

Errata

J722S/TDA4VEN/TDA4AEN/AM67 Processor Silicon Revision 1.0 Errata



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1 Modules Affected

Table 1-1 shows the module(s) that are affected by each usage note.

Table 1-1. Usage Note by Modules

MODULE	USAGE NOTE
USB	i2134 — USB: 2.0 Compliance Receive Sensitivity Test Limitation

Table 1-2 shows the module(s) that are affected by each advisory.

Table 1-2. Advisories by Modules

MODULE	ADVISORY
BCDMA	i2431 — BCDMA: RX Channel can lockup in certain scenarios
	i2436 — BCDMA: BCDMA RX_IGNORE_LONG setting in RX CHAN CFG register doesn't work
Boot	i2366 — Boot: ROM does not comprehend specific JEDEC SFDP features for 8D-8D-8D operation
	i2372 — Boot: ROM doesn't support select multi-plane addressing schemes in Serial NAND boot
	i2410 — Boot: ROM may fail to boot due to i2409
	i2419 — Boot: When disabling deskew calibration, ROM does not check if deskew calibration was enabled
C7x SE	i2457 — Boot: Missing data in UART transfer causes boot failures
	i2120 — C71x: SE Hangs on Non-Parity Error Detection in Transposed Streams With LEZR
	i2199 — C71x: SE returning incorrect data when non-aligned transposed stream crosses AM1 circular buffer boundary
CPSW	i2399 — C7x: CPU NLC Module Not Clearing State on Interrupt
	i2208 — CPSW: ALE IET Express Packet Drops
	i2401 — CPSW: Host Timestamps Cause CPSW Port to Lock up
CSI	i2190 — CSI_RX_IF may enter unknown state following an incomplete frame
DDR	i2160 — DDR: Valid VRef Range Must be Defined During LPDDR4 Command Bus Training
	i2330 — DDRSS Register Configuration Tool Updates
DSS	i2097 — DSS: Disabling a Layer Connected to Overlay May Result in Synclost During the Next Frame
ECC AGGR	i2049 — ECC AGGR: Potential IP Clockstop/reset sequence hang due to pending ECC Aggregator interrupts
IA	i2196 — IA: Potential deadlock scenarios in IA
MCAN	i2278 — MCAN: Message Transmit order not guaranteed from dedicated Tx Buffers configured with same Message ID
	i2279 — MCAN: Specification Update for dedicated Tx Buffers and Tx Queues configured with same Message ID
MMCSDB	i2312 — MMCSDB: HS200 and SDR104 Command Timeout Window Too Small
	i2478 — MMCSDB0: HS400 Mode not supported
OSPI	i2189 — OSPI: Controller PHY Tuning Algorithm
	i2249 — OSPI: Internal PHY Loopback and Internal Pad Loopback clocking modes with DDR timing inoperable
	i2351 — OSPI: Controller does not support Continuous Read mode with NAND Flash
	i2383 — OSPI: 2-byte address is not supported in PHY DDR mode
PCIe	i2242 — PCIe: The SerDes PCIe Reference Clock Output is temporarily disabled while changing Data Rates
	i2243 — PCIe: Timing requirement for disabling output refclk during L1.2 substate is not met
	i2326 — PCIe: MAIN_PLLx operating in fractional mode, which is required for enabling SSC, is not compliant with PCIe Refclk jitter limits
PLL	i2424 — PLL: PLL Programming Sequence May Introduce PLL Instability
PRG	i2253 — PRG: CTRL_MMR STAT registers are unreliable indicators of POK threshold failure
PSIL	i2137 — Clock stop operation can result in undefined behavior
RAT	i2062 — RAT: Error Interrupt Triggered Even When Error Logging Disable Is Set
Reset	i2407 — RESET: MCU_RESETSTATz unreliable when MCU_RESETz is asserted low
SGMII	i2362 — 10-100M SGMII: Marvell PHY does not ignore the preamble byte resulting in link failure
USART	i2310 — USART: Erroneous clear/trigger of timeout interrupt

Table 1-2. Advisories by Modules (continued)

MODULE	ADVISORY
	i2311 — USART: Spurious DMA Interrupts
USB	i2409 — USB2 PHY locks up due to short suspend

2 Nomenclature, Package Symbolization, and Revision Identification

2.1 Device and Development-Support Tool Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all microprocessors (MPUs) and support tools. Each device has one of three prefixes: X, P, or null (no prefix) (for example, XJ722SAAMW

). Texas Instruments recommends two of three possible prefix designators for its support tools: TMDX and TMDS. These prefixes represent evolutionary stages of product development from engineering prototypes (TMDX) through fully qualified production devices and tools (TMDS).

Device development evolutionary flow:

- X** Experimental device that is not necessarily representative of the final device's electrical specifications and may not use production assembly flow.
- P** Prototype device that is not necessarily the final silicon die and may not necessarily meet final electrical specifications.
- null** Production version of the silicon die that is fully qualified.

Support tool development evolutionary flow:

TMDX Development-support product that has not yet completed Texas Instruments internal qualification testing.

TMDS Fully-qualified development-support product.

X and P devices and TMDX development-support tools are shipped against the following disclaimer:

"Developmental product is intended for internal evaluation purposes."

Production devices and TMDS development-support tools have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

Predictions show that prototype devices (X or P) have a greater failure rate than the standard production devices. Texas Instruments recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

For additional information how to read the complete device name for any J722S device, see the specific-device Datasheet (SPRSP96).

2.2 Devices Supported

This document supports the following devices:

- J722S, TDA4VEN, TDA4AEN, AM67

2.3 Package Symbolization and Revision Identification

Figure 2-1 shows an example of package symbolization.

Table 2-1 lists the device revision codes.

