



## LM2831 High-Frequency 1.5-A Load — Step-Down DC-DC Regulator

### 1 Features

- Space-Saving SOT-23 Package
- Input Voltage Range of 3 V to 5.5 V
- Output Voltage Range of 0.6 V to 4.5 V
- 1.5-A Output Current
- High Switching Frequency
  - 1.6 MHz (LM2831X)
  - 0.55 MHz (LM2831Y)
  - 3 MHz (LM2831Z)
- 130-mΩ PMOS Switch
- 0.6-V, 2% Internal Voltage Reference
- Internal Soft Start
- Current Mode, PWM Operation
- Thermal Shutdown
- Overvoltage Protection

### 2 Applications

- Local 5 V to Vcore Step-Down Converters
- Core Power in HDDs
- Set-Top Boxes
- USB Powered Devices
- DSL Modems

### 3 Description

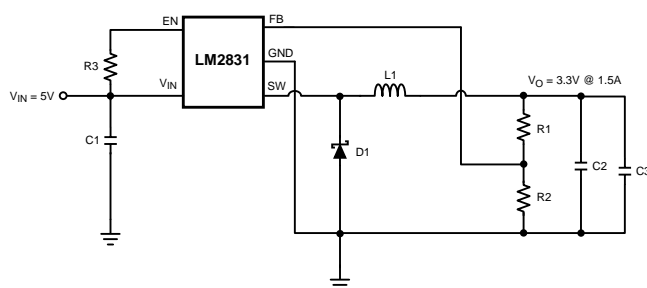
The LM2831 regulator is a monolithic, high-frequency, PWM step-down DC-DC converter in a 5-pin SOT-23 and a 6-Pin WSON package. The LM2831 provides all the active functions to provide local DC-DC conversion with fast transient response and accurate regulation in the smallest possible PCB area. With a minimum of external components, the LM2831 is easy to use. The ability to drive 1.5-A loads with an internal 130-mΩ PMOS switch using state-of-the-art 0.5-μm BiCMOS technology results in the best power density available. The world-class control circuitry allows on-times as low as 30 ns, thus supporting exceptionally high frequency conversion over the entire 3 V to 5.5 V input operating range, down to the minimum output voltage of 0.6 V. Switching frequency is internally set to 550 kHz, 1.6 MHz, or 3 MHz, allowing the use of extremely small surface mount inductors and chip capacitors. Even though the operating frequency is high, efficiencies of up to 93% are easy to achieve. External shutdown is included, featuring an ultra-low standby current of 30 nA. The LM2831 utilizes current-mode control and internal compensation to provide high-performance regulation over a wide range of operating conditions. Additional features include internal soft-start circuitry to reduce inrush current, pulse-by-pulse current limit, thermal shutdown, and output overvoltage protection.

#### Device Information<sup>(1)</sup>

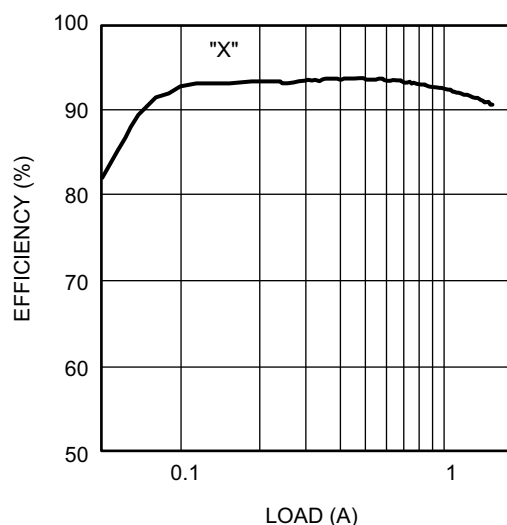
PART NUMBER	PACKAGE	BODY SIZE (NOM)
LM2831	WSON (6)	3.00 mm × 3.00 mm
	SOT-23 (5)	1.60 mm × 2.90 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

#### Typical Application Circuit



#### Efficiency vs Load



## Table of Contents

<b>1 Features</b> .....	<b>1</b>	7.4 Device Functional Modes.....	<b>11</b>
<b>2 Applications</b> .....	<b>1</b>	<b>8 Application and Implementation</b> .....	<b>12</b>
<b>3 Description</b> .....	<b>1</b>	8.1 Application Information.....	<b>12</b>
<b>4 Revision History</b> .....	<b>2</b>	8.2 Typical Applications .....	<b>12</b>
<b>5 Pin Configuration and Functions</b> .....	<b>3</b>	<b>9 Power Supply Recommendations</b> .....	<b>25</b>
<b>6 Specifications</b> .....	<b>4</b>	<b>10 Layout</b> .....	<b>25</b>
6.1 Absolute Maximum Ratings .....	4	10.1 Layout Guidelines .....	25
6.2 ESD Ratings.....	4	10.2 Layout Example .....	29
6.3 Recommended Operating Conditions.....	4	<b>11 Device and Documentation Support</b> .....	<b>30</b>
6.4 Thermal Information .....	4	11.1 Device Support.....	30
6.5 Electrical Characteristics.....	5	11.2 Documentation Support .....	30
6.6 Typical Characteristics .....	6	11.3 Community Resources.....	30
<b>7 Detailed Description</b> .....	<b>9</b>	11.4 Trademarks .....	30
7.1 Overview .....	9	11.5 Electrostatic Discharge Caution.....	30
7.2 Functional Block Diagram .....	9	11.6 Glossary .....	30
7.3 Feature Description.....	9	<b>12 Mechanical, Packaging, and Orderable Information</b> .....	<b>30</b>

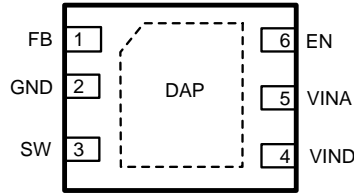
## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

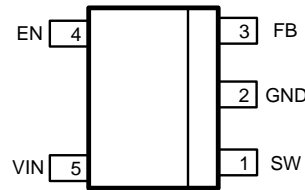
Changes from Revision C (April 2013) to Revision D	Page
<ul style="list-style-type: none"> <li>Added <i>ESD Ratings</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i>, <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Layout</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section. ....</li> </ul>	<b>1</b>
Changes from Revision B (April 2013) to Revision C	Page
<ul style="list-style-type: none"> <li>Changed layout of National Data Sheet to TI format .....</li> </ul>	<b>24</b>

## 5 Pin Configuration and Functions

**NGG Package  
6-Pins WSON  
Top View**



**DBV Package  
5-Pin SOT-23  
Top View**



**Pin Functions**

PIN			I/O	DESCRIPTION
NAME	SOT-23	WSON		
EN	4	6	I	Enable control input. Logic high enables operation. Do not allow this pin to float or be greater than $V_{IN} + 0.3\text{ V}$ , or $V_{INA} + 0.3\text{ V}$ for WSON.
FB	3	1	I	Feedback pin. Connect to external resistor divider to set output voltage.
GND	2	2	PWR	Signal and power ground pin. Place the bottom resistor of the feedback network as close as possible to this pin.
SW	1	3	O	Output switch. Connect to the inductor and catch diode.
VIN	5	—	PWR	Input supply voltage
VINA	—	5	PWR	Control circuitry supply voltage. Connect VINA to VIND on PC board.
VIND	—	4	PWR	Power input supply
Die Attach Pad	—	DAP	PWR	Connect to system ground for low thermal impedance, but it cannot be used as a primary GND connection.

## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)(2)</sup>

	MIN	MAX	UNIT
V <sub>IN</sub>	–0.5	7	V
FB Voltage	–0.5	3	V
EN Voltage	–0.5	7	V
SW Voltage	–0.5	7	V
Junction Temperature <sup>(3)</sup>		150	°C
Soldering Information      Infrared or Convection Reflow (15 sec)		220	°C
Storage Temperature, T <sub>stg</sub>	–65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) Thermal shutdown will occur if the junction temperature exceeds the maximum junction temperature of the device.

### 6.2 ESD Ratings

	VALUE	UNIT
V <sub>(ESD)</sub> Electrostatic discharge      Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	NOM	MAX	UNIT
V <sub>IN</sub>	3		5.5	V
Junction Temperature	–40		125	°C

### 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		LM2831		UNIT
		SOT-23 (DBV)	WSON (NGG)	
		5 PINS	6 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance <sup>(2)</sup>	163.4	54.9	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance <sup>(2)</sup>	114.4	50.8	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	26.8	29.2	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	12.4	0.6	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	26.2	29.3	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	N/A	9.2	°C/W

- (1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).
- (2) Applies for packages soldered directly onto a 3" × 3" PC board with 2 oz. copper on 4 layers in still air.

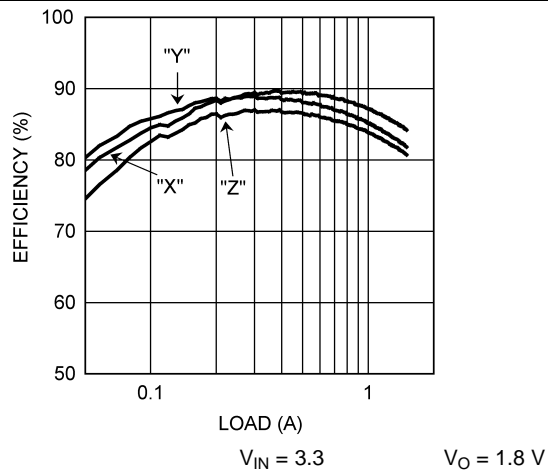
## 6.5 Electrical Characteristics

$V_{IN} = 5\text{ V}$  unless otherwise indicated under the *Test Conditions* column. Limits are for  $T_J = 25^\circ\text{C}$ . Minimum and Maximum limits are specified through test, design, or statistical correlation. Typical values represent the most likely parametric norm at  $T_J = 25^\circ\text{C}$ , and are provided for reference purposes only.

