common-mode rejection. Although 15  $\Omega$  or less of stray resistance can be tolerated while maintaining specified CMRR, small stray resistances of tens of  $\Omega$ s in series with the REF pin can cause noticeable degradation in CMRR.

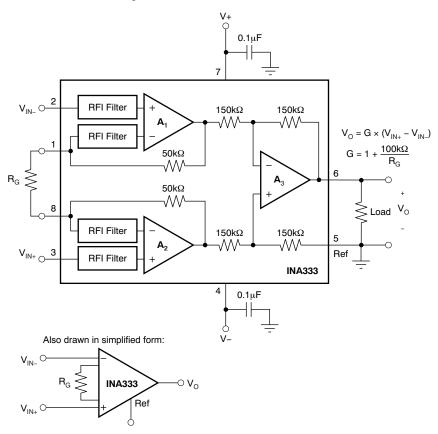


Figure 32. Basic Connections



#### Typical Application (continued)

#### 8.2.1 Design Requirements

The device can be configured to monitor the input differential voltage when the gain of the input signal is set by the external resistor RG. The output signal references to the Ref pin. The most common application is where the output is referenced to ground when no input signal is present by connecting the Ref pin to ground. When the input signal increases, the output voltage at the OUT pin increases, too.

#### 8.2.2 Detailed Design Procedure

#### 8.2.2.1 Setting the Gain

Gain of the INA333 device is set by a single external resistor, R<sub>G</sub>, connected between pins 1 and 8. The value of R<sub>G</sub> is selected according to Equation 1:

$$G = 1 + (100 \text{ k}\Omega / \text{R}_{\text{G}}) \tag{1}$$

Table 1 lists several commonly-used gains and resistor values. The 100 k $\Omega$  in Equation 1 comes from the sum of the two internal feedback resistors of A<sub>1</sub> and A<sub>2</sub>. These on-chip resistors are laser trimmed to accurate absolute values. The accuracy and temperature coefficient of these resistors are included in the gain accuracy and drift specifications of the INA333 device.

The stability and temperature drift of the external gain setting resistor, R<sub>G</sub>, also affects gain. The contribution of R<sub>G</sub> to gain accuracy and drift can be directly inferred from the gain Equation 1. Low resistor values required for high gain can make wiring resistance important. Sockets add to the wiring resistance and contribute additional gain error (possibly an unstable gain error) in gains of approximately 100 or greater. To ensure stability, avoid parasitic capacitance of more than a few picofarads at the R<sub>G</sub> connections. Careful matching of any parasitics on both R<sub>G</sub> pins maintains optimal CMRR over frequency.

DESIRED GAIN	R <sub>G</sub> (Ω)	NEAREST 1% R <sub>G</sub> (Ω)
1	NC <sup>(1)</sup>	NC
2	100k	100k
5	25k	24.9k
10	11.1k	11k
20	5.26k	5.23k
50	2.04k	2.05
100	1.01k	1k
200	502.5	499
500	200.4	200
1000	100.1	100

Table 1. Commonly-Used Gains and Resistor Values

#### 8.2.2.2 Internal Offset Correction

The INA333 device internal operational amplifiers use an auto-calibration technique with a time-continuous 350kHz operational amplifier in the signal path. The amplifier is zero-corrected every 8 µs using a proprietary technique. Upon power-up, the amplifier requires approximately 100 μs to achieve specified V<sub>OS</sub> accuracy. This design has no aliasing or flicker noise.

#### 8.2.2.3 Offset Trimming

Most applications require no external offset adjustment; however, if necessary, adjustments can be made by applying a voltage to the REF pin. Figure 33 shows an optional circuit for trimming the output offset voltage. The voltage applied to REF pin is summed at the output. The operational amplifier buffer provides low impedance at the REF pin to preserve good common-mode rejection.

> Submit Documentation Feedback Product Folder Links: INA333

<sup>(1)</sup> NC denotes no connection. When using the SPICE model, the simulation will not converge unless a resistor is connected to the R<sub>G</sub> pins; use a very large resistor value.