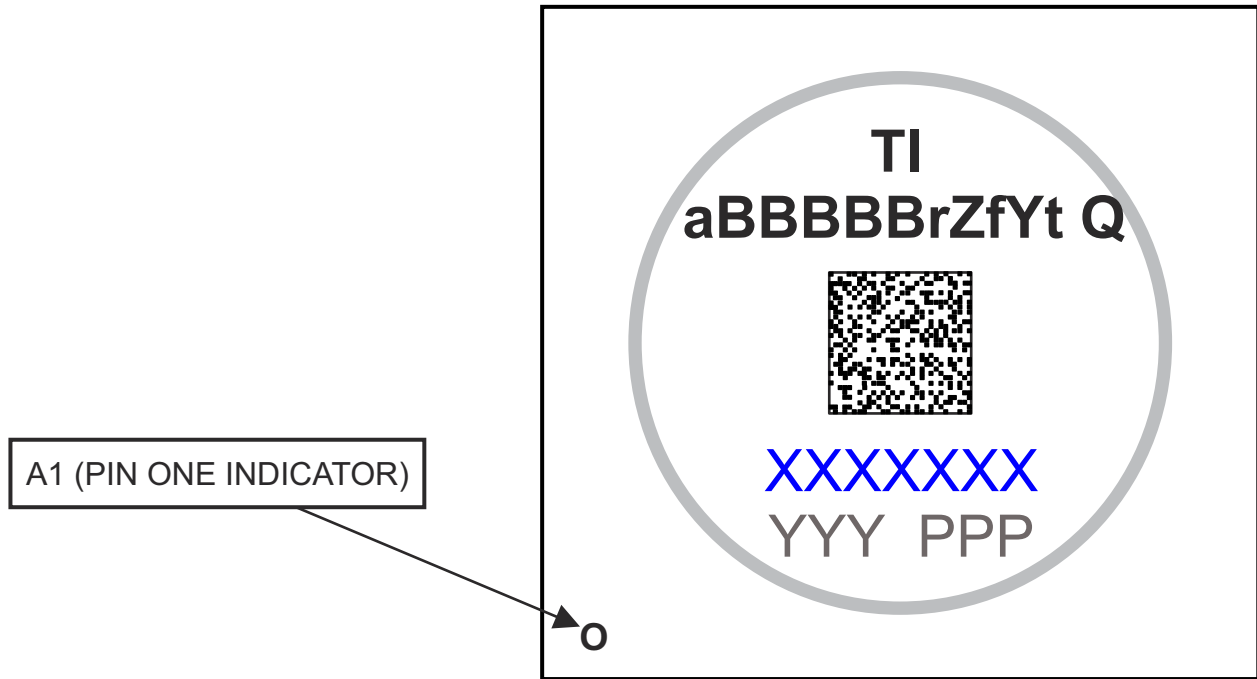


Figure 2-1. Package Symbolization

Table 2-1. Revision Identification

DEVICE REVISION CODE	SILICON REVISION	COMMENTS
A or BLANK	1.0	

3 Silicon Revision 1.0 Usage Notes and Advisories

This section lists the usage notes and advisories for this silicon revision.

3.1 Silicon Revision 1.0 Usage Notes

i2134 **USB: 2.0 Compliance Receive Sensitivity Test Limitation**

Details:

Performing receive sensitivity tests (EL_16 and EL_17) as defined in the USB-IF USB 2.0 Electrical Compliance Test Specification may invoke the problem described in Advisory i2091.

The issue was originally found while performing these tests using automation software, which increased USB signal amplitude while sending packets. The software was sweeping the amplitude from a value less than 100 mV to a value greater than 150 mV while verifying the device under test (DUT) NAK'd all packets below 100 mV and NAK'd no packets above 150 mV. However, increasing the amplitude through the squelch threshold while sending valid packets may lock the PHY as described in Advisory i2091.

Workaround(s):

3.2 Silicon Revision 1.0 Advisories

i2049 **ECC_AGGR: Potential IP Clockstop/Reset Sequence Hang due to Pending ECC Aggregator Interrupts**

Details:

The ECC Aggregator module is used to aggregate safety error occurrences (which are rare) and generate interrupts to notify software. The ECC Aggregator provides software control over the enabling/disabling and clearing of safety errors interrupts.

When software is performing a clockstop/reset sequence on an IP, the sequence can potentially not complete because the IP's associated ECC Aggregator instance is not idle. The ECC Aggregator idle status is dependent upon any pending safety error interrupts either enabled or disabled, which have not been cleared by software. As a result, the IP's clockstop/reset sequence may never complete (hang) if there are any pending safety errors interrupts that remain uncleared.

The affected ECC_AGGRs can be determined by the value listed in the Technical Reference Manual (TRM) for their REV register at Register Offset 0h. The REV register encodes the ECC_AGGR version in its fields as follows:

v[REVM AJ].[REVM IN].[REVRTL]

ECC_AGGR versions before v2.1.1 are affected. ECC_AGGR versions v2.1.1 and later are not affected.

Affected Example:

REVM AJ = 2

REVM IN = 1

REVRTL = 0

The above values decode to ECC_AGGR Version v2.1.0, which is Affected.

Not Affected Example:

REVM AJ = 2

i2049 (continued) ***ECC_AGGR: Potential IP Clockstop/Reset Sequence Hang due to Pending ECC Aggregator Interrupts***

REVMIN = 1

REVRTL = 1

The above values decode ECC_AGGR Version v2.1.1, which is Not Affected.

Workaround(s):

General Note:

Clockstopping the ECC Aggregator is not supported in functional safety use-cases.

Software should use the following workaround for non-functional safety use-cases:

1. Enable all ECC Aggregator interrupts for the IP
2. Service and clear all Pending interrupts
3. Step 3:
 - a. Disable all interrupt sources to the ECC Aggregator, followed by performing Clockstop/reset sequence.
 - b. Perform Clockstop/reset sequence, while continuing to service/clear pending interrupts.

Due to interrupts being external stimuli, software has two options for step 3:

1. Disable all interrupt sources (EDC CTRL checkers) that can generate pending ECC_AGGR interrupts prior to performing the clockstop/reset sequence
2. Continue to service/clear pending interrupts that occur while performing the clkstop/reset sequence. The sequence would proceed when all interrupts are cleared.

Software in general may need to detect pending interrupts that continuously fire during this entire sequence (ex. in the case of a stuck-at fault scenario), and disable their associated EDC CTRL safety checkers to allow the clockstop/reset sequence to progress towards completion.

i2062 ***RAT: Error Interrupt Triggered Even When Error Logging Disable Is Set***

Details:

If the RAT error logging is programmed to disable logging and enable interrupts, then an error will incorrectly trigger an interrupt but the error log registers will correctly not be updated. The error interrupt should not have been generated.

Workaround(s):

If the RAT error logging is disabled, then the error interrupt should also be disabled by software.

i2097 ***DSS: Disabling a Layer Connected to Overlay May Result in Synclost During the Next Frame***

Details:

Disabling a layer (for example VID1) connected to an OVR (that is toggling DSS_VID_ATTRIBUTESx[0] ENABLE from 1 to 0) may result in synclost during the next frame. The synclost may result in a corrupted or blank frame (all pixel data sent out of DSS during the frame is 0x0). The occurrence of synclost is dependent on the timing of setting the GO bit (that is DSS_VP_CONTROL[5] GOBIT to 1) vis-à-vis the disabling of the layer. If the “disable layer” MMR write operation and “set GO bit” MMR write operation happens within the same frame boundary, no synclost occurs. If the operations happen across the frame boundary, then synclost occurs (for one frame). The design

i2097 (continued) DSS: Disabling a Layer Connected to Overlay May Result in Synclost During the Next Frame

automatically recovers and returns to normal operation from the next frame after GO bit is set, see [Figure 3-1](#).

