1 Features
• Bus-Pin Fault Protection to:
  – > ±70 V (SN65HVD1780, SN65HVD1781)
  – > ±30 V (SN65HVD1782)
• Operation With 3.3-V to 5-V Supply Range
• ±16-kV HBM Protection on Bus Pins
• Reduced Unit Load for Up to 320 Nodes
• Failsafe Receiver for Open-Circuit, Short-Circuit, and Idle-Bus Conditions
• Low Power Consumption
  – Low Standby Supply Current, 1 µA Maximum
  – $I_{CC}$ 4-mA Quiescent Current During Operation
• Pin-Compatible With Industry-Standard SN75176
• Signaling Rates of 115 kbps, 1 Mbps, and up to 10 Mbps
• Create a Custom Design using the SN65HVD178x with the WEBENCH® Power Designer

2 Applications
• HVAC Networks
• Security Electronics
• Building Automation
• Telecommunication Equipment
• Motion Control
• Industrial Networks

3 Description
The SN65HVD178x devices are designed to survive overvoltage faults such as direct shorts to power supplies, mis-wiring faults, connector failures, cable crushes, and tool mis-applications. The devices are also robust to ESD events with high levels of protection to the human-body-model specification.

The SN65HVD178x devices combine a differential driver and a differential receiver, which operate from a single power supply. In the SN65HVD1782, the driver differential outputs and the receiver differential inputs are connected internally to form a bus port suitable for half-duplex (two-wire bus) communication. This port features a wide common-mode voltage range, making the devices suitable for multipoint applications over long cable runs. These devices are characterized from –40°C to 125°C. These devices are pin-compatible with the industry-standard SN75176 transceiver, making them drop-in upgrades in most systems.

These devices are fully compliant with ANSI TIA/EIA 485-A with a 5-V supply and can operate with a 3.3-V supply with reduced driver output voltage for low-power applications. For applications where operation is required over an extended common-mode voltage range, see the SN65HVD1785 (SLLS872) data sheet.

Device Information(1)

<table>
<thead>
<tr>
<th>PART NUMBER</th>
<th>PACKAGE</th>
<th>BODY SIZE (NOM)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SN65HVD178x</td>
<td>SOIC (8)</td>
<td>4.90 mm × 3.91 mm</td>
</tr>
<tr>
<td></td>
<td>PDIP (8)</td>
<td>9.81 mm × 6.35 mm</td>
</tr>
</tbody>
</table>

(1) For all available packages, see the orderable addendum at the end of the data sheet.
4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision G (August 2015) to Revision H

- Added WEBENCH information to the Features, Detailed Design Procedure, and Device Support sections .......... 1
- Added values to the Storage temperature in the Absolute Maximum Ratings table ........................................ 4
- Added the Equivalent Input Schematic section ........................................................................................................ 14

Changes from Revision F (August 2012) to Revision G

- Added Pin Configuration and Functions section, ESD Ratings table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and Mechanical, Packaging, and Orderable Information section ........................................... 1

Changes from Revision E (September 2008) to Revision F

- Deleted text from the first Description paragraph - The internal current-limit circuits allow fault survivability without causing the high bus currents that otherwise might damage external components or power supplies. ......................... 1
- Changed From: Voltage input range, transient pulse, A and B, through 100 Ω in the Absolute Maximum Ratings table To: Transient overvoltage pulse through 100 Ω per TIA-485 ................................................................. 4
- Changed Figure 13 title From: Measurement of Receiver Enable Times With Driver Disabled To: Measurement of Receiver Enable Times With Driver Disabled .................................................. 13

Changes from Revision D (August 2008) to Revision E

- Changed Bus input current (disabled driver), separating the condition for the different devices ............................. 6
### Changes from Revision C (July 2008) to Revision D

<table>
<thead>
<tr>
<th>Change Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Changed Receiver propagation delay max value From: 70 ns To: 80 ns</td>
<td>8</td>
</tr>
</tbody>
</table>

### Changes from Revision B (April 2008) to Revision C

<table>
<thead>
<tr>
<th>Change Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Added two new part numbers 1780 and 1782</td>
<td>1</td>
</tr>
<tr>
<td>Deleted Features Bullet: Designed for RS-485 and RS-422 Networks</td>
<td>1</td>
</tr>
<tr>
<td>Changed making it a drop-in upgrade for most devices -to- making them drop-in upgrades in most systems</td>
<td>1</td>
</tr>
</tbody>
</table>

### Changes from Revision A (January 2008) to Revision B

<table>
<thead>
<tr>
<th>Change Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Changed the $I_{OS}$ Min value From: -150 To: -200 and Max value From: 150 To: 200</td>
<td>6</td>
</tr>
</tbody>
</table>

### Changes from Original (December 2007) to Revision A

<table>
<thead>
<tr>
<th>Change Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Changed Receiver propagation delay max value From: 50 ns To: 70 ns</td>
<td>8</td>
</tr>
<tr>
<td>Changed $t_{PLZ}$, $t_{PHZ}$ Receiver disable time From 3000 ns To 100 ns</td>
<td>8</td>
</tr>
</tbody>
</table>
## 5 Device Comparison Table

<table>
<thead>
<tr>
<th>TRANSCIEVER</th>
<th>SIGNALING RATE</th>
<th>NUMBER OF NODES</th>
</tr>
</thead>
<tbody>
<tr>
<td>SN65HVD1780</td>
<td>Up to 115 kbps</td>
<td>Up to 320</td>
</tr>
<tr>
<td>SN65HVD1781</td>
<td>Up to 1 Mbps</td>
<td>Up to 320</td>
</tr>
<tr>
<td>SN65HVD1782</td>
<td>Up to 10 Mbps</td>
<td>Up to 64</td>
</tr>
</tbody>
</table>

## 6 Pin Configuration and Functions

### D Package and P Package
8-Pin SOIC and 8-Pin PDIP

![Pin Configuration Diagram]

