











LMH6622

SNOS986E - DECEMBER 2001-REVISED JULY 2014

LMH6622 Dual Wideband, Low Noise, 160 MHz, Operational Amplifiers

Features

- $V_S = \pm 6 \text{ V}$, $T_A = 25^{\circ}\text{C}$, Typical Values Unless
- Bandwidth $(A_V = +2)$ 160 MHz
- Supply Voltage Range ±2.5 V to ±6 V; + 5 V to +12
- Slew Rate 85V/µs
- Supply Current 4.3 mA/amp
- Input Common Mode Voltage -4.75 V to +5.7 V
- Output Voltage Swing ($R_L = 100 \Omega$) ±4.6 V
- Input Voltage Noise 1.6 nV/√Hz
- Input Current Noise 1.5 pA/√Hz
- Linear Output Current 90 mA
- Excellent Harmonic Distortion 90 dBc

Applications

- xDSL Receiver
- Low Noise Instrumentation Front End
- Ultrasound Preamp
- Active Filters
- Cellphone Basestation

3 Description

The LMH6622 is a dual high speed voltage feedback operational amplifier specifically optimized for low noise. A voltage noise specification of 1.6nV/√Hz, a current noise specification 1.5pA/\(\sqrt{Hz}\), a bandwidth of 160 MHz, and a harmonic distortion specification that exceeds 90 dBc combine to make the LMH6622 an ideal choice for the receive channel amplifier in ADSL, VDSL, or other xDSL designs. The LMH6622 operates from ±2.5 V to ±6 V in dual supply mode and from +5 V to +12 V in single supply configuration. The LMH6622 is stable for $A_V \ge 2$ or $A_V \le -1$. The fabrication of the LMH6622 on TI's advanced VIP10 process enables excellent (160 MHz) bandwidth at a current consumption of only 4.3 mA/amplifier. Packages for this dual amplifier are the 8-lead SOIC and the 8-lead VSSOP.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LMH6622	SOIC (8)	4.90 mm × 3.91 mm
LMH6622	VSSOP (8)	3.00 mm × 3.00 mm

(1) For all available packages, see the orderable addendum at the end of the datasheet.

XDSL Analog Front End

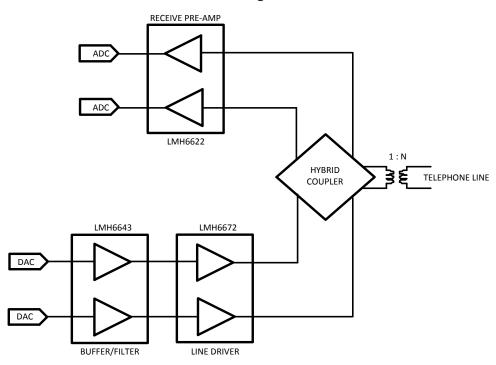




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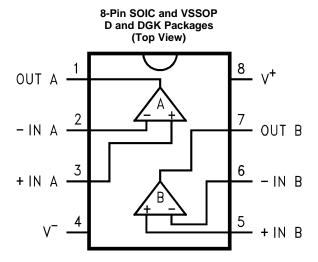
4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	hanges from Revision D (March 2013) to Revision E	Page
•	Changed data sheet flow and layout to conform with new TI standards. Added the following sections: Device Information Table, Application and Implementation; Power Supply Recommendations; Layout; Device and Documentation Support; Mechanical, Packaging, and Ordering Information	1
•	Changed R _G to R _C . Changed A _V from +10 to +9 for Figure 38	20
<u>.</u>	Changed R _G to R _C . Changed A _V from +10 to +9 for Figure 39	20
С	hanges from Revision C (March 2013) to Revision D	Page
•	Changed layout of National Data Sheet to TI format	1



5 Pin Configuration and Functions



Pin Functions

PIN		1/0	DESCRIPTION
NAME	NO.	1/0	DESCRIPTION
OUT A	1	0	ChA Output
-IN A	2	I	ChA Inverting Input
+IN A	3	I	ChA Non-inverting Input
V-	4	I	V- Supply Pin
+IN B	5	I	ChB Non-inverting Input
-IN B	6	I	ChB Inverting Input
OUT B	7	Ī	ChB Output
V+	8	I	V+ Supply Pin



6 Specifications

6.1 Absolute Maximum Ratings (1)(2)

	MIN MA	X	UNIT
V _{IN} Differential	±1.	2	V
Supply Voltage (V ⁺ – V ⁻)	13.	2	V
Voltage at Input Pins	V ⁺ +(V ⁻ -().5,).5	V
SOLDERING INFORMATION		•	
Infrared or Convection (20 sec)	235	5	°C
Wave Soldering (10 sec)	260)	°C
Junction Temperature (3)	+15	0	°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.
- (3) The maximum power dissipation is a function of $T_{J(MAX)}$, $R_{\theta JA}$ and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} T_A)/R_{\theta JA}$. All numbers apply for packages soldered directly onto a PC board.