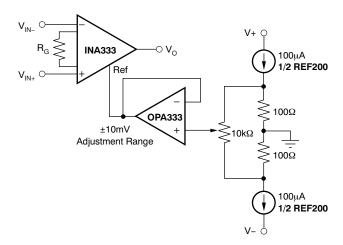


Figure 33. Optional Trimming of Output Offset Voltage

#### 8.2.2.4 Noise Performance

The auto-calibration technique used by the INA333 device results in reduced low frequency noise, typically only 50 nV/ $\sqrt{\text{Hz}}$ , (G = 100). The spectral noise density can be seen in detail in Figure 8. Low frequency noise of the INA333 device is approximately 1  $\mu$ V<sub>PP</sub> measured from 0.1 Hz to 10 Hz, (G = 100).

#### 8.2.2.5 Input Bias Current Return Path

The input impedance of the INA333 device is extremely high—approximately 100 G $\Omega$ . However, a path must be provided for the input bias current of both inputs. This input bias current is typically  $\pm 70$  pA. High input impedance means that this input bias current changes very little with varying input voltage.

Input circuitry must provide a path for this input bias current for proper operation. Figure 34 shows various provisions for an input bias current path. Without a bias current path, the inputs float to a potential that exceeds the common-mode range of the INA333 device, and the input amplifiers will saturate. If the differential source resistance is low, the bias current return path can be connected to one input (see the thermocouple example in Figure 34). With higher source impedance, using two equal resistors provides a balanced input with possible advantages of lower input offset voltage as a result of bias current and better high-frequency common-mode rejection.



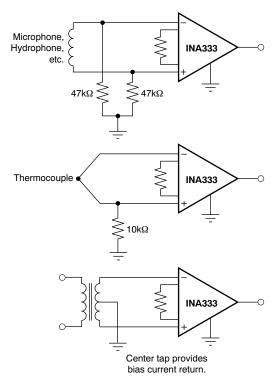


Figure 34. Providing an Input Common-Mode Current Path

#### 8.2.2.6 Input Common-Mode Range

The linear input voltage range of the input circuitry of the INA333 device is from approximately 0.1 V below the positive supply voltage to 0.1 V above the negative supply. As a differential input voltage causes the output voltage to increase, however, the linear input range is limited by the output voltage swing of amplifiers  $A_1$  and  $A_2$ . Thus, the linear common-mode input range is related to the output voltage of the complete amplifier. This behavior also depends on supply voltage—see Figure 20 to Figure 23 in the *Typical Characteristics* section.

Input overload conditions can produce an output voltage that appears normal. For example, if an input overload condition drives both input amplifiers to the respective positive output swing limit, the difference voltage measured by the output amplifier is near zero. The output of the INA333 is near 0 V even though both inputs are overloaded.

#### 8.2.2.7 Operating Voltage

The INA333 operates over a power-supply range of 1.8 V to 5.5 V ( $\pm 0.9$  V to  $\pm 2.75$  V). Supply voltages higher than 7 V (absolute maximum) can permanently damage the device. Parameters that vary over supply voltage or temperature are shown in the *Typical Characteristics* section of this data sheet.

#### 8.2.2.8 Low Voltage Operation

The INA333 device can be operated on power supplies as low as  $\pm 0.9$  V. Most parameters vary only slightly throughout this supply voltage range—see the *Typical Characteristics* section. Operation at very low supply voltage requires careful attention to assure that the input voltages remain within the linear range. Voltage swing requirements of internal nodes limit the input common-mode range with low power-supply voltage. Figure 20 to Figure 23 show the range of linear operation for various supply voltages and gains.

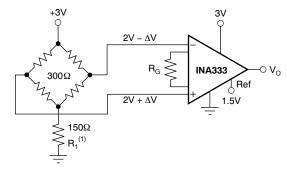
#### 8.2.2.9 Single-Supply Operation

The INA333 device can be used on single power supplies of 1.8 V to 5.5 V. Figure 35 shows a basic single-supply circuit. The output REF pin is connected to mid-supply. Zero differential input voltage demands an output voltage of mid-supply. Actual output voltage swing is limited to approximately 50 mV more than ground, when the load is referred to ground as shown. Figure 29 shows how the output voltage swing varies with output current.



