1 Features

- AEC-Q100-qualified for automotive applications
  - Device temperature grade 1: –40°C to +125°C, ambient temperature range
- Functional Safety-Capable
  - Documentation available to aid functional safety system design
- Designed for reliable and rugged applications
  - Wide input voltage range of 6 V to 100 V
  - –40°C to +150°C junction temperature range
  - Fixed 3.5-ms internal soft-start timer
  - Peak current-limit protection
  - Input UVLO and thermal shutdown protection
- Optimized for ultra-low EMI requirements
  - Meets CISPR 25 class 5 standard
- Suited for scalable automotive power supplies
  - Pin-to-pin compatible with the LM5163-Q1 and LM5164-Q1 (100 V, 0.5 A, or 1 A)
  - 50-ns low minimum on times and off times
  - 10-µA no-load sleep current
  - 3.1-µA shutdown quiescent current
- Integration reduces solution size and cost
  - COT mode control architecture
  - Integrated 100-V, 0.25-Ω power MOSFET
  - 1.2-V internal voltage reference
  - No loop compensation components
  - Internal VCC bias regulator and bootstrap diode
- Create a custom regulator design with the LM5013-Q1 using WEBENCH® Power Designer

2 Applications

- Hybrid, electric, and powertrain systems
- Inverter and motor control
- Industrial transport

3 Description

The LM5013-Q1 non-synchronous buck converter is designed to regulate over a wide input voltage range, minimizing the need for external surge suppression components. A minimum controllable on time of 50 ns facilitates large step-down conversion ratios, enabling the direct step-down from a 48-V nominal input to low-voltage rails for reduced system complexity and solution cost. The LM5013-Q1 operates during input voltage dips as low as 6 V, at nearly 100% duty cycle if needed, making it an excellent choice for high-performance 48-V battery automotive applications and MHEV/EV systems.

With integrated high-side power MOSFET, the LM5013-Q1 delivers up to 3.5 A of output current. A constant on-time (COT) control architecture provides nearly constant switching frequency with excellent load and line transient response. Additional features of the LM5013-Q1 include ultra-low I_Q operation for high light-load efficiency, innovative peak overcurrent protection, integrated VCC bias supply and bootstrap diode, precision enable and input UVLO, and thermal shutdown protection with automatic recovery. An open-drain PGOOD indicator provides sequencing, fault reporting, and output voltage monitoring.

The LM5013-Q1 is qualified to automotive AEC-Q100 grade 1 and is available in a 8-pin SO PowerPAD™ package. The 1.27-mm pin pitch provides adequate spacing for high-voltage applications.

Device Information

<table>
<thead>
<tr>
<th>PART NUMBER</th>
<th>PACKAGE(1)</th>
<th>BODY SIZE (NOM)</th>
</tr>
</thead>
<tbody>
<tr>
<td>LM5013-Q1</td>
<td>SO PowerPAD (8)</td>
<td>4.89 mm × 3.90 mm</td>
</tr>
</tbody>
</table>

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Typical Application

Typical Application Efficiency, V_{OUT} = 12 V
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4 Revision History

<table>
<thead>
<tr>
<th>DATE</th>
<th>REVISION</th>
<th>NOTES</th>
</tr>
</thead>
<tbody>
<tr>
<td>April 2022</td>
<td>*</td>
<td>Initial release</td>
</tr>
</tbody>
</table>
5 Pin Configuration and Functions

![Diagram of 8-Pin SO PowerPAD DDA Package (Top View)]

Table 5-1. Pin Functions

<table>
<thead>
<tr>
<th>Pin</th>
<th>Type(1)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>GND</td>
<td>G</td>
<td>Ground connection for internal circuits</td>
</tr>
<tr>
<td>VIN</td>
<td>P/I</td>
<td>Regulator supply input pin to high-side power MOSFET and internal bias regulator. Connect directly to the input supply of the buck converter with short, low impedance paths.</td>
</tr>
<tr>
<td>EN/UVLO</td>
<td>I</td>
<td>Precision enable and undervoltage lockout (UVLO) programming pin. If the EN/UVLO voltage is below 1.1 V, the converter is in shutdown mode with all functions disabled. If the UVLO voltage is greater than 1.1 V and below 1.5 V, the converter is in standby mode with the internal VCC regulator operational and no switching. If the EN/UVLO voltage is above 1.5 V, the start-up sequence begins.</td>
</tr>
<tr>
<td>RON</td>
<td>I</td>
<td>On-time programming pin. A resistor between this pin and GND sets the buck switch on time.</td>
</tr>
<tr>
<td>FB</td>
<td>I</td>
<td>Feedback input of voltage regulation comparator</td>
</tr>
<tr>
<td>PGOOD</td>
<td>O</td>
<td>Power-good indicator. This pin is an open-drain output pin. Connect to a source voltage through an external pullup resistor between 10 kΩ to 100 kΩ.</td>
</tr>
<tr>
<td>BST</td>
<td>P/I</td>
<td>Bootstrap gate-drive supply. Required to connect a high-quality 2.2-nF, 50-V X7R ceramic capacitor between BST and SW to bias the internal high-side gate driver.</td>
</tr>
<tr>
<td>SW</td>
<td>P</td>
<td>Switching node that is internally connected to the source of the high-side NMOS buck switch. Connect to the switching node of the power inductor and schottky diode.</td>
</tr>
<tr>
<td>EP</td>
<td>—</td>
<td>Exposed pad of the package. No internal electrical connection. Connect the EP to the GND pin and connect to a large copper plane to reduce thermal resistance.</td>
</tr>
</tbody>
</table>

(1) G = Ground, I = Input, O = Output, P = Power
# 6 Specifications

## 6.1 Absolute Maximum Ratings

Over operating junction temperature range (unless otherwise noted) \(^{(1)}\)

<table>
<thead>
<tr>
<th>Pin voltage</th>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>VIN to GND</td>
<td>–0.3</td>
<td>100</td>
<td>V</td>
</tr>
<tr>
<td>SW to GND</td>
<td>–1.5</td>
<td>100</td>
<td>V</td>
</tr>
<tr>
<td>SW to GND, &lt;20-ns transient</td>
<td>–3</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BST to GND</td>
<td>–3</td>
<td>105.5</td>
<td>V</td>
</tr>
<tr>
<td>BST to SW</td>
<td>–0.3</td>
<td>5.5</td>
<td>V</td>
</tr>
<tr>
<td>EN/UVLO to GND</td>
<td>–0.3</td>
<td>100</td>
<td>V</td>
</tr>
<tr>
<td>FB, RON to GND</td>
<td>–0.3</td>
<td>5.5</td>
<td>V</td>
</tr>
<tr>
<td>PGOOD to GND</td>
<td>–0.3</td>
<td>14</td>
<td>V</td>
</tr>
</tbody>
</table>

**Bootstrap capacitor**

| External BST to SW capacitor | 1.5 | 2.5 | nF |

**Operating junction temperature**

| \(T_J\) | –40 | 150 | °C |

**Storage temperature**

| \(T_{stg}\) | –65 | 150 | °C |

(1) Operation outside the **Absolute Maximum Ratings** may cause permanent damage to the device. **Absolute Maximum Ratings** do not imply functional operation of the device at these or any other conditions beyond those listed under **Recommended Operating Conditions**. If used outside the **Recommended Operating Conditions** but within the **Absolute Maximum Ratings**, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