6.2 Handling Ratings

			MIN	MAX	UNIT
T _{stg}	Storage temperature rang	e	−65°	+150	°C
V		Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins (1)		2000 (2)	\/
V _(ESD)		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins (3)		200 ⁽²⁾	V

- (1) JEDEC document JEP155 states that 2000-V HBM allows safe manufacturing with a standard ESD control process.
- (2) Human body model, 1.5 kΩ in series with 100 pF. Machine model, 0 Ω in series with 200 pF.
- (3) JEDEC document JEP157 states that 200-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions⁽¹⁾

	MIN	MAX	UNIT
Supply Voltage (V ⁺ – V ⁻)	±2.25	±6	V
Temperature Range ⁽²⁾⁽³⁾	-40	+85	°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.
- (2) Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C.
- (3) The maximum power dissipation is a function of T_{J(MAX)}, R_{θJA} and T_A. The maximum allowable power dissipation at any ambient temperature is P_D = (T_{J(MAX)} − T_A)/R_{θJA}. All numbers apply for packages soldered directly onto a PC board.

6.4 Thermal Information

	THEDMAI METDIC(1)		LMH6622	
THERMAL METRIC ⁽¹⁾		Package D	Package DGK	UNIT
		8 PINS	8 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance (2)	166°	211°	°C/W

- 1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.
- (2) The maximum power dissipation is a function of $T_{J(MAX)}$, $R_{\theta JA}$ and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} T_A)/R_{\theta JA}$. All numbers apply for packages soldered directly onto a PC board.



6.5 ±6 V Electrical Characteristics

Unless otherwise specified, $T_J = 25^{\circ}C$, $V^+ = 6$ V, $V^- = -6$ V, $V_{CM} = 0$ V, $A_V = +2$, $R_F = 500$ Ω , $R_L = 100$ Ω . Some limits apply at the temperature extremes as noted in the table.

	PARAMETER	TEST CONDITIONS		IPERATU XTREME		TEM	ROOM IPERATU	RE	UNIT
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	MIN ⁽¹⁾ TYP ⁽²⁾		MAX ⁽¹⁾	
DYNAM	IC PERFORMANCE				•				
f _{CL}	-3dB BW	V _O = 200 mV _{PP}					160		MHz
BW _{0.1dB}	0.1dB Gain Flatness	$V_O = 20 0 \text{mV}_{PP}$					30		MHz
SR	Slew Rate ⁽³⁾	V _O = 2 V _{PP}					85		V/µs
TS	Settling Time	$V_{O} = 2 V_{PP} \text{ to } \pm 0.1\%$					40		
		$V_0 = 2 V_{PP} \text{ to } \pm 1.0\%$					35		ns
Tr	Rise Time	V _O = 0.2 V Step, 10% to 90%					2.3		ns
Tf	Fall Time	V _O = 0.2 V Step, 10% to 90%					2.3		ns
DISTOR	TION and NOISE RESPONS	SE .							
e _n	Input Referred Voltage Noise	f = 100 kHz					1.6		nV/√Hz
i _n	Input Referred Current Noise	f = 100 kHz					1.5		pA/√Hz
DG	Differential Gain	$R_L = 150 \Omega$, $R_F = 470 \Omega$, NTSC					0.03%		
DP	Differential Phase	$R_L = 150 \Omega$, $R_F = 470 \Omega$, NTSC					0.03		deg
HD2	2 nd Harmonic Distortion	$f_c = 1 \text{ MHz}, V_O = 2 V_{PP},$ $R_L = 100 \Omega$				-90		į.	
		$f_c = 1 \text{ MHz}, V_O = 2 V_{PP},$ $R_L = 500 \Omega$					-100		dBc
HD3	3 rd Harmonic Distortion	$f_c = 1 \text{ MHz}, V_O = 2 V_{PP},$ $R_L = 100 \Omega$				-94		4D.	
		f_c = 1 MHz, V_O = 2 V_{PP} , R_L = 500 Ω					-100		dBc
MTPR	Upstream	$V_O = 0.6 V_{RMS}$, 26 kHz to 132 kHz (see Figure 33)					- 78		dBc
	Downstream	$V_O = 0.6 V_{RMS}$, 144 kHz to 1.1 MHz (see Figure 33)					- 70		ивс
INPUT C	CHARACTERISTICS								
Vos	Input Offset Voltage	V _{CM} = 0 V	-2		+2	-1.2	+0.2	+1.2	mV
TC V _{OS}	Input Offset Average Drift	V _{CM} = 0 V ⁽⁴⁾					-2.5		μV/°C
Ios	Input Offset Current	$V_{CM} = 0V$	-1.5		1.5	-1	-0.04	1	μΑ
I _B	Input Bias Current	V _{CM} = 0V		<u></u>	15		4.7	10	μA
R _{IN}	Input Resistance	Common Mode					17		ΜΩ
		Differential Mode					12		kΩ
C _{IN}	Input Capacitance	apacitance Common Mode 0.9		pF					
		Differential Mode					1.0		pF
CMVR	Input Common Mode	CMRR ≥ 60dB					-4.75	-4.5	
	Voltage Range					5.5	+5.7		V
CMRR	Common-Mode Rejection Ratio	Input Referred, V _{CM} = -4.2 V to +5.2 V	75			80	100		dB