With single-supply operation,  $V_{IN+}$  and  $V_{IN-}$  must both be 0.1 V more than ground for linear operation. For instance, the inverting input cannot be connected to ground to measure a voltage connected to the noninverting input.

To show the issues affecting low voltage operation, consider the circuit in Figure 35. It shows the INA333 device operating from a single 3-V supply. A resistor in series with the low side of the bridge assures that the bridge output voltage is within the common-mode range of the amplifier inputs.



(1) R<sub>1</sub> creates proper common-mode voltage, only for low-voltage operation—see Single-Supply Operation.

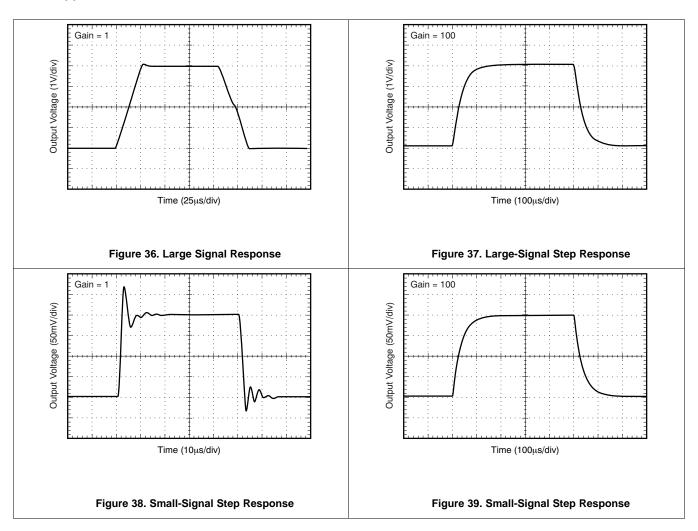
Figure 35. Single-Supply Bridge Amplifier

#### 8.2.2.10 Input Protection

The input pins of the INA333 device are protected with internal diodes connected to the power-supply rails. These diodes clamp the applied signal to prevent it from damaging the input circuitry. If the input signal voltage can exceed the power supplies by more than 0.3 V, the input signal current should be limited to less than 10 mA to protect the internal clamp diodes. This current limiting can generally be done with a series input resistor. Some signal sources are inherently current-limited and do not require limiting resistors.



#### 8.2.3 Application Curves



# 9 Power Supply Recommendations

The minimum power supply voltage for INA333 is 1.8 V and the maximum power supply voltage is 5.5 V. For optimum performance, 3.3 V to 5 V is recommended. TI recommends adding a bypass capacitor at the input to compensate for the layout and power supply source impedance.

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#### 10 Layout

#### 10.1 Layout Guidelines

Attention to good layout practices is always recommended. Keep traces short and, when possible, use a printedcircuit-board (PCB) ground plane with surface-mount components placed as close to the device pins as possible. Place a 0.1-µF bypass capacitor closely across the supply pins. These guidelines should be applied throughout the analog circuit to improve performance and provide benefits such as reducing the electromagneticinterference (EMI) susceptibility.

Instrumentation amplifiers vary in the susceptibility to radio-frequency interference (RFI). RFI can generally be identified as a variation in offset voltage or DC signal levels with changes in the interfering RF signal. The INA333 device has been specifically designed to minimize susceptibility to RFI by incorporating passive RC filters with an 8-MHz corner frequency at the  $V_{IN+}$  and  $V_{IN-}$  inputs. As a result, the INA333 device demonstrates remarkably low sensitivity compared to previous generation devices. Strong RF fields may continue to cause varying offset levels, however, and may require additional shielding.