## 6.2 ESD Ratings

<table>
<thead>
<tr>
<th>(V_{(ESD)})</th>
<th>Electrostatic discharge</th>
<th>VALUE</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Human body model (HBM), per AEC-Q100-002 (^{(1)})</td>
<td>(\pm2000)</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>HBM ESD Classification Level 2</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Charge device model (CDM), per AEC-Q100-011, CDM ESD Classification Level C4B</td>
<td>All pins</td>
<td>(\pm500)</td>
<td>V</td>
</tr>
<tr>
<td>Corner pins</td>
<td>(\pm750)</td>
<td>V</td>
<td></td>
</tr>
</tbody>
</table>

(1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification

## 6.3 Recommended Operating Conditions

Over the operating junction temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>(V_{IN})</th>
<th>Input voltage voltage range</th>
<th>MIN</th>
<th>NOM</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pin voltage</td>
<td>SW to GND</td>
<td>–0.3</td>
<td>100</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Pin voltage</td>
<td>BST to GND</td>
<td>–0.3</td>
<td>105.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Pin voltage</td>
<td>BST to SW</td>
<td>–0.3</td>
<td>5.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Pin voltage</td>
<td>FB, RON to GND</td>
<td>–0.3</td>
<td>5.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Pin voltage</td>
<td>EN/UVLO to GND</td>
<td>–0.3</td>
<td>100</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>PGOOD to GND</td>
<td></td>
<td>–0.3</td>
<td>14</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>(I_{OUT})</td>
<td>Output current range</td>
<td>3.0</td>
<td>3.5</td>
<td>A</td>
<td></td>
</tr>
<tr>
<td>(F_{SW})</td>
<td></td>
<td>3.0</td>
<td>3.5</td>
<td>kHz</td>
<td></td>
</tr>
<tr>
<td>(I_{ON})</td>
<td>Programmable on time</td>
<td>50</td>
<td>1000</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>(C_{BST})</td>
<td>External BST to SW capacitance</td>
<td>2.2</td>
<td>nF</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(T_J)</td>
<td>Operating junction temperature</td>
<td>–40</td>
<td>150</td>
<td>°C</td>
<td></td>
</tr>
</tbody>
</table>
6.4 Thermal Information

<table>
<thead>
<tr>
<th>THERMAL METRIC(1)</th>
<th>DDA (SOIC)</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>RθJA</td>
<td>Junction-to-ambient thermal resistance (LM5013-Q1 EVM)</td>
<td>29.0</td>
</tr>
<tr>
<td>RθJA</td>
<td>Junction-to-ambient thermal resistance</td>
<td>34.8</td>
</tr>
<tr>
<td>RθJC(top)</td>
<td>Junction-to-case (top) thermal resistance</td>
<td>22.8</td>
</tr>
<tr>
<td>RθJB</td>
<td>Junction-to-board thermal resistance</td>
<td>9.5</td>
</tr>
<tr>
<td>RθJC(bot)</td>
<td>Junction-to-case (bottom) thermal resistance</td>
<td>1.3</td>
</tr>
<tr>
<td>ΨJB</td>
<td>Junction-to-board characterization parameter</td>
<td>9.4</td>
</tr>
<tr>
<td>ΨJT</td>
<td>Junction-to-top characterization parameter</td>
<td>0.3</td>
</tr>
</tbody>
</table>

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

6.5 Electrical Characteristics

T<sub>J</sub> = –40°C to +150°C, V<sub>IN</sub> = 24 V. Typical values are at T<sub>J</sub> = 25°C and V<sub>EN/UVLO</sub> = 2 V (unless otherwise noted).

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>I&lt;sub&gt;Q-SHUTDOWN&lt;/sub&gt;</td>
<td>VIN shutdown current</td>
<td>3.1</td>
<td>9.9</td>
<td>µA</td>
<td></td>
</tr>
<tr>
<td>I&lt;sub&gt;Q-SLEEP&lt;/sub&gt;</td>
<td>VIN sleep current</td>
<td>10</td>
<td>20</td>
<td>µA</td>
<td></td>
</tr>
<tr>
<td>I&lt;sub&gt;Q-STANDBY&lt;/sub&gt;</td>
<td>VIN standby current</td>
<td>25</td>
<td>40</td>
<td>µA</td>
<td></td>
</tr>
<tr>
<td>I&lt;sub&gt;Q-ACTIVE&lt;/sub&gt;</td>
<td>VIN active current</td>
<td>450</td>
<td></td>
<td>µA</td>
<td></td>
</tr>
<tr>
<td>V&lt;sub&gt;G&lt;/sub&gt;-RISING</td>
<td>Shutdown threshold</td>
<td>1.1</td>
<td></td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>V&lt;sub&gt;G&lt;/sub&gt;-FALLING</td>
<td>Shutdown threshold</td>
<td>0.45</td>
<td></td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>V&lt;sub&gt;EN&lt;/sub&gt;-RISING</td>
<td>EN threshold</td>
<td>1.43</td>
<td>1.5</td>
<td>1.6</td>
<td>V</td>
</tr>
<tr>
<td>V&lt;sub&gt;EN&lt;/sub&gt;-FALLING</td>
<td>EN threshold</td>
<td>1.35</td>
<td>1.4</td>
<td>1.47</td>
<td>V</td>
</tr>
<tr>
<td>V&lt;sub&gt;REF&lt;/sub&gt;</td>
<td>FB regulation voltage</td>
<td>1.181</td>
<td>1.2</td>
<td>1.218</td>
<td>V</td>
</tr>
<tr>
<td>I&lt;sub&gt;ON1&lt;/sub&gt;</td>
<td>On time1</td>
<td>2550</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>I&lt;sub&gt;ON2&lt;/sub&gt;</td>
<td>On time2</td>
<td>830</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>I&lt;sub&gt;ON3&lt;/sub&gt;</td>
<td>On time3</td>
<td>625</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>I&lt;sub&gt;ON4&lt;/sub&gt;</td>
<td>On time4</td>
<td>245</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>I&lt;sub&gt;ON5&lt;/sub&gt;</td>
<td>On time5</td>
<td>330</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>I&lt;sub&gt;ON6&lt;/sub&gt;</td>
<td>On time6</td>
<td>128</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>V&lt;sub&gt;FB&lt;/sub&gt;-LTH</td>
<td>FB upper threshold for PGOOD high to low</td>
<td>1.1</td>
<td>1.14</td>
<td>1.2</td>
<td>V</td>
</tr>
<tr>
<td>V&lt;sub&gt;FB&lt;/sub&gt;-HTH</td>
<td>FB lower threshold for PGOOD high to low</td>
<td>1.05</td>
<td>1.08</td>
<td>1.12</td>
<td>V</td>
</tr>
<tr>
<td>V&lt;sub&gt;FB&lt;/sub&gt;-HYS</td>
<td>PGOOD upper and lower threshold hysteresis</td>
<td>60</td>
<td></td>
<td>mV</td>
<td></td>
</tr>
<tr>
<td>R&lt;sub&gt;P&lt;/sub&gt;</td>
<td>PGOOD pulldown resistance</td>
<td>8</td>
<td></td>
<td>Ω</td>
<td></td>
</tr>
<tr>
<td>V&lt;sub&gt;BST-UV&lt;/sub&gt;</td>
<td>Gate drive UVLO</td>
<td>2.4</td>
<td>3.4</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>R&lt;sub&gt;DSON-HS&lt;/sub&gt;</td>
<td>High-side MOSFET R&lt;sub&gt;DSON&lt;/sub&gt;</td>
<td>0.25</td>
<td></td>
<td>Ω</td>
<td></td>
</tr>
<tr>
<td>I&lt;sub&gt;SS&lt;/sub&gt;</td>
<td>Internal soft start</td>
<td>1.75</td>
<td>3.5</td>
<td>4.75</td>
<td>ms</td>
</tr>
<tr>
<td>I&lt;sub&gt;PEAK&lt;/sub&gt;</td>
<td>Peak current limit threshold</td>
<td>3.7</td>
<td>4.2</td>
<td>5</td>
<td>A</td>
</tr>
</tbody>
</table>
### 6.5 Electrical Characteristics (continued)

$T_J = -40^\circ C$ to $+150^\circ C$, $V_{IN} = 24$ V. Typical values are at $T_J = 25^\circ C$ and $V_{EN/UVLO} = 2$ V (unless otherwise noted).