### Pin Functions

<table>
<thead>
<tr>
<th>PIN</th>
<th>NAME</th>
<th>NUMBER</th>
<th>I/O</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>6</td>
<td>Bus</td>
<td>6</td>
<td>Driver output or receiver input (complimentary to B)</td>
</tr>
<tr>
<td>B</td>
<td>7</td>
<td>Bus</td>
<td>7</td>
<td>Driver output or receiver input (complimentary to A)</td>
</tr>
<tr>
<td>D</td>
<td>4</td>
<td>Digital</td>
<td>4</td>
<td>Driver data input</td>
</tr>
<tr>
<td>DE</td>
<td>3</td>
<td>Digital</td>
<td>3</td>
<td>Driver enable high</td>
</tr>
<tr>
<td>GND</td>
<td>5</td>
<td>Reference potential</td>
<td>5</td>
<td>Local device ground</td>
</tr>
<tr>
<td>R</td>
<td>1</td>
<td>Digital output</td>
<td>1</td>
<td>Receive data output</td>
</tr>
<tr>
<td>RE</td>
<td>2</td>
<td>Digital input</td>
<td>2</td>
<td>Receiver enable low</td>
</tr>
<tr>
<td>VCC</td>
<td>8</td>
<td>Supply</td>
<td>8</td>
<td>4.5-V to 5.5-V supply</td>
</tr>
</tbody>
</table>

## 7 Specifications

### 7.1 Absolute Maximum Ratings

<table>
<thead>
<tr>
<th></th>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage, V CC</td>
<td>–0.5</td>
<td>7</td>
<td>V</td>
</tr>
<tr>
<td>Voltage at bus pin</td>
<td>–70</td>
<td>70</td>
<td>V</td>
</tr>
<tr>
<td>Input voltage at any logic pin</td>
<td>–0.3</td>
<td>V CC + 0.3</td>
<td>V</td>
</tr>
<tr>
<td>Transient overvoltage pulse through 100 Ω per TIA-485</td>
<td>–70</td>
<td>70</td>
<td>V</td>
</tr>
<tr>
<td>Receiver output current</td>
<td>–24</td>
<td>24</td>
<td>mA</td>
</tr>
<tr>
<td>Junction temperature, T J</td>
<td>–55</td>
<td>170</td>
<td>°C</td>
</tr>
<tr>
<td>Storage temperature, T stab</td>
<td>–55</td>
<td>150</td>
<td>°C</td>
</tr>
</tbody>
</table>

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
7.2 ESD Ratings: JEDEC

<table>
<thead>
<tr>
<th>(V_{(ESD)})</th>
<th>Electrostatic discharge</th>
<th>(V_{(ESD)})</th>
<th><strong>VALUE</strong></th>
<th><strong>UNIT</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>Bus pins and GND</td>
<td>±16000</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>All pins</td>
<td>±4000</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Charged device model (CDM), per JEDEC specification JESD22-C101, all pins</td>
<td>±2000</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Machine model JEDEC Standard 22, Test Method A115, all pins</td>
<td>±400</td>
<td>V</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 ESD Ratings: IEC

<table>
<thead>
<tr>
<th>(V_{(ESD)})</th>
<th>Electrostatic discharge</th>
<th><strong>VALUE</strong></th>
<th><strong>UNIT</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>IEC 60749-26 ESD (human body model), bus terminals and GND</td>
<td>±16000</td>
<td>V</td>
<td></td>
</tr>
</tbody>
</table>

7.4 Recommended Operating Conditions

<table>
<thead>
<tr>
<th><strong>MIN</strong></th>
<th><strong>NOM</strong></th>
<th><strong>MAX</strong></th>
<th><strong>UNIT</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>(V_C)</td>
<td>Supply voltage</td>
<td>3.15</td>
<td>5</td>
</tr>
<tr>
<td>(V_i)</td>
<td>Input voltage at any bus terminal (separately or common mode)</td>
<td>–7</td>
<td>12</td>
</tr>
<tr>
<td>(V_{IH})</td>
<td>High-level input voltage (driver, driver enable, and receiver enable inputs)</td>
<td>2</td>
<td>(V_{CC})</td>
</tr>
<tr>
<td>(V_{IL})</td>
<td>Low-level input voltage (driver, driver enable, and receiver enable inputs)</td>
<td>0</td>
<td>0.8</td>
</tr>
<tr>
<td>(V_{ID})</td>
<td>Differential input voltage</td>
<td>–12</td>
<td>12</td>
</tr>
<tr>
<td>(I_o)</td>
<td>Output current, driver</td>
<td>–60</td>
<td>60</td>
</tr>
<tr>
<td>Output current, receiver</td>
<td>–8</td>
<td>8</td>
<td>mA</td>
</tr>
<tr>
<td>(R_L)</td>
<td>Differential load resistance</td>
<td>54</td>
<td>60</td>
</tr>
<tr>
<td>(C_L)</td>
<td>Differential load capacitance</td>
<td>50</td>
<td></td>
</tr>
</tbody>
</table>

1/tUI | Signaling rate | SN65HVD1780 | 115 | kbps |
| SN65HVD1781 | 1 | Mbps |
| SN65HVD1782 | 10 | |

| \(T_A\) | Operating free-air temperature (See Power Dissipation Characteristics) | 5-V supply | –40 | 105 | °C |
| 3.3-V supply | –40 | 125 | |
| \(T_J\) | Junction temperature | –40 | 150 | °C |

(1) By convention, the least positive (most negative) limit is designated as minimum in this data sheet.