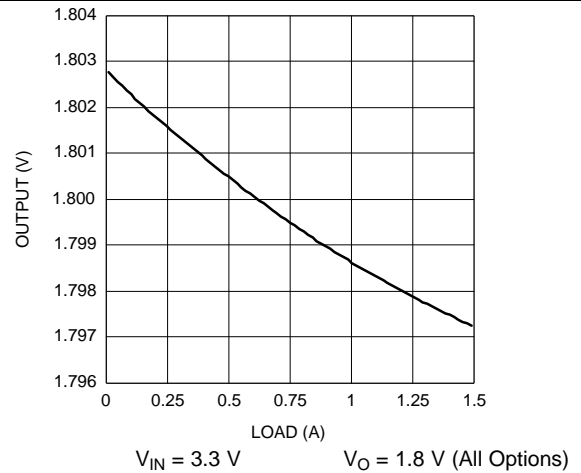
PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
$V_{FB}$	Feedback Voltage	WSO <sub>N</sub> and SOT-23 Package	$T_J = 25^\circ\text{C}$		0.600		V
			$-40^\circ\text{C}$ to $125^\circ\text{C}$	0.588		0.612	
$\Delta V_{FB}/V_{IN}$	Feedback Voltage Line Regulation	$V_{IN} = 3\text{ V}$ to $5\text{ V}$			0.02		%/V
$I_B$	Feedback Input Bias Current		$T_J = 25^\circ\text{C}$		0.1		nA
			$-40^\circ\text{C}$ to $125^\circ\text{C}$			100	
UVLO	Undervoltage Lockout	$V_{IN}$ Rising	$T_J = 25^\circ\text{C}$		2.73		V
			$-40^\circ\text{C}$ to $125^\circ\text{C}$			2.90	
		$V_{IN}$ Falling	$T_J = 25^\circ\text{C}$		2.3		V
			$-40^\circ\text{C}$ to $125^\circ\text{C}$	1.85			
	UVLO Hysteresis				0.43		V
$F_{SW}$	Switching Frequency	LM2831-X	$T_J = 25^\circ\text{C}$		1.6		MHz
			$-40^\circ\text{C}$ to $125^\circ\text{C}$	1.2		1.95	
		LM2831-Y	$T_J = 25^\circ\text{C}$		0.55		
			$-40^\circ\text{C}$ to $125^\circ\text{C}$	0.4		0.7	
		LM2831-Z	$T_J = 25^\circ\text{C}$		3		
			$-40^\circ\text{C}$ to $125^\circ\text{C}$	2.25		3.75	
$D_{MAX}$	Maximum Duty Cycle	LM2831-X	$T_J = 25^\circ\text{C}$		94%		
			$-40^\circ\text{C}$ to $125^\circ\text{C}$	86%			
		LM2831-Y	$T_J = 25^\circ\text{C}$		96%		
			$-40^\circ\text{C}$ to $125^\circ\text{C}$	90%			
		LM2831-Z	$T_J = 25^\circ\text{C}$		90%		
			$-40^\circ\text{C}$ to $125^\circ\text{C}$	82%			
$D_{MIN}$	Minimum Duty Cycle	LM2831-X			5%		
		LM2831-Y			2%		
		LM2831-Z			7%		
$R_{DS(ON)}$	Switch On Resistance	WSO <sub>N</sub> Package			150		m $\Omega$
		SOT-23 Package	$T_J = 25^\circ\text{C}$		130		
			$-40^\circ\text{C}$ to $125^\circ\text{C}$			195	
$I_{CL}$	Switch Current Limit	$V_{IN} = 3.3\text{ V}$	$T_J = 25^\circ\text{C}$		2.5		A
			$-40^\circ\text{C}$ to $125^\circ\text{C}$	1.8			
$V_{EN\_TH}$	Shutdown Threshold Voltage		$-40^\circ\text{C}$ to $125^\circ\text{C}$			0.4	V
	Enable Threshold Voltage		$-40^\circ\text{C}$ to $125^\circ\text{C}$	1.8			
$I_{SW}$	Switch Leakage				100		nA
$I_{EN}$	Enable Pin Current	Sink/Source			100		nA
$I_Q$	Quiescent Current (switching)	LM2831X $V_{FB} = 0.55$	$T_J = 25^\circ\text{C}$		3.3		mA
			$-40^\circ\text{C}$ to $125^\circ\text{C}$			5	
		LM2831Y $V_{FB} = 0.55$	$T_J = 25^\circ\text{C}$		2.8		
			$-40^\circ\text{C}$ to $125^\circ\text{C}$			4.5	
		LM2831Z $V_{FB} = 0.55$	$T_J = 25^\circ\text{C}$		4.3		
			$-40^\circ\text{C}$ to $125^\circ\text{C}$			6.5	
	Quiescent Current (shutdown)	All Options $V_{EN} = 0\text{ V}$			30		nA
$T_{SD}$	Thermal Shutdown Temperature				165		$^\circ\text{C}$

## 6.6 Typical Characteristics

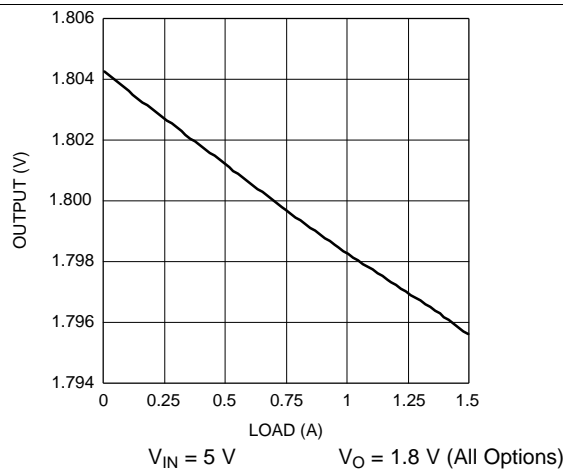
All curves taken at  $V_{IN} = 5\text{ V}$  with configuration in typical application circuit shown in [Application Information](#) section of this datasheet.  $T_J = 25^\circ\text{C}$ , unless otherwise specified.



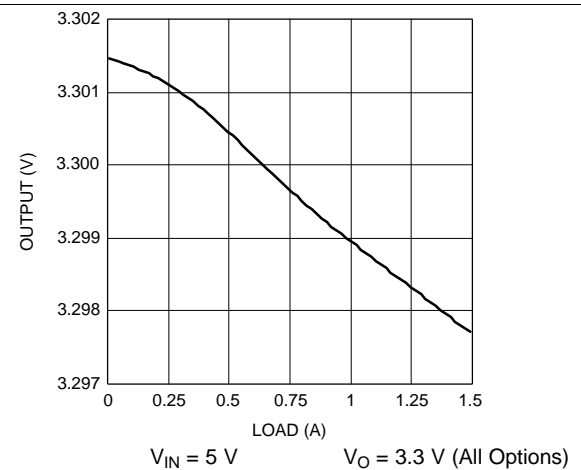
**Figure 1.  $\eta$  vs Load – X, Y, and Z Options**



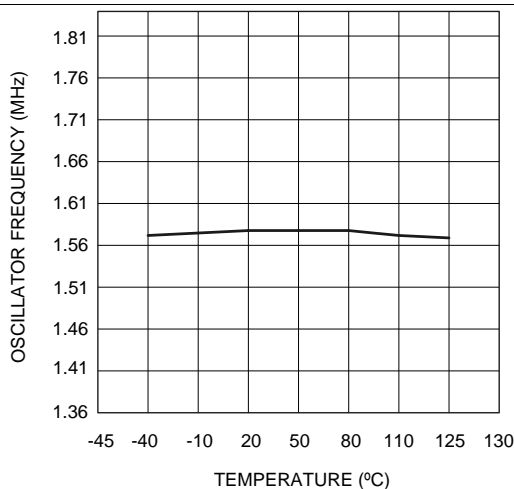
**Figure 2. Load Regulation**



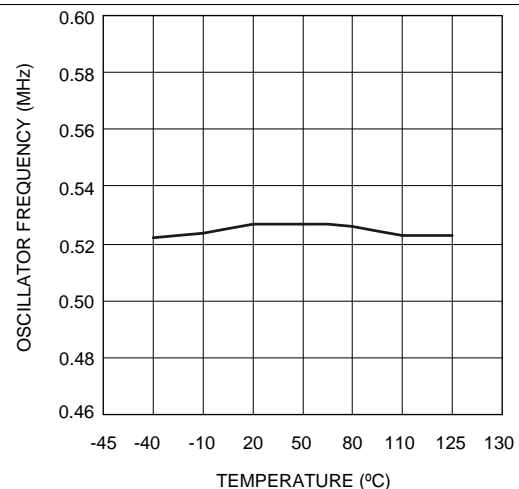
**Figure 3. Load Regulation**



**Figure 4. Load Regulation**



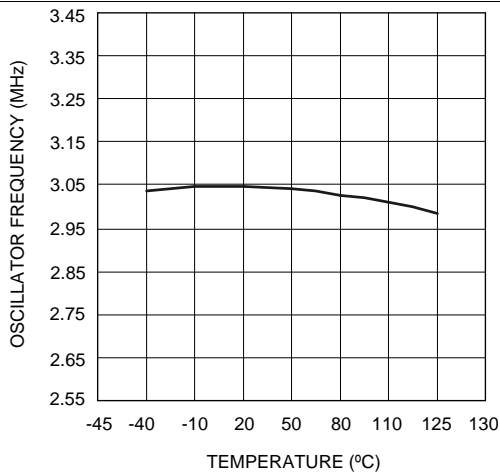
**Figure 5. Oscillator Frequency vs Temperature – X Option**



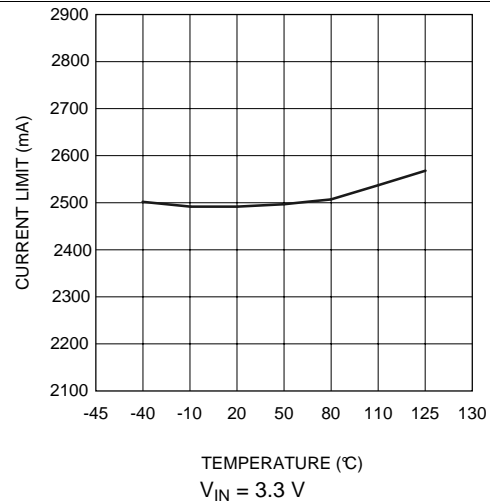
**Figure 6. Oscillator Frequency vs Temperature – Y Option**

## Typical Characteristics (continued)

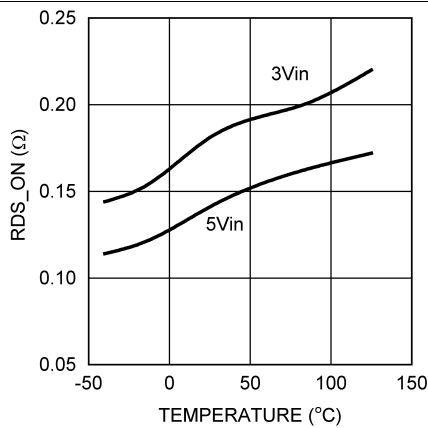
All curves taken at  $V_{IN} = 5\text{ V}$  with configuration in typical application circuit shown in [Application Information](#) section of this datasheet.  $T_J = 25^\circ\text{C}$ , unless otherwise specified.



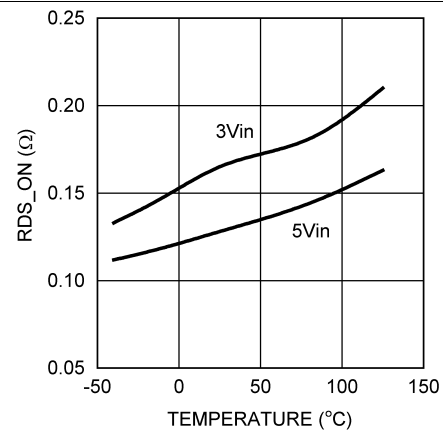
**Figure 7. Oscillator Frequency vs Temperature – Z Option**



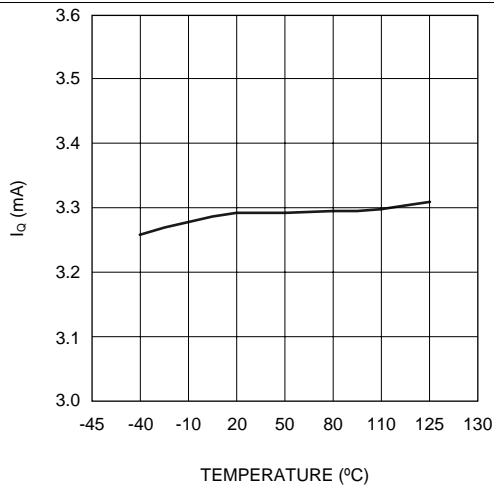
**Figure 8. Current Limit vs Temperature**



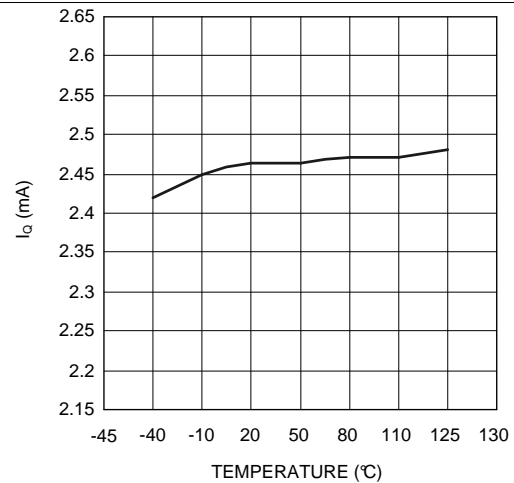
**Figure 9. RDS\_ON vs Temperature (WSN Package)**



