TPUL1G313-Q1 Automotive Single Retriggerable Pulse Generator With Extended RC Timing, Rising and Falling Edge Triggers, and Asynchronous Clear

1 Features

- AEC-Q100 qualified for automotive applications:
  - Device temperature grade 1: -40°C to +125°C
  - Device HBM ESD classification level 2
  - Device CDM ESD classification level C4B
- RC configurable from 10ms to 880s
- Extended pulse width functionality reduces capacitor value required for long pulse widths by factor of 1000
- For pulses less than 10ms, use TPUL1G123-Q1
- 1% typical, 10% maximum pulse width variation
- Wide operating range from 1.5V to 5.5V
- Inputs accept voltages up to 5.5V
- Schmitt-trigger architecture on all inputs

2 Applications

- Generate a positive fixed-width digital pulse
- Detect a digital signal rising edge
- Detect a digital signal falling edge
- Debounce a switch

3 Description

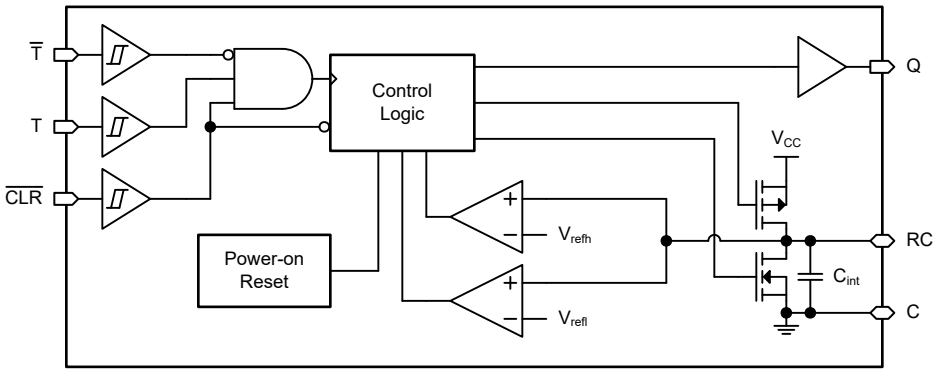
The TPUL1G313-Q1 device is a single RC configurable retriggerable monostable multivibrator designed for operation from 1.5V to 5.5V. The output pulse duration is configured by selecting external resistance and capacitance values with an approximate output pulse width of $t_w = 1000 \times R \times C$.

This device features three trigger inputs, allowing for rising edge (T) and falling edge ($\overline{T}$) triggers and a clear input ($\overline{CLR}$) that can be used asynchronously to stop an active output pulse, forcing the output low and resetting device. All trigger inputs include Schmitt-trigger architecture to allow for slow input transition rates and improve noise immunity.

Package Information

PART NUMBER	PACKAGE (1)	PACKAGE SIZE(2)	BODY SIZE
TPUL1G313-Q1	DCU (VSSOP, 8)	3.1mm × 2mm	2.3mm × 2mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.
(2) The package size (length × width) is a nominal value and includes pins, where applicable.



Functional Block Diagram

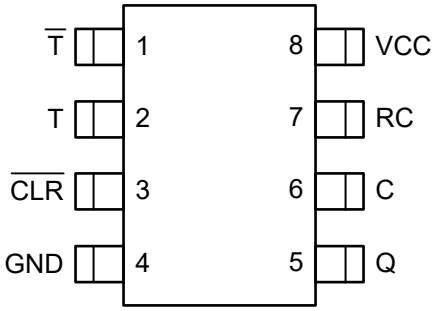
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4 Pin Configuration and Functions



See mechanical drawings for dimensions.

Figure 4-1. DCU Package 8-Pin VSSOP Top View

Table 4-1. Pin Functions

PIN		TYPE[1]	DESCRIPTION
NAME	NO.		
C	6	G	External timing capacitor negative connection; provides a return path for discharge current of the external timing capacitor; internally connected to ground
$\overline{CLR}$	3	I	Asynchronous clear input, active low; also can operate as rising edge trigger input if $\overline{T}$ is held low and T is held high
GND	4	G	Ground
Q	5	O	Output
RC	7	I/O	External timing node connection; see Section 8.1 for detailed operation instructions
$\overline{T}$	1	I	Falling edge trigger input; requires T and $\overline{CLR}$ to be held high
T	2	I	Rising edge trigger input; requires $\overline{T}$ to be held low and $\overline{CLR}$ to be held high
V_{CC}	8	P	Positive supply

(1) I = Input, O = Output, G = Ground, P = Power

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5 Specifications

5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

			MIN	MAX	UNIT
V_{CC}	Supply voltage range		–0.5	6.5	V
V_I	Digital input voltage range(2)		–0.5	6.5	V
V_O	Digital output voltage range in the active state		–0.5	V_{CC} + 0.5	V
V_O	Digital output voltage range in the high-impedance state(3)		–0.5	6.5	V
V_{RC}	RC pin voltage range		–0.5	V_{CC} + 0.5	V
I_{IK}	Input clamp diode current, V_I < -0.5V	continuous		–20	mA
		pulsed 1µs		–200	mA
I_{OK}	Output clamp diode current, V_I < -0.5V	continuous		–20	mA
		pulsed 1µs		–200	mA
I_O	Digital output current, V_O = 0 to V_{CC}	continuous		±50	mA
		pulsed 1µs		±200	mA
	Continuous current through V_{CC} or GND			±200	mA
R_{ext}	External timing resistance		1		kΩ
C_{ext}	External timing capacitance			1(3)	µF
T_J	Junction temperature			150	°C
T_{stg}	Storage temperature		–65	150	°C

(1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. Absolute maximum ratings do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If briefly operating outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not sustain damage, but it may not be fully functional. Operating the device in this manner may affect device reliability, functionality, performance, and shorten the device lifetime.
(2) The voltage ratings may be exceeded if the associated clamp diode current ratings are observed.
(3) The timing capacitance maximum value can be exceeded if an external diode is added. See *Application and Implementation* section for details.

5.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per AEC Q100-002 HBM ESD Classification Level 2(1)	±2000	V
		Charged device model (CDM), per AEC Q100-011 CDM ESD Classification Level C4B	±1000	

(1) AEC Q100-002 indicate that HBM stressing shall be in accordrance with the ANSI/ESDA/JEDEC JS-001 specification.

5.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
V_{CC}	Supply voltage		1.5	5.5	V
V_I	Input Voltage(1)		0	5.5	V
V_O	Output Voltage		0	V_{CC}	V
I_{OH} (2)	High-level output current	V_{CC} = 1.5V		–4	mA
		V_{CC} = 1.8V		–6	mA
		V_{CC} = 2.5V		–26	mA
		V_{CC} = 3V to 5.5V		–50	mA

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5.3 Recommended Operating Conditions (continued)

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
I_{OL} (2)	Low-level output current	V_{CC} = 1.5V		4	mA
		V_{CC} = 1.8V		6	mA
		V_{CC} = 2.5V		26	mA
		V_{CC} = 3V to 5.5V		50	mA
R_{ext} (3)	External timing resistance	V_{CC} = 1.5V to 5.5V	6.5	1000	kΩ
C_{ext} (3)	External timing capacitance	V_{CC} = 1.5V to 5.5V	0.1	1000	nF
t_{wo}	Configured output pulse width	V_{CC} = 1.5V to 5.5V	0.01	880	s
C_L	Digital output load capacitance	V_{CC} = 1.5V to 5.5V		50	pF
V_{POR}	Power-on reset ramp voltage	$\Delta t/\Delta V_{CC} \geq 20\mu s/V$	0.3	1.5	V
$\Delta t/\Delta V_{CC}$	Power-on ramp rate	V_{CC} = 0.3V to 1.5V	20		μs/V
$\Delta t/\Delta v$	Input transition rise or fall rate	V_{CC} = 1.5V to 5.5V		100	ms/V
T_A	Operating free-air temperature		–40	125	°C

(1) All unused inputs of the device must be held at V_{CC} or GND to ensure proper device operation.
(2) Recommended maximum output current for continuous operation; see *Electrical Characteristics* for test current values to maintain V_{OH} and V_{OL} specifications. Operating with average output current greater than 12mA may impact device reliability and shorten the device lifetime.
(3) Recommended R_{ext} and C_{ext} values maintain maximum error provided as Δt_{wo} in the *Switching Characteristics* table.

5.4 Thermal Information

PACKAGE	PINS	THERMAL METRIC(1)						UNIT
		$R_{\theta JA}$	$R_{\theta JC(top)}$	$R_{\theta JB}$	Ψ_{JT}	Ψ_{JB}	$R_{\theta JC(bot)}$	
DCU (VSSOP)	8	247.4	137.6	166.9	60.2	166.5	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application note.

5.5 Electrical Characteristics

Over operating free-air temperature range; typical values measured at T_A = 25°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
V_{T+}	Positive switching threshold		1.5V	0.75	0.90	0.99	V
			1.8V	0.86	1.03	1.17	
			2.5V	1.1	1.29	1.47	
			3.3V	1.37	1.56	1.76	
			5V	1.92	2.16	2.4	
			5.5V	2.08	2.33	2.6	
V_{T-}	Negative switching threshold		1.5V	0.41	0.47	0.54	V
			1.8V	0.48	0.53	0.6	
			2.5V	0.63	0.69	0.76	
			3.3V	0.8	0.87	0.96	
			5V	1.13	1.25	1.39	
			5.5V	1.22	1.36	1.51	

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5.5 Electrical Characteristics (continued)

Over operating free-air temperature range; typical values measured at T_A = 25°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
ΔV_T	Hysteresis (V_{T+} - V_{T-})		1.5V	0.34	0.45	0.6	V
			1.8V	0.38	0.5	0.66	
			2.5V	0.47	0.6	0.78	
			3.3V	0.56	0.69	0.89	
			5V	0.77	0.9	1.12	
			5.5V	0.83	0.96	1.2	
V_{OH}	High-level output voltage	I_{OH} = -50µA	1.5V to 5.5V	V_{CC} – 0.1	V_{CC} – 0.01		V
		I_{OH} = -1mA	1.65V	1.2	1.61		
		I_{OH} = -2mA	2.3V	2.1	2.24		
		I_{OH} = -8mA	3V	2.4	2.78		
		I_{OH} = -12mA	4.5V	3.94	4.21		
		I_{OH} = -12mA	5.5V	4.94	5.23		
V_{OL}	Low-level output voltage	I_{OL} = 50µA	1.5V to 5.5V		0.01	0.1	V
		I_{OL} = 1mA	1.65V		0.03	0.45	
		I_{OL} = 2mA	2.3V		0.04	0.2	
		I_{OL} = 8mA	3V		0.13	0.4	
		I_{OL} = 12mA	4.5V		0.15	0.5	
		I_{OL} = 12mA	5.5V		0.13	0.5	
I_I	Input leakage current	V_I = 5.5V or GND	0V to 5.5V			±50	nA
I_{CEXT}	Capacitor pin current	Monitor state, V_{CEXT} = 5.5V	1.5V to 5.5V			±50	nA
		Active state, discharging, V_{CEXT} = 1.5V	1.5V			11	mA
		Active state, discharging, V_{CEXT} = 2.3V	2.3V			29	mA
		Active state, discharging, V_{CEXT} = 3V	3V			45	mA
		Active state, discharging, V_{CEXT} = 4.5V	4.5V			95	mA
		Active state, discharging, V_{CEXT} = 5.5V	5.5V			138	mA
I_{off}	Partial power-off current	V_I or V_O = V_{CC} or GND	0V to 0.3V		0.25	10	µA
I_{CC}	Supply current	Standby state, V_I = V_{CC} or GND, I_O = 0	5.5V		0.19	2	µA
I_{CC}	Supply current	Active state, V_I = V_{CC} or GND, I_O = 0	1.5V			180	µA
			1.65V			200	
			2.3V			290	
			3V			450	
			4.5V			836	
			5.5V			1126	
ΔI_{CC}	Supply-current change	One input, 0 ≤ V_i ≤ V_{CC}, all other inputs at V_{CC} or GND, I_O = 0	1.5V to 5.5V			1.5	mA
C_I		V_I = 5.5V or GND	5.5V		2		pF
C_O		V_O = 5.5V or GND	0V		4		pF

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5.5 Electrical Characteristics (continued)

Over operating free-air temperature range; typical values measured at T_A = 25°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
C_{int}	Internal capacitance	C_{ext} = 0pF; V_{cext} = 0 to V_{CC}	1.5V	16	17.9	20	pF
			1.65V	14	15.5	17	
			2.3V	7	9.7	13	
			3V	6	9.9	14	
			4.5V	5	7.7	10	
			5.5V	4	5.7	7	