7.5 Thermal Information

<table>
<thead>
<tr>
<th>THERMAL METRIC (^{(1)})</th>
<th><strong>SN65HVD178x</strong></th>
<th><strong>UNIT</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>D (SOIC)</strong></td>
<td><strong>P (PDIP)</strong></td>
<td></td>
</tr>
<tr>
<td>8 PINS</td>
<td>8 PINS</td>
<td></td>
</tr>
<tr>
<td>(R_{JA})</td>
<td>Junction-to-ambient thermal resistance</td>
<td>JEDEC high-K model</td>
</tr>
<tr>
<td>JEDEC low-K model</td>
<td>242</td>
<td>128</td>
</tr>
<tr>
<td>(R_{JC(top)})</td>
<td>Junction-to-case (top) thermal resistance</td>
<td>61</td>
</tr>
<tr>
<td>(R_{JB})</td>
<td>Junction-to-board thermal resistance</td>
<td>62</td>
</tr>
<tr>
<td>(\psi_{JT})</td>
<td>Junction-to-top characterization parameter</td>
<td>3.4</td>
</tr>
<tr>
<td>(\psi_{JB})</td>
<td>Junction-to-board characterization parameter</td>
<td>33.4</td>
</tr>
<tr>
<td>(R_{JC(bot)})</td>
<td>Junction-to-case (bottom) thermal resistance</td>
<td>N/A</td>
</tr>
</tbody>
</table>

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.
### 7.6 Electrical Characteristics

over operating-free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>( V_{OD} )</td>
<td>Driver differential output voltage magnitude</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>( R_L = 60 \Omega, 4.75 \text{ V} \leq V_{CC} \leq 12 \text{ V} )</td>
<td>1.5</td>
<td>1.4</td>
<td>T&lt;sub&gt;A&lt;/sub&gt; = 85°C</td>
<td></td>
</tr>
<tr>
<td></td>
<td>( R_L = 54 \Omega, 4.75 \text{ V} \leq V_{CC} \leq 5.25 \text{ V} )</td>
<td>1.7</td>
<td>2</td>
<td>T&lt;sub&gt;A&lt;/sub&gt; = 125°C</td>
<td></td>
</tr>
<tr>
<td></td>
<td>( R_L = 54 \Omega, 3.15 \text{ V} \leq V_{CC} \leq 3.45 \text{ V} )</td>
<td>0.8</td>
<td>1</td>
<td>T&lt;sub&gt;A&lt;/sub&gt; = 85°C</td>
<td></td>
</tr>
<tr>
<td></td>
<td>( R_L = 100 \Omega, 4.75 \text{ V} \leq V_{CC} \leq 5.25 \text{ V} )</td>
<td>2.2</td>
<td>2.5</td>
<td>T&lt;sub&gt;A&lt;/sub&gt; = 125°C</td>
<td></td>
</tr>
<tr>
<td>( \Delta V_{OD} )</td>
<td>Change in magnitude of driver differential output voltage</td>
<td>( R_L = 54 \Omega )</td>
<td>–50</td>
<td>0</td>
<td>50</td>
</tr>
<tr>
<td>( V_{OC(SS)} )</td>
<td>Steady-state common-mode output voltage</td>
<td>( V_{CC}/2 )</td>
<td>3</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>( \Delta V_{OC} )</td>
<td>Change in differential driver output common-mode voltage</td>
<td>–50</td>
<td>0</td>
<td>50</td>
<td>mV</td>
</tr>
<tr>
<td>( V_{OCPP} )</td>
<td>Peak-to-peak driver common-mode output voltage</td>
<td>Center of two 27-Ω load resistors</td>
<td>500</td>
<td>mV</td>
<td></td>
</tr>
<tr>
<td>( C_{OD} )</td>
<td>Differential output capacitance</td>
<td>23</td>
<td>pF</td>
<td></td>
<td></td>
</tr>
<tr>
<td>( V_{IT+} )</td>
<td>Positive-going receiver differential input voltage threshold</td>
<td>–100</td>
<td>–35</td>
<td>mV</td>
<td></td>
</tr>
<tr>
<td>( V_{IT–} )</td>
<td>Negative-going receiver differential input voltage threshold</td>
<td>–180</td>
<td>–150</td>
<td>mV</td>
<td></td>
</tr>
<tr>
<td>( V_{IVS} )</td>
<td>Receiver differential input voltage threshold hysteresis</td>
<td>( V_{IT+} - V_{IT–} )</td>
<td>30</td>
<td>50</td>
<td>mV</td>
</tr>
<tr>
<td>( V_{OH} )</td>
<td>Receiver high-level output voltage</td>
<td>( I_{OH} = –8 \text{ mA} )</td>
<td>0.2</td>
<td>0.4</td>
<td>V</td>
</tr>
<tr>
<td>( V_{OL} )</td>
<td>Receiver low-level output voltage</td>
<td>( I_{OL} = 8 \text{ mA} )</td>
<td>0.2</td>
<td>0.4</td>
<td>V</td>
</tr>
<tr>
<td>( I_{ILOGIC} )</td>
<td>Driver input, driver enable, and receiver enable input current</td>
<td>–50</td>
<td>50</td>
<td>μA</td>
<td></td>
</tr>
<tr>
<td>( I_{OZ} )</td>
<td>Receiver output high-impedance current</td>
<td>( V_O = 0 \text{ V} ) or ( V_{CC} ) RE at ( V_{CC} )</td>
<td>–1</td>
<td>1</td>
<td>μA</td>
</tr>
<tr>
<td>( I_{OS} )</td>
<td>Driver short-circuit output current</td>
<td>–200</td>
<td>200</td>
<td>mA</td>
<td></td>
</tr>
<tr>
<td>( I_{BUS} )</td>
<td>Bus input current (disabled driver)</td>
<td>( V_{CC} = 3.15 \text{ to } 5.5 \text{ V} ) or ( V_{CC} = 0 \text{ V}, \text{ DE at } 0 \text{ V} )</td>
<td>1780, 1781</td>
<td>75</td>
<td>100</td>
</tr>
<tr>
<td></td>
<td>( V_I = 12 \text{ V} )</td>
<td>1782</td>
<td>400</td>
<td>500</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td>( V_I = –7 \text{ V} )</td>
<td>1780, 1781</td>
<td>–60</td>
<td>–40</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td>( V_I = –7 \text{ V} )</td>
<td>1782</td>
<td>–400</td>
<td>–300</td>
<td>mA</td>
</tr>
<tr>
<td>( I_{CC} )</td>
<td>Supply current (quiescent)</td>
<td>4</td>
<td>6</td>
<td>mA</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Driver and receiver enabled</td>
<td>( DE = V_{CC}, \ RE = \text{ GND}, \text{ no load} )</td>
<td>3</td>
<td>5</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td>Driver enabled, receiver disabled</td>
<td>( DE = V_{CC}, \ RE = V_{CC}, \text{ no load} )</td>
<td>2</td>
<td>4</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td>Driver disabled, receiver enabled</td>
<td>( DE = \text{ GND}, \ RE = \text{ GND}, \text{ no load} )</td>
<td>0.15</td>
<td>1</td>
<td>μA</td>
</tr>
<tr>
<td></td>
<td>Drive and receiver disabled (standby mode)</td>
<td>( DE = \text{ GND}, \ D = \text{ open}, \ RE = V_{CC}, \text{ no load} )</td>
<td>0.15</td>
<td>1</td>
<td>μA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( T&lt;sub&gt;A&lt;/sub&gt; = 85°C )</td>
<td>12</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Supply current (dynamic) See Typical Characteristics
7.7 Power Dissipation Characteristics

