





TEXAS INSTRUMENTS

SCES934A – SEPTEMBER 2021 – REVISED DECEMBER 2021

# SN74LXC1T45 Single-Bit Dual-Supply Bus Transceiver With Configurable Level Shifting

# 1 Features

- Fully configurable dual-rail design allows each port to operate from 1.1 V to 5.5 V
- Robust, glitch-free power supply sequencing
- Up to 420-Mbps support for 3.3 V to 5.0 V
- Schmitt-trigger inputs allow for slow or noisy inputs
- I/O's with integrated dynamic pull-down resistors help reduce external component count
- Control inputs with integrated static pull-down resistors allow for floating control inputs
- High drive strength (up to 32 mA at 5 V)
- Low power consumption
  - 3-µA maximum (25°C)
  - 6-µA maximum (–40°Ć to 125°C)
- V<sub>CC</sub> isolation and V<sub>cc</sub> disconnect (I<sub>off-float</sub>) feature
  - If either V<sub>CC</sub> supply is < 100 mV or disconnected, all I/O's get pulled-down and then become high-impedance
- I<sub>off</sub> supports partial-power-down mode operation
- Compatible with LVC family level shifters
- Control logic (DIR and  $\overline{\text{OE}})$  are referenced to  $V_{\text{CCA}}$
- Operating temperature from –40°C to +125°C
- Latch-up performance exceeds 100 mA per JESD 78, class II
- ESD protection exceeds JESD 22
  - 4000-V human-body model
  - 1000-V charged-device model

# **2** Applications

- Eliminate slow or noisy input signals
- Driving indicator LEDs or buzzers
- Debouncing a mechanical switch
- · General purpose I/O level shifting

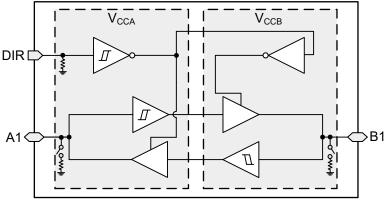
### **3 Description**

SN74LXC1T45 The is а 1-bit. dual-supply noninverting bidirectional voltage level translation device. The I/O pin A and control pin (DIR) are referenced to  $V_{CCA}$  logic levels, and the I/O pin B are referenced to V<sub>CCB</sub> logic levels. The A pin is able to accept I/O voltages ranging from 1.1 V to 5.5 V, while the B pin can accept I/O voltages from 1.1 V to 5.5 V. A high on DIR allows data transmission from A to B and a low on DIR allows data transmission from B to A. See Device Functional Modes for a summary of the operation of the control logic.

#### Device Information <sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)									
SN74LXC1T45DRL	SOT (6)	1.60 mm × 1.20 mm									
SN74LXC1T45DRY	SON (6)	1.45 mm × 1.00 mm									
SN74LXC1T45DBV	SOT-23 (6)	2.90 mm × 1.60 mm									
SN74LXC1T45DCK	SC70 (6)	2.00 mm × 1.25 mm									
SN74LXC1T45DTQ	X2SON (6)	1.00 mm × 0.80 mm									

(1) For all available packages, see the orderable addendum at the end of the data sheet.



SN74LXC1T45 Block Diagram



# **Table of Contents**

1 Features1	
2 Applications1	
3 Description1	
4 Revision History2	
5 Pin Configuration and Functions	
6 Specifications4	
6.1 Absolute Maximum Ratings4	
6.2 ESD Ratings4	
6.3 Recommended Operating Conditions5	
6.4 Thermal Information5	
6.5 Electrical Characteristics6	
6.6 Switching Characteristics, V <sub>CCA</sub> = 1.2 ± 0.1 V9	
6.7 Switching Characteristics, V <sub>CCA</sub> = 1.5 ± 0.1 V 10	
6.8 Switching Characteristics, $V_{CCA} = 1.8 \pm 0.15 V \dots 11$	
6.9 Switching Characteristics, $V_{CCA} = 2.5 \pm 0.2 V \dots 12$	
6.10 Switching Characteristics, $V_{CCA} = 3.3 \pm 0.3 V \dots 13$	
6.11 Switching Characteristics, $V_{CCA} = 5.0 \pm 0.5 V \dots 14$	
6.12 Switching Characteristics: T <sub>sk</sub> , T <sub>MAX</sub> 15	
6.13 Operating Characteristics15	
6.14 Typical Characteristics16	
7 Parameter Measurement Information17	
7.1 Load Circuit and Voltage Waveforms17	
8 Detailed Description19	

8.1 Overview	.19
8.2 Functional Block Diagram	. 19
8.3 Feature Description.	
8.4 Device Functional Modes	
9 Application and Implementation	.23
9.1 Application Information	
9.2 Enable Times	
9.3 Typical Application	
10 Power Supply Recommendations	
11 Layout	
11.1 Layout Guidelines	. 24
11.2 Layout Example	
12 Device and Documentation Support	
12.1 Device Support	. 25
12.2 Documentation Support	
12.3 Receiving Notification of Documentation Updates.	.25
12.4 Support Resources	. 25
12.5 Trademarks	
12.6 Electrostatic Discharge Caution	.25
12.7 Glossary	.25
13 Mechanical, Packaging, and Orderable	
Information	. 25

### **4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Cł	nanges from Revision * (September 2021) to Revision A (December 2021)	Page
•	Changed the status of the data sheet from: Advanced Information to: Production Data	1



# **5** Pin Configuration and Functions

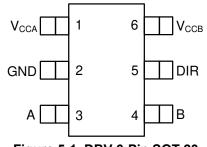
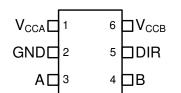


Figure 5-1. DBV 6-Pin SOT-23 Top View





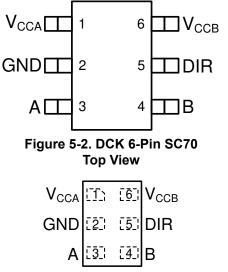


Figure 5-4. DRY Package Preview 6-Pin SON Top View

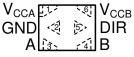


Figure 5-5. DTQ Package Preview 6-Pin X2SON Transparent Top View

PIN								
NAME	DBV, DCK, DRL, DRY, DTQ	TYPE	DESCRIPTION					
A	3	I/O	Input or output A. Referenced to V <sub>CCA</sub> .					
В	4	I/O	Input or output B. Referenced to V <sub>CCB</sub> .					
DIR	5	I	Direction-control signal for all ports. Referenced to V <sub>CCA</sub> .					
GND	2	—	Ground.					
DIR	5	I	Direction-control signal for all ports. Referenced to V <sub>CCA</sub> .					
V <sub>CCA</sub>	1	—	A-port supply voltage. 1.1 V $\leq$ V <sub>CCA</sub> $\leq$ 5.5 V.					
V <sub>CCB</sub>	6	_	B-port supply voltage. 1.1 V $\leq$ V <sub>CCB</sub> $\leq$ 5.5 V.					

#### Table 5-1. Pin Functions



### 6 Specifications

#### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

			MIN	MAX	UNIT	
V <sub>CCA</sub>	Supply voltage A		-0.5	6.5	V	
V <sub>CCB</sub>	Supply voltage B		-0.5	6.5	V	
		I/O Ports (A Port)	-0.5	6.5		
VI	Input Voltage <sup>(2)</sup>	I/O Ports (B Port)	-0.5	6.5	V	
V <sub>ССВ</sub> Su           V1         Inp           V0         Vo           V0         Vo           Inp         Inp           Inp         Inp		Control Inputs	-0.5	6.5		
V	Voltage applied to any output in the high-impedance or power-off	A Port	-0.5	6.5	V	
vo	state <sup>(2)</sup>	B Port	-0.5	6.5	v	
V	Voltage explicit to any extruction the high or law state $\binom{2}{3}$	A Port	-0.5	V <sub>CCA</sub> + 0.5	V	
v <sub>o</sub>	Voltage applied to any output in the high or low state <sup>(2) (3)</sup>	B Port	-0.5	V <sub>CCB</sub> + 0.5	V	
I <sub>IK</sub>	Input clamp current	V <sub>1</sub> < 0	-50		mA	
I <sub>OK</sub>	Output clamp current	V <sub>O</sub> < 0	-50		mA	
I <sub>O</sub>	Continuous output current	·	-50	50	mA	
	Continuous current through V <sub>CC</sub> or GND		-200	200	mA	
Tj	Junction Temperature		150	°C		
T <sub>stg</sub>	Storage temperature		-65	150	°C	

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions If briefly ooperating outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, this device may not sustain damage, but it may not be fully functional. Operating the device in this manner may affect device reliability, functionality, performance, and shorten the device lifetime.