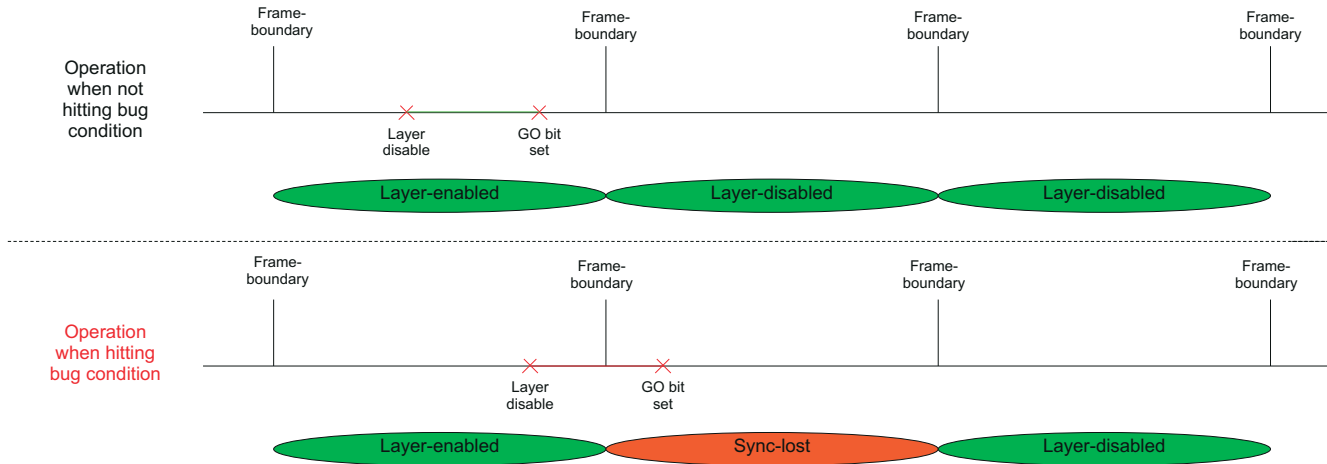


Figure 3-1. Bug Condition

Workaround(s):

A simple software workaround exists. In the workaround, prior to disabling a layer on the OVR, it is moved to the “non-visible” area of the OVR (for example: `DSS_OVR_ATTRIBUTES_x[17-6] POSX = max_value_of_posx` or `DSS_OVR_ATTRIBUTES_x[30-19] POSY = max_value_of_posy`). This avoids the synclost when the layer is disabled.

A sample software workaround pseudo-code is shown on [Figure 3-2](#). In this case, the regular “disable layer” MMR write operation and “set GO bit set” MMR write operation are replaced with macros which implement the software workaround.

```

macro disable_layer (overlay n , layer m)
set OVR[n].ATTRIBUTES2[m].PO SX = posx_max;
set OVR[n].ATTRIBUTES2[m].PO SY = posy_max;
global_ovr_layer_disable_tracker[n][m] = 1;
endmacro

macro set_go_bit (vp n)
if(! (global_ovr_layer_disable_tracker[n])//any bit set
{
set VP[n].CONTROL.GOBIT = 1;
Wait for 10 DSS FUNC CLK cycles;
for (i=0;i<NUM_LAYERS;i++)
{
if(global_ovr_layer_disable_tracker[n][i])
{
Clear OVR[n].ATTRIBUTES[i].ENABLE = 0;
global_ovr_layer_disable_tracker[n][i] = 0;
}
}
}
set VP[n].CONTROL.GOBIT = 1;
endmacro

```

- Replace layer disable MMR write operation with a macro which positions the layer to the non-visible area of the OVR
- Track which layers are disabled. This will be used while GO bit is set
- Replace GO bit set MMR write operation with this macro
- First, set GO Bit for the changes in “disable_layer” macro (and any other earlier changes) to take effect
- After the first GO bit set, few idle_cycles (10 DSS functional clock cycles) are necessary before we move to the second step
- In the second step, actually disable the layers based on the previously tracked information
- Set the GO bit for the second time for the disable of the layers to take effect

Figure 3-2. Workaround Pseudo-code

i2120

C71x: SE Hangs on Non-Parity Error Detection in Transposed Streams With LEZR

Details:

The C71x Streaming Engine's (SE) pipeline for returning formatted data and return report internal error information is always monitoring the tags for the data that it is working on. When an error is detected for a line of data used to format data back to the CPU, all

i2120 (continued) *C71x: SE Hangs on Non-Parity Error Detection in Transposed Streams With LEZR*

fetching side execution for queuing up commands to go to UMC, uTLB, and the formatting pipeline back to CPU is halted.

In general operation, the only tags monitored for errors are the ones being used for the current command. For transposed mode, this is all tags touched by the current array column. A gap in suppressing internal tag monitoring causes the formatting pipeline to monitor tags that it is not currently working on while creating zero vectors for the LEZR feature. If the SE's fetching side encounters and records an error for a future column, the formatting side may notice it and halt the fetching side before the command for that column has been committed for formatting.

Errors are only reported back to the CPU for commands that are internally committed for formatting, thus halting internal execution before committing the column results in no error being reported to the CPU. Because the SE has halted fetching operations without reporting an error, the CPU proceeds to hang, waiting for either return data or an error from the SE, until an unrelated external event or interrupt occurs.

Workaround(s): The only 100% workaround is to not use stream templates with both LEZR and transposed mode enabled.

i2137 *PSIL: Clock stop operation can result in undefined behavior*

Details: The clock stop interface is a request/acknowledge interface used to coordinate the handshaking of properly stopping the main clock to the module. Attempting a clock stop on the module without first performing the channel teardowns or clearing of global enable bits will result in module-specific behavior that may be undefined.

The impacted modules are PDMA, SA2UL, Ethernet SW, CSI, UDMAP, ICSS, and CAL.

Workaround(s): Before attempting to perform a clock stop operation, software is required to teardown all active channels (via UDMAP “real time” registers in the UDMAP, or PSIL register 0x408 in PSIL based modules), and after this is complete, also clear the global enable bit for all channels (via PSIL register 0x2 in both the UDMAP and PSIL based modules).

i2160 *DDR: Valid VRef Range Must be Defined During LPDDR4 Command Bus Training*

Details: The DDR PHY updates VREF(ca) for the command/address bus during LPDDR4 Command Bus Training (CBT). If VREF(ca) search range is set to invalid values such as no working settings can be found during CBT, the training process could fail or hang.

Workaround(s): Set the following fields to known valid working values before enabling CBT.

For frequency set 0: DDRSS_PI_199[6-0] PI_CALVL_VREF_INITIAL_START_POINT_F0 and DDRSS_PI_199[14-8] PI_CALVL_VREF_INITIAL_STOP_POINT_F0 bit fields.