5.6 Timing Characteristics

over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER	DESCRIPTION	CONDITION	V_{CC}	MIN	MAX	UNIT
t_{wi}	Pulse duration	Any trigger input	1.5V	18.2		ns
			1.8V ± 0.15V	9.9		
			2.5V ± 0.2V	7.8		
			3.3V ± 0.3V	5.8		
			5V ± 0.5V	4.1		
t_{su}	Setup time between trigger inputs	$\overline{T}$ low before T↑ or $\overline{CLR}$↑	1.5V	9.6		ns
			1.8V ± 0.15V	8		
			2.5V ± 0.2V	6.9		
			3.3V ± 0.3V	6.6		
			5V ± 0.5V	6.5		
		T high before $\overline{T}$↓ or $\overline{CLR}$↑	1.5V	5		ns
			1.8V ± 0.15V	5		
			2.5V ± 0.2V	5		
			3.3V ± 0.3V	5		
			5V ± 0.5V	5		
		$\overline{CLR}$ high before $\overline{T}$↓ or T↑	1.5V	9.2		ns
			1.8V ± 0.15V	7.8		
			2.5V ± 0.2V	6.7		
			3.3V ± 0.3V	6.5		
			5V ± 0.5V	6.4		
t_h	Hold time	Any trigger input	1.5V	9.3		ns
			1.8V ± 0.15V	7.8		
			2.5V ± 0.2V	6.7		
			3.3V ± 0.3V	6.5		
			5V ± 0.5V	6.4		

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over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER	DESCRIPTION	CONDITION	V_{CC}	MIN	MAX	UNIT
t_{rr} (1)	Retrigger time	Any trigger input, R_{ext} = 100kΩ, C_{ext} = 100pF	1.5V	13.1		µs
			1.8V ± 0.15V	13		
			2.5V ± 0.2V	12.6		
			3.3V ± 0.3V	12.5		
			5V ± 0.5V	12.2		
		Any trigger input, R_{ext} = 10kΩ, C_{ext} = 0.1µF	1.5V	2		ms
			1.8V ± 0.15V	2		
			2.5V ± 0.2V	2		
			3.3V ± 0.3V	2.1		
			5V ± 0.5V	2.1		
		Any trigger input, R_{ext} = 10kΩ, C_{ext} = 10µF	1.5V	912		ms
			1.8V ± 0.15V	911		
			2.5V ± 0.2V	904		
			3.3V ± 0.3V	893		
			5V ± 0.5V	864		
$t_{startup}$ (2)	Startup time		1.5V - 5.5V		0	µs

(1) Triggering the clear input ($\overline{CLR}$) more often than 11.4 × t_{rr} may affect long term reliability of the device. Repeated fast triggering of the clear input causes excessive average current at the RC pin.

(2) Triggers may be ignored during startup time. External timing capacitor takes time to charge during startup; wait at least one retirgger time (t_{rr}) for most accurate first pulse results.

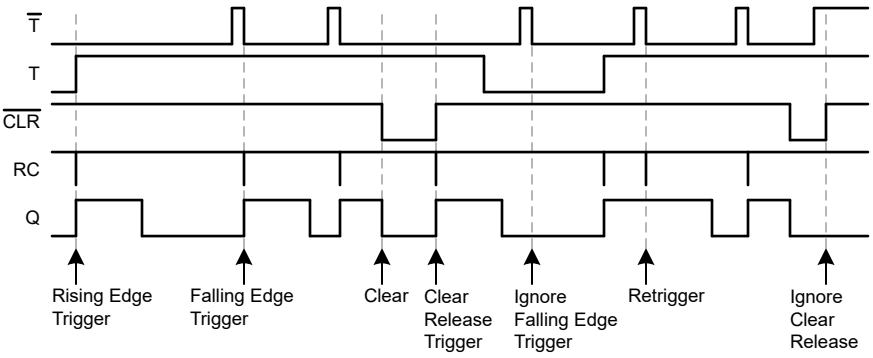


Figure 5-1. Timing Diagram

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5.7 Switching Characteristics

over operating free-air temperature range; typical values measured at T_A = 25°C (unless otherwise noted). See *Parameter Measurement Information*.

PARAMETER	FROM (INPUT)	TO (OUTPUT)	TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
t_{pd}	$\overline{T}$, T, or $\overline{CLR}$	Q	C_L = 15pF	1.5V	11.9	35	63.4	ns
				1.65V	10.1	28.6	50.3	ns
				2.3V	6.7	16.6	26.6	ns
				3V	5.4	12.4	18.4	ns
				4.5V	4.4	9.4	12.1	ns
				5.5V	4	9.2	10.3	ns
			C_L = 50pF	1.5V	13.3	37	66.5	ns
				1.65V	11.1	30.2	53	ns
				2.3V	7.3	17.6	28.2	ns
				3V	5.9	13	19.6	ns
				4.5V	4.7	9.8	13.2	ns
				5.5V	4.3	9.6	11.2	ns
t_t		Q	C_L = 15pF	1.5V		4.3	8.3	ns
				1.65V		3.9	7	ns
				2.3V		3	5.6	ns
				3V		2.5	5	ns
				4.5V		2.4	4.9	ns
				5.5V		2.7	5.8	ns
			C_L = 50pF	1.5V		8.2	34.4	ns
				1.65V		7	28	ns
				2.3V		4.5	24.6	ns
				3V		3.9	17.4	ns
				4.5V		3.1	12.6	ns
				5.5V		2.9	8.7	ns
t_{wo} (1)		Q	R_{ext} = 1MΩ; C_{ext} = 0; C_L = 50pF	1.5V	2.3	3.6	4.4	ms
				1.65V	2.5	3.5	4.3	ms
				2.3V	2.2	3.4	4.1	ms
				3V	2.2	3.3	4	ms
				4.5V	2.1	3.2	3.8	ms
				5.5V	2	3.1	3.8	ms
			R_{ext} = 10kΩ; C_{ext} = 0.1µF; C_L = 50pF	1.5V	831	934	1017	ms
				1.65V	832	934	1018	ms
				2.3V	837	932	1024	ms
				3V	842	938	1030	ms
				4.5V	852	949	1043	ms
				5.5V	857	954	1049	ms
			R_{ext} = 330kΩ; C_{ext} = 1µF; C_L = 50pF	1.5V	261	295	324	s
				1.65V	250	301	316	s
				2.3V	253	298	315	s
				3V	255	300	317	s
				4.5V	261	306	320	s
				5.5V	264	310	323	s

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over operating free-air temperature range; typical values measured at T_A = 25°C (unless otherwise noted). See *Parameter Measurement Information*.

PARAMETER	FROM (INPUT)	TO (OUTPUT)	TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
Δt_{wo} (2)		Q	C_L = 50pF	1.5V to 5.5V		±1	±10	%
C_{pd} (3)		Q	T = V_{CC}, $\overline{T}$ = GND, f_I = 10MHz, C_L = 50pF, C_{ext} = 0pF, R_{ext} = 1MΩ	1.5V		35.6		pF
				1.65V		37.5		pF
				2.3V		39.1		pF
				3V		30.7		pF
				4.5V		32.4		pF
				5.5V		34		pF

(1) Output pulse width
(2) Variation in output pulse width as compared to typical characteristics for K factor excluding variations in external timing components.
(3) Power dissipation capacitance is calculated in accordance with CMOS Power Consumption and Cpd Calculation.

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5.8 Typical Characteristics

T_A = 25°C (unless otherwise noted)

Table 5-1. Pulse width using common RC, V_{CC} = 3.3V

Resistor Value	Capacitor Value						
	10µF	1µF	100nF	10nF	1nF	100pF	10pF
1kΩ	10.1s	1.01s	106ms	11.0ms	1.21ms(1)	179µs(1)	61.9µs(1)
1.5kΩ	15.0s	1.50s	153ms	15.9ms	1.74ms(1)	242µs(1)	69.4µs(1)
2.2kΩ	21.7s	2.17s	220ms	22.7ms	2.49ms(1)	331µs(1)	84.7µs(1)
3.3kΩ	32.1s	3.21s	326ms	33.5ms	3.64ms(1)	468µs(1)	102µs(1)
4.7kΩ	45.3s	4.53s	460ms	47.2ms	5.14ms(1)	643µs(1)	125µs(1)
6.8kΩ	65.2s	6.52s	661ms	68.1ms	7.36ms(1)	904µs(1)	157µs(1)
10kΩ	95.1s	9.51s	966ms	99.5ms	10.8ms	1.30ms(1)	207µs(1)
15kΩ	143s	14.3s	1.44s	149ms	16.1ms	1.92ms(1)	281µs(1)
22kΩ	209s	20.9s	2.12s	218ms	23.4ms	2.79ms(1)	387µs(1)
33kΩ	313s	31.3s	3.16s	327ms	35.3ms	4.14ms(1)	552µs(1)
47kΩ	444s	44.4s	4.50s	464ms	49.8ms	5.88ms(1)	763µs(1)
68kΩ	644s	64.4s	6.52s	670ms	72.3ms	8.47ms(1)	1.06ms(1)
100kΩ	946s	94.6s	9.58s	985ms	106ms	12.5ms	1.55ms(1)
150kΩ	1420s	142s	14.3s	1.48s	160ms	18.5ms	2.29ms(1)
220kΩ	2080s	208s	21.0s	2.17s	234ms	27.3ms	3.32ms(1)
330kΩ	2924s(2)	312s	31.5s	3.25s	351ms	40.6ms	4.94ms(1)
470kΩ	2939s(2)	444s	44.9s	4.64s	501ms	58.0ms	7.02ms(1)
680kΩ	2962s(2)	643s	64.9s	6.69s	724ms	84.3ms	10.1ms
1MΩ	2995s(2)	940s	95.8s	9.88s	1.06s	125ms	14.8ms

(1) Pulse widths configured for less than 10ms (K×R×C < 10µs) can fail to properly trigger the state machine resulting in very short output pulses (t_{wo} < 10µs).
(2) Pulse widths configured for more than 2253s (K×R×C > 2.2s) can vary significantly due to exceeding the digital timing circuitry capabilities.

