1 Features

- Qualified for automotive applications
- Functional Safety-Capable
  - Documentation available to aid in functional safety system design
- 2-Bit bidirectional translator for SDA and SCL lines in mixed-mode I²C applications
- Standard-mode, fast-mode, and fast-mode plus I²C and SMBus compatible
- I³C compatible (12.5 MHz supported)
- Allows voltage-level translation between
  - 0.9-V \( V_{REF1} \) and 1.8-V, 2.5-V, 3.3-V, or 5-V \( V_{REF2} \)
  - 1.2-V \( V_{REF1} \) and 1.8-V, 2.5-V, 3.3-V, or 5-V \( V_{REF2} \)
  - 1.8-V \( V_{REF1} \) and 2.5-V, 3.3-V, or 5-V \( V_{REF2} \)
  - 2.5-V \( V_{REF1} \) and 3.3-V or 5-V \( V_{REF2} \)
  - 3.3-V \( V_{REF1} \) and 5-V \( V_{REF2} \)
- Provides bidirectional voltage translation with no direction pin
- Low ON-state resistance between input and output ports provides less signal distortion
- Open-drain I²C I/O ports (SCL1, SDA1, SCL2, and SDA2)
- 5-V Tolerant I²C I/O ports to support mixed-mode signal operation
- High-impedance SCL1, SDA1, SCL2, and SDA2 pins for EN = Low
- Lockup-free operation for isolation when EN = Low
- Flow-through pinout for ease of printed-circuit-board trace routing
- ESD Protection Exceeds JESD 22
  - 2000-V human-body model (A114-A)
  - 1000-V charged-device model (C101)

2 Applications

- I²C, SMBus, PMBus, MDIO, UART, low-speed SDIO, GPIO, and other two-signal interfaces
- Servers
- Routers (telecom switching equipment)
- Personal computers
- Industrial automation

3 Description

The TCA39306-Q1 is a dual bidirectional voltage-level translator compatible with I²C, SMBus, and I³C with an enable (EN) input, and is operational from 0.9-V to 3.3-V \( V_{REF1} \) and 1.8-V to 5.5-V \( V_{REF2} \).

The device allows bidirectional voltage translations between 0.85 V and 5 V, without the use of a direction pin. The low ON-state resistance (\( R_{ON} \)) of the switch allows connections to be made with minimal propagation delay. When EN is high, the translator switch is ON, and the SCL1 and SDA1 I/O are connected to the SCL2 and SDA2 I/O, respectively, allowing bidirectional data flow between ports. When EN is low, the translator switch is off, and a high-impedance state exists between ports.

In addition to voltage translation, the TCA39306-Q1 can be used to isolate a higher speed bus from a lower speed bus by controlling the EN pin to disconnect the slower bus during fast-mode communication.

Device Information

<table>
<thead>
<tr>
<th>PART NUMBER</th>
<th>PACKAGE(1)</th>
<th>BODY SIZE (NOM)</th>
</tr>
</thead>
<tbody>
<tr>
<td>TCA39306-Q1</td>
<td>VSSOP (8)</td>
<td>2.30 mm x 2.00 mm</td>
</tr>
</tbody>
</table>

(1) For all available packages, see the orderable addendum at the end of the datasheet.

![Simplified Application Diagram]
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4 Revision History
NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision * (June 2021) to Revision A (December 2021)

- Changed the document from Advanced Information to Production data.
5 Pin Configuration and Functions

![DCU Package, 8-Pin VSSOP, Top View](image)

**Table 5-1. Pin Functions**

<table>
<thead>
<tr>
<th>PIN NAME</th>
<th>NO.</th>
<th>I/O</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>DCU EN</td>
<td>8</td>
<td>I</td>
<td>Switch enable input</td>
</tr>
<tr>
<td>DCU GND</td>
<td>1</td>
<td>—</td>
<td>Ground, 0 V</td>
</tr>
<tr>
<td>DCU SCL1</td>
<td>3</td>
<td>I/O</td>
<td>Serial clock, low-voltage side</td>
</tr>
<tr>
<td>DCU SCL2</td>
<td>6</td>
<td>I/O</td>
<td>Serial clock, high-voltage side</td>
</tr>
<tr>
<td>DCU SDA1</td>
<td>4</td>
<td>I/O</td>
<td>Serial data, low-voltage side</td>
</tr>
<tr>
<td>DCU SDA2</td>
<td>5</td>
<td>I/O</td>
<td>Serial data, high-voltage side</td>
</tr>
<tr>
<td>DCU VREF1</td>
<td>2</td>
<td>I</td>
<td>Low-voltage-side reference supply voltage for SCL1 and SDA1</td>
</tr>
<tr>
<td>DCU VREF2</td>
<td>7</td>
<td>I</td>
<td>High-voltage-side reference supply voltage for SCL2 and SDA2</td>
</tr>
</tbody>
</table>
6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)\(^{(1)}\)

<table>
<thead>
<tr>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>V_{REF1}</td>
<td>DC reference voltage range</td>
<td>-0.5</td>
</tr>
<tr>
<td>V_{REF2}</td>
<td>DC reference bias voltage range</td>
<td>-0.5</td>
</tr>
<tr>
<td>V_i</td>
<td>Input voltage range (^{(2)})</td>
<td>-0.5</td>
</tr>
<tr>
<td>V_{IO}</td>
<td>Input-output voltage range (^{(2)})</td>
<td>-0.5</td>
</tr>
<tr>
<td>I_{IX}</td>
<td>Continuous channel current</td>
<td>128</td>
</tr>
<tr>
<td>T_{J(\text{Max})}</td>
<td>Junction temperature</td>
<td>150</td>
</tr>
<tr>
<td>T_{stg}</td>
<td>Storage temperature</td>
<td>-65</td>
</tr>
</tbody>
</table>

\(^{(1)}\) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

\(^{(2)}\) The input and input-output negative voltage ratings may be exceeded if the input and output current ratings are observed.