For frequency set 1: DDRSS_PI_199[22-16] PI_CALVL_VREF_INITIAL_START_POINT_F1 and DDRSS_PI_199[30-24] PI_CALVL_VREF_INITIAL_STOP_POINT_F1 bit fields.

For frequency set 2: DDRSS_PI_200[6-0] PI_CALVL_VREF_INITIAL_START_POINT_F2 and DDRSS_PI_200[14-8] PI_CALVL_VREF_INITIAL_STOP_POINT_F2 bit fields.

i2160 (continued) DDR: Valid VRef Range Must be Defined During LPDDR4 Command Bus Training

Recommendation is to use the nominal VRef value (based on the device programming of VDDQ/3 or VDDQ/2.5 along with the drive/termination settings used) +/- 4%.

i2189 OSPI: Controller PHY Tuning Algorithm

Details:

The OSPI controller uses a DQS signal to sample data when the PHY Module is enabled. However, there is an issue in the module which requires that this sample must occur within a window defined by the internal clock. Read operations are subject to external delays, which change with temperature. In order to guarantee valid reads at any temperature, a special tuning algorithm must be implemented which selects the most robust TX, RX, and Read Delay values.

Workaround(s):

The workaround for this bug is described in detail in [SPRACT2](#). To sample data under some PVT conditions, it is necessary to increment the Read Delay field to shift the internal clock sampling window. This allows sampling of the data anywhere within the data eye. However, this has these side effects:

1. PHY Pipeline mode must be enabled for all read operations. Because PHY Pipeline mode must be disabled for writes, reads and writes must be handled separately.
2. Hardware polling of the busy bit is broken when the workaround is in place, so SW polling must be used instead. Writes must occur through DMA accesses, within page boundaries, to prevent interruption from either the host or the flash device. Software must poll the busy bit between page writes. Alternatively, writes can be performed in non-PHY mode with hardware polling enabled.
3. STIG reads must be padded with extra bytes, and the received data must be right-shifted.

i2190 CSI: CSI_RX_IF may enter unknown state following an incomplete frame

Details:

When an incomplete frame with potential CRC error is received by the CSI2 interface, the module may enter an unknown state. In which case all the subsequent image frames will not be captured.

Workaround(s):

Reset the CSI_RX_IF module.

i2196 IA: Potential deadlock scenarios in IA

Details:

The interrupt Aggregator (IA) has one main function, which is to convert events arriving on the Event Transport Lane (ETL) bus, can convert them to interrupt status bits which are used to generate level interrupts. The block that performed this function in IA version 1.0 was called the status event block.

In addition to the status event block, there are two other main processing blocks; the multicast event block, and the counted event block. The multicast block really functions as an event splitter. For every event it takes in, it can generate two output events. The counted event block is used to convert high frequency events into a readable count. It

i2196 (continued) IA: Potential deadlock scenarios in IA

counts input events and generates output events on count transitions to/from 0 to/from non-zero count values. Unlike the status event block, the multicast and counted event blocks generate output ETL events that are then mapped to other processing blocks.

An issue was found after design that could cause the IA to deadlock. The issue occurs when event “loops” occur between these three processing blocks. It is possible to create a situation where a processing block can not output an event because the path is blocked, and since it can not output an event, it can not take any new input events. This inability to take input events prevents the output path from being able to unwind, and thus both paths remain blocked.

Workaround(s):

Figure 3-3 shows the conceptual block diagram of IA 1.0. Potential loops are avoided by adopting the policy of not allowing the counted event block to send events to the multicast block. This method was chosen because it is more common to split an event first, and then count one while sending the other elsewhere. With this path blocked by convention, it is not possible for a single event to visit any block more than once and thus not possible for paths to become blocked so long as the outputs remain unblocked.

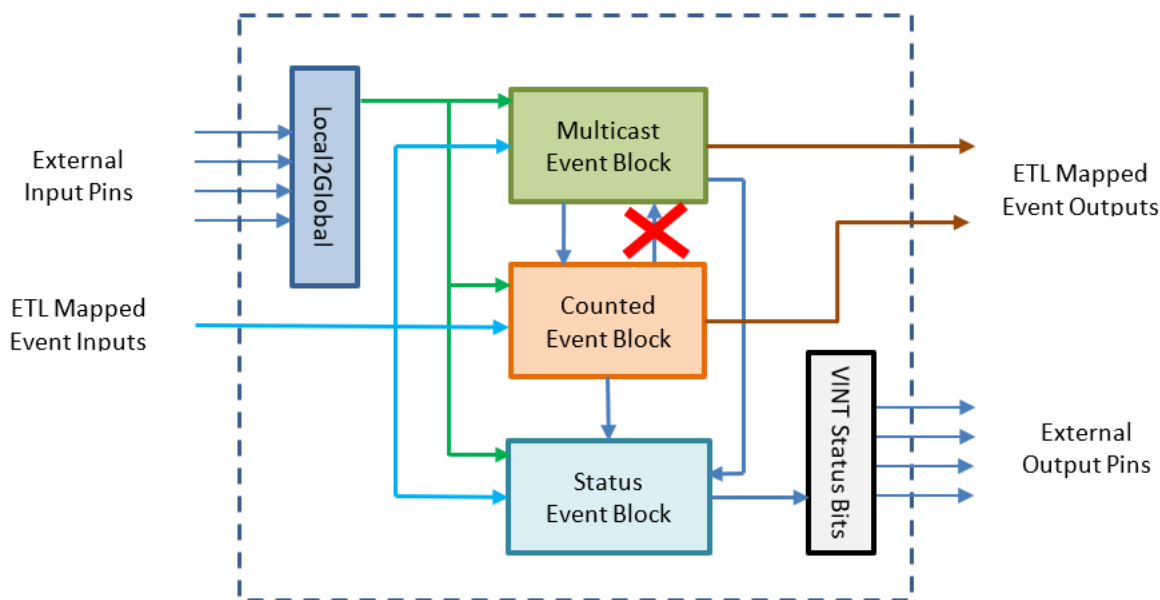


Figure 3-3. Interrupt Aggregator Version 1.0

By following the conventions outlined here, the system is safe from looping hazards that can create a deadlock scenario.

i2199 C71x: SE returning incorrect data when non-aligned transposed stream crosses AM1 circular buffer boundary

Details:

When AM1 refers to a larger circular buffer size than AM0, SE can reuse the wrong 64B line of data during non-aligned transposed streams. This occurs when one of the rows being transposed crosses the AM1 circular buffer boundary, but not the AM0 boundary.

i2199 (continued) **C71x: SE returning incorrect data when non-aligned transposed stream crosses AM1 circular buffer boundary**

Workaround(s): Have the transposed stream either be fully aligned, meaning that the start address and all scaled DIM values be multiples of 64B, or to not configure AM1 to be a larger circular addressing buffers size than AM0.

i2208 **CPSW: ALE IET Express Packet Drops**

Details: This issue impacts the following Module:

The issue with ALE is due to CPSW frequency and IET operation with short express traffic and pre-empted packets that get pre-empted between 60-69 bytes on non-10G capable ports.