**Figure 10. RDS\_ON vs Temperature (SOT-23 Package)**



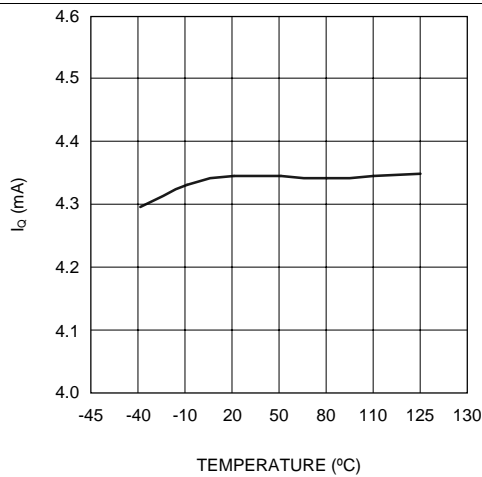
**Figure 11. LM2831X  $I_Q$  (Quiescent Current)**



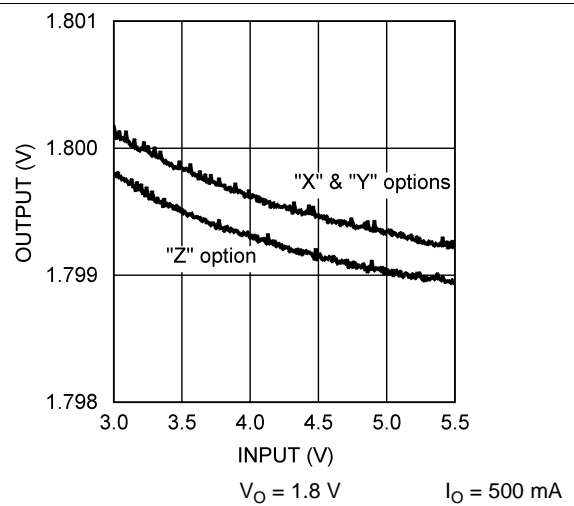
**Figure 12. LM2831Y  $I_Q$  (Quiescent Current)**

## Typical Characteristics (continued)

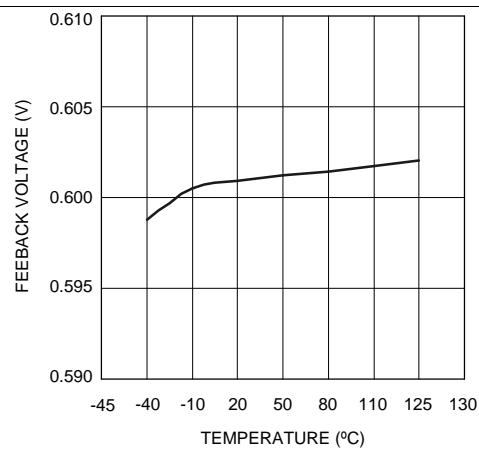
All curves taken at  $V_{IN} = 5\text{ V}$  with configuration in typical application circuit shown in [Application Information](#) section of this datasheet.  $T_J = 25^\circ\text{C}$ , unless otherwise specified.



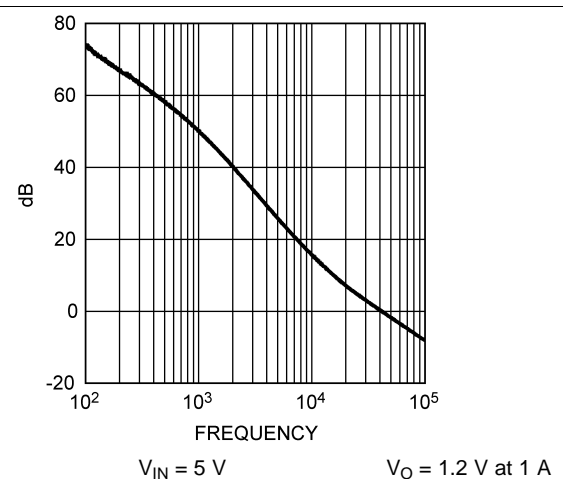
**Figure 13. LM2831Z  $I_Q$  (Quiescent Current)**



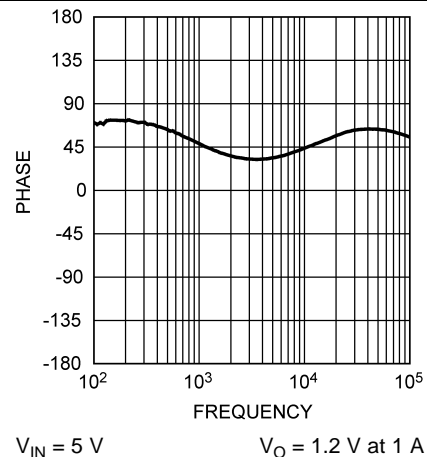
**Figure 14. Line Regulation**



**Figure 15.  $V_{FB}$  vs Temperature**



**Figure 16. Gain vs Frequency**



**Figure 17. Phase Plot vs Frequency**

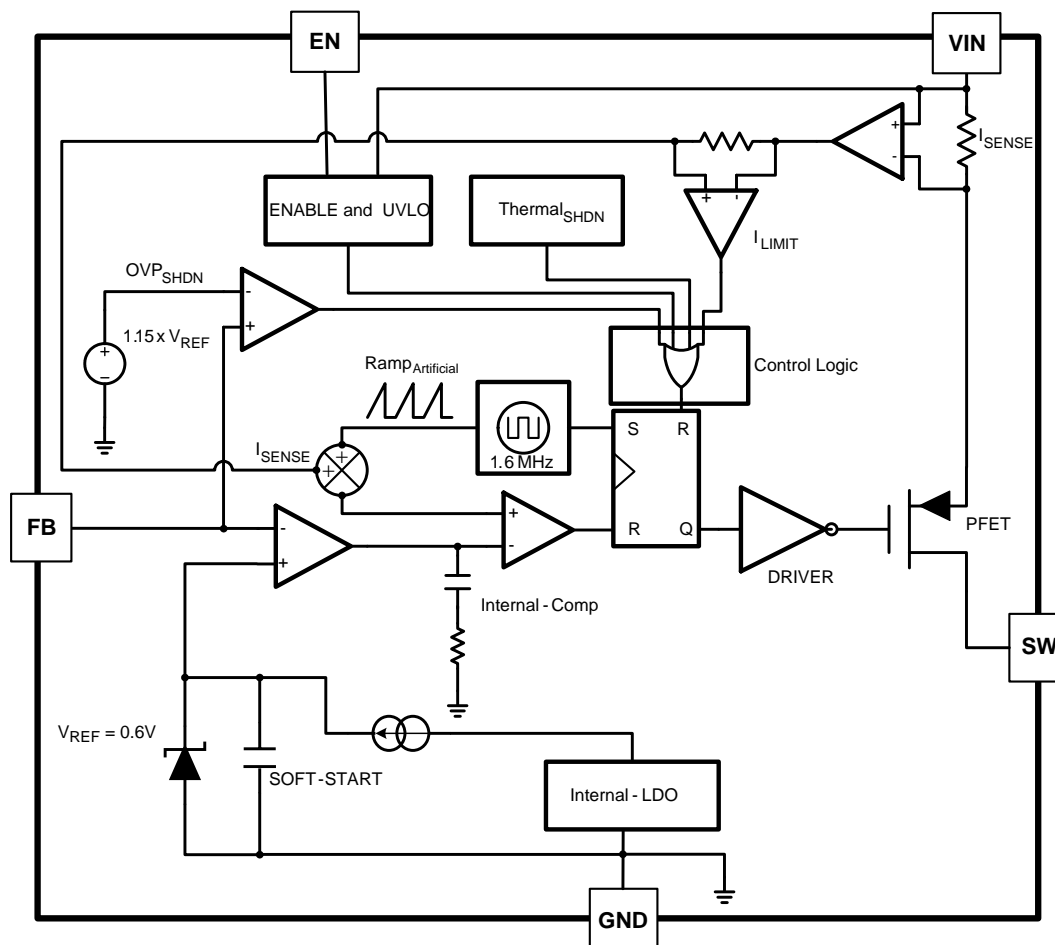


## 7 Detailed Description

### 7.1 Overview

The LM2831 device is a constant-frequency PWM buck regulator IC that delivers a 1.5-A load current. The regulator has a preset switching frequency of 550 kHz, 1.6 MHz, or 3 MHz. This high-frequency allows the LM2831 to operate with small surface mount capacitors and inductors, resulting in a DC-DC converter that requires a minimum amount of board space. The LM2831 is internally compensated, so the device is simple to use and requires few external components.

### 7.2 Functional Block Diagram



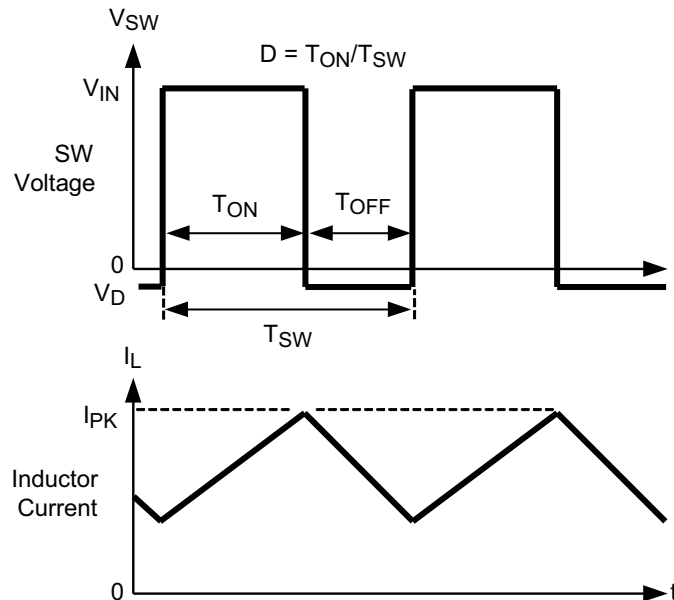
### 7.3 Feature Description

#### 7.3.1 Theory of Operation

The LM2831 uses current-mode control to regulate the output voltage. The following operating description of the LM2831 will refer to [Functional Block Diagram](#) and to the waveforms in [Figure 18](#). The LM2831 supplies a regulated output voltage by switching the internal PMOS control switch at constant-frequency and variable duty cycle. A switching cycle begins at the falling edge of the reset pulse generated by the internal oscillator. When this pulse goes low, the output control logic turns on the internal PMOS control switch. During this on-time, the SW pin voltage ( $V_{SW}$ ) swings up to approximately  $V_{IN}$ , and the inductor current ( $I_L$ ) increases with a linear slope.  $I_L$  is measured by the current sense amplifier, which generates an output proportional to the switch current. The sense signal is summed with the regulator's corrective ramp and compared to the error amplifier's output, which

## Feature Description (continued)

is proportional to the difference between the feedback voltage and  $V_{REF}$ . When the PWM comparator output goes high, the output switch turns off until the next switching cycle begins. During the switch off-time, inductor current discharges through the Schottky catch diode, which forces the SW pin to swing below ground by the forward voltage ( $V_D$ ) of the Schottky catch diode. The regulator loop adjusts the duty cycle ( $D$ ) to maintain a constant output voltage.



**Figure 18. Typical Waveforms**

### 7.3.2 Soft Start

This function forces  $V_{OUT}$  to increase at a controlled rate during start up. During soft start, the error amplifier's reference voltage ramps from 0 V to its nominal value of 0.6 V in approximately 600  $\mu$ s. This forces the regulator output to ramp up in a controlled fashion, which helps reduce inrush current.

### 7.3.3 Output Overvoltage Protection

The overvoltage comparator compares the FB pin voltage to a voltage that is 15% higher than the internal reference  $V_{REF}$ . Once the FB pin voltage goes 15% above the internal reference, the internal PMOS control switch is turned off, which allows the output voltage to decrease toward regulation.