#### 10.2 Layout Example

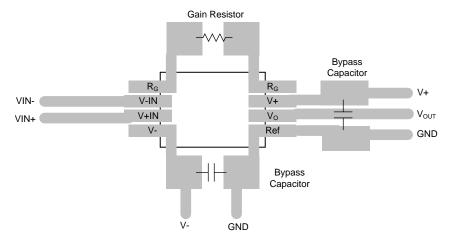


Figure 40. INA333 Layout

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# 11 Device and Documentation Support

#### 11.1 Device Support

#### 11.1.1 Development Support

#### 11.1.1.1 TINA-TI (Free Download Software)

#### Using TINA-TI SPICE-Based Analog Simulation Program with the INA333

TINA is a simple, powerful, and easy-to-use circuit simulation program based on a SPICE engine. TINA-TI is a free, fully functional version of the TINA software, preloaded with a library of macromodels in addition to a range of both passive and active models. It provides all the conventional DC, transient, and frequency domain analysis of SPICE as well as additional design capabilities.

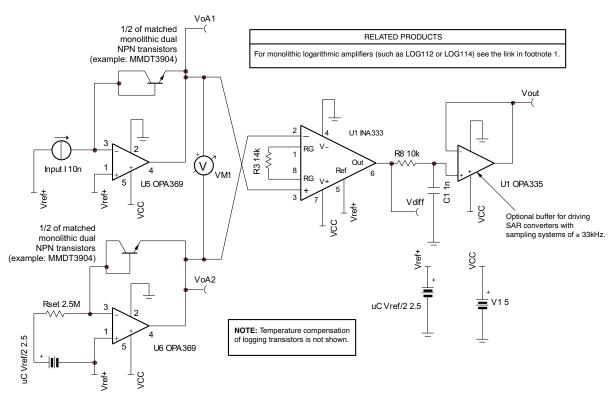
Available as a free download from the Analog eLab Design Center, TINA-TI offers extensive post-processing capability that allows users to format results in a variety of ways.

Virtual instruments offer users the ability to select input waveforms and probe circuit nodes, voltages, and waveforms, creating a dynamic quick-start tool.

Figure 41 and Figure 42 show example TINA-TI circuits for the INA333 device that can be used to develop, modify, and assess the circuit design for specific applications. Links to download these simulation files are given below.

#### NOTE

These files require that either the TINA software (from DesignSoft) or TINA-TI software be installed. Download the free TINA-TI software from the TINA-TI folder.



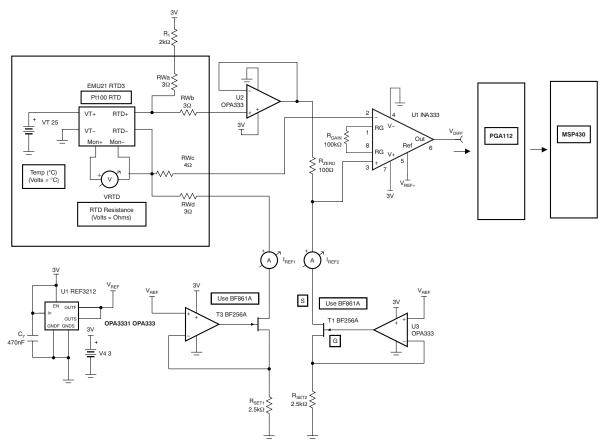
(1) The following link launches the TI logarithmic amplifiers web page: Logarithmic Amplifier Products Home Page

Figure 41. Low-Power Log Function Circuit for Portable Battery-Powered Systems (Example Glucose Meter)



#### **Device Support (continued)**

To download a compressed file that contains the TINA-TI simulation file for this circuit, click the following link: Log Circuit.



RWa, RWb, RWc, and RWd simulate wire resistance. These resistors are included to show the four-wire sense technique immunity to line mismatches. This method assumes the use of a four-wire RTD.

Figure 42. Four-Wire, 3-V Conditioner for a PT100 RTD With Programmable Gain Acquisition System

To download a compressed file that contains the TINA-TI simulation file for this circuit, click the following link: PT100 RTD.

#### 11.2 Documentation Support

#### 11.2.1 Related Documentation

For related documentation see the following:

- Precision, Low-Noise, Rail-to-Rail Output, 36-V, Zero-Drift Operational Amplifiers, SBOS642
- 50µV VOS, 0.25µV/°C, 35µA CMOS OPERATIONAL AMPLIFIERS Zerø-Drift Series, SBOS432
- 4ppm/°C, 100µA, SOT23-6 SERIES VOLTAGE REFERENCE, SBVS058
- Circuit Board Layout Techniques, SLOA089

#### 11.3 Trademarks

All trademarks are the property of their respective owners.