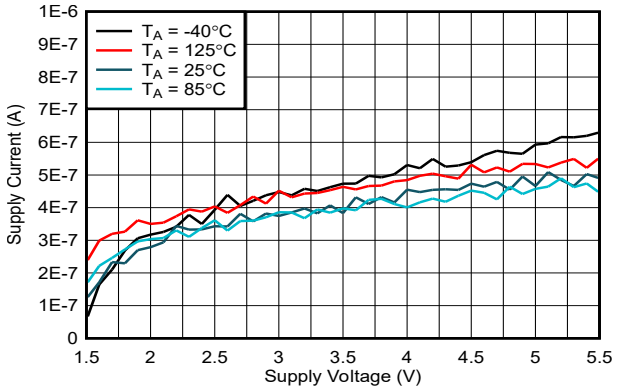


Figure 5-2. Supply Current vs Supply Voltage

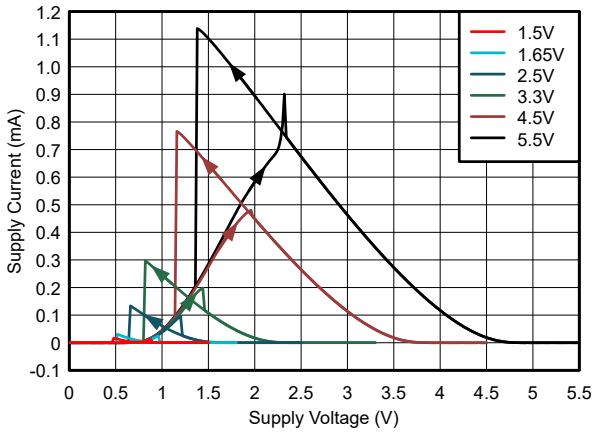


Figure 5-3. Supply Current vs Input Voltage

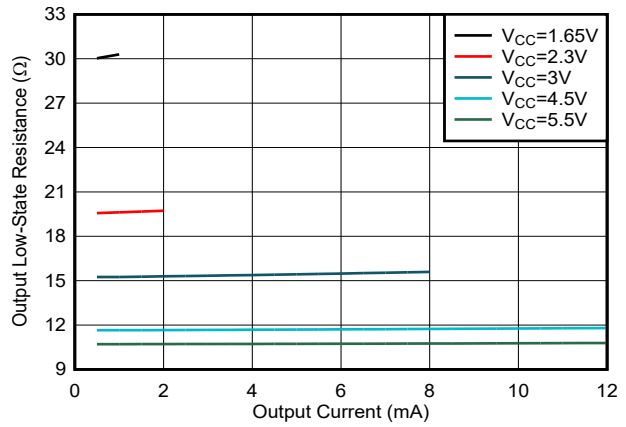


Figure 5-4. Output Low-State Resistance vs Output Current

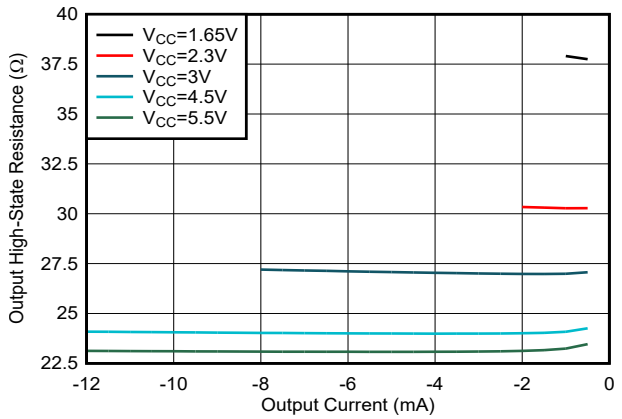


Figure 5-5. Output High-State Resistance vs Output Current

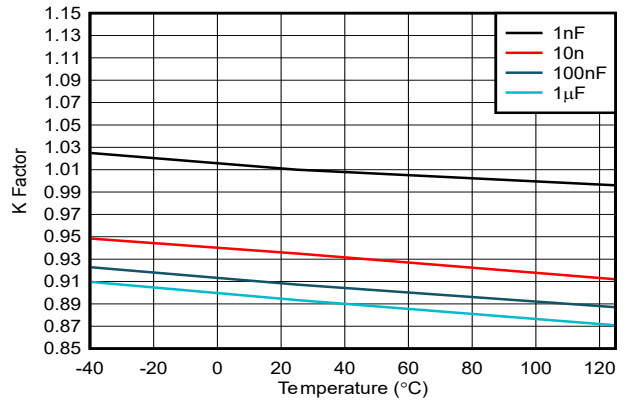


Figure 5-6. K Factor vs Temperature, R_{ext} = 10kΩ

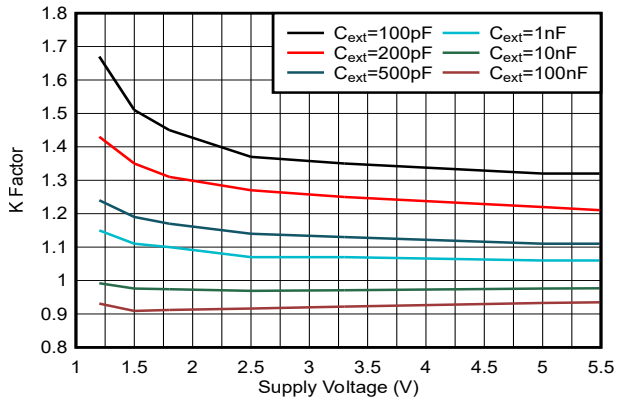


Figure 5-7. K Factor vs Supply Voltage, R_{ext} = 10kΩ

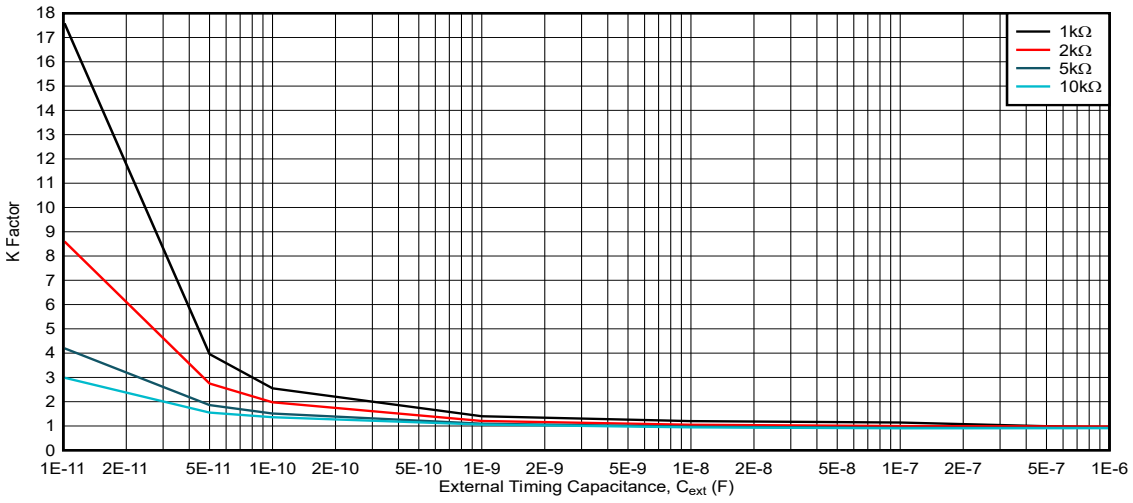


Figure 5-8. K Factor, V_{CC} = 1.5V, R_{ext} = 1kΩ to 10kΩ

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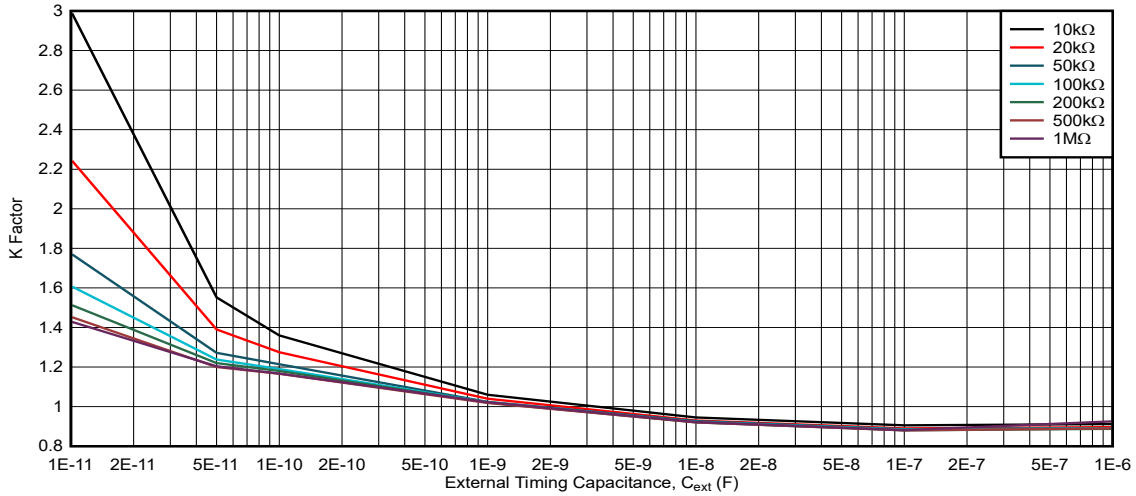


Figure 5-9. K Factor, V_{CC} = 1.5V, R_{ext} = 10kΩ to 1MΩ

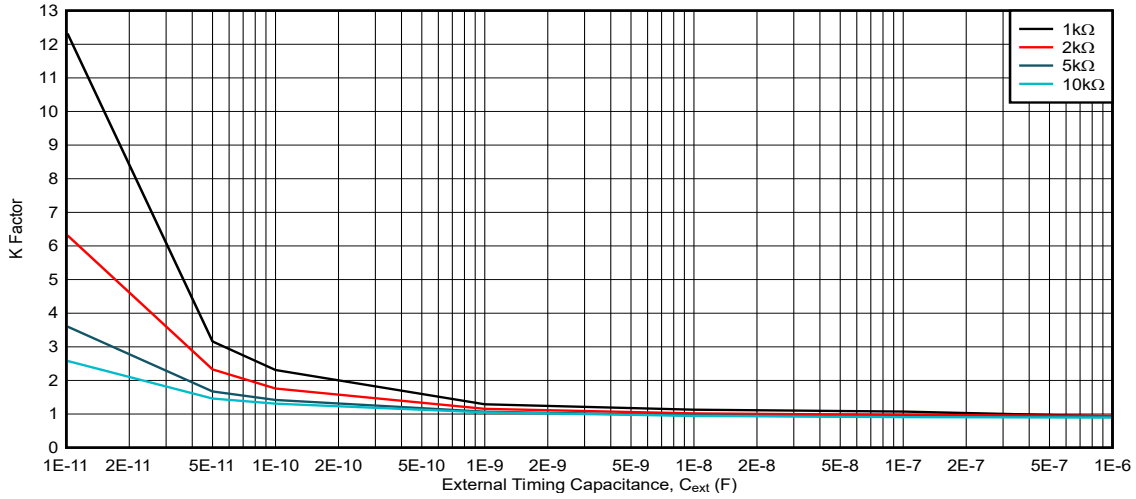


Figure 5-10. K Factor, V_{CC} = 1.8V, R_{ext} = 1kΩ to 10kΩ

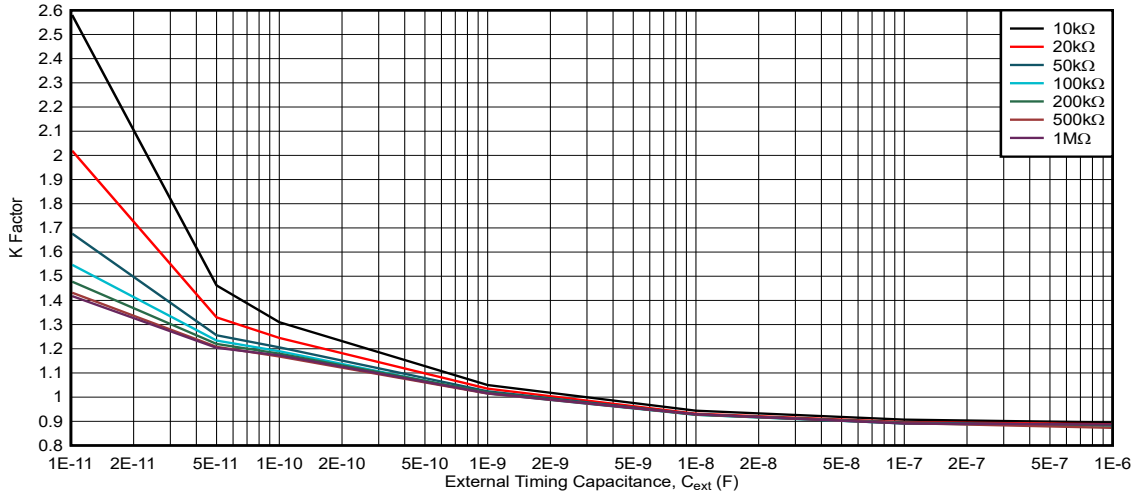


Figure 5-11. K Factor, V_{CC} = 1.8V, R_{ext} = 10kΩ to 1MΩ

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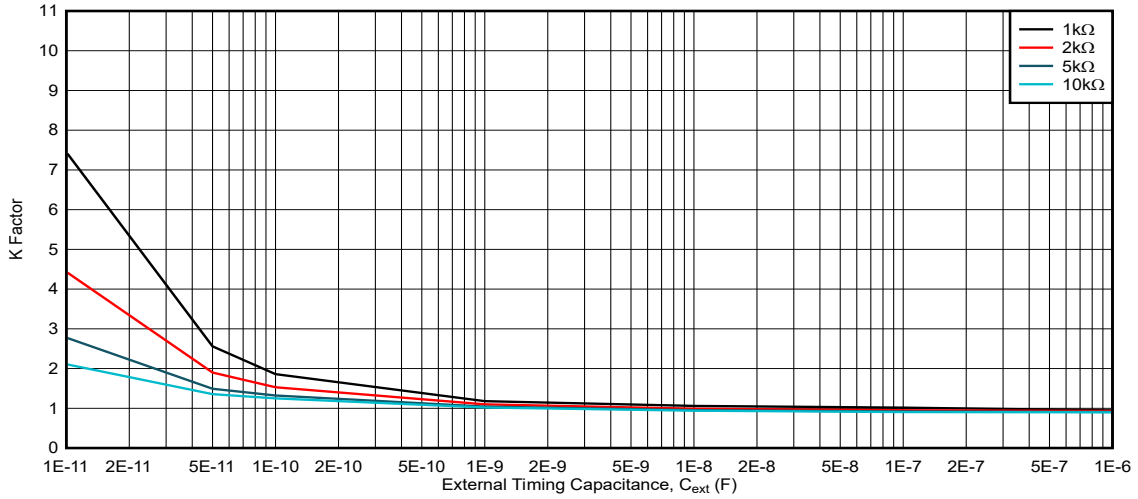