6.2 ESD Ratings

<table>
<thead>
<tr>
<th>VALUE</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>V_{(ESD)} ^{(1)}</td>
<td>Electrostatic discharge</td>
</tr>
<tr>
<td>Human body model (HBM), per ANSI/ESDA/ JEDEC JS-001 (^{(1)})</td>
<td>±2000</td>
</tr>
<tr>
<td>Charged device model (CDM), per ANSI/ESDA/ JEDEC JS-002 (^{(2)})</td>
<td>±1000</td>
</tr>
</tbody>
</table>

\(^{(1)}\) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

\(^{(2)}\) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>V_{IO}</td>
<td>Input-output voltage</td>
<td>SCL1, SDA1, SCL2, SDA2</td>
</tr>
<tr>
<td>V_{REF1} (^{(1)})</td>
<td>Reference Voltage</td>
<td>0</td>
</tr>
<tr>
<td>V_{REF2} (^{(1)})</td>
<td>Reference Voltage</td>
<td>0</td>
</tr>
<tr>
<td>EN^{(2)}</td>
<td>Switch mode enable voltage (Switch mode enable voltage)</td>
<td>1.5</td>
</tr>
<tr>
<td>EN</td>
<td>Enable input voltage</td>
<td>0</td>
</tr>
<tr>
<td>I_{PASS}</td>
<td>Pass switch current</td>
<td>64</td>
</tr>
<tr>
<td>T_A</td>
<td>Ambient temperature</td>
<td>-40</td>
</tr>
</tbody>
</table>

\(^{(1)}\) To support translation, \(V_{REF1}\) supports 0.85 V to \(V_{REF2}\) - 0.6 V. \(V_{REF2}\) must be between \(V_{REF1} + 0.6 \text{ V}\) to 5.5 V. See Typical Application for more information.

\(^{(2)}\) To support switching, \(V_{REF1}\) and \(V_{REF2}\) Do not need to be connected. EN pin should use a voltage not less than 1.5V when the switch mode is to be enabled. Enabled voltage on this pin should be equal to 1.5V or I/O supply voltage, whichever is higher.
6.4 Thermal Information

<table>
<thead>
<tr>
<th>THERMAL METRIC(1)</th>
<th>TCA39306-Q1</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$R_{ja}$</td>
<td>275.5</td>
<td>°C/W</td>
</tr>
<tr>
<td>$R_{jct}$</td>
<td>127.1</td>
<td>°C/W</td>
</tr>
<tr>
<td>$R_{jb}$</td>
<td>186.9</td>
<td>°C/W</td>
</tr>
<tr>
<td>$\Psi_{jt}$</td>
<td>65.7</td>
<td>°C/W</td>
</tr>
<tr>
<td>$\Psi_{jb}$</td>
<td>185.9</td>
<td>°C/W</td>
</tr>
</tbody>
</table>

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

6.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP (1)</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{IK}$</td>
<td>$I_i = -18 \text{ mA}$</td>
<td>EN = 0 V</td>
<td>-1.2</td>
<td>0</td>
<td>V</td>
</tr>
<tr>
<td>$I_{IH}$</td>
<td>$V_i = 5 \text{ V}, V_o = 0 \text{ V}$</td>
<td>EN = 0 V</td>
<td>5</td>
<td>µA</td>
<td></td>
</tr>
<tr>
<td>$V_T$</td>
<td>$I_o = 500 \mu \text{A}$</td>
<td>$V_i = 0.1 \text{ V}, V_o = 0 \text{ V}$, Find $V_{EN}$ where $I_o = 500 \mu \text{A}$</td>
<td>0.7</td>
<td>1.0</td>
<td>V</td>
</tr>
<tr>
<td>$C_{I(EN)}$</td>
<td>$V_i = 3 \text{ V or 0 V}$</td>
<td></td>
<td>11</td>
<td>pF</td>
<td></td>
</tr>
<tr>
<td>$C_{IO(off)}$</td>
<td>SCLn, SDAn</td>
<td>$V_o = 3 \text{ V or 0 V}$</td>
<td>EN = 0 V</td>
<td>4</td>
<td>6</td>
</tr>
<tr>
<td>$C_{IO(on)}$</td>
<td>SCLn, SDAn</td>
<td>$V_o = 3 \text{ V or 0 V}$</td>
<td>EN = 3 V</td>
<td>10.5</td>
<td>12.5</td>
</tr>
<tr>
<td>$R_{ON}$ (2)</td>
<td>SCLn, SDAn (~40 to 125°C)</td>
<td>$V_i = 0 \text{ V}$</td>
<td>$I_o = 64 \text{ mA}$</td>
<td>EN = 4.5 V</td>
<td>3.5</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$V_i = 0 \text{ V}$</td>
<td>$I_o = 64 \text{ mA}$</td>
<td>EN = 3 V</td>
<td>4.7</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$V_i = 0 \text{ V}$</td>
<td>$I_o = 64 \text{ mA}$</td>
<td>EN = 2.3 V</td>
<td>6.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$V_i = 0 \text{ V}$</td>
<td>$I_o = 15 \text{ mA}$</td>
<td>EN = 1.5 V</td>
<td>25.5</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$V_i = 2.4 \text{ V}$</td>
<td>$I_o = 15 \text{ mA}$</td>
<td>EN = 4.5 V</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$V_i = 2.4 \text{ V}$</td>
<td>$I_o = 15 \text{ mA}$</td>
<td>EN = 3 V</td>
<td>20</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$V_i = 1.7 \text{ V}$</td>
<td>$I_o = 15 \text{ mA}$</td>
<td>EN = 2.3 V</td>
<td>20</td>
</tr>
</tbody>
</table>
### 6.5 Electrical Characteristics (continued)