#### 11.4 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.



#### 11.5 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

# 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

www.ti.com 20-Aug-2021

#### **PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
INA333AIDGKR	ACTIVE	VSSOP	DGK	8	2500	RoHS & Green	NIPDAU   NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	1333	Samples
INA333AIDGKRG4	ACTIVE	VSSOP	DGK	8	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	1333	Samples
INA333AIDGKT	ACTIVE	VSSOP	DGK	8	250	RoHS & Green	NIPDAU   NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	1333	Samples
INA333AIDGKTG4	ACTIVE	VSSOP	DGK	8	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	1333	Samples
INA333AIDRGR	ACTIVE	SON	DRG	8	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333A	Samples
INA333AIDRGT	ACTIVE	SON	DRG	8	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333A	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

# **PACKAGE OPTION ADDENDUM**

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

#### **OTHER QUALIFIED VERSIONS OF INA333:**

Automotive: INA333-Q1

NOTE: Qualified Version Definitions:

• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

# **PACKAGE MATERIALS INFORMATION**

www.ti.com 3-Jun-2022

#### TAPE AND REEL INFORMATION



# TAPE DIMENSIONS KO PI BO BO Cavity AO

A0	Dimension designed to accommodate the component width							
В0	Dimension designed to accommodate the component length							
K0	Dimension designed to accommodate the component thickness							
W	Overall width of the carrier tape							
P1	Pitch between successive cavity centers							

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
INA333AIDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA333AIDGKT	VSSOP	DGK	8	250	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA333AIDRGR	SON	DRG	8	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
INA333AIDRGT	SON	DRG	8	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2

www.ti.com 3-Jun-2022



#### \*All dimensions are nominal

7 till dillitorioriorio di o riorimilar							
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
INA333AIDGKR	VSSOP	DGK	8	2500	366.0	364.0	50.0
INA333AIDGKT	VSSOP	DGK	8	250	366.0	364.0	50.0
INA333AIDRGR	SON	DRG	8	3000	356.0	356.0	35.0
INA333AIDRGT	SON	DRG	8	250	210.0	185.0	35.0

# DRG (S-PWSON-N8)

# PLASTIC SMALL OUTLINE NO-LEAD

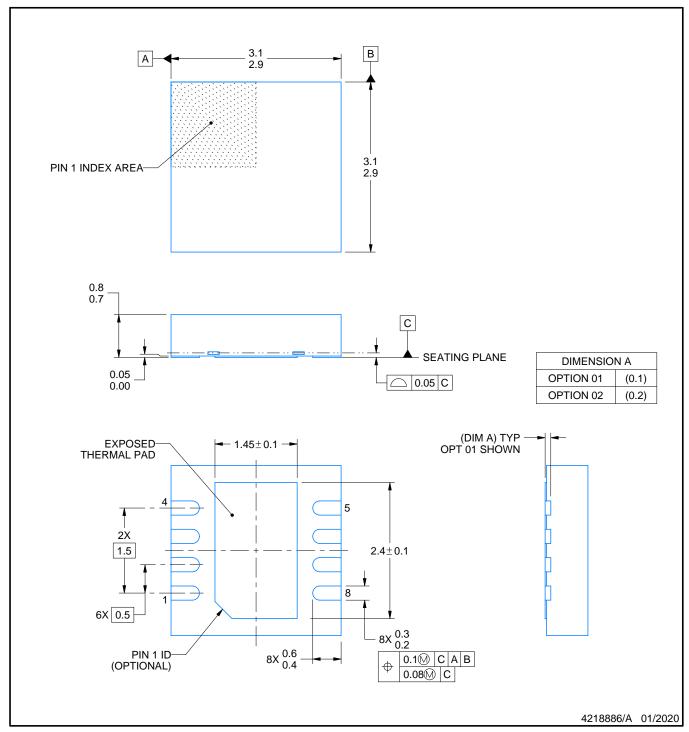


- NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M—1994.
  - B. This drawing is subject to change without notice.
  - C. SON (Small Outline No-Lead) package configuration.
  - The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.
  - E. JEDEC MO-229 package registration pending.