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$P_D$ Power dissipation</td>
<td>$V_{CC} = 5.5 \text{ V}$, $T_J = 150^\circ \text{C}$, $R_L = 300 \Omega$, $C_L = 50 \text{ pF (driver)}$, $C_L = 15 \text{ pF (receiver)}$ 5-V supply, unterminated$^{(1)}$</td>
<td>290</td>
<td>mW</td>
</tr>
<tr>
<td>$T_{SD}$ Thermal-shutdown junction temperature</td>
<td></td>
<td>170</td>
<td>°C</td>
</tr>
</tbody>
</table>

$^{(1)}$ Driver and receiver enabled, 50% duty cycle square-wave signal at signaling rate: 1 Mbps.

7.8 Switching Characteristics

over recommended operating conditions (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>DRIVER (SN65HVD1780)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$t_r$, $t_f$ Driver differential output rise or fall time</td>
<td>$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$, See Figure 8</td>
<td>0.4</td>
<td>1.4</td>
<td>1.8</td>
<td>µs</td>
</tr>
<tr>
<td>$t_{PHL}$, $t_{PLH}$ Driver propagation delay</td>
<td>$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$, See Figure 8</td>
<td>0.8</td>
<td>2</td>
<td></td>
<td>µs</td>
</tr>
<tr>
<td>$t_{SK(P)}$ Driver differential output pulse skew, $</td>
<td>t_{PHL} - t_{PLH}</td>
<td>$</td>
<td>$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$, See Figure 8</td>
<td>20</td>
<td>250</td>
</tr>
<tr>
<td>$t_{PH2}$, $t_{PL2}$ Driver disable time</td>
<td>See Figure 9 and Figure 10</td>
<td>0.1</td>
<td>5</td>
<td></td>
<td>µs</td>
</tr>
<tr>
<td>$t_{PZ2}$, $t_{PL2}$ Driver enable time</td>
<td>Receiver enabled See Figure 9 and Figure 10</td>
<td>0.2</td>
<td>3</td>
<td></td>
<td>µs</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>DRIVER (SN65HVD1781)</th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>$t_r$, $t_f$ Driver differential output rise or fall time</td>
<td>$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$, See Figure 8</td>
<td>50</td>
<td>300</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$t_{PHL}$, $t_{PLH}$ Driver propagation delay</td>
<td>$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$, See Figure 8</td>
<td>200</td>
<td></td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$t_{SK(P)}$ Driver differential output pulse skew, $</td>
<td>t_{PHL} - t_{PLH}</td>
<td>$</td>
<td>$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$, See Figure 8</td>
<td>25</td>
<td></td>
</tr>
<tr>
<td>$t_{PH2}$, $t_{PL2}$ Driver disable time</td>
<td>See Figure 9 and Figure 10</td>
<td>3</td>
<td></td>
<td></td>
<td>µs</td>
</tr>
<tr>
<td>$t_{PZ2}$, $t_{PL2}$ Driver enable time</td>
<td>Receiver enabled See Figure 9 and Figure 10</td>
<td>300</td>
<td></td>
<td></td>
<td>ns</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>DRIVER (SN65HVD1782)</th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>$t_r$, $t_f$ Driver differential output rise or fall time</td>
<td>$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$</td>
<td>All $V_{CC}$ and Temperature $V_{CC} &gt; 4.5 \text{ V}$ and $T &lt; 105^\circ \text{C}$</td>
<td></td>
<td>50</td>
<td>ns</td>
</tr>
<tr>
<td>$t_{PHL}$, $t_{PLH}$ Driver propagation delay</td>
<td>$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$, See Figure 8</td>
<td>55</td>
<td></td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$t_{SK(P)}$ Driver differential output pulse skew, $</td>
<td>t_{PHL} - t_{PLH}</td>
<td>$</td>
<td>$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$, See Figure 8</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>$t_{PH2}$, $t_{PL2}$ Driver disable time</td>
<td>See Figure 9 and Figure 10</td>
<td>3</td>
<td></td>
<td></td>
<td>µs</td>
</tr>
</tbody>
</table>
## Switching Characteristics (continued)