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>( R_{\text{ON}} )</td>
<td>On-state resistance</td>
<td>( V_1 = 0 \text{ V}, \ V_{\text{CC}2} = 5 \text{ V}(5) )</td>
<td>( I_0 = 64 \text{ mA} )</td>
<td>( V_{\text{CC}1} = 1 \text{ V} )</td>
<td>5</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( V_{\text{CC}1} = 1.8 \text{ V} )</td>
<td>4</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( V_{\text{CC}1} = 2.5 \text{ V} )</td>
<td>3</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( V_{\text{CC}1} = 3.3 \text{ V} )</td>
<td>3</td>
</tr>
<tr>
<td></td>
<td>SCLn, SDAn</td>
<td>( V_1 = 1.8 \text{ V}, \ V_{\text{CC}2} = 5 \text{ V}(5) )</td>
<td>( I_0 = 15 \text{ mA} )</td>
<td>( V_{\text{CC}1} = 3.3 \text{ V} )</td>
<td>4</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( V_{\text{CC}1} = 1 \text{ V} )</td>
<td>5</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( V_{\text{CC}1} = 1.8 \text{ V} )</td>
<td>4</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( V_{\text{CC}1} = 2.5 \text{ V} )</td>
<td>3</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( V_{\text{CC}1} = 3.3 \text{ V} )</td>
<td>3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( V_1 = 1 \text{ V}, \ V_{\text{CC}2} = 3.3 \text{ V}(5) )</td>
<td>( I_0 = 10 \text{ mA} )</td>
<td>( V_{\text{CC}1} = 1.8 \text{ V} )</td>
<td>7</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( V_{\text{CC}1} = 1 \text{ V} )</td>
<td>5</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( V_1 = 0 \text{ V}, \ V_{\text{CC}2} = 3.3 \text{ V}(5) )</td>
<td>( I_0 = 10 \text{ mA} )</td>
<td>( V_{\text{CC}1} = 1 \text{ V} )</td>
<td>6</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( V_1 = 0 \text{ V}, \ V_{\text{CC}2} = 1.8 \text{ V}(5) )</td>
<td>( I_0 = 10 \text{ mA} )</td>
<td>( V_{\text{CC}1} = 1 \text{ V} )</td>
<td>5</td>
</tr>
</tbody>
</table>

(1) All typical values are at \( T_A = 25^\circ \text{C} \).
(2) Measured by the voltage drop between the SCL1 and SCL2, or SDA1 and SDA2 terminals, at the indicated current through the switch. Minimum ON-state resistance is determined by the lowest voltage of the two terminals.
(3) Measured in current source configuration only. See Figure 7-1
(4) Measured in current sink configuration only. See Figure 7-1
(5) Measured in application connected current source configuration only. See Figure 7-3

### 6.6 Switching Characteristics (Translating Down)

over operating free-air temperature range (unless otherwise noted)[(1)]

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>( T_{\text{PLH}} )</td>
<td>Low-to-high propagation delay</td>
<td>( EN = 3.3 \text{ V}, \ V_{\text{IH}} = 3.3 \text{ V}, \ V_{L} = 0, \ V_{M} = 1.15 \text{ V}(2) )</td>
<td>( C_L = 15 \text{ pF} )</td>
<td>0</td>
<td>0.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( C_L = 30 \text{ pF} )</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( C_L = 50 \text{ pF} )</td>
<td>0</td>
</tr>
<tr>
<td>( T_{\text{PHL}} )</td>
<td>High to low propagation delay</td>
<td>( EN = 1.15 \text{ V}(2) )</td>
<td>( C_L = 15 \text{ pF} )</td>
<td>0</td>
<td>0.75</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( C_L = 30 \text{ pF} )</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( C_L = 50 \text{ pF} )</td>
<td>0</td>
</tr>
<tr>
<td>( T_{\text{PLH}} )</td>
<td>Low-to-high propagation delay</td>
<td>( EN = 2.5 \text{ V}, \ V_{\text{IH}} = 3.3 \text{ V}, \ V_{L} = 0, \ V_{M} = 0.75 \text{ V}(2) )</td>
<td>( C_L = 15 \text{ pF} )</td>
<td>0</td>
<td>0.4</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( C_L = 30 \text{ pF} )</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( C_L = 50 \text{ pF} )</td>
<td>0</td>
</tr>
<tr>
<td>( T_{\text{PHL}} )</td>
<td>High to low propagation delay</td>
<td>( EN = 0.75 \text{ V}(2) )</td>
<td>( C_L = 15 \text{ pF} )</td>
<td>0</td>
<td>0.8</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( C_L = 30 \text{ pF} )</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( C_L = 50 \text{ pF} )</td>
<td>0</td>
</tr>
</tbody>
</table>
### 6.6 Switching Characteristics (Translating Down) (continued)

Over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$T_{PLH}$</td>
<td>Low-to-high propagation delay</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>$EN = 2.5\ V, V_{IH} = 2.5\ V, V_{IL} = 0, V_{M} = 0.75\ V^{(2)}$</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$T_{PHL}$</td>
<td>High to low propagation delay</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>$EN = 2.5\ V, V_{IH} = 2.5\ V, V_{IL} = 0, V_{M} = 0.75\ V^{(2)}$</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1. Guaranteed by simulation, not tested in production
2. Translating Down: the high-voltage side driving toward the low-voltage side. See Fig 7.2 Direct Propagation Measurement

