

ISO308x Isolated 5-V Full- and Half-Duplex RS-485 Transceivers

1 Features

- Meets or exceeds TIA/EIA RS-485 requirements
- Signaling rates up to 20 Mbps
- 1/8 unit load – up to 256 nodes on a bus
- Thermal shutdown protection
- Low bus capacitance – 16 pF (typical)
- 50 kV/μs typical transient immunity
- Fail-safe receiver for bus open, short, idle
- 3.3-V inputs are 5-V tolerant
- Bus-pin ESD protection
 - 12-kV HBM between bus pins and GND2
 - 6-kV HBM between bus pins and GND1
- Safety-related certifications:
 - 4000- V_{PK} basic insulation, 560 V_{PK} V_{IORM} per DIN EN IEC 60747-17 (VDE 0884-17)
 - 2500 V_{RMS} isolation per UL 1577
 - 4000 V_{PK} isolation per CSA 62368-1

2 Applications

- Security systems
- Chemical production
- Factory automation
- Motor and motion control
- HVAC and building automation networks
- Networked security stations

3 Description

The ISO3080 and ISO3086 devices are isolated full-duplex differential line drivers and receivers while the ISO3082 and ISO3088 devices are isolated half-duplex differential line transceivers for TIA/EIA 485/422 applications.

These devices are ideal for long transmission lines because the ground loop is broken to allow for a much larger common-mode voltage range. The symmetrical isolation barrier of the device is tested to provide 2500 V_{RMS} of isolation for 60 s per UL 1577 between the bus-line transceiver and the logic-level interface.

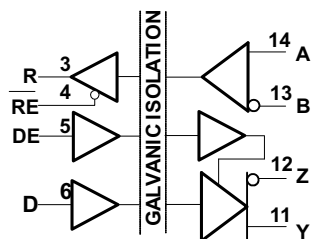
Any cabled I/O can be subjected to electrical noise transients from various sources. These noise transients can cause damage to the transceiver or nearby sensitive circuitry if they are of sufficient magnitude and duration. These isolated devices can significantly increase protection and reduce the risk of damage to expensive control circuits.

The ISO3080, ISO3082, ISO3086, and ISO3088 device are qualified for use from -40°C to $+85^{\circ}\text{C}$.

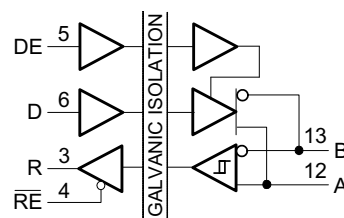
Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
ISO3080	SOIC (16)	10.30 mm × 7.50 mm
ISO3082		
ISO3086		
ISO3088		

(1) For all available packages, see the orderable addendum at the end of the data sheet.



ISO3080, ISO3086 Function Diagram



ISO3082, ISO3088 Function Diagram



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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision I (April 2017) to Revision J (August 2023)	Page
• Updated the numbering format for tables, figures, and cross-references throughout the document.....	1
• Updated Thermal Characteristics, Safety Limiting Values, and Thermal Derating Curves to provide more accurate system-level thermal calculations.....	6
• Updated electrical and switching characteristics to match device performance.....	8
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Changes from Revision H (December 2015) to Revision I (April 2017)	Page
• Switched the R and D pins of the master device in the <i>Typical RS-485 Network With Full-Duplex Transceivers</i> figure.....	22
• Added the <i>Receiving Notification of Documentation Updates</i> section.....	26
• Changed the <i>Electrostatic Discharge Caution</i> statement.....	26
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Changes from Revision G (July 2015) to Revision H (December 2015)	Page
• Moved the last list item "Routing the high-speed traces..." to the second list items in <i>Layout Guidelines</i> section.....	24
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Changes from Revision F (May 2015) to Revision G (July 2015)	Page
• Changed the <i>Layout Guidelines</i> section	24
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Changes from Revision E (September 2011) to Revision F (May 2015)	Page
• Added <i>ESD Rating</i> table, <i>Thermal Information</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i> , <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Layout</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section.....	1
• Changed <i>Features</i> list item From: IEC 60747-5-2 (VDE 0884, Rev. 2) To: DIN V VDE V 0884-10 (VDE V 0884-10): 2006-12.....	1
• VDE standard changed to DIN V VDE V 0884-10 (VDE V 0884-10):2006-12.....	1

Changes from Revision D (January 2011) to Revision E (September 2011) Page

- Changed *Features* list item From: 16 kV HBM To: 12 kV HBM..... **1**

Changes from Revision C (October 2009) to Revision D (January 2011) Page

- Changed graph for " DW-16 θ_{JC} Thermal Derating Curve per IEC 60747-5-2 " , *Thermal Derating Curve* **12**
- Added the *ISO3086 Recommended Minimum Differential Input Voltage vs Signaling Rate* graph..... **13**
- Added note to bottom of first page of the *Parameter Measurement Information* **15**
- Added Footnotes to the *Driver Function Table* and *Receiver Function Table* **20**

Changes from Revision A (June 2008) to Revision B (December 2008) Page

- Changed *Features* bullet From: 4000- V_{PEAK} Isolation, To: 4000- V_{PEAK} Isolation,, 560- V_{PEAK} V_{IORM} **1**

5 Pin Configuration and Functions

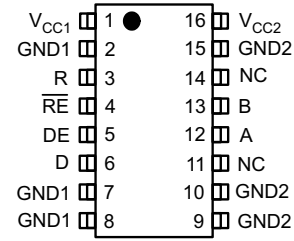
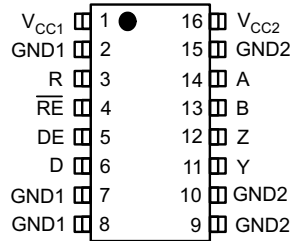


Figure 5-1. ISO3080 and ISO3086 DW Package 16-Pin SOIC Top View

Figure 5-2. ISO3082 and ISO3088 DW Package 16-Pin SOIC Top View

Table 5-1. Pin Functions

NAME	PIN		I/O	DESCRIPTION
	ISO3080, ISO3086	ISO3082, ISO3088		
A	14	—	I	Receiver noninverting input on the bus-side
	—	12	I/O	Transceiver noninverting Input or output (I/O) on the bus-side
B	13	—	I	Receiver inverting Input on the bus-side
	—	13	I/O	Transceiver inverting input or output (I/O) on the bus-side
D	6	6	I	Driver input
DE	5	5	I	Enables (when high) or disables (when low or open) driver output of ISO308x
GND1	2	2	—	Ground connection for V_{CC1}
	7	7		
	8	8		
GND2	9	9	—	Ground connection for V_{CC2}
	10	10		
	15	15		
NC	—	11	—	No connect
	—	14		
R	3	3	O	Receiver output
RE	4	4	I	Disables (when high or open) or enables (when low) receiver output of ISO308x
V_{CC1}	1	1	—	Power supply, V_{CC1}
V_{CC2}	16	16	—	Power supply, V_{CC2}
Y	11	—	O	Driver noninverting output
Z	12	—	O	Driver inverting output

6 Specifications

6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
V_{CC} ⁽²⁾	Supply voltage, V_{CC1} , V_{CC2}	-0.3	6	V
V_O	Voltage at any bus I/O terminal	-9	14	V
V_{IT}	Voltage input, transient pulse, A, B, Y, and Z (through 100 Ω , see Figure 21)	-50	50	V
V_I	Voltage input at any D, DE or RE terminal	-0.5	6	V
I_O	Receiver output current	-10	10	mA
T_J	Junction temperature		150	$^{\circ}$ C
T_{STG}	Storage temperature	-65	150	$^{\circ}$ C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values except differential I/O bus voltages are with respect to network ground terminal and are peak voltage values.

6.2 ESD Ratings

		VALUE	UNIT	
$V_{(ESD)}$ Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	Bus pins and GND1	± 6000	V
		Bus pins and GND2	± 12000	V
		All pins	± 4000	V
	Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾		± 1000	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

		MIN	TYP	MAX	UNIT
V_{CC1}	Logic-side supply voltage	3.15		5.5	V
V_{CC2}	Bus-side supply voltage	4.5	5	5.5	V
V_{OC}	Voltage at either bus I/O pin A, B	-7		12	V
V_{IH}	High-level input voltage (D, DE, \overline{RE} inputs)	2		V_{CC}	V
V_{IL}	Low-level input voltage (D, DE, \overline{RE} inputs)	0		0.8	V
V_{ID}	Differential input voltage, A with respect to B	-12		12	V
V_{ID}	Differential input voltage, Dynamic (ISO3086)	See Figure 10			V
R_L	Differential load resistance	54	60		Ω
I_O	Output current, Driver	-60		60	mA
I_O	Output current, Receiver	-8		8	mA
T_A	Operating ambient temperature (ISO15 and ISO35)	-40		85	$^{\circ}$ C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		ISO308x	UNIT
		DW (SOIC)	
		16 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	79.6	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	39.7	°C/W
R _{θJB}	Junction-to-board thermal resistance	44.7	°C/W
Ψ _{JT}	Junction-to-top characterization parameter	13.2	°C/W
Ψ _{JB}	Junction-to-board characterization parameter	44.0	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	—	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics application report](#).