### 7.3.4 Undervoltage Lockout

Undervoltage lockout (UVLO) prevents the LM2831 from operating until the input voltage exceeds 2.73 V (typical). The UVLO threshold has approximately 430 mV of hysteresis, so the part will operate until  $V_{IN}$  drops below 2.3 V (typical). Hysteresis prevents the part from turning off during power up if  $V_{IN}$  is non-monotonic.

### 7.3.5 Current Limit

The LM2831 uses cycle-by-cycle current limiting to protect the output switch. During each switching cycle, a current limit comparator detects if the output switch current exceeds 2.5 A (typical), and turns off the switch until the next switching cycle begins.

### 7.3.6 Thermal Shutdown

Thermal shutdown limits total power dissipation by turning off the output switch when the IC junction temperature exceeds 165°C. After thermal shutdown occurs, the output switch doesn't turn on until the junction temperature drops to approximately 150°C.

## 7.4 Device Functional Modes

The LM2831 has an enable pin (EN) control Input. A logic high enables device operation. Do not float this pin or let this pin be greater than  $V_{IN} + 0.3\text{ V}$  for the SOT package option, or  $V_{INA} + 0.3\text{ V}$  for the WSON package option.

## 8 Application and Implementation

### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 8.1 Application Information

The LM2831 device will operate with input voltage range from 3 V to 5.5 V and provide a regulated output voltage. This device is optimized for high-efficiency operation with minimum number of external components. For component selection, see [Detailed Design Procedure](#).

### 8.2 Typical Applications

#### 8.2.1 LM2831X Design Example 1

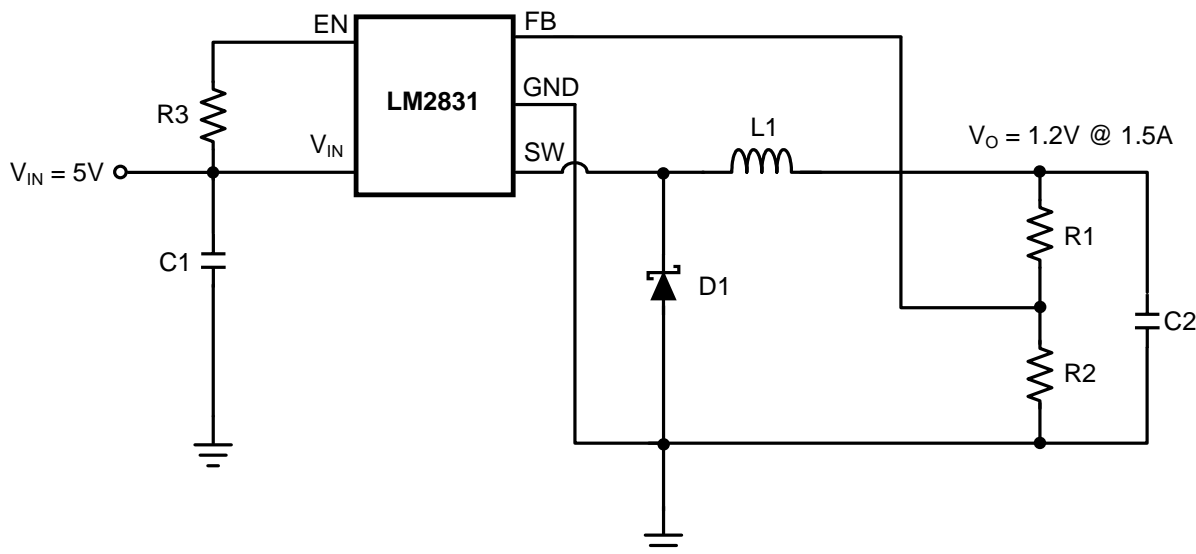


Figure 19. LM2831X (1.6 MHz):  $V_{IN} = 5\text{ V}$ ,  $V_O = 1.2\text{ V}$  at 1.5 A

##### 8.2.1.1 Design Requirements

The device must be able to operate at any voltage within the recommended operating range. Load current must be defined to properly size the inductor, input, and output capacitors. Inductor should be able to handle full expected load current as well as the peak current generated during load transients and start up. Inrush current at start-up will depend on the output capacitor selection. More details are provided in [Detailed Design Procedure](#).

## Typical Applications (continued)

### 8.2.1.2 Detailed Design Procedure

**Table 1. Bill of Materials**

PART ID	PART VALUE	MANUFACTURER	PART NUMBER
U1	1.5-A Buck Regulator	TI	LM2831X
C1, Input Cap	22 $\mu$ F, 6.3 V, X5R	TDK	C3216X5ROJ226M
C2, Output Cap	2x22 $\mu$ F, 6.3 V, X5R	TDK	C3216X5ROJ226M
D1, Catch Diode	0.3 V <sub>f</sub> Schottky 1.5 A, 30 V <sub>R</sub>	TOSHIBA	CRS08
L1	3.3 $\mu$ H, 2.2 A	TDK	VLCF5020T-3R3N2R0-1
R2	15.0 k $\Omega$ , 1%	Vishay	CRCW08051502F
R1	15.0 k $\Omega$ , 1%	Vishay	CRCW08051502F
R3	100 k $\Omega$ , 1%	Vishay	CRCW08051003F

#### 8.2.1.2.1 Inductor Selection

The duty cycle (D) can be approximated quickly using the ratio of output voltage (V<sub>O</sub>) to input voltage (V<sub>IN</sub>):

$$D = \frac{V_{OUT}}{V_{IN}} \quad (1)$$

The catch diode (D1) forward voltage drop and the voltage drop across the internal PMOS must be included to calculate a more accurate duty cycle. Calculate D by using the following formula:

$$D = \frac{V_{OUT} + V_D}{V_{IN} + V_D - V_{SW}} \quad (2)$$

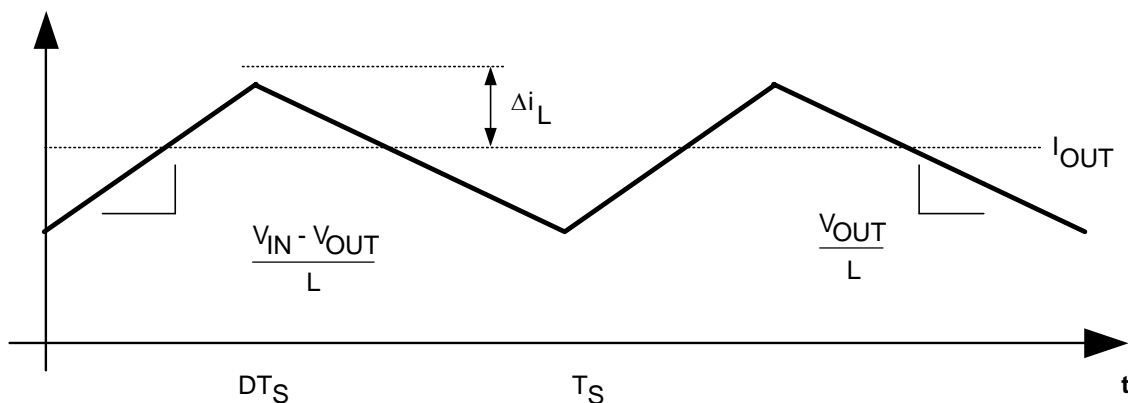
V<sub>SW</sub> can be approximated by:

$$V_{SW} = I_{OUT} \times R_{DS(on)} \quad (3)$$

The diode forward drop (V<sub>D</sub>) can range from 0.3 V to 0.7 V depending on the quality of the diode. The lower the V<sub>D</sub>, the higher the operating efficiency of the converter. The inductor value determines the output ripple current. Lower inductor values decrease the size of the inductor, but increase the output ripple current. An increase in the inductor value will decrease the output ripple current.

One must ensure that the minimum current limit (1.8 A) is not exceeded, so the peak current in the inductor must be calculated. The peak current (I<sub>LPK</sub>) in the inductor is calculated by:

$$I_{LPK} = I_{OUT} + \Delta i_L \quad (4)$$


**Figure 20. Inductor Current**

$$\frac{V_{IN} - V_{OUT}}{L} = \frac{2\Delta i_L}{DT_S} \quad (5)$$

In general,

$$\Delta i_L = 0.1 \times (I_{OUT}) \rightarrow 0.2 \times (I_{OUT}) \quad (6)$$

If  $\Delta i_L = 20\%$  of 1.50 A, the peak current in the inductor will be 1.8 A. The minimum ensured current limit over all operating conditions is 1.8 A. One can either reduce  $\Delta i_L$ , or make the engineering judgment that zero margin will be safe enough. The typical current limit is 2.5 A.

The LM2831 operates at frequencies allowing the use of ceramic output capacitors without compromising transient response. Ceramic capacitors allow higher inductor ripple without significantly increasing output ripple. See the [Output Capacitor](#) section for more details on calculating output voltage ripple. Now that the ripple current is determined, the inductance is calculated by:

$$L = \left( \frac{DT_S}{2\Delta i_L} \right) \times V_{IN} - V_{OUT} \quad (7)$$

Where:

$$T_S = \frac{1}{f_S} \quad (8)$$

When selecting an inductor, make sure that it is capable of supporting the peak output current without saturating. Inductor saturation will result in a sudden reduction in inductance and prevent the regulator from operating correctly. Because of the speed of the internal current limit, the peak current of the inductor need only be specified for the required maximum output current. For example, if the designed maximum output current is 1 A and the peak current is 1.25 A, then the inductor should be specified with a saturation current limit of > 1.25 A. There is no need to specify the saturation or peak current of the inductor at the 2.5-A typical switch current limit. The difference in inductor size is a factor of 5. Because of the operating frequency of the LM2831, ferrite based inductors are preferred to minimize core losses. This presents little restriction since the variety of ferrite-based inductors is huge. Lastly, inductors with lower series resistance ( $R_{DCR}$ ) will provide better operating efficiency. For recommended inductors, see [LM2831X Design Example 2](#) through [LM2831X Buck Converter and Voltage Double Circuit With LDO Follower Design Example 9](#).

#### 8.2.1.2.2 Input Capacitor

An input capacitor is necessary to ensure that  $V_{IN}$  does not drop excessively during switching transients. The primary specifications of the input capacitor are capacitance, voltage, RMS current rating, and ESL (Equivalent Series Inductance). The recommended input capacitance is 22  $\mu$ F. The input voltage rating is specifically stated by the capacitor manufacturer. Make sure to check any recommended deratings and also verify if there is any significant change in capacitance at the operating input voltage and the operating temperature. The input capacitor maximum RMS input current rating ( $I_{RMS-IN}$ ) must be greater than:

$$I_{RMS-IN} \sqrt{D \left[ I_{OUT}^2 (1-D) + \frac{\Delta i^2}{3} \right]} \quad (9)$$

Neglecting inductor ripple simplifies the above equation to:

$$I_{RMS-IN} = I_{OUT} \times \sqrt{D(1-D)} \quad (10)$$

It can be shown from the above equation that maximum RMS capacitor current occurs when  $D = 0.5$ . Always calculate the RMS at the point where the duty cycle  $D$  is closest to 0.5. The ESL of an input capacitor is usually determined by the effective cross sectional area of the current path. A large leaded capacitor will have high ESL and a 0805 ceramic chip capacitor will have very low ESL. At the operating frequencies of the LM2831, leaded capacitors may have an ESL so large that the resulting impedance ( $2\pi fL$ ) will be higher than that required to provide stable operation. As a result, surface mount capacitors are strongly recommended.

Sanyo POSCAP, Tantalum or Niobium, Panasonic SP, and multilayer ceramic capacitors (MLCC) are all good choices for both input and output capacitors and have very low ESL. For MLCCs it is recommended to use X7R or X5R type capacitors due to their tolerance and temperature characteristics. Consult capacitor manufacturer data sheets to see how rated capacitance varies over operating conditions.