over recommended operating conditions (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t_{PZH}, t_{PZL}$ Driver enable time</td>
<td>Receiver enabled: See Figure 9 and Figure 10</td>
<td>300</td>
<td></td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td></td>
<td>Receiver disabled: See Figure 9 and Figure 10</td>
<td>9</td>
<td></td>
<td></td>
<td>µs</td>
</tr>
<tr>
<td><strong>RECEIVER</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$t_r, t_f$ Receiver output rise or fall time</td>
<td>$C_L = 15$ pF, See Figure 11</td>
<td>All devices</td>
<td>4</td>
<td>15</td>
<td>ns</td>
</tr>
<tr>
<td>$t_{PHL}, t_{PLH}$ Receiver propagation delay time</td>
<td>$C_L = 15$ pF, See Figure 11</td>
<td>SN65HVD1780, SN65HVD1781</td>
<td>100</td>
<td>200</td>
<td>ns</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$t_{SK(P)}$ Receiver output pulse skew, $</td>
<td>t_{PHL} - t_{PLH}</td>
<td>$</td>
<td>$C_L = 15$ pF, See Figure 11</td>
<td>SN65HVD1780, SN65HVD1781</td>
<td>6</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$t_{PLZ}, t_{PHZ}$ Receiver disable time</td>
<td>Driver enabled, See Figure 12</td>
<td>15</td>
<td>100</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$t_{PZL(1)}, t_{PZH(1)}$ Receiver enable time</td>
<td>Driver enabled, See Figure 12</td>
<td>80</td>
<td>300</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$t_{PZL(2)}, t_{PZH(2)}$ Receiver enable time</td>
<td>Driver disabled, See Figure 13</td>
<td>3</td>
<td>9</td>
<td></td>
<td>µs</td>
</tr>
</tbody>
</table>
### 7.9 Typical Characteristics

<table>
<thead>
<tr>
<th>V (VCC)</th>
<th>Differential Output (VOD)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3.15</td>
<td>0.5</td>
</tr>
<tr>
<td>3.3</td>
<td>0.7</td>
</tr>
<tr>
<td>4.5</td>
<td>0.9</td>
</tr>
<tr>
<td>5.5</td>
<td>1.1</td>
</tr>
<tr>
<td>3.3</td>
<td>1.3</td>
</tr>
<tr>
<td>5</td>
<td>1.5</td>
</tr>
<tr>
<td>5.5</td>
<td>1.7</td>
</tr>
<tr>
<td>3.3</td>
<td>1.9</td>
</tr>
<tr>
<td>5</td>
<td>2.1</td>
</tr>
<tr>
<td>5.5</td>
<td>2.3</td>
</tr>
</tbody>
</table>

- **VCC** = Supply Voltage (V)  
- **R** = 50 Ω  
- **C** = 50 pF  
- **L** = 54 Ω  
- **V** = 3.3 V  
- **V** = 5 V  
- **TA** = 25°C  
- **DE** at **VCC**  
- **D** at **VCC**  

#### Figures

- **Figure 1. Driver Output Current vs Supply Voltage**
- **Figure 2. RMS Supply Current vs Signaling Rate**
- **Figure 3. Differential Output Voltage vs Differential Load Current**
- **Figure 4. SN65HVD1782 Rise or Fall Time**
- **Figure 5. SN65HVD1780 Differential Output Amplitude and Transition Time vs Supply Voltage**
8 Parameter Measurement Information

Input generator rate is 100 kbps, 50% duty cycle, rise or fall time is less than 6 ns, output impedance is 50 Ω.

Figure 6. Measurement of Driver Differential Output Voltage With Common-Mode Load

Figure 7. Measurement of Driver Differential and Common-Mode Output With RS-485 Load

Figure 8. Measurement of Driver Differential Output Rise and Fall Times and Propagation Delays

NOTE: D at 3 V to test non-inverting output, D at 0 V to test inverting output.

Figure 9. Measurement of Driver Enable and Disable Times With Active High Output and Pulldown Load
Figure 10. Measurement of Driver Enable and Disable Times With Active-Low Output and Pullup Load

Figure 11. Measurement of Receiver Output Rise and Fall Times and Propagation Delays
Parameter Measurement Information (continued)

![Diagram](image-url)

**Figure 12. Measurement of Receiver Enable and Disable Times With Driver Enabled**
Parameter Measurement Information (continued)

![Circuit Diagram]

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Figure 13. SN65HVD1781 Measurement of Receiver Enable Times With Driver Disabled
Parameter Measurement Information (continued)

8.1 Equivalent Input Schematic

When the input digital pins float, internal high value resistors pull D/REB pins to \( V_{CC} \) and DE pin to GND to place the device into known states. If the voltage level of D/REB input pins is higher than that of power rail, input current can flow through the input resistor and pull up resistor to \( V_{CC} \).

![Equivalent Input Schematic Diagrams](image-url)

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Figure 14. Equivalent Input Schematic Diagrams
9 Detailed Description

9.1 Overview

The SN65HVD178x devices are half-duplex RS-485 transceivers available in three speed grades suitable for data transmission up to 115 kbps, 1 Mbps, and 10 Mbps.

These devices feature a wide common-mode operating range and bus-pin fault protection up to ±70 V. Each device has an active-HIGH driver enable and active-LOW receiver enable. A standby current of less than 1 µA can be achieved by disabling both driver and receiver.

9.2 Functional Block Diagram

9.3 Feature Description

Internal ESD protection circuits protect the transceiver bus terminals against ±16 kV human body model (HBM) electrostatic discharges.

Device operation is specified over a wide temperature range from –40°C to 125°C.

9.3.1 70-V Fault Protection

The SN65HVD178x family of RS-485 transceivers is designed to survive bus pin faults up to ±70 V. The SN65HVD1782 will not survive a bus pin fault with a direct short to voltages above 30 V when:

- The device is powered on, AND
- The driver is enabled (DE = HIGH), AND
  - D = HIGH AND the bus fault is applied to the A pin, OR
  - D = LOW AND the bus fault is applied to the B pin

Under other conditions, the device will survive shorts to bus pin faults up to ±70 V. Table 1 summarizes the conditions under which the device may be damaged, and the conditions under which the device will not be damaged.