Figure 5-12. K Factor, V_{CC} = 2.5V, R_{ext} = 1kΩ to 10kΩ

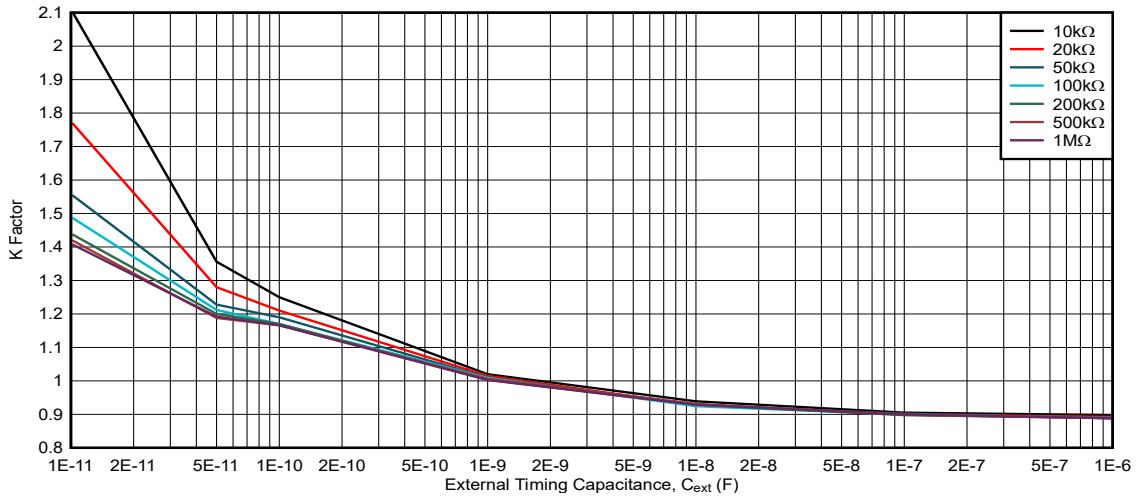


Figure 5-13. K Factor, V_{CC} = 2.5V, R_{ext} = 10kΩ to 1MΩ

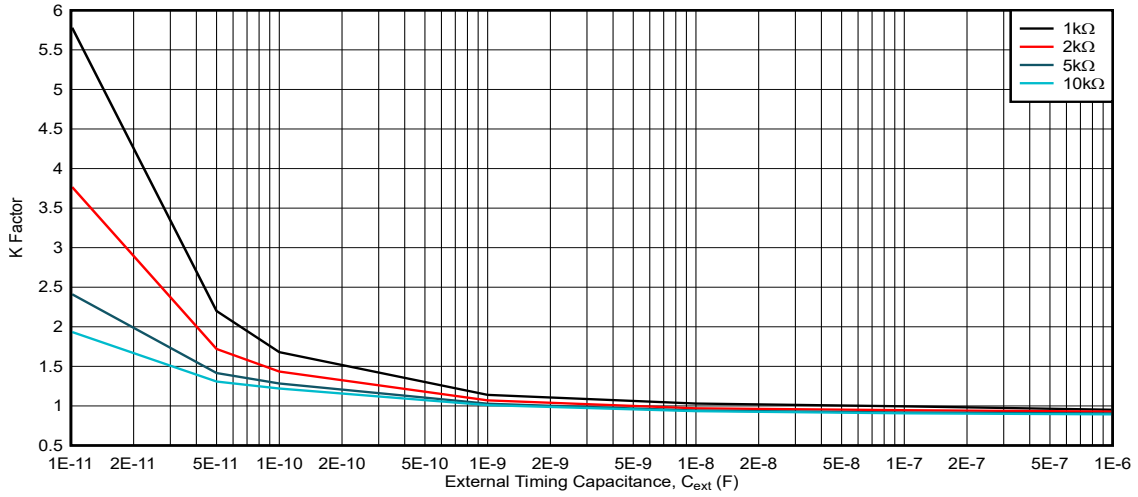


Figure 5-14. K Factor, V_{CC} = 3.3V, R_{ext} = 1kΩ to 10kΩ

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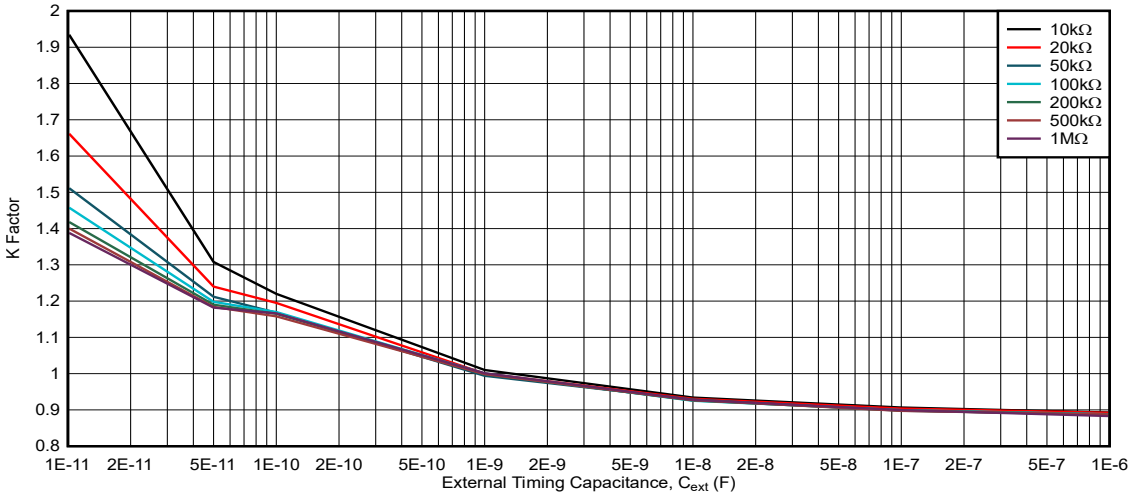


Figure 5-15. K Factor, V_{CC} = 3.3V, R_{ext} = 10kΩ to 1MΩ

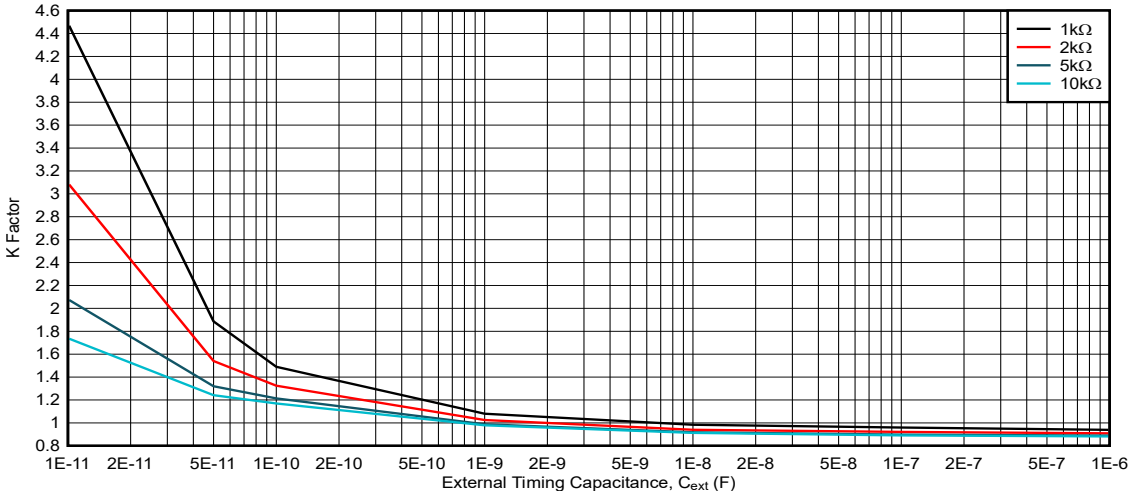


Figure 5-16. K Factor, V_{CC} = 5V, R_{ext} = 1kΩ to 10kΩ

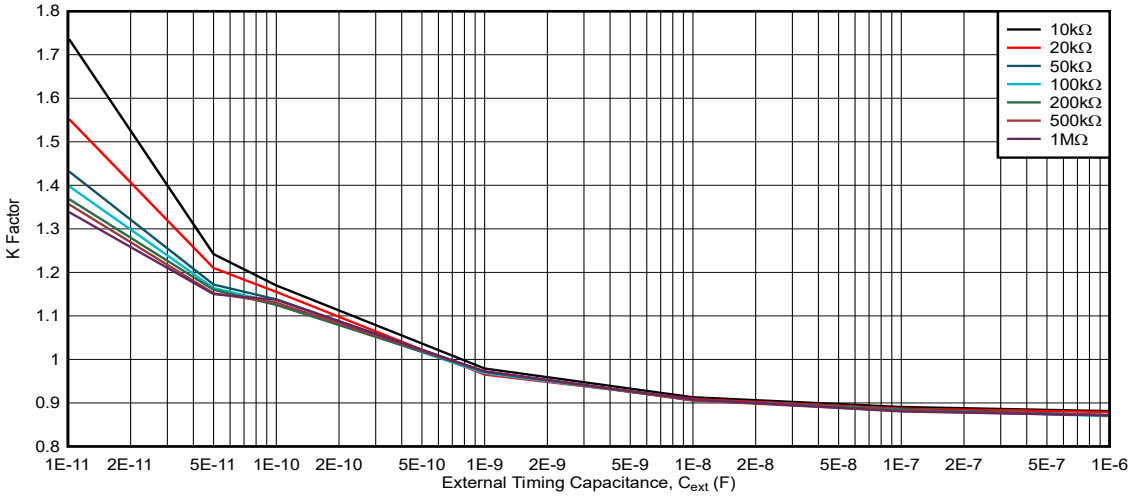


Figure 5-17. K Factor, V_{CC} = 5V, R_{ext} = 10kΩ to 1MΩ

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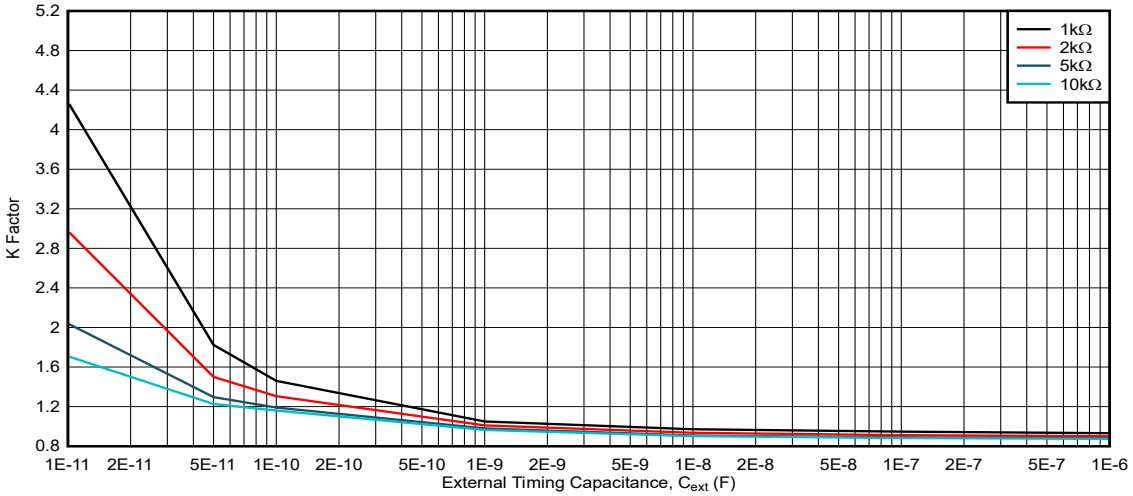


Figure 5-18. K Factor, V_{CC} = 5.5V, R_{ext} = 1kΩ to 10kΩ

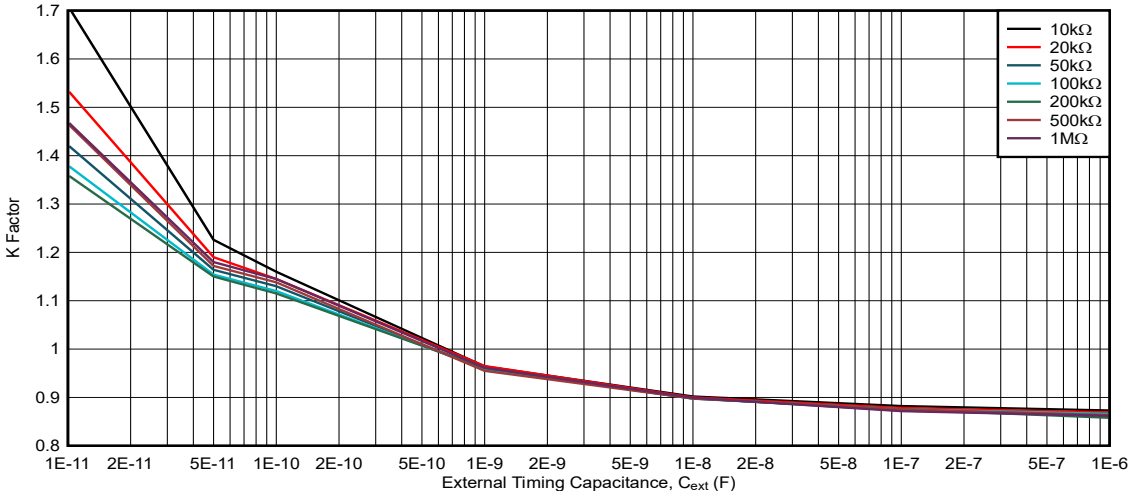


Figure 5-19. K Factor, V_{CC} = 5.5V, R_{ext} = 10kΩ to 1MΩ

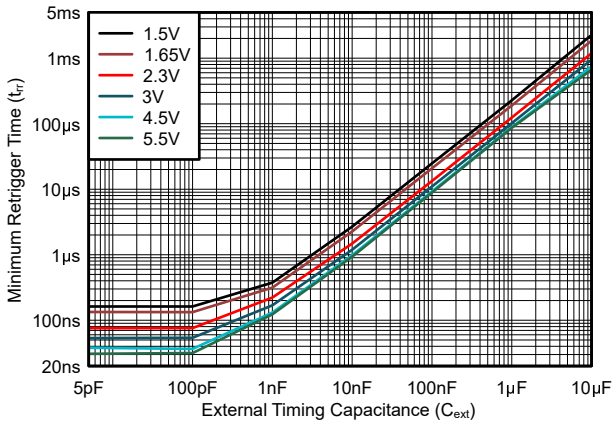


Figure 5-20. Minimum Retrigger Time vs External Timing Capacitor Value

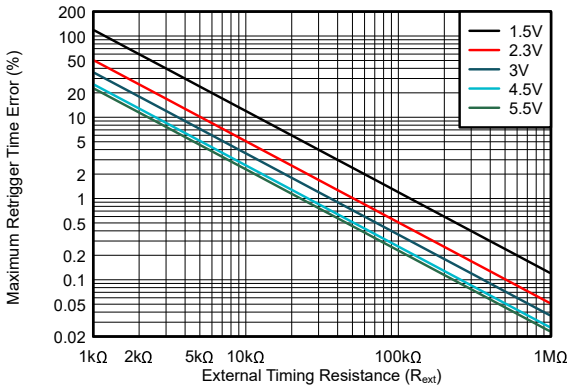


Figure 5-21. Maximum Retrigger Time Error as a Percentage of Total Pulse Width vs External Timing Resistor Value

Error data in the following plots indicates changes from typical behavior (nominal material, T_A = 25°C) due to variation in manufacturing process and operating free-air temperature.