If an IET pre-emptible packet get interrupted at 60-69 bytes, the lookup will occur when the next chunk arrives. The CPSW only gives the ALE 64 bytes from the pre-emptible MAC.

As a result, a short express traffic lookup will start at the end of a 64 byte express traffic, but when the pre-empted queue continues, the pre-empted traffic will complete the 64 bytes and attempt a lookup for the pre-empt packet. But this lookup is less than 64 clocks from the express lookup start, so the express lookup will be aborted (express traffic dropped) and start the new lookup for the pre-empted traffic.

Rules to induce the issue:

1. You are in IET (Interspersed Express Traffic) mode on ports not capable of 5/10G operation
2. Remote express packets can be preempt packets as low as 60 bytes
3. Pre-empt packet traffic that is 128 bytes or more.
4. Express traffic that interrupts the pre-empt traffic between 60-69 bytes.
5. A short express traffic immediately followed by the continuation of the pre-empt traffic.
 - a. Gap between express frame and pre-empt frame be its minimum.
6. The CPSW frequency is at its lowest capability for the speeds required.

Workaround(s): During IET negotiation, tell the remote to fragment at 128 bytes.

i2242**PCIe: The SerDes PCIe Reference Clock Output is temporarily disabled while changing Data Rates**

Details

The SerDes PCIe Reference Clock Output will be temporarily disabled when changing Data Rates to or from 8.0 GT/s in Derived Refclk mode (as opposed to Received Refclk mode) and using a single SerDes PLL to generate the PCIe TX and RX clocks. This is due to the PLL reprogramming which must be performed when changing the data rate from 2.5 GT/s or 5.0 GT/s to 8.0 GT/s in this mode.

Some external PCIe components that are using the PCIe Reference Clock may not tolerate the disabling of the clock when changing data rates. However, the SerDes in this Device family does not have an issue accepting this Reference Clock behavior. This means that a link that connects the SerDes in one Device to the SerDes in a second Device will not have an issue when one Device generates the Reference Clock and the other Device receives the Reference Clock.

Workaround

Option 1:

Configure the SerDes to use one PLL to generate the clocks for 2.5 GT/s and 5.0 GT/s data rates, and a second PLL to generate the clocks for 8.0 GT/s data rate. This option imposes some limitations:

A) If Internal SSC mode is used, the two PLLs will not spread in sync with each other. This could result in up to 5000ppm difference between frequency of the two PLLs, and therefore between the TX and RX of the link partners. Because of this, Internal SSC mode is not recommended.

B) Protocols used simultaneously with PCIe on different Lanes of the SerDes must be compatible with sharing the PLL configuration of at least one of the two PLLs used for PCIe.

Option 2:

Use Received Refclk mode. Note that this mode is impacted by the separate Output Refclk jitter errata advisory (i2241)

Option 3:

Do not operate the PCIe interface at the 8.0 GT/s Data Rate

Option 4:

Use an external clock source to supply the PCIe Reference Clock to both the Root Complex and End Point Devices of the Link.

i2243**PCIe: Timing requirement for disabling output refclk during L1.2 substate is not met****Details**

PCIe base specification requires Refclk to reach idle electrical state within 100ns of CLKREQ# deassertion when entering L1.2 substate (please refer TL10_REFCLK_OFF parameter).

This timing requirement cannot be met when sourcing Refclk from the device since hardware does not automatically gate Refclk. Refclk gating has to be performed by software by writing to PHY_EN_REFCLK field in SERDES_RST register.

As a result, Refclk cannot be gated in L1.2 substate. Generally, allowing Refclk to run in L1.2 substate is not expected to cause any functional issues. However, if gating Refclk within 100ns is required by the system, L1.2 substate cannot be supported.

Workaround

Use an external Refclk generator to supply the PCIe reference clock

i2249**OSPI: Internal PHY Loopback and Internal Pad Loopback clocking modes with DDR timing inoperable****Details**

The OSPI Internal PHY Loopback mode and Internal Pad Loopback mode uses “launch edge as capture edge” (same edge capture, or 0-cycle timing).

The programmable receive delay line (Rx PDL) is used to compensate for the round trip delay (Tx clock to Flash device, Flash clock to output and Flash data to Controller).

In the case of internal and IO loopback modes, the total delay of the Rx PDL is not sufficient to compensate for the round trip delay, and thus these modes cannot be used.

The table below describes the recommended clocking topologies in the OSPI controller. All other modes not described here are affected by the advisory in DDR mode and are not recommended clocking topologies.

Table 3-1. OSPI Clocking Topologies

Clocking Mode Terminology	CONFIG_REG.PHY_MODE_ENABLE	READ_DATA_CAPTURE.BYPASS	READ_DATA_CAPTURE.DQS_EN	Board implementation
No Loopback, no PHY	0 (PHY disabled)	1 (disable adapted loopback clock)	X	None. Relying on internal clock. Max freq 50MHz.
External Board Loopback with PHY	1 (PHY enabled)	0 (enable adapted loopback clock)	0 (DQS disabled)	External Board Loopback (OSPI_LOOPBACK_CLK_SEL = 0)
DQS with PHY	1 (PHY enabled)	X (DQS enable has priority)	1 (DQS enabled)	Memory strobe connected to SOC DQS pin

Workaround

None. Please use one of the unaffected clocking modes based on the table in the description

i2253**PRG: CTRL_MMR STAT registers are unreliable indicators of POK threshold failure****Details**

The POK overvoltage and undervoltage flags in the CTRL_MMR PRG STAT registers are unreliable indicators of whether the POK has seen a failure. As a result, they are being marked as Reserved in the device Technical Reference Manual (TRM).

i2253 (continued) *PRG: CTRL_MMR STAT registers are unreliable indicators of POK threshold failure*

Workaround

The filtered POK output updates ESM flags.

Upon POK initialization (i.e. enable), the ESM flags should be cleared (due to comparisons carried out during the bandgap and / or the POK settling time). After this initial clear, the ESM flags can be used as a reliable indicator of failure (or no failure) from the POKs.

i2278 *MCAN: Message Transmit order not guaranteed from dedicated Tx Buffers configured with same Message ID*

Details

The erratum is limited to the case when multiple Tx Buffers are configured with the same Message ID (TXBC.NDTB > 1).

Under the following conditions, a message may be transmitted out of order:

- Multiple Tx Buffers configured with the same Message ID
- Tx requests for these Tx Buffers are submitted sequentially with delays between each

Workaround

Workaround #1:

After writing the Tx messages with same Message ID to the Message RAM, request transmission of all these message concurrently by single write access to TXBAR. Make sure none of these messages have a pending Tx request before making the concurrent request.