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$T_{J-SD}$</td>
<td>Thermal shutdown threshold (1)</td>
<td></td>
<td></td>
<td>175</td>
<td>°C</td>
</tr>
<tr>
<td>$T_{J-HYS}$</td>
<td>Thermal shutdown hysteresis (1)</td>
<td></td>
<td></td>
<td>10</td>
<td>°C</td>
</tr>
</tbody>
</table>

(1) Specified by design, not product tested
6.6 Typical Characteristics

At $T_A = 25^\circ$C, $V_{OUT} = 12$ V, $L_O = 33$ $\mu$H, $R_{RON} = 105$ k$\Omega$, unless otherwise specified.
6.6 Typical Characteristics (continued)

At $T_A = 25^\circ C$, $V_{OUT} = 12$ V, $L_O = 33 \, \mu H$, $R_{RON} = 105 \, k\Omega$, unless otherwise specified.

![Figure 6-7. Peak Current Limit Versus Temperature](image1)

![Figure 6-8. COT On Time Versus $V_{IN}$](image2)
7 Detailed Description

7.1 Overview

The LM5013-Q1 is an easy-to-use, ultra-low IQ constant on-time (COT) non-synchronous step-down buck regulator. With an integrated high-side power MOSFET, the LM5013-Q1 is a low-cost, highly efficient buck converter that operates from a wide input voltage of 6 V to 100 V, delivering up to 3.5-A DC load current. The LM5013-Q1 is available in an 8-pin SO PowerPAD package with 1.27-mm pin pitch for adequate spacing in high-voltage applications. This constant on-time (COT) converter is ideal for low-noise, high-current, and fast load transient requirements, operating with a predictive on-time switching pulse. Over the input voltage range, input voltage feedforward is employed to achieve a quasi-fixed switching frequency. A controllable on time as low as 50 ns permits high step-down ratios and a minimum forced off time of 50 ns provides extremely high duty cycles, allowing VIN to drop close to VOUT before frequency foldback occurs. At light loads, the device transitions into an ultra-low IQ mode to maintain high efficiency and prevent draining battery cells connected to the input when the system is in standby. The LM5013-Q1 implements a peak current limit detection circuit to ensure robust protection during output short circuit conditions. Control loop compensation is not required for this regulator, reducing design time and external component count.

The LM5013-Q1 incorporates additional features for comprehensive system requirements:

- Power-rail sequencing and fault reporting
- Internally-fixed soft start
- Open-drain power good
- Monotonic start-up into prebiased loads
- Precision enable for programmable line undervoltage lockout (UVLO)
- Smart cycle-by-cycle current limit for optimal inductor sizing
- Thermal shutdown with automatic recovery

These features enable a flexible and easy-to-use platform for a wide range of applications. The LM5013-Q1 supports a wide range of end-equipment systems requiring a regulated output from a high input supply where the transient voltage deviates from the DC level. The following are examples of such end equipment systems:

- 48-V automotive systems
- High cell-count battery-pack systems
- Hybrid, electric, and powertrain systems
- Inverter and motor control

The pin arrangement is designed for a simple layout requiring only a few external components.
7.3 Feature Description

7.3.1 Control Architecture

The LM5013-Q1 step-down switching converter employs a constant on-time (COT) control scheme. The COT control scheme sets a fixed on time, $t_{ON}$, of the high-side FET using a timing resistor ($R_{ON}$). $t_{ON}$ is adjusted as $V_{IN}$ changes and is inversely proportional to the input voltage to maintain a fixed frequency when in continuous conduction mode (CCM). After $t_{ON}$ expires, the high-side FET remains off until the feedback pin is equal or below the 1.2-V reference voltage. To maintain stability, the feedback comparator requires a minimal ripple voltage that is in-phase with the inductor current during the off time. Furthermore, this change in feedback voltage during the off time must be large enough to dominate any noise present at the feedback node. The minimum recommended ripple voltage is 20 mV. See Table 7-1 for different types of ripple injection schemes that ensure stability over the full input voltage range.

During a rapid start-up or a positive load step, the regulator operates with minimum off times until regulation is achieved. This feature enables extremely fast load transient response with minimum output voltage undershoot. When regulating the output in steady-state operation, the off time automatically adjusts itself to produce the SW-pin duty cycle required for output voltage regulation to maintain a fixed switching frequency. In CCM, the switching frequency, $F_{SW}$, is programmed by the $R_{RON}$ resistor. Use Equation 1 to calculate the switching frequency.
\[ F_{SW} \text{ (kHz)} = \frac{V_{OUT} \cdot 2500}{R_{RON} \text{ (kΩ)}} \]  

Table 7-1. Ripple Generation Methods

<table>
<thead>
<tr>
<th>Type 1</th>
<th>Type 2</th>
<th>Type 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lowest Cost</td>
<td>Reduced Ripple</td>
<td>Minimum Ripple</td>
</tr>
</tbody>
</table>

Table 7-1 presents three different methods for generating appropriate voltage ripple at the feedback node. Type-1 ripple generation method uses a single resistor, \( R_{ESR} \), in series with the output capacitor. The generated voltage ripple has two components: capacitive ripple caused by the inductor ripple current charging and discharging the output capacitor and resistive ripple caused by the inductor ripple current flowing into the output capacitor and through series resistance, \( R_{ESR} \). The capacitive ripple component is out-of-phase with the inductor current and does not decrease monotonically during the off time. The resistive ripple component is in-phase with the inductor current and decreases monotonically during the off time. The resistive ripple must exceed the capacitive ripple at \( V_{OUT} \) for stable operation. If this condition is not satisfied, unstable switching behavior is observed in COT converters with multiple on-time bursts in close succession followed by a long off time. The lowest cost equations define the value of the series resistance \( R_{ESR} \) to ensure sufficient in-phase ripple at the feedback node.

Type-2 ripple generation uses a \( C_{FF} \) capacitor in addition to the series resistor. As the output voltage ripple is directly AC-coupled by \( C_{FF} \) to the feedback node, the \( R_{ESR} \) and ultimately the output voltage ripple, are reduced by a factor of \( V_{OUT} / V_{FB1} \).

Type-3 ripple generation uses an RC network consisting of \( R_A \) and \( C_A \), and the switch node voltage to generate a triangular ramp that is in-phase with the inductor current. This triangular wave is the AC-coupled into the feedback node with capacitor \( C_B \). Because this circuit does not use output voltage ripple, it is suited for applications where low output voltage ripple is critical. The AN-1481 Controlling Output Ripple and Achieving ESR Independence in Constant On-time (COT) Regulator Designs Application Note provides additional details on this topic.

Note

For all methods specified, 12 mV is the minimum FB ripple voltage. 20 mV is calculated as a conservative figure. For wide-\( V_{IN} \) ranges, calculating for 20 mV can be insufficient to achieve 12-mV FB ripple at minimum input voltage. Careful evaluation should be done to ensure the minimum ripple requirement is fulfilled, or the design can be faced with large output ripple/irregular switching at the application minimum output voltage.