All limits are specified by testing or statistical analysis.
Typical values represent the most likely parametric norm.
Slew rate is the slowest of the rising and falling slew rates. (2)

Offset voltage average drift is determined by dividing the change in VOS at temperature extremes into the total temperature change.



±6 V Electrical Characteristics (continued)

Unless otherwise specified, $T_J = 25^{\circ}C$, $V^+ = 6$ V, $V^- = -6$ V, $V_{CM} = 0$ V, $A_V = +2$, $R_F = 500$ Ω , $R_L = 100$ Ω . Some limits apply at the temperature extremes as noted in the table.

	PARAMETER	TEST CONDITIONS		IPERATU XTREME:		TEM	ROOM IPERATU	RE	UNIT
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
TRANSI	FER CHARACTERISTICS				,			,	
A _{VOL}	Large Signal Voltage Gain	$V_O = 4 V_{PP}$	70			74	83		dB
X _t	Crosstalk	f = 1 MHz					- 75		dB
OUTPU	T CHARACTERISTICS								
Vo	Output Swing	No Load, Positive Swing	4.6			4.8	5.2		
		No Load, Negative Swing			-4.4		-5.0	-4.6	V
		$R_L = 100 \Omega$, Positive Swing	3.8			4.0	4.6		V
		R_L = 100 Ω, Negative Swing			-3.8		-4.6	-4	
Ro	Output Impedance	f = 1 MHz					0.08		Ω
I _{SC}	Output Short Circuit Current	Sourcing to Ground $\Delta V_{IN} = 200 \text{ mV}^{(5)},^{(6)}$				100	135		Λ
		Sinking to Ground $\Delta V_{IN} = -200 \text{ mV}^{(5)}$, (6)				100	130		mA
I _{OUT}	Output Current	Sourcing, $V_O = +4.3 \text{ V}$ Sinking, $V_O = -4.3 \text{ V}$					90		mA
POWER	SUPPLY								
+PSRR	Positive Power Supply Rejection Ratio	Input Referred, V _S = +5 V to +6 V	74			80	95		dB
-PSRR	Negative Power Supply Rejection Ratio	Input Referred, V _S = -5 V to -6 V	69			75	90		uБ
I _S	Supply Current (per amplifier)	No Load			6.5		4.3	6	mA

⁽⁵⁾ Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C.

6.6 ±2.5 V Electrical Characteristics

Unless otherwise specified, T_J = 25°C, V+ = 2.5 V, V- = -2.5 V, V_{CM} = 0 V, A_V = +2, R_F = 500 Ω , R_L = 100 Ω . Some limits apply at the temperature extremes as noted in the table.