6.5 Insulation Specifications

PARAMETER		TEST CONDITIONS	VALUE	UNIT
			DW-16	
CLR	External clearance ⁽¹⁾	Shortest terminal-to-terminal distance through air	8	mm
CPG	External creepage ⁽¹⁾	Shortest terminal-to-terminal distance across the package surface	8	mm
DTI	Distance through the insulation	Minimum internal gap (internal clearance)	8	um
CTI	Comparative tracking index	DIN EN 60112 (VDE 0303-11); IEC 60112	>400	V
	Material group	According to IEC 60664-1	II	
	Overvoltage category per IEC 60664-1	Rated mains voltage ≤ 150 V _{RMS}	I-IV	
		Rated mains voltage ≤ 300 V _{RMS}	I-III	
DIN EN IEC 60747-17 (VDE 0884-17) ⁽²⁾				
V _{IORM}	Maximum repetitive peak isolation voltage	AC voltage (bipolar)	560	V _{PK}
V _{IOTM}	Maximum transient isolation voltage	V _{TEST} = V _{IOTM} , t = 60 s (qualification); V _{TEST} = 1.2 x V _{IOTM} , t = 1 s (100% production)	4000	V _{PK}
q _{pd}	Apparent charge ⁽³⁾	Method b; At routine test (100% production) V _{ini} = 1.2 x V _{IOTM} , t _{ini} = 1 s; V _{pd(m)} = 1.5x V _{IORM} , t _m = 1 s	≤5	pC
C _{IO}	Barrier capacitance, input to output ⁽⁴⁾	V _{IO} = 0.4 x sin(2πft), f = 1 MHz	2	pF
C _I	Input capacitance to ground	V _I = VCC/ 2 + 0.4×sin(2πft), f = 1 MHz, VCC = 5 V	2	pF
R _{IO}	Isolation resistance ⁽⁴⁾	V _{IO} = 500 V, T _A = 25°C	>10 ¹²	Ω
		V _{IO} = 500 V, T _S = 150°C	>10 ⁹	
	Pollution degree		2	
	Climatic category		40/125/21	
UL 1577				
V _{ISO}	Maximum withstanding isolation voltage	V _{TEST} = V _{ISO} , t = 60 s (qualification), V _{TEST} = 1.2 x V _{ISO} , t = 1 s (100% production)	2500	V _{RMS}

- Creepage and clearance requirements should be applied according to the specific equipment isolation standards of an application. Care should be taken to maintain the creepage and clearance distance of a board design to ensure that the mounting pads of the isolator on the printed-circuit board do not reduce this distance. Creepage and clearance on a printed-circuit board become equal in certain cases. Techniques such as inserting grooves and/or ribs on a printed-circuit board are used to help increase these specifications.
- This coupler is suitable for *basic electrical insulation* only within the safety ratings. Compliance with the safety ratings shall be ensured by means of suitable protective circuits.
- Apparent charge is electrical discharge caused by a partial discharge (pd).

- (4) All pins on each side of the barrier tied together creating a two-terminal device.

6.6 Safety-Related Certifications

VDE	CSA	UL
Certified according to DIN EN IEC 60747-17 (VDE 0884-17)	Certified according to IEC 60950-1 and IEC 62368-1	Recognized under UL 1577 Component Recognition Program
Basic insulation, 4000 V _{PK} Maximum transient isolation voltage, 560 V _{PK} Maximum repetitive peak isolation voltage	4000V _{RMS} Isolation Rating; Reinforced insulation per CSA 60950-1 and IEC 60950-1 148 V _{RMS} working voltage; Basic insulation per CSA 62368-1 and IEC 62368-1 300V _{RMS} working voltage	Single protection, 2500 V _{RMS}
Certificate number: 40047657	Master contract number: 220991	File number: E181974

6.7 Safety Limiting Values

Safety limiting⁽¹⁾ intends to minimize potential damage to the isolation barrier upon failure of input or output circuitry.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
DW-16 PACKAGE						
I _S	Safety input, output, or supply current	R _{θJA} = 79.6°C/W, V _I = 5.5 V, T _J = 150°C, T _A = 25°C, see			286	mA
T _S	Maximum safety temperature				150	°C

- (1) The maximum safety temperature, T_S, has the same value as the maximum junction temperature, T_J, specified for the device. The I_S and P_S parameters represent the safety current and safety power respectively. The maximum limits of I_S and P_S should not be exceeded. These limits vary with the ambient temperature, T_A. The junction-to-air thermal resistance, R_{θJA}, in the table is that of a device installed on a high-K test board for leaded surface-mount packages. Use these equations to calculate the value for each parameter:
 $T_J = T_A + R_{\theta JA} \times P$, where P is the power dissipated in the device.
 $T_{J(max)} = T_S = T_A + R_{\theta JA} \times P_S$, where T_{J(max)} is the maximum allowed junction temperature.
 $P_S = I_S \times V_I$, where V_I is the maximum input voltage.

6.8 Electrical Characteristics: Driver

All typical specs are at $V_{CC1}=3.3V$, $V_{CC2}=5V$, $T_A=27^\circ C$, (Min/Max specs are over recommended operating conditions unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$ V_{OD} $	Driver differential-output voltage magnitude	$I_O = 0$ mA, no load	3	4.3	V_{CC2}	V
		$R_L = 54 \Omega$, See Figure 11	1.5	2.3		V
		$R_L = 100 \Omega$ (RS-422), See Figure 11	2	2.3		V
		V_{test} from -7 V to $+12$ V, See Figure 12	1.5			V
$\Delta V_{OD} $	Change in differential output voltage between two states	See Figure 11 and Figure 12	-200		200	mV
V_{OC}	Common-mode output voltage	See Figure 13	1	2.6	3	V
$\Delta V_{OC(SS)}$	change in steady-state common-mode output voltage between two states	See Figure 13	-100		100	mV
$V_{OC(PP)}$	Peak-to-peak common-mode output voltage	See Figure 13		0.5		V
I_I	Input current	D, DE, V_I at 0 V or V_{CC1}	-10		10	μA
I_{OZ}	High-impedance state output current	ISO3082, ISO3088		See the receiver bias input current parameter		
		ISO3080, ISO3086; V_Y or $V_Z = 12$ V, $V_{CC} = 0$ V or 5 V, DE = 0 V, Other input at 0 V			1	μA
		ISO3080, ISO3086; V_Y or $V_Z = -7$ V, $V_{CC} = 0$ V or 5 V, DE = 0 V, Other input at 0 V	-1			μA
I_{OS}	Short-circuit output current	V_A or V_B at -7 V, Other input at 0 V	-200		200	mA
		V_A or V_B at 12 V, Other input at 0 V	-200		200	mA
CMTI	Common-mode transient immunity	$V_I = V_{CC}$ or 0 V, See Figure 14 and Figure 15	25	50		kV/ μs

6.9 Electrical Characteristics: Receiver

All typical specs are at $V_{CC1}=3.3V$, $V_{CC2}=5V$, $T_A=27^\circ C$, (Min/Max specs are over recommended operating conditions unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{IT+}	Positive-going input threshold voltage	$I_O = -8$ mA		-85	-10	mV
V_{IT-}	Negative-going input threshold voltage	$I_O = 8$ mA	-200	-115		mV
V_{hys}	Input hysteresis ($V_{IT+} - V_{IT-}$)			30		mV
V_{OH}	High-level output voltage	$V_{ID} = 200$ mV, $I_O = -8$ mA, 3.3 V V_{CC1}	$V_{CC1} - 0.4$	3.1		V
	High-level output voltage	$V_{ID} = 200$ mV, $I_O = -8$ mA, 5 V V_{CC1}	4	4.8		V
V_{OL}	Low-level output voltage	$V_{ID} = -200$ mV, $I_O = 8$ mA, 3.3 V V_{CC1}		0.15	0.4	V
	Low-level output voltage	$V_{ID} = -200$ mV, $I_O = 8$ mA, 5 V V_{CC1}		0.15	0.4	V
$I_{O(Z)}$	Output high-impedance current on the R pin	$V_I = -7$ to 12 V, Other input = 0 V	-1		1	μA

All typical specs are at $V_{CC1}=3.3V$, $V_{CC2}=5V$, $T_A=27^{\circ}C$, (Min/Max specs are over recommended operating conditions unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
I_I	Bus input current	V_A or $V_B = 12\text{ V}$, Other input at 0 V		0.04	0.1	mA
		V_A or $V_B = 12\text{ V}$, $V_{CC} = 0$, Other input at 0 V		0.06	0.13	mA
		V_A or $V_B = -7\text{ V}$, Other input at 0 V	-0.1	-0.04		mA
		V_A or $V_B = -7\text{ V}$, $V_{CC} = 0$, Other input at 0 V	-0.05	-0.03		mA
I_{IH}	High-level input current, RE	$V_{IH} = 2\text{ V}$	-10		10	μA
I_{IL}	Low-level input current, RE	$V_{IL} = 0.8\text{ V}$	-10		10	μA
R_{ID}	Differential input resistance	A, B	48			kohm
C_{ID}	Differential input capacitance	Test input signal is a 1.5-MHz sine wave with 1- V_{PP} amplitude. C_D is measured across A and B		16		pF
C_I	Input capacitance to ground	$V_I = 0.4 \sin(4E6\pi t)$		8		pF

6.10 Supply Current

Bus loaded or unloaded (over recommended operating conditions unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DRIVER ENABLED, RECEIVER DISABLED					
I _{CC1}	Logic-side supply current, \overline{RE} at 0 V or V _{CC} , DE at 0 V or V _{CC1} , 3.3-V V _{CC1}			8	mA
	Logic-side supply current, \overline{RE} at 0 V or V _{CC} , DE at 0 V or V _{CC1} , 5-V V _{CC1}			10	mA
I _{CC2}	Bus-side supply current, \overline{RE} at 0 V or V _{CC} , DE at 0 V, No load			15	mA

6.11 Switching Characteristics: Driver

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
ALL DEVICES						
t _{PHL} , t _{PLH}	Propagation delay	ISO3080/82, See Figure 14		0.7	1.3	μs
		ISO3086/88, See Figure 14		25	45	ns
PWD	Pulse width distortion ⁽¹⁾ , t _{PHL} – t _{PLH}	ISO3080/82, See Figure 14		20	200	ns
		ISO3086/88, See Figure 14		3	9	ns
t _r , t _f	Differential output rise time and fall time	ISO3080/82, See Figure 14	0.5	0.9	1.5	μs
		ISO3086/88, See Figure 14		7	15	ns
t _{PZH} , t _{PZL}	Propagation delay, high-impedance-to-high-level output and high-impedance-to-low-level output	ISO3080/82, See Figure 15 and Figure 16, DE at 0 V, 50% V _o		2.5	7	μs
		ISO3080/82, See Figure 15 and Figure 16, DE at 0 V, 90% V _o		1.8		μs
		ISO3086/88, See Figure 15 and 16		25	55	ns
t _{PHZ} , t _{PLZ}	Propagation delay, high-level-to-highimpedance output and low-level to highimpedance output	ISO3080/28, See Figure 15 and 16		95	225	ns
		ISO3086/88, See Figure 15 and 16		25	55	ns

(1) Also known as pulse skew.