Workaround #2:

Use the Tx FIFO instead of dedicated Tx Buffers (set bit MCAN_TXBC[30] TFQM = 0 to use Tx FIFO) for the transmission of several messages with the same Message ID in a specific order.

i2279 *MCAN: Specification Update for dedicated Tx Buffers and Tx Queues configured with same Message ID*

Details

The erratum updates the descriptions in Section 3.5.2 Dedicated Tx Buffers and 3.5.4 Tx Queue of the M_CAN User's Manual related to message transmission from multiple dedicated Tx Buffers configured with the same Message ID.

Workaround

Workaround #1:

After writing the Tx messages with same Message ID to the Message RAM, request transmission of all these message concurrently by single write access to TXBAR. Make sure none of these messages have a pending Tx request before making the concurrent request.

Workaround #2:

Use the Tx FIFO instead of dedicated Tx Buffers (set bit MCAN_TXBC[30] TFQM = 0 to use Tx FIFO) for the transmission of several messages with the same Message ID in a specific order.

i2310 ***USART: Erroneous clear/trigger of timeout interrupt***

Details: The USART may erroneously clear or trigger the timeout interrupt when RHR/MSR/LSR registers are read.

Workaround(s):
For CPU use-case.

- If the timeout interrupt is erroneously cleared:
 - This is Valid since the pending data inside the FIFO will retrigger the timeout interrupt
- If timeout interrupt is erroneously set, and the FIFO is empty, use the following SW workaround to clear the interrupt:
 - Set a high value of timeout counter in TIMEOUTH and TIMEOUTL registers
 - Set EFR2 bit 6 to 1 to change timeout mode to periodic
 - Read the IIR register to clear the interrupt
 - Set EFR2 bit 6 back to 0 to change timeout mode back to the original mode

For DMA use-case.

- If timeout interrupt is erroneously cleared:
 - This is valid since the next periodic event will retrigger the timeout interrupt
 - User must ensure that RX timeout behavior is in periodic mode by setting EFR2 bit6 to 1
- If timeout interrupt is erroneously set:
 - This will cause DMA to be torn down by the SW driver
 - Valid since next incoming data will cause SW to setup DMA again

i2311 ***USART Spurious DMA Interrupts***

Details: Spurious DMA interrupts may occur when DMA is used to access TX/RX FIFO with a non-power-of-2 trigger level in the TLR register.

Workaround(s):

Use power of 2 values for TX/RX FIFO trigger levels (1, 2, 4, 8, 16, and 32).

i2312 ***MMCSDB: HS200 and SDR104 Command Timeout Window Too Small***

Details: Under high speed HS200 and SDR104 modes, the functional clock for MMC modules will reach up to 192 MHz. At this frequency, the maximum obtainable timeout through of MMC host controller using MMCSDB_SYSCTL[19:16] DTO = 0xE is $(1/192\text{MHz}) * 2^{27} = 700\text{ms}$. Commands taking longer than 700ms may be affected by this small window frame.

Workaround(s):

If the command requires a timeout longer than 700ms, then the MMC host controller command timeout can be disabled (MMCSDB_CON[6] MIT=0x1) and a software implementation may be used in its place. Detailed steps as follows (in Linux):

1. During MMC host controller probe function (omap_hsmmc.c:omap_hsmmc_probe()), inform processor that the host controller is incapable of supporting all the necessary timeouts.

i2312 (continued) *MMCSDB: HS200 and SDR104 Command Timeout Window Too Small*

2. Modify the MMC core software layer functionality so the core times out on its own when the underlying MMC host controller is unable to support the required timeout.

i2326 *PCIe: MAIN_PLLx operating in fractional mode, which is required for enabling SSC, is not compliant with PCIe Refclk jitter limits*

Details:

The MAIN_PLLx, which optionally supplies the 100MHz PCIe Refclk for SERDES and external components, does not comply to the PCIe Refclk jitter limits when configured in fractional mode. Fractional mode is required for enabling SSC, therefore SSC mode is not compliant to the PCIe Refclk jitter limits.

Workaround(s):

When sourcing the 100MHz PCIe Refclk from the MAIN_PLLx, the MAIN_PLLx should be configured in integer mode only (DACEN = 0, DSMEN = 0). This prevents the use of SSC for PCIe Refclk, which requires the PLL to operate in fractional mode. If SSC is required on the PCIe interface, an external Refclk generator with SSC should be used to provide the SERDES 100MHz Refclk.

i2330 *DDRSS Register Configuration Tool Updates*

Details:

The DDR Register Configuration Tool provides custom register settings based on system level details such as the architecture (density, data width, ranks) of the DDR device, frequency of operation, and IO settings determined through board simulations. This tool may be updated over time to support new devices and/or features, fix issues identified with the tool, and most importantly, capture work-arounds of errata or recent updates identified to register calculations which improve performance, signal integrity, or timing relationships between signals.

Workaround(s):

In order to ensure that parameters are set appropriately based on lessons learned and reduce the risk of functional failure, the latest DDR register configuration tool should always be used to generate register values. As the DDR register configuration tool can periodically be updated, the revision history of the tool should be reviewed and evaluated whether tool changes apply to existing systems. When applicable, the configuration of an existing system should be updated appropriately. The latest version of the tool can be found at <http://dev.ti.com/sysconfig>, and choosing DDR Configuration under Software Product drop down for the applicable device that is being used.

i2351 *OSPI: Direct Access Controller (DAC) does not support Continuous Read mode with NAND Flash*

Details:

The OSPI Direct Access Controller (DAC) doesn't support Continuous Read mode with NAND Flash since the OSPI controller can deassert the CSn signal (by design intent) to the Flash memory between internal DMA bus requests to the OSPI controller.

The issue occurs because "Continuous Read" mode offered by some OSPI/QSPI NAND Flash memories requires the Chip Select input to remain asserted for an entire burst transaction.

The SoC internal DMA controllers and other initiators are limited to 1023 B or smaller transactions, and arbitration/queuing can happen both inside of the various DMA

i2351 (continued) *OSPI: Direct Access Controller (DAC) does not support Continuous Read mode with NAND Flash*

controllers or in the interconnect between any DMA controller and the OSPI peripheral. This results in delays in bus requests to the OSPI controller that result in the external CSn signal being deasserted.

NOR Flash memories are not affected by CSn de-assertion and Continuous Read mode works as expected.