<table>
<thead>
<tr>
<th>POWER</th>
<th>DE</th>
<th>D</th>
<th>A</th>
<th>B</th>
<th>RESULTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>OFF</td>
<td>X</td>
<td>X</td>
<td>–70 V &lt; V_A &lt; 70 V</td>
<td>–70 V &lt; V_B &lt; 70 V</td>
<td>Device survives</td>
</tr>
<tr>
<td>ON</td>
<td>L</td>
<td>X</td>
<td>–70 V &lt; V_A &lt; 70 V</td>
<td>–70 V &lt; V_B &lt; 70 V</td>
<td>Device survives</td>
</tr>
<tr>
<td>ON</td>
<td>H</td>
<td>L</td>
<td>–70 V &lt; V_A &lt; 70 V</td>
<td>–70 V &lt; V_B &lt; 30 V</td>
<td>Device survives</td>
</tr>
<tr>
<td>ON</td>
<td>H</td>
<td>L</td>
<td>–70 V &lt; V_A &lt; 70 V</td>
<td>30 V &lt; V_B</td>
<td>Damage may occur</td>
</tr>
<tr>
<td>ON</td>
<td>H</td>
<td>H</td>
<td>–70 V &lt; V_A &lt; 30 V</td>
<td>–70 V &lt; V_B &lt; 30 V</td>
<td>Device survives</td>
</tr>
<tr>
<td>ON</td>
<td>H</td>
<td>H</td>
<td>30 V &lt; V_A</td>
<td>–70 V &lt; V_B &lt; 30 V</td>
<td>Damage may occur</td>
</tr>
</tbody>
</table>
9.3.2 Receiver Failsafe

The SN65HVD178x family of half-duplex transceivers provides internal biasing of the receiver input thresholds in combination with large input-threshold hysteresis. At a positive input threshold of $V_{IT+} = -35 \text{ mV}$ and an input hysteresis of $V_{HYS} = 30 \text{ mV}$, the receiver output remains logic high under bus-idle, bus-short, or open bus conditions in the presence of up to $130 \text{ mV}_{pp}$ differential noise without the need for external failsafe biasing resistors.

9.3.3 Hot-Plugging

These devices are designed to operate in "hot swap" or "hot pluggable" applications. Key features for hot-pluggable applications are power-up and power-down glitch-free operation, default disabled input and output pins, and receiver failsafe.

As shown in Figure 1, an internal power-on reset circuit keeps the driver outputs in a high-impedance state until the supply voltage has reached a level at which the device will reliably operate. This ensures that no problems will occur on the bus pin outputs as the power supply turns on or turns off.

As shown in Device Functional Modes, the enable inputs have the feature of default disable on both the driver enable and receiver enable. This ensures that the device will neither drive the bus nor report data on the R pin until the associated controller actively drives the enable pins.

9.4 Device Functional Modes

When the driver enable pin, DE, is logic high, the differential outputs A and B follow the logic states at data input D. A logic high at D causes A to turn high and B to turn low. In this case the differential output voltage defined as $V_{OD} = V_A - V_B$ is positive. When D is low, the output states reverse, B turns high, A becomes low, and $V_{OD}$ is negative.

When DE is low, both outputs turn high-impedance. In this condition the logic state at D is irrelevant. The DE pin has an internal pulldown resistor to ground, thus, when left open, the driver is disabled (high-impedance) by default. The D pin has an internal pullup resistor to $V_{CC}$, thus, when left open while the driver is enabled, output A turns high and B turns low.

<table>
<thead>
<tr>
<th>INPUT</th>
<th>ENABLE</th>
<th>OUTPUTS</th>
<th>FUNCTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>DE</td>
<td>A</td>
<td>B</td>
</tr>
<tr>
<td>H</td>
<td>H</td>
<td>H</td>
<td>L</td>
</tr>
<tr>
<td>L</td>
<td>H</td>
<td>L</td>
<td>H</td>
</tr>
<tr>
<td>X</td>
<td>L</td>
<td>Z</td>
<td>Z</td>
</tr>
<tr>
<td>X</td>
<td>OPEN</td>
<td>Z</td>
<td>Z</td>
</tr>
<tr>
<td>OPEN</td>
<td>H</td>
<td>H</td>
<td>L</td>
</tr>
</tbody>
</table>

\(^{(1)}\) When both the driver and receiver are disabled, the device enters a low-power standby mode.

When the receiver enable pin, RE, is logic low, the receiver is enabled. When the differential input voltage defined as $V_{ID} = V_A - V_B$ is positive and higher than the positive input threshold, $V_{IT+}$, the receiver output, R, turns high. When $V_{ID}$ is negative and lower than the negative input threshold, $V_{IT-}$, the receiver output, R, turns low. If $V_{ID}$ is between $V_{IT+}$ and $V_{IT-}$, the output is indeterminate.

When $RE$ is logic high or left open, the receiver output is high-impedance and the magnitude and polarity of $V_{ID}$ are irrelevant. Internal biasing of the receiver inputs causes the output to go failsafe-high when the transceiver is disconnected from the bus (open-circuit), the bus lines are shorted (short-circuit), or the bus is not actively driven (idle bus).
Table 3. Receiver Function Table

<table>
<thead>
<tr>
<th>DIFFERENTIAL INPUT</th>
<th>ENABLE</th>
<th>OUTPUT</th>
<th>FUNCTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{ID} = V_A - V_B$</td>
<td>RE</td>
<td>R</td>
<td></td>
</tr>
<tr>
<td>$V_{IT-} &lt; V_{ID}$</td>
<td>L</td>
<td>H</td>
<td>Receive valid bus high</td>
</tr>
<tr>
<td>$V_{IT-} &lt; V_{ID} &lt; V_{IT+}$</td>
<td>L</td>
<td>?</td>
<td>Indeterminate bus state</td>
</tr>
<tr>
<td>$V_{ID} &lt; V_{IT-}$</td>
<td>L</td>
<td>L</td>
<td>Receive valid bus low</td>
</tr>
<tr>
<td>X</td>
<td>H</td>
<td>Z</td>
<td>Receiver disabled (1)</td>
</tr>
<tr>
<td>X</td>
<td>OPEN</td>
<td>Z</td>
<td>Receiver disabled by default (1)</td>
</tr>
<tr>
<td>Open-circuit bus</td>
<td>L</td>
<td>H</td>
<td>Fail-safe high output</td>
</tr>
<tr>
<td>Short-circuit bus</td>
<td>L</td>
<td>H</td>
<td>Fail-safe high output</td>
</tr>
<tr>
<td>Idle (terminated) bus</td>
<td>L</td>
<td>H</td>
<td>Fail-safe high output</td>
</tr>
</tbody>
</table>

(1) When both the driver and receiver are disabled, the device enters a low-power standby mode.
10 Application and Implementation

**NOTE**
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI’s customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

10.1 Application Information

The SN65HVD178x devices are half-duplex RS-485 transceivers commonly used for asynchronous data transmissions. The driver and receiver enable pins allow for the configuration of different operating modes.