(2) The input voltage and output negative-voltage ratings may be exceeded if the input and output current ratings are observed.

(3) The output positive-voltage rating may be exceeded up to 6.5 V maximum if the output current rating is observed.

#### 6.2 ESD Ratings

		VALUE	UNIT
V	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>		V
V(ESD	Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	±1000	V

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



#### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted) (1) (2) (3)

				MIN	MAX	UNIT	
V <sub>CCA</sub>	Supply voltage A			1.1	5.5	V	
V <sub>CCB</sub>	Supply voltage B			1.1	5.5	V	
			V <sub>CCO</sub> = 1.1 V		-0.1		
			V <sub>CCO</sub> = 1.4 V		-4		
		urront	V <sub>CCO</sub> = 1.65 V		-8	mA	
I <sub>OH</sub>	High-level output current		V <sub>CCO</sub> = 2.3 V		-12	IIIA	
			V <sub>CCO</sub> = 3 V		-24		
			V <sub>CCO</sub> = 4.5 V		-32		
			V <sub>CCO</sub> = 1.1 V		0.1		
			V <sub>CCO</sub> = 1.4 V		4		
			V <sub>CCO</sub> = 1.65 V		8		
I <sub>OL</sub>	Low-level output c	urrent	V <sub>CCO</sub> = 2.3 V		12	mA	
			V <sub>CCO</sub> = 3 V		24		
			V <sub>CCO</sub> = 4.5 V		32		
VI	Input voltage <sup>(3)</sup>			0	5.5	V	
V	Output voltoga	Active State				v	
Vo	Output voltage	Tri-State		0	5.5	V	
T <sub>A</sub>	Operating free-air	temperature		-40	125	°C	

(1)  $V_{CCI}$  is the  $V_{CC}$  associated with the input port.

(2)  $V_{CCO}$  is the  $V_{CC}$  associated with the output port.

(3) All control inputs and data I/Os of this device have weak pulldowns to ensure the line is not floating when undefined external to the device. The input leakage from these weak pulldowns is defined by the I<sub>I</sub> specification indicated under the *Electrical Characteristics*.

#### 6.4 Thermal Information

		SN74LXC1T45							
	THERMAL METRIC <sup>(1)</sup>	DBV (SOT-23)	DCK (SC70)	DRL (SOT)	DRY (SON)	DTQ (X2SON)	UNIT		
		6 PINS	6 PINS	6 PINS	6 PINS	6 PINS			
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	217.4	216.1	TBD	TBD	TBD	°C/W		
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	136.0	143.6	TBD	TBD	TBD	°C/W		
R <sub>θJB</sub>	Junction-to-board thermal resistance	98.5	75.9	TBD	TBD	TBD	°C/W		
Y <sub>JT</sub>	Junction-to-top characterization parameter	75.8	58.5	TBD	TBD	TBD	°C/W		
Y <sub>JB</sub>	Junction-to-board characterization parameter	98.2	75.6	TBD	TBD	TBD	°C/W		
R <sub>θ</sub> JC(bottom)	Junction-to-case (bottom) thermal resistance	N/A	N/A	TBD	TBD	TBD	°C/W		

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

### **6.5 Electrical Characteristics**

over operating free-air temperature range (unless otherwise noted)<sup>(1) (2)</sup>

					0	peratir	ng free	-air temperat	ure (T	A)		
P/	ARAMETER	TEST CONDITIONS	V <sub>CCA</sub>	V <sub>CCB</sub>		25°C		<b>-40</b> °	°C to 85°C	<b>-40°</b>	C to 125°C	UNIT
					MIN	TYP	MAX	MIN	TYP MAX	MIN	ΤΥΡ ΜΑΧ	
			1.1 V	1.1 V				0.44	0.88	0.44	0.88	
			1.4 V	1.4 V				0.60	0.98	0.60	0.98	
		Data Inputs	1.65 V	1.65 V				0.76	1.13	0.76	1.13	
		(Ax, Bx)	2.3 V	2.3 V				1.08	1.56	1.08	1.56	V
		(Referenced to V <sub>CCI</sub> )	3 V	3 V				1.48	1.92	1.48	1.92	
	Positive-		4.5 V	4.5 V				2.19	2.74	2.19	2.74	
V <sub>T+</sub>	going input-		5.5 V	5.5 V				2.65	3.33	2.65	3.33	]
v⊺+	threshold		1.1 V	1.1 V				0.44	0.88	0.44	0.88	
	voltage		1.4 V	1.4 V				0.60	0.98	0.60	0.98	
		Control Input	1.65 V	1.65 V				0.76	1.13	0.76	1.13	
		(DIR) (Referenced to	2.3 V	2.3 V				1.08	1.56	1.08	1.56	V
		V <sub>CCA</sub> )	3 V	3 V				1.48	1.92	1.48	1.92	
			4.5 V	4.5 V				2.19	2.74	2.19	2.74	
			5.5 V	5.5 V				2.65	3.33	2.65	3.33	
			1.1 V	1.1 V				0.17	0.48	0.17	0.48	
		Data Inputs (Ax, Bx) (Referenced to V <sub>CCI</sub> )	1.4 V	1.4 V				0.28	0.59	0.28	0.59	1
			1.65 V	1.65 V				0.35	0.69	0.35	0.69	1
			2.3 V	2.3 V				0.56	0.97	0.56	0.97	v
			3 V	3 V				0.89	1.5	0.89	1.5	
	Newsters		4.5 V	4.5 V				1.51	1.97	1.51	1.97	
. ,	Negative- going input- threshold voltage		5.5 V	5.5 V				1.88	2.4	1.88	2.4	-
V <sub>T-</sub>		Control Input (DIR) (Referenced to V <sub>CCA</sub> )	1.1 V	1.1 V				0.17	0.48	0.17	0.48	
			1.4 V	1.4 V				0.28	0.6	0.28	0.6	1
			1.65 V	1.65 V				0.35	0.71	0.35	0.71	1
			2.3 V	2.3 V				0.56	1	0.56	1	
			3 V	3 V				0.89	1.5	0.89	1.5	
			4.5 V	4.5 V				1.51	2	1.51	2	
			5.5 V	5.5 V				1.88	2.46	1.88	2.46	1
			1.1 V	1.1 V				0.2	0.4	0.2	0.4	
			1.4 V	1.4 V				0.25	0.5	0.25	0.5	
		Data Inputs	1.65 V	1.65 V				0.3	0.55	0.3	0.55	-
		(Ax, Bx)	2.3 V	2.3 V				0.38	0.65	0.38	0.65	v
		(Referenced to $V_{CCI}$ )	3 V	3 V				0.46	0.72	0.46	0.72	-
			4.5 V	4.5 V				0.58	0.93	0.58	0.93	
	Input- threshold		5.5 V	5.5 V				0.69	1.06	0.69	1.06	1
ΔV <sub>T</sub>	hysteresis		1.1 V	1.1 V				0.2	0.4	0.2	0.4	
	$(V_{T+} - V_{T-})$		1.4 V	1.4 V				0.25	0.5	0.25	0.5	4
		Control Input	1.65 V	1.65 V				0.3	0.55	0.3	0.55	1
		(DIR)	2.3 V	2.3 V				0.38	0.65	0.38	0.65	
		(Referenced to V <sub>CCA</sub> )	3 V	3 V	-			0.46	0.72	0.46	0.72	-
			4.5 V	4.5 V				0.58	0.93	0.58	0.93	
			5.5 V	5.5 V				0.69	1.06	0.69	1.06	-



### 6.5 Electrical Characteristics (continued)

over operating free-air temperature range (unless otherwise noted)<sup>(1) (2)</sup>