6.12 Switching Characteristics: Receiver

All typical specs are at V_{CC1}=3.3V, V_{CC2}=5V, T_A=27°C, (Min/Max specs are over recommended operating conditions unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
ALL DEVICES						
t _r , t _f	Differential output rise time and fall time	See Figure 18		1		ns
t _{PHL} , t _{PLH}	Propagation delay			90	125	ns
PWD	Pulse width distortion ⁽¹⁾ , t _{PHL} – t _{PLH}	ISO3080/82 See Figure 18		4	20	ns
PWD	Pulse width distortion ⁽¹⁾ , t _{PHL} – t _{PLH}	ISO3086/88 See Figure 18		4	12	ns
t _{PHZ} , t _{PZH}	Propagation delay, high-level-tohigh-impedance output and highimpedance-to-high-level output	See Figure 19			22	ns
t _{PZL} , t _{PLZ}	Propagation delay, highimpedance-to-low-level output and low-level-to-high-impedance output	See Figure 20			22	ns

(1) Also known as pulse skew

6.13 Insulation Characteristics Curves

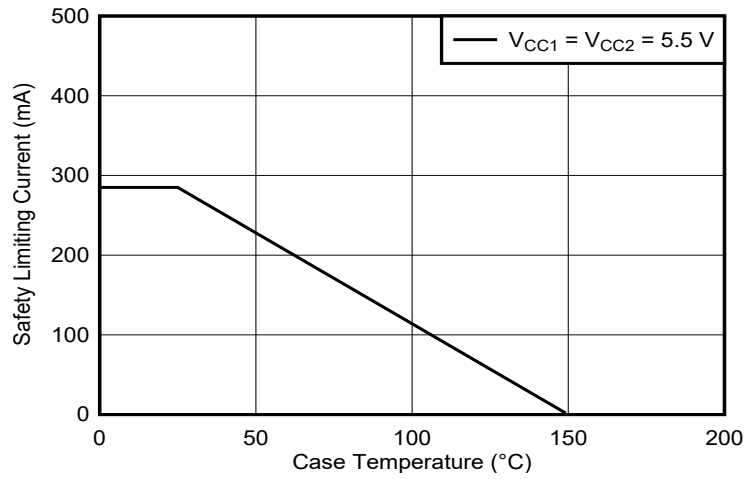


Figure 6-1. Thermal Derating Curve for Limiting Current per VDE

6.14 Typical Characteristics

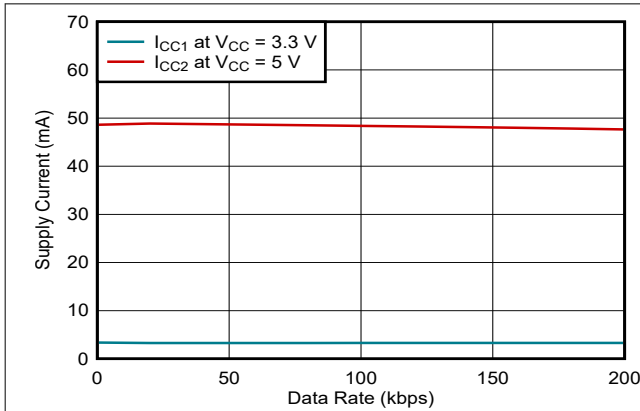


Figure 6-2. ISO3080 Supply Current vs Data Rate With Load

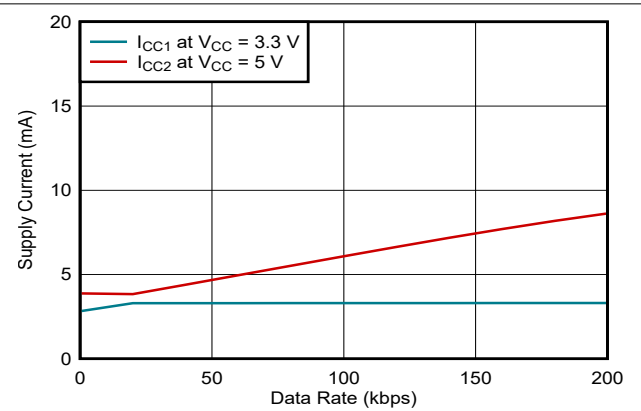


Figure 6-3. ISO3080 Supply Current vs Data Rate With No Load

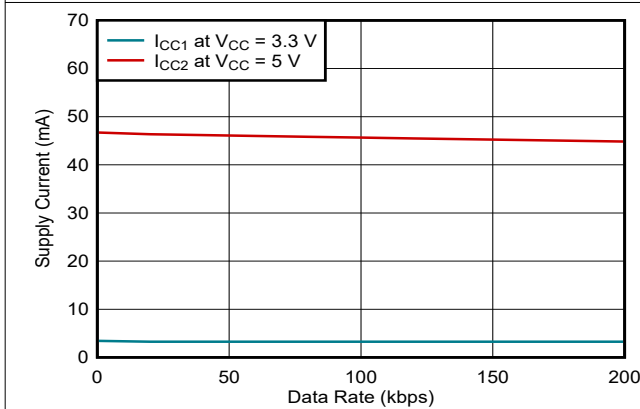


Figure 6-4. ISO3082 Supply Current vs Data Rate With Load

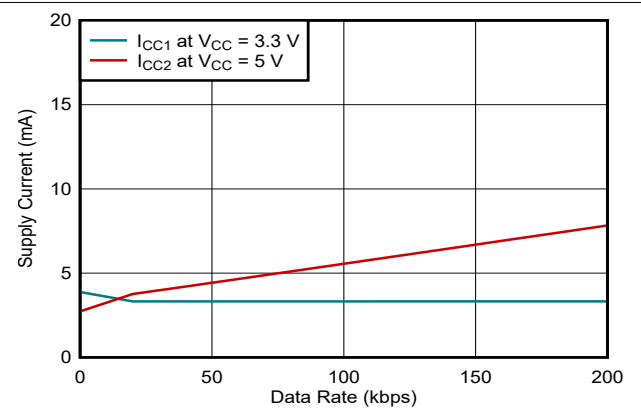


Figure 6-5. ISO3082 Supply Current vs Data Rate With No Load

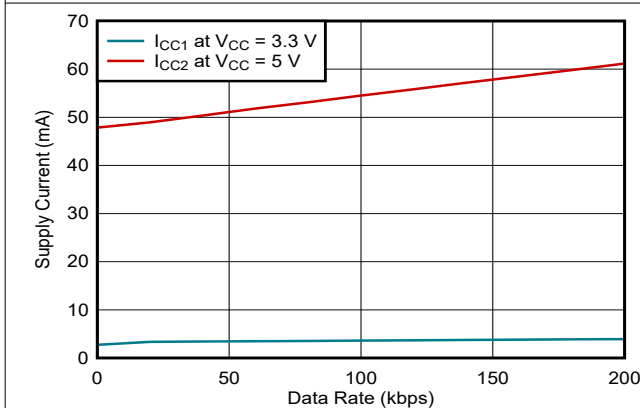


Figure 6-6. ISO3086 Supply Current vs Data Rate With Load

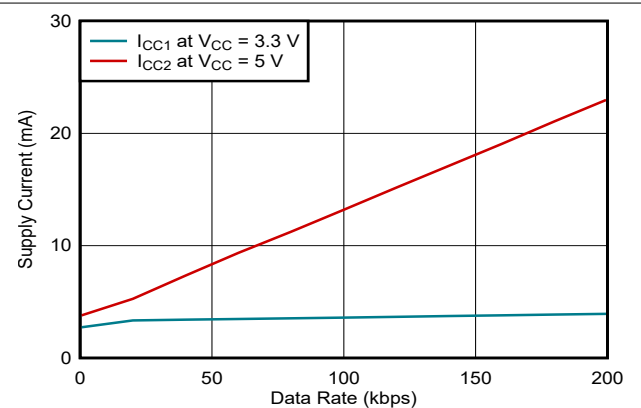


Figure 6-7. ISO3086 Supply Current vs Data Rate With No Load

6.14 Typical Characteristics (continued)

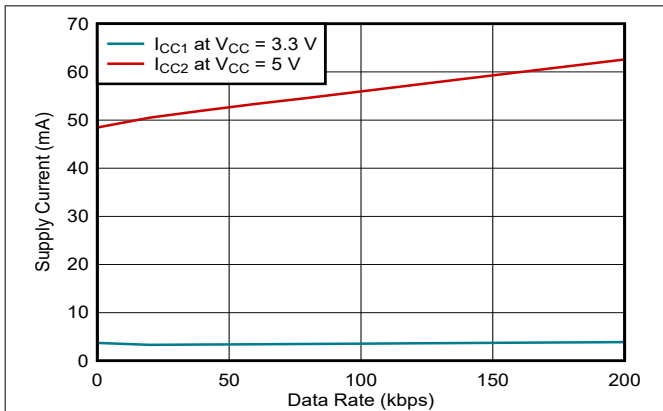


Figure 6-8. ISO3088 Supply Current vs Data Rate With Load

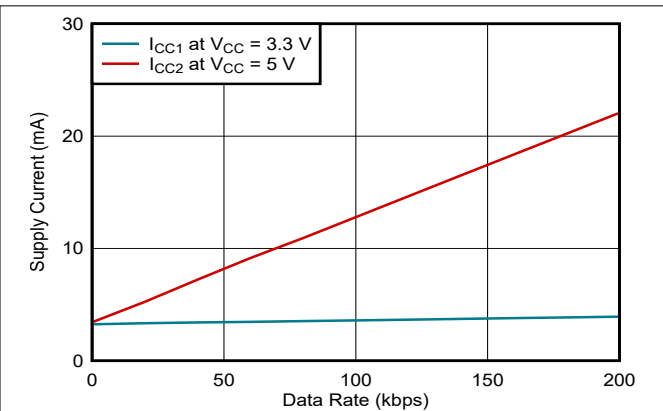


Figure 6-9. ISO3088 Supply Current vs Data Rate With No Load

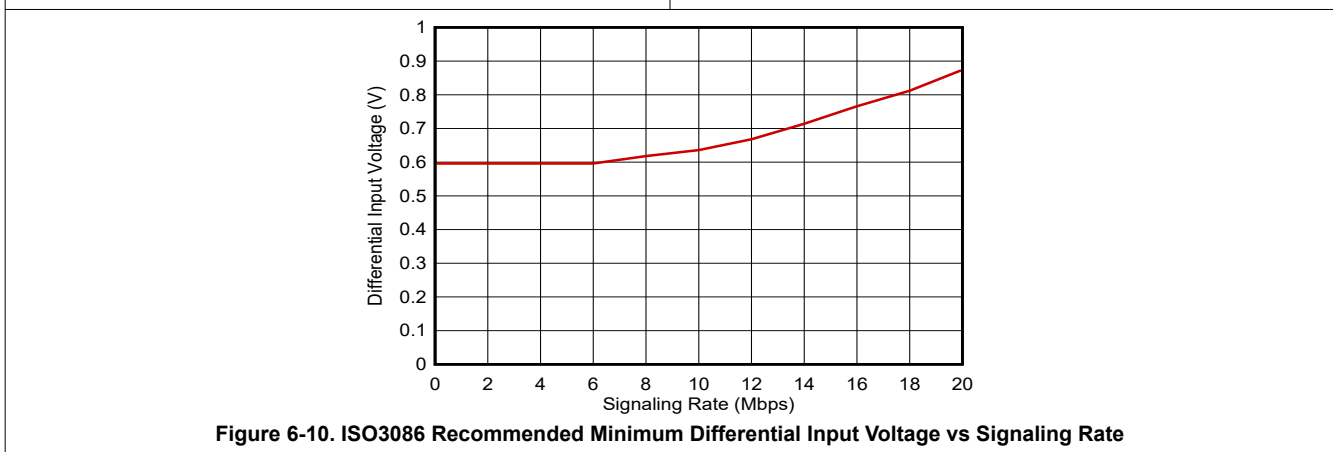


Figure 6-10. ISO3086 Recommended Minimum Differential Input Voltage vs Signaling Rate