7.3.2 Internal VCC Regulator and Bootstrap Capacitor

The LM5013-Q1 contains an internal linear regulator that is powered from \( V_{IN} \) with a nominal output of 5 V, eliminating the need for an external capacitor to stabilize the linear regulator. The internal VCC regulator supplies current to internal circuit blocks including the asynchronous FET driver and logic circuits. The input pin (\( V_{IN} \)) can be connected directly to line voltages up to 100 V. As the power MOSFET has a low total gate charge, use a low bootstrap capacitor value to reduce the stress on the internal regulator. It is required to select a
An applicative value of 2.2-nF, 50-V X7R as specified in the *Absolute Maximum Ratings*. VCC does not have current limit protection, so selecting a higher value capacitance stresses the internal VCC regulator and can damage the device. A lower capacitance than required is not sufficient to drive the internal gate of the power MOSFET. An internal diode connects from the VCC regulator to the BST pin to replenish the charge in the high-side gate drive bootstrap capacitor when the SW voltage is low.

### 7.3.3 Regulation Comparator

The feedback voltage at FB is compared to an internal 1.2-V reference. The LM5013-Q1 voltage regulation loop regulates the output voltage by maintaining the FB voltage equal to the internal reference voltage, $V_{REF}$. A resistor divider programs the ratio from output voltage, $V_{OUT}$, to FB.

For a target $V_{OUT}$ setpoint, use Equation 2 to calculate $R_{FB2}$ based on the selected $R_{FB1}$.

$$R_{FB2} = \frac{1.2V}{V_{OUT} - 1.2V} \cdot R_{FB1}$$

TI recommends selecting $R_{FB1}$ in the range of 100 kΩ to 1 MΩ for most applications. A larger $R_{FB1}$ consumes less DC current, which is mandatory if light-load efficiency is critical. $R_{FB1}$ larger than 1 MΩ is not recommended as the feedback path becomes more susceptible to noise. It is important to route the feedback trace away from the noisy area of the PCB and minimize the feedback node size. It is important to route the feedback trace away from the noisy areas of the PCB and minimize the feedback node size. FB resistors, type 3 ripple injection resistors, or both should be kept close to the device pin.

### 7.3.4 Internal Soft Start

The LM5013-Q1 employs an internal soft-start control ramp that allows the output voltage to gradually reach a steady-state operating point, thereby reducing start-up stresses and current surges. The soft-start feature produces a controlled, monotonic output voltage start-up. The soft-start time is internally set to 3.5 ms.

### 7.3.5 On-Time Generator

The on time of the LM5013-Q1 high-side FET is determined by the $R_{RON}$ resistor and is inversely proportional to the input voltage, $V_{IN}$. The inverse relationship with $V_{IN}$ results in a nearly constant frequency as $V_{IN}$ is varied. Use Equation 3 to calculate the on time.

$$t_{ON} (\mu s) = \frac{R_{RON} (k\Omega)}{V_{IN} (V) \cdot 2.5}$$

Use Equation 4 to determine the $R_{RON}$ resistor to set a specific switching frequency in CCM.

$$R_{RON} (k\Omega) = \frac{V_{OUT} (V) \cdot 2500}{F_{SW} (kHz)}$$

Select $R_{RON}$ for a minimum on time (at maximum $V_{IN}$) greater than 50 ns for proper operation. In addition to this minimum on time, the maximum frequency for this device is limited to 1 MHz.

### 7.3.6 Current Limit

The LM5013-Q1 manages overcurrent conditions with cycle-by-cycle current limiting of the peak inductor current. The current sensed in the high-side MOSFET is compared every switching cycle to the current limit threshold (4.5 A). There is a 100-ns leading-edge blanking time following the high-side MOSFET turn-on transition to eliminate false tripping off the current limit comparator. To protect the converter from potential current runaway conditions, the LM5013-Q1 includes a $t_{OFF}$ timer that is proportional to $V_{IN}$ and $V_{OUT}$ that is enabled if a 4.5-A peak current limit is detected. As shown in Figure 7-1, if the peak current in the high-side MOSFET exceeds 4.5 A (typical), the present cycle is immediately terminated regardless of the programmed on time ($t_{ON}$), the high-side MOSFET is turned off and the $t_{OFF}$ timer is activated. This allows the peak inductor...
current to fall from 4.5-A peak to an acceptable value to ensure no excessive current in the power stage. This method folds back the switching frequency to prevent overheating and limits the average output current to less than 4.5 A to ensure proper short-circuit and heavy-load protection of the LM5013-Q1. This innovative current limit scheme enables ultra-low duty-cycle operation, permitting large step-down voltage conversions while ensuring robust protection of the converter.

![Current Limit Timing Diagram](image)

**Figure 7-1. Current Limit Timing Diagram**

### 7.3.7 N-Channel Buck Switch and Driver

The LM5013-Q1 integrates an N-channel buck switch and an associated floating high-side gate driver. The gate-driver circuit works in conjunction with an external bootstrap capacitor and an internal high-voltage bootstrap diode. A high-quality 2.2-nF, 50-V X7R ceramic capacitor connected between the BST and SW pins provides the voltage to the high-side driver during the buck switch on time. During the off time, the SW pin is pulled down to approximately 0 V, and the bootstrap capacitor charges from the internal VCC through the internal bootstrap diode. The minimum off timer, set to 50 ns (typical), ensures a minimum time each cycle to recharge the bootstrap capacitor. When the on time is less than 300 ns, the minimum off timer is forced to 250 ns to ensure that the BST capacitor is charged in a single cycle. This is vital during wake-up from sleep mode when the BST capacitor is most likely discharged.

### 7.3.8 Schottky Diode Selection

A Schottky diode is required for all LM5013-Q1 applications to re-circulate the energy in the output inductor when the high-side MOSFET is off. The reverse breakdown rating of the diode should be greater than the maximum $V_{IN}$ plus a 25% safety margin, as specified in Section 8. The current rating of the diode should exceed the maximum DC output current and support the peak current limit (IPEAK current limit) for the best reliability. In this case, the diode will carry the maximum load current.

### 7.3.9 Enable/Undervoltage Lockout (EN/UVLO)

The LM5013-Q1 contains a dual-level EN/UVLO circuit. When the EN/UVLO voltage is below 1.1 V (typical), the converter is in a low-current shutdown mode and the input quiescent current ($I_Q$) is dropped down to 3 µA. When the voltage is greater than 1.1 V but less than 1.5 V (typical), the converter is in standby mode. In standby mode, the internal bias regulator is active while the control circuit is disabled. When the voltage exceeds the rising threshold of 1.5 V (typical), normal operation begins. Install a resistor divider from VIN to GND to set the minimum operating voltage of the regulator. Use Equation 5 and Equation 6 to calculate the input UVLO turn-on and turn-off voltages, respectively.

$$V_{IN(on)} = 1.5V \cdot \left(1 + \frac{R_{UV1}}{R_{UV2}}\right)$$  \hspace{1cm} (5)
\[ V_{\text{IN(off)}} = 1.4 \, V \cdot \left(1 + \frac{R_{\text{UV1}}}{R_{\text{UV2}}}ight) \]  

(6)

TI recommends selecting \( R_{\text{UV1}} \) in the range of no more than 1 M\( \Omega \) for most applications. A larger \( R_{\text{UV1}} \) consumes less DC current, which is mandatory if light-load efficiency is critical. If input UVLO is not required, the power-supply designer can either drive EN/UVLO as an enable input driven by a logic signal or connect it directly to VIN. If EN/UVLO is directly connected to VIN, the regulator begins switching as soon as the internal bias rails are active.