			V <sub>CCA</sub>		Operating free-air temperature (T <sub>A</sub> )									
PA	RAMETER	TEST CONDITIONS		V <sub>CCB</sub>		25°C		<b>-40</b> °	C to 8	5°C	-40°0	C to 12	25°C	UNI
					MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
		I <sub>OH</sub> = –100 μA	1.1V – 5.5V	1.1V – 5.5V				V <sub>CCO</sub> - 0.1			V <sub>CCO</sub> - 0.1			
	High-level	I <sub>OH</sub> =4 mA	1.4 V	1.4 V				1			1			
V <sub>OH</sub>	output	I <sub>OH</sub> =8 mA	1.65 V	1.65 V				1.2			1.2			v
	voltage <sup>(3)</sup>	I <sub>OH</sub> = -12 mA	2.3 V	2.3 V				1.9			1.9			
		I <sub>OH</sub> = -24 mA	3 V	3 V				2.4			2.4			
		I <sub>OH</sub> = -32 mA	4.5 V	4.5 V				3.8			3.8			
		I <sub>OL</sub> = 100 μA	1.1V – 5.5V	1.1V – 5.5V						0.1			0.1	
		I <sub>OL</sub> = 4 mA	1.4 V	1.4 V						0.3			0.3	
	Low-level	I <sub>OL</sub> = 8 mA	1.65 V	1.65 V						0.45			0.45	
V <sub>OL</sub>	output voltage <sup>(4)</sup>	I <sub>OL</sub> = 12 mA	2.3 V	2.3 V						0.3			0.3	V
	Vollage	I <sub>OL</sub> = 24 mA	3 V	3 V						0.55			0.55	
		I <sub>OL</sub> = 32 mA	4.5 V	4.5 V						0.55			0.55	
h   '	Input leakage	Control input (DIR) V <sub>I</sub> = V <sub>CCA</sub> or GND	1.1V – 5.5V	1.1V – 5.5V	-0.1		1	-0.1		2	-0.1		2	μΑ
	current	Data Inputs <sup>(5)</sup> (Ax, Bx) $V_I = V_{CCI}$ or GND	1.1V – 5.5V	1.1V – 5.5V	-0.3		1	-1		1	-2		2	μA
I <sub>off</sub> Partial power down current	Partial power	A Port or B Port	0 V	0 V - 5.5 V	-1		1	-2		2	-2.5		2.5	
	V <sub>1</sub> or V <sub>O</sub> = 0 V - 5.5 V	0 V - 5.5 V	0 V	-1		1	-2		2	-2.5		2.5	μA	
	Floating		Floating <sup>(6)</sup>	0 V - 5.5 V	-1.5		1.5	-2		2	-2.5		2.5	
I <sub>off-float</sub>	supply Partial power down current	A Port or B Port V <sub>I</sub> or V <sub>O</sub> = GND	0 V - 5.5 V	Floating <sup>(6)</sup>	-1.5		1.5	-2		2	-2.5		2.5	μA
			1.1V – 5.5V	1.1V – 5.5V			2			2			4	
	V <sub>CCA</sub> supply	$V_I = V_{CCI}$ or GND $I_O = 0$	0 V	5.5 V	-0.2			-0.5			-1			
I <sub>CCA</sub>	current		5.5 V	0 V			1			1			2	μA
		$V_{I} = GND$ $I_{O} = 0$	5.5 V	Floating <sup>(6)</sup>			1			1			2	
			1.1V – 5.5V	1.1V – 5.5V			2			2			4	
		$V_I = V_{CCI}$ or GND $I_O = 0$	0 V	5.5 V			1			1			2	
I <sub>CCB</sub>	V <sub>CCB</sub> supply current	10 - 0	5.5 V	0 V	-0.2			-0.5			-1			μA
		$V_1 = GND$ $I_0 = 0$	Floating <sup>(6)</sup>	5.5 V			1			1			2	
I <sub>CCA</sub> + I <sub>CCB</sub>	Combined supply current	$V_{I} = V_{CCI}$ or GND $I_{O} = 0$	1.1V – 5.5V	1.1V – 5.5V			3			4			6	μA
ΔI <sub>CCA</sub>	V <sub>CCA</sub> additional supply	Control input (DIR): $V_1 = V_{CCA} - 0.6 V$ A port = VCCA or GND B Port = open	3.0V - 5.5V	3.0V - 5.5V						50			75	μ
000	current per input	A Port: $V_I = V_{CCA} - 0.6 V$ DIR = $V_{CCA}$ , B Port = open	3.0V - 5.5V	3.0V - 5.5V						50			75	

### 6.5 Electrical Characteristics (continued)

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup> (2)

						0	peratir	ng free	-air te	nperat	ure (T⊿	)		
PA	RAMETER	TEST CONDITIONS	V <sub>CCA</sub>	V <sub>CCB</sub>		25°C		–40°C to 85°C			-40°C to 125°C			UNIT
					MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
ΔI <sub>CCB</sub>	V <sub>CCB</sub> additional supply current per input	B Port: $V_1 = V_{CCB} - 0.6 V$ DIR = GND, A Port = open	3.0V - 5.5V	3.0V - 5.5V						50			75	μA
C <sub>i</sub>	Control Input Capacitance	V <sub>I</sub> = 3.3 V or GND	3.3 V	3.3 V		2.2				5			5	pF
C <sub>io</sub>	Data I/O Capacitance	V <sub>CCO</sub> = 0V V <sub>O</sub> = 1.65V DC +1 MHz -16 dBm sine wave	3.3 V	3.3 V		4.3				10.5			10.5	pF

(1)  $V_{CCI}$  is the  $V_{CC}$  associated with the input port (2)  $V_{CCO}$  is the  $V_{CC}$  associated with the output port (3) Tested at  $V_I = V_{T+(MAX)}$ 

(4) Tested at V<sub>1</sub> = V<sub>1+(MAX)</sub>
(5) For I/O ports, the parameter I<sub>1</sub> includes the I<sub>OZ</sub> current
(6) Floating is defined as a node that is both not actively driven by an external device and has leakage not exceeding 10nA



## 6.6 Switching Characteristics, $V_{CCA} = 1.2 \pm 0.1 V$

	<u> </u>					<u> </u>			B-I	Port Supply	Voltage (	<b>∕<sub>ССВ</sub>)</b>						
	PARAMETER	FROM	то	Test Conditions	1.2 ±	0.1 V	1.5 ± 0	1 V	1.8	± 0.15 V	2.5 ±	0.2 V	3.	3 ± 0.3 V	5.	.0 ± 0.5 V		UNIT
					MIN TY	Έ ΜΑΧ	MIN TYP	MAX	MIN .	ΤΥΡ ΜΑΧ	MIN TY	Έ ΜΑΧ	MIN	TYP MAX	MIN	TYP N	IAX	
		A	в	-40°C to 85°C	6	85	4	41	3	36	1	33	1	34	1		44	
+	Propagation			-40°C to 125°C	8	55	6	37	5	33	3	30	3	30	2		33	ns
t <sub>pd</sub>	delay	В	A	-40°C to 85°C	6	85	5	71	4	67	3	60	3	57	3		58	115
		В		-40°C to 125°C	8	55	6	47	6	43	5	38	4	37	4		36	
		DIR	A	-40°C to 85°C	5	53	5	53	5	53	5	53	5	53	4		53	
+	Disable time	DIK		-40°C to 125°C	7	47	7	47	7	47	7	47	7	47	7		47	ns
t <sub>dis</sub>	Disable time	DIR	в	-40°C to 85°C	10	85	7	47	6	41	5	34	5	33	4		32	115
		DIR		-40°C to 125°C	14	71	11	48	10	41	8	34	8	33	6		32	
		DIR	A	-40°C to 85°C	21	150	17	110	16	99	13	86	13	83	12		85	
	Enable time	DIR	A	-40°C to 125°C	27	121	23	89	21	80	17	68	17	65	15		63	-
t <sub>en</sub>		DIR	в	-40°C to 85°C	16	118	14	89	13	84	12	81	11	82	11		92	ns
				-40°C to 125°C	19	97	18	79	17	73	16	68	15	67	14		70	