### 8.2.1.2.3 Output Capacitor

The output capacitor is selected based upon the desired output ripple and transient response. The initial current of a load transient is provided mainly by the output capacitor. The output ripple of the converter is:

$$V_{OUT} = \Delta I_L \left( R_{ESR} + \frac{1}{8 \times F_{SW} \times C_{OUT}} \right) \quad (11)$$

When using MLCCs, the ESR is typically so low that the capacitive ripple may dominate. When this occurs, the output ripple will be approximately sinusoidal and 90° phase shifted from the switching action. Given the availability and quality of MLCCs and the expected output voltage of designs using the LM2831, there is really no need to review any other capacitor technologies. Another benefit of ceramic capacitors is their ability to bypass high frequency noise. A certain amount of switching edge noise will couple through parasitic capacitances in the inductor to the output. A ceramic capacitor will bypass this noise while a tantalum will not. Since the output capacitor is one of the two external components that control the stability of the regulator control loop, most applications will require a minimum of 22 µF of output capacitance. Capacitance often, but not always, can be increased significantly with little detriment to the regulator stability. Like the input capacitor, recommended multilayer ceramic capacitors are X7R or X5R types.

### 8.2.1.2.4 Catch Diode

The catch diode (D1) conducts during the switch off-time. A Schottky diode is recommended for its fast switching times and low forward voltage drop. The catch diode should be chosen so that its current rating is greater than:

$$I_{D1} = I_{OUT} \times (1-D) \quad (12)$$

The reverse breakdown rating of the diode must be at least the maximum input voltage plus appropriate margin. To improve efficiency, choose a Schottky diode with a low forward voltage drop.

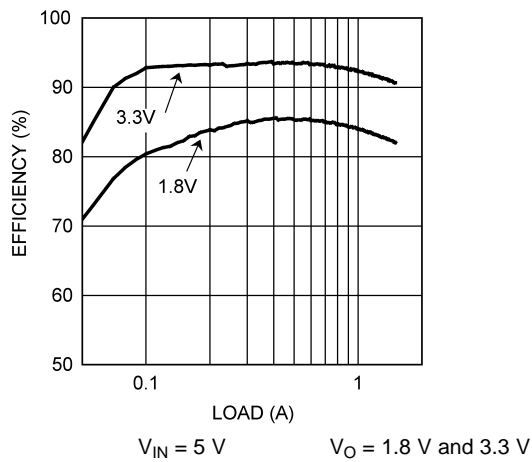
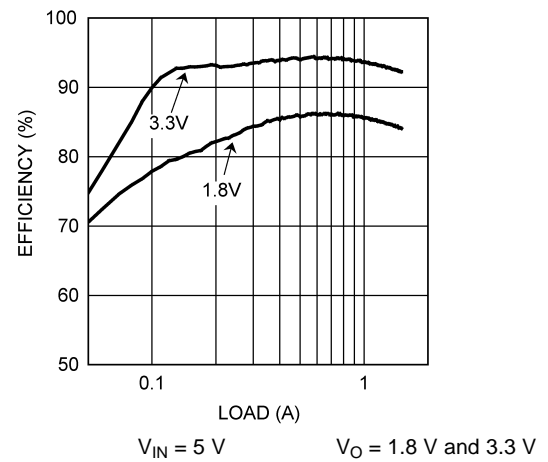
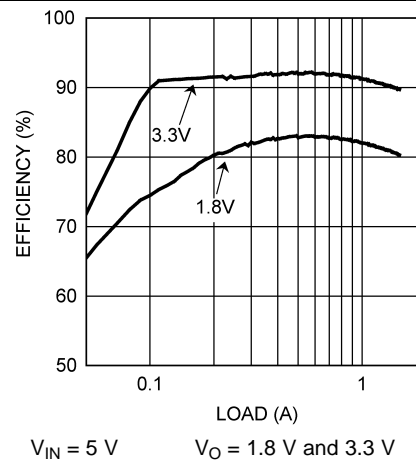
### 8.2.1.2.5 Output Voltage

The output voltage is set using the following equation where R2 is connected between the FB pin and GND, and R1 is connected between V<sub>O</sub> and the FB pin. A good value for R2 is 10 kΩ. When designing a unity gain converter (V<sub>O</sub> = 0.6 V), R1 should be from 0 Ω to 100 Ω, and R2 should be equal or greater than 10 kΩ.

$$R1 = \left( \frac{V_{OUT}}{V_{REF}} - 1 \right) \times R2 \quad (13)$$

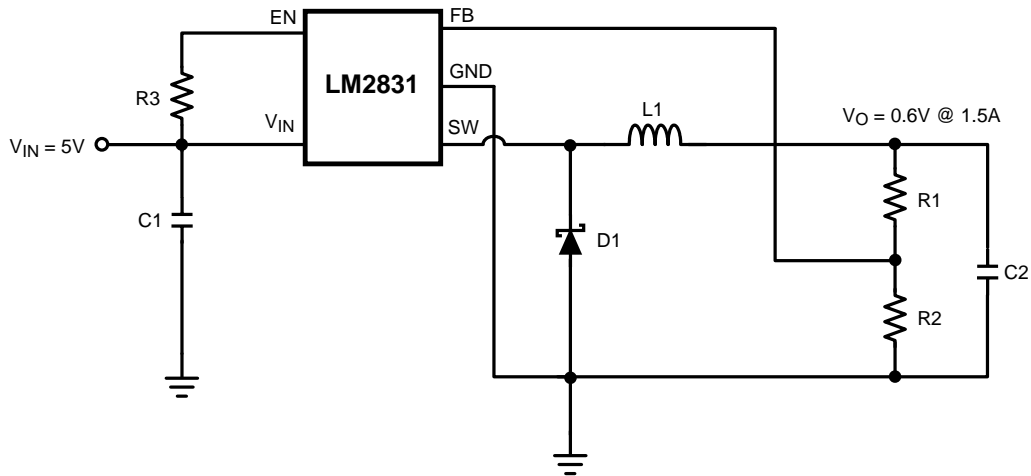
$$V_{REF} = 0.60 \text{ V} \quad (14)$$

### 8.2.1.3 Application Curves

 See [Typical Characteristics](#).

**Figure 21.  $\eta$  vs Load – X Option**

**Figure 22.  $\eta$  vs Load – Y Option**

**Figure 23.  $\eta$  vs Load – Z Option**



### 8.2.2 LM2831X Design Example 2



**Figure 24. LM2831X (1.6 MHz):  $V_{IN} = 5\text{ V}$ ,  $V_O = 0.6\text{ V}$  at  $1.5\text{ A}$**

**Table 2. Bill of Materials**

PART ID	PART VALUE	MANUFACTURER	PART NUMBER
U1	1.5-A Buck Regulator	TI	LM2831X
C1, Input Capacitor	22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
C2, Output Capacitor	2x22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
D1, Catch Diode	0.3 $V_f$ Schottky 1.5 A, 30 $V_R$	TOSHIBA	CRS08
L1	3.3 $\mu\text{H}$ , 2.2 A	TDK	VLCF5020T- 3R3N2R0-1
R2	10.0 k $\Omega$ , 1%	Vishay	CRCW08051000F
R1	0 $\Omega$		
R3	100 k $\Omega$ , 1%	Vishay	CRCW08051003F

## LM2831

SNVS422D – AUGUST 2006 – REVISED SEPTEMBER 2015

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### 8.2.3 LM2831X Design Example 3

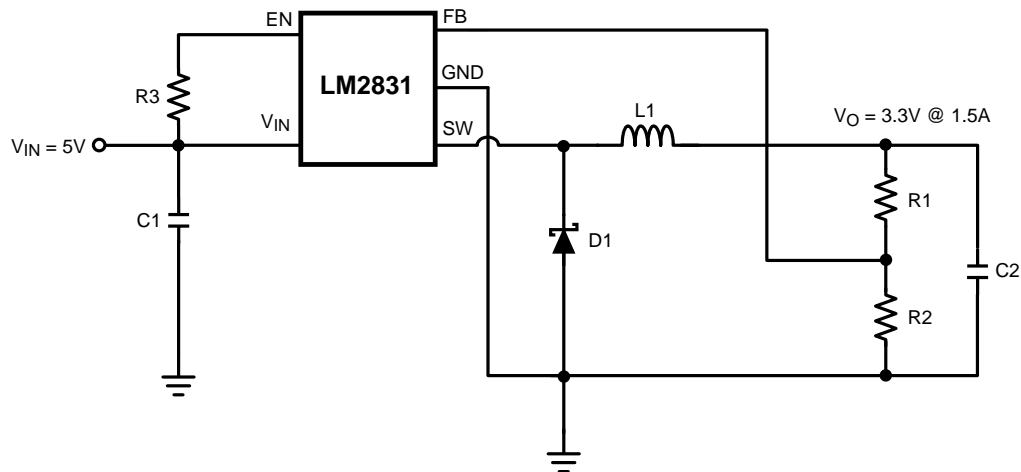
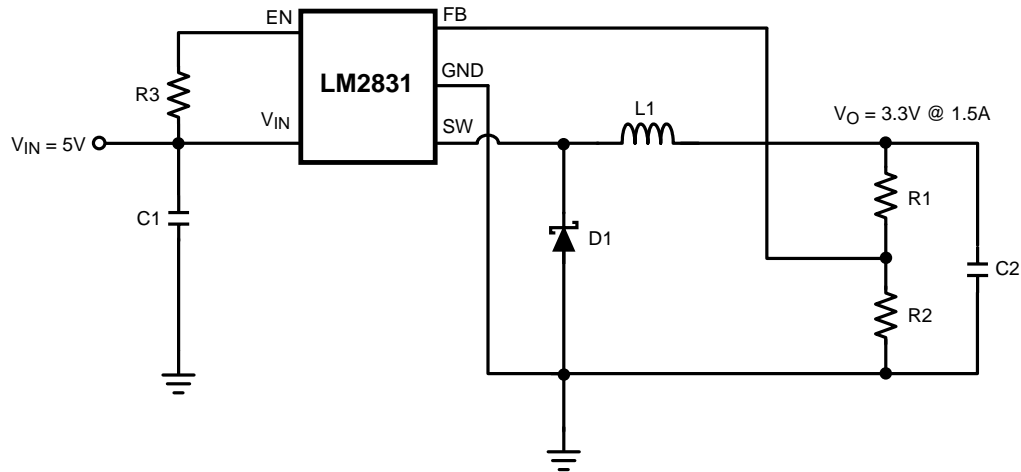


Figure 25. LM2831X (1.6 MHz):  $V_{IN} = 5\text{ V}$ ,  $V_O = 3.3\text{ V}$  at 1.5 A

Table 3. Bill of Materials

PART ID	PART VALUE	MANUFACTURER	PART NUMBER
U1	1.5-A Buck Regulator	TI	LM2831X
C1, Input Cap	22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
C2, Output Cap	2x22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
D1, Catch Diode	0.3 $V_f$ Schottky 1.5 A, 30 $V_R$	TOSHIBA	CRS08
L1	2.7 $\mu\text{H}$ 2.3 A	TDK	VLCF5020T-2R7N2R2-1
R2	10.0 $\text{k}\Omega$ , 1%	Vishay	CRCW08051002F
R1	45.3 $\text{k}\Omega$ , 1%	Vishay	CRCW08054532F
R3	100 $\text{k}\Omega$ , 1%	Vishay	CRCW08051003F

## 8.2.4 LM2831Y Design Example 4



**Figure 26. LM2831Y (550 kHz):  $V_{IN} = 5\text{ V}$ ,  $V_{OUT} = 3.3\text{ V}$  at  $1.5\text{ A}$**

**Table 4. Bill of Materials**

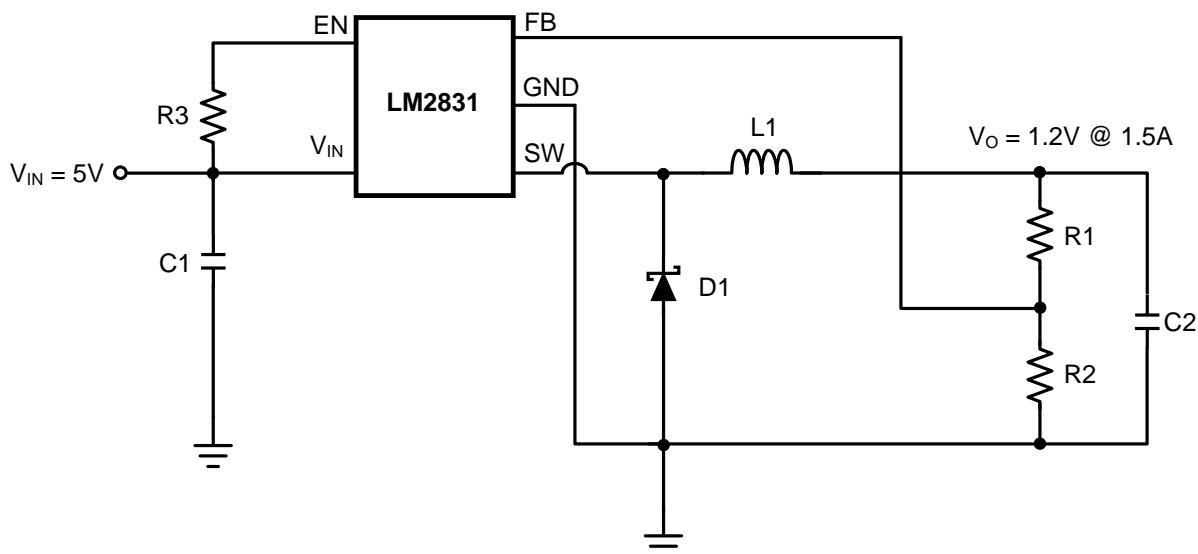
PART ID	PART VALUE	MANUFACTURER	PART NUMBER
U1	1.5-A Buck Regulator	TI	LM2831Y
C1, Input Cap	22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
C2, Output Cap	2x22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
D1, Catch Diode	0.3 $V_f$ Schottky 1.5 A, 30 $V_R$	TOSHIBA	CRS08
L1	4.7 $\mu\text{H}$ 2.1 A	TDK	SLF7045T-4R7M2R0-PF
R1	45.3 $\text{k}\Omega$ , 1%	Vishay	CRCW080545K3FKEA
R2	10.0 $\text{k}\Omega$ , 1%	Vishay	CRCW08051002F

## LM2831

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### 8.2.5 LM2831Y Design Example 5

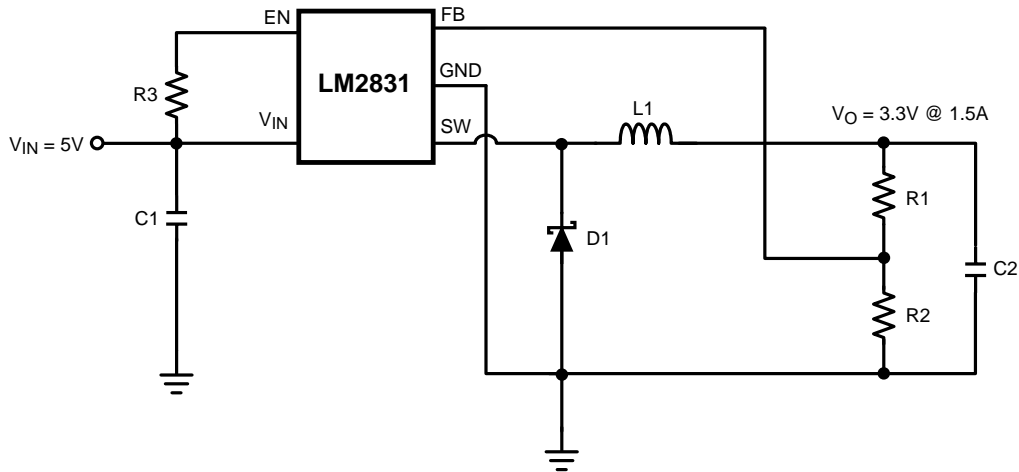


**Figure 27. LM2831Y (550 kHz):  $V_{IN} = 5\text{ V}$ ,  $V_{OUT} = 1.2\text{ V}$  at  $1.5\text{ A}$**

**Table 5. Bill of Materials**

PART ID	PART VALUE	MANUFACTURER	PART NUMBER
U1	1.5-A Buck Regulator	TI	LM2831Y
C1, Input Cap	22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
C2, Output Cap	2x22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
D1, Catch Diode	0.3 $V_f$ Schottky 1.5 A, 30 $V_R$	TOSHIBA	CRS08
L1	6.8 $\mu\text{H}$ 1.8 A	TDK	SLF7045T-6R8M1R7
R1	10.0 k $\Omega$ , 1%	Vishay	CRCW08051002F
R2	10.0 k $\Omega$ , 1%	Vishay	CRCW08051002F

## 8.2.6 LM2831Z Design Example 6



**Figure 28. LM2831Z (3 MHz):  $V_{IN} = 5\text{ V}$ ,  $V_O = 3.3\text{ V}$  at  $1.5\text{ A}$**

**Table 6. Bill of Materials**

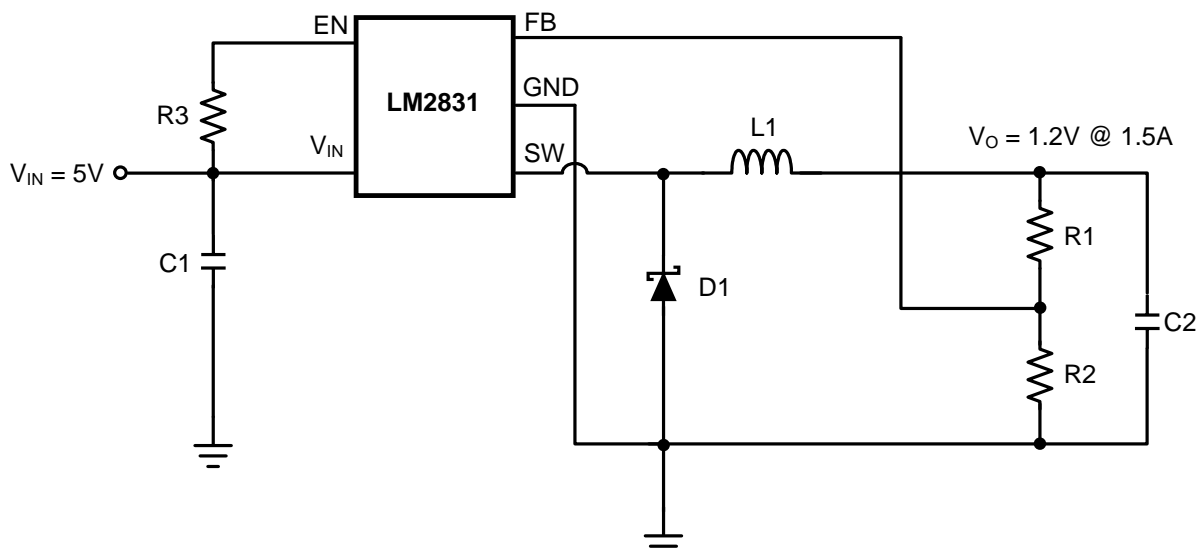
PART ID	PART VALUE	MANUFACTURER	PART NUMBER
U1	1.5-A Buck Regulator	TI	LM2831Z
C1, Input Cap	22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
C2, Output Cap	2x22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
D1, Catch Diode	0.3 $V_f$ Schottky 1.5 A, 30 $V_R$	TOSHIBA	CRS08
L1	1.6 $\mu\text{H}$ 2.0 A	TDK	VLCF4018T-1R6N1R7-2
R2	10.0 $\text{k}\Omega$ , 1%	Vishay	CRCW08051002F
R1	45.3 $\text{k}\Omega$ , 1%	Vishay	CRCW08054532F
R3	100 $\text{k}\Omega$ , 1%	Vishay	CRCW08051003F

## LM2831

SNVS422D – AUGUST 2006 – REVISED SEPTEMBER 2015

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### 8.2.7 LM2831Z Design Example 7

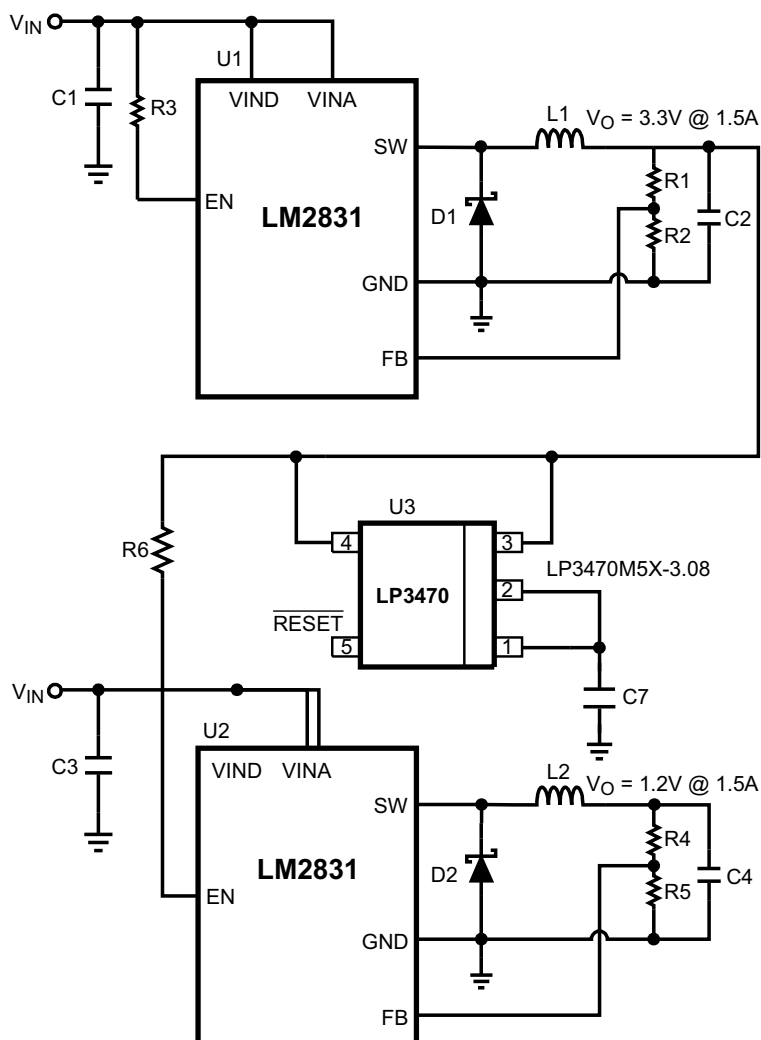


**Figure 29. LM2831Z (3 MHz):  $V_{IN} = 5\text{ V}$ ,  $V_O = 1.2\text{ V}$  at  $1.5\text{ A}$**

**Table 7. Bill of Materials**

PART ID	PART VALUE	MANUFACTURER	PART NUMBER
U1	1.5-A Buck Regulator	TI	LM2831Z
C1, Input Cap	22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
C2, Output Cap	2x22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
D1, Catch Diode	0.3 $V_f$ Schottky 1.5 A, 30 $V_R$	TOSHIBA	CRS08
L1	1.6 $\mu\text{H}$ , 2.0 A	TDK	VLCF4018T- 1R6N1R7-2
R2	10.0 k $\Omega$ , 1%	Vishay	CRCW08051002F
R1	10.0 k $\Omega$ , 1%	Vishay	CRCW08051002F
R3	100 k $\Omega$ , 1%	Vishay	CRCW08051003F

