LMP8278Q High Common Mode, 14 x Gain, Precision Current Sensing Amplifier

Check for Samples: LMP8278

FEATURES

- TCVos ±15μV/°C Max
- CMRR 80 dB Min
- Input Offset Voltage ±2 mV max
- CMVR -2V to 40V
- Operating Ambient Temperature Range −40°C to 125°C
- Single Supply Operation
- Min / Max Limits 100% Tested unless Otherwise Noted
- LMP8278Q Available in Automotive AEC-Q100 Grade 1 Qualified Version

DESCRIPTION

The LMP8278 is a fixed 14x gain precision current sense amplifier. The part amplifies and filters small differential signals in the presence of high common mode voltages. The part operates from a single 5V supply voltage. With an input common mode voltage range from -2V to +28V the gain is very precise (±0.5%). The part can handle common mode voltages in the range -2V to +40V with relaxed specifications. The LMP8278 is a member of the Linear Monolithic Precision (LMP™) family and is ideal for unidirectional current sensing applications. The parameter values that are shown in the Electrical Characteristics table are 100% tested and all bold values are also 100% tested over temperature, unless otherwise noted.

The part has a precise gain of 14x which is adequate in most targeted applications to drive an ADC to its full scale value. The fixed gain is achieved in two separate stages, a preamplifier with a gain of 7x and an output stage buffer amplifier with a gain of 2x. The connection between the two stages of the signal path is brought out on two pins to enable the possibility to create an additional filter network around the output buffer amplifier. These pins can also be used for alternative configurations with different gain as described in Application Information.

The LMP8278Q incorporates enhanced manufacturing and support processes for the automotive market, including defect detection methodologies. Reliability qualification is compliant with the requirements and temperature grades defined in the AEC Q100 standard.

APPLICATIONS

- High Side and Low Side Driver Configuration Current Sensing
- Automotive Fuel Injection Control
- Transmission Control
- Power Steering
- Battery Management Systems

Typical Applications
Block Diagram

Connection Diagram

PIN DESCRIPTIONS

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>GND</td>
<td>Power Ground</td>
</tr>
<tr>
<td>7</td>
<td>V_S</td>
<td>Positive Supply Voltage</td>
</tr>
<tr>
<td>1</td>
<td>-IN</td>
<td>Negative Input</td>
</tr>
<tr>
<td>8</td>
<td>+IN</td>
<td>Positive Input</td>
</tr>
<tr>
<td>3</td>
<td>A1</td>
<td>Preamplifier output</td>
</tr>
<tr>
<td>4</td>
<td>A2</td>
<td>Input from the external filter network and / or A1</td>
</tr>
<tr>
<td>5</td>
<td>OUT</td>
<td>Single ended output</td>
</tr>
<tr>
<td>6</td>
<td>N/C</td>
<td>No Connect (floating)</td>
</tr>
</tbody>
</table>

Figure 1. 8-Pin VSSOP Package
See Package Number DGK0008A
These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

**Absolute Maximum Ratings**

<table>
<thead>
<tr>
<th>ESD Tolerance (2)</th>
<th>Human Body For input pins only ±8000V For all other pins ±2000V</th>
<th>Machine Model 200V</th>
<th>Charge Device Model 1000V</th>
<th>Supply Voltage (V&lt;sub&gt;S&lt;/sub&gt; - GND) 6V</th>
<th>Continuous Input Voltage (-IN and +IN) (3) -12V to 50V</th>
<th>Max Voltage at A1, A2 and OUT V&lt;sub&gt;S&lt;/sub&gt; +0.3V</th>
<th>Min Voltage at A1, A2 and OUT GND -0.3V</th>
<th>Storage Temperature Range -65°C to 150°C</th>
<th>Junction Temperature (4) 150°C</th>
</tr>
</thead>
</table>

(1) “Absolute Maximum Ratings” indicate limits beyond which damage to the device may occur, including inoperability and degradation of the device reliability and/or performance. Functional operation of the device and/or non-degradation at the Absolute Maximum Ratings or other conditions beyond those indicated in the Recommended Operating Conditions is not implied. The Recommended Operating Conditions indicate conditions at which the device is functional and the device should not be beyond such conditions. All voltages are measured with respect to the ground pin, unless otherwise specified.