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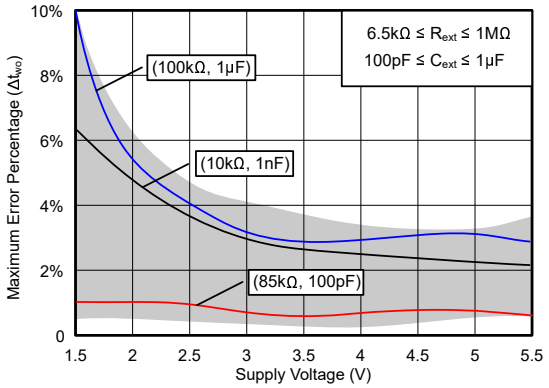


Figure 5-22. Maximum Output Pulse Width Error (Absolute Value) Across Supply Voltage Each Line: One Timing Component Combination Shaded Area: All Timing Component Combinations

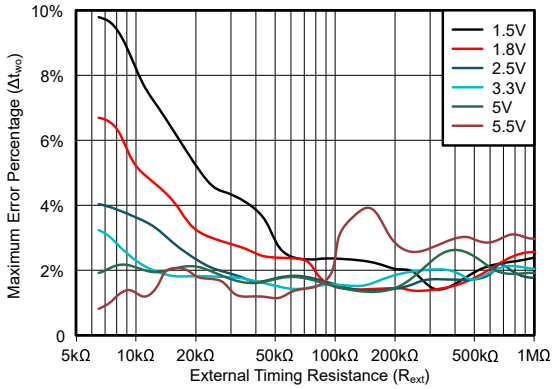


Figure 5-23. Maximum Output Pulse Width Error (Absolute Value) vs Timing Resistor Values With C_{ext} = 100pF

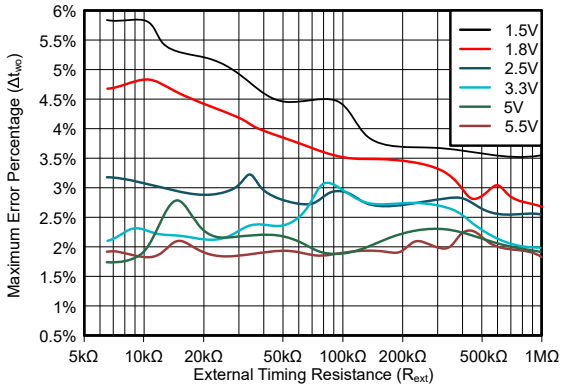
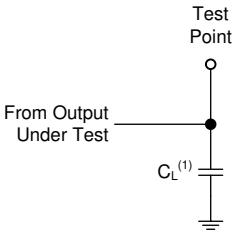


Figure 5-24. Maximum Output Pulse Width Error (Absolute Value) vs Timing Resistor Values With C_{ext} = 1nF

6 Parameter Measurement Information

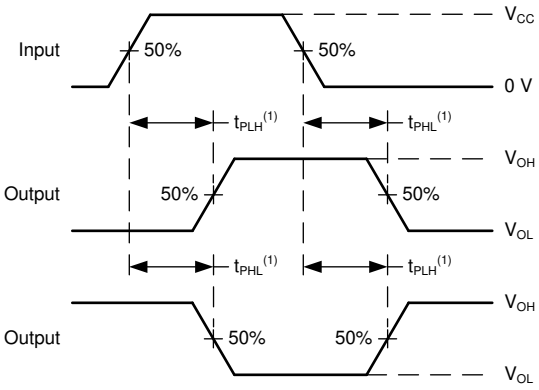
Phase relationships between waveforms are chosen arbitrarily for the examples listed in the following table. Generators with the following characteristics supply all input pulses: PRR ≤ 1MHz, Z_O = 50Ω, t_t < 2.5ns.

The outputs are measured individually with one input transition per measurement.



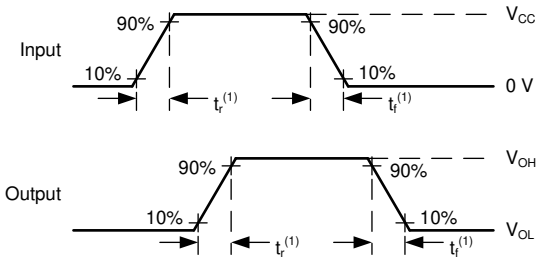
(1) C_L includes probe and test-fixture capacitance.

Figure 6-1. Load Circuit for Push-Pull Outputs



(1) The greater between t_{PLH} and t_{PHL} is the same as t_{pd}.

Figure 6-2. Voltage Waveforms Propagation Delays



(1) The greater between t_r and t_f is the same as t_t.

Figure 6-3. Voltage Waveforms, Input and Output Transition Times

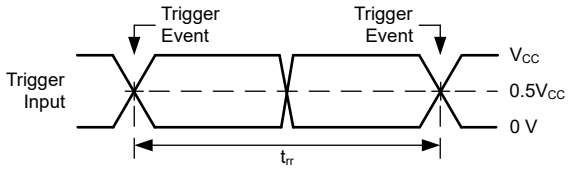


Figure 6-4. Voltage Waveforms, Retrigger Time

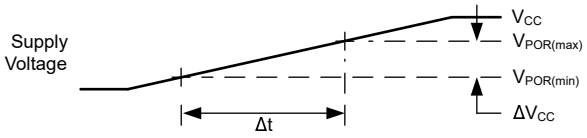


Figure 6-5. Voltage Waveforms, Supply Ramp

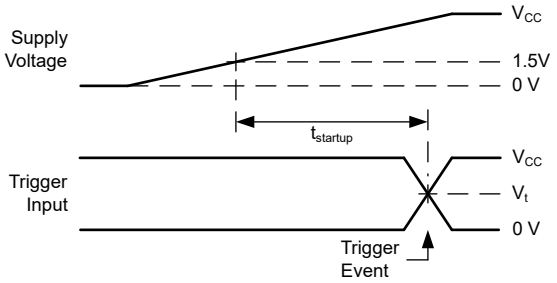


Figure 6-6. Voltage Waveforms, Startup Time

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7 Detailed Description

7.1 Overview

The TPUL1G313-Q1 device contains one extended-pulse-width retriggerable monostable multivibrator circuit. A monostable multivibrator, also commonly known as a *one shot*, produces a single digital pulse when triggered and otherwise maintains a constant output state.

The TPUL1G313-Q1 device features three gated trigger inputs for each channel. For a rising edge trigger, the T or $\overline{CLR}$ input is used. For a falling edge trigger the $\overline{T}$ input is used.

The TPUL1G313-Q1 device includes an asynchronous clear input ($\overline{CLR}$) that can be used to terminate an ongoing output pulse.

When triggered, the TPUL1G313-Q1 outputs a positive digital pulse with pulse width defined as $t_{wo} = 1024 \times K \times R_{ext} \times C_{ext}$, with R_{ext} and C_{ext} being the external timing resistor and external timing capacitor component values measured in Ω and F, respectively, and K being a unitless nonlinearity correction factor provided in the *Typical Characteristics* section. The external timing components must be connected as shown in Figure 7-1 or Figure 7-2. The external ground connection to the C terminal is optional.

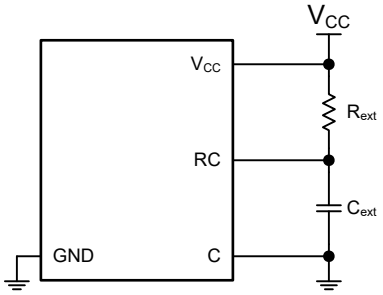


Figure 7-1. Timing Component Connection, With External Ground

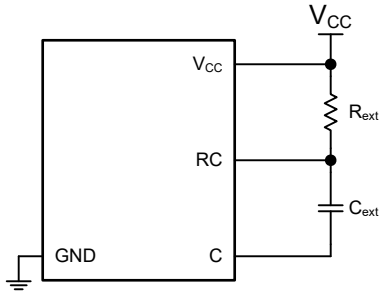


Figure 7-2. Timing Component Connection, Without External Ground

7.1.1 State Machine Description

The TPUL1G313-Q1 contains a state machine as shown in Figure 7-3. When triggered, the device immediately starts an output pulse. The external RC components are measured using an internal digital logic circuit. The RC charge time is saved and digitally repeated 1024 times (total). After 1024 cycles have completed, the output is released back to the stable state and the device is ready to be triggered again.

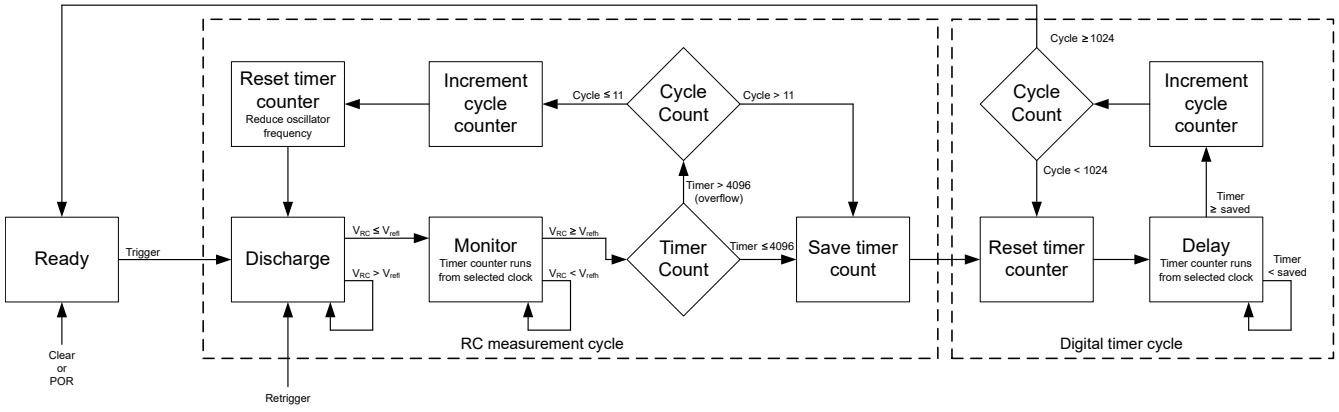


Figure 7-3. State Machine Diagram

7.1.1.1 Ready

- Behavior
  - Oscillators disabled

  - Measurement circuitry disabled
  - Counters reset
  - RC = High
  - Q = Low
- Transitions
  - In
    - Power-on reset active
    - From any state, clear active
    - From digital timer cycle, cycle counter value ≥ 1024
  - Out
    - To discharge state, trigger input

7.1.1.2 RC Measurement Cycle

The RC measurement cycle is the method by which the TPUL1G313-Q1 determines the external analog component values. Analog comparators and the currently selected oscillator are enabled.

7.1.1.2.1 Discharge

- Behavior
  - Timer counter runs from currently selected clock source
  - RC = Low
  - Q = High
- Transitions
  - In
    - From any state, trigger input
  - Out
    - To ready state, clear active
    - To monitor state, $V_{RC} \leq V_{refl}$

7.1.1.2.2 Monitor

- Behavior
  - RC = High-impedance
  - External RC circuit controls V_{RC}
  - Q = High
- Transitions
  - In
    - From discharge state, $V_{RC} \leq V_{refl}$
  - Out
    - To ready state, clear active
    - To discharge state, trigger
    - To timer count decision, $V_{RC} \geq V_{refh}$

7.1.1.2.3 Timer Count Decision

- Transitions
  - In
    - From monitor state, $V_{RC} \geq V_{refh}$
  - Out
    - To cycle count decision, timer counter value > 4096 (overflow)
    - To save timer count state, timer counter value ≤ 4096

7.1.1.2.4 Cycle Count Decision

- Transitions

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- In
  - From timer count decision, timer counter value > 4096 (overflow)
- Out
  - To increment cycle counter state, cycle counter value ≤ 11
  - To save timer count state, cycle counter value > 11

7.1.1.2.5 Increment Cycle Counter

- Behavior
  - Cycle counter value increased by 1
  - RC = High
  - Q = High
  - $\overline{Q}$ = Low
- Transitions
  - In
    - From cycle count decision, cycle counter value ≤ 11
  - Out
    - To ready state, clear active
    - To discharge state, trigger
    - To reset timer counter state, task complete

7.1.1.2.6 Reset Timer Counter

- Behavior
  - Timer counter value cleared
  - Active oscillator and clock frequency divider change based on new cycle counter value. See Table 7-1 table.
  - RC = High
  - Q = High
  - $\overline{Q}$ = Low
- Transitions
  - In
    - From increment cycle counter state, task complete
  - Out
    - To ready state, clear active
    - To RC measurement cycle, trigger
    - To discharge state, task complete

Table 7-1. Timer Counter Clock Frequency

Cycle	Active Oscillator	Frequency Divider	Counter Clock		Maximum Output Pulse Width(1)
			Frequency(1)	Period(1)	
1	10MHz(2)	1	13.5MHz	74ns	311ms
2	1MHz(3)	1	1.47MHz	680ns	2.85s
3	1MHz(3)	2	735kHz	1.36µs	5.71s
4	1MHz(3)	4	368kHz	2.72µs	11.4s
5	1MHz(3)	8	184kHz	5.44µs	22.8s
6	1MHz(3)	16	91.9kHz	10.9µs	45.7s
7	1MHz(3)	32	45.9kHz	21.8µs	91.3s
8	1MHz(3)	64	23.0kHz	43.5µs	183s
9	1MHz(3)	128	11.5kHz	87.1µs	365s
10	1MHz(3)	256	5.74kHz	174µs	730s
11	1MHz(3)	512	2.87kHz	348µs	1461s

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Table 7-1. Timer Counter Clock Frequency (continued)

Cycle	Active Oscillator	Frequency Divider	Counter Clock		Maximum Output Pulse Width(1)
			Frequency(1)	Period(1)	
12	1MHz(3)	1024	1.44kHz	697µs	2922s(4)

(1) Typical values
(2) 10MHz oscillator can vary from 7.8MHz to 18.9MHz
(3) 1MHz oscillator can vary from 1.1MHz to 1.9MHz
(4) Maximum digitally timed output pulse width can vary from 2253s to 3892s; total pulse width can increase beyond the maximum due to analog RC charge time

7.1.1.2.7 Save Timer Count

- Behavior
  - If timer counter overflow flag is true, timer counter value is set to 4096
  - Timer counter value is saved to an internal register for use in the digital timer cycle
  - RC = High
  - Q = High
  - $\overline{Q}$ = Low
- Transitions
  - In
    - From timer count decision, timer counter value ≤ 4096
    - From cycle count decision, cycle counter value > 11
  - Out
    - To ready state, clear active
    - To RC measurement cycle, trigger
    - To digital timer cycle, task complete

7.1.1.3 Digital Timer Cycle

The digital timer cycle is the method by which the TPUL1G313-Q1 produces the 1024 multiplier for the external RC component time constant while disabling the analog measurement circuitry to save power. The total number of cycles will always be 1024, however there can be up to 12 cycles used for RC value measurement, and thus the digital timer cycle can operate between 1012 and 1023 cycles. The analog comparators are disabled and the selected clock found in the RC measurement cycle is enabled.

7.1.1.3.1 Reset Timer Counter

- Behavior
  - Timer counter value cleared
  - RC = High
  - Q = High
  - $\overline{Q}$ = Low
- Transitions
  - In
    - From RC measurement cycle, task complete
    - From cycle count in digital timing cycle, cycle counter value < 1024
  - Out
    - To ready state, clear active
    - To RC measurment cycle, trigger
    - To delay state, task complete

7.1.1.3.2 Delay

- Behavior
  - Timer counter runs on clock source determined from RC measurement cycle
  - RC = High
  - Q = High

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  - $\overline{Q}$ = Low
- Transitions
  - In
    - From reset timer counter state, task complete
  - Out
    - To ready state, clear active
    - To RC measurement cycle, trigger
    - To increment cycle counter state, timer counter value ≥ saved timer count value from RC measurement process

7.1.1.3.3 Increment Cycle Counter

- Behavior
  - Cycle counter value is increased by 1
  - RC = High
  - Q = High
  - $\overline{Q}$ = Low
- Transitions
  - In
    - From delay state, timer counter value ≥ saved timer counter value from RC measurement process
  - Out
    - To ready state, clear active
    - To RC measurement cycle, trigger
    - To cycle count decision, task complete

7.1.1.3.4 Cycle Count Decision

- Transitions
  - In
    - From increment cycle counter state, task complete
  - Out
    - To reset timer counter state, timer counter value < 1024
    - To ready state, cycle counter value ≥ 1024

7.2 Functional Block Diagram

$$V_{refh} = 0.69 \times V_{CC} \quad (1)$$

$$V_{refl} = 0.25 \times V_{CC} \quad (2)$$

C_{int} indicates total internal parasitic capacitance and can be found in the *Electrical Characteristics* table.

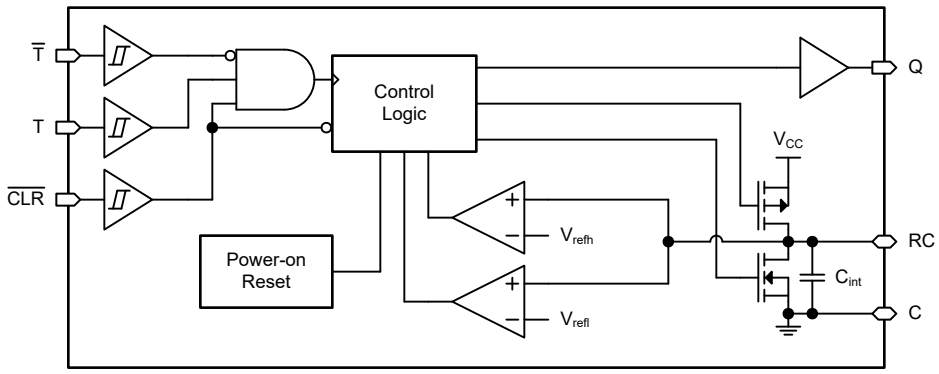


Figure 7-4. Functional Block Diagram

7.3 Feature Description

7.3.1 Naming Convention

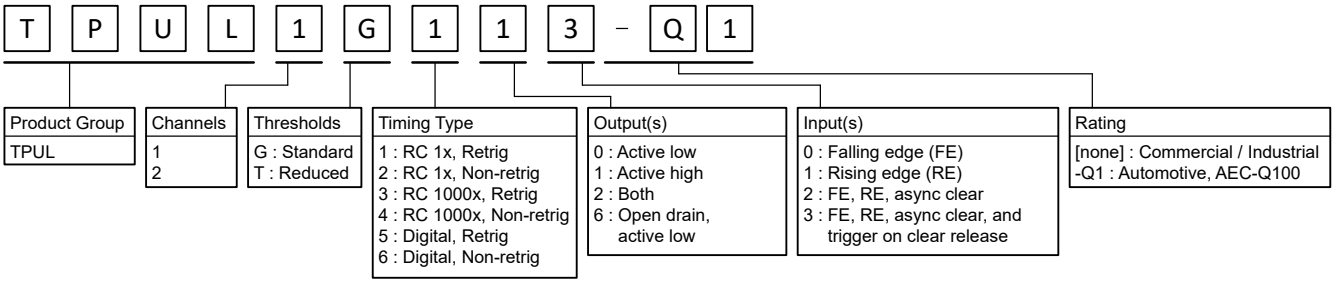


Figure 7-5. Device name meaning

7.3.2 Retriggerable One-Shot

This device includes a retriggerable monostable multivibrator (one-shot) circuit that produces a fixed-width output pulse. The output pulse width for a retriggerable one-shot is extended by additional input triggers while the output is active. The output pulse will expire after the configured time period if no other triggers have been received.

The output pulse width after a retrigger event is always shorter than the normal output pulse width because the timing capacitor does not need to be fully discharged for a retrigger event. The maximum error due to this change is the time to discharge the selected timing capacitor. The error due to retrigger timing can be minimized by selecting larger resistor values and smaller capacitor values for a given pulse width. See retrigger plots in the *Typical Characteristics* section for more details.

7.3.3 Extended RC Timed One-Shot

The output pulse width (t_{wo}) is controlled by the selection of external timing components R_{ext} and C_{ext}. The TPUL1G313-Q1 has been designed to target a typical output pulse width of $t_{wo} \cong 1000 \times R_{ext} \times C_{ext}$, however the actual pulse width changes with multiple variables, and thus a nonlinearity correction factor, K, is added to provide the system designer with a more accurate pulse width estimation. Equation 3 is used to most accurately predict the output pulse width.

$$t_{wo} = K \times 1024 \times R_{ext} \times C_{ext} \quad (3)$$

The output pulse width is dependent on multiple variables:

- External timing components (R_{ext}, C_{ext})
- Voltage
- Temperature
- Manufacturing and design
- Digital state machine operation

The external timing component values directly control the output pulse width, and any variations in component values due to manufacturing, voltage, or temperature will directly impact the output pulse width.

Most resistors maintain very consistent values during operation, and thus tend to have little impact on accuracy.

Most capacitors have a wide variation of manufacturing values, and additionally can vary due to temperature and operating voltage. Typically, the timing capacitor is the largest single source of error for RC timed monostable multivibrators.

There is also some error introduced by the TPUL1G313-Q1. This error is provided as Δt_{wo} in the *Switching Characteristics* section and includes variations due to digital state machine operation, design, manufacturing, and temperature. There is additionally some randomness inherent to the pulse width even with all other factors held constant which is typically less than 1% and is accounted for in the Δt_{wo} specification.

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Estimating the percent error of the output pulse width ($e_{\Delta two}$) requires multiple inputs. Equation 4 provides the best method to estimate total pulse width error due to tolerance of components, with e_R being the error introduced by the timing resistor, e_C being the error introduced by the timing capacitor, and Δt_{wo} being the error introduced by the TPUL1G313-Q1.

$$e_{\Delta two} = e_R + e_C + e_R e_C + \Delta t_{wo}(1 + e_R + e_C + e_R e_C) \quad (4)$$

For a quick estimate, the sum of the error values can be used ($e_{\Delta two} \cong e_R + e_C + \Delta t_{wo}$). For example, a typical TPUL1G313-Q1 application circuit using an X7R capacitor (5% manufacturing tolerance + 15% temperature variation), 0.1% resistor, and Δt_{wo} of 5% would have a quickly estimated maximum error of 25.1%. With the more accurate equation, the maximum error is actually 26.126%.

7.3.4 Balanced CMOS Push-Pull Outputs

This device includes balanced CMOS push-pull outputs. The term *balanced* indicates that the device can sink and source similar currents. The drive capability of this device can create fast edges into light loads, so routing and load conditions must be considered to prevent ringing. Additionally, the outputs of this device are capable of driving larger currents than the device can sustain without being damaged. Limit the output power of the device to avoid damage due to overcurrent. The electrical and thermal limits defined in the *Absolute Maximum Ratings* must be followed at all times.

Unused push-pull CMOS outputs must be left disconnected.

7.3.5 CMOS Schmitt-Trigger Inputs

This device includes inputs with the Schmitt-trigger architecture. These inputs are high impedance and are typically modeled as a resistor in parallel with the input capacitance given in the *Electrical Characteristics* table from the input to ground. The worst case resistance is calculated with the maximum input voltage, given in the *Absolute Maximum Ratings* table, and the maximum input leakage current, given in the *Electrical Characteristics* table, using Ohm's law (R = V ÷ I).

The Schmitt-trigger input architecture provides hysteresis as defined by ΔV_T in the *Electrical Characteristics* table, which makes this device extremely tolerant to slow or noisy inputs. While the inputs can be driven much slower than standard CMOS inputs, it is still recommended to properly terminate unused inputs. Driving the inputs with slow transitioning signals will increase dynamic current consumption of the device with the maximum value per input defined as ΔI_{CC} in the *Electrical Characteristics* table. For additional information regarding Schmitt-trigger inputs, please see *Understanding Schmitt Triggers*.

Do not leave inputs floating at any time during operation. Unused inputs must be terminated at a valid high or low voltage level. If a system is not actively driving an input at all times, then a pull-up or pull-down resistor can be added to provide a valid input voltage during these times. The resistor value will depend on multiple factors; however, a 10kΩ resistor is recommended and will typically meet all requirements.

7.3.6 Latching Logic with Known Power-Up State

This device includes latching logic circuitry. Latching circuits commonly include D-type latches and D-type flip-flops, but include all logic circuits that act as volatile memory. In typical logic devices, the output state of each latching circuit is unknown after power is initially applied; however, this device includes an added Power On Reset (POR) circuit which sets the states of all included latching circuits during the power-up ramp prior to the device starting normal functionality.

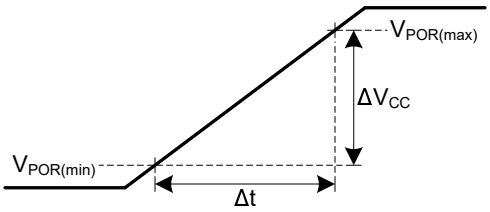


Figure 7-6. Supply (V_{CC}) Ramp Characteristics for Known Power-Up State

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Figure 7-6 shows a correct supply voltage turn-on ramp and defines values used in the *Recommended Operating Conditions* and *Electrical Characteristics* tables.

Prior to starting the power-on ramp, the supply must be completely off ($V_{CC} \leq V_{POR(min)}$).

The supply voltage must ramp at a rate within the range provided in the *Recommended Operating Conditions* table.

The output state of each latching logic circuit only remains stable as long as power is applied to the device ($V_{CC} \geq V_{POR(max)}$).

Variation from these recommendations will result in the device having an unknown power-up state.