## 6.7 Switching Characteristics, $V_{CCA} = 1.5 \pm 0.1 V$

											В	-Port S	Supply	Voltag	e (V <sub>CC</sub>	в)							
	PARAMETER	FROM	то	Test Conditions	1.	2 ± 0.1 V	·	1.	5 ± 0.1	V	1.8	3 ± 0.15	5 V	2.	5 ± 0.2	V	3.	3 ± 0.3	v	5.	0 ± 0.5	v	UNIT
					MIN	TYP N	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
		A	в	-40°C to 85°C	5		71	3		29	1		24	1		20	1		19	1		19	
+	Propagation	^		-40°C to 125°C	6		47	4		30	3		25	2		21	2		20	1		20	ns
t <sub>pd</sub>	delay	в	A	-40°C to 85°C	4		41	3		29	2		27	1		23	1		22	1		21	115
		В		-40°C to 125°C	6		37	4		30	4		27	3		24	3		22	2		22	
		DIR	A	-40°C to 85°C	2		26	2	·	26	2		26	2		26	2		26	2		26	
+	Disable time	DIIX		-40°C to 125°C	4		27	4		27	4		27	4		27	4		27	4		27	ns
t <sub>dis</sub>		DIR	в	-40°C to 85°C	8		71	6		38	5		32	3		25	3		24	2		22	115
		DIIX		-40°C to 125°C	12		61	10		39	9		34	6		26	6		25	4		23	
		DIR	A	-40°C to 85°C	17		106	13		63	12		54	9		44	9		41	8		39	
+	Enable time	DIK	A	-40°C to 125°C	23		92	19		64	17		56	14		45	14		42	12		40	-
t <sub>en</sub>		DIR	в	-40°C to 85°C	12		90	10		51	9		45	8		40	7		39	7		39	ns
				-40°C to 125°C	16		69	14		51	13		47	12		42	11		40	10		40	



## 6.8 Switching Characteristics, $V_{CCA}$ = 1.8 ± 0.15 V

										В	-Port S	Supply	Voltag	e (V <sub>CC</sub>	в)							
	PARAMETER	FROM	то	Test Conditions	1.2	2 ± 0.1 V	1	.5 ± 0.1	V	1.8	3 ± 0.15	5 V	2.	5 ± 0.2	V	3.	3 ± 0.3	V	5.	0 ± 0.5	V	UNIT
					MIN	TYP MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
		А	в	-40°C to 85°C	4	67	2		27	1		22	1		18	1		16	1		16	
+	Propagation	^		-40°C to 125°C	6	43	4		27	3		22	2		18	1		17	1		16	ns
<sup>t</sup> pd	delay	в	A	-40°C to 85°C	3	36	i 1		24	1		22	1		19	1		18	1		17	115
		Б		-40°C to 125°C	5	33	3		25	3		22	2		19	2		18	1		18	
		DIR	A	-40°C to 85°C	2	21	2		21	2		21	2		21	2		21	1		21	
+	Disable time	DIK		-40°C to 125°C	3	22	2 3		22	3		22	3		22	3		22	3		22	ns
t <sub>dis</sub>	Disable time	DIR	в	-40°C to 85°C	7	65	5 5		35	4		29	2		22	2		21	1		19	115
		DIK		-40°C to 125°C	10	56	8		36	7		30	6		24	5		22	3		20	
		DIR	A	-40°C to 85°C	15	96	5 11		54	10		46	8		36	7		34	6		31	
+	Enable time	DIK		-40°C to 125°C	20	82	17		56	15		48	13		38	12		35	10		33	
t <sub>en</sub>		DIR	в	-40°C to 85°C	11	80	9		42	7		37	7		33	6		31	6		30	ns
		UIK		-40°C to 125°C	14	60	12		43	11		39	10		34	9		33	9		32	



## 6.9 Switching Characteristics, $V_{CCA} = 2.5 \pm 0.2 V$

										В	-Port S	upply	Voltag	e (V <sub>CCI</sub>	в)							
	PARAMETER	FROM	то	Test Conditions	1.2	2 ± 0.1 V	1.	5 ± 0.1	V	1.8	3 ± 0.15	5 V	2.	5 ± 0.2	V	3.	3 ± 0.3	V	5.	0 ± 0.5	V	UNIT
					MIN	TYP MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
		A	в	-40°C to 85°C	3	60	1		23	1		19	1		15	1		14	1		13	
+	Propagation	^		-40°C to 125°C	5	38	3		24	2		19	1		15	1		14	1		13	ns
Lpd	delay	в	A	-40°C to 85°C	1	33	1		20	1		18	1		15	1		14	1		14	115
		В		-40°C to 125°C	3	30	2		21	2		18	1		15	1		14	1		14	
		DIR	A	-40°C to 85°C	1	15	1		15	1		15	1		15	1		15	1		15	
+	Disable time	DIK	A	-40°C to 125°C	1	15	1		15	1		15	1		15	1		15	1		15	
t <sub>dis</sub>	Disable time	DIR	в	-40°C to 85°C	5	54	4		30	3		25	2		19	2		18	1		16	ns
		DIIX		-40°C to 125°C	8	47	7		31	6		26	5		21	4		19	2		17	
		DIR	A	-40°C to 85°C	12	82	9		44	8		37	6		29	6		27	5		24	
+	Enable time	DIK	A	-40°C to 125°C	17	68	14		45	13		39	11		31	10		29	8		26	
t <sub>en</sub>		DIR	в	-40°C to 85°C	8	67	6		33	5		29	4		25	4		23	4		22	ns
		DIK	D	-40°C to 125°C	11	49	9		34	8		30	7		26	7		24	6		23	



## 6.10 Switching Characteristics, $V_{CCA}$ = 3.3 ± 0.3 V

									B-Port	Supply	Voltage (V <sub>CC</sub>	:в)						
	PARAMETER	FROM	то	Test Conditions	1.2 ± 0.1	V	1.5 ± 0.1	V	1.8 ± 0.1	15 V	2.5 ± 0.2	2 V	3.	3 ± 0.3 V	5	.0 ± 0.5	V	UNIT
					MIN TYP	MAX	MIN TYP	MAX	MIN TYP	MAX	MIN TYP	MAX	MIN	TYP MAX	MIN	TYP	MAX	
		A	в	-40°C to 85°C	3	57	1	22	1	18	1	14	1	13	1		12	
+	Propagation			-40°C to 125°C	4	37	3	22	2	18	1	14	1	13	1		12	ns
Lpd	delay	в	A	-40°C to 85°C	1	34	1	19	1	16	1	13	1	13	1		12	115
		В		-40°C to 125°C	3	30	2	20	1	17	1	14	1	13	1		12	
		DIR	A	-40°C to 85°C	1	14	1	14	1	14	1	14	1	14	1		14	
+	Disable time	DIR		-40°C to 125°C	1	14	1	14	1	14	1	14	1	14	1		14	ns
t <sub>dis</sub>		DIR	в	-40°C to 85°C	5	49	3	27	3	23	1	18	2	17	1		15	115
		DIR		-40°C to 125°C	8	44	6	28	5	24	4	19	4	18	2		16	
		DIR	A	-40°C to 85°C	12	78	8	39	7	33	6	26	5	25	4		22	
+	Enable time	DIK		-40°C to 125°C	16	64	13	40	11	35	9	28	9	26	7		23	na
t <sub>en</sub>		DIR	в	-40°C to 85°C	8	64	6	30	5	26	4	23	4	21	4		20	ns
				-40°C to 125°C	11	46	9	31	8	27	7	24	6	22	6		21	