	PARAMETER	TEST CONDITIONS TEMPERATURE EXTREMES TEM	1			1		RE	UNIT
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
DYNAMI	C PERFORMANCE								
f_{CL}	-3 dB BW	$V_O = 200 \text{ mV}_{PP}$					150		MHz
BW _{0.1dB}	0.1dB Gain Flatness	$V_O = 200 \text{ mV}_{PP}$					20		MHz
SR	Slew Rate (3)	$V_O = 2 V_{PP}$					80		V/µs
T _S	Settling Time	$V_{O} = 2 V_{PP} \text{ to } \pm 0.1\%$					45		
		$V_{O} = 2 V_{PP} \text{ to } \pm 1.0\%$					40		ns
T _r	Rise Time	V _O = 0.2 V Step, 10% to 90%					2.5		ns
T _f	Fall Time	V _O = 0.2 V Step, 10% to 90%					2.5		ns

- 1) All limits are specified by testing or statistical analysis.
- (2) Typical values represent the most likely parametric norm.
- (3) Slew rate is the slowest of the rising and falling slew rates.

⁽⁶⁾ Short circuit test is a momentary test. Output short circuit duration is infinite for V_S ≤ ±2.5 V, at room temperature and below. For V_S > ±2.5 V, allowable short circuit duration is 1.5ms.



±2.5 V Electrical Characteristics (continued)

Unless otherwise specified, T_J = 25°C, V+ = 2.5 V, V- = -2.5 V, V_{CM} = 0 V, A_V = +2, R_F = 500 Ω , R_L = 100 Ω . Some limits apply at the temperature extremes as noted in the table.

	PARAMETER	TEST CONDITIONS		IPERATU XTREME:		TEM	ROOM	IRE	UNIT
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
DISTOR	TION and NOISE RESPONS	E	•		•				
e _n	Input Referred Voltage Noise	f = 100 kHz					1.7		nV/√Hz
i _n	Input Referred Current Noise	f = 100 kHz					1.5		pA/√Hz
HD2	2 nd Harmonic Distortion	$fc = 1 \text{ MHz}, V_O = 2V_{PP},$ $R_L = 100 \Omega$					-88		-ID -
		$fc = 1 \text{ MHz}, V_O = 2V_{PP},$ $R_L = 500 \Omega$					-98		dBc
HD3	3 rd Harmonic Distortion	fc = 1 MHz, V_O = 2 V_{PP} , R_L = 100 Ω					-92		-ID -
		fc = 1 MHz, V_O = 2 V_{PP} , R_L = 500 Ω					-100)	dBc
MTPR	Upstream	$V_O = 0.4V_{RMS}$, 26kHz to 132kHz (see Figure 33)					-76		dDo
	Downstream	V _O = 0.4 V _{RMS} , 144 kHz to 1.1 MHz (see Figure 33)					-68		dBc
INPUT C	CHARACTERISTICS				•				
Vos	Input Offset Voltage	V _{CM} = 0 V	-2.3		+2.3	- 1.5	+0.3	+1.5	mV
TC V _{OS}	Input Offset Average Drift	V _{CM} = 0 V ⁽⁴⁾					-2.5		μV/°C
Ios	Input Offset Current	V _{CM} = 0 V	-2.5		2.5	-1.5	+0.01	1.5	μΑ
I _B	Input Bias Current	V _{CM} = 0 V			15		4.6	10	μΑ
R _{IN}	Input Resistance	Common Mode					17		ΜΩ
		Differential Mode					12		kΩ
C _{IN}	Input Capacitance	Common Mode					0.9		pF
		Differential Mode					1.0		pF
CMVR	Input Common Mode	CMRR ≥ 60dB					-1.25	-1	V
	Voltage Range					2	+2.2		V
CMRR	Common Mode Rejection Ratio	Input Referred, V _{CM} = -0.7 V to +1.7 V	75			80	100		dB
TRANSF	FER CHARACTERISTICS								
A _{VOL}	Large Signal Voltage Gain	$V_O = 1 V_{PP}$				74	82		dB
X_t	Crosstalk	f = 1 MHz					- 75		dB

⁽⁴⁾ Offset voltage average drift is determined by dividing the change in V_{OS} at temperature extremes into the total temperature change.



±2.5 V Electrical Characteristics (continued)

Unless otherwise specified, T_J = 25°C, V+ = 2.5 V, V- = -2.5 V, V_{CM} = 0 V, A_V = +2, R_F = 500 Ω , R_L = 100 Ω . Some limits apply at the temperature extremes as noted in the table.