7.3.7 Partial Power Down (I_{off})

This device includes circuitry to disable all outputs when the supply pin is held at 0V. When disabled, the outputs neither source nor sink current, regardless of the input voltages. The amount of leakage current at each output is defined by the I_{off} specification in the *Electrical Characteristics* table.

7.3.8 Clamp Diode Structure

Figure 7-7 shows the inputs and outputs to this device have negative clamping diodes only.

CAUTION

Voltages beyond the values specified in the *Absolute Maximum Ratings* table can cause damage to the device. The input and output voltage ratings may be exceeded if the input and output clamp-current ratings are observed.

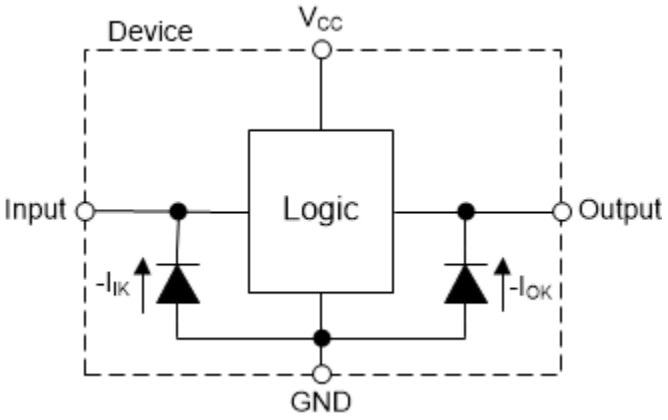


Figure 7-7. Electrical Placement of Clamping Diodes for Each Input and Output

7.3.9 Over-Voltage Tolerant Inputs

The TPUL1G313-Q1 includes over-voltage tolerant inputs. The input pins support high-state input voltages larger than the supply voltage by utilizing an input protection circuit that does not include a standard positive clamp diode. See *Recommended Operating Conditions* for the recommended input voltage.

CAUTION

Do not exceed the maximum input voltage range provided in *Absolute Maximum Ratings*. Exceeding the maximum input voltage range rating can cause immediate and permanent damage to the device.

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7.4 Device Functional Modes

7.4.1 Off-State Operation

The TPUL1G313-Q1 includes partial-power-down (I_{off}) protection, which forces the outputs into a high-impedance state when the supply voltage is approximately 0V. In the powered-off state, voltages can be applied to the digital inputs and outputs and the device will not respond or have any back-powering. This protection does not apply to the RC pin.

7.4.2 Startup Operation

The TPUL1G313-Q1 includes an internal power-on reset (POR) circuit that prevents erroneous triggers from occurring during startup. There are details on the supply ramp requirements provided in *Latching Logic with Known Power-Up State*. Normal operation can be started after the startup time ($t_{startup}$) has expired per the *Timing Requirements* table. While active, the POR circuit holds the TPUL1G313-Q1 in the *Ready* state.

7.4.3 On-State Operation

The table below lists the on-state functional modes for the TPUL1G313-Q1.

Table 7-2. Function Table

INPUTS(1)			OUTPUT(2)
$\overline{CLR}$	$\overline{T}$	T	Q
L	X	X	L
H	H	X	L(3)
H	X	L	L(3)
H	L	↑	⎍ (4)
H	↓	H	⎍ (4)
↑	L	H	⎍

(1) H = high voltage level, L = low voltage level, X = don't care
(2) L = driving low, H = driving high, ⎍ = driving high for the defined pulse width time, ⎎ = driving low for the defined pulse width time
(3) These outputs are based on the assumption that the indicated steady-state conditions at the inputs have been set up long enough to complete any output pulse.
(4) If an output pulse is triggered while a previous output pulse is still active, the output continues to drive high for one additional pulse width.

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8 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

The TPUL1G313-Q1 is used to generate a fixed-width pulse from an input trigger event. This device is retriggerable, meaning that input triggers received while the output is active will cause the output pulse to extend and it will not expire until one configured time period after the most recent trigger.

The input trigger event comes from three gated inputs: $\overline{T}$, T, and $\overline{CLR}$. These inputs are combined in a 3-input AND gate, with $\overline{T}$ internally inverted such that the logic follows the boolean equation Y = !($\overline{T}$) • T • $\overline{CLR}$. Each input has a Schmitt-trigger architecture, and thus includes hysteresis allowing for slow transitioning or noisy signals. An input signal is detected as a logic high if the signal is larger than V_{T+}, and a low if the input signal is smaller than V_{T-}. Between V_{T+} and V_{T-}, the input signal is detected as the last valid state until one of those values is crossed. An output pulse is triggered on the rising edge of the aforementioned internal Y signal.

The output pulse width is controlled by the selection of external timing components R_{ext} and C_{ext}. Plots are provided in the *Typical Characteristics* section to easily select appropriate component values for a desired pulse width. See the *Features* section for additional information regarding the impact of external components on the timing accuracy of the TPUL1G313-Q1.

8.2 Typical Application

8.2.1 1s Pulse Generator

In this application, the TPUL1G313-Q1 is used to produce a 1s output pulse from a rising edge input trigger. The circuit configuration is shown in Figure 8-1. Select R_{ext} = 102kΩ and C_{ext} = 10nF for a typical pulse width of 1.005s. With a 1% resistor and a 20% capacitor, the expected minimum pulse width is 670ms and the expected maximum pulse width is 1.340s.

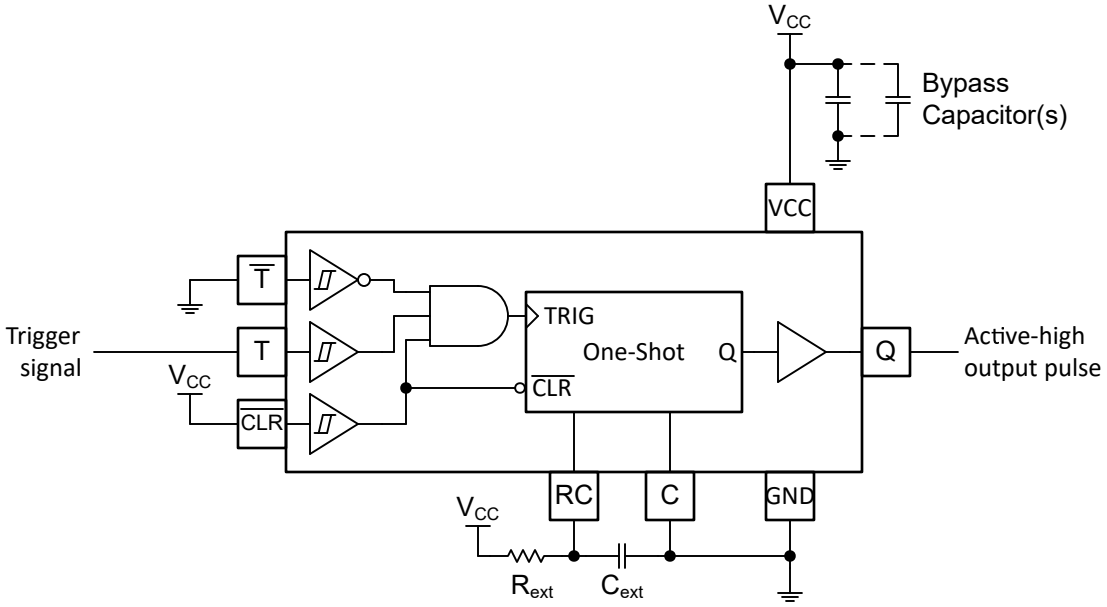


Figure 8-1. Pulse Generation Using the TPUL1G313-Q1

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8.2.1.1 Design Requirements

8.2.1.1.1 Timing Components

The external timing components will directly determine the output pulse width of the TPUL1G313-Q1.

The range of supported values for R_{ext} and C_{ext} are provided in the *Recommended Operating Conditions* table.

The TPUL1G313-Q1 can be used with the C_{ext} pin left disconnected, which is described as C_{ext} = 0pF. In this condition, the output pulse width is determined by the operating voltage and external timing resistor, R_{ext}, only. See detailed plots in *Typical Characteristics* for expected output pulse width in this condition.

8.2.1.1.2 Input Considerations

Input signals must cross $V_{t-(min)}$ to be considered a logic LOW, and $V_{t+(max)}$ to be considered a logic HIGH. Do not exceed the maximum input voltage range found in the *Absolute Maximum Ratings*.

Unused inputs must be terminated to either V_{CC} or ground. The unused inputs can be directly terminated if the input is completely unused, or they can be connected with a pull-up or pull-down resistor if the input will be used sometimes, but not always. A pull-up resistor is used for a default state of HIGH, and a pull-down resistor is used for a default state of LOW. The drive current of the controller, leakage current into the TPUL1G313-Q1 (as specified in the *Electrical Characteristics*), and the desired input transition rate limits the resistor size. A 10kΩ resistor value is often used due to these factors.

The TPUL1G313-Q1 has no input signal transition rate requirements because it has Schmitt-Trigger inputs, however it is characterized for operation within the limits provided in the *Recommended Operating Conditions* table.

Schmitt-Trigger inputs also provide significant noise rejection, however noise with a large enough amplitude can still cause issues. Refer to the hysteresis value, $\Delta V_{T(min)}$ in the *Electrical Characteristics*, which will provide the peak-to-peak noise rejection limit.

Unlike what happens with standard CMOS inputs, Schmitt-Trigger inputs can be held at any valid voltage value without causing huge increases in power consumption. The typical additional current caused by holding an input at a value other than V_{CC} or ground is plotted in the *Typical Characteristics*.

Refer to the *Feature Description* section for additional information regarding the inputs for this device.

8.2.1.1.3 Output Considerations

The positive supply voltage is used to produce the output HIGH-state voltage. Drawing current from the output will decrease the output voltage as specified by the V_{OH} specification in the *Electrical Characteristics*. The ground voltage is used to produce the output LOW-state voltage. Sinking current into the output will increase the output voltage as specified by the V_{OL} specification in the *Electrical Characteristics*.

Push-pull outputs that could be in opposite states, even for a very short time period, should never be connected directly together. This can cause excessive current and damage to the device.

Unused outputs can be left floating. Do not connect outputs directly to V_{CC} or ground.

Refer to the *Feature Description* section for additional information regarding the outputs for this device.

8.2.1.1.4 Power Considerations

Ensure the desired supply voltage is within the range specified in the *Recommended Operating Conditions*. The supply voltage sets the device's electrical characteristics of the device as described in the *Electrical Characteristics* section.

The positive voltage supply must be capable of sourcing current equal to the total current to be sourced by all outputs of the TPUL1G313-Q1 plus the maximum static supply current, I_{CC}, listed in the *Electrical Characteristics*, and any transient current required for switching. The logic device can only source as much current that is provided by the positive supply source. Ensure the maximum total current through V_{CC} listed in the *Absolute Maximum Ratings* is not exceeded. After the output pulse is complete, the external capacitor is quickly recharged to V_{CC} using the supply with maximum current draw as described by $I_{Cext(max)}$ in the *Electrical*

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Characteristics. Additionally, the external timing circuitry will draw power from the supply with a maximum current draw of $I_{ext(max)} = V_{CC} / R_{ext}$, which is pulled directly from the supply and thus is not part of the I_{CC} value for the TPUL1G313-Q1. The dynamic power consumption from the external circuit can be estimated by $P_{RC} = C_{ext} V_{CC}^{2} / t_w$.

The ground must be capable of sinking current equal to the total current to be sunk by all outputs of the TPUL1G313-Q1 plus the maximum supply current, I_{CC}, listed in the *Electrical Characteristics*, and any transient current required for switching. The logic device can only sink as much current that can be sunk into its ground connection. Ensure the maximum total current through GND listed in the *Absolute Maximum Ratings* is not exceeded.

The TPUL1G313-Q1 can drive a load with a total capacitance less than or equal to 50pF while still meeting all of the data sheet specifications. Larger capacitive loads can be applied; however, it is not recommended to exceed 50pF.

The TPUL1G313-Q1 can drive a load with total resistance described by $R_L \geq V_O / I_O$, with the output voltage and current defined in the *Electrical Characteristics* table with V_{OH} and V_{OL}. When outputting in the HIGH state, the output voltage in the equation is defined as the difference between the measured output voltage and the supply voltage at the V_{CC} pin.

Total power consumption can be calculated using the information provided in *CMOS Power Consumption and Cpd Calculation*.

Thermal increase can be calculated using the information provided in *Thermal Characteristics of Standard Linear and Logic (SLL) Packages and Devices*.

CAUTION

The maximum junction temperature, $T_{J(max)}$ listed in the *Absolute Maximum Ratings*, is an additional limitation to prevent damage to the device. Do not violate any values listed in the *Absolute Maximum Ratings*. These limits are provided to prevent damage to the device.