## 6.11 Switching Characteristics, $V_{CCA}$ = 5.0 ± 0.5 V

										В	-Port S	Supply	Voltag	je (V <sub>CC</sub>	в)							
	PARAMETER	FROM	то	Test Conditions	1.:	2 ± 0.1 V	1	.5 ± 0.1	V	1.8	3 ± 0.15	5 V	2.	.5 ± 0.2	V	3.	3 ± 0.3	V	5.	0 ± 0.5	V	UNIT
					MIN	TYP MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
		A	в	-40°C to 85°C	3	58	1		21	1		17	1		14	1		12	1		11	
+	Propagation	^		-40°C to 125°C	4	36	6 2		22	1		18	1		14	1		13	1		11	ns
t <sub>pd</sub>	delay	в	A	-40°C to 85°C	1	44	1		19	1		16	1		13	1		12	1		11	115
		В		-40°C to 125°C	2	33	1		20	1		16	1		13	1		12	1		11	
		DIR	A	-40°C to 85°C	1	12	2 1		12	1		12	1		12	1		12	1		12	
+	Disable time	DIK		-40°C to 125°C	1	12	! 1		12	1		12	1		12	1		12	1		12	ns
t <sub>dis</sub>	Disable line	DIR	в	-40°C to 85°C	5	48	3		26	3		21	1		16	2		16	1		14	115
		DIK		-40°C to 125°C	8	43	6		26	5		22	3		17	3		17	2		15	
		DIR	A	-40°C to 85°C	11	87	8		38	7		31	5		24	5		22	4		20	
+	Enable time	DIK		-40°C to 125°C	15	66	12		39	10		32	8		25	8		24	6		21	<b>n</b> 0
t <sub>en</sub>		DIR	в	-40°C to 85°C	7	63	5		28	4		24	3		20	3		19	2		18	ns
				-40°C to 125°C	9	43	5 7		28	6		25	5		21	4		19	4		18	



## 6.12 Switching Characteristics: T<sub>sk</sub>, T<sub>MAX</sub>

over operating free-air temperature range (unless otherwise noted)

						ting fre erature		
PARAMETER	TEST CONDI	TIONS	V <sub>CCI</sub>	V <sub>cco</sub>	-40°(	C to 12	5°C	UNIT
					MIN	TYP	MAX	
			3.0 V - 3.6 V	4.5 V - 5.5 V	200	420		
			2.25 V - 2.75 V	4.5 V - 5.5 V	150	300		
			1.65 V - 1.95 V	4.5 V - 5.5 V	100	200		
		Up Translation	1.1 V - 1.3 V	4.5 V - 5.5 V	20	40		
			1.65 V - 1.95 V	3.0 V - 3.6 V	100	210		
	50% Duty Cycle Input		1.1 V - 1.3 V	3.0 V - 3.6 V	10	20		
T <sub>MAX</sub> - Maximum	One channel switching		1.1 V - 1.3 V	1.65 V - 1.95 V	5	10		Mbps
Data Rate	20% of pulse > $0.7^*V_{CCO}$		4.5 V - 5.5 V	3.0 V - 3.6 V	100	210		Mups
	20% of pulse < $0.3^*V_{CCO}$		4.5 V - 5.5 V	2.25 V - 2.75 V	75	140		
			4.5 V - 5.5 V	1.65 V - 1.95 V	50	75		
		Down Translation	4.5 V - 5.5 V	1.1 V - 1.3 V	15	30		
			3.0 V - 3.6 V	1.65 V - 1.95 V	40	75		
			3.0 V - 3.6 V	1.1 V - 1.3 V	10	20		
			1.65 V - 1.95 V	1.1 V - 1.3 V	5	10		

#### 6.13 Operating Characteristics

T<sub>A</sub> = 25°C <sup>(1)</sup>

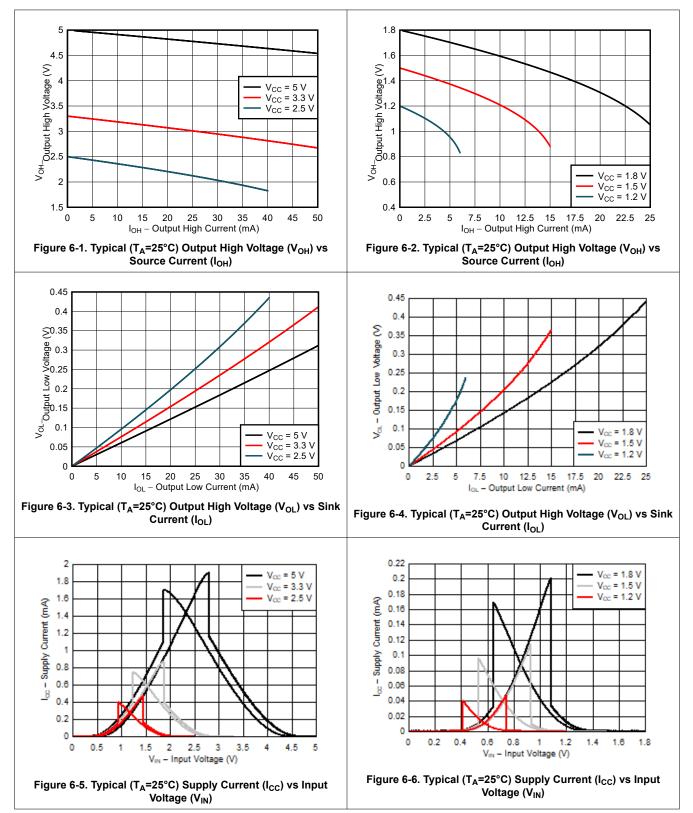
				Su	pply Voltage	$(V_{CCB} = V_{CC})$	:A)		
	PARAMETER	Test Conditions	1.2 ± 0.1V	1.5 ± 0.1V	1.8 ± 0.15V	2.5 ± 0.2V	3.3 ± 0.3V	5.0 ± 0.5V	UNIT
			TYP	TYP	TYP	TYP	TYP	TYP	]
	A to B	A Port	3.2	3.4	3.5	3.7	3.9	5.1	
C <sub>pdA</sub> <sup>(2)</sup>	B to A	$\begin{array}{l} CL = 0, \ RL = Open \\ f = 10 \ MHz \\ t_{rise} = t_{fall} = 1 \ ns \end{array}$	19.4	19.6	19.8	20.4	21.8	25.7	pF
	A to B	B Port	19.3	19.5	19.7	20.4	21.6	25.3	
C <sub>pdB</sub> <sup>(2)</sup>	B to A	$\begin{array}{l} CL = 0, \ RL = Open \\ f = 10 \ MHz \\ t_{rise} = t_{fall} = 1 \ ns \end{array}$	3.3	3.5	3.6	4.0	4.4	5.0	pF

For more information about power dissipation capacitance, see the CMOS Power Consumption and  $C_{pd}$  Calculation application report  $C_{pdA}$  and  $C_{pdB}$  are repectively A-Port and B-Port power dissipation capacitances per transceiver (1)

(2)



#### 6.14 Typical Characteristics



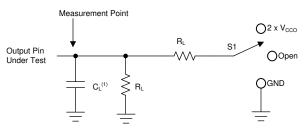


### 7 Parameter Measurement Information

### 7.1 Load Circuit and Voltage Waveforms

Unless otherwise noted, all input pulses are supplied by generators having the following characteristics:

- f = 1 MHz
- Z<sub>O</sub> = 50 Ω
- Δt/ΔV ≤ 1 ns/V

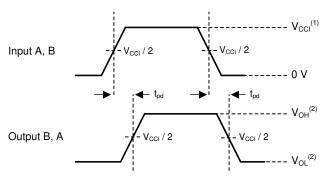


A. C<sub>L</sub> includes probe and jig capacitance.

Figure 7-1. Load Circuit

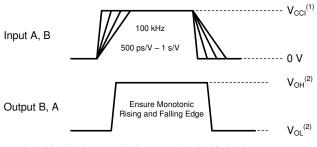
		au circui	Conditions		
Parameter	V <sub>cco</sub>	RL	CL	S <sub>1</sub>	V <sub>TP</sub>
t <sub>pd</sub> Propagation (delay) time	1.1 V – 5.5 V	2 kΩ	15 pF	Open	N/A
	1.1 V – 1.6 V	2 kΩ	15 pF	$2 \times V_{CCO}$	0.1 V
t <sub>en</sub> , t <sub>dis</sub> Enable time, disable time	1.65 V – 2.7 V	2 kΩ	15 pF	$2 \times V_{CCO}$	0.15 V
	3.0 V – 5.5 V	2 kΩ	15 pF	$2 \times V_{CCO}$	0.3 V
	1.1 V – 1.6 V	2 kΩ	15 pF	GND	0.1 V
$t_{en}$ , $t_{dis}$ Enable time, disable time	1.65 V – 2.7 V	2 kΩ	15 pF	GND	0.15 V
	3.0 V – 5.5 V	2 kΩ	15 pF	GND	0.3 V