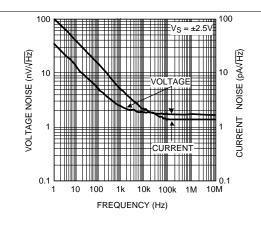
PARAMETER		TEST CONDITIONS		IPERATU XTREME:		TEN	UNIT		
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
OUTPU	T CHARACTERISTICS				·			·	
Vo	Output Swing	No Load, Positive Swing	1.2			1.4	1.7		
		No Load, Negative Swing			-1		-1.5	-1.2	V
		$R_L = 100 \Omega$, Positive Swing	1			1.2	1.5		V
		$R_L = 100 \Omega$, Negative Swing			-0.9		-1.4	-1.1	
Ro	Output Impedance	f = 1 MHz					0.1		Ω
I _{SC} Output Short Circuit Current		Sourcing to Ground $\Delta V_{IN} = 200 \text{ mV}^{(5)(6)}$				100	137		
		Sinking to Ground $\Delta V_{IN} = -20 \text{ 0mV}^{(5)(6)}$				100	134		mA
I _{OUT}	Output Current	Sourcing, $V_O = +0.8 \text{ V}$ Sinking, $V_O = -0.8 \text{ V}$					90		mA
POWER	SUPPLY	•			,				
+PSRR	Positive Power Supply Rejection Ratio	Input Referred, V _S = +2.5 V to +3 V	72			78	93		dB
-PSRR	Negative Power Supply Rejection Ratio	Input Referred, V _S = -2.5 V to -3 V	70			75	88		dB
I _S	Supply Current (per amplifier)	No Load			6.4		4.1	5.8	mA

⁽⁵⁾ Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C.

⁽⁶⁾ Short circuit test is a momentary test. Output short circuit duration is infinite for V_S ≤ ±2.5 V, at room temperature and below. For V_S > ±2.5 V, allowable short circuit duration is 1.5ms.



6.7 Typical Performance Characteristics



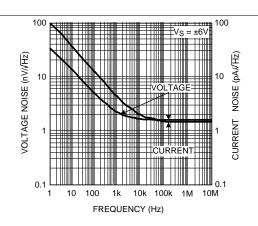
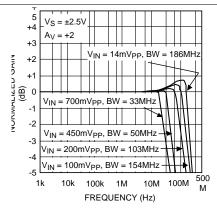


Figure 1. Current and Voltage Noise vs. Frequency





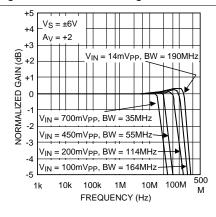


Figure 3. Frequency Response vs. Input Signal Level

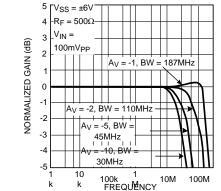


Figure 4. Frequency Response vs. Input Signal Level

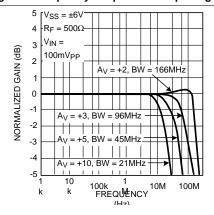
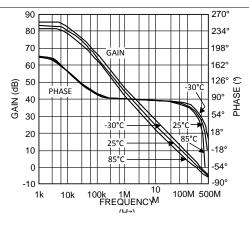


Figure 5. Inverting Amplifier Frequency Response

Figure 6. Non-Inverting Amplifier Frequency Response



Typical Performance Characteristics (continued)



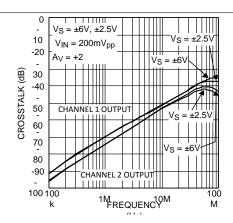


Figure 7. Open Loop Gain and Phase Response

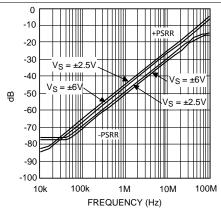


Figure 8. Crosstalk vs. Frequency

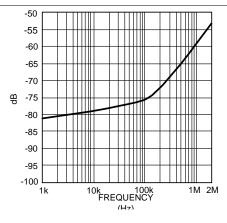


Figure 9. PSRR vs. Frequency

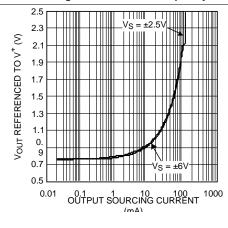


Figure 10. CMRR vs. Frequency

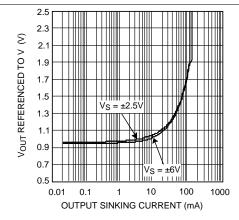


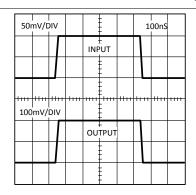
Figure 11. Positive Output Swing vs. Source Current