### 7.3.10 Power Good (PGOOD)

The LM5013-Q1 provides a PGOOD flag pin to indicate when the output voltage is within the regulation level. Use the PGOOD signal for start-up sequencing of downstream converters or for fault protection and output monitoring. PGOOD is an open-drain output that requires a pullup resistor to a DC supply not greater than 14 V. The typical range of pullup resistance is 10 k\( \Omega \) to 100 k\( \Omega \). If necessary, use a resistor divider to decrease the voltage from a higher voltage pullup rail. When the FB voltage exceeds 95% of the internal reference, \( V_{\text{REF}} \), the internal PGOOD switch turns off and PGOOD can be pulled high by the external pullup. If the FB voltage falls below 90% of \( V_{\text{REF}} \), an internal 8-\( \Omega \) PGOOD switch turns on and PGOOD is pulled low to indicate that the output voltage is out of regulation. The rising edge of PGOOD has a built-in deglitch delay of 5 \( \mu \)s.

### 7.3.11 Thermal Protection

The LM5013-Q1 includes an internal junction temperature monitor to protect the device in the event of a higher than normal junction temperature. If the junction temperature exceeds 175°C (typical), thermal shutdown occurs to prevent further power dissipation and temperature rise. The LM5013-Q1 initiates a restart sequence when the junction temperature falls to 165°C, based on a typical thermal shutdown hysteresis of 10°C. This is a non-latching protection, so the device cycles into and out of thermal shutdown if the fault persists.
7.4 Device Functional Modes

7.4.1 Shutdown Mode

EN/UVLO provides ON and OFF control for the LM5013-Q1. When $V_{\text{EN/UVLO}}$ is below approximately 1.1 V, the device is in shutdown mode. Both the internal linear regulator and the switching regulator are off. The quiescent current in shutdown mode drops to 3 µA at $V_{\text{IN}} = 24$ V. The LM5013-Q1 also employs internal bias rail undervoltage protection. If the internal bias supply voltage is below the UV threshold, the regulator remains off.

7.4.2 Standby Mode

The LM5013-Q1 enters standby mode during light or no-load on the output. The LM5013-Q1 enters standby mode to prevent draining the input power supply. All internal controller circuits are turned off to reduce the current consumption. The quiescent current in standby mode is 25 µA (typical).

7.4.3 Active Mode

The LM5013-Q1 is in active mode when $V_{\text{EN/UVLO}}$ is above the precision enable threshold and the internal bias rail is above its UV threshold. In COT active mode, the LM5013-Q1 is in one of three modes depending on the load current:

- CCM with fixed switching frequency when load current is above half of the peak-to-peak inductor current ripple
- The LM5013-Q1 will enter discontinuous conduction mode when the load current is less than half of the peak-to-peak inductor current ripple in CCM operation.
- Current limit CCM with peak current limit protection when an overcurrent condition is applied at the output

7.4.4 Sleep Mode

During discontinuous conduction mode, the load current is lower than half of the peak-to-peak inductor current ripple and the switching frequency decreases when the load is further decreased in pulse skipping mode. A switching pulse is set when $V_{\text{FB}}$ drops below 1.2 V.

As the frequency of operation decreases and $V_{\text{FB}}$ remains above 1.2 V ($V_{\text{REF}}$) with the output capacitor sourcing the load current for greater than 15 µs, the converter enters an ultra-low $I_0$ sleep mode to prevent draining the input power supply. The input quiescent current ($I_0$) required by the LM5013-Q1 decreases to 10 µA in sleep mode, improving the light-load efficiency of the regulator. In this mode, all internal controller circuits are turned off to ensure very low current consumption by the device. Such low $I_0$ renders the LM5013-Q1 as the best option to extend operating lifetime for off-battery applications. The FB comparator and internal bias rail are active to detect when the FB voltage drops below the internal reference, $V_{\text{REF}}$, and the converter transitions out of sleep mode into active mode. There is a 9-µs wake-up delay from sleep to active states.
8 Application and Implementation

Note
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI’s customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information
The LM5013-Q1 requires only a few external components to step down from a wide range of supply voltages to a fixed output voltage. Several features are integrated to meet system design requirements, including the following:
• Precision enable
• Input voltage UVLO
• Internal soft start
• Programmable switching frequency
• A PGOOD indicator

To expedite the process of designing with LM5013-Q1, a LM5013-Q1 design calculator is available on the product folder under the Design tools & simulation section. This calculator is complemented by an evaluation module for order, PSPICE models, as well as TI's WEBENCH® Power Designer.

8.2 Typical Application
Figure 8-1 shows the schematic for 48-V to 12-V conversion.

![Typical Application Schematic](image)

**Figure 8-1. Typical Application, V_{IN(nom)} = 48 V, V_{OUT} = 12 V, I_{OUT(max)} = 3.5 A, F_{SW(nom)} = 300 kHz**

Note
This and subsequent design examples are provided herein to showcase the LM5013-Q1 converter in several different applications. Depending on the source impedance of the input supply bus, an electrolytic capacitor can be required at the input to ensure stability, particularly at low input voltage and high output current operating conditions. See the Power Supply Recommendations for more details.
8.2.1 Design Requirements
The target full-load efficiency is 92% based on a nominal input voltage of 48 V and an output voltage of 12 V. The required input voltage range is 15 V to 100 V. The switching frequency is set by resistor \( R_{ON} \) at 300 kHz. The output voltage soft-start time is 3.5 ms. Refer to \textit{LM5013-Q1 EVM User's Guide} for more details on component selection.

8.2.2 Detailed Design Procedure
8.2.2.1 Custom Design With WEBENCH® Tools
Click here to create a custom design using the LM5013-Q1 device with the WEBENCH® Power Designer.

1. Start by entering the input voltage \( V_{IN} \), output voltage \( V_{OUT} \), and output current \( I_{OUT} \) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial. The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:
- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

8.2.2.2 Switching Frequency \( (R_{ON}) \)
The switching frequency of the LM5013-Q1 is set by the on-time programming resistor placed at \( R_{ON} \). As shown by Equation 7, a standard 100-kΩ, 1% resistor sets the switching frequency at 300 kHz.

\[
R_{ON}(k\Omega) = \frac{V_{OUT}(V) \cdot 2500}{F_{SW}(kHz)}
\]

(7)

Note that at very low duty cycles, the 50-ns minimum controllable on time of the high-side MOSFET, \( t_{ON(min)} \), limits the maximum switching frequency. In CCM, \( t_{ON(min)} \) limits the voltage conversion step-down ratio for a given switching frequency. Use Equation 8 to calculate the minimum controllable duty cycle.

\[
D_{MIN} = \frac{t_{ON(min)} \cdot F_{SW}}{1}
\]

(8)

Ultimately, the choice of switching frequency for a given output voltage affects the available input voltage range, solution size, and efficiency. Use Equation 9 to calculate the maximum supply voltage for a given \( t_{ON(min)} \) before switching frequency reduction occurs.

\[
V_{IN(max)} = \frac{V_{OUT}}{t_{ON(min)} \cdot F_{SW}}
\]

(9)

8.2.2.3 Buck Inductor \( (L_O) \)
Use Equation 10 and Equation 11 to calculate the inductor ripple current (assuming CCM operation) and peak inductor current, respectively.

\[
\Delta L = \frac{V_{OUT}}{F_{SW} \cdot L_O} \left(1 - \frac{V_{OUT}}{V_{IN}} \right)
\]

(10)

\[
I_{L(peak)} = \frac{V_{OUT}}{F_{SW} \cdot L_O}
\]
For most applications, choose an inductance such that the inductor ripple current, $\Delta I_L$, is between 30% and 50% of the rated load current at nominal input voltage. Use Equation 12 to calculate the inductance.

\[
L_\text{L(peak)} = L_{\text{OUT(max)}} + \frac{\Delta I_L}{2}
\]  

(11)

For applications in which the device must support input transients exceeding 72 V, it is advised to select the inductor to be at least 22 $\mu$H. This ensures that excessive current rise does not occur in the power stage due to the potential large inductor current slew that could occur in an output short-circuit condition.