(2) Human Body Model per MIL-STD-883, Method 3015.7. Machine Model, per JESD22-A115-A. Field-Induced Charge-Device Model, per JESD22-C101-C.

(3) For the VSSOP package, the pitch of the solder pads is too narrow for reliable use at higher voltages (V<sub>CM</sub> > 25V). Therefore, it is strongly advised to add a conformal coating on the PCB assembled with the LMP8278 / LMP8278Q.

(4) The maximum power dissipation must be derated at elevated temperatures and is dictated by T<sub>J(MAX)</sub>, θ<sub>JA</sub>, and the ambient temperature, T<sub>A</sub>. The maximum allowable power dissipation P<sub>DMAX</sub> = (T<sub>J(MAX)</sub> - T<sub>A</sub>) / θ<sub>JA</sub> or the number given in Absolute Maximum Ratings, whichever is lower.

**Operating Ratings**

<table>
<thead>
<tr>
<th>Supply Voltage (V&lt;sub&gt;S&lt;/sub&gt; - GND)</th>
<th>4.5V to 5.5V</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature Range (2)</td>
<td>-40°C to +125°C</td>
</tr>
<tr>
<td>Package Thermal Resistance (2)</td>
<td>230°C/W</td>
</tr>
</tbody>
</table>

(1) “Absolute Maximum Ratings” indicate limits beyond which damage to the device may occur, including inoperability and degradation of the device reliability and/or performance. Functional operation of the device and/or non-degradation at the Absolute Maximum Ratings or other conditions beyond those indicated in the Recommended Operating Conditions is not implied. The Recommended Operating Conditions indicate conditions at which the device is functional and the device should not be beyond such conditions. All voltages are measured with respect to the ground pin, unless otherwise specified.

(2) The maximum power dissipation must be derated at elevated temperatures and is dictated by T<sub>J(MAX)</sub>, θ<sub>JA</sub>, and the ambient temperature, T<sub>A</sub>. The maximum allowable power dissipation P<sub>DMAX</sub> = (T<sub>J(MAX)</sub> - T<sub>A</sub>) / θ<sub>JA</sub> or the number given in Absolute Maximum Ratings, whichever is lower.
5.0V Electrical Characteristics *(1)*

Unless otherwise specified, all limits ensured at \( T_A = 25^\circ C \), \( V_S = 5.0V \), GND = 0V, \(-2V \leq V_{CM} \leq 28V\), and \( R_L = \infty \), 10nF between \( V_S \) and GND. **Boldface** limits apply at the temperature extremes.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN <em>(2)</em></th>
<th>TYP <em>(3)</em></th>
<th>MAX <em>(2)</em></th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>( I_S )</td>
<td>Supply Current</td>
<td>0.3</td>
<td>0.4</td>
<td>0.55</td>
<td>mA</td>
</tr>
<tr>
<td>( A_V )</td>
<td>Total Gain</td>
<td>(-2V &lt; V_{CM} &lt; 28V)</td>
<td>13.93</td>
<td>14</td>
<td>14.07</td>
</tr>
<tr>
<td></td>
<td>(-2V &lt; V_{CM} &lt; 40V)</td>
<td>13.86</td>
<td>14</td>
<td>14.14</td>
<td></td>
</tr>
<tr>
<td>( Gain )</td>
<td>Gain Drift</td>
<td>(-40^\circ C \leq T_A \leq 125^\circ C)</td>
<td>( \pm 2 )</td>
<td>( \pm 25 )</td>
<td>ppm/(^\circ C)</td>
</tr>
<tr>
<td>( SR )</td>
<td>Slew Rate</td>
<td>( V_{IN} = \pm 0.2V)</td>
<td>0.7</td>
<td>V/( \mu )s</td>
<td></td>
</tr>
<tr>
<td>( BW )</td>
<td>Bandwidth</td>
<td>90</td>
<td>kHz</td>
<td></td>
<td></td>
</tr>
<tr>
<td>( V_{OS} )</td>
<td>Input Offset Voltage</td>
<td>( V_{CM} = V_S / 2)</td>
<td>( \pm 0.25 )</td>
<td>( \pm 2 )</td>
<td>mV</td>
</tr>
<tr>
<td>( TCV_{OS} )</td>
<td>Input Offset Voltage Drift <em>(4)</em></td>
<td>(-40^\circ C \leq T_A \leq 125^\circ C)</td>
<td>( \pm 2.5 )</td>
<td>( \pm 15 )</td>
<td>( \mu V/^\circ C)</td>
</tr>
<tr>
<td>( e_n )</td>
<td>Input Referred Voltage Noise</td>
<td>0.1 Hz – 10 Hz, 6–Sigma</td>
<td>Spectral Density, 1 kHz</td>
<td>11</td>
<td>( \mu V_{PP} )</td>
</tr>
<tr>
<td></td>
<td></td>
<td>285</td>
<td>nV/( \sqrt{Hz} )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>( PSRR )</td>
<td>Power Supply Rejection Ratio</td>
<td>DC, 4.5V \leq V_S \leq 5.5V, ( V_{CM} = V_S/2)</td>
<td>70</td>
<td>80</td>
<td>dB</td>
</tr>
</tbody>
</table>