PLASTIC SMALL OUTLINE - NO LEAD

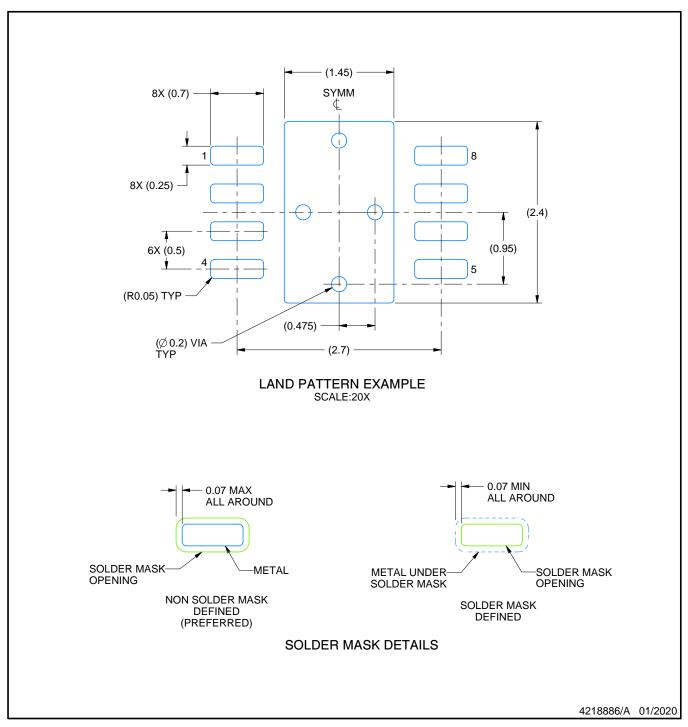


#### NOTES:

- All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
   This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



PLASTIC SMALL OUTLINE - NO LEAD

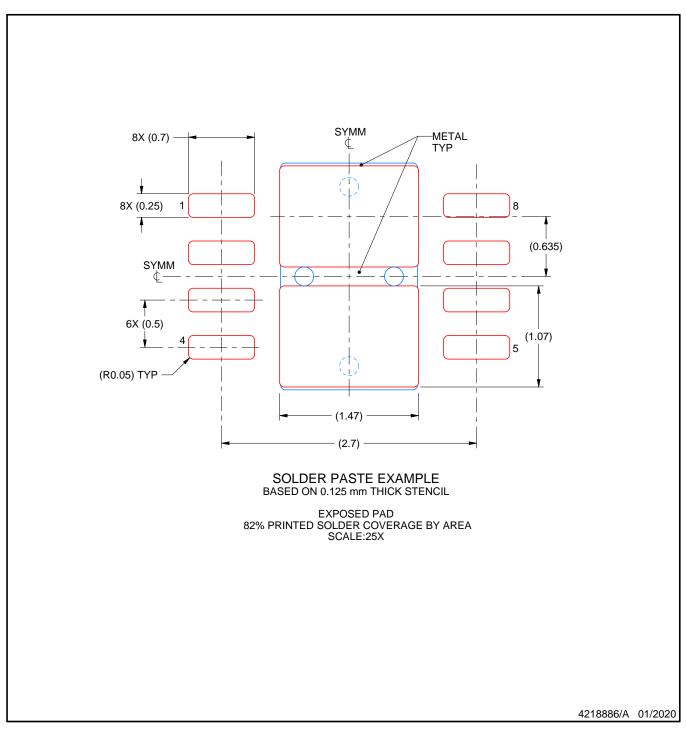


NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.





SMALL OUTLINE PACKAGE



#### NOTES:

PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187.



SMALL OUTLINE PACKAGE



NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.
- 9. Size of metal pad may vary due to creepage requirement.



SMALL OUTLINE PACKAGE



NOTES: (continued)

- 11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 12. Board assembly site may have different recommendations for stencil design.



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