### 6.7 Switching Characteristics (Translating Up)

Over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$T_{PLH}$</td>
<td>Low-to-high propagation delay</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>$EN = 3.3\ V, V_{IH} = 2.3\ V, V_{IL} = 3.3\ V, V_{M} = 1.15\ V^{(2)}$</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$T_{PHL}$</td>
<td>High to low propagation delay</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>$EN = 2.5\ V, V_{IH} = 2.5\ V, V_{IL} = 3.3\ V, V_{M} = 0.75\ V^{(2)}$</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1. Guaranteed by simulation, not tested in production
2. Translating up: the low-voltage side driving toward the high-voltage side. See Fig 7.2 Direct Propagation Measurement
### 6.8 Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>TPLH</strong></td>
<td>Low-to-high propagation delay(^{(1)})</td>
<td>13</td>
<td>32</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(V_{CC1} = 0.85) V, (V_{CC2} = 1.98) V, (R_{L_input} = 1.35) k(\Omega)</td>
<td>15</td>
<td>45</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(C_L = 15) pF</td>
<td>20</td>
<td>46</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(C_L = 50) pF</td>
<td>3</td>
<td>5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(C_L = 50) pF</td>
<td>3</td>
<td>5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(C_L = 50) pF</td>
<td>3</td>
<td>5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td><strong>TPHL</strong></td>
<td>High-to-low propagation delay(^{(1)})</td>
<td>3</td>
<td>4</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(V_{CC1} = 0.85) V, (V_{CC2} = 1.98) V, (R_{L_input} = 1.35) k(\Omega)</td>
<td>3</td>
<td>5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(C_L = 15) pF</td>
<td>3</td>
<td>5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(C_L = 50) pF</td>
<td>3</td>
<td>5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(C_L = 50) pF</td>
<td>3</td>
<td>5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(C_L = 50) pF</td>
<td>3</td>
<td>5</td>
<td>ns</td>
<td></td>
</tr>
</tbody>
</table>

\(^{(1)}\) Measured with an application propagation delay setup. See Figure 7-4
6.9 Typical Characteristics

**Figure 6-1. On-Resistance (R\textsubscript{ON}) vs Input Voltage (V\textsubscript{SDA1} or V\textsubscript{SCL1})**

- **VEN = 1.5 V**
- **I\textsubscript{I} = 15 mA**

**Figure 6-2. On-Resistance (R\textsubscript{ON}) vs Input Voltage (V\textsubscript{SDA1} or V\textsubscript{SCL1})**

- **VEN = 4.5 V**
- **I\textsubscript{I} = 15 mA**

**Figure 6-3. Typical Bandwidth**

- **VEN = 2.5 V**
- **V\textsubscript{BIAS} = GND**
7 Parameter Measurement Information

A) Current Source Configuration

B) Current Sink Configuration

Figure 7-1. Current Source and Current Sink Configurations for Direct $R_{ON}$ Measurements

Figure 7-2. Direct Propagation Measurement
Figure 7-3. Application Setup for $R_{ON}$ Delay

Figure 7-4. Application Setup for Propagation Delays Delay
Figure 7-5. Load Circuit for Outputs

NOTES:
A. $C_L$ includes probe and jig capacitance
B. All input pulses are supplied by generators having the following characteristics: $PRR \leq 10 \text{ MHz}$, $Z_0 = 50 \Omega$, $t_r \leq 2 \text{ ns}$, $t_f \leq 2 \text{ ns}$.
C. The outputs are measured one at a time, with one transition per measurement.
8 Detailed Description
8.1 Overview

The TCA39306-Q1 is a dual bidirectional voltage-level translator compatible with I²C, SMBus, and I³C with an enable (EN) input, and is operational from 0.9-V to 3.3-V \(V_{\text{REF1}}\) and 1.8-V to 5.5-V \(V_{\text{REF2}}\).

The device allows bidirectional voltage translations between 0.85 V and 5 V, without the use of a direction pin. The low ON-state resistance (\(R_{\text{ON}}\)) of the switch allows connections to be made with minimal propagation delay. When EN is high, the translator switch is ON, and the SCL1 and SDA1 I/O are connected to the SCL2 and SDA2 I/O, respectively, allowing bidirectional data flow between ports. When EN is low, the translator switch is off, and a high-impedance state exists between ports.

In addition to voltage translation, the TCA39306-Q1 can be used to isolate a higher speed bus from a lower speed bus by controlling the EN pin to disconnect the slower bus during fast-mode communication.

In I²C applications, the bus capacitance limit of 400 pF for Standard and Fast Modes, 550 pF for Fast Mode Plus restricts the number of devices and bus length. The capacitive load on both sides of the device must be taken into account when approximating the total load of the system, specifying the sum of both sides is under 400/550 pF.

Both the SDA and SCL channels of the device have the same electrical characteristics, and there is minimal deviation from one output to another in voltage or propagation delay. This is a benefit over discrete-transistor voltage-translation solutions, because the fabrication of the switch is symmetrical.

8.1.1 Definition of threshold voltage

This document references a threshold voltage denoted as \(V_{\text{th}}\), which appears multiple times throughout this document when discussing the NFET between \(V_{\text{REF1}}\) and \(V_{\text{REF2}}\). The value of \(V_{\text{th}}\) is approximately 0.6 V at room temperature.

8.1.2 Correct Device Set Up

In a normal set up shown in Figure 8-1, the enable pin and \(V_{\text{REF2}}\) are shorted together and tied to a 200-kΩ resistor, and a reference voltage equal to \(V_{\text{REF1}}\) plus the FET threshold voltage is established. This reference voltage is used to help pass lows from one side to another more effectively while still separating the different pull up voltages on both sides.

![Figure 8-1. Normal Setup](image-url)

Care should be taken to make sure \(V_{\text{REF2}}\) has an external resistor tied between it and \(V_{\text{CC2}}\). If \(V_{\text{REF2}}\) is tied directly to the \(V_{\text{CC2}}\) rail without a resistor, then there is no external resistance from the \(V_{\text{CC2}}\) to \(V_{\text{CC1}}\) to limit the current such as in Figure 8-2. This effectively looks like a low impedance path for current to travel through and...
potentially break the pass FET if the current flowing through the pass FET is larger than the absolute maximum continuous channel current specified in the Absolute Maximum Ratings. The continuous channel current is larger with a higher voltage difference between \( V_{CC1} \) and \( V_{CC2} \).