Preamplifier (From input pins –IN (pin 1) and +IN (pin 8) to A1 (pin 3))

| \( R_{CM} \) | Input Impedance Common Mode | \(-2V \leq V_{CM} \leq 40\) | 100 | 125 | kΩ |
| \( R_{DM} \) | Input Impedance Differential Mode *(5)* | \(-2V \leq V_{CM} \leq 40\) | 60 | 85 | kΩ |
| \( V_{OS} \) | Input Offset Voltage | \( V_{CM} = V_S / 2\) | \( \pm 0.25 \) | \( \pm 2 \) | mV |
| \( TCG_{OS} \) | Input Offset Voltage Drift *(4)* | \(-40^\circ C \leq T_A \leq 125^\circ C\) | \( \pm 2.5 \) | \( \pm 15 \) | \( \mu V/\^\circ C\) |
| \( DC \) \( CMRR \) | DC Common Mode Rejection Ratio | \(-2V \leq V_{CM} \leq 40V\) | 80 | 90 | dB |
| \( AC \) \( CMRR \) | AC Common Mode Rejection Ratio | \( f = 1 \) kHz | 90 | dB |
|            |                 | \( f = 10 \) kHz | 85 |
| \( CMVR \) | Input Common Mode Voltage Range | for 80 dB CMRR | \(-2 \) | 40 | V |
| \( A1 \) \( V_{OUT} \) | Gain | 6.93 | 7.0 | 7.07 | V/V |
| \( R_{F-INT} \) | Output Impedance Filter Resistor | 97 | 100 | 103 | kΩ |
| \( TCR_{F-INT} \) | Output Impedance Filter Resistor Drift | 20 | \( \pm 100 \) | ppm/\( ^\circ C\) |
| \( A1 \) \( V_{OUT} \) | Preamplifier Output Voltage Swing | \( V_{OL} \) | \( R_L = \infty \) | 4 | 10 | mV |
|            |                   | \( V_{OH} \) | 4.80 | 4.95 | V |

Output Buffer (From A2 (pin 4) to OUT (pin 5))

| \( V_{OS} \) | Input Offset Voltage | \( 0V \leq V_{CM} \leq V_S-1\) | \( \pm 0.25 \) | \( \pm 2 \) | mV |
| \( A2 \) \( V_{OUT} \) | Gain | 1.98 | 2 | 2.02 | V/V |
| \( I_B \) | Input Bias Current of Output Buffer *(6)*(6) | \( \pm 20 \) | pA |
| \( A2 \) \( V_{OUT} \) | Output Buffer Output Voltage Swing *(7) *(8) | \( V_{OL} \) | \( R_L = 100 \) kΩ | 7 | 20 | mV |
|            |                   | \( V_{OH} \) | 4.80 | 4.99 | V |
| \( A2 \) \( V_{OUT} \) | Output Buffer Output Voltage Swing *(7) *(8) | \( V_{OL} \) | \( R_L = 10 \) kΩ | 15 | 30 | mV |
|            |                   | \( V_{OH} \) | 4.75 | 4.95 | V |

*(1)* The Electrical Characteristics table lists ensured specifications under the listed Recommended Operating Conditions except as otherwise modified or specified by the Electrical Characteristics Conditions and/or Notes. Typical specifications are estimations only and are not ensured.

*(2)* Datasheet min/max specification limits are ensured by test, unless otherwise noted.