Using independent enable lines provides the most flexible control as it allows for the driver and the receiver to be turned on and off individually. While this configuration requires two control lines, it allows for selective listening into the bus traffic, whether the driver is transmitting data or not.

Combining the enable signals simplifies the interface to the controller by forming a single direction-control signal. In this configuration, the transceiver operates as a driver when the direction-control line is high, and as a receiver when the direction-control line is low.

Additionally, only one line is required when connecting the receiver-enable input to ground and controlling only the driver-enable input. In this configuration, a node not only receives the data from the bus, but also the data it sends and can verify that the correct data have been transmitted.

10.2 Typical Application

An RS-485 bus consists of multiple transceivers connecting in parallel to a bus cable. To eliminate line reflections, each cable end is terminated with a termination resistor, $R_T$, whose value matches the characteristic impedance, $Z_0$, of the cable. This method, known as parallel termination, allows for higher data rates over longer cable length.
Typical Application (continued)

10.2.1 Design Requirements

RS-485 is a robust electrical standard suitable for long-distance networking that may be used in a wide range of applications with varying requirements, such as distance, data rate, and number of nodes.

10.2.1.1 Data Rate and Bus Length

There is an inverse relationship between data rate and bus length, meaning the higher the data rate, the shorter the cable length; and conversely, the lower the data rate, the longer the cable may be without introducing data errors. While most RS-485 systems use data rates from 10 kbps to 100 kbps, some applications require data rates up to 250 kbps at distances of 4000 feet and longer. Longer distances are possible by allowing for small signal jitter of up to 5% or 10%.

![Figure 17. Cable Length vs Data Rate Characteristic](image)

Even higher data rates are achievable (for example, 10 Mbps for the SN65HVD1782) in cases where the interconnect is short enough (or has suitably low attenuation at signal frequencies) to not degrade the data.

10.2.1.2 Stub Length

When connecting a node to the bus, the distance between the transceiver inputs and the cable trunk, known as the stub, should be as short as possible. Stubs present a non-terminated piece of bus line which can introduce reflections as the length of the stub increases. As a general guideline, the electrical length, or round-trip delay, of a stub should be less than one-tenth of the rise time of the driver, thus giving a maximum physical stub length as shown in Equation 1.

\[ L_{\text{stub}} \leq 0.1 \times t_r \times v \times c \]

where
- \( t_r \) is the 10/90 rise time of the driver
- \( c \) is the speed of light (3 × 10^8 m/s)
- \( v \) is the signal velocity of the cable or trace as a factor of \( c \)

10.2.1.3 Bus Loading

The RS-485 standard specifies that a compliant driver must be able to drive 32 unit loads (UL), where 1 unit load represents a load impedance of approximately 12 kΩ. The SN65HVD1780 and SN65HVD1781 are 1/10 unit load transceivers, and so up to 320 can be placed on a common bus. The SN65HVD1782 is a 1/2 unit load transceiver, so up to 64 can share a bus.
Typical Application (continued)

10.2.1.4 Receiver Failsafe

The differential receivers of the SN65HVD178x family are “failsafe” to invalid bus states caused by:
- Open bus conditions, such as a disconnected connector
- Shorted bus conditions, such as cable damage shorting the twisted-pair together
- Idle bus conditions that occur when no driver on the bus is actively driving

In any of these cases, the differential receiver will output a failsafe logic High state so that the output of the receiver is not indeterminate.

Receiver failsafe is accomplished by offsetting the receiver thresholds such that the “input indeterminate” range does not include zero volts differential. To comply with the RS-422 and RS-485 standards, the receiver output must output a High when the differential input \( V_{ID} \) is more positive than +200 mV, and must output a Low when \( V_{ID} \) is more negative than –200 mV. The receiver parameters which determine the failsafe performance are \( V_{IT(+)} \), \( V_{IT(-)} \), and \( V_{HYS} \) (the separation between \( V_{IT(+)} \) and \( V_{IT(-)} \)). As shown in the Electrical Characteristics, differential signals more negative than –200 mV will always cause a Low receiver output, and differential signals more positive than +200 mV will always cause a High receiver output.

When the differential input signal is close to zero, it is still above the maximum \( V_{IT(+)} \) threshold of –35 mV, and the receiver output will be High. Only when the differential input is more than \( V_{HYS} \) below \( V_{IT(+)} \) will the receiver output transition to a Low state. Therefore, the noise immunity of the receiver inputs during a bus fault condition includes the receiver hysteresis value, \( V_{HYS} \), as well as the value of \( V_{IT(+)} \).

![Figure 18. SN65HVD178x Noise Immunity Under Bus Fault Conditions](image)

10.2.2 Detailed Design Procedure

10.2.2.1 Custom Design with WEBENCH® Tools

Click here to create a custom design using the SN65HVD178x device with the WEBENCH® Power Designer.