Figure 8-2 shows an improper set up. If \( V_{CC2} \) is larger than \( V_{CC1} \) but less than \( V_{th} \), the impedance between \( V_{CC1} \) and \( V_{CC2} \) is high resulting in a low drain to source current, which does not cause damage to the device. Concern arises when \( V_{CC2} \) becomes larger than \( V_{CC1} \) by \( V_{th} \). During this event, the NFET turns on and begin to conduct current. This current is dependent on the gate to source voltage and drain to source voltage.

8.1.3 Disconnecting a Responder from the Main Bus Using the EN Pin

TCA39306-Q1 can be used as a switch to disconnect one side of the device from the main bus, whether isolating \( \text{I}^2\text{C} \) and \( \text{I}^\text{2C} \) devices or different speed groups. This can be advantageous in multiple situations. One instance of this situation is if there are devices on the \( \text{I}^\text{2C} \) bus which only supports fast mode (400 kHz) while other devices on the bus support fast mode plus (1 MHz). An example of this is displayed in Figure 8-3.

![Figure 8-3. Example of an \( \text{I}^\text{2C} \) bus with multiple supported frequencies](image)

In this situation, if the controller is on the 1 MHz side then communicating at 1 MHz should not be attempted if TCA39306-Q1 were enabled. It needs to be disabled for the device to avoid possibly glitching state machines in devices which were designed to operate correctly at 400 kHz or slower. When the device is disabled, the controller can communicate with the 1 MHz devices without disturbing the 400 kHz bus. When the device is enabled, communication across both sides at 400 kHz is acceptable.

8.1.4 Supporting Remote Board Insertion to Backplane with TCA39306-Q1

Another situation where TCA39306-Q1 is advantageous when using its enable feature is when a remote board with \( \text{I}^2\text{C} \) lines needs to be attached to a main board (backplane) with an \( \text{I}^\text{2C} \) bus such as in Figure 8-4. If connecting a remote board to a backplane is not done properly, the connection could result in data corruption during a transaction or the insertion could generate an unintended pulse on the SCL line. Which could glitch an \( \text{I}^\text{2C} \) device state machine causing the \( \text{I}^\text{2C} \) bus to get stuck.
TCA39306-Q1 can be used to support this application because it can be disabled while making the connection. Then it is enabled once the remote board is powered on and the buses on both sides are IDLE.

### 8.1.5 Switch Configuration

TCA39306-Q1 has the capability of being used with its \( V_{REF1} \) voltage equal to \( V_{REF2} \). This essentially turns the device from a translator to a device which can be used as a switch, and in some situations this can be useful. The switch configuration is shown in Figure 8-5 and translation mode is shown in Figure 8-6.

When TCA39306-Q1 is in the switch configuration (\( V_{REF1} = V_{REF2} \)), the propagation delays are different compared to the translator configuration. Taking a look at the propagation delays, if the pull up resistance and capacitance on both sides of the bus are equal, then in switch mode the device has the same propagation delay from side one to two and side two to one. The propagation delays become lower when \( V_{CC1}/V_{CC2} \) is larger. For example, the propagation delay at 1.8 V is longer than at 5 V in the switching configuration. When the device is

---

**Figure 8-4. An example of connecting a remote board to a main board (backplane)**

**Figure 8-5. Switch Configuration**

**Figure 8-6. Translation Configuration**
in translation mode, side one propagate lows to side two faster than side two can propagate lows to side 1. This time difference becomes larger the larger the difference between $V_{CC2}$ and $V_{CC1}$ becomes.

8.1.6 Controller on Side 1 or Side 2 of Device

I2C and SMBus are bidirectional protocol meaning devices on the bus can both transmit and receive data. TCA39306-Q1 was designed to allow for signals to be able to be transmitted from either side, thus allowing for the controller to be able to place on either side of the device. Figure 8-7 shows the controller on side two as opposed to the diagram on page 1 of this data sheet.

![Figure 8-7. Controller on side 2](image)

8.1.7 LDO and TCA39306-Q1 Concerns

The $V_{REF1}$ pin can be supplied by a low-dropout regulator (LDO), but in some cases the LDO may lose its regulation because of the bias current from $V_{REF2}$ to $V_{REF1}$. If the LDO cannot sink the bias current, then the current has no other paths to ground and instead charges up the capacitance on the $V_{REF1}$ node (both external and parasitic). This results in an increase in voltage on the $V_{REF1}$ node. If no other paths for current to flow are established (such as back biasing of body diodes or clamping diodes through other devices on the $V_{REF1}$ node), then the $V_{REF1}$ voltage ends up stabilizing when $V_{gs}$ of the pass FET is equal to $V_{th}$. This means $V_{REF1}$ node voltage is $V_{CC2} - V_{th}$. Note that any secondary or primaries running off of the LDO now see the $V_{CC2} - V_{th}$ voltage which may cause damage to those secondary or primaries if they are not rated to handle the increased voltage.

![Figure 8-8. Example of no leakage current path when using LDO](image)

To make sure the LDO does not lose regulation due to the bias current of TCA39306-Q1, a weak pull down resistor can be placed on $V_{REF1}$ to ground to provide a path for the bias current to travel. The recommended pull down resistor is calculated by Equation 4 where 0.75 gives about 25% margin for error incase bias current increases during operation.
Figure 8-9. Example with Leakage current path when using an LDO

\[ V_{en} = V_{REF1} + V_{th} \]  
\[ \text{(1)} \]

where

- \( V_{th} \) is approximately 0.6 V

\[ I_{bias} = (V_{CC2} - V_{en})/200 \text{ k} \]  
\[ \text{(2)} \]

\[ R_{pulldown} = V_{OUT}/I_{bias} \]  
\[ \text{(3)} \]

Recommended \( R_{pulldown} = R_{pulldown} \times 0.75 \)  
\[ \text{(4)} \]

8.1.8 Current Limiting Resistance on \( V_{REF2} \)

The resistor is used to limit the current between \( V_{REF2} \) and \( V_{REF1} \) (denoted as \( R_{CC} \)) and helps to establish the reference voltage on the enable pin. The 200k resistor can be changed to a lower value; however, the bias current proportionally increases as the resistor decreases.

\[ I_{bias} = (V_{CC2} - V_{en})/R_{CC} : V_{en} = V_{REF1} + V_{th} \]  
\[ \text{(5)} \]

where

- \( V_{th} \) is approximately 0.6 V

Keep in mind \( R_{CC} \) should not be sized low enough that \( I_{CC} \) exceeds the absolute maximum continuous channel current specified in the Absolute Maximum Ratings which is described in Equation 6.

\[ R_{CC(min)} \geq (V_{CC2} - V_{en})/0.128 : V_{en} = V_{REF1} + V_{th} \]  
\[ \text{(6)} \]

where

- \( V_{th} \) is approximately 0.6 V
8.2 Functional Block Diagram

8.3 Feature Description

8.3.1 Enable (EN) Pin

The device is a double-pole, single-throw switch in which the gate of the transistors is controlled by the voltage on the EN pin. In Figure 9-1, the device is always enabled when power is applied to \( V_{\text{REF2}} \). In Figure 9-2, the device is enabled when a control signal from a processor is in a logic-high state.

8.3.2 Voltage Translation

The primary feature of the device is translating voltage from an \( \text{I}^2\text{C} \) bus referenced to \( V_{\text{REF1}} \) up to an \( \text{I}^2\text{C} \) bus referenced to \( V_{\text{DPU}} \), to which \( V_{\text{REF2}} \) is connected through a 200-k\( \Omega \) pullup resistor. Translation on a standard, open-drain \( \text{I}^2\text{C} \) bus is achieved by simply connecting pullup resistors from SCL1 and SDA1 to \( V_{\text{REF1}} \) and connecting pullup resistors from SCL2 and SDA2 to \( V_{\text{DPU}} \). Information on sizing the pullup resistors can be found in the Sizing Pullup Resistors section.

8.4 Device Functional Modes

<table>
<thead>
<tr>
<th>INPUT EN(^{(1)})</th>
<th>TRANSLATOR FUNCTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>( H )</td>
<td>Logic Lows are propagated from one side to the other, Logic Highs blocked (independent pull up resistors passively drive the line high)</td>
</tr>
<tr>
<td>( L )</td>
<td>Disconnect</td>
</tr>
</tbody>
</table>

\(^{(1)}\) The SCL switch conducts if EN is \( \geq 0.6 \text{ V} \) higher than SCL1 or SCL2. The same is true of SDA.
9 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI’s customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

9.1 Application Information

9.1.1 General Applications of I^2C

As with the standard I^2C system, pullup resistors are required to provide the logic-high levels on the translator bus. The size of these pullup resistors depends on the system, but each side of the repeater must have a pullup resistor. The device is designed to work with standard-mode and fast-mode I^2C devices in addition to SMBus devices. Standard-mode I^2C devices only specify 3 mA in a generic I^2C system where standard-mode devices and multiple controllers are possible. Under certain conditions, high termination currents can be used. When the SDA1 or SDA2 port is low, the clamp is in the ON state, and a low-resistance connection exists between the SDA1 and SDA2 ports. Assuming the higher voltage is on the SDA2 port when the SDA2 port is high, the voltage on the SDA1 port is limited to the voltage set by V_{REF1}. When the SDA1 port is high, the SDA2 port is pulled to the pullup supply voltage of the drain (V_{DP1}) by the pullup resistors. This functionality allows a seamless translation between higher and lower voltages selected by the user, without the need for directional control. The SCL1-SCL2 channel also functions in the same way as the SDA1-SDA2 channel.

9.2 Typical Application

Figure 9-1 and Figure 9-2 show how these pullup resistors are connected in a typical application, as well as two options for connecting the EN pin.

![Typical Application Circuit (Switch Always Enabled)](image_url)
9.2.1 Design Requirements

<table>
<thead>
<tr>
<th></th>
<th>MIN</th>
<th>TYP(^{(1)})</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>(V_{\text{REF2}})</td>
<td>Reference voltage</td>
<td>(V_{\text{REF1}} + 0.6)</td>
<td>2.1</td>
<td>5 V</td>
</tr>
<tr>
<td>EN</td>
<td>Enable input voltage</td>
<td>(V_{\text{REF1}} + 0.6)</td>
<td>2.1</td>
<td>5 V</td>
</tr>
<tr>
<td>(V_{\text{REF1}})</td>
<td>Reference voltage</td>
<td></td>
<td>0.9</td>
<td>1.5</td>
</tr>
<tr>
<td>(I_{\text{PASS}})</td>
<td>Pass switch current</td>
<td></td>
<td>6</td>
<td>mA</td>
</tr>
<tr>
<td>(I_{\text{REF}})</td>
<td>Reference-transistor current</td>
<td></td>
<td>5</td>
<td>µA</td>
</tr>
</tbody>
</table>

\(^{(1)}\) All typical values are at \(T_A = 25^\circ\) C.

9.2.2 Detailed Design Procedure

9.2.2.1 Bidirectional Voltage Translation

For the bidirectional clamping configuration (higher voltage to lower voltage or lower voltage to higher voltage), the EN input must be connected to \(V_{\text{REF2}}\) and both pins pulled to high-side \(V_{\text{DPU}}\) through a pullup resistor (typically 200 kΩ). This allows \(V_{\text{REF2}}\) to regulate the EN input. A 100-pF filter capacitor connected to \(V_{\text{REF2}}\) is recommended. The \(I^2C\) bus controller output can be push-pull or open-drain (pullup resistors may be required) and the \(I^2C\) bus device output can be open-drain (pullup resistors are required to pull the SCL2 and SDA2 outputs to \(V_{\text{DPU}}\)). However, if either output is push-pull, data must be unidirectional or the outputs must be 3-state capable and be controlled by some direction-control mechanism to prevent high-to-low contentions in either direction. If both outputs are open-drain, no direction control is needed.