*(3)* Typical values represent the most likely parameter norms at \( T_A = +25^\circ C \) and at the Recommended Operation Conditions at the time of product characterization and are not ensured.

*(4)* Offset voltage drift determined by dividing the change in \( V_{OS} \) at temperature extremes by the total temperature change.

*(5)* Specification is ensured by design and is not tested in production.

*(6)* Positive current corresponds to current flowing into the device.

*(7)* For this test input is driven from A1 stage.

*(8)* For \( V_{OL} \), \( R_L \) is connected to \( V_S \) and for \( V_{OH} \), \( R_L \) is connected to GND.
5.0V Electrical Characteristics (1) (continued)

Unless otherwise specified, all limits ensured at \( T_A = 25 \degree C, V_S = 5.0V, GND = 0V, -2V \leq V_{CM} \leq 28V, \) and \( R_L = \infty, 10nF \) between \( V_S \) and GND. **Boldface** limits apply at the temperature extremes.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN(2)</th>
<th>TYP(3)</th>
<th>MAX(2)</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>( I_{SC} )</td>
<td>Output Short-Circuit Current (6)(9)</td>
<td></td>
<td></td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td>Sourcing, ( V_{IN} = V_S, V_{OUT} = GND )</td>
<td>-10</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Sinking, ( V_{IN} = GND, V_{OUT} = V_S )</td>
<td>10</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(9) Short-Circuit test is a momentary test. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C.
Typical Performance Characteristics

Unless otherwise specified, measurements taken at $T_A = 25^\circ C$, $V_S = 5V$, GND = 0V, $-2V \leq V_{CM} \leq 28V$, and $R_L = \infty$, 10nF between $V_S$ and GND.

Figure 2.

A1 Input Bias Current vs. $V_{CM}$

Figure 4.

A2 Input Bias Current vs. $V_{CM}$, at 25°C

Figure 5.

A2 Input Bias Current vs. $V_{CM}$, at 125°C

Figure 6.

Input Referred Voltage Noise vs. Frequency

Figure 7.
Typical Performance Characteristics (continued)

Unless otherwise specified, measurements taken at $T_A = 25^\circ C$, $V_S = 5V$, GND = 0V, $-2V \leq V_{CM} \leq 28V$, and $R_L = \infty$, 10nF between $V_S$ and GND.

![PSRR vs. Frequency](image1)

**Figure 8.**

![CMRR vs. Frequency](image2)

**Figure 9.**

![Gain vs. Frequency, $V_{out}=500mV$](image3)

**Figure 10.**

![Gain vs. Frequency, $V_{out}=4.5V$](image4)

**Figure 11.**

![Settling Time (Falling Edge)](image5)

**Figure 12.**

![Settling Time (Rising Edge)](image6)

**Figure 13.**
Typical Performance Characteristics (continued)

Unless otherwise specified, measurements taken at \( T_A = 25 \, ^\circ C \), \( V_S = 5 \, V \), GND = 0V, \(-2V \leq V_{CM} \leq 28V\), and \( R_L = \infty \), 10nF between \( V_S \) and GND.

**Step Response**

- **Positive Swing vs. \( I_{LOAD} \)**

**Negative Swing vs. \( I_{LOAD} \)**

**\( V_{OS} \) Distribution**

**TCV\( _{OS} \) Distribution**

**CMRR Distribution**

Figure 14.

Figure 15.

Figure 16.

Figure 17.

Figure 18.

Figure 19.
APPLICATION INFORMATION

GENERAL
The LMP8278 is a fixed gain differential voltage precision amplifier with a gain of 14x and a -2V to +40V input common mode voltage range when operating from a single 5V supply. The LMP8278 is a member of the LMP™ family and is ideal for unidirectional current sensing applications. Because of its proprietary level-shift input stage the LMP8278 achieves very low offset, very low thermal offset drift, and very high CMRR. The LMP8278 amplifies and filters small differential signals in the presence of high common mode voltages.

The LMP8278 uses level shift resistors at the inputs. Because of these resistors, the LMP8278 can easily withstand very large differential input voltages that may exist in fault conditions where some other less protected current sense amplifiers might sustain permanent damage.

The LMP8278 is available in an 8–Pin VSSOP package. For the VSSOP package, the pitch of the solder pads is too narrow for reliable use at higher voltages (V_{CM} > 25V). Therefore, it is strongly advised to add a conformal coating on the PCB assembled with the LMP8278 in VSSOP package.