- 1.  $V_{CCI}$  is the supply pin associated with the input port.
- V<sub>OH</sub> and V<sub>OL</sub> are typical output voltage levels that occur with specified R<sub>L</sub>, C<sub>L</sub>, and S<sub>1</sub>

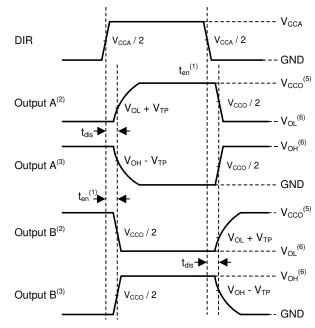
#### Figure 7-2. Propagation Delay



- 1.  $V_{CCI}$  is the supply pin associated with the input port.
- 2.  $V_{OH}$  and  $V_{OL}$  are typical output voltage levels that occur with specified R<sub>L</sub>, C<sub>L</sub>, and S<sub>1</sub>

#### Figure 7-3. Input Transition Rise and Fall Rate





- A. 1. Illustrative purposes only. Enable time is a calculation as described in *Enable Times*.
  - 2. Output waveform on the condition that input is driven to a valid Logic low.
  - 3. Output waveform on the condition that input is driven to a valid Logic high.
  - 4.  $V_{CCI}$  is the supply pin associated with the input port.
  - 5.  $V_{CCO}$  is the supply pin associated with the output port.
  - 6.  $V_{OH}$  and  $V_{OL}$  are typical output voltage levels with specified R<sub>L</sub>, C<sub>L</sub>, and S<sub>1</sub>.

#### Figure 7-4. Enable Time And Disable Time



# 8 Detailed Description

#### 8.1 Overview

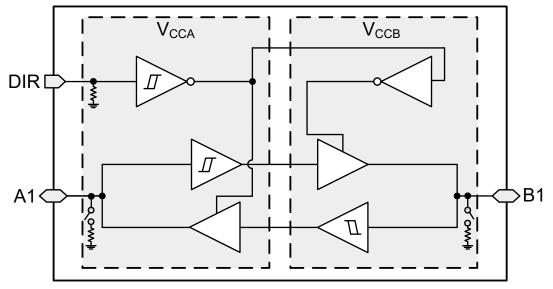
The SN74LXC1T45 is an 1-bit translating transceiver that uses two individually configurable power-supply rails. The device is operational with both  $V_{CCA}$  and  $V_{CCB}$  supplies as low as 1.1 V and as high as 5.5 V. Additionally, the device can be operated with  $V_{CCA} = V_{CCB}$ . The A port is designed to track  $V_{CCA}$ , and the B port is designed to track  $V_{CCB}$ .

The SN74LXC1T45 device is designed for asynchronous communication between devices and transmits data from A to B or from B to A based on the logic level of the direction-control input (DIR). The control pins of the SN74LXC1T45 (DIR) is referenced to  $V_{CCA}$ . The input circuitry on both A and B ports is always active and must have a logic HIGH or LOW level applied to prevent excess ICC and ICCZ.

This device is fully specified for partial-power-down applications using the  $I_{off}$  current. The  $I_{off}$  protection circuitry ensures that no excessive current is drawn from or sourced into an input, output, or I/O while the device is powered down.

The V<sub>CC</sub> isolation or V<sub>CC</sub> disconnect feature ensures that if either V<sub>CC</sub> is less than 100 mV or disconnected with the complementary supply within the recommended operating conditions, then both I/O ports are weakly pulled-down and then set to the high-impedance state by disabling their outputs while the supply current is maintained. The I<sub>off-float</sub> circuitry ensures that no excessive current is drawn from or sourced into an input, output, or I/O while the supply is floating.

Glitch-free power supply sequencing allows either supply rail to be powered on or off in any order while providing robust power sequencing performance.



#### 8.2 Functional Block Diagram

#### 8.3 Feature Description

#### 8.3.1 CMOS Schmitt-Trigger Inputs with Integrated Pulldowns

Standard CMOS inputs are high impedance and are typically modeled as a resistor in parallel with the input capacitance given in the *Electrical Characteristics*. The worst case resistance is calculated with the maximum input voltage, given in the *Absolute Maximum Ratings*, and the maximum input leakage current, given in the *Electrical Characteristics*, using ohm's law ( $R = V \div I$ ).

The Schmitt-trigger input architecture provides hysteresis as defined by  $\Delta V_T$  in the *Electrical Characteristics*, which makes this device extremely tolerant to slow or noisy inputs. Driving the inputs slowly will increase dynamic current consumption of the device. For additional information regarding Schmitt-trigger inputs, see *Understanding Schmitt Triggers*.

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#### 8.3.1.1 I/O's with Integrated Dynamic Pull-Down Resistors

Input circuits of the data I/O's are always active even when the device is disabled. It is recommended to keep a valid voltage level at the I/O's to avoid high current consumption. To help avoid floating inputs on the I/O's during disabling, this device has 100-k $\Omega$  typical integrated weak dynamic pull-downs on all data I/O's. When the device is disabled, the dynamic pull-downs are activated for only a short period of time to help drive and keep low any floating inputs before the device I/O's become high impedance. If the I/O lines are to be floated after the device is disabled, then it is recommended to keep them at a valid input voltage level using the external pull-downs. This feature is ideal for loads of 30 pF or less. If greater capactive loading is present, then external pull-downs are recommended. If an external pull-up is required, then it should be no larger than 15 k $\Omega$  to avoid contention with the 100 k $\Omega$  internal pull-down.

#### 8.3.1.2 Control Inputs with Integrated Static Pull-Down Resistors

Similar to the data I/O's, a floating control input can cause high current consumption. To help avoid this concern, this device has integrated weak static pull-downs of  $5-M\Omega$  typical on the control input (DIR). These pull-downs are always present. So for example if the DIR pin is left floating, then the B port will be configured as an input and the A port configured as an output.

#### 8.3.2 Balanced High-Drive CMOS Push-Pull Outputs

A balanced output allows the device to sink and source similar currents. The high drive capability of this device creates fast edges into light loads so routing and load conditions should be considered to prevent ringing. Additionally, the outputs of this device are capable of driving larger currents than the device can sustain without being damaged. The electrical and thermal limits defined in the *Absolute Maximum Ratings* must be followed at all times.

#### 8.3.3 Partial Power Down (Ioff)

The inputs and outputs for this device enter a high-impedance state when the device is powered down, inhibiting current backflow into the device. The maximum leakage into or out of any input or output pin on the device is specified by I<sub>off</sub> in the *Electrical Characteristics*.

#### 8.3.4 V<sub>CC</sub> Isolation and V<sub>CC</sub> Disconnect (I<sub>off-float</sub>)

This device has *I/O's with Integrated Dynamic Pull-Down Resistors*. The I/O's will get pulled down and then enter a high-impedance state when either supply is < 100 mV or left floating (disconnected), while the other supply is still connected to the device. It is recommended that the I/O's for this device are not driven and kept at a logic low state prior to floating (disconnecting) either supply.

The maximum supply current is specified by  $I_{CCx}$ , while  $V_{CCx}$  is floating, in the *Electrical Characteristics*. The maximum leakage into or out of any input or output pin on the device is specified by  $I_{off(float)}$  in the *Electrical Characteristics*.