9.2.2.2 Sizing Pullup Resistors

To get an estimate for the range of values that can be used for the pullup resistor, please refer to the application note SLVA689. Figure 9-3 and Figure 9-4 respectively show the maximum and minimum pullup resistance allowable by the \(I^2C\) specification for standard-mode (100 kHz) and fast-mode (400 kHz) operation.
9.2.2.3 Bandwidth

The maximum frequency of the device depends on the application. The device can operate at speeds of > 100 MHz given the correct conditions. The maximum frequency is dependent upon the loading of the application.

However, this is an analog type of measurement. For digital applications, the signal should not degrade up to the fifth harmonic of the digital signal. The frequency bandwidth should be at least five times the maximum digital clock rate. This component of the signal is important in determining the overall shape of the digital signal. In the case of the device, digital clock frequency of > 100 MHz can be achieved.

The device does not provide any drive capability like the TCA9517 or other buffered translators. Therefore, higher-frequency applications require higher drive strength from the host side. No pullup resistor is needed on the host side (3.3 V) if the device is being driven by standard CMOS push-pull output driver. Ideally, it is best to minimize the trace length from device on the sink side (1.8 V) to minimize signal degradation.

You can then use a simple formula to compute the maximum practical frequency component or the knee frequency (\( f_{\text{knee}} \)). All fast edges have an infinite spectrum of frequency components. However, there is an inflection (or knee) in the frequency spectrum of fast edges where frequency components higher than \( f_{\text{knee}} \) are insignificant in determining the shape of the signal.

To calculate \( f_{\text{knee}} \):

\[
\begin{align*}
    f_{\text{knee}} &= 0.5 / RT \quad (10\%-90\%) \\
    f_{\text{knee}} &= 0.4 / RT \quad (20\%-80\%)
\end{align*}
\]

For signals with rise-time characteristics based on 10- to 90-percent thresholds, \( f_{\text{knee}} \) is equal to 0.5 divided by the rise time of the signal. For signals with rise-time characteristics based on 20- to 80-percent thresholds, which is very common in many current device specifications, \( f_{\text{knee}} \) is equal to 0.4 divided by the rise time of the signal.

Some guidelines to follow that help maximize the performance of the device:
- Keep trace length to a minimum by placing the device close to the \( \text{I}^2\text{C} \) output of the processor.
- The trace length should be less than half the time of flight to reduce ringing and line reflections or non-monotonic behavior in the switching region.
- To reduce overshoots, a pullup resistor can be added on the 1.8 V side; be aware that a slower fall time is to be expected.

9.2.3 Application Curve

![Figure 9-3. Maximum Pullup Resistance (\( R_{p(\text{max})} \)) vs Bus Capacitance (\( C_b \))](image)

<table>
<thead>
<tr>
<th>Mode</th>
<th>Condition</th>
<th>Rise Time (ns)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standard mode</td>
<td>( f_{\text{SCL}} = 100 , \text{kHz}, ) (&lt; t_r = 1 , \mu\text{s} )</td>
<td>( t_r = 1 , \mu\text{s} )</td>
</tr>
<tr>
<td>Fast mode</td>
<td>( f_{\text{SCL}} = 400 , \text{kHz}, ) (&lt; t_r = 300 , \text{ns} )</td>
<td>( t_r = 300 , \text{ns} )</td>
</tr>
<tr>
<td>Fast mode plus</td>
<td>( f_{\text{SCL}} = 1000 , \text{kHz}, ) (&lt; t_r = 120 , \text{ns} )</td>
<td>( t_r = 120 , \text{ns} )</td>
</tr>
</tbody>
</table>

![Figure 9-4. Minimum Pullup Resistance (\( R_{p(\text{min})} \)) vs Pullup Reference Voltage (\( V_{\text{DPUX}} \))](image)

\[
\begin{align*}
    V_{\text{OL}} &= 0.2 \times V_{\text{DPUX}} \quad \text{for} \ V_{\text{DPUX}} \leq 2 \, \text{V} \\
    V_{\text{OL}} &= 0.4 \, \text{V} \quad \text{for} \ V_{\text{DPUX}} > 2 \, \text{V}
\end{align*}
\]
9.3 Systems Examples: I3C Usage Considerations

The TCA39306-Q1 has bandwidth to support the high speeds needed for I3C, but there are special considerations which are required. Since I3C uses both push-pull and open-drain, it may not be possible to support all I3C applications with a FET-based translator.

9.3.1 I3C Bus Switching

Bus switching is when the bus path is enabled or disabled, but does not translate the bus voltage. External pull-up resistors are not needed for I3C, because the controller enables or disables the pull-up resistor on the SDA line. This presents a unique challenge for FET-based translators, like the TCA39306-Q1, because they rely on a pull-up resistor to pull the output side of the switch all the way to supply. For the switching use case, there is no translation, but the enable voltage must be high enough for the switch to stay on for the entire voltage range of the bus (0 V to bus voltage).

$R_{\text{ON}}$ must be low enough for the full push-pull voltage range. The EN voltage must be at least $1 \text{ V} (\sim 0.6 \text{ V})$ above the maximum desired pass-voltage. This comes out to $V_{\text{EN}} \geq V_{\text{BUS}} + 0.6 \text{ V}$. Since the switch enable voltage is being directly controlled, the $V_{\text{REF1}}$ and $V_{\text{REF2}}$ pins are not needed, and can be shorted to ground to improve power consumption.

It is possible to control the EN pin with a voltage equal to $V_{\text{BUS}}$, but external pull-up resistors on the downstream side are a requirement to ensure the bus is pulled entirely to $V_{\text{BUS}}$.