PERFORMANCE GUARANTIES
To guaranty the high performance of the LMP8278, minimum and maximum values shown in the Electrical Characteristics of this datasheet are 100% tested and all bold limits are also 100% tested over temperature, unless otherwise noted.

THEORY OF OPERATION
The schematic shown in Figure 20 gives a schematic representation of the internal operation of the LMP8278.

The signal on the input pins is typically a small differential voltage across a current sensing shunt resistor. The input signal may appear at a high common mode voltage. The input signals are accessed through two input resistors. The proprietary level shift circuit brings the common mode voltage behind the input resistors within the supply rails. Subsequently, the signal is gained up by a factor of 7 and brought out on the A1 pin through a trimmed 100 kΩ resistor. In the application, additional gain adjustment or filtering components can be added between the A1 and A2 pins as will be explained in subsequent sections. The signal on the A2 pin is further amplified by a factor of 2 and brought out on the OUT pin.

![Figure 20. Theory of Operation](image-url)
ADDITIONAL SECOND ORDER LOW PASS FILTER

The bandwidth of the output buffer can be reduced by adding a capacitor on the A1 pin to create a first order low pass filter with a time constant determined by the 100 kΩ internal resistor and the external filter capacitor.

It is also possible to create an additional second order Sallen-Key low pass filter, as illustrated in Figure 21, by adding external components R₂, C₁ and C₂. Together with the internal 100 kΩ resistor R₁, this circuit creates a second order low-pass filter characteristic.

When the corner frequency of the additional filter is much lower than 90 kHz, the transfer function of the described amplifier can be written as:

\[
H(s) = \frac{K_1 \cdot K_2}{s^2 + s \left[ \frac{1}{R_1C_2} + \frac{1}{R_2C_2} + \frac{(1 - K_2)}{R_2C_1} \right] + \frac{1}{R_1R_2C_1C_2}}
\]

where

- K₁ equals the gain of the preamplifier
- K₂ that of the buffer amplifier

The above equation can be written in the normalized frequency response for a 2ⁿᵈ order low pass filter:

\[
G(j\omega) = \frac{K_2}{\omega_o^2 + \frac{j\omega}{Q\omega_o} + 1}
\]

The cut-off frequency \(\omega_o\) in rad/sec (divide by 2π to get the cut-off frequency in Hz) is given by:

\[
\omega_o = \frac{1}{\sqrt{R_1R_2C_1C_2}}
\]

And the quality factor of the filter is given by:

\[
Q = \frac{\sqrt{R_1R_2C_1C_2}}{R_1C_1 + R_2C_1 + (1 - K_2) \cdot R_1C_2}
\]

With \(K_2 > 1\), the above equation results in:

\[
Q = \frac{\sqrt{R_1R_2C_1C_2}}{R_1C_1 + R_2C_1 + (1 - K_2) \cdot R_1C_2}
\]

For any filter gain \(K > 1\), the design procedure can be very simple if the two capacitors are chosen in a certain ratio.

\[
C_2 = \frac{C_1}{K - 1}
\]

In this case, given the predetermined value of \(R_1 = 100\) kΩ (the internal resistor), the quality factor is set solely by the value of the resistor \(R_2\).
R₂ can be calculated based on the desired value of Q as the first step of the design procedure with the following equation:

\[ R₂ = \frac{R₁}{(K - 1)Q²} \]  \hspace{1cm} (7)

For the gain of 2 for the LMP8278 this results in:

\[ R₂ = \frac{R₁}{Q²} \]  \hspace{1cm} (8)

For instance, the value of Q can be set to \(0.5\sqrt{2}\) to create a Butterworth response, to \(1/\sqrt{3}\) to create a Bessel response, or to 0.5 to create a critically damped response. Once the value of R₂ has been found, the second and last step of the design procedure is to calculate the required value of C to give the desired low-pass cut-off frequency using:

\[ C₁ = \frac{(K-1)Q}{R₁\omega₀} \]  \hspace{1cm} (9)

Which for the gain=2 will give:

\[ C₁ = \frac{Q}{R₁\omega₀} \]  \hspace{1cm} (10)

For \(C₂\) the value is calculated with:

\[ C₂ = \frac{C₁}{K - 1} \]  \hspace{1cm} (11)

Or, for a gain=2, \(C₂=C₁\)
Note that the frequency response achieved using this procedure will only be accurate if the cut-off frequency of the second order filter is much smaller than the intrinsic 90 kHz low-pass response. In other words, choose the frequency response of the circuit such that the internal poles of the LMP8278 do not affect the external second order filter.