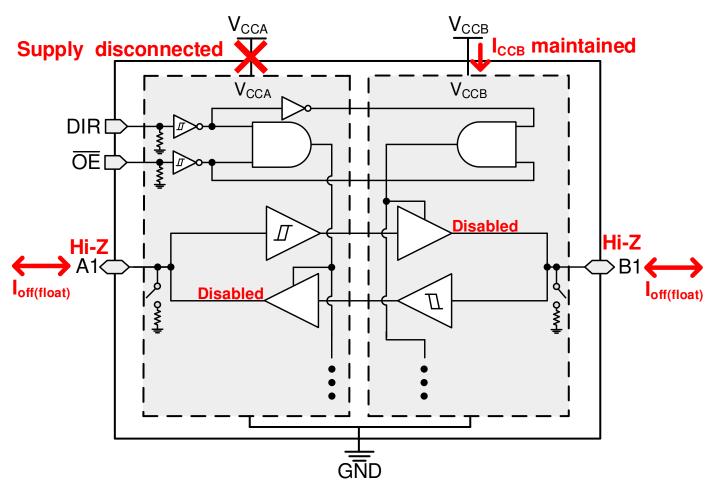


Figure 8-1. V<sub>CC</sub> Disconnect Feature

#### 8.3.5 Over-Voltage Tolerant Inputs

Input signals to this device can be driven above the supply voltage so long as they remain below the maximum input voltage value specified in the *Recommended Operating Conditions*.

#### 8.3.6 Glitch-Free Power Supply Sequencing

Either supply rail may be powered on or off in any order without producing a glitch on the I/Os (that is, where the output erroneously transitions to VCC when it should be held low or vice versa). Glitches of this nature can be misinterpreted by a peripheral as a valid data bit, which could trigger a false device reset of the peripheral, a false device configuration of the peripheral, or even a false data initialization by the peripheral.

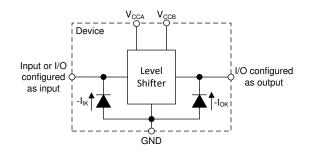


#### 8.3.7 Negative Clamping Diodes

Figure 8-2 shows the inputs and outputs to this device that have negative clamping diodes.

#### CAUTION

Voltages beyond the values specified in the *Absolute Maximum Ratings* table can cause damage to the device. The input negative voltage and output voltage ratings may be exceeded if the input and output clamp current ratings are observed.



#### Figure 8-2. Electrical Placement of Clamping Diodes for Each Input and Output

#### 8.3.8 Fully Configurable Dual-Rail Design

Both the  $V_{CCA}$  and  $V_{CCB}$  pins can be supplied at any voltage from 1.1 V to 5.5 V, making the device suitable for translating between any of the voltage nodes (1.2 V, 1.5 V, 1.8 V, 3.3 V, and 5.0 V).

#### 8.3.9 Supports High-Speed Translation

The SN74LXC1T45 device can support high data rate applications. The translated signal data rate can be up to 420 Mbps when the signal is translated from 3.3 V to 5.0 V.

#### 8.4 Device Functional Modes

		-1. I unction fabi	C
CONTROL INPUTS (1)	PORT	STATUS	OPERATION
DIR	A PORT	B PORT	OFERATION
L	Output (Enabled)	Input (Hi-Z)	B data to A bus
Н	Input (Hi-Z)	Output (Enabled)	A data to B bus

#### Table 8-1. Function Table

(1) Input circuits of the data I/Os are always active and should be kept at a valid logic level.



### 9 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

#### 9.1 Application Information

The SN74LXC1T45 device can be used in level-translation applications for interfacing devices or systems operating at different interface voltages with one another. The SN74LXC1T45 device is ideal for use in applications where a push-pull driver is connected to the data I/Os. The maximum data rate can be up to 420 Mbps when the device translates a signal from 3.3 V to 5.0 V.

#### 9.2 Enable Times

Calculate the enable times for the SN74LXC1T45 using the following formulas:

$$t_{A_{en}} (DIR \text{ to } A) = t_{dis} (DIR \text{ to } B) + t_{pd} (B \text{ to } A)$$
(1)

$$t_{B_{en}} (DIR \text{ to } B) = t_{dis} (DIR \text{ to } A) + t_{pd} (A \text{ to } B)$$
(2)

In a bidirectional application, these enable times provide the maximum delay time from the time the DIR bit is switched until an output is expected. For example, if the SN74LXC1T45 initially is transmitting from A to B, then the DIR bit is switched; the B port of the device must be disabled  $(t_{dis})$  before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay  $(t_{pd})$ . To avoid bus contention, care should be taken to not apply an input signal prior to the output being disabled  $(t_{dis} maximum)$ .

#### 9.3 Typical Application

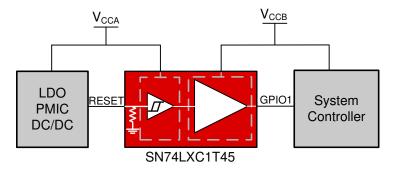


Figure 9-1. LED Driver Application

#### 9.3.1 Design Requirements

For this design example, use the parameters listed in Table 9-1.

 Table 9-1. Design Parameters

DESIGN PARAMETERS	EXAMPLE VALUES
Input voltage range	1.1 V to 5.5 V
Output voltage range	1.1 V to 5.5 V



#### 9.3.2 Detailed Design Procedure

To begin the design process, determine the following:

- Input voltage range
  - Use the supply voltage of the device that is driving the SN74LXC1T45 device to determine the input voltage range. For a valid logic-high, the value must exceed the positive-going input-threshold voltage (V<sub>t+</sub>) of the input port. For a valid logic low the value must be less than the negative-going input-threshold voltage (V<sub>t-</sub>) of the input port.
- Output voltage range
  - Use the supply voltage of the device that the SN74LXC1T45 device is driving to determine the output voltage range.

#### **10 Power Supply Recommendations**

Always apply a ground reference to the GND pins first. This device is designed for glitch free power sequencing without any supply sequencing requirements such as ramp order or ramp rate.

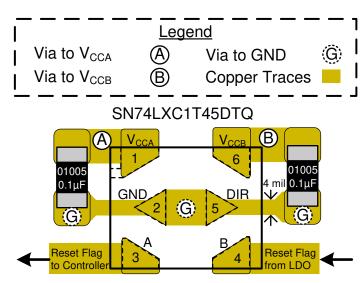
This device was designed with various power supply sequencing methods in mind to help prevent unintended triggering of downstream devices, as described in *Glitch-free Power Supply Sequencing*.

#### 11 Layout

#### 11.1 Layout Guidelines

To ensure reliability of the device, the following common printed-circuit board layout guidelines are recommended:

- Use bypass capacitors on the power supply pins and place them as close to the device as possible. A 0.1 μF capacitor is recommended, but transient performance can be improved by having both 1 μF and 0.1 μF capacitors in parallel as bypass capacitors.
- The high drive capability of this device creates fast edges into light loads so routing and load conditions should be considered to prevent ringing.



### 11.2 Layout Example

Figure 11-1. Layout Example – SN74LXC1T45



# 12 Device and Documentation Support

#### **12.1 Device Support**

#### 12.1.1 Regulatory Requirements

No statutory or regulatory requirements apply to this device.

There are no special characteristics for this product.

#### **12.2 Documentation Support**

#### 12.2.1 Related Documentation

For related documentation, see the following:

• Texas Instruments, Understanding Schmitt Triggers application report

#### 12.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### **12.4 Support Resources**

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

#### 12.5 Trademarks

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#### 12.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 12.7 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

### 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



#### PACKAGING INFORMATION

Orderable Device		Package Type		Pins	-		Lead finish/	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	Ball material	(3)		(4/5)	
SN74LXC1T45DBVR	ACTIVE	SOT-23	DBV	6	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2LSF	Samples
SN74LXC1T45DCKR	ACTIVE	SC70	DCK	6	3000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 125	1L1	Samples
SN74LXC1T45DRYR	ACTIVE	SON	DRY	6	5000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	МК	Samples
SN74LXC1T45DTQR	ACTIVE	X2SON	DTQ	6	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	ME	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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# **GENERIC PACKAGE VIEW**