7 Parameter Measurement Information

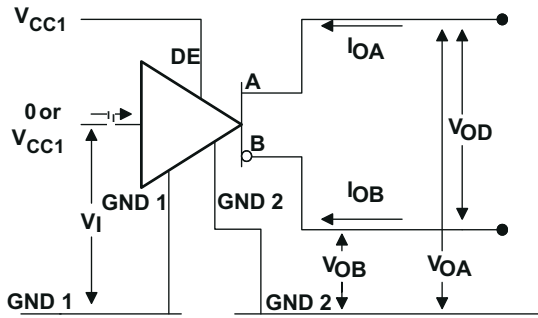


Figure 7-1. Driver V_{OD} Test and Current Definitions

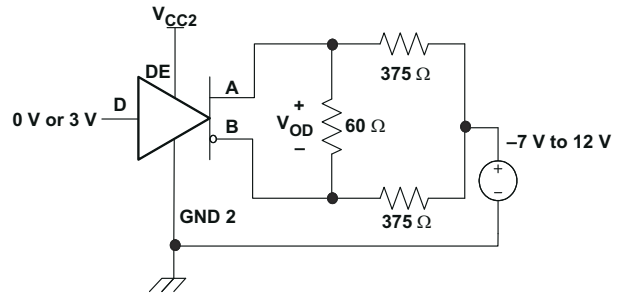


Figure 7-2. Driver V_{OD} With Common-Mode Loading Test Circuit

Note

Unless otherwise stated, test circuits are shown for half-duplex devices, ISO3082 and ISO3088. For full-duplex devices, the driver output pins are Y and Z.

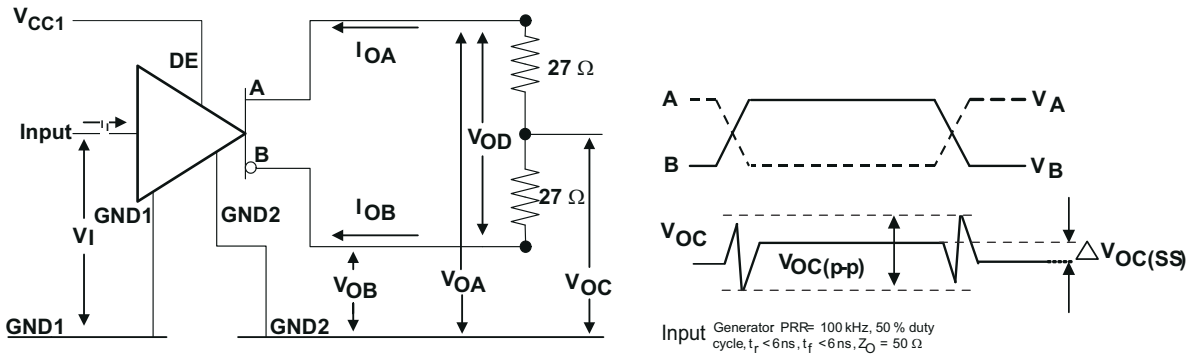


Figure 7-3. Test Circuit and Waveform Definitions For The Driver Common-Mode Output Voltage

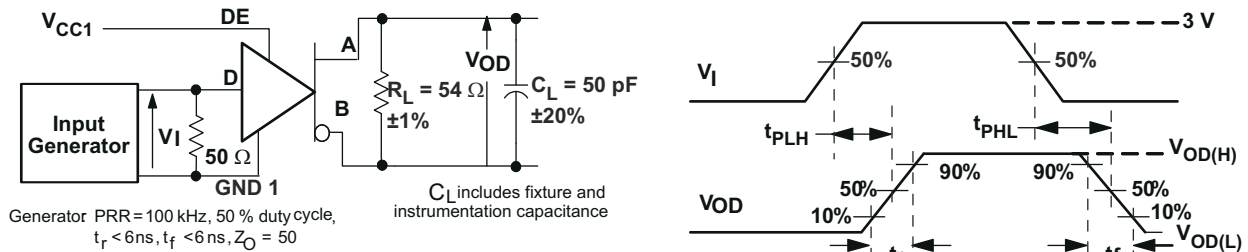


Figure 7-4. Driver Switching Test Circuit and Voltage Waveforms

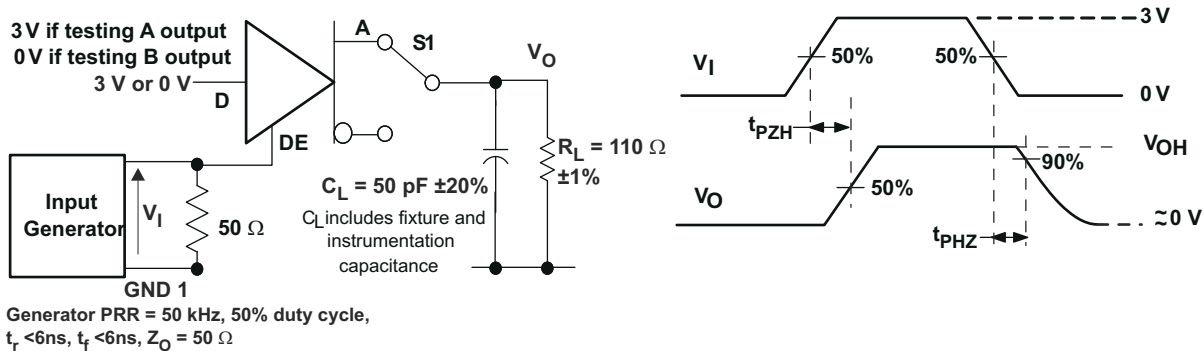


Figure 7-5. Driver High-Level Output Enable and Disable Time Test Circuit and Voltage Waveforms

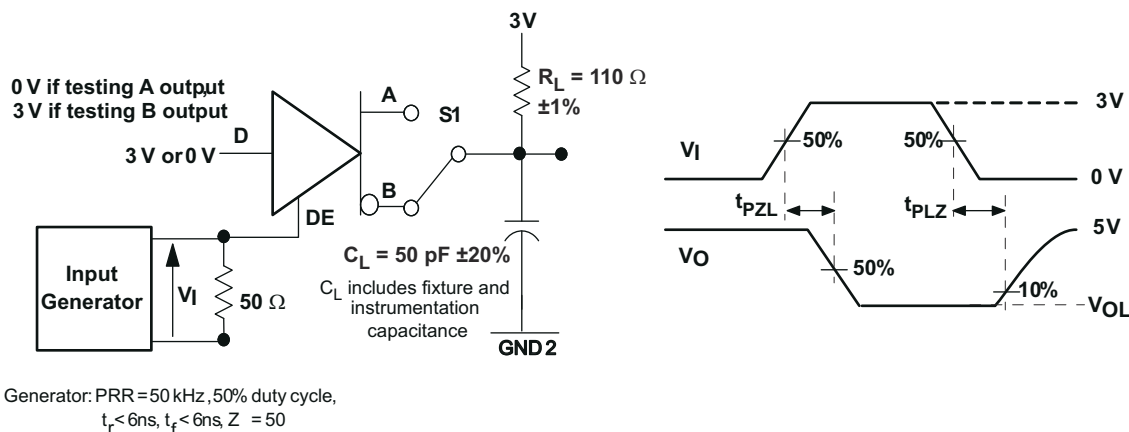


Figure 7-6. Driver Low-Level Output Enable and Disable Time Test Circuit and Voltage Waveform

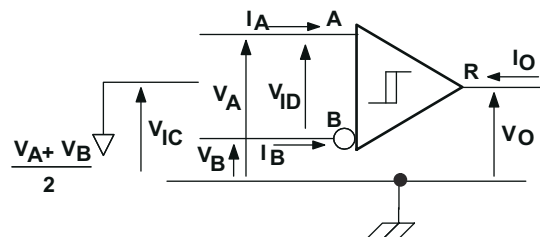


Figure 7-7. Receiver Voltage and Current Definitions

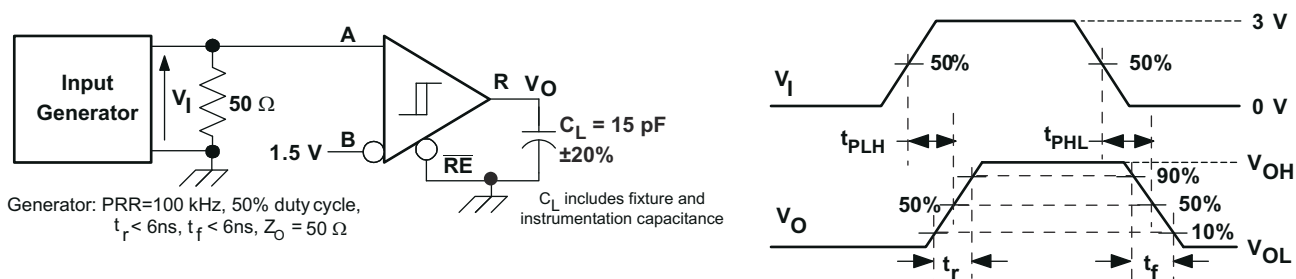


Figure 7-8. Receiver Switching Test Circuit and Waveforms

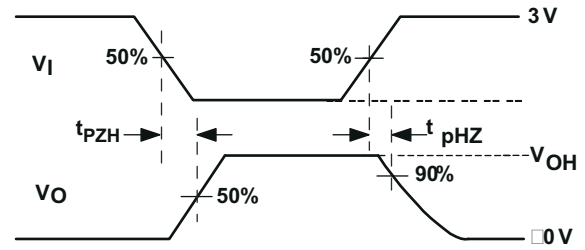
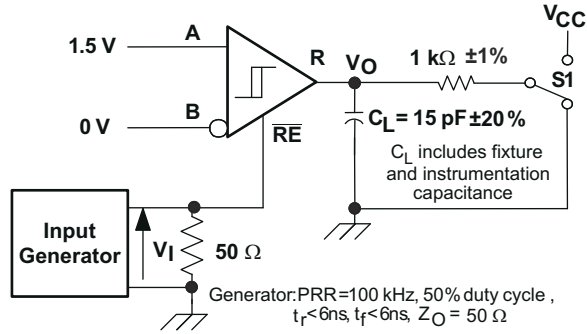