For a desired Q = 0.707 and a cut off frequency = 3 kHz, this will result in rounded values for \( R_2 = 200 \, \text{k}\Omega, \; C_1; C_2 = 390 \, \text{pF} \).

**GAIN ADJUSTMENT**

The gain of the LMP8278 is 14; however, this gain can be adjusted as the signal path in between the two internal amplifiers is available on the external pins.

**Reduce Gain**

*Figure 22* shows the configuration that can be used to reduce the gain of the LMP8278.

\( R_r \) creates a resistive divider together with the internal 100 k\( \Omega \) resistor such that the reduced gain \( G_r \) becomes:

\[
G_r = \frac{14 \, R_r}{R_r + 100 \, \text{k}\Omega}
\]  
(12)

Given a desired value of the reduced gain \( G_r \), using this equation the required value for \( R_r \) can be calculated with:

\[
R_r = \frac{100 \, \text{k}\Omega \times G_r}{14 - G_r}
\]  
(13)

**Increase Gain**

*Figure 23* shows the configuration that can be used to increase the gain of the LMP8278.

\( R_i \) creates positive feedback from the output pin to the input of the buffer amplifier. The positive feedback increases the gain. The increased gain \( G_i \) becomes:

\[
G_i = \frac{14 \, R_i}{R_i - 100 \, \text{k}\Omega}
\]  
(14)

From this equation, for a desired value of the gain, the required value of \( R_i \) can be calculated with:

\[
R_i = \frac{100 \, \text{k}\Omega \times G_i}{G_i - 14}
\]  
(15)

It should be noted from the equation for the gain \( G_i \) that for large gains \( R_i \) approaches 100 k\( \Omega \). In this case, the denominator in the equation becomes close to zero. In practice, for large gains the denominator will be determined by tolerances in the values of the external resistor \( R_i \) and the internal 100 k\( \Omega \) resistor. In this case, the gain becomes very inaccurate. If the denominator becomes equal to zero, the system will even become unstable. It is recommended to limit the application of this technique to gain values of 35 or smaller.
POWER SUPPLY DECOUPLING

In order to decouple the LMP8278 from AC noise on the power supply, it is recommended to use a 0.1 µF bypass capacitor between the $V_S$ and GND pins. This capacitor should be placed as close as possible to the supply pins. In some cases an additional 10 µF bypass capacitor may further reduce the supply noise.

DRIVING SWITCHED CAPACITIVE LOADS

Some ADCs load their signal source with a sample and hold capacitor. The capacitor may be discharged prior to being connected to the signal source. If the LMP8278 is driving such ADCs the sudden current that should be delivered when the sampling occurs may disturb the output signal. This effect was simulated with the circuit shown in Figure 24 where the output is connected to a capacitor that is driven by a rail to rail square wave.
This circuit simulates the switched connection of a discharged capacitor to the LMP8278 output. The resulting \( V_{\text{OUT}} \) disturbance signal is shown in Figure 25.

The figure can be used to estimate the disturbance that will be caused when driving a switched capacitive load. To minimize the error signal introduced by the sampling that occurs on the ADC input, an additional RC filter can be placed in between the LMP8278 and the ADC as illustrated in Figure 26.

The external capacitor absorbs the charge that flows when the ADC sampling capacitor is connected. The external capacitor should be much larger than the sample and hold capacitor at the input of the ADC and the RC time constant of the external filter should be such that the speed of the system is not affected.