Choosing a 22-$\mu$H inductor in this design results in 1.36-A peak-to-peak ripple current at a nominal input voltage of 48 V, equivalent to 39% of the 3.5-A rated load current. For designs that must operate up to the maximum input voltage at the full-rated load current of 3.5 A, the inductance will need to increase to ensure current limit ($I_{\text{PEAK current limit}}$) is not hit.

Check the inductor data sheet to make sure the saturation current of the inductor is well above the current limit setting of the LM5013-Q1. It is recommended that the saturation current be greater than 7 A. Ferrite-core inductors have relatively lower core losses and are preferred at high switching frequencies, but exhibit a hard saturation characteristic — the inductance collapses abruptly when the saturation current is exceeded. This results in an abrupt increase in inductor ripple current, higher output voltage ripple, and reduced efficiency, in turn compromising reliability. Note that inductor saturation current levels generally decrease as the core temperature increases.

8.2.2.4 Schottky Diode ($D_{\text{SW}}$)

The breakdown voltage rating of the diode is preferred to be 25% higher than the maximum input voltage. In the target application, the power rating for the diode should exceed the maximum DC output current and support the peak current limit ($I_{\text{PEAK current limit}}$) for best reliability in most applications.

For example, the LM5013-Q1EVM uses the V8P12-M3/86A Schottky diode. The 120-V breakdown voltage rating and 8-A current rating make sure that the design can support a 100-V input and a short-circuit condition without any reliability concern. Furthermore, being that it is a Schottky diode with a low forward voltage and has small switching losses due to its low junction capacitance, the efficiency figure of the design can be optimized. With what loss does occur in the device, the package of the diode should be selected so it can have good heat conduction out of it into the copper ground plane.

8.2.2.5 Output Capacitor ($C_{\text{OUT}}$)

Select a ceramic output capacitor to limit the capacitive voltage ripple at the converter output. This is the sinusoidal ripple voltage that is generated from the triangular inductor current ripple flowing into and out of the capacitor. Select an output capacitance using Equation 13 to limit the voltage ripple component to 0.5% of the output voltage.

\[
C_{\text{OUT}} \geq \frac{\Delta I_L}{8 \cdot F_{\text{SW}} \cdot V_{\text{OUT(ripple)}}}
\]

(13)

Substituting $\Delta I_L(nom)$ of 1.36 A gives $C_{\text{OUT}}$ greater than 10 $\mu$F. Considering the voltage coefficients of ceramic capacitors, a 22-$\mu$F, 25-V rated capacitor with X7R dielectric is selected.

8.2.2.6 Input Capacitor ($C_{\text{IN}}$)

An input capacitor is necessary to limit the input ripple voltage while providing AC current to the buck power stage at every switching cycle. To minimize the parasitic inductance in the switching loop, position the input
capacitors as close as possible to the VIN and GND pins of the LM5013-Q1. The input capacitors conduct a square-wave current of peak-to-peak amplitude equal to the output current. It follows that the resultant capacitive component of AC ripple voltage is a triangular waveform.

Along with the ESR-related ripple component, use Equation 14 to calculate the peak-to-peak ripple voltage amplitude.

\[ V_{\text{IN(ripple)}} = \frac{I_{\text{OUT}} \cdot D \cdot (1-D)}{F_{\text{SW}} \cdot C_{\text{IN}}} + I_{\text{OUT}} \cdot R_{\text{ESR}} \]  

(14)

Use Equation 15 to calculate the input capacitance required for a load current, based on an input voltage ripple specification (ΔVIN).

\[ C_{\text{IN}} \geq \frac{I_{\text{OUT}} \cdot D \cdot (1-D)}{F_{\text{SW}} \cdot (V_{\text{IN(ripple)}} - I_{\text{OUT}} \cdot R_{\text{ESR}})} \]  

(15)

The recommended high-frequency input capacitance is 4.4 µF or higher. Ensure the input capacitor is a high-quality X7S or X7R ceramic capacitor with sufficient voltage rating for C_{IN}. Based on the voltage coefficient of ceramic capacitors, choose a voltage rating preferably twice the maximum input voltage. Additionally, some bulk capacitance can be required for large input loop inductance or long wire harnesses used in the system. This capacitor provides parallel damping to the resonance associated with parasitic inductance of the supply lines and high-Q ceramics. See the Power Supply Recommendations for more detail.

### 8.2.2.7 Type 3 Ripple Network

A Type 3 ripple generation network uses an RC filter consisting of R_A and C_A across SW and V_{OUT} to generate a triangular ramp that is in-phase with the inductor current. This triangular ramp is then AC-coupled into the feedback node using capacitor C_B as shown in Figure 8-1. Type 3 ripple injection is suited for applications where low output voltage ripple is crucial.

Use Equation 16 and Equation 17 to calculate R_A and C_A to provide the required ripple amplitude at the FB pin.

\[ C_A \geq \frac{10}{F_{SW} \cdot (R_{FB1} || R_{FB2})} \]  

(16)

For the feedback resistors R_{FB1} = 453 kΩ and R_{FB2} = 49.9 kΩ values shown in Figure 8-1, Equation 16 dictates a minimum C_A of 742 pF. In this design, a 3300-pF capacitance is chosen. This is done to keep R_A within practical limits between 100 kΩ and 1 MΩ when using Equation 17.

\[ R_A C_A \geq \frac{(V_{IN(nom)} - V_{OUT}) \cdot t_{ON(nom)}}{20 \text{ mV}} \]  

(17)

Based on C_A set at 3.3 nF, R_A is calculated to be 453 kΩ to provide a 20-mV ripple voltage at FB. The general recommendation for a Type 3 network is to calculate R_A and C_A to get 20 mV of ripple at typical operating conditions. A smaller R_A can be required to operate below nominal 48-V input.

---

**Note**

12 mV of FB ripple or more should be ensured at the minimum input voltage of the design to ensure stability.

While the amplitude of the generated ripple does not affect the output voltage ripple, it impacts the output regulation as it reflects as a DC error of approximately half the amplitude of the generated ripple. For example,
a converter circuit with Type 3 network that generates a 40-mV ripple voltage at the feedback node has approximately 10-mV worse load regulation scaled up through the FB divider to $V_{OUT}$ than the same circuit that generates a 20-mV ripple at FB. Use Equation 18 to calculate the coupling capacitance, $C_B$.

$$C_B \geq \frac{t_{\text{TR-settling}}}{3 \cdot R_{FB1}}$$  \hspace{1cm} (18)

where

- $t_{\text{TR-settling}}$ is the desired load transient response settling time.

$C_B$ calculates to 56 pF based on a 75-µs settling time. This value avoids excessive coupling capacitor discharge by the feedback resistors during sleep intervals when operating at light loads. To avoid capacitance fall-off with DC bias, use a C0G or NP0 dielectric capacitor for $C_B$. 