Figure 7-9. Receiver Enable Test Circuit and Waveforms, Data Output High

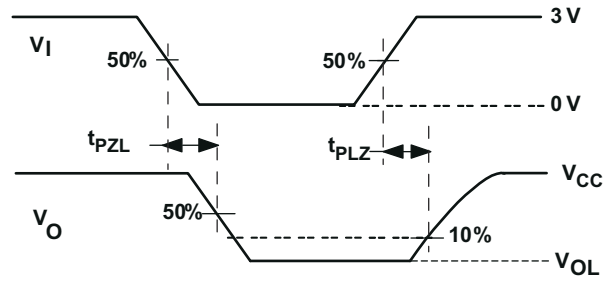
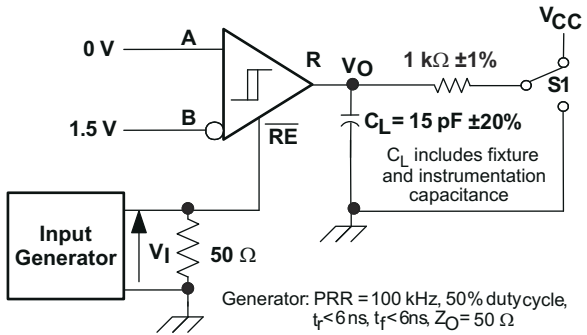
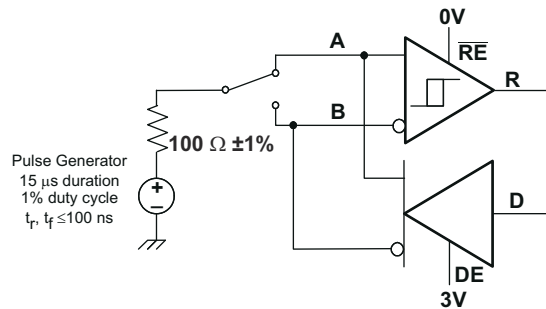


Figure 7-10. Receiver Enable Test Circuit and Waveforms, Data Output Low



Note: This test is conducted to test survivability only.
Data stability at the R output is not specified.

Figure 7-11. Transient Overvoltage Test Circuit

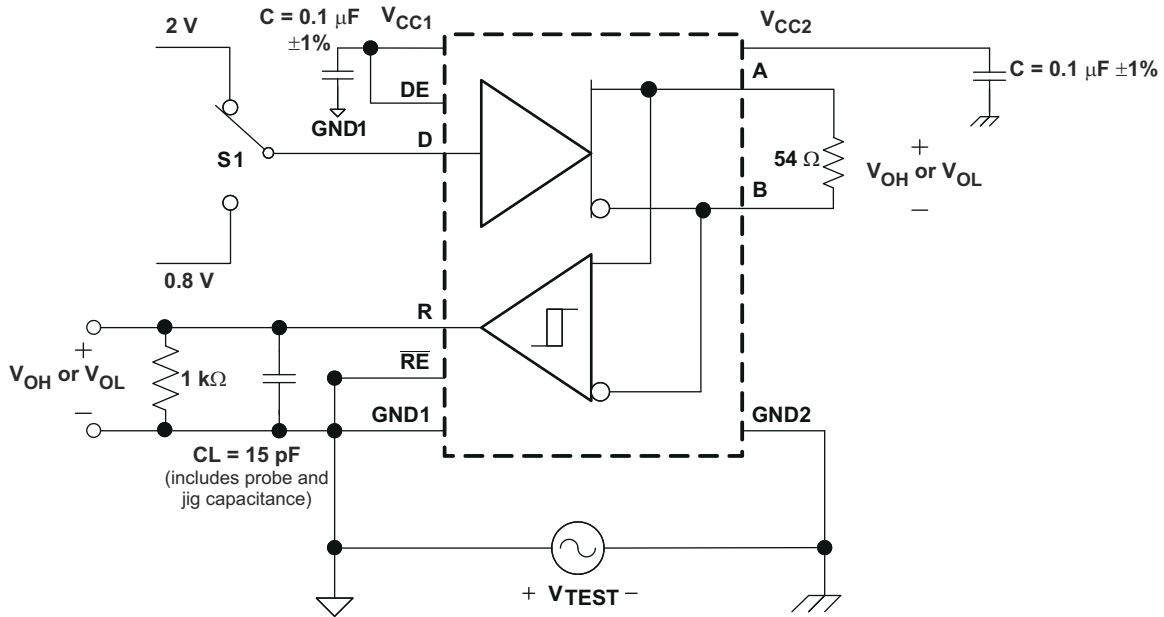


Figure 7-12. Half-Duplex Common-Mode Transient Immunity Test Circuit

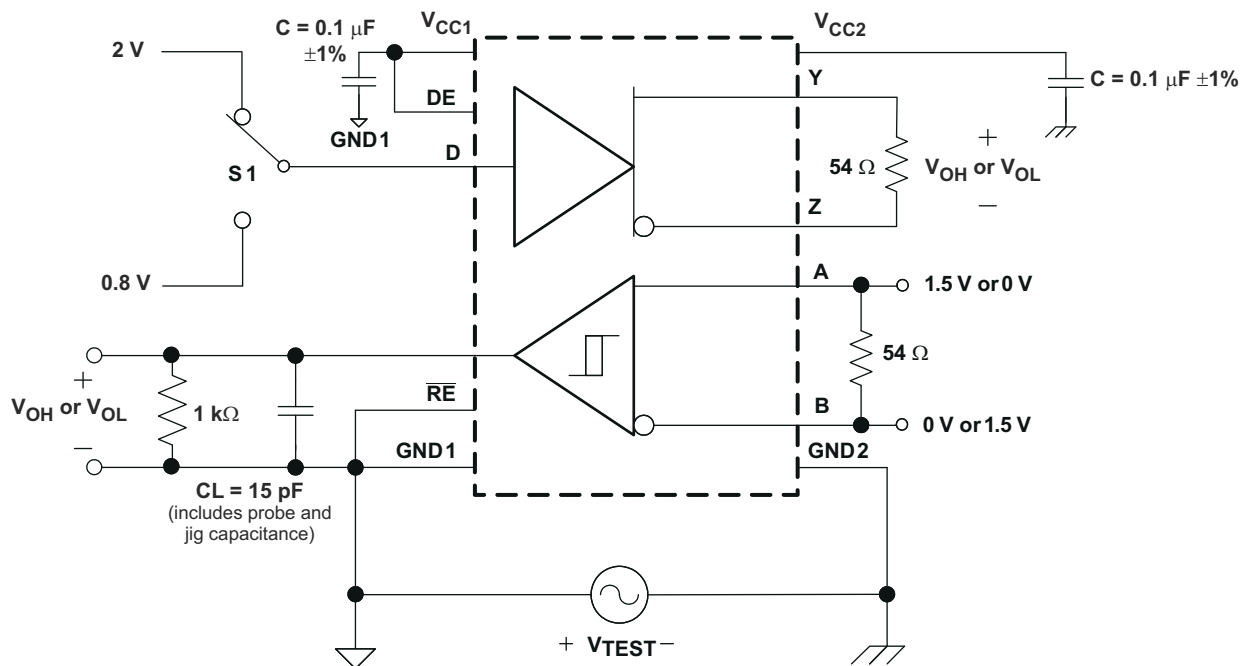


Figure 7-13. Full-Duplex Common-Mode Transient Immunity Test Circuit

8 Detailed Description

8.1 Overview

The ISO3080 and ISO3086 devices are isolated full-duplex differential line drivers and receivers while the ISO3082 and ISO3088 devices are isolated half-duplex differential line transceivers for TIA/EIA 485/422 applications. They are rated to provide galvanic isolation of up to 2500 V_{RMS} for 60 s as per the standard. They have active-high driver enables and active-low receiver enables to control the data flow. They are available in two speed grades suitable for data transmission up to 200 kbps and 20 Mbps.

When the driver enable pin, DE, is logic high, the differential outputs Y and Z follow the logic states at data input D. A logic high at D causes Y to turn high and Z to turn low. In this case the differential output voltage defined as $V_{OD} = V_{(Y)} - V_{(Z)}$ is positive. When D is low, the output states reverse, Z turns high, Y becomes low, and V_{OD} is negative. When DE is low, both outputs turn high-impedance. In this condition the logic state at D is irrelevant. The DE pin has an internal pulldown resistor to ground, thus when left open the driver is disabled (high-impedance) by default. The D pin has an internal pullup resistor to V_{CC} , thus, when left open while the driver is enabled, output Y turns high and Z turns low.

When the receiver enable pin, RE, is logic low, the receiver is enabled. When the differential input voltage defined as $V_{ID} = V_{(A)} - V_{(B)}$ is positive and higher than the positive input threshold, V_{IT+} , the receiver output, R, turns high. When V_{ID} is negative and less than the negative and lower than the negative input threshold, V_{IT-} , the receiver output, R, turns low. If V_{ID} is between V_{IT+} and V_{IT-} the output is indeterminate. When RE is logic high or left open, the receiver output is high-impedance and the magnitude and polarity of V_{ID} are irrelevant. Internal biasing of the receiver inputs causes the output to go failsafe-high when the transceiver is disconnected from the bus (open-circuit), the bus lines are shorted (short-circuit), or the bus is not actively driven (idle bus).

8.2 Functional Block Diagrams

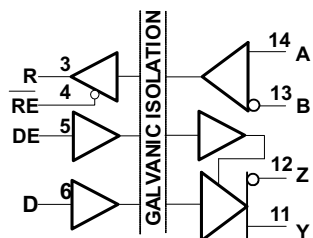


Figure 8-1. ISO3080, IOS3086 Functional Diagram

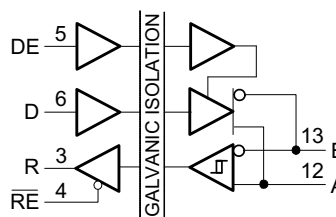


Figure 8-2. ISO3082, IOS3088 Functional Diagram

8.3 Feature Description

Table 8-1 provides an overview of the device features.