Workaround(s): Software can use page/buffered read modes to access NAND flash.

i2362 *10-100M SGMII: Marvell PHY does not ignore the preamble byte resulting in link failure*

Details: The CPSW SGMII module outputs up to 5 bytes of 0x50 preamble data when in 10/100 mode and there is an odd number of clocks between packets. All bytes should be 0x55. In 1000Mbps mode, which does not have the issue, there are seven 0x55's in the preamble previous to the SFD. In 100Mbps mode there are 70 bytes in the preamble before the SFD (because the data is replicated 10 times from 1000Mbps mode). The first five bytes of the seventy can be 0x50 when the issue occurs. This issue has been undetected until now due to testing only with the PHYs that allow the preamble to be eroded and don't care about the actual data in the first number of bytes. However, this issue was recently detected with a Marvel PHY (88Q1111 or similar) that looks at the preamble data and makes packet keep/discard decisions based on preamble data of 0x50.

Workaround(s): The workaround options are:

1. Use 1000M mode which does not have the issue.

OR

2. Use a TI PHY (DP83869 or similar) or any other PHY which can erode/ignore the preamble data in 10/100/1000M mode.

i2366 *Boot: ROM does not comprehend specific JEDEC SFDP features for 8D-8D-8D operation*

Details: JEDEC spec JESD216 - SERIAL FLASH DISCOVERABLE PARAMETERS (SFDP) details the parameter table used in certain serial flash devices to describe features and how to communicate/configure the device. The ROM interprets relevant portions of the SFDP for a device's features (such as a how to change from 1S-1S-1S to 8D-8D-8D mode), but does not properly comprehend a flash device that requires:

- A swapped byte order in 8D-8D-8D mode compared to 1S-1S-1S mode
- A command extension that in 8D-8D-8D mode that requires a different command than the first byte sent (such as an inversion of the opcode or another unique byte)

Workaround(s): Review the SFDP table of any candidate flash memory that is compliant with JEDEC JESD216; in most cases vendors do not publish this table and can instead be requested from the flash vendor. If the 18th DWORD of the JEDEC Basic Flash Parameter table has bit 31 with a value of "1b", then the memory must be programmed with a swapped byte order from the factory or programmed with the SoC. If bits [30:29] have a value other

i2366 (continued) **Boot: ROM does not comprehend specific JEDEC SFDP features for 8D-8D-8D operation**

than "00b" then it will not work with any bootmodes in 8D-8D-8D mode. Avoid using any 8D-8D-8D bootmodes with that flash device as a result.

i2372 **Boot: ROM doesn't support select multi-plane addressing schemes in Serial NAND boot**

Details:

The ROM bootloader does not support certain multi-plane Serial SPI NAND flash memories that require the read from cache/buffer command to comprehend changing the cache/buffer/plane number to access the correct data.

Workaround(s):

Carefully review the addressing requirements of a candidate flash memory for references to a special bit for selecting a plane/buffer/cache in the read from cache/buffer command. Do not use memories that have such a requirement.

i2383***OSPI: 2-byte address is not supported in PHY DDR mode***

Details:

When the OSPI controller is configured for 2-byte addressing in PHY DDR Mode, an internal state machine mis-compares the number of address bytes transmitted to a value of 1 (instead of 2). This results in a state machine lockup in the address phase, rendering PHY DDR mode non-operable.

This issue does not occur when using any Tap mode or PHY SDR mode. This issue also doesn't occur when using 4 byte addressing in PHY DDR mode.

Workaround(s):

For compatible OSPI memories that have programmable address byte settings, set the amount of address bytes required from 2 to 4 on the flash. This may involve sending a specific command to change address bytes and/or writing a configuration register on the flash. Once done, update the amount of address bytes sent in the controller settings from 2 to 4.

For compatible OSPI memories that only support 2-byte addressing and cannot be re-programmed, PHY DDR mode will not be compatible with that memory. Alternative modes include:

- PHY SDR mode
- TAP (no-PHY) DDR mode
- TAP (no-PHY) SDR mode

i2399***C7x: CPU NLC Module Not Clearing State on Interrupt***

Details:

Data corruption will occur when:

1. An application is running that involves task switching. In this case there are at least 2 tasks that may use NLC.
2. There is a NLCINIT issued that would be followed by a TICK when an interrupt comes in for Task A. This action ends up setting some internal state in the NLC module that says we need to reload the ILCNT_INIT value to ILCNT on the next TICK since the forwarded case it computed was flushed. This state is not being properly cleared when the interrupt is taken.
3. The ISR performs a task switch to Task B, which is also running NLC code. The NLC code being returned to needs to be in-progress and have a different ILCNT_INIT value than the NLC loop in the original task.
4. After returning from the ISR, the next TICK will end up setting ILCNT to the wrong value (ILCNT_INIT - 2) due to the corrupted state.

At this point the ILCNT is corrupted and the NLC loop will execute the wrong number of iterations, leading to data corruption.

Workaround(s):

Issue a NLCINIT (parameters don't matter and there's no need for TICK's/BNL afterwards) in ISR's as part of the context saving. There is no performance impact due to the work-around.

i2401***CPSW: Host Timestamps Cause CPSW Port to Lock up***

Details:

The CPSW offers two mechanisms for communicating packet ingress timestamp information to the host.

The first mechanism is via the CPTS Event FIFO which records timestamps when triggered by certain events. One such event is the reception of an Ethernet packet with

i2401 (continued)***CPSW: Host Timestamps Cause CPSW Port to Lock up***

a specified EtherType field. Most commonly this is used to capture ingress timestamps for PTP packets. With this mechanism the host must read the timestamp (from the CPTS FIFO) separately from the packet payload which is delivered via DMA. This mode is supported and is not affected by this errata.

The second mechanism is to enable receive timestamps for all packets, not just PTP packets. With this mechanism the timestamp is delivered alongside the packet payload via DMA. This second mechanism is the subject of this errata.

When the CPTS host timestamp is enabled, every packet to the internal CPSW port FIFO requires a timestamp from the CPTS. When the packet preamble is corrupted due to EMI or any other corruption mechanism a timestamp request may not be sent to the CPTS. In this case the CPTS will not produce the timestamp which causes a lockup condition in the CPSW port FIFO. When the CPTS host timestamp is disabled by clearing the `tstamp_en` bit in the `CPTS_CONTROL` register the lockup condition is prevented from occurring.

Workaround(s):

Ethernet to host timestamps must be disabled.

CPTS Event FIFO timestamping can be used instead of CPTS host timestamps.

i2407***RESET: MCU_RESETSTATz unreliable when MCU_RESETz is asserted low*****Details:**

`MCU_RESETSTATz` goes high periodically for a short duration and then low again while `MCU_RESETz` is still asserted low. This issue is seen only when `MCU_RESETz` is asserted low for greater than 100us. The device remains in reset while `MCU_RESETz` is low; the advisory only applies to the signal `MCU_RESETSTATz`.