8.2.3 Application Curves

**Figure 8-2. Conversion Efficiency (Log Scale)**

- $V_{OUT} = 12 \text{ V}$
- $R_{ON} = 102 \text{ kΩ}$
- $L_{O} = 22 \mu\text{H}$

**Figure 8-3. Conversion Efficiency (Linear Scale)**

- $V_{OUT} = 12 \text{ V}$
- $R_{ON} = 102 \text{ kΩ}$
- $L_{O} = 22 \mu\text{H}$

**Figure 8-4. Load and Line Regulation Performance**

- $V_{OUT} = 12 \text{ V}$
- $R_{ON} = 102 \text{ kΩ}$
- $L_{O} = 22 \mu\text{H}$

**Figure 8-5. Load Step Response**

- $V_{IN} = 48 \text{ V}$
- $V_{OUT} = 12 \text{ V}$
- $I_{OUT} = 1.75 \text{ A} \text{ to } 3.5 \text{ A}$
- (Rise/fall time = 1A/μS)

**Figure 8-6. No-Load Start-Up with EN/UVLO**

- $V_{IN} = 48 \text{ V}$
- $V_{OUT} = 12 \text{ V}$
- $I_{OUT} = 0 \text{ A}$

**Figure 8-7. Short Circuit Applied**

- $V_{IN} = 48 \text{ V}$
- $V_{OUT} = 12 \text{ V}$
- Load = 0 A to Short
Figure 8-8. Short Circuit Recovery

Figure 8-9. Light-Load Switching

Figure 8-10. Full-Load Switching

Filter used for EMC scan. Additionally, the regulator was housed in an enclosed shield.

Figure 8-11. Suggested EMC Filter for CISPR 25 Class 5 Compliance

Figure 8-12. CISPR 25 Class 5 Conducted Emissions Plot, 150 kHz to 110 MHz
9 Power Supply Recommendations

The LM5013-Q1 buck converter is designed to operate from a wide input voltage range between 6 V and 100 V. In addition, the input supply must be capable of delivering the required input current to the fully loaded regulator. Use Equation 19 to estimate the average input current.

\[
I_{IN} = \frac{V_{OUT} \cdot I_{OUT}}{V_{IN} \cdot \eta}
\]

where

- \( \eta \) is the efficiency.

If the converter is connected to an input supply through long wires or PCB traces with a large impedance, take special care to achieve stable performance. The parasitic inductance and resistance of the input cables can have an adverse effect on converter operation. The parasitic inductance in combination with the low-ESR ceramic input capacitors form an underdamped resonant circuit. This circuit can cause overvoltage transients at VIN each time the input supply is cycled ON and OFF. The parasitic resistance causes the input voltage to dip during a load transient. If the converter is operating close to the minimum input voltage, this dip can cause false UVLO fault triggering and a system reset, in addition to potential stability issues. The circuit can be damped with a "parallel damping network." For example, a 22-\( \mu \)F damping capacitor in series with a 1.4-\( \Omega \) resistor connected to the VIN node creates a parallel damped network, providing sufficient damping for a 8.2-\( \mu \)F input filter inductor and 4.4-\( \mu \)F ceramic input capacitance. Damping is not only needed for an input EMC filter, but also when the application utilizes a power harness which can present a large input loop inductance. For example, two cables (one for VIN and one for GND), each one meter (approximately three feet) long with approximately 1-mm diameter (18 AWG), placed 1 cm (approximately 0.4 inch) apart, forms a rectangular loop resulting in about 1.2 \( \mu \)H of inductance. The Input Filter Design for Switching Power Supplies Application Report provides more detail on this topic.

An EMI input filter is often used in front of the regulator that, unless carefully designed, can lead to instability as well as some of the effects mentioned above. The Simple Success with Conducted EMI for DC-DC Converters Application Report provides helpful suggestions when designing an input filter for any switching regulator.
10 Layout

10.1 Layout Guidelines

PCB layout is a critical portion of good power supply design. There are several paths that conduct high slew-rate currents or voltages that can interact with stray inductance or parasitic capacitance to generate noise and EMI or degrade the power supply performance.

- To help eliminate these problems, bypass the VIN pin to GND with a low-ESR ceramic bypass capacitor with a high-quality dielectric. Place C\textsubscript{IN} as close as possible to the LM5013-Q1 VIN and GND pins. Grounding for both the input and output capacitors must consist of localized top-side planes that connect to the GND pin and GND PAD.
- Minimize the loop area formed by the input capacitor connections to the VIN and GND pins.
- Locate the inductor and Schottky diode close to the SW pin. Minimize the area of the SW trace or plane to prevent excessive capacitive coupling.
- Place the Schottky diode anode terminal in close proximity to the input capacitor ground/return.
- Tie the GND pin directly to the power pad under the device and to a heat-sinking PCB ground plane.
- Use a ground plane in one of the middle layers as a noise shielding and heat dissipation path.
- Place a single-point ground connection to the plane. Route the ground connections for the feedback, soft start, and enable components to the ground plane. This prevents any switched or load currents from flowing in analog ground traces. If not properly handled, poor grounding results in degraded load regulation or erratic output voltage ripple behavior.
- Make V\textsubscript{IN}, V\textsubscript{OUT}, and ground bus connections as wide as possible. This reduces any voltage drops on the input or output paths of the converter and maximizes efficiency.
- Minimize trace length to the FB pin. Place both feedback resistors, R\textsubscript{FB1} and R\textsubscript{FB2}, close to the FB pin. Place C\textsubscript{FF} (if needed) directly in parallel with R\textsubscript{FB1}. If output setpoint accuracy at the load is important, connect the V\textsubscript{OUT} sense path away from noisy nodes and preferably through a layer on the other side of a grounded shielding layer.
- The RON pin is sensitive to noise. Thus, locate the R\textsubscript{RON} resistor as close as possible to the device and route with minimal lengths of trace. The parasitic capacitance from RON to GND must not exceed 20 pF.
- Provide adequate heat sinking for the LM5013-Q1 to keep the junction temperature below 150°C. For operation at full rated load, the top-side ground plane is an important heat-dissipating area. Use an array of heat-sinking vias to connect the exposed pad to the PCB ground plane. If the PCB has multiple copper layers, these thermal vias must also be connected to inner layer heat-spreading ground planes.
- Reference Section 10.2.

10.1.1 Compact PCB Layout for EMI Reduction

Radiated EMI generated by high di/dt components relates to pulsing currents in switching converters. The larger area covered by the path of a pulsing current, the more electromagnetic emission is generated. The key to minimizing radiated EMI is to identify the pulsing current path and minimize the area of that path.

Figure 10-1 denotes the critical switching loop of the buck converter power stage in terms of EMI. The topological architecture of a buck converter means that a particularly high di/dt current path exists in the loop comprising the input capacitor, the integrated MOSFET of the LM5013-Q1, and Schottky diode. It becomes mandatory to reduce the parasitic inductance of this loop by minimizing the effective loop area.
The input capacitor provides the primary path for the high di/dt components of the current of the high-side MOSFET. Placing a ceramic capacitor as close as possible to the VIN and GND pins is the key to EMI reduction. In addition, the cathode of the Schottky diode should be placed closely to the SW pin of the device, while its anode is kept closely to the GND pin.

Keep the trace connecting SW to the inductor as short as possible and just wide enough to carry the load current without excessive heating. Use short, thick traces or copper pours (shapes) for current conduction path to minimize parasitic resistance. Place the output capacitor close to the V_OUT side of the inductor, and connect the return terminal of the capacitor to the GND pin and exposed PAD of the LM5013-Q1.

**10.1.2 Feedback Resistors**

Reduce noise sensitivity of the output voltage feedback path by placing the resistor divider close to the FB pin, rather than close to the load. This reduces the trace length of FB signal and noise coupling. The FB pin is the input to the feedback comparator, and as such, is a high impedance node sensitive to noise. The output node is a low impedance node, so the trace from V_OUT to the resistor divider can be long if a short path is not available.

Route the voltage sense trace from the load to the feedback resistor divider, keeping away from the SW node, the inductor, and V_IN to avoid contaminating the feedback signal with switch noise, while also minimizing the trace length. This is most important when high feedback resistances greater than 100 kΩ are used to set the output voltage. Also, route the voltage sense trace on a different layer from the inductor, SW node, and V_IN so there is a ground plane that separates the feedback trace from the inductor and SW node copper polygon. This provides further shielding for the voltage feedback path from switching noise sources.
10.2 Layout Example

Figure 10-2 shows an example layout for the PCB top layer of a 2-layer board with essential components placed on the top side.

![Figure 10-2. LM5013-Q1 Layout Example](image)

10.2.1 Thermal Considerations

As with any power conversion device, the LM5013-Q1 dissipates internal power while operating. The effect of this power dissipation is to raise the internal temperature of the converter above ambient. The internal die temperature ($T_J$) is a function of the following:

- Ambient temperature
- Power loss
- Effective thermal resistance, $R_{θ_{JA}}$, of the device
- PCB combination

The maximum internal die temperature for the LM5013-Q1 must be limited to 150°C. This establishes a limit on the maximum device power dissipation and, therefore, the load current. Equation 20 shows the relationships between the important parameters. It is easy to see that larger ambient temperatures ($T_A$) and larger values of $R_{θ_{JA}}$ reduce the maximum available output current. The converter efficiency can be estimated by using the curves provided in this data sheet. Note that these curves include the power loss in the inductor. If the desired operating conditions cannot be found in one of the curves, then interpolation can be used to estimate the efficiency. Alternatively, the EVM can be adjusted to match the desired application requirements and the efficiency can be measured directly. The correct value of $R_{θ_{JA}}$ is more difficult to estimate. As stated in the Semiconductor and IC Package Thermal Metrics Application Report, the value of $R_{θ_{JA}}$ given in the Thermal
Information is not valid for design purposes and must not be used to estimate the thermal performance of the application. The values reported in that table were measured under a specific set of conditions that are rarely obtained in an actual application. The data given for \( R_{\theta JC(bott)} \) and \( \Psi_{JT} \) can be useful when determining thermal performance. See the *Semiconductor and IC Package Thermal Metrics Application Report* for more information and the resources given at the end of this section.

\[
I_{\text{OUT MAX}} = \frac{(T_J - T_A)}{R_{\theta JA}} \cdot \eta \cdot \frac{1}{V_{\text{OUT}}}
\]

(20)

where

- \( \eta \) is the efficiency.

The effective \( R_{\theta JA} \) is a critical parameter and depends on many factors such as the following:

- Power dissipation
- Air temperature/flow
- PCB area
- Copper heat-sink area
- Number of thermal vias under the package
- Adjacent component placement

The LM5013-Q1 features a die attach paddle, or “thermal pad” (EP), to provide a place to solder down to the PCB heat-sinking copper. This provides a good heat conduction path from the regulator junction to the heat sink and must be properly soldered to the PCB heat sink copper. Typical examples of \( R_{\theta JA} \) can be found in Figure 10-3. The copper area given in the graph is for each layer. The top and bottom layers are 2-oz copper each, while the inner layers are 1 oz. Remember that the data given in this graph is for illustration purposes only, and the actual performance in any given application depends on all of the previously mentioned factors.

![Figure 10-3. Typical \( R_{\theta JA} \) Versus Copper Area](image)

To continue with the design example, assume that the user has an ambient temperature of 70ºC and wishes to estimate the required copper area to keep the device junction temperature below 125ºC, at full load. From the curves in Section 8.2.3, an efficiency of about 92% was found at an input voltage of 48 V with output of 12 V with 1.75-A load. The efficiency will be somewhat less at high junction temperatures, so an efficiency of approximately 90% is assumed. This gives a total loss of about 2.3 W. Subtracting out the conduction loss alone for the inductor and catch diode, the user arrives at a device dissipation of about 1.54 W. With this information, the user can calculate the required \( R_{\theta JA} \) of about 30ºC/W. Based on Figure 10-3, the required copper area is about 40 cm² for a two-layer PCB.
The engineer's best judgment is to be used if using a lossy inductor, diode, or both in the application, as their large losses can contribute to localized heating of the component, as well, the nearby regulator. As an example, biasing the Schottky diode (D_{SW}) with 1.3-A continuous current (average current for 1.75-A load current) results in approximately 10°C rise in the case temperature of the regulator. This should be “buffered” for in the ambient temperature used in the previous calculation. For more details on these calculations, please see the *PCB Thermal Design Tips for Automotive DC/DC Converters Application Note*.

The following resources can be used as a guide to optimal thermal PCB design and estimating $R_{θJA}$ for a given application environment:

- LM5013 Thermal Optimization and Example PCB design
- *Semiconductor and IC Package Thermal Metrics Application Report*
- *AN-2020 Thermal Design By Insight, Not Hindsight Application Report*
- *A Guide to Board Layout for Best Thermal Resistance for Exposed Pad Packages Application Report*
- *Using New Thermal Metrics Application Report*
- *PCB Thermal Design Tips for Automotive DC/DC Converters Application Report*
11 Device and Documentation Support

11.1 Device Support

11.1.1 Third-Party Products Disclaimer

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11.1.2 Development Support

- **LM5013-Q1 Quickstart Calculator**
- **LM5013-Q1 Simulation Models**
- **TI Reference Design Library**
- Technical Articles:
  - *Use a Low-quiescent-current Switcher for High-voltage Conversion*
  - *How a DC/DC Converter Package and Pinout Design Can Enhance Automotive EMI Performance*

11.1.2.1 Custom Design With WEBENCH® Tools

Click here to create a custom design using the LM5013-Q1 device with the WEBENCH® Power Designer.

1. Start by entering the input voltage ($V_{IN}$), output voltage ($V_{OUT}$), and output current ($I_{OUT}$) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at [www.ti.com/WEBENCH](http://www.ti.com/WEBENCH).

11.2 Documentation Support

11.2.1 Related Documentation

For related documentation see the following:

- Texas Instruments, *Selecting an Ideal Ripple Generation Network for Your COT Buck Converter Application Report*
- Texas Instruments, *Valuing Wide $V_{IN}$, Low-EMI Synchronous Buck Circuits for Cost-Effective, Demanding Applications White Paper*
- Texas Instruments, *An Overview of Conducted EMI Specifications for Power Supplies White Paper*
- Texas Instruments, *An Overview of Radiated EMI Specifications for Power Supplies White Paper*
- Texas Instruments, *24-V AC Power Stage with Wide $V_{IN}$ Converter and Battery Gauge for Smart Thermostat Design Guide*
- Texas Instruments, *Accurate Gauging and 50-μA Standby Current, 13S, 48-V Li-ion Battery Pack Reference Design Guide*
- Texas Instruments, *AN-2162: Simple Success with Conducted EMI from DC/DC Converters Application Report*
- Texas Instruments, *Automotive Cranking Simulator User’s Guide*
- Texas Instruments, *Powering Drones with a Wide $V_{IN}$ DC/DC Converter Application Report*
- Texas Instruments, *Semiconductor and IC Package Thermal Metrics Application Report*
11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on Subscribe to updates to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.4 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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11.6 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.7 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.
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