Table 8-1. Device Features

DEVICE	RATED ISOLATION ⁽¹⁾	TYPE	DATA RATE
ISO3080	4000 V _{PK} / 2500 V _{RMS}	Full-duplex	200 kbps
ISO3086	4000 V _{PK} / 2500 V _{RMS}	Full-duplex	20 Mbps
ISO3082	4000 V _{PK} / 2500 V _{RMS}	Half-duplex	200 kbps
ISO3088	4000 V _{PK} / 2500 V _{RMS}	Half-duplex	20 Mbps

(1) See *Safety-Related Certifications* table for detailed isolation ratings.

8.4 Device Functional Modes

Table 8-2 lists the driver functional modes and Table 8-3 lists the receiver functional modes.

Table 8-2. Driver Function Table⁽¹⁾

V _{CC1}	V _{CC2}	INPUT (D)	ENABLE INPUT (DE)	OUTPUTS ⁽¹⁾	
				Y / A	Z / B
PU	PU	H	H	H	L
PU	PU	L	H	L	H
PU	PU	X	L	Hi-Z	Hi-Z
PU	PU	X	OPEN	Hi-Z	Hi-Z
PU	PU	OPEN	H	H	L
PD	PU	X	X	Hi-Z	Hi-Z
PU	PD	X	X	Hi-Z	Hi-Z
PD	PD	X	X	Hi-Z	Hi-Z

(1) Driver output pins are Y and Z for full-duplex devices and A and B for half-duplex devices.

Table 8-3. Receiver Function Table⁽¹⁾

V _{CC1}	V _{CC2}	DIFFERENTIAL INPUT V _{ID} = (V _A – V _B)	ENABLE (RE)	OUTPUT (R)
PU	PU	-0.01 V ≤ V _{ID}	L	H
PU	PU	-0.2 V < V _{ID} < -0.01 V	L	?
PU	PU	V _{ID} ≤ -0.2 V	L	L
PU	PU	X	H	Hi-Z
PU	PU	X	OPEN	Hi-Z
PU	PU	Open circuit	L	H
PU	PU	Short circuit	L	H
PU	PU	Idle (terminated) bus	L	H
PD	PU	X	X	Hi-Z
PU	PD	X	L	H

(1) PU = Powered Up; PD = Powered Down; H = Logic High; L = Logic Low; X = Irrelevant, Hi-Z = High Impedance (off), ? = Indeterminate

8.4.1 Device I/O Schematics

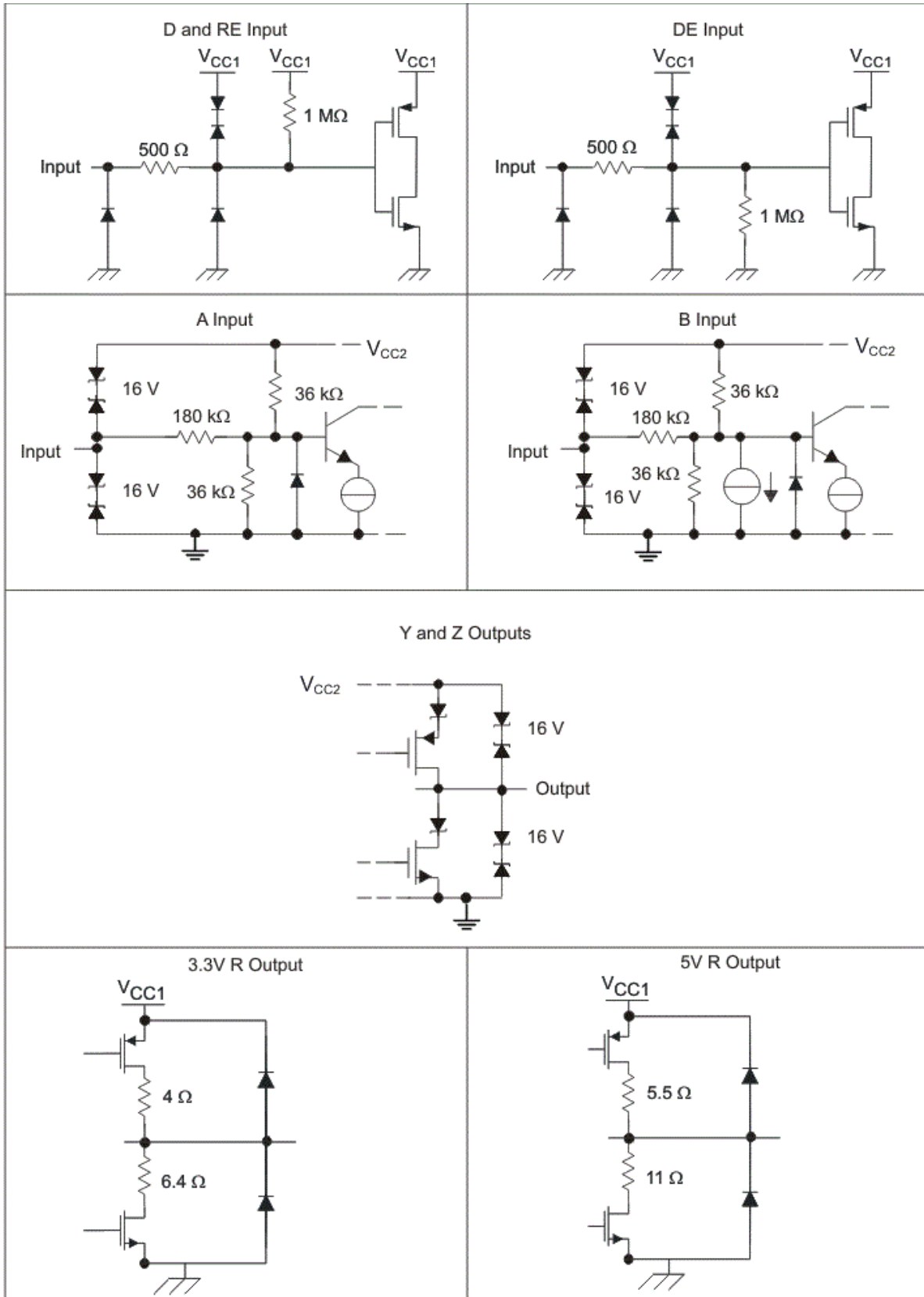


Figure 8-3. Device I/O Schematics

9 Application and Implementation

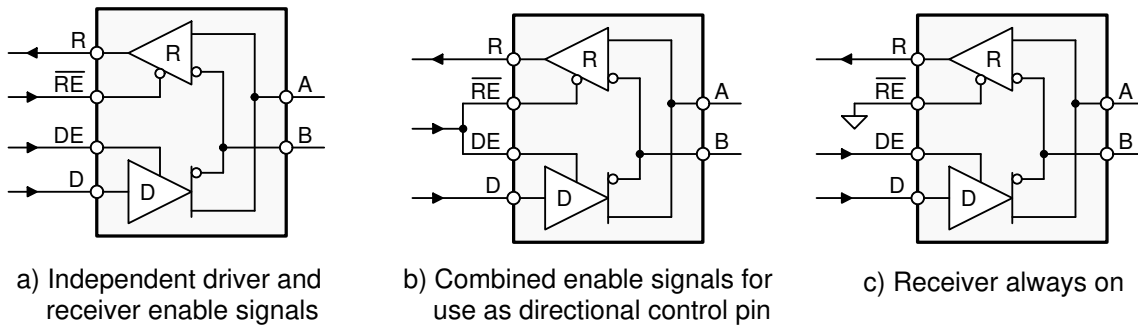
Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

9.1 Application Information

The ISO308x family consists of RS-485 transceivers commonly used for asynchronous data transmissions. Full-duplex implementation requires two signal pairs (four wires), and allows each node to transmit data on one pair while simultaneously receiving data on the other pair. For half-duplex transmission, only one pair is shared for both transmission and reception of data. To eliminate line reflections, each cable end is terminated with a termination resistor, $R_{(T)}$, whose value matches the characteristic impedance, Z_0 , of the cable. This method, known as parallel termination, allows for higher data rates over longer cable length.

9.2 Typical Application



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Figure 9-1. Half-Duplex Transceiver Configurations

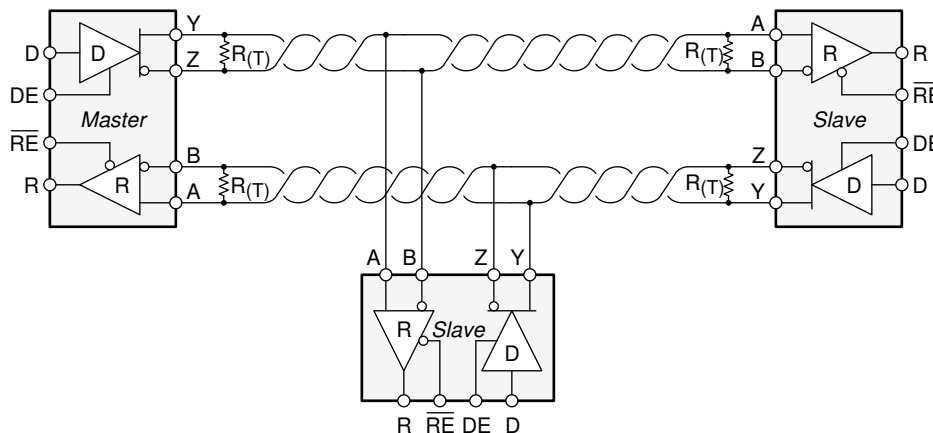


Figure 9-2. Typical RS-485 Network With Full-Duplex Transceivers

9.2.1 Design Requirements

RS-485 is a robust electrical standard suitable for long-distance networking that can be used in a wide range of applications with varying requirements, such as distance, data rate, and number of nodes. [Table 9-1](#) lists the design parameters.