8.2.1.2 Detailed Design Procedure

1. Using the plots provided in *Typical Characteristics*, select a timing resistor, R_{ext}, and timing capacitor, C_{ext}, value to meet the system pulse width requirements. TI recommends starting with a resistor value near the midpoint of the range provided in the *Recommended Operating Conditions*, as this will allow for maximum flexibility for adjustments in the final system.
2. Connect the selected timing resistor from RC to V_{CC}.
3. Connect the selected capacitor from RC (positive) to C (negative). The C pin can additionally connect to ground, however it is not required for normal operation.
4. Add a 0.1µF decoupling capacitor from V_{CC} to GND. Place the capacitor physically close to the device and electrically close to both the V_{CC} and GND pins. The *Layout* section shows an example layout.
5. Verify the capacitive load at the output is ≤ 50pF. This is not a hard limit; by design, however, it optimizes performance. This can be accomplished by providing short, appropriately sized traces from the TPUL1G313-Q1 to one or more of the receiving devices.
6. Verify the resistive load at the output is larger than $(V_{CC} / I_{O(max)})\Omega$. Doing this prevents the maximum output current from the *Absolute Maximum Ratings* from being violated. Most CMOS inputs have a resistive load measured in MΩ; much larger than the minimum calculated previously.
7. Thermal issues are rarely a concern for TPUL family devices; the power consumption and thermal increase, however, can be calculated using the steps provided in the application note, *CMOS Power Consumption and Cpd Calculation*.

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8.2.1.3 Application Curves

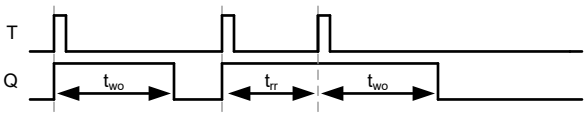


Figure 8-2. Output Pulse Timing Diagram

8.3 Power Supply Recommendations

The power supply can be any voltage between the minimum and maximum supply voltage rating listed in the *Recommended Operating Conditions*.

During startup, the power supply should ramp within the provided power-up ramp rate range in the *Recommended Operating Conditions* table.

Each V_{CC} terminal must have a good bypass capacitor to prevent power disturbance. For normal operation of the TPUL1G313-Q1, a 0.1µF bypass capacitor is recommended. To reject different frequencies of noise, use multiple bypass capacitors in parallel. Capacitors with values of 0.1µF and 1µF are commonly used in parallel.

8.4 Layout

8.4.1 Layout Guidelines

- Timing component placement
  - Place near the device
  - Provide an electrically short path to the device terminal connections
- Bypass capacitor placement
  - Place near the positive supply terminal of the device
  - Provide an electrically short ground return path
  - Use wide traces to minimize impedance
  - Keep the device, capacitors, and traces on the same side of the board whenever possible
- Signal trace geometry
  - 8mil to 12mil trace width
  - Lengths less than 12cm to minimize transmission line effects
  - Avoid 90° corners for signal traces
  - Use an unbroken ground plane below signal traces
  - Flood fill areas around signal traces with ground
  - For traces longer than 12cm
    - Use impedance controlled traces
    - Source-terminate using a series damping resistor near the output
    - Avoid branches; buffer signals that must branch separately

8.4.2 Layout Example

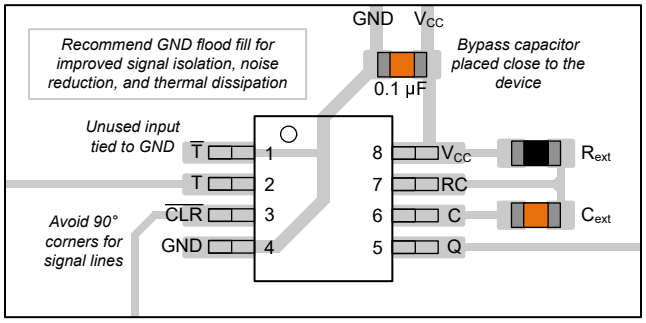


Figure 8-3. Layout Example

9 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed below.

9.1 Documentation Support

9.1.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, *CMOS Power Consumption and C_{pd} Calculation* application note
- Texas Instruments, *Designing With Logic* application note
- Texas Instruments, *Thermal Characteristics of Standard Linear and Logic (SLL) Packages and Devices* application note

9.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

9.3 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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9.4 Trademarks

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9.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

9.6 Glossary

TI Glossary	This glossary lists and explains terms, acronyms, and definitions.

10 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from February 28, 2026 to June 6, 2026 (from Revision * (February 2026) to Revision A (July 2026))	Page
• Changed the document status from Advance Information to Production Data	1

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11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
PTPUL1G313DCURQ1	Active	Preproduction	VSSOP (DCU) | 8	3000 | LARGE T&R	-	Call TI	Call TI	-40 to 125	

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

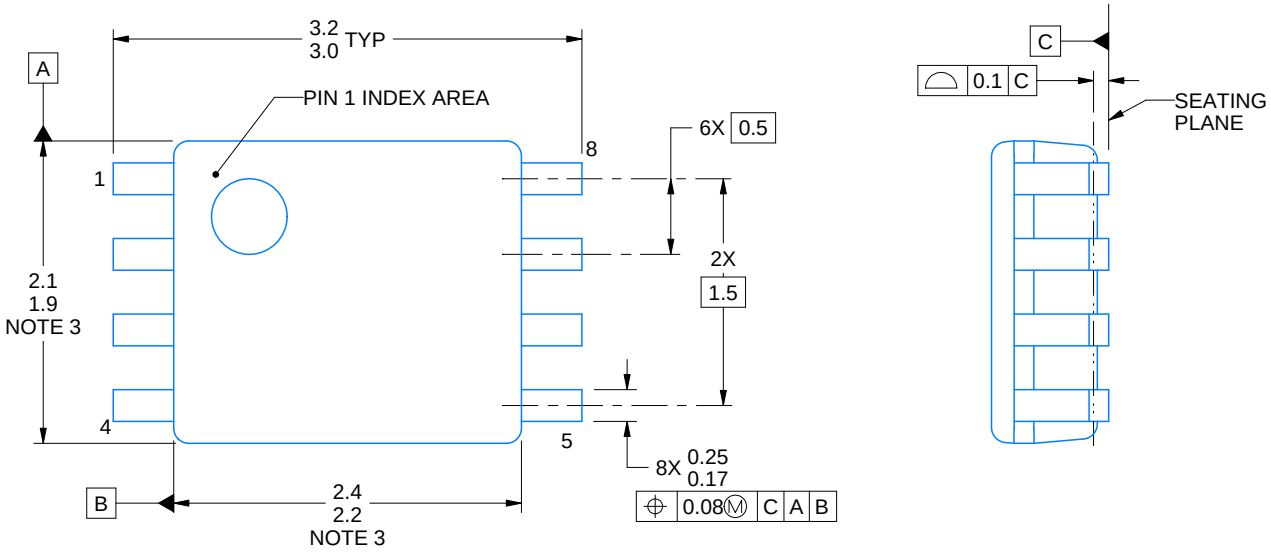
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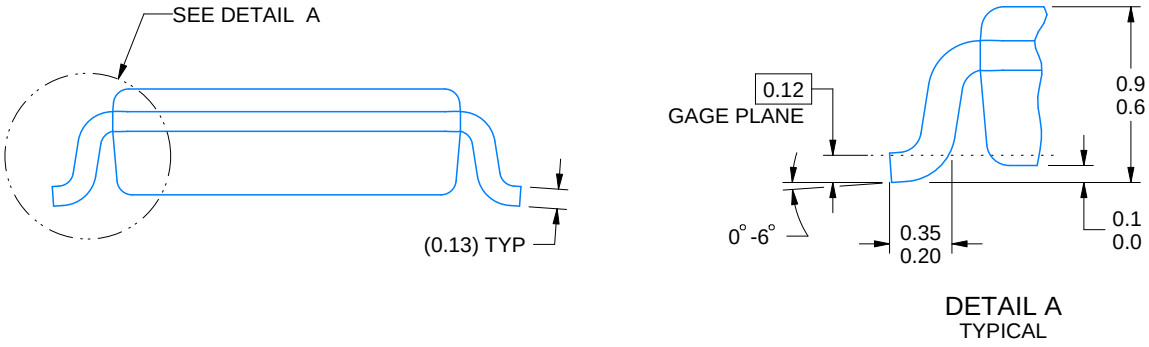


PACKAGE OUTLINE

VSSOP - 0.9 mm max height

SMALL OUTLINE PACKAGE

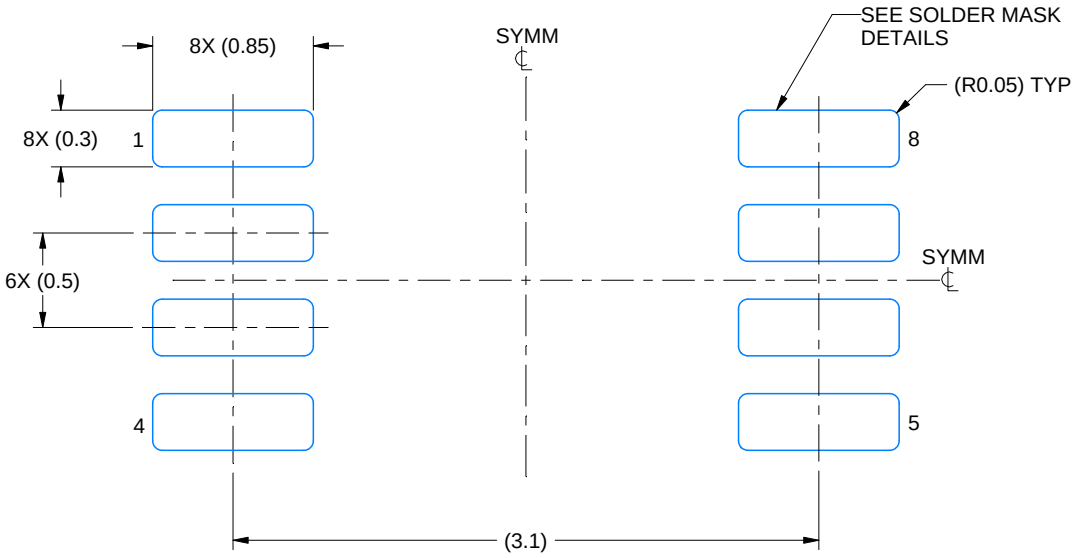




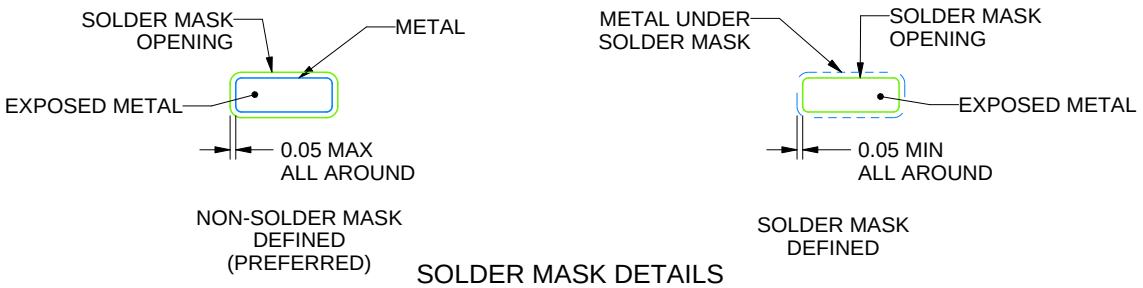
4225266/A 09/2014

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. Reference JEDEC registration MO-187 variation CA.



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 25X

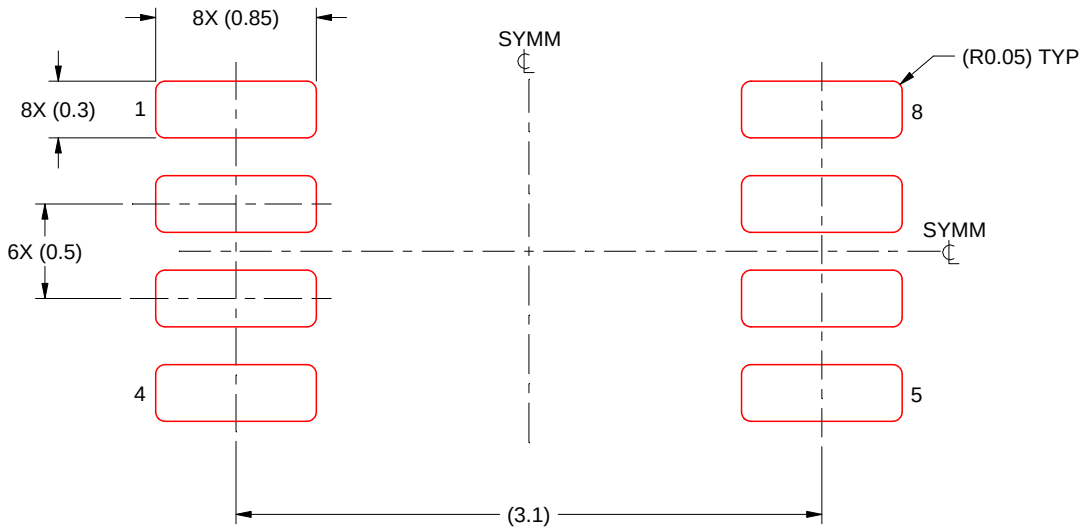


SOLDER MASK DETAILS

4225266/A 09/2014

NOTES: (continued)

5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE: 25X

4225266/A 09/2014

NOTES: (continued)

7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
8. Board assembly site may have different recommendations for stencil design.

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