### 8.2.8 LM2831X Dual Converters with Delayed Enabled Design Example 8



**Figure 30. LM2831X (1.6 MHz):  $V_{IN} = 5\text{ V}$ ,  $V_O = 1.2\text{ V}$  at 1.5 A and 3.3 V at 1.5 A**

### Table 8. Bill of Materials

PART ID	PART VALUE	MANUFACTURER	PART NUMBER
U1, U2	1.5-A Buck Regulator	TI	LM2831X
U3	Power on Reset	TI	LP3470M5X-3.08
C1, C3 Input Cap	22 $\mu$ F, 6.3 V, X5R	TDK	C3216X5ROJ226M
C2, C4 Output Cap	2x22 $\mu$ F, 6.3 V, X5R	TDK	C3216X5ROJ226M
C7	Trr delay capacitor	TDK	
D1, D2 Catch Diode	0.3 V <sub>f</sub> Schottky 1.5 A, 30 V <sub>R</sub>	TOSHIBA	CRS08
L1, L2	3.3 $\mu$ H, 2.2 A	TDK	VLCF5020T-3R3N2R0-1
R2, R4, R5	10.0 k $\Omega$ , 1%	Vishay	CRCW08051002F
R1, R6	45.3 k $\Omega$ , 1%	Vishay	CRCW08054532F
R3	100 k $\Omega$ , 1%	Vishay	CRCW08051003F

## LM2831

SNVS422D – AUGUST 2006 – REVISED SEPTEMBER 2015

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### 8.2.9 LM2831X Buck Converter and Voltage Double Circuit With LDO Follower Design Example 9

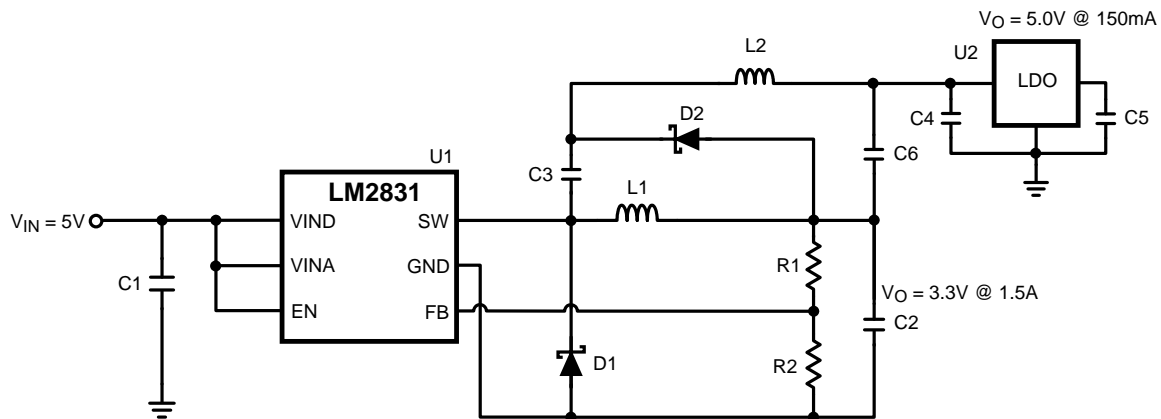


Figure 31. LM2831X (1.6 MHz):  $V_{IN} = 5\text{ V}$ ,  $V_O = 3.3\text{ V}$  at 1.5 A and LP2986-5.0 at 150 mA

Table 9. Bill of Materials

PART ID	PART VALUE	MANUFACTURER	PART NUMBER
U1	1.5-A Buck Regulator	TI	LM2831X
U2	200-mA LDO	TI	LP2986-5.0
C1, Input Cap	22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
C2, Output Cap	22 $\mu\text{F}$ , 6.3 V, X5R	TDK	C3216X5ROJ226M
C3 – C6	2.2 $\mu\text{F}$ , 6.3 V, X5R	TDK	C1608X5R0J225M
D1, Catch Diode	0.3 $V_f$ Schottky 1.5 A, 30 $V_R$	TOSHIBA	CRS08
D2	0.4 $V_f$ Schottky 20 $V_R$ , 500 mA	ON Semi	MBR0520
L2	10 $\mu\text{H}$ , 800 mA	CoilCraft	ME3220-103
L1	3.3 $\mu\text{H}$ , 2.2 A	TDK	VLCF5020T-3R3N2R0-1
R2	45.3 k $\Omega$ , 1%	Vishay	CRCW08054532F
R1	10.0 k $\Omega$ , 1%	Vishay	CRCW08051002F



## 9 Power Supply Recommendations

The LM2831 device is designed to operate from various DC power supplies. The impedance of the input supply rail should be low enough that the input current transient does not cause a drop below the UVLO level. If the input supply is connected by using long wires, additional bulk capacitance may be required in addition to normal input capacitor.

## 10 Layout

### 10.1 Layout Guidelines

When planning layout there are a few things to consider when trying to achieve a clean, regulated output. The most important consideration is the close coupling of the GND connections of the input capacitor and the catch diode D1. These ground ends should be close to one another and be connected to the GND plane with at least two through-holes. Place these components as close to the IC as possible. Next in importance is the location of the GND connection of the output capacitor, which should be near the GND connections of CIN and D1. There should be a continuous ground plane on the bottom layer of a two-layer board except under the switching node island. The FB pin is a high impedance node and care should be taken to make the FB trace short to avoid noise pickup and inaccurate regulation. The feedback resistors should be placed as close as possible to the IC, with the GND of R1 placed as close as possible to the GND of the IC. The  $V_{OUT}$  trace to R2 should be routed away from the inductor and any other traces that are switching. High AC currents flow through the  $V_{IN}$ , SW and  $V_{OUT}$  traces, so they should be as short and wide as possible. However, making the traces wide increases radiated noise, so the designer must make this trade-off. Radiated noise can be decreased by choosing a shielded inductor. The remaining components should also be placed as close as possible to the IC. See Application Note AN-1229 [SNVA054](#) for further considerations and the LM2831 demo board as an example of a 4-layer layout.

#### 10.1.1 Calculating Efficiency and Junction Temperature

The complete LM2831 DC-DC converter efficiency can be calculated in the following manner.

$$\eta = \frac{P_{OUT}}{P_{IN}} \quad (15)$$

Or

$$\eta = \frac{P_{OUT}}{P_{OUT} + P_{LOSS}} \quad (16)$$

Calculations for determining the most significant power losses are shown below. Other losses totaling less than 2% are not discussed.

Power loss ( $P_{LOSS}$ ) is the sum of two basic types of losses in the converter: switching and conduction. Conduction losses usually dominate at higher output loads, whereas switching losses remain relatively fixed and dominate at lower output loads. The first step in determining the losses is to calculate the duty cycle (D):

$$D = \frac{V_{OUT} + V_D}{V_{IN} + V_D - V_{SW}} \quad (17)$$

$V_{SW}$  is the voltage drop across the internal PFET when it is on, and is equal to:

$$V_{SW} = I_{OUT} \times R_{DS(on)} \quad (18)$$

$V_D$  is the forward voltage drop across the Schottky catch diode. It can be obtained from the diode manufactures [Electrical Characteristics](#) section. If the voltage drop across the inductor ( $V_{DCR}$ ) is accounted for, the equation becomes:

$$D = \frac{V_{OUT} + V_D + V_{DCR}}{V_{IN} + V_D + V_{DCR} - V_{SW}} \quad (19)$$

The conduction losses in the free-wheeling Schottky diode are calculated as follows:

$$P_{DIODE} = V_D \times I_{OUT} \times (1-D) \quad (20)$$

## Layout Guidelines (continued)

Often this is the single most significant power loss in the circuit. Care should be taken to choose a Schottky diode that has a low forward voltage drop.

Another significant external power loss is the conduction loss in the output inductor. The equation can be simplified to:

$$P_{IND} = I_{OUT}^2 \times R_{DCR} \quad (21)$$

The LM2831 conduction loss is mainly associated with the internal PFET:

$$P_{COND} = (I_{OUT}^2 \times D) \left( 1 + \frac{1}{3} \times \left( \frac{\Delta I_L}{I_{OUT}} \right)^2 \right) R_{DS(ON)} \quad (22)$$

If the inductor ripple current is fairly small, the conduction losses can be simplified to:

$$P_{COND} = I_{OUT}^2 \times R_{DS(ON)} \times D \quad (23)$$

Switching losses are also associated with the internal PFET. They occur during the switch on and off transition periods, where voltages and currents overlap resulting in power loss. The simplest means to determine this loss is to empirically measuring the rise and fall times (10% to 90%) of the switch at the switch node.

Switching power loss is calculated as follows:

$$P_{SWR} = 1/2(V_{IN} \times I_{OUT} \times F_{SW} \times T_{RISE}) \quad (24)$$

$$P_{SWF} = 1/2(V_{IN} \times I_{OUT} \times F_{SW} \times T_{FALL}) \quad (25)$$

$$P_{SW} = P_{SWR} + P_{SWF} \quad (26)$$

Another loss is the power required for operation of the internal circuitry:

$$P_Q = I_Q \times V_{IN} \quad (27)$$

$I_Q$  is the quiescent operating current, and is typically around 2.5 mA for the 0.55-MHz frequency option.

Typical application power losses are:

**Table 10. Power Loss Tabulation**

PARAMETER	VALUE	PARAMETER	VALUE
$V_{IN}$	5 V		
$V_{OUT}$	3.3 V	$P_{OUT}$	4.125 W
$I_{OUT}$	1.25 A		
$V_D$	0.45 V	$P_{DIODE}$	188 mW
$F_{SW}$	550 kHz		
$I_Q$	2.5 mA	$P_Q$	12.5 mW
$T_{RISE}$	4 nS	$P_{SWR}$	7 mW
$T_{FALL}$	4 nS	$P_{SWF}$	7 mW
$R_{DS(ON)}$	150 mΩ	$P_{COND}$	156 mW
$IND_{DCR}$	70 mΩ	$P_{IND}$	110 mW
$D$	0.667	$P_{LOSS}$	481 mW
$\eta$	88%	$P_{INTERNAL}$	183 mW

$$\Sigma P_{COND} + P_{SW} + P_{DIODE} + P_{IND} + P_Q = P_{LOSS} \quad (28)$$

$$\Sigma P_{COND} + P_{SWF} + P_{SWR} + P_Q = P_{INTERNAL} \quad (29)$$

$$P_{INTERNAL} = 183 \text{ mW} \quad (30)$$

### 10.1.2 Thermal Definitions

$T_J$  Chip junction temperature

$T_A$  Ambient temperature

$R_{\theta JC}$  Thermal resistance from chip junction to device case

$R_{\theta JA}$  Thermal resistance from chip junction to ambient air

Heat in the LM2831 due to internal power dissipation is removed through conduction and/or convection.

**Conduction** Heat transfer occurs through cross sectional areas of material. Depending on the material, the transfer of heat can be considered to have poor to good thermal conductivity properties (insulator vs. conductor).

Heat Transfer goes as:

Silicon → package → lead frame → PCB

**Convection:** Heat transfer is by means of airflow. This could be from a fan or natural convection. Natural convection occurs when air currents rise from the hot device to cooler air.

Thermal impedance is defined as:

$$R_{\theta} = \frac{\Delta T}{\text{Power}} \quad (31)$$

Thermal impedance from the silicon junction to the ambient air is defined as:

$$R_{\theta JA} = \frac{T_J - T_A}{\text{Power}} \quad (32)$$

The PCB size, weight of copper used to route traces and ground plane, and number of layers within the PCB can greatly effect  $R_{\theta JA}$ . The type and number of thermal vias can also make a large difference in the thermal impedance. Thermal vias are necessary in most applications. They conduct heat from the surface of the PCB to the ground plane. Four to six thermal vias should be placed under the exposed pad to the ground plane if the WSON package is used.

Thermal impedance also depends on the thermal properties of the application operating conditions ( $V_{in}$ ,  $V_o$ ,  $I_o$ , and so forth), and the surrounding circuitry.