Workaround(s):

Any one of the following could be used as a workaround for this advisory

- Do not use `MCU_RESETz` in a functional system. `MCU_RESETz` can still be used for debug, realizing the errata limitation.
- Limit the maximum low duration of `MCU_RESETz` to less than 100us.
- Use Main Domain `RESETSTATz` instead of `MCU_RESETSTATz`. `MCU_RESETz` also causes a Main reset, so Main Domain `RESETSTATz` could be used for device reset observation. Consult the datasheet for `RESETSTATz` timing specifications.
- For new designs, the circuits which produce Main Domain reset and MCU Domain reset should be combined with an AND gate as an input to `RESETz`. Also connect MCU Domain reset circuit to the `MCU_RESETz` input. This will provide full functionality of MCU warm reset using `MCU_RESETz` and `MCU_RESETSTATz` to indicate status of MCU domain reset. `RESETz` will be triggered on either a MAIN domain reset or MCU domain reset by using the AND gate.

i2409***USB: USB2 PHY locks up due to short suspend*****Details:**

The USB 2.0 PHY may hang in response to a USB wake-up event that occurs within 3 microseconds of the USB controller entering suspend. This PHY hang can only be recovered via a power cycle as warm reset is ineffectual.

Workaround(s):

Note: this workaround is only applicable if USB is not the primary boot mode. If USB is the primary boot mode, no workaround is available.

i2409 (continued) *USB: USB2 PHY locks up due to short suspend*

In order to prevent this issue from occurring, a specific order of operations must be observed during the USB controller initialization process:

For USB 2.0 Controller:

1. Remove USB controller reset via the LPSC.
2. Set PLL_REG12.pll_ldo_ref_en field (bit 5) in PHY2 region to '1'.
3. Set PLL_REG12.pll_ldo_ref_en_en field (bit 4) in PHY2 region to '1'.
4. Proceed with normal USB controller initialization.

For USB3.0 Controller

1. Remove USB controller reset via the LPSC.
2. Set USB controller suspend_residency_enable field in SUSP_CTRL to '1'.
3. Proceed with normal USB controller initialization

i2410 *Boot: ROM may fail to boot due to i2409*

Details:

Due to i2409, the ROM may fail to boot in USB boot mode after a warm reset. If the USB 2.0 PHY locks up, the ROM does not implement any of the workarounds listed in i2409, and thus the ROM will hang and fail to boot.

Workaround(s):

The advisory described in i2409 should be avoided by implementing one of the workarounds described in the advisory in software.

i2419 *Boot: When disabling deskew calibration, ROM does not check if deskew calibration was enabled*

Details:

If PLL Deskew calibration is being disabled, the ROM driver code intends to check if deskew calibration is enabled and if lock has failed. However the current code has an assignment in an if condition. As a result, it does not check if deskew calibration is enabled before clearing the config bit. There is no functional issue.

Workaround(s):

None

i2424 *PLL: PLL Programming Sequence May Introduce PLL Instability*

Details:

PLL programming sequence has been changed to ensure that, if used, all calibration fields are configured prior to enabling the PLL calibration. In addition to the change to the control of the calibration logic, other changes are implemented so that PLL parameters are unchanged while the PLL is enabled.

When in integer mode, the software enables the PLL calibration feature on calibration-capable PLLs. The previous software adjusted calibration modes after CAL_LOCK was asserted. These writes have been observed to cause a loss of PLL lock on some devices. Additionally, even on susceptible devices, the loss of lock is intermittent, but when it

i2424 (continued) *PLL: PLL Programming Sequence May Introduce PLL Instability*

occurs, dependent circuitry runs at an incorrect frequency; this wrong frequency can show up as slow algorithm execution or communication failures.

Limit on the impact: The calibration logic cannot be used when the PLL is in fractional mode. Therefore, PLLs that are programmed to use fractional mode should not see a failure related to the calibration programming. Nevertheless, because of the change to the full PLL sequence, the new software is recommended for all users.

Workaround(s): Do not use `clk_pll_16fft_cal_option4()` in SYSFW. Ensure to use updated PLL programming sequences in SDK v10.0 or later when performing any PLL configuration change.

i2431 *BCDMA: RX Channel can lockup in certain scenarios*

Details: BCDMA RX chan Teardown can lockup channel and cannot be used for subsequent transfers if none of the TRs have EOP flag set in configuration specific flags field. Subsequently when channel is re-enabled, transfer would not complete and will terminate with various errors in TR response.

Workaround(s):

- a) When receiving data from a PSIL/PDMA peripheral, EOP flag needs to be set in the each TR's configuration specific flag field and PDMA's 1 X-Y FIFO Mode Static TR "Z" parameter should be set to non zero value in order for channel teardown to function properly and cleanup the internal state memory. Otherwise it leads to channel lockups on subsequent runs. The PDMA Z count should also match the TR size, so that PDMA delineates each transfer as an individual packet. This is especially problematic in cases like where TRPD has infinite reload count set to perform cyclic transfer using a single set of TRs in streaming mode, in which case each TR could potentially be the last one.
- b) If the usecase doesn't allow for PDMA Z count to be set in advance or packet EOP cannot be set then alternate is to use PKTDMA in single buffer mode instead of BCDMA.

i2436 *BCDMA: BCDMA RX_IGNORE_LONG setting in RX CHAN CFG register doesn't work*

Details: RX_IGNORE_LONG flag in RXCHAN CFG register of BCDMA gets ignored and BCDMA reports errors in TR response when remote endpoints don't send EOP to match TR boundary.

Workaround(s): RX_IGNORE_LONG is unusable, so remote endpoint such as PDMA should close packet by sending EOP to match TR boundary (PDMA X*Y*Z should match TR ICNT0*ICNT1*ICNT2*ICNT3)

If infinite stream is desired (PDMA Z=0) then switch to PKTDMA and use Single Buffer Mode

i2457 *Boot: Missing data in UART transfer causes boot failures*

Details: The ROM fix implemented to workaround a previous errata causes a race condition which leads to missing in-flight data. This increases the chance of causing xmodem

i2457 (continued) **Boot: Missing data in UART transfer causes boot failures**

NAK. Current xmodem implementation would cancel transfer after receiving more than 10 NAK. This causes image transfer to fail and therefore a boot failure.

Note

Silicon device revisions which are not affected by this advisory must set BOOTMODE7=0 (when UART is primary boot mode) or BOOTMODE13=0 (when UART is backup boot mode) in order to enable the ROM code that fixes this advisory. See latest version of the device specific TRM for more information on boot mode signals.

Workaround(s):

Build a special version of the xmodem transfer tool 'sx' to insert an inter-character delay of 50ms. This will reduce the throughput accordingly.

i2478 **MMCS0: HS400 Mode not supported**

Details: HS400 Mode is not supported on MMCS0 due to bus timing limitations.

Workaround(s): Use HS200 Mode instead.

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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from March 31, 2024 to April 30, 2025 (from Revision * (March 2024) to Revision A (April 2025))

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