![Figure 24. Driving Switched Capacitive Load](image)

![Figure 25. Capacitive Load Response](image)

![Figure 26. Reduce Error When Driving ADCs](image)
LOW SIDE CURRENT SENSING APPLICATION

Figure 27 illustrates a low side current sensing application with a low side driver. The power transistor is pulse width modulated to control the average current flowing through the inductive load which is connected to a relatively high battery voltage. The current through the load is measured across a shunt resistor \( R_{\text{SENSE}} \) in series with the load. When the power transistor is on, current flows from the battery through the inductive load, the shunt resistor and the power transistor to ground. In this case, the common mode voltage on the shunt is close to ground. When the power transistor is off, current flows through the inductive load, through the shunt resistor and through the freewheeling diode. In this case the common mode voltage on the shunt is at least one diode voltage drop above the battery voltage. Therefore, in this application the common mode voltage on the shunt is varying between a large positive voltage and a relatively low voltage. Because the large common mode voltage range of the LMP8278 and because of the high AC common mode rejection ratio, the LMP8278 is very well suited for this application.

HIGH SIDE CURRENT SENSING APPLICATION

Figure 28 illustrates the application of the LMP8278 in a high side sensing application. This application is similar to the low side sensing discussed above, except in this application the common mode voltage on the shunt drops below ground when the driver is switched off. Because the common mode voltage range of the LMP8278 extends below the negative rail, the LMP8278 is also very well suited for this application.
RF-PA CONTROL APPLICATION

Figure 29 illustrates how the LMP8278 can be used to monitor current flow in an RF power amplifier control application. The fact that the LMP8278 can measure small voltages at a high common mode voltage outside its own supply range makes this part a good choice for such an application. The output signal of the LMP8278 is used as an input for the PA controller. The PA controller can be used to regulate the output power of the RF-PA by measuring the output amplifier supply current.

Figure 28. High Side Current Sensing Application

Figure 29. RF Power Amplifier Control Application
REVISION HISTORY

Changes from Original (March 2013) to Revision A

<table>
<thead>
<tr>
<th>Change Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Changed layout of National Data Sheet to TI format</td>
<td>16</td>
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</tbody>
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## PACKAGING INFORMATION

<table>
<thead>
<tr>
<th>Orderable Device</th>
<th>Status (1)</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>Package Qty</th>
<th>Eco Plan (2)</th>
<th>Lead finish/ Ball material (6)</th>
<th>MSL Peak Temp (3)</th>
<th>Op Temp (°C)</th>
<th>Device Marking (4/5)</th>
<th>Samples</th>
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<tbody>
<tr>
<td>LMP8278QMM/NOPB</td>
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<td>DGK</td>
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<td>1000</td>
<td>RoHS &amp; Green</td>
<td>SN</td>
<td>Level-1-260C-UNLIM</td>
<td>-40 to 125</td>
<td>AB7A</td>
<td>Samples</td>
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<td>AB7A</td>
<td>Samples</td>
</tr>
<tr>
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<td>DGK</td>
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<td>3500</td>
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<td>Level-1-260C-UNLIM</td>
<td>-40 to 125</td>
<td>AB7A</td>
<td>Samples</td>
</tr>
</tbody>
</table>

(1) The marketing status values are defined as follows:
- **ACTIVE:** Product device recommended for new designs.
- **LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
- **NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
- **PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.
- **OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

- **RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
- **Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.
TAPE AND REEL INFORMATION

**REEL DIMENSIONS**

- Reel Diameter
- Reel Width (W1)

**TAPE DIMENSIONS**

- A0: Dimension designed to accommodate the component width
- B0: Dimension designed to accommodate the component length
- K0: Dimension designed to accommodate the component thickness
- W: Overall width of the carrier tape
- P1: Pitch between successive cavity centers

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**

- Pocket Quadrants
- Sprocket Holes
- User Direction of Feed

*All dimensions are nominal*

<table>
<thead>
<tr>
<th>Device</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>SPQ</th>
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<th>Reel Width W1 (mm)</th>
<th>A0 (mm)</th>
<th>B0 (mm)</th>
<th>K0 (mm)</th>
<th>P1 (mm)</th>
<th>W (mm)</th>
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<td>Q1</td>
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## TAPE AND REEL BOX DIMENSIONS

*All dimensions are nominal

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<td>35.0</td>
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</tbody>
</table>
DGK (S-PDSO-G8)

PLASTIC SMALL-OUTLINE PACKAGE

NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 per end.
D. Body width does not include interlead flash. Interlead flash shall not exceed 0.50 per side.
E. Falls within JEDEC MO-187 variation AA, except interlead flash.

4073329/E 05/06
NOTES:

A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Publication IPC-7351 is recommended for alternate designs.
D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.
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