Table 9-1. Design Parameters

PARAMETER	VALUE
Pullup and pulldown resistors	1 kΩ to 10 kΩ
Decoupling capacitors	100 nF

9.2.2 Detailed Design Procedure

The data rate and cable length have an inverse relationship which means the higher the data rate, the shorter the cable length; and conversely, the lower the data rate, the longer the cable length. When connecting a node to the bus, the distance between the transceiver inputs and the cable trunk, known as the stub, should be as short as possible. Stubs present a nonterminated piece of bus line which can introduce reflections as the length of the stub increases. As a general guideline, the electrical length, or round-trip delay, of a stub should be less than one-tenth of the rise time of the driver. The RS-485 standard specifies that a compliant driver must be able to driver 32 unit loads (ULs), where 1 UL represents a load impedance of approximately 12 kΩ. Because the ISO308x family consists of 1/8 UL transceivers, connecting up to 256 receivers to the bus is possible.

9.2.3 Application Curve

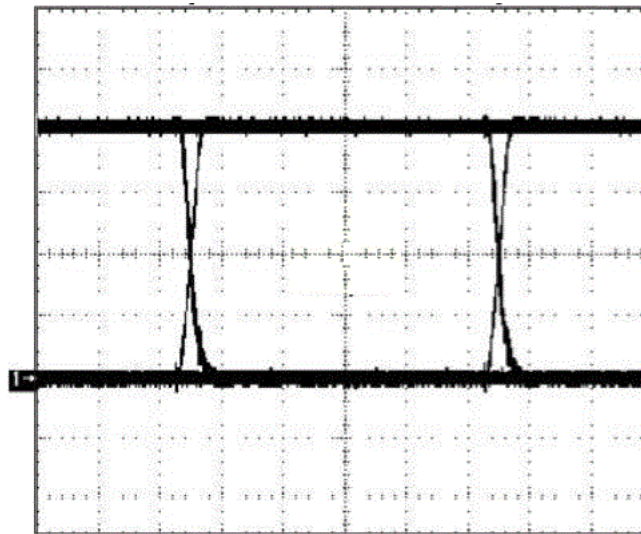


Figure 9-3. ISO308x Output

10 Power Supply Recommendations

To help ensure reliable operation at all data rates and supply voltages, a 0.1- μ F bypass capacitor is recommended at the input and output supply pins (V_{CC1} and V_{CC2}). The capacitors should be placed as close to the supply pins as possible. If only a single primary-side power supply is available in an application, isolated power can be generated for the secondary-side with the help of a transformer driver such as Texas Instruments' [SN6501](#). For such applications, detailed power supply design and transformer selection recommendations are available in [SN6501 Transformer Driver for Isolated Power Supplies](#).

11 Layout

11.1 Layout Guidelines

ON-chip IEC-ESD protection is good for laboratory and portable equipment but never sufficient for EFT and surge transients occurring in industrial environments. Therefore, robust and reliable bus node design requires the use of external transient protection devices. Because ESD and EFT transients have a wide frequency bandwidth from approximately 3-MHz to 3-GHz, high-frequency layout techniques must be applied during PCB design. A minimum of four layers is required to accomplish a low EMI PCB design (see [Figure 11-1](#)).

- Layer stacking should be in the following order (top-to-bottom): high-speed signal layer, ground plane, power plane, and low-frequency signal layer.
- Routing the high-speed traces on the top layer avoids the use of vias (and the introduction of their inductances) and allows for clean interconnects between the isolator and the transmitter and receiver circuits of the data link.
- Placing a solid ground plane next to the high-speed signal layer establishes controlled impedance for transmission line interconnects and provides an excellent low-inductance path for the return current flow.
- Placing the power plane next to the ground plane creates additional high-frequency bypass capacitance of approximately 100 pF/in².
- Routing the slower speed control signals on the bottom layer allows for greater flexibility as these signal links usually have margin to tolerate discontinuities such as vias.
- Place the protection circuitry close to the bus connector to prevent noise transients from penetrating your board.
- Use V_{CC} and ground planes to provide low-inductance. High-frequency currents might follow the path of least inductance and not necessarily the path of least resistance.
- Design the protection components into the direction of the signal path. Do not force the transient currents to divert from the signal path to reach the protection device.
- Apply 0.1- μ F bypass capacitors as close as possible to the V_{CC} -pins of transceiver, UART, and controller ICs on the board.
- Use at least two vias for V_{CC} and ground connections of bypass capacitors and protection devices to minimize effective via-inductance.
- Use 1-k Ω to 10-k Ω pullup and pulldown resistors for enable lines to limit noise currents in these lines during transient events.
- Insert pulse-proof resistors into the A and B bus lines if the TVS clamping voltage is higher than the specified maximum voltage of the transceiver bus pins. These resistors limit the residual clamping current into the transceiver and prevent it from latching up.
- While pure TVS protection is sufficient for surge transients up to 1 kV, higher transients require metal-oxide varistors (MOVs) which reduce the transients to a few hundred volts of clamping voltage, and transient blocking units (TBUs) that limit transient current to less than 1 mA.

If an additional supply voltage plane or signal layer is needed, add a second power or ground plane system to the stack to keep it symmetrical. This makes the stack mechanically stable and prevents it from warping. Also the power and ground plane of each power system can be placed closer together, thus increasing the high-frequency bypass capacitance significantly.

For detailed layout recommendations, refer to the [Digital Isolator Design Guide](#).

11.2 Layout Example

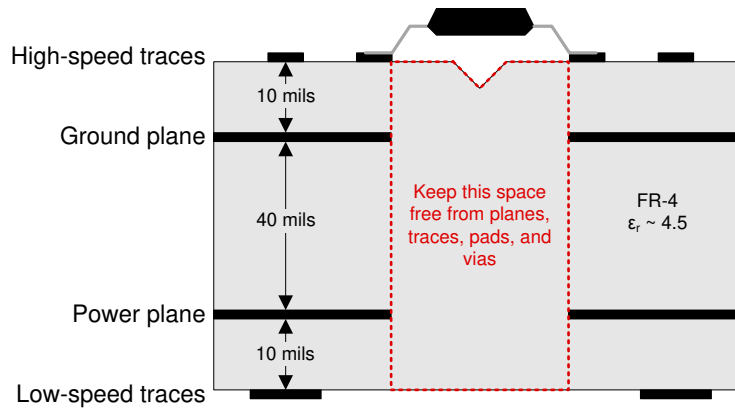


Figure 11-1. Recommended Layer Stack

12 Device and Documentation Support

12.1 Documentation Support

12.1.1 Related Documentation

For related documentation see the following:

- [Communication Module Reference Design for Functional Isolated RS-485, CAN, and I2C Data Transmission](#)
- [Digital Isolator Design Guide](#)
- [Dual Isolated Half-Duplex RS-485 Repeater](#)
- [Isolation Glossary](#)
- [Programmable Logic Controller \(PLC\) I/O Module Front- End Controller with Tiva C Series ARM®Cortex®-M4 MCU](#)
- [Small Form Factor, Digital Isolator-Based Half-Duplex RS- 485 Interface Module Reference Design](#)
- [SN6501 Transformer Driver for Isolated Power Supplies](#)

12.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

12.3 Support Resources

TI E2E™ [support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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12.4 Trademarks

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ARM® and Cortex® are registered trademarks of ARM Ltd..
All trademarks are the property of their respective owners.

12.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

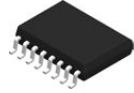
ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

12.6 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

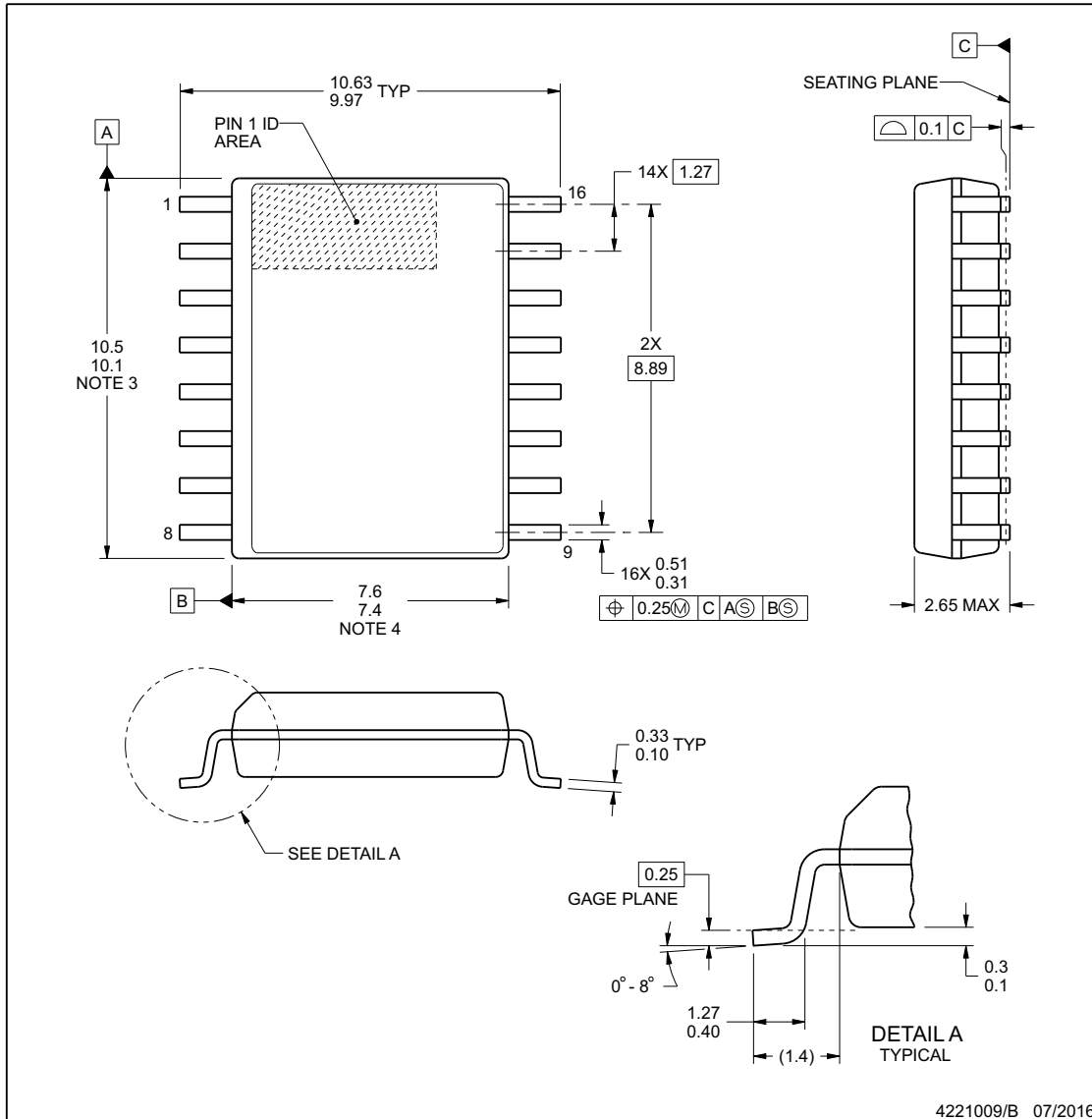
The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



DW0016B

PACKAGE OUTLINE
SOIC - 2.65 mm max height

SOIC



NOTES:

1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm, per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm, per side.
5. Reference JEDEC registration MS-013.