![Figure 9-5. I3C Bus Switching Application (Without Pull-up Resistors)](image-url)
Figure 9-6. I3C Bus Switching Application (With Pull-up Resisters)

9.3.2 I3C Bus Voltage Translation

Bus voltage translation is when the bus voltage is translated up or down. This presents a unique challenge with I3C for FET-based translators, like the TCA39306-Q1, because they rely on a pull-up resistor to translate the voltage up from the low-voltage side. The pull-up resistor selected must be strong enough to meet the timing requirements (based on bus capacitance and translation voltages), but not so strong to violate the $V_{IL}$ requirements of the I3C devices.

The pull-up resistors are needed on both sides. The reason for this is that with the normal translation setup, the switch is "on" when either side's bus voltage drops to roughly $V_{PU_1}$. This means that the pull-up resistors are required to pull the bus voltage on the high-voltage side from $V_{PU_1}$ to $V_{PU_2}$. When the device on the high-voltage side is controlling the bus, the switch will turn off at $V_{PU_1}$. The pull-up resistors on the low-voltage side are used to bleed off any additional current that might "leak" through the switch.
**10 Power Supply Recommendations**

For supplying power to the device, the $V_{REF1}$ pin can be connected directly to a power supply. The $V_{REF2}$ pin must be connected to the $V_{DPU}$ power supply through a 200-kΩ resistor. Failure to have a high-impedance resistor between $V_{REF2}$ and $V_{DPU}$ results in excessive current draw and unreliable device operation. It is also worth noting, that in order to support voltage translation, the device must have the EN and $V_{REF2}$ pins shorted and then pulled up to $V_{DPU}$ through a high-impedance resistor.
11 Layout

11.1 Layout Guidelines

For printed-circuit board (PCB) layout of the device, common PCB layout practices should be followed, but additional concerns related to high-speed data transfer such as matched impedances and differential pairs are not a concern for I^2C signal speeds.

In all PCB layouts, it is a best practice to avoid right angles in signal traces, to fan out signal traces away from each other on leaving the vicinity of an integrated circuit (IC), and to use thicker trace widths to carry higher amounts of current that commonly pass through power and ground traces. The 100-pF filter capacitor should be placed as close to VREF as possible. A larger decoupling capacitor can also be used, but a longer time constant of two capacitors and the 200-kΩ resistor results in longer turnon and turnoff times for the TCA39306-Q1 device. These best practices are shown in Figure 11-1.

For the layout example provided in Figure 11-1, it would be possible to fabricate a PCB with only two layers by using the top layer for signal routing and the bottom layer as a split plane for power (VCC) and ground (GND). However, a four-layer board is preferable for boards with higher-density signal routing. On a four-layer PCB, it is common to route signals on the top and bottom layer, dedicate one internal layer to a ground plane, and dedicate the other internal layer to a power plane. In a board layout using planes or split planes for power and ground, vias are placed directly next to the surface-mount component pad, which must attach to VCC or GND, and the via is connected electrically to the internal layer or the other side of the board. Vias are also used when a signal trace must be routed to the opposite side of the board, but this technique is not demonstrated in Figure 11-1.

11.2 Layout Example

![Figure 11-1. Layout Example](image-url)
12 Device and Documentation Support

12.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on Alert me to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

12.2 Support Resources

TI E2E™ support forums are an engineer’s go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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12.3 Trademarks

TI E2E™ is a trademark of Texas Instruments.

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12.4 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

12.5 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most-current data available for the designated device. This data is subject to change without notice and without revision of this document. For browser-based versions of this data sheet, see the left-hand navigation pane.
## PACKAGING INFORMATION

<table>
<thead>
<tr>
<th>Orderable Device</th>
<th>Status</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>Package Qty</th>
<th>Eco Plan</th>
<th>Lead finish/ Ball material</th>
<th>MSL Peak Temp</th>
<th>Op Temp (°C)</th>
<th>Device Marking</th>
<th>Samples</th>
</tr>
</thead>
<tbody>
<tr>
<td>PTCA39306DCURQ1</td>
<td>ACTIVE</td>
<td>VSSOP</td>
<td>DCU</td>
<td>8</td>
<td>3000</td>
<td>TBD</td>
<td>Call TI</td>
<td>Call TI</td>
<td>-40 to 125</td>
<td></td>
<td></td>
</tr>
<tr>
<td>TCA39306DCURQ1</td>
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<td>VSSOP</td>
<td>DCU</td>
<td>8</td>
<td>3000</td>
<td>RoHS &amp; Green</td>
<td>NIPDAU</td>
<td>Level-1-260C-UNLIM</td>
<td>-40 to 125</td>
<td>2GST</td>
<td></td>
</tr>
</tbody>
</table>

(1) The marketing status values are defined as follows:

**ACTIVE**: Product device recommended for new designs.

**LIFEBUY**: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND**: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW**: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE**: TI has discontinued the production of the device.

(2) **RoHS**: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substances do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt**: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green**: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) **MSL, Peak Temp.** - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.
OTHER QUALIFIED VERSIONS OF TCA39306-Q1:

- Catalog: TCA39306

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product
### TAPE AND REEL INFORMATION

#### TAPE DIMENSIONS

- **A0**: Dimension designed to accommodate the component width
- **B0**: Dimension designed to accommodate the component length
- **K0**: Dimension designed to accommodate the component thickness
- **W**: Overall width of the carrier tape
- **P1**: Pitch between successive cavity centers

#### REEL DIMENSIONS

- **Reel Diameter**
- **Reel Width (W1)**

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

- **Q1**, **Q2**, **Q3**, **Q4**: Pocket Quadrants
- **Sprocket Holes**
- **User Direction of Feed**

*All dimensions are nominal*

<table>
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<tr>
<th>Device</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>SPQ</th>
<th>Reel Diameter (mm)</th>
<th>Reel Width W1 (mm)</th>
<th>A0 (mm)</th>
<th>B0 (mm)</th>
<th>K0 (mm)</th>
<th>P1 (mm)</th>
<th>W (mm)</th>
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### TAPE AND REEL BOX DIMENSIONS

*All dimensions are nominal

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*All dimensions are nominal
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