#### 10.1.2.1 Silicon Junction Temperature Determination Method 1

To accurately measure the silicon temperature for a given application, two methods can be used. The first method requires the user to know the thermal impedance of the silicon junction to top case temperature.

Some clarification must be made before we go any further.

$R_{\theta JC}$  is the thermal impedance from all six sides of an IC package to silicon junction.

$R_{\phi JC}$  is the thermal impedance from top case to the silicon junction.

In this data sheet we will use  $R_{\phi JC}$  so that it allows the user to measure top case temperature with a small thermocouple attached to the top case.

$R_{\phi JC}$  is approximately 30°C/Watt for the 6-pin WSON package with the exposed pad. Knowing the internal dissipation from the efficiency calculation given previously, and the case temperature, which can be empirically measured on the bench we have:

$$R_{\phi JC} = \frac{T_J - T_C}{\text{Power}} \quad (33)$$

Therefore:

$$T_J = (R_{\phi JC} \times P_{\text{LOSS}}) + T_C \quad (34)$$

From the previous example:

$$T_J = (R_{\phi JC} \times P_{\text{INTERNAL}}) + T_C \quad (35)$$

$$T_J = 30^{\circ}\text{C/W} \times 0.189 \text{ W} + T_C \quad (36)$$

The second method can give a very accurate silicon junction temperature.

The first step is to determine  $R_{\theta JA}$  of the application. The LM2831 has overtemperature protection circuitry. When the silicon temperature reaches 165°C, the device stops switching. The protection circuitry has a hysteresis of about 15°C. Once the silicon temperature has decreased to approximately 150°C, the device will start to switch again. Knowing this, the  $R_{\theta JA}$  for any application can be characterized during the early stages of the design one may calculate the  $R_{\theta JA}$  by placing the PCB circuit into a thermal chamber. Raise the ambient temperature in the given working application until the circuit enters thermal shutdown. If the SW-pin is monitored, it will be obvious when the internal PFET stops switching, indicating a junction temperature of 165°C. Knowing the internal power dissipation from the above methods, the junction temperature, and the ambient temperature  $R_{\theta JA}$  can be determined.

$$R_{\theta JA} = \frac{165^{\circ}\text{C} - T_a}{P_{\text{INTERNAL}}} \quad (37)$$

Once this is determined, the maximum ambient temperature allowed for a desired junction temperature can be found.

An example of calculating  $R_{\theta JA}$  for an application using the Texas Instruments LM2831 WSON demonstration board is shown below.

The four layer PCB is constructed using FR4 with ½ oz copper traces. The copper ground plane is on the bottom layer. The ground plane is accessed by two vias. The board measures 3 cm × 3 cm. It was placed in an oven with no forced airflow. The ambient temperature was raised to 144°C, and at that temperature, the device went into thermal shutdown.

From the previous example:

$$P_{\text{INTERNAL}} = 189 \text{ mW} \quad (38)$$

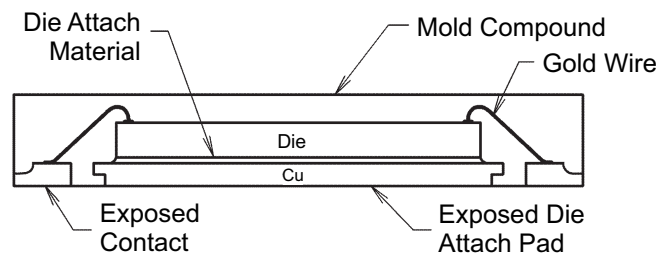
$$R_{\theta JA} = \frac{165^{\circ}\text{C} - 144^{\circ}\text{C}}{189 \text{ mW}} = 111^{\circ}\text{C} / \text{W} \quad (39)$$

If the junction temperature was to be kept below 125°C, then the ambient temperature could not go above 109°C

$$T_j - (R_{\theta JA} \times P_{\text{LOSS}}) = T_a \quad (40)$$

$$125^{\circ}\text{C} - (111^{\circ}\text{C}/\text{W} \times 189 \text{ mW}) = 104^{\circ}\text{C} \quad (41)$$

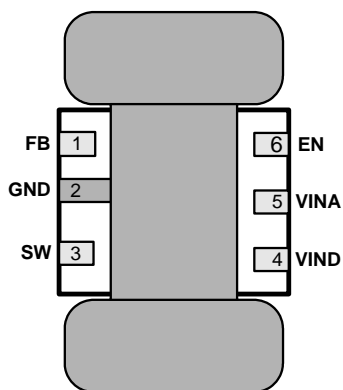
### 10.1.3 WSON Package



**Figure 32. Internal WSON Connection**

For certain high power applications, the PCB land may be modified to a "dog bone" shape (see [Figure 33](#)). By increasing the size of ground plane, and adding thermal vias, the  $R_{\theta JA}$  for the application can be reduced.

## 10.2 Layout Example



**Figure 33. 6-Lead WSON PCB Dog Bone Layout**

## 11 Device and Documentation Support

### 11.1 Device Support

#### 11.1.1 Third-Party Products Disclaimer

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### 11.2 Documentation Support

#### 11.2.1 Related Documentation

For related documentation, see the following:

*AN-1229 SIMPLE SWITCHER® PCB Layout Guidelines*, [SNVA054](#)

### 11.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At [e2e.ti.com](#), you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

### 11.4 Trademarks

E2E is a trademark of Texas Instruments.

All other trademarks are the property of their respective owners.

### 11.5 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### 11.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">LM2831XMF/NOPB</a>	Active	Production	SOT-23 (DBV)   5	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SKYB
LM2831XMF/NOPB.A	Active	Production	SOT-23 (DBV)   5	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SKYB
<a href="#">LM2831XMF/NOPB</a>	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SKYB
LM2831XMF/NOPB.A	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SKYB
<a href="#">LM2831XSD/NOPB</a>	Active	Production	WSON (NGG)   6	1000   SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L193B
LM2831XSD/NOPB.A	Active	Production	WSON (NGG)   6	1000   SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L193B
<a href="#">LM2831XSDX/NOPB</a>	Active	Production	WSON (NGG)   6	4500   LARGE T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L193B
LM2831XSDX/NOPB.A	Active	Production	WSON (NGG)   6	4500   LARGE T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L193B
<a href="#">LM2831YMF/NOPB</a>	Active	Production	SOT-23 (DBV)   5	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SKZB
LM2831YMF/NOPB.A	Active	Production	SOT-23 (DBV)   5	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SKZB
<a href="#">LM2831YMF/NOPB</a>	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SKZB
LM2831YMF/NOPB.A	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SKZB
<a href="#">LM2831YSD/NOPB</a>	Active	Production	WSON (NGG)   6	1000   SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L194B
LM2831YSD/NOPB.A	Active	Production	WSON (NGG)   6	1000   SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L194B
<a href="#">LM2831ZMF/NOPB</a>	Active	Production	SOT-23 (DBV)   5	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SLAB
LM2831ZMF/NOPB.A	Active	Production	SOT-23 (DBV)   5	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SLAB
<a href="#">LM2831ZSD/NOPB</a>	Active	Production	WSON (NGG)   6	1000   SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L195B
LM2831ZSD/NOPB.A	Active	Production	WSON (NGG)   6	1000   SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L195B

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM2831XMF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2831XMF/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2831XSD/NOPB	WSO	NGG	6	1000	177.8	12.4	3.3	3.3	1.0	8.0	12.0	Q1
LM2831XSD/NOPB	WSO	NGG	6	4500	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q1
LM2831YMF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2831YMF/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2831YSD/NOPB	WSO	NGG	6	1000	177.8	12.4	3.3	3.3	1.0	8.0	12.0	Q1
LM2831ZMF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2831ZSD/NOPB	WSO	NGG	6	1000	177.8	12.4	3.3	3.3	1.0	8.0	12.0	Q1

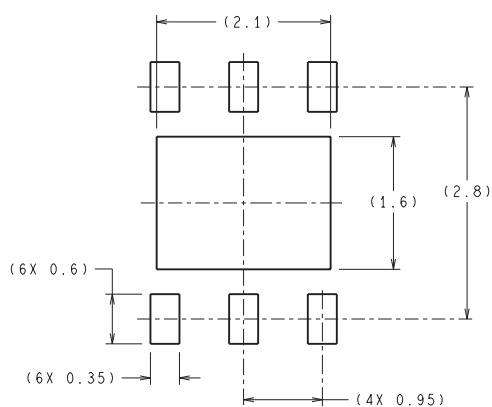
## TAPE AND REEL BOX DIMENSIONS



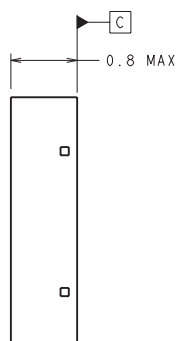
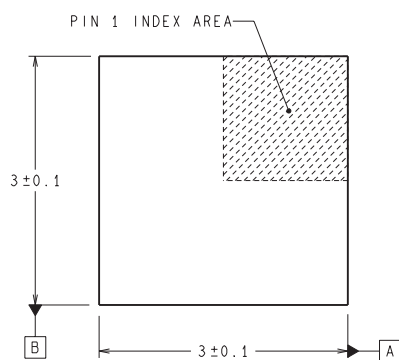
\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM2831XMF/NOPB	SOT-23	DBV	5	1000	210.0	185.0	35.0
LM2831XMF/NOPB	SOT-23	DBV	5	3000	210.0	185.0	35.0
LM2831XSD/NOPB	WSON	NGG	6	1000	208.0	191.0	35.0
LM2831XSDX/NOPB	WSON	NGG	6	4500	356.0	356.0	36.0
LM2831YMF/NOPB	SOT-23	DBV	5	1000	210.0	185.0	35.0
LM2831YMF/NOPB	SOT-23	DBV	5	3000	210.0	185.0	35.0
LM2831YSD/NOPB	WSON	NGG	6	1000	208.0	191.0	35.0
LM2831ZMF/NOPB	SOT-23	DBV	5	1000	210.0	185.0	35.0
LM2831ZSD/NOPB	WSON	NGG	6	1000	208.0	191.0	35.0

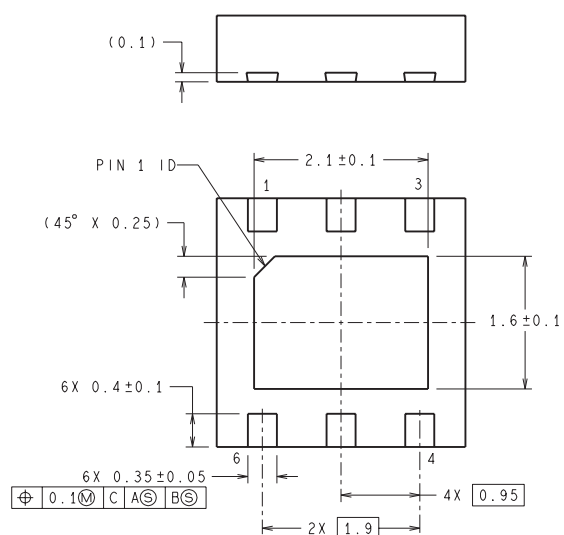
NGG0006A



RECOMMENDED LAND PATTERN



DIMENSIONS ARE IN MILLIMETERS  
DIMENSION IN ( ) FOR REFERENCE ONLY



SDE06A (Rev A)

**DBV0005A****PACKAGE OUTLINE****SOT-23 - 1.45 mm max height**

SMALL OUTLINE TRANSISTOR

**NOTES:**

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Reference JEDEC MO-178.
4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
5. Support pin may differ or may not be present.

# EXAMPLE BOARD LAYOUT

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:15X



SOLDER MASK DETAILS

4214839/K 08/2024

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

## EXAMPLE STENCIL DESIGN

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE:15X

4214839/K 08/2024

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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Last updated 10/2025