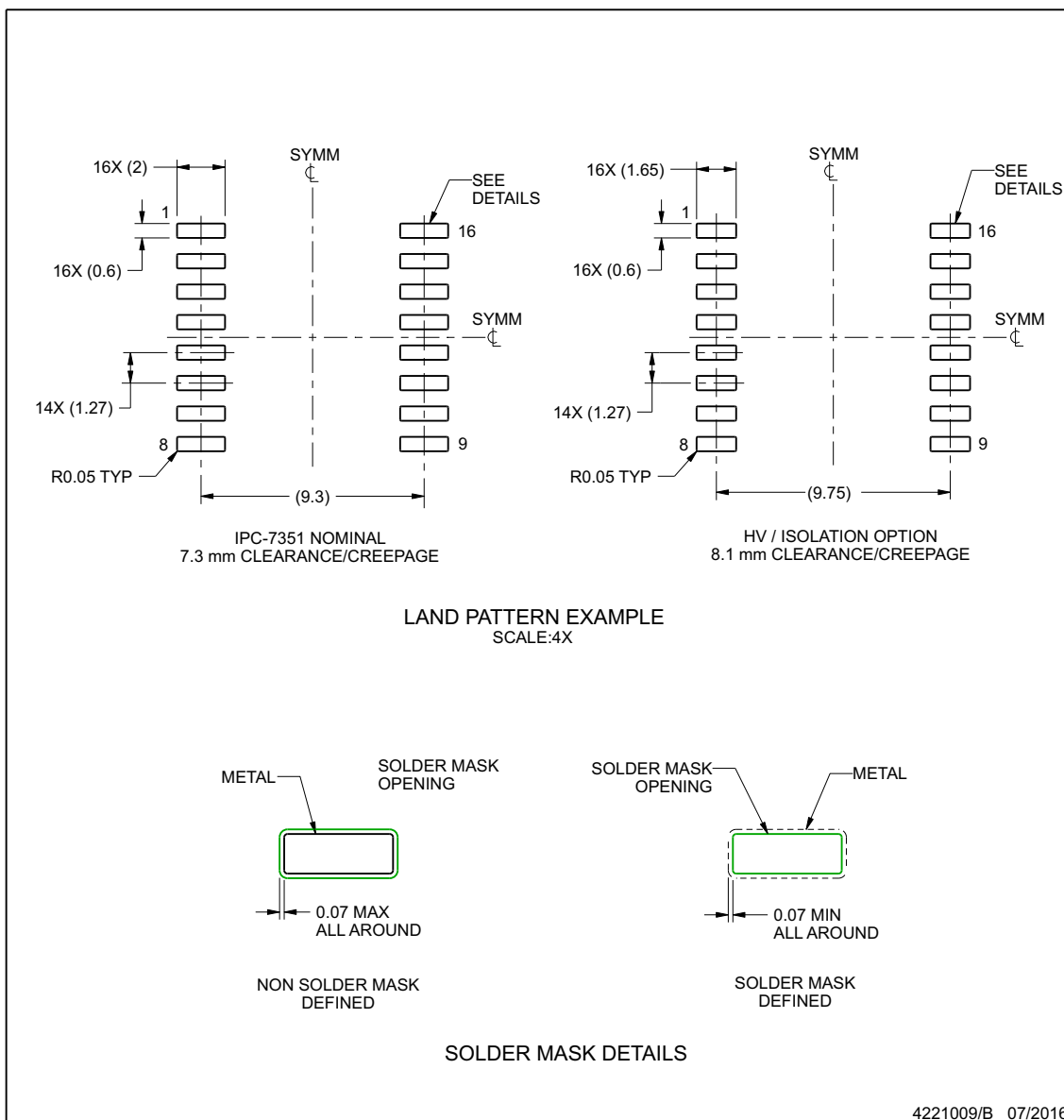
www.ti.com

EXAMPLE BOARD LAYOUT

DW0016B

SOIC - 2.65 mm max height

SOIC



NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

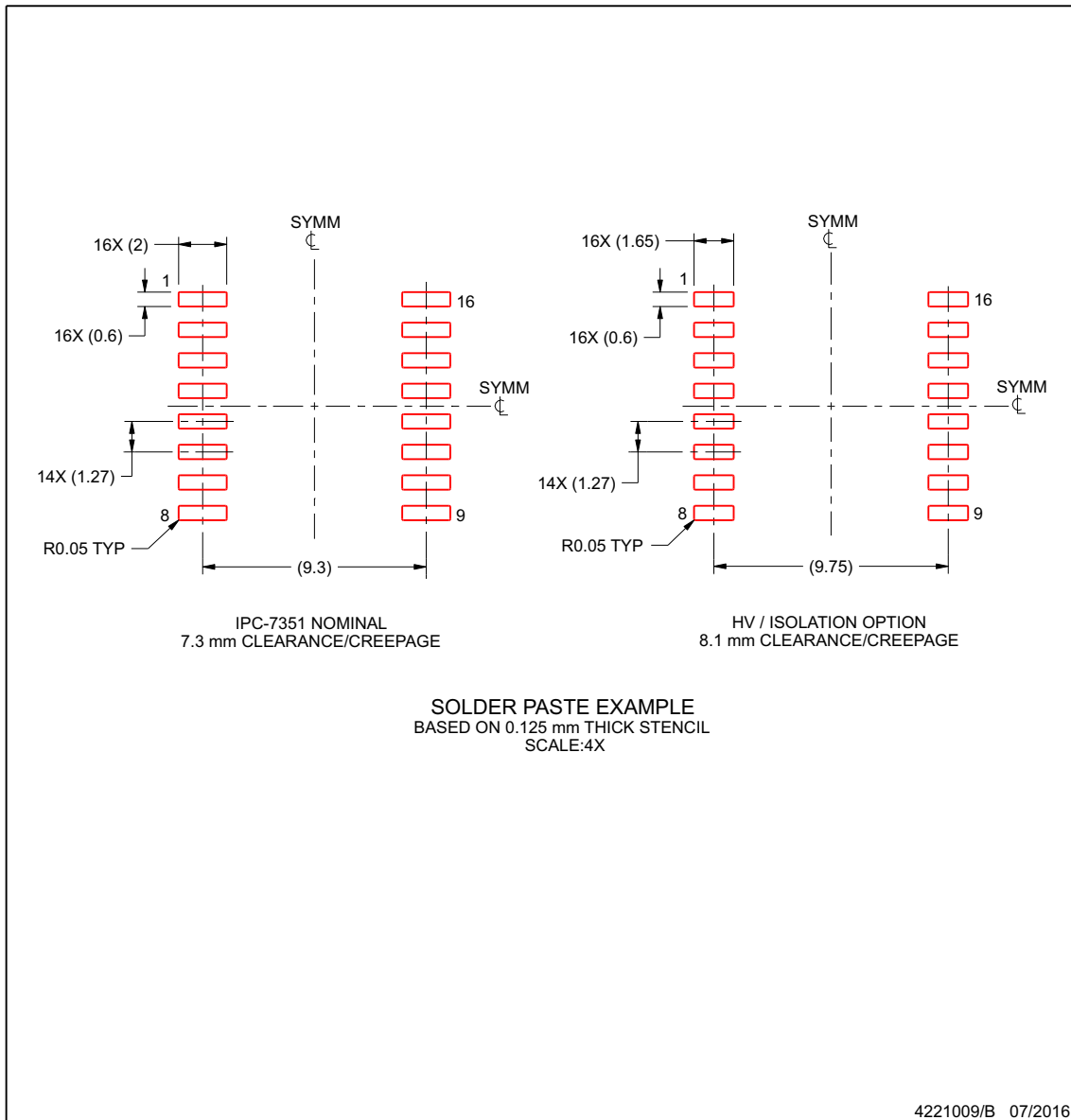
www.ti.com

EXAMPLE STENCIL DESIGN

DW0016B

SOIC - 2.65 mm max height

SOIC



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
ISO3080DW	Obsolete	Production	SOIC (DW) 16	-	-	Call TI	Call TI	-40 to 85	ISO3080
ISO3080DWR	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3080
ISO3080DWR.Z	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3080
ISO3080DWRG4.Z	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3080
ISO3082DW	Obsolete	Production	SOIC (DW) 16	-	-	Call TI	Call TI	-40 to 85	ISO3082
ISO3082DWR	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3082
ISO3082DWR.Z	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3082
ISO3082DWRG4	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3082
ISO3086DW	Obsolete	Production	SOIC (DW) 16	-	-	Call TI	Call TI	-40 to 85	ISO3086
ISO3086DWR	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3086
ISO3086DWR.Z	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3086
ISO3086DWRG4.Z	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3086
ISO3088DW	Obsolete	Production	SOIC (DW) 16	-	-	Call TI	Call TI	-40 to 85	ISO3088
ISO3088DWR	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3088
ISO3088DWR.Z	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3088
ISO3088DWRG4	Active	Production	SOIC (DW) 16	2000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ISO3088

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ISO3080DWR	SOIC	DW	16	2000	330.0	16.4	10.75	10.7	2.7	12.0	16.0	Q1
ISO3082DWR	SOIC	DW	16	2000	330.0	16.4	10.75	10.7	2.7	12.0	16.0	Q1
ISO3086DWR	SOIC	DW	16	2000	330.0	16.4	10.75	10.7	2.7	12.0	16.0	Q1
ISO3088DWR	SOIC	DW	16	2000	330.0	16.4	10.75	10.7	2.7	12.0	16.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ISO3080DWR	SOIC	DW	16	2000	353.0	353.0	32.0
ISO3082DWR	SOIC	DW	16	2000	353.0	353.0	32.0
ISO3086DWR	SOIC	DW	16	2000	353.0	353.0	32.0
ISO3088DWR	SOIC	DW	16	2000	353.0	353.0	32.0

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