1. Start by entering your \( V_{IN} \), \( V_{OUT} \), and \( I_{OUT} \) requirements.
2. Optimize your design for key parameters like efficiency, footprint and cost using the optimizer dial and compare this design with other possible solutions from Texas Instruments.
3. The WEBENCH Power Designer provides you with a customized schematic along with a list of materials with real time pricing and component availability.
4. In most cases, you will also be able to:
   - Run electrical simulations to see important waveforms and circuit performance
   - Run thermal simulations to understand the thermal performance of your board
   - Export your customized schematic and layout into popular CAD formats
   - Print PDF reports for the design, and share your design with colleagues

Although the SN65HVD178x family is internally protected against human-body-model ESD strikes up to 16 kV, additional protection against higher-energy transients can be provided at the application level by implementing external protection devices.
Figure 19. RS-485 Transceiver With External Transient Protection

Figure 19 shows a protection circuit intended to withstand 8-kV IEC ESD (per IEC 61000-4-2) as well as 4-kV EFT (per IEC 61000-4-4).

Table 4. Bill of Materials

<table>
<thead>
<tr>
<th>DEVICE</th>
<th>FUNCTION</th>
<th>ORDER NUMBER</th>
<th>MANUFACTURER</th>
</tr>
</thead>
<tbody>
<tr>
<td>XCVR</td>
<td>RS-485 Transceiver</td>
<td>SN65HVD1781</td>
<td>TI</td>
</tr>
<tr>
<td>R1,R2</td>
<td>10 Ω, Pulse-Proof Thick-Film Resistor</td>
<td>CRCW0603010RJNEAHP</td>
<td>Vishay</td>
</tr>
<tr>
<td>TVS</td>
<td>Bidirectional 600-W Transient Suppressor</td>
<td>SMBJ43CA</td>
<td>Littelfuse</td>
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</tbody>
</table>

10.2.3 Application Curve

Figure 20. SN65HVD1780 Differential Output at 115 kbps
11 Power Supply Recommendations

To assure reliable operation at all data rates and supply voltages, each supply should be buffered with a 100-nF ceramic capacitor located as close to the supply pins as possible. The TPS76350 is a linear voltage regulator suitable for the 5-V supply.

12 Layout

12.1 Layout Guidelines

On-chip IEC-ESD protection is good for laboratory and portable equipment but often insufficient for EFT and surge transients occurring in industrial environments. Therefore robust and reliable bus node design requires the use of external transient protection devices.

Because ESD and EFT transients have a wide-frequency bandwidth from approximately 3 MHz to 3 GHz, high-frequency layout techniques must be applied during PCB design.

1. Place the protection circuitry close to the bus connector to prevent noise transients from entering the board.
2. Use VCC and ground planes to provide low-inductance. Note that high-frequency currents follow the path of least inductance and not the path of least impedance.
3. Design the protection components into the direction of the signal path. Do not force the transient currents to divert from the signal path to reach the protection device.
4. Apply 100-nF to 220-nF bypass capacitors as close as possible to the VCC pins of the transceiver, UART, or controller ICs on the board.
5. Use at least two vias for VCC and ground connections of bypass capacitors and protection devices to minimize effective via-inductance.
6. Use 1-kΩ to 10-kΩ pullup and pulldown resistors for enable lines to limit noise currents in these lines during transient events.
7. While pure TVS protection is sufficient for surge transients up to 1 kV, higher transients require metal-oxide varistors (MOVs) which reduce the transients to a few hundred volts of clamping voltage, and transient blocking units (TBUs) that limit transient current to less than 1 mA.

12.2 Layout Example

![SN65HVD178x Half-Duplex Layout Example](image)

Figure 21. SN65HVD178x Half-Duplex Layout Example
13 Device and Documentation Support

13.1 Device Support

13.1.1 Custom Design with WEBENCH® Tools

Click here to create a custom design using the SN65HVD178x device with the WEBENCH® Power Designer.

1. Start by entering your \( V_{IN} \), \( V_{OUT} \), and \( I_{OUT} \) requirements.
2. Optimize your design for key parameters like efficiency, footprint and cost using the optimizer dial and compare this design with other possible solutions from Texas Instruments.
3. The WEBENCH Power Designer provides you with a customized schematic along with a list of materials with real time pricing and component availability.
4. In most cases, you will also be able to:
   - Run electrical simulations to see important waveforms and circuit performance
   - Run thermal simulations to understand the thermal performance of your board
   - Export your customized schematic and layout into popular CAD formats
   - Print PDF reports for the design, and share your design with colleagues
5. Get more information about WEBENCH tools at www.ti.com/WEBENCH.

13.1.2 Third-Party Products Disclaimer

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13.2 Documentation Support

13.2.1 Related Documentation

For related documentation, see the following:

SN65HVD17xx Fault-Protected RS-485 Transceivers With Extended Common-Mode Range, SLLS872

13.3 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

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13.4 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on Alert me to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.
13.5 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

**TI E2E™ Online Community**  *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support**  *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

13.6 Trademarks

E2E is a trademark of Texas Instruments.
WEBENCH is a registered trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

13.7 Electrostatic Discharge Caution

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

13.8 Glossary

**SLYZ022 — TI Glossary.**
This glossary lists and explains terms, acronyms, and definitions.

14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.
## PACKAGING INFORMATION

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</table>

(1) The marketing status values are defined as follows:
- **ACTIVE**: Product device recommended for new designs.
- **LIFEBUY**: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
- **NRND**: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS**: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt**: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green**: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) **MSL, Peak Temp.** - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) **Lead/Ball Finish** - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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**OTHER QUALIFIED VERSIONS OF SN65HVD1780, SN65HVD1781, SN65HVD1782**:

- **Automotive**: SN65HVD1780-Q1, SN65HVD1781-Q1, SN65HVD1782-Q1

**NOTE**: Qualified Version Definitions:

- **Automotive** - Q100 devices qualified for high-reliability automotive applications targeting zero defects
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All dimensions are nominal.
### TAPE AND REEL BOX DIMENSIONS

*All dimensions are nominal*

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NOTES:  
A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Falls within JEDEC MS-001 variation BA.
NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.
NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE: 8X

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.
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