# USON - 0.6 mm max height PLASTIC SMALL OUTLINE - NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



4207181/G

# **DRY0006A**



# **PACKAGE OUTLINE**

# USON - 0.6 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.



# DRY0006A

# **EXAMPLE BOARD LAYOUT**

# USON - 0.6 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

3. For more information, see QFN/SON PCB application report in literature No. SLUA271 (www.ti.com/lit/slua271).



# DRY0006A

# **EXAMPLE STENCIL DESIGN**

# USON - 0.6 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



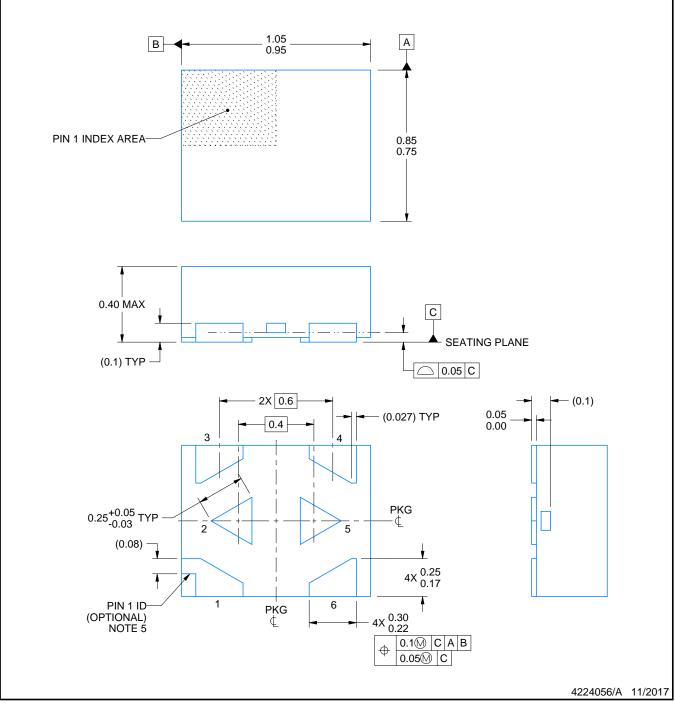
# **DTQ0006A**



# **PACKAGE OUTLINE**

# X2SON - 0.4 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- The package thermal pads must be soldered to the printed circuit board for optimal thermal and mechanical performance.
   The size and shape of this feature may vary.
- 5. Features may not exist. Recommend use of pin 1 marking on top of package for orientation purposes.

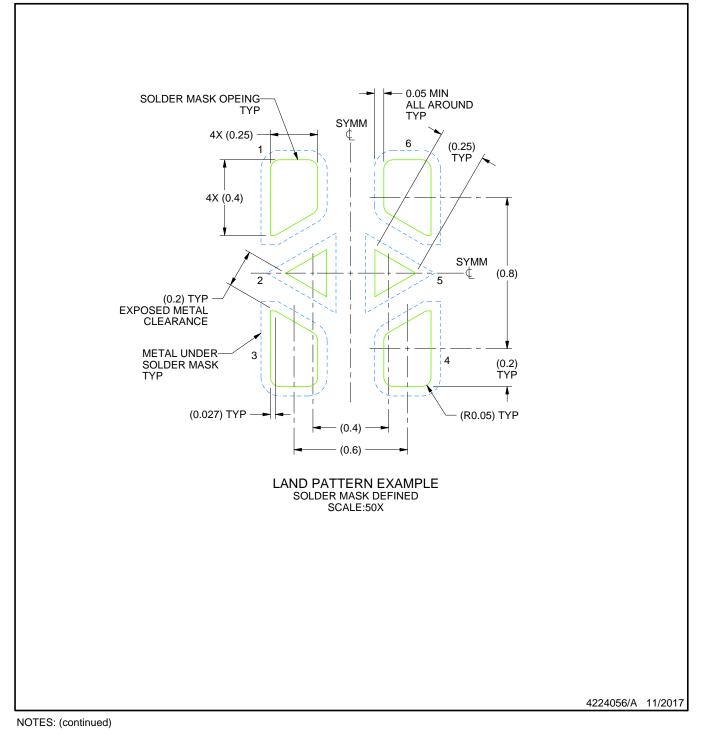


# **DTQ0006A**

# **EXAMPLE BOARD LAYOUT**

# X2SON - 0.4 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



6. This package is designed to be soldered to a thermal pads on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

7. Vias are optional depending on application, refer to device data sheet. If some or all are implemented, recommended via locations are shown.

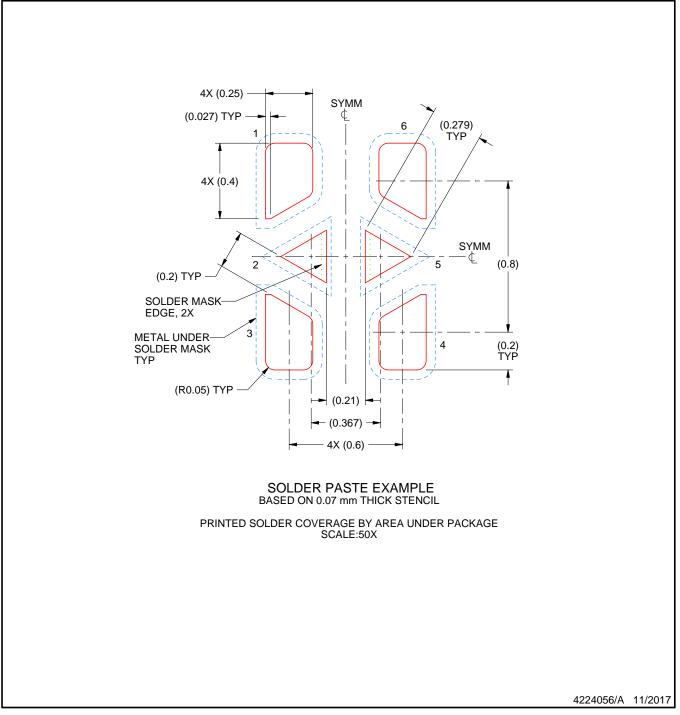


# DTQ0006A

# **EXAMPLE STENCIL DESIGN**

## X2SON - 0.4 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



# **DBV0006A**



# **PACKAGE OUTLINE**

# SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
  2. This drawing is subject to change without notice.
  3. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.25 per side.

- 4. Leads 1,2,3 may be wider than leads 4,5,6 for package orientation.
- 5. Refernce JEDEC MO-178.



# **DBV0006A**

# **EXAMPLE BOARD LAYOUT**

# SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

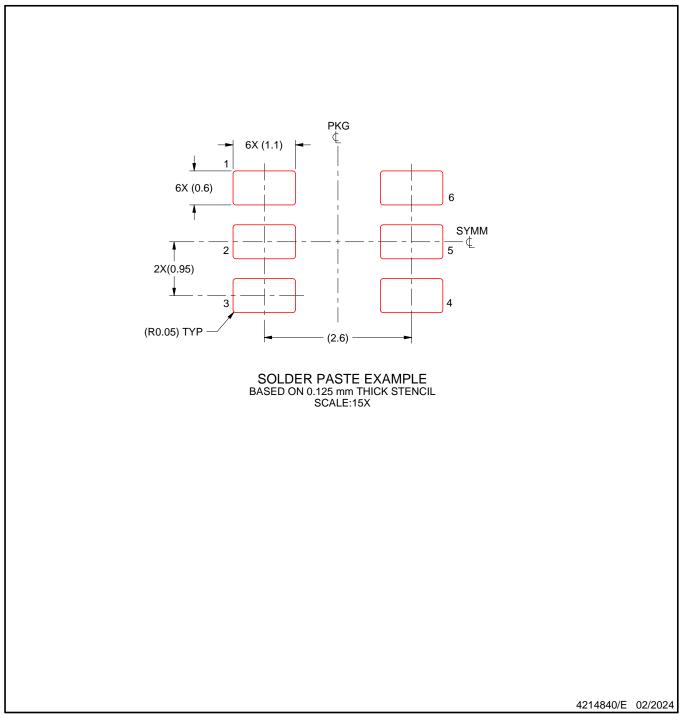


# **DBV0006A**

# **EXAMPLE STENCIL DESIGN**

# SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

9. Board assembly site may have different recommendations for stencil design.



DCK (R-PDSO-G6)

PLASTIC SMALL-OUTLINE PACKAGE



- NOTES: A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.
  - D. Falls within JEDEC MO-203 variation AB.



# LAND PATTERN DATA



NOTES:

- A. All linear dimensions are in millimeters.B. This drawing is subject to change without notice.
- C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
- D. Publication IPC-7351 is recommended for alternate designs.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.



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