Figure 12. Negative Output Swing vs. Sink Current

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Typical Performance Characteristics (continued)



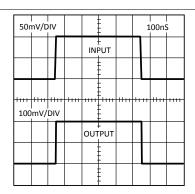
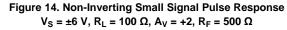
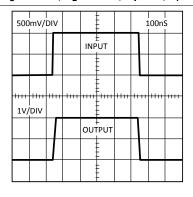


Figure 13. Non-Inverting Small Signal Pulse Response $V_S=\pm 2.5~V,~R_L=100~\Omega,~A_V=\pm 2,~R_F=500~\Omega$





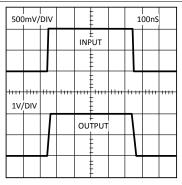
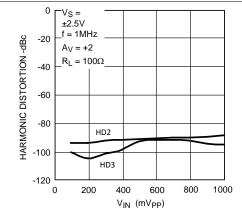


Figure 15. Non-Inverting Large Signal Pulse Response $V_S = \pm 2.5~V,~R_L = 100~\Omega,~A_V = +2,~R_F = 500~\Omega$

Figure 16. Non-Inverting Large Signal Pulse Response $\rm V_S=\pm 6~V,~R_L=100~\Omega,~A_V=+2,~R_F=500~\Omega$



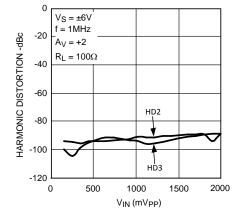
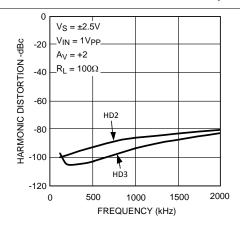


Figure 17. Harmonic Distortion vs. Input Signal Level

Figure 18. Harmonic Distortion vs. Input Signal Level

TEXAS INSTRUMENTS

Typical Performance Characteristics (continued)



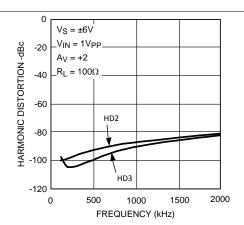
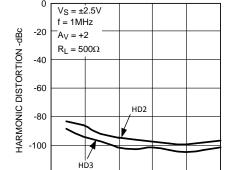


Figure 19. Harmonic Distortion vs. Frequency



400

-120

0

200

Figure 20. Harmonic Distortion vs. Frequency

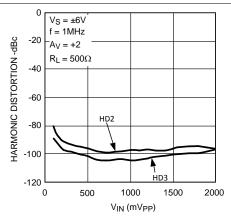


Figure 21. Harmonic Distortion vs. Input Signal Level

 $V_{IN} (mV_{PP})$

600

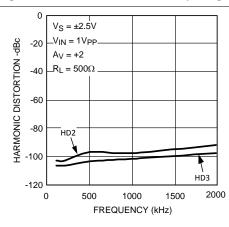


Figure 22. Harmonic Distortion vs. input Signal Level

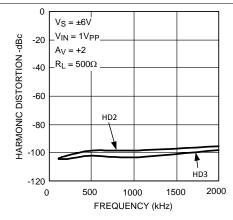


Figure 23. Harmonic Distortion vs. Input Frequency

Figure 24. Harmonic Distortion vs. Input Frequency

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Typical Performance Characteristics (continued)

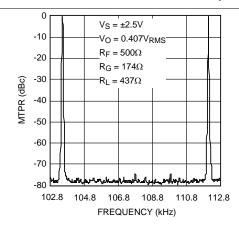


Figure 25. Full Rate ADSL (DMT) Upstream MTPR $@V_S = \pm 2.5 \text{ V}$

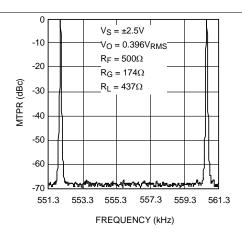


Figure 26. Full Rate ADