

# LM82 Remote Diode and Local Digital Temperature Sensor with Two-Wire Interface

Check for Samples: [LM82](#)

## FEATURES

- Accurately Senses Die Temperature of Remote ICs, or Diode Junctions
- On-board Local Temperature Sensing
- SMBus and I<sup>2</sup>C Compatible Interface, Supports SMBus 1.1 TIMEOUT
- Two Interrupt Outputs:  $\overline{\text{INT}}$  and  $\overline{\text{T\_CRIT\_A}}$
- Register Readback Capability
- 7 bit Plus Sign Temperature Data Format, 1°C Resolution
- 2 Address Select Pins Allow Connection of 9 LM82s on a Single Bus

## APPLICATIONS

- System Thermal Management
- Computers
- Electronic Test Equipment
- Office Electronics
- HVAC

## KEY SPECIFICATIONS

- Supply Voltage: 3.0 to 3.6V
- Supply Current: 0.8mA (max)
- Local Temp Accuracy (includes quantization error):
  - 0 to +85 ±3.0°C (max)
- Remote Diode Temp Accuracy (includes quantization error):
  - +25°C to +100°C ±3°C (max)
  - 0°C to +125°C ±4°C (max)

## DESCRIPTION

The LM82 is a digital temperature sensor with a 2 wire serial interface that senses the voltage and thus the temperature of a remote diode using a Delta-Sigma analog-to-digital converter with a digital over-temperature detector. The LM82 accurately senses its own temperature as well as the temperature of external devices, such as Pentium II Processors or diode connected 2N3904s. The temperature of any ASIC can be detected using the LM82 as long as a dedicated diode (semiconductor junction) is available on the die. Using the SMBus interface a host can access the LM82's registers at any time. Activation of a  $\overline{\text{T\_CRIT\_A}}$  output occurs when any temperature is greater than a programmable comparator limit,  $\overline{\text{T\_CRIT}}$ . Activation of an  $\overline{\text{INT}}$  output occurs when any temperature is greater than its corresponding programmable comparator HIGH limit.

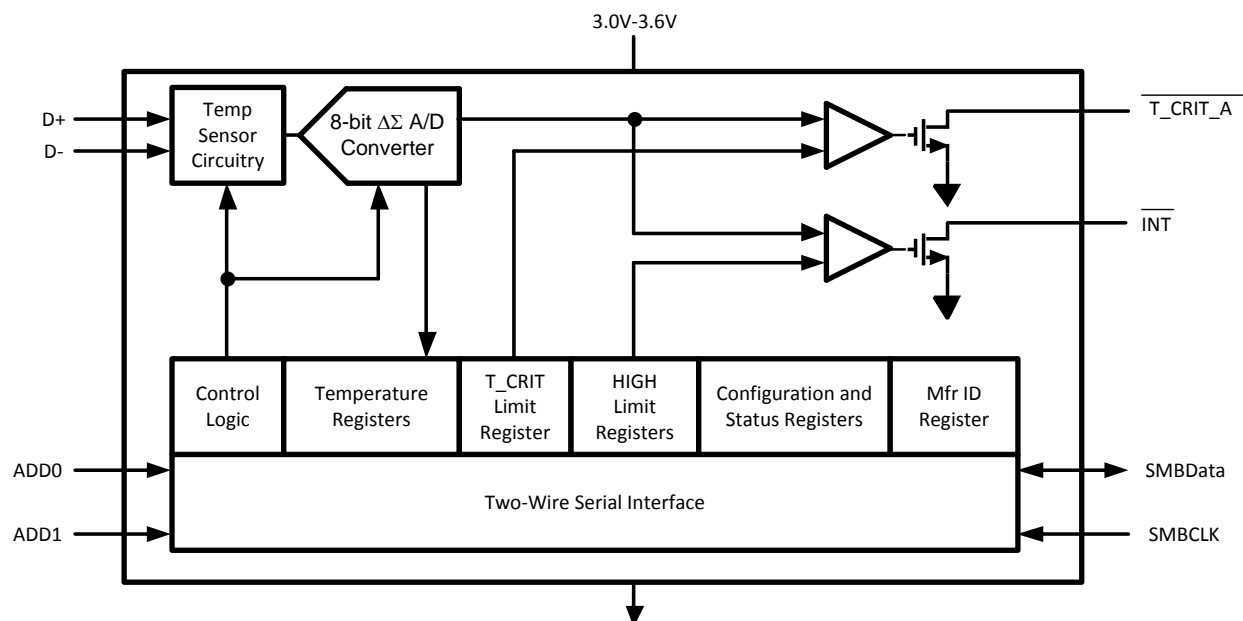
The host can program as well as read back the state of the  $\overline{\text{T\_CRIT}}$  register and the 2  $\overline{\text{T\_HIGH}}$  registers. Three state logic inputs allow two pins (ADD0, ADD1) to select up to 9 SMBus address locations for the LM82. The sensor powers up with default thresholds of 127°C for  $\overline{\text{T\_CRIT}}$  and all  $\overline{\text{T\_HIGH}}$ s. The LM82 is pin for pin and register compatible with the LM84, Maxim MAX1617 and Analog Devices ADM1021.



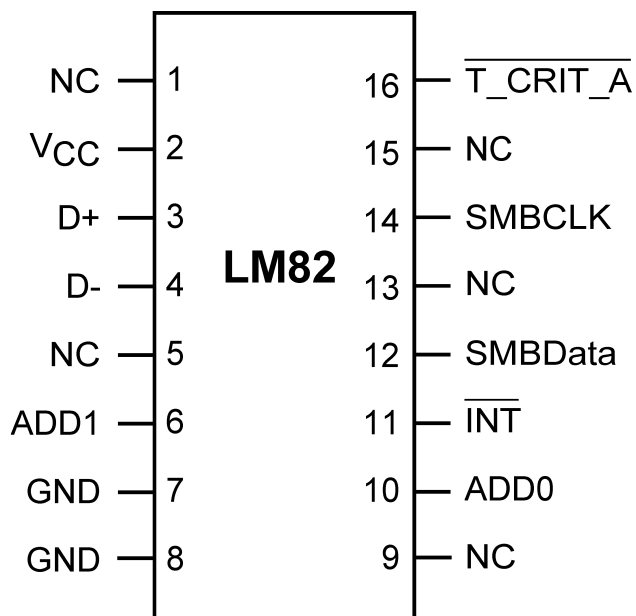
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## Simplified Block Diagram

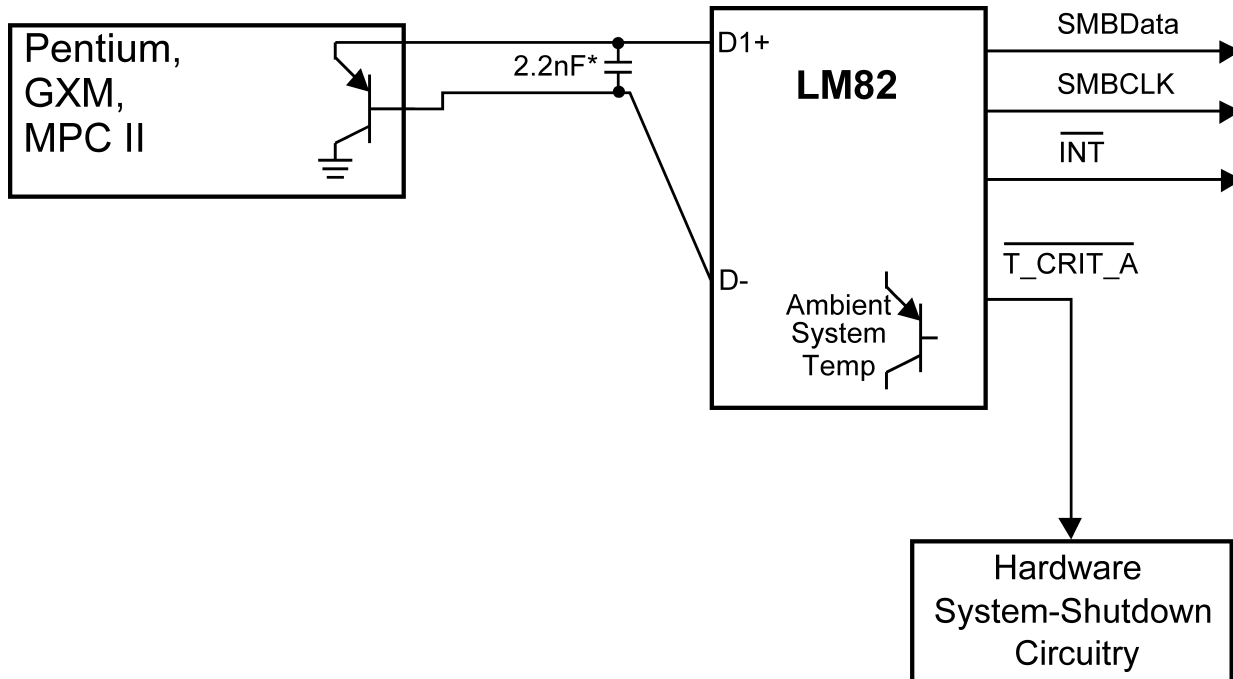


## Connection Diagram



**Figure 1. SSOP-TOP VIEW**  
See DBQ Package

## Typical Application



\*Note: 2.2nF Capacitors must be placed as close as possible to D+ and D- pins of the LM82.

### PIN DESCRIPTIONS

| Label           | Pin #     | Function  | Typical Connection   |
|-----------------|-----------|---|--|
| NC              | 1, 5      | floating, unconnected   | Left floating. PC board traces may be routed through the pads for these pins. No restrictions applied.   |
| V <sub>CC</sub> | 2         | Positive Supply Voltage Input   | DC Voltage from 3.0 V to 3.6 V   |
| D+              | 3         | Diode Current Source  | To Diode Anode. Connected to remote discrete diode junction or to the diode junction on a remote IC whose die temperature is being sensed. When not used they should be left floating.   |
| D-              | 4         | Diode Return Current Sink   | To Diode Cathode. Must float when not used.  |
| ADD0–ADD1       | 10, 6     | User-Set SMBus (I <sup>2</sup> C) Address Inputs                            | Ground (Low, "0"), V <sub>CC</sub> (High, "1") or open ("TRI-LEVEL")   |
| GND             | 7, 8      | Power Supply Ground   | Ground   |
| NC              | 9, 13, 15 | Manufacturing test pins.  | Left floating. PC board traces may be routed through the pads for these pins, although the components that drive these traces should share the same supply as the LM82 so that the Absolute Maximum Rating, Voltage at Any Pin, is not violated. |
| INT             | 11        | Interrupt Output, open-drain  | Pull Up Resistor, Controller Interrupt or Alert Line   |
| SMBData         | 12        | SMBus (I <sup>2</sup> C) Serial Bi-Directional Data Line, open-drain output | From and to Controller, Pull-Up Resistor   |
| SMBCLK          | 14        | SMBus (I <sup>2</sup> C) Clock Input  | From Controller, Pull-Up Resistor  |
| T_CRIT_A        | 16        | Critical Temperature Alarm, open-drain output                               | Pull Up Resistor, Controller Interrupt Line or System Shutdown   |



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## Absolute Maximum Ratings <sup>(1)</sup>

|   |                          |                               |
|---|--------------------------|-------------------------------|
| Supply Voltage  |                          | -0.3 V to 6.0 V               |
| Voltage at SMBData, SMBCLK, $\overline{T\_CRIT\_A}$ & $\overline{INT}$ pins |                          | -0.5V to 6V                   |
| Voltage at Other Pins   |                          | -0.3 V to ( $V_{CC} + 0.3$ V) |
| D- Input Current  |                          | ±1 mA                         |
| Input Current at All Other Pins <sup>(2)</sup>                              |                          | 5 mA                          |
| Package Input Current <sup>(2)</sup>  |                          | 20 mA                         |
| SMBData, $\overline{T\_CRIT\_A}$ , $\overline{INT}$ Output Sink Current     |                          | 10 mA                         |
| Storage Temperature   |                          | -65°C to +150°C               |
| Soldering Information, Lead Temperature                                     |                          |                               |
| SSOP Package <sup>(3)</sup>   | Vapor Phase (60 seconds) | 215°C                         |
|   | Infrared (15 seconds)    | 220°C                         |
| ESD Susceptibility <sup>(4)</sup>   | Human Body Model         | 2000 V                        |
|   | Machine Model            | 250 V                         |

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. DC and AC electrical specifications do not apply when operating the device beyond its rated operating conditions.
- (2) When the input voltage (V<sub>I</sub>) at any pin exceeds the power supplies (V<sub>I</sub> < GND or V<sub>I</sub> > V<sub>CC</sub>), the current at that pin should be limited to 5 mA. The 20 mA maximum package input current rating limits the number of pins that can safely exceed the power supplies with an input current of 5 mA to four. Parasitic components and or ESD protection circuitry are shown in the figure below for the LM82's pins. The nominal breakdown voltage of the zener D3 is 6.5 V. Care should be taken not to forward bias the parasitic diode, D1, present on pins: D+, D-, ADD1 and ADD0. Doing so by more than 50 mV may corrupt a temperature or voltage measurement.
- (3) See the section titled "Surface Mount" found in a current Texas Instruments Linear Data Book for other methods of soldering surface mount devices.
- (4) Human body model, 100 pF discharged through a 1.5 kΩ resistor. Machine model, 200 pF discharged directly into each pin.

## Operating Ratings

|   |                                      |
|---|--------------------------------------|
| Specified Temperature Range             | T <sub>MIN</sub> to T <sub>MAX</sub> |
| LM82                                    | -40°C to +125°C                      |
| Supply Voltage Range (V <sub>CC</sub> ) | +3.0V to +3.6V                       |

## Temperature-to-Digital Converter Characteristics

Unless otherwise noted, these specifications apply for V<sub>CC</sub>=+3.0 Vdc to 3.6 Vdc. **Boldface limits apply for T<sub>A</sub> = T<sub>J</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>**; all other limits T<sub>A</sub>= T<sub>J</sub>=+25°C, unless otherwise noted.

| Parameter   | Conditions  | Typical <sup>(1)</sup> | Limits <sup>(2)</sup> | Units (Limit) |
|---|---|------------------------|-----------------------|---------------|
| Temperature Error using Local Diode <sup>(3)</sup>  | T <sub>A</sub> = 0 °C to +85°C, V <sub>CC</sub> =+3.3V    | ±1                     | <b>±3</b>             | °C (max)      |
|   | T <sub>A</sub> = -40 °C to +125°C, V <sub>CC</sub> =+3.3V |                        | <b>±4</b>             | °C (max)      |
| Temperature Error using Remote Diode <sup>(3)</sup> | T <sub>A</sub> = +60 °C to +100°C, V <sub>CC</sub> =+3.3V |                        | <b>±3</b>             | °C (max)      |
|   | T <sub>A</sub> = 0 °C to +100°C, V <sub>CC</sub> =+3.3V   |                        | <b>±3</b>             | °C (max)      |
|   | T <sub>A</sub> = 0 °C to +125°C, V <sub>CC</sub> =+3.3V   |                        | <b>±4</b>             | °C (max)      |
| Resolution  |   | 8                      |                       | Bits          |
|   |   | 1                      |                       | °C            |

- (1) Typicals are at T<sub>A</sub> = 25°C and represent most likely parametric norm.
- (2) Limits are ensured to AOQL (Average Outgoing Quality Level).
- (3) The Temperature Error will vary less than ±1.0°C for a variation in V<sub>CC</sub> of 3V to 3.6V from the nominal of 3.3V.

## Temperature-to-Digital Converter Characteristics (continued)

Unless otherwise noted, these specifications apply for  $V_{CC}=+3.0$  Vdc to 3.6 Vdc. **Boldface limits apply for  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$** ; all other limits  $T_A = T_J = +25^{\circ}\text{C}$ , unless otherwise noted.

| Parameter  | Conditions                             | Typical <sup>(1)</sup> | Limits <sup>(2)</sup>    | Units (Limit)      |
|--|--|------------------------|--------------------------|--------------------|
| Conversion Time of All Temperatures                                    | <sup>(4)</sup>                         | 460                    | <b>600</b>               | ms (max)           |
| Quiescent Current <sup>(5)</sup>                                       | SMBus (I <sup>2</sup> C) Inactive      | 0.500                  | <b>0.80</b>              | mA (max)           |
| D– Source Voltage  |  | 0.7                    |                          | V                  |
| Diode Source Current   | (D+ – D–)=+ 0.65V; high level          |                        | <b>125</b>               | μA (max)           |
|  |  |                        | <b>60</b>                | μA (min)           |
|  | Low level                              |                        | <b>15</b>                | μA (max)           |
|  |  |                        | <b>5</b>                 | μA (min)           |
| $\overline{T\_CRIT\_A}$ and $\overline{INT}$ Output Saturation Voltage | I <sub>OUT</sub> = 3.0 mA              |                        | <b>0.4</b>               | V (max)            |
| Power-On Reset Threshold   | On V <sub>CC</sub> input, falling edge |                        | <b>2.3</b><br><b>1.8</b> | V (max)<br>V (min) |
| Local and Remote T_CRIT and HIGH Default Temperature settings          | See <sup>(6)</sup>                     | +127                   |                          | °C                 |

(4) This specification is provided only to indicate how often temperature data is updated. The LM82 can be read at any time without regard to conversion state (and will yield last conversion result).

(5) Quiescent current will not increase substantially with an active SMBus.

(6) Default values set at power up.

## Logic Electrical Characteristics- DIGITAL DC CHARACTERISTICS

Unless otherwise noted, these specifications apply for  $V_{CC}=+3.0$  to 3.6 Vdc. **Boldface limits apply for  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$** ; all other limits  $T_A = T_J = +25^{\circ}\text{C}$ , unless otherwise noted.

| Symbol                     | Parameter                                   | Conditions                                       | Typical <sup>(1)</sup> | Limits <sup>(2)</sup>    | Units (Limit) |
|----------------------------|---|--|------------------------|--------------------------|---------------|
| <b>SMBData, SMBCLK</b>     |   |  |                        |                          |               |
| V <sub>IN(1)</sub>         | Logical “1” Input Voltage                   |  |                        | <b>2.1</b>               | V (min)       |
| V <sub>IN(0)</sub>         | Logical “0” Input Voltage                   |  |                        | <b>0.8</b>               | V (max)       |
| V <sub>IN(HYST)</sub>      | SMBData and SMBCLK Digital Input Hysteresis |  | 300                    |                          | mV            |
| I <sub>IN(1)</sub>         | Logical “1” Input Current                   | V <sub>IN</sub> = V <sub>CC</sub>                | 0.005                  | <b>1.5</b>               | μA (max)      |
| I <sub>IN(0)</sub>         | Logical “0” Input Current                   | V <sub>IN</sub> = 0 V                            | –0.005                 | <b>1.5</b>               | μA (max)      |
| <b>ADD0, ADD1</b>          |   |  |                        |                          |               |
| V <sub>IN(1)</sub>         | Logical “1” Input Voltage                   |  | V <sub>CC</sub>        | <b>1.5</b>               | V (min)       |
| V <sub>IN(0)</sub>         | Logical “0” Input Voltage                   |  | GND                    | <b>0.6</b>               | V (max)       |
| I <sub>IN(1)</sub>         | Logical “1” Input Current                   | V <sub>IN</sub> = V <sub>CC</sub>                |                        | <b>2</b>                 | μA (max)      |
| I <sub>IN(0)</sub>         | Logical “0” Input Current                   | V <sub>IN</sub> = 0 V                            |                        | <b>–2</b>                | μA (max)      |
| <b>ALL DIGITAL INPUTS</b>  |   |  |                        |                          |               |
| C <sub>IN</sub>            | Input Capacitance                           |  | 20                     |                          | pF            |
| <b>ALL DIGITAL OUTPUTS</b> |   |  |                        |                          |               |
| I <sub>OH</sub>            | High Level Output Current                   | V <sub>OH</sub> = V <sub>CC</sub>                |                        | <b>100</b>               | μA (max)      |
| V <sub>OL</sub>            | SMBus Low Level Output Voltage              | I <sub>OL</sub> = 3 mA<br>I <sub>OL</sub> = 6 mA |                        | <b>0.4</b><br><b>0.6</b> | V (max)       |

(1) Typicals are at  $T_A = 25^{\circ}\text{C}$  and represent most likely parametric norm.

(2) Limits are ensured to AOQL (Average Outgoing Quality Level).

## Logic Electrical Characteristics- SMBus DIGITAL SWITCHING CHARACTERISTICS

Unless otherwise noted, these specifications apply for  $V_{CC}=+3.0$  Vdc to  $+3.6$  Vdc,  $C_L$  (load capacitance) on output lines = 80 pF. **Boldface limits apply for  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$** ; all other limits  $T_A = T_J = +25^\circ\text{C}$ , unless otherwise noted.

The switching characteristics of the LM82 fully meet or exceed the published specifications of the SMBus or I<sup>2</sup>C bus. The following parameters are the timing relationships between SMBCLK and SMBData signals related to the LM82. They are not the I<sup>2</sup>C or SMBus bus specifications.

| Symbol            | Parameter  | Conditions                      | Typical <sup>(1)</sup> | Limits <sup>(2)</sup>    | Units (Limit)                   |
|-------------------|--|---------------------------------|------------------------|--------------------------|---------------------------------|
| $f_{SMB}$         | SMBus Clock Frequency  |                                 |                        | <b>100</b><br><b>10</b>  | kHz (max)<br>kHz (min)          |
| $t_{LOW}$         | SMBus Clock Low Time   | 10 % to 10 %                    |                        | <b>1.3</b><br><b>25</b>  | $\mu\text{s}$ (min)<br>ms (max) |
| $t_{LOWMEXT}$     | Cumulative Clock Low Extend Time   |                                 |                        | <b>10</b>                | ms (max)                        |
| $t_{HIGH}$        | SMBus Clock High Time  | 90 % to 90%                     |                        | <b>0.6</b>               | $\mu\text{s}$ (min)             |
| $t_{R,SMB}$       | SMBus Rise Time  | 10% to 90%                      | 1                      |                          | $\mu\text{s}$ (max)             |
| $t_{F,SMB}$       | SMBus Fall Time  | 90% to 10%                      | 0.3                    |                          | ns (max)                        |
| $t_{OF}$          | Output Fall Time   | $C_L = 400$ pF,<br>$I_O = 3$ mA |                        | <b>250</b>               | ns (max)                        |
| $t_{TIMEOUT}$     | SMBData and SMBCLK Time Low for Reset of Serial Interface <sup>(3)</sup> |                                 |                        | <b>25</b><br><b>40</b>   | ms (min)<br>ms (max)            |
| $t_1$             | SMBCLK (Clock) Period  |                                 |                        | <b>10</b>                | $\mu\text{s}$ (min)             |
| $t_2, t_{SU,DAT}$ | Data In Setup Time to SMBCLK High  |                                 |                        | <b>100</b>               | ns (min)                        |
| $t_3, t_{HD,DAT}$ | Data Out Stable after SMBCLK Low   |                                 |                        | <b>300</b><br><b>TBD</b> | ns (min)<br>ns (max)            |
| $t_4, t_{HD,STA}$ | SMBData Low Setup Time to SMBCLK Low                                     |                                 |                        | <b>100</b>               | ns (min)                        |
| $t_5, t_{SU,STO}$ | SMBData High Delay Time after SMBCLK High (Stop Condition Setup)         |                                 |                        | <b>100</b>               | ns (min)                        |
| $t_6, t_{SU,STA}$ | SMBus Start-Condition Setup Time   |                                 |                        | <b>0.6</b>               | $\mu\text{s}$ (min)             |
| $t_{BUF}$         | SMBus Free Time  |                                 |                        | <b>1.3</b>               | $\mu\text{s}$ (min)             |

(1) Typicals are at  $T_A = 25^\circ\text{C}$  and represent most likely parametric norm.

(2) Limits are ensured to AOQL (Average Outgoing Quality Level).

(3) Holding the SMBData and/or SMBCLK lines Low for a time interval greater than  $t_{TIMEOUT}$  will cause the LM82 to reset SMBData and SMBCLK to the IDLE state of an SMBus communication (SMBCLK and SMBData set High).

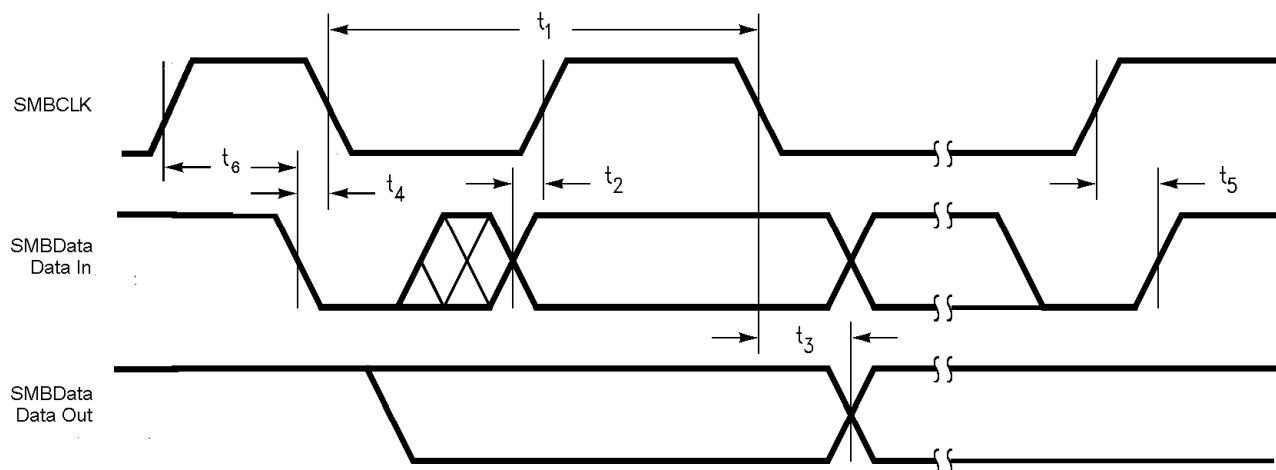
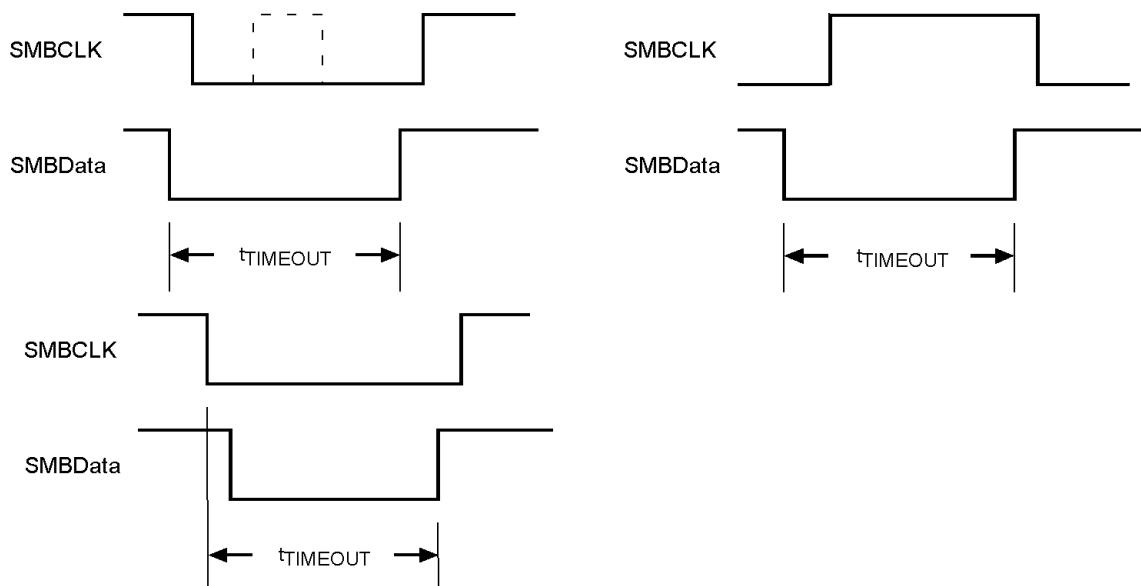


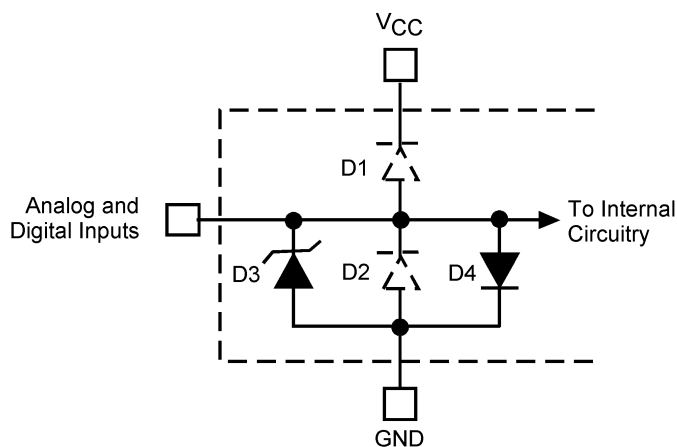
Figure 2. SMBus Communication



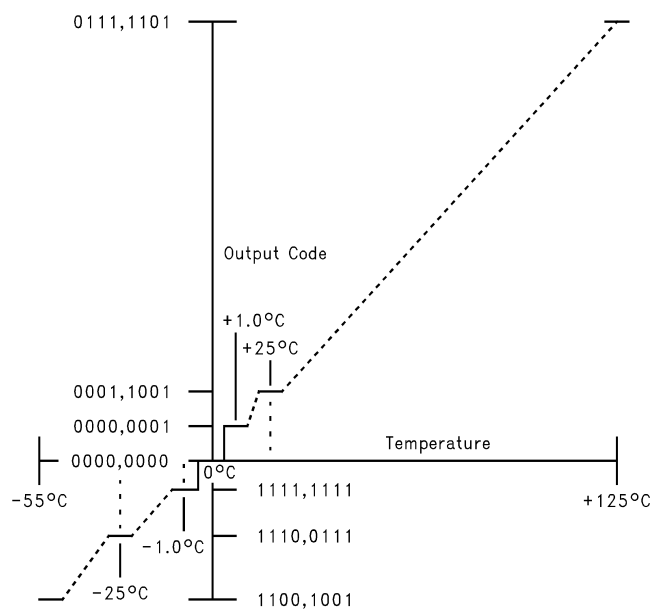
**Figure 3. SMBus TIMEOUT**

| Pin Name        | D1 | D2 | D3               | D4 | Pin Name                                   | D1 | D2 | D3 | D4 |
|-----------------|----|----|------------------|----|--|----|----|----|----|
| NC (pins 1 & 5) |    |    |                  |    | $\overline{T\_CRIT\_A}$ & $\overline{INT}$ |    | x  |    |    |
| $V_{CC}$        |    |    | x <sup>(1)</sup> |    | SMBData                                    |    | x  | x  |    |
| D+              | x  | x  | x                |    | NC (pins 9 & 15)                           | x  | x  | x  |    |
| D-              | x  | x  | x                | x  | SMBCLK                                     |    | x  | x  |    |
| ADD0, ADD1      | x  | x  | x                |    | NC (pin 13)                                |    | x  | x  |    |

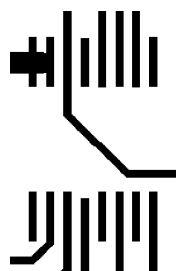
(1) Note: An x indicates that the diode exists.



**Figure 4. ESD Protection Input Structure**



**Figure 5. Temperature-to-Digital Transfer Function (Non-linear scale for clarity)**



**Figure 6. Printed Circuit Board Used for Thermal Resistance Specifications**



## FUNCTIONAL DESCRIPTION

The LM82 temperature sensor incorporates a band-gap type temperature sensor using a Local or Remote diode and an 8-bit ADC (Delta-Sigma Analog-to-Digital Converter). The LM82 is compatible with the serial SMBus and I<sup>2</sup>C two wire interfaces. Digital comparators compare Local (LT) and Remote (RT) temperature readings to user-programmable setpoints (LHS, RHS, and TCS). Activation of the  $\overline{\text{INT}}$  output indicates that a comparison is greater than the limit preset in a HIGH register. The T\_CRIT setpoint (TCS) interacts with all the temperature readings. Activation of the  $\overline{\text{T\_CRIT\_A}}$  output indicates that any or all of the temperature readings have exceed the T\_CRIT setpoint.

## CONVERSION SEQUENCE

The LM82 converts its own temperature as well as a remote diode temperature in the following sequence:

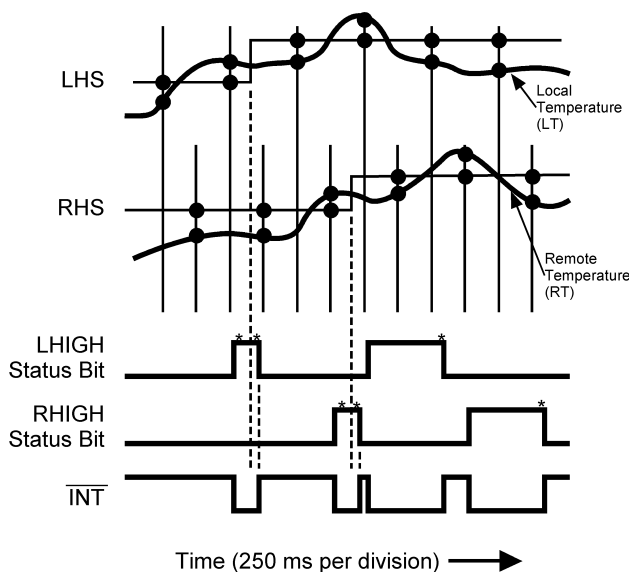
1. Local Temperature (LT)
2. Remote Diode (RT)

This round robin sequence takes approximately 480 ms to complete.

## $\overline{\text{INT}}$ OUTPUT and T\_HIGH LIMITS

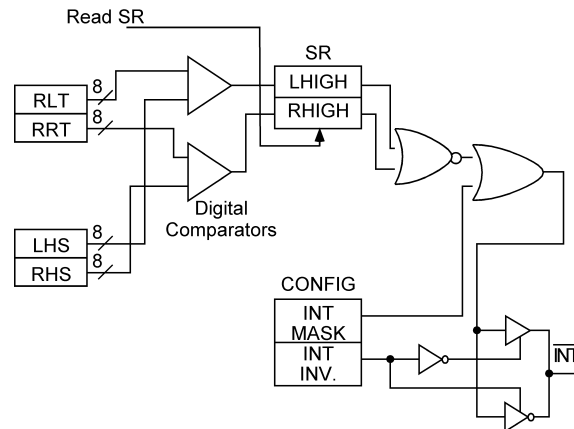
Each temperature reading (LT, and RT) is associated with a T\_HIGH setpoint register (LHS, RHS). At the end of a temperature reading a digital comparison determines whether that reading has exceeded its HIGH setpoint. If the temperature reading is greater than the HIGH setpoint, a bit is set in one of the Status Registers, to indicate which temperature reading, and the  $\overline{\text{INT}}$  output is activated.

Local and remote temperature diodes are sampled in sequence by the A/D converter. The  $\overline{\text{INT}}$  output and the Status Register flags are updated at the completion of a conversion, which occurs approximately 60 ms after a temperature diode is sampled.  $\overline{\text{INT}}$  is deactivated when the Status Register, containing the set bit, is read and a temperature reading is less than or equal to it's corresponding HIGH setpoint, as shown in Figure 7. Figure 8 shows a simplified logic diagram for the  $\overline{\text{INT}}$  output and related circuitry.



\* Note: Status Register Bits are reset by a read of Status Register where bit is located.

**Figure 7.  $\overline{\text{INT}}$  Temperature Response Diagram**



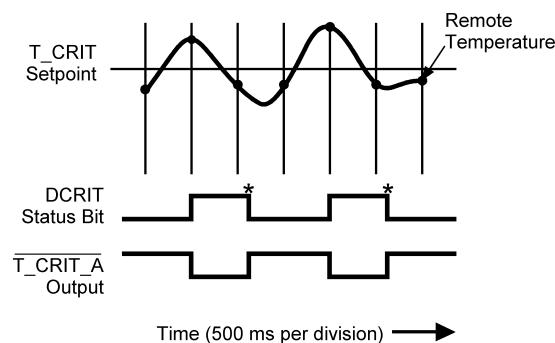
**Figure 8.  $\overline{\text{INT}}$  output related circuitry logic diagram**

The  $\overline{\text{INT}}$  output can be disabled by setting the  $\overline{\text{INT}}$  mask bit, D7, of the configuration register.  $\overline{\text{INT}}$  can be programmed to be active high or low by the state of the  $\overline{\text{INT}}$  inversion bit, D1, in the configuration register. A "0" would program  $\overline{\text{INT}}$  to be active low.  $\overline{\text{INT}}$  is an open-drain output.

### $\overline{\text{T\_CRIT\_A}}$ OUTPUT and $\text{T\_CRIT}$ LIMIT

$\overline{\text{T\_CRIT\_A}}$  is activated when any temperature reading is greater than the limit preset in the critical temperature setpoint register ( $\text{T\_CRIT}$ ), as shown in Figure 9. The Status Registers can be read to determine which event caused the alarm. A bit in the Status Registers is set high to indicate which temperature reading exceeded the  $\text{T\_CRIT}$  setpoint temperature and caused the alarm, see STATUS REGISTER.

Local and remote temperature diodes are sampled in sequence by the A/D converter. The  $\overline{\text{T\_CRIT\_A}}$  output and the Status Register flags are updated at the completion of a conversion.  $\overline{\text{T\_CRIT\_A}}$  and the Status Register flags are reset only after the Status Register is read and if a temperature conversion is below the  $\text{T\_CRIT}$  setpoint, as shown in Figure 9. Figure 10 shows a simplified logic diagram of the  $\overline{\text{T\_CRIT\_A}}$  and related circuitry.



\* Note: Status Register Bits are reset by a read of Status Register where bit is located.

**Figure 9.  $\overline{\text{T\_CRIT\_A}}$  Temperature Response Diagram**

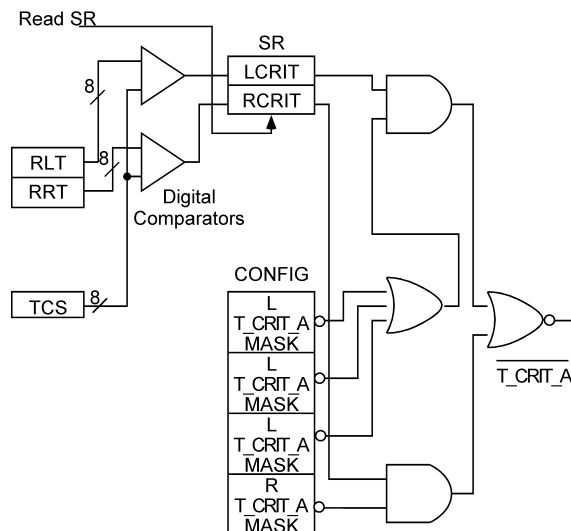


Figure 10.  $\overline{T\_CRIT\_A}$  output related circuitry logic diagram

Located in the Configuration Register are the mask bits for each temperature reading, see [CONFIGURATION REGISTER](#). When a mask bit is set, its corresponding status flag will not propagate to the  $\overline{T\_CRIT\_A}$  output, but will still be set in the Status Registers. Configuration register bits D5 and D3, labeled “Remote  $\overline{T\_CRIT\_A}$  mask” must be set high before the  $\overline{T\_CRIT}$  setpoint is lowered in order for the  $\overline{T\_CRIT\_A}$  output to function properly. Setting all four mask bits or programming the  $\overline{T\_CRIT}$  setpoint to 127°C will disable the  $\overline{T\_CRIT\_A}$  output.

## POWER ON RESET DEFAULT STATES

LM82 always powers up to these known default states:

1. Command Register set to 00h
2. Local Temperature set to 0°C
3. Remote Temperature set to 0°C until the LM82 senses a diode present between the D+ and D- input pins.
4. Status Register set to 00h.
5. Configuration Register set to 00h;  $\overline{INT}$  enabled and all  $\overline{T\_CRIT}$  setpoints enabled to activate  $\overline{T\_CRIT\_A}$ .
6. Local and Remote  $\overline{T\_CRIT}$  set to 127°C

## SMBus INTERFACE

The LM82 operates as a slave on the SMBus, so the SMBCLK line is an input (no clock is generated by the LM82) and the SMBData line is bi-directional. According to SMBus specifications, the LM82 has a 7-bit slave address. Bit 4 (A3) of the slave address is hard wired inside the LM82 to a 1. The remainder of the address bits are controlled by the state of the address select pins ADD1 and ADD0, and are set by connecting these pins to ground for a low, (0), to  $V_{CC}$  for a high, (1), or left floating (TRI-LEVEL).

Therefore, the complete slave address is:

|     |    |    |   |    |    |     |
|-----|----|----|---|----|----|-----|
| A6  | A5 | A4 | 1 | A2 | A1 | A0  |
| MSB |    |    |   |    |    | LSB |

and is selected as follows:

| Address Select Pin State |           | LM82 SMBus Slave Address |
|--------------------------|-----------|--------------------------|
| ADD0                     | ADD1      | A6:A0 binary             |
| 0                        | 0         | 001 1000                 |
| 0                        | TRI-LEVEL | 001 1001                 |

| Address Select Pin State |           | LM82 SMBus Slave Address |
|--------------------------|-----------|--------------------------|
| ADD0                     | ADD1      | A6:A0 binary             |
| 0                        | 1         | 001 1010                 |
| TRI-LEVEL                | 0         | 010 1001                 |
| TRI-LEVEL                | TRI-LEVEL | 010 1010                 |
| TRI-LEVEL                | 1         | 010 1011                 |
| 1                        | 0         | 100 1100                 |
| 1                        | TRI-LEVEL | 100 1101                 |
| 1                        | 1         | 100 1110                 |

The LM82 latches the state of the address select pins during the first read or write on the SMBus. Changing the state of the address select pins after the first read or write to any device on the SMBus will not change the slave address of the LM82.

## TEMPERATURE DATA FORMAT

Temperature data can be read from the Local and Remote Temperature, T\_CRIT, and HIGH setpoint registers; and written to the T\_CRIT and HIGH setpoint registers. Temperature data is represented by an 8-bit, two's complement byte with an LSB (Least Significant Bit) equal to 1°C:

| Temperature | Digital Output |     |
|-------------|----------------|-----|
|             | Binary         | Hex |
| +125°C      | 0111 1101      | 7Dh |
| +25°C       | 0001 1001      | 19h |
| +1°C        | 0000 0001      | 01h |
| 0°C         | 0000 0000      | 00h |
| -1°C        | 1111 1111      | FFh |
| -25°C       | 1110 0111      | E7h |
| -55°C       | 1100 1001      | C9h |

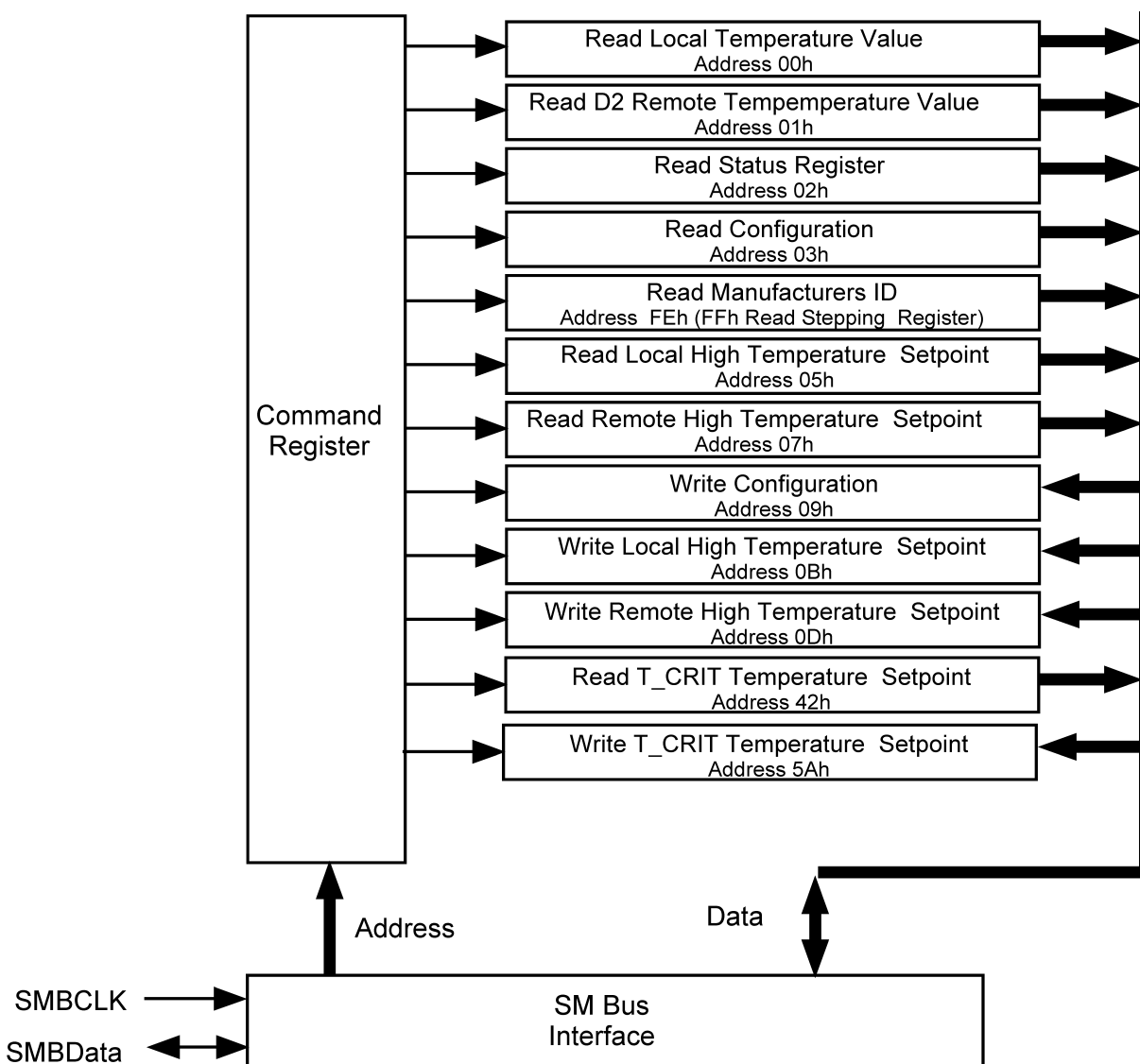
## OPEN-DRAIN OUTPUTS

The SMBData,  $\overline{\text{INT}}$  and  $\overline{\text{T\_CRIT\_A}}$  outputs are open-drain outputs and do not have internal pull-ups. A “high” level will not be observed on these pins until pull-up current is provided from some external source, typically a pull-up resistor. Choice of resistor value depends on many system factors but, in general, the pull-up resistor should be as large as possible. This will minimize any internal temperature reading errors due to internal heating of the LM82. The maximum resistance of the pull up, based on LM82 specification for High Level Output Current, to provide a 2.1V high level, is 30kΩ. Care should be taken in a noisy system because a high impedance pull-up will be more likely to couple noise into the signal line.

## DIODE FAULT DETECTION

Before each external conversion the LM82 goes through an external diode fault detection sequence. If D+ input is shorted to V<sub>CC</sub> or floating then the temperature reading will be +127 °C, and the OPEN bit in the Status Register will be set. If the T\_CRIT setpoint is set to less than +127 °C then the D+ input RTCRIT bit in the Status Register will be set which will activate the  $\overline{\text{T\_CRIT\_A}}$  output, if enabled. If a D+ is shorted to GND or D-, its temperature reading will be 0 °C and its OPEN bit in the Status Register will not be set.

## COMMUNICATING with the LM82



There are 13 data registers in the LM82, selected by the Command Register. At power-up the Command Register is set to "00", the location for the Read Local Temperature Register. The Command Register latches the last location it was set to. Reading the Status Register resets T\_CRIT\_A and INT, so long as a temperature comparison does not signal a fault (see [INT OUTPUT and T\\_HIGH LIMITS](#) and [T\\_CRIT\\_A OUTPUT and T\\_CRIT LIMIT](#)). All other registers are predefined as read only or write only. Read and write registers with the same function contain mirrored data.

A **Write** to the LM82 will always include the address byte and the command byte. A write to any register requires one data byte.

**Reading** the LM82 can take place either of two ways:

1. If the location latched in the Command Register is correct (most of the time it is expected that the Command Register will point to one of the Read Temperature Registers because that will be the data most frequently read from the LM82), then the read can simply consist of an address byte, followed by retrieving the data byte.
2. If the Command Register needs to be set, then an address byte, command byte, repeat start, and another address byte will accomplish a read.

The data byte has the most significant bit first. At the end of a read, the LM82 can accept either Acknowledge or No Acknowledge from the Master (No Acknowledge is typically used as a signal for the slave that the Master has read its last byte).

## SERIAL INTERFACE ERROR RECOVERY

The LM82 SMBus lines will be reset to the SMBus idle state if the SMBData or SMBCLK lines are held low for 40 ms or more ( $t_{\text{TIMEOUT}}$ ). The LM82 may or may not reset the state of the serial interface logic if either of the SMBData or SMBCLK lines are held low between 25 ms and 40 ms. TIMEOUT allows a clean recovery in cases where the master may be reset while the LM82 is transmitting a low bit thus preventing possible bus lock up.

Whenever the LM82 sees the start condition its serial interface will reset to the beginning of the communication, thus the LM82 will expect to see an address byte next. This simplifies recovery when the master is reset while the LM82 is transmitting a high.

## LM82 Registers

### COMMAND REGISTER

Selects which registers will be read from or written to. Data for this register should be transmitted during the Command Byte of the SMBus write communication.

| P7 | P6             | P5 | P4 | P3 | P2 | P1 | P0 |
|----|----------------|----|----|----|----|----|----|
| 0  | Command Select |    |    |    |    |    |    |

P0-P7: Command Select

| Command Select Address | Power On Default State |                 | Register Name | Register Function          |
|------------------------|------------------------|-----------------|---------------|----------------------------|
|                        | <D7:D0> binary         | <D7:D0> decimal |               |                            |
| 00h                    | 0000 0000              | 0               | RLT           | Read Local Temperature     |
| 01h                    | 0000 0000              | 0               | RRT           | Read Remote Temperature    |
| 02h                    | 0000 0000              | 0               | RSR           | Read Status Register       |
| 03h                    | 0000 0000              | 0               | RC            | Read Configuration         |
| 04h                    | 0000 0000              | 0               |               | Reserved                   |
| 05h                    | 0111 1111              | 127             | RLHS          | Read Local HIGH Setpoint   |
| 06h                    |                        |                 |               | Reserved                   |
| 07h                    | 0111 1111              | 127             | RRHS          | Read Remote HIGH Setpoint  |
| 08h                    |                        |                 |               | Reserved                   |
| 09h                    | 0000 0000              |                 | WC            | Write Configuration        |
| 0Ah                    |                        |                 |               | Reserved                   |
| 0Bh                    | 0111 1111              | 127             | WLHS          | Write Local HIGH Setpoint  |
| 0Ch                    |                        |                 |               | Reserved                   |
| 0Dh                    | 0111 1111              | 127             | WRHS          | Write Remote HIGH Setpoint |
| 0Eh-2Fh                |                        |                 |               | Reserved for Future Use    |
| 30h-31h                | 0000 0000              | 0               |               | Reserved                   |
| 32h-34h                |                        |                 |               | Reserved for Future Use    |
| 35h                    | 0000 0000              | 0               |               | Reserved                   |
| 36h-37h                |                        |                 |               | Reserved for Future Use    |
| 38h                    | 0111 1111              | 127             |               | Reserved                   |
| 39h                    |                        |                 |               | Reserved for Future Use    |
| 3Ah                    | 0111 1111              | 127             |               | Reserved                   |
| 3Bh-41h                |                        |                 |               | Reserved for Future Use    |
| 42h                    | 0111 1111              | 127             | RTCS          | Read T_CRIT Setpoint       |
| 43h-4Fh                |                        |                 |               | Reserved for Future Use    |

| Command Select Address | Power On Default State |                 | Register Name | Register Function                  |
|------------------------|------------------------|-----------------|---------------|------------------------------------|
|                        | <D7:D0> binary         | <D7:D0> decimal |               |                                    |
| <P7:P0> hex            |                        |                 |               |                                    |
| 50h                    | 0111 1111              | 127             |               | Reserved                           |
| 51h                    |                        |                 |               | Reserved for Future Use            |
| 52h                    | 0111 1111              | 127             |               | Reserved                           |
| 53h-59h                |                        |                 |               | Reserved for Future Use            |
| 5Ah                    | 0111 1111              | 127             | WTCS          | Write T_CRIT Setpoint              |
| 5Ch-6Fh and F0h-FDh    |                        |                 |               | Reserved for Future Use            |
| FEh                    | 0000 0001              | 1               | RMID          | Read Manufacturers ID              |
| FFh                    | 0000 0011              | 3               | RSR           | Read Stepping or Die Revision Code |

## LOCAL and REMOTE TEMPERATURE REGISTERS (LT, and RT)

**Table 1. LOCAL and REMOTE TEMPERATURE REGISTERS (LT, and RT) (Read Only Address 00h, and 01h):**

| D7  | D6    | D5    | D4    | D3    | D2    | D1    | D0  |
|-----|-------|-------|-------|-------|-------|-------|-----|
| MSB | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | LSB |

D7–D0: Temperature Data. One LSB = 1°C. Two's complement format.

## STATUS REGISTER

**Table 2. STATUS REGISTER (Read Only Address 02h):**

| D7 | D6    | D5 | D4    | D3 | D2   | D1    | D0    |
|----|-------|----|-------|----|------|-------|-------|
| 0  | LHIGH | 0  | RHIGH | 0  | OPEN | RCRIT | LCRIT |

Power up default is with all bits “0” (zero).

D0: LCRIT: When set to a 1 indicates an Local Critical Temperature alarm.

D1: RCRIT: When set to a 1 indicates a Remote Diode Critical Temperature alarm.

D2: D2OPEN: When set to 1 indicates a Remote Diode disconnect.

D4: D2RHIGH: When set to 1 indicates a Remote Diode HIGH Temperature alarm.

D6: LHIGH: When set to 1 indicates a Local HIGH Temperature alarm.

D7, D5, and D3: These bits are always set to 0 and reserved for future use.

## MANUFACTURERS ID AND DIE REVISION (Stepping) REGISTERS

MANUFACTURERS ID AND DIE REVISION (Stepping) REGISTERS (Read Address FEh and FFh) Default value 01h for Manufacturers ID(FEh ).

## CONFIGURATION REGISTER

**Table 3. CONFIGURATION REGISTER (Read Address 03h/Write Address 09h):**

| D7                           | D6 | D5                         | D4                         | D3                         | D2                        | D1                                | D0 |
|------------------------------|----|----------------------------|----------------------------|----------------------------|---------------------------|-----------------------------------|----|
| $\overline{\text{INT}}$ mask | 0  | Remote<br>T_CRIT_A<br>mask | Remote<br>T_CRIT_A<br>mask | Remote<br>T_CRIT_A<br>mask | Local<br>T_CRIT_A<br>mask | $\overline{\text{INT}}$ Inversion | 0  |

Power up default is with all bits “0” (zero).

D7:  $\overline{\text{INT}}$  mask: When set to 1  $\overline{\text{INT}}$  interrupts are masked.

D5: T\_CRIT mask, this bit must be set to a 1 before the T\_CRIT setpoint is lowered below 127 in order for T\_CRIT\_A pin to function properly.

D4: T\_CRIT mask for Remote temperature, when set to 1 a remote temperature reading that exceeds T\_CRIT setpoint will not activate the  $\overline{T\_CRIT\_A}$  pin.

D3: T\_CRIT mask, this bit must be set to a 1 before the T\_CRIT setpoint is lowered below 127 in order for  $\overline{T\_CRIT\_A}$  pin to function properly.

D2: T\_CRIT mask for Local reading, when set to 1 a Local temperature reading that exceeds T\_CRIT setpoint will not activate the  $\overline{T\_CRIT\_A}$  pin.

D1:  $\overline{INT}$  active state inversion. When  $\overline{INT}$  Inversion is set to a 1 the active state of the  $\overline{INT}$  output will be a logical high. A low would then select an active state of a logical low.

D6 and D0: These bits are always set to 0 and reserved for future use. A write of 1 will return a 0 when read.

## LOCAL AND REMOTE HIGH SETPOINT REGISTERS (LHS, RHS)

**Table 4. LOCAL AND REMOTE HIGH SETPOINT REGISTERS (LHS, RHS) (Read Address 05h, 07h/Write Address 0Bh, 0Dh):**

| D7  | D6    | D5    | D4    | D3    | D2    | D1    | D0  |
|-----|-------|-------|-------|-------|-------|-------|-----|
| MSB | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | LSB |

D7–D0: HIGH setpoint temperature data. Power up default is LHIGH = RHIGH = 127°C.

## T\_CRIT REGISTER (TCS)

**Table 5. T\_CRIT REGISTER (TCS) (Read Address 42h/Write Address 5Ah):**

| D7  | D6    | D5    | D4    | D3    | D2    | D1    | D0  |
|-----|-------|-------|-------|-------|-------|-------|-----|
| MSB | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | LSB |

D7–D0: T\_CRIT setpoint temperature data. Power up default is T\_CRIT = 127°C.



## SMBus Timing Diagrams

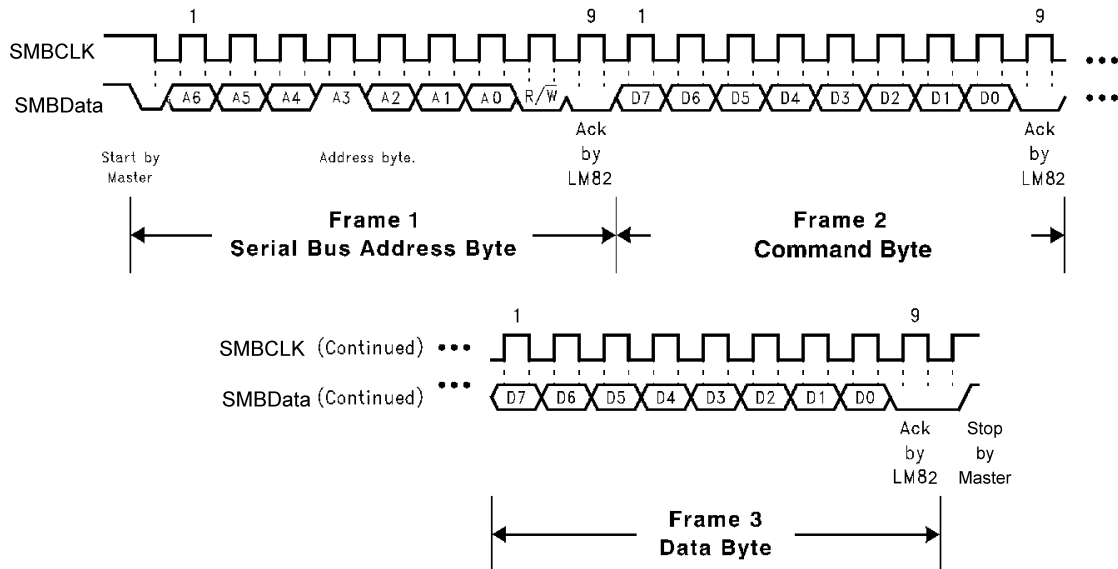


Figure 11. (a) Serial Bus Write to the internal Command Register followed by a the Data Byte

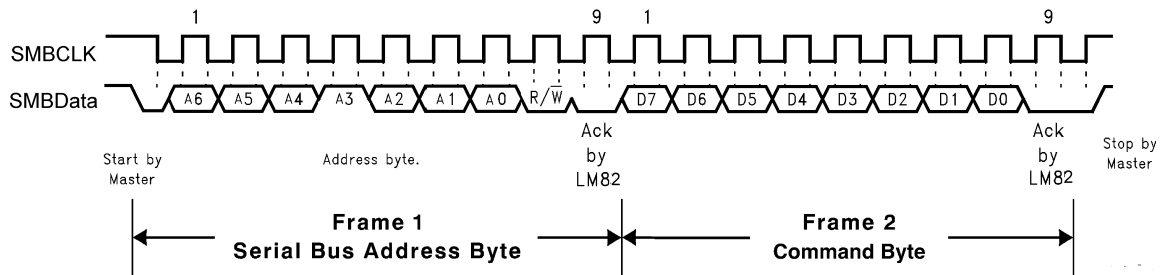


Figure 12. (b) Serial Bus Write to the internal Command Register

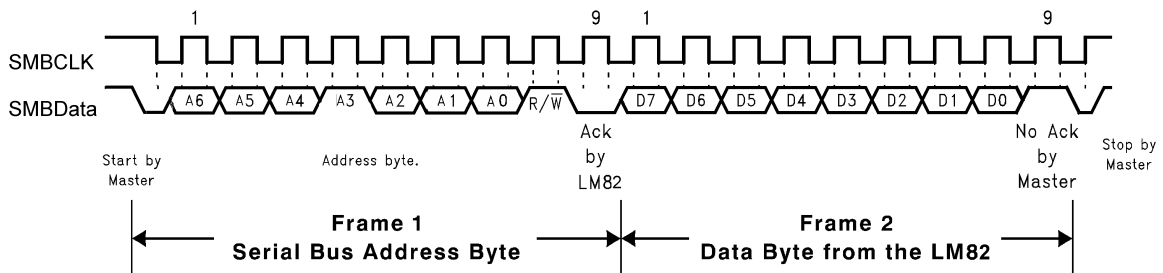
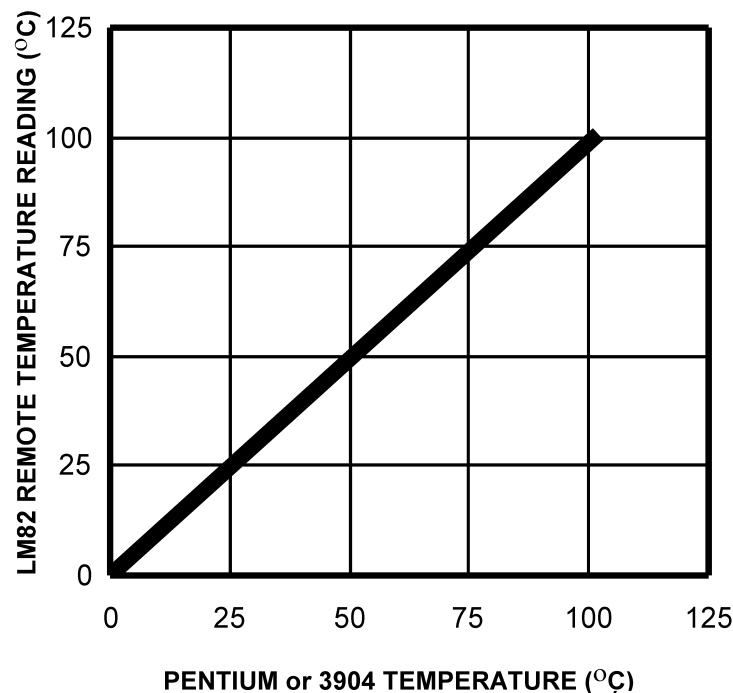


Figure 13. (c) Serial Bus Read from a Register with the internal Command Register preset to desired value

## Application Hints

The LM82 can be applied easily in the same way as other integrated-circuit temperature sensors and its remote diode sensing capability allows it to be used in new ways as well. It can be soldered to a printed circuit board, and because the path of best thermal conductivity is between the die and the pins, its temperature will effectively be that of the printed circuit board lands and traces soldered to the LM82's pins. This presumes that the ambient air temperature is almost the same as the surface temperature of the printed circuit board; if the air temperature is much higher or lower than the surface temperature, the actual temperature of the LM82 die will be at an intermediate temperature between the surface and air temperatures. Again, the primary thermal conduction path is through the leads, so the circuit board temperature will contribute to the die temperature much more strongly than will the air temperature.

To measure temperature external to the LM82's die, use a remote diode. This diode can be located on the die of a target IC, allowing measurement of the IC's temperature, independent of the LM82's temperature. The LM82 has been optimized to measure the remote diode of a Pentium II processor as shown in Figure 14. A discrete diode can also be used to sense the temperature of external objects or ambient air. Remember that a discrete diode's temperature will be affected, and often dominated, by the temperature of its leads.



**Figure 14. Pentium or 3904 Temperature vs LM82 Temperature Reading**

Most silicon diodes do not lend themselves well to this application. It is recommended that a 2N3904 transistor base emitter junction be used with the collector tied to the base.

A diode connected 2N3904 approximates the junction available on a Pentium microprocessor for temperature measurement. Therefore, the LM82 can sense the temperature of this diode effectively.

### ACCURACY EFFECTS OF DIODE NON-IDEALITY FACTOR

The technique used in today's remote temperature sensors is to measure the change in  $V_{BE}$  at two different operating points of a diode. For a bias current ratio of  $N:1$ , this difference is given as:

$$\Delta V_{BE} = \eta \frac{kT}{q} \ln(N)$$

where

- $\eta$  is the non-ideality factor of the process the diode is manufactured on,

- $q$  is the electron charge,
  - $k$  is the Boltzmann's constant,
  - $N$  is the current ratio,
  - $T$  is the absolute temperature in °K.
- (1)

The temperature sensor then measures  $\Delta V_{BE}$  and converts to digital data. In this equation,  $k$  and  $q$  are well defined universal constants, and  $N$  is a parameter controlled by the temperature sensor. The only other parameter is  $\eta$ , which depends on the diode that is used for measurement. Since  $\Delta V_{BE}$  is proportional to both  $\eta$  and  $T$ , the variations in  $\eta$  cannot be distinguished from variations in temperature. Since the non-ideality factor is not controlled by the temperature sensor, it will directly add to the inaccuracy of the sensor. For the Pentium II Intel specifies a  $\pm 1\%$  variation in  $\eta$  from part to part. As an example, assume a temperature sensor has an accuracy specification of  $\pm 3^\circ\text{C}$  at room temperature of  $25^\circ\text{C}$  and the process used to manufacture the diode has a non-ideality variation of  $\pm 1\%$ . The resulting accuracy of the temperature sensor at room temperature will be:

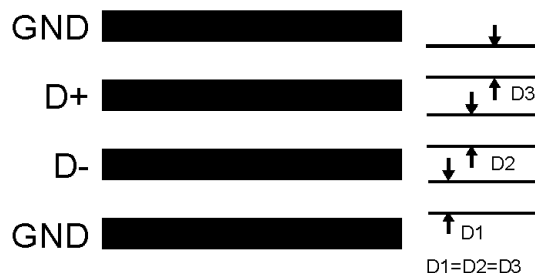
$$T_{ACC} = \pm 3^\circ\text{C} + (\pm 1\% \text{ of } 298^\circ\text{K}) = \pm 6^\circ\text{C}$$
(2)

The additional inaccuracy in the temperature measurement caused by  $\eta$ , can be eliminated if each temperature sensor is calibrated with the remote diode that it will be paired with.

### PCB LAYOUT FOR MINIMIZING NOISE

In a noisy environment, such as a processor mother board, layout considerations are very critical. Noise induced on traces running between the remote temperature diode sensor and the LM82 can cause temperature conversion errors. The following guidelines should be followed:

1. Place a  $0.1\ \mu\text{F}$  power supply bypass capacitor as close as possible to the  $V_{CC}$  pin and the recommended  $2.2\ \text{nF}$  capacitor as close as possible to the D+ and D– pins. Make sure the traces to the  $2.2\ \text{nF}$  capacitor are matched.
2. The recommended  $2.2\ \text{nF}$  diode bypass capacitor actually has a range of  $200\ \text{pF}$  to  $3.3\ \text{nF}$ . The average temperature accuracy will not degrade. Increasing the capacitance will lower the corner frequency where differential noise error affects the temperature reading thus producing a reading that is more stable. Conversely, lowering the capacitance will increase the corner frequency where differential noise error affects the temperature reading thus producing a reading that is less stable.
3. Ideally, the LM82 should be placed within  $10\ \text{cm}$  of the Processor diode pins with the traces being as straight, short and identical as possible. Trace resistance of  $1\ \Omega$  can cause as much as  $1^\circ\text{C}$  of error.
4. Diode traces should be surrounded by a GND guard ring to either side, above and below if possible. This GND guard should not be between the D+ and D– lines. In the event that noise does couple to the diode lines it would be ideal if it is coupled common mode. That is equally to the D+ and D– lines. (See [Figure 15](#))
5. Avoid routing diode traces in close proximity to power supply switching signals or filtering inductors.
6. Avoid running diode traces close to or parallel to high speed digital and bus lines. Diode traces should be kept at least  $2\ \text{cm}$ . apart from the high speed digital traces.
7. If it is necessary to cross high speed digital traces, the diode traces and the high speed digital traces should cross at a  $90^\circ$  degree angle.
8. The ideal place to connect the LM82's GND pin is as close as possible to the Processors GND associated with the sense diode.
9. Leakage current between D+ and GND should be kept to a minimum. One nano-ampere of leakage can cause as much as  $1^\circ\text{C}$  of error in the diode temperature reading. Keeping the printed circuit board as clean as possible will minimize leakage current.



**Figure 15. Ideal Diode Trace Layout**

Noise coupling into the digital lines greater than 300mVp-p (typical hysteresis), overshoot greater than 500mV above  $V_{CC}$ , and undershoot less than 500mV below GND, may prevent successful SMBus communication with the LM82. SMBus no acknowledge is the most common symptom, causing unnecessary traffic on the bus. Although, the SMBus maximum frequency of communication is rather low (100kHz max) care still needs to be taken to ensure proper termination within a system with multiple parts on the bus and long printed circuit board traces. An R/C lowpass filter with a 3db corner frequency of about 40MHz has been included on the LM82's SMBCLK input. Additional resistance can be added in series with the SMBData and SMBCLK lines to further help filter noise and ringing. Minimize noise coupling by keeping digital traces out of switching power supply areas as well as ensuring that digital lines containing high speed data communications cross at right angles to the SMBData and SMBCLK lines.

## REVISION HISTORY

### Changes from Revision C (March 2013) to Revision D

### Page

- Changed layout of National Data Sheet to TI format ..... [20](#)

## PACKAGING INFORMATION

| Orderable part number | Status<br>(1) | Material type<br>(2) | Package   Pins  | Package qty   Carrier | RoHS<br>(3) | Lead finish/<br>Ball material<br>(4) | MSL rating/<br>Peak reflow<br>(5) | Op temp (°C) | Part marking<br>(6) |
|-----------------------|---------------|----------------------|-----------------|-----------------------|-------------|--------------------------------------|-----------------------------------|--------------|---------------------|
| LM82CIMQA/NOPB        | Obsolete      | Production           | SSOP (DBQ)   16 | -                     | -           | Call TI                              | Call TI                           | -40 to 125   | 82CI<br>MQA         |
| LM82CIMQAX/NOPB       | Active        | Production           | SSOP (DBQ)   16 | 2500   LARGE T&R      | Yes         | NIPDAU   SN                          | Level-1-260C-UNLIM                | -40 to 125   | 82CI<br>MQA         |
| LM82CIMQAX/NOPB.A     | Active        | Production           | SSOP (DBQ)   16 | 2500   LARGE T&R      | Yes         | NIPDAU                               | Level-1-260C-UNLIM                | -40 to 125   | 82CI<br>MQA         |

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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**DBQ0016A**

# PACKAGE OUTLINE

**SSOP - 1.75 mm max height**

SHRINK SMALL-OUTLINE PACKAGE



4214846/A 03/2014

## NOTES:

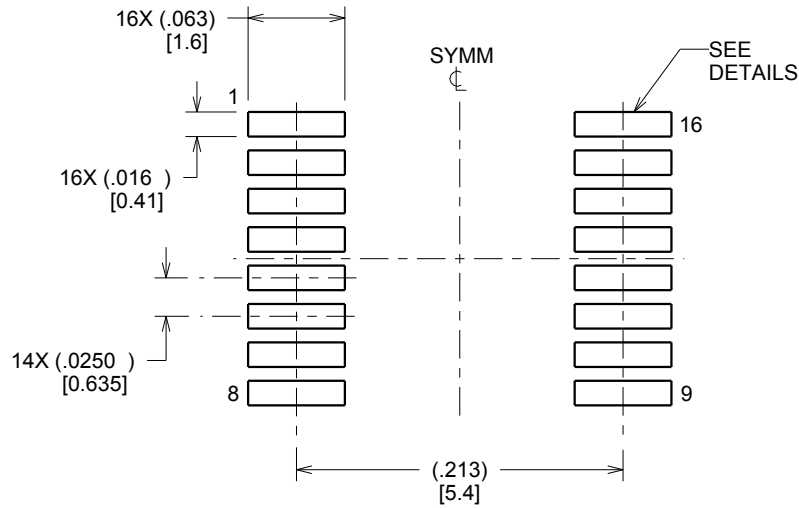
- Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- This drawing is subject to change without notice.
- This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 inch, per side.
- This dimension does not include interlead flash.
- Reference JEDEC registration MO-137, variation AB.

# EXAMPLE BOARD LAYOUT

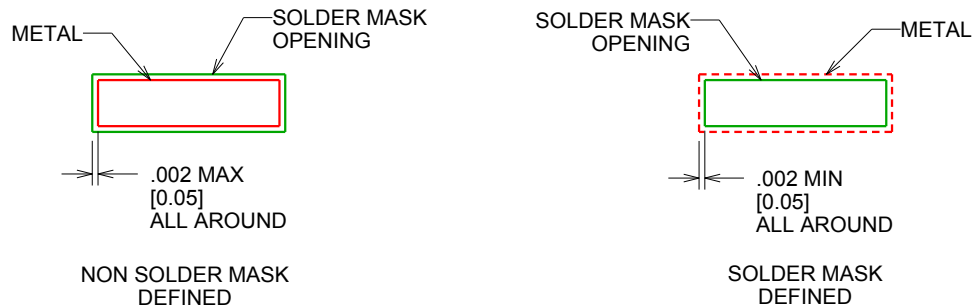
DBQ0016A

SSOP - 1.75 mm max height

SHRINK SMALL-OUTLINE PACKAGE



LAND PATTERN EXAMPLE  
SCALE:8X



SOLDER MASK DETAILS

4214846/A 03/2014

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

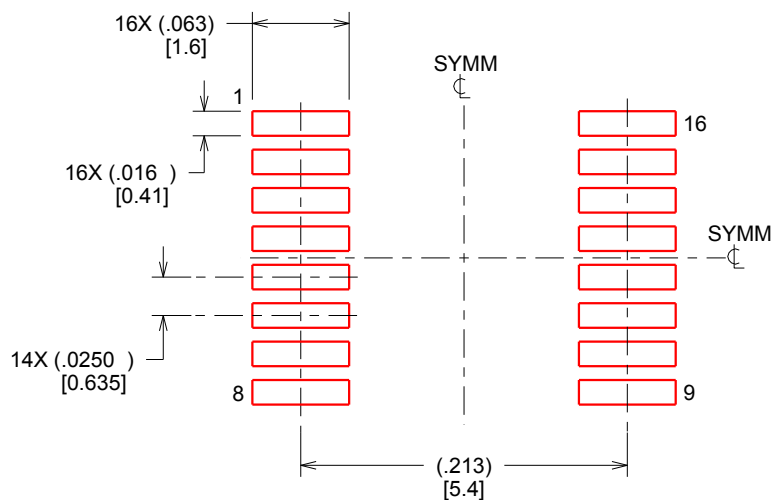


## EXAMPLE STENCIL DESIGN

DBQ0016A

SSOP - 1.75 mm max height

SHRINK SMALL-OUTLINE PACKAGE



SOLDER PASTE EXAMPLE  
BASED ON .005 INCH [0.127 MM] THICK STENCIL  
SCALE:8X

4214846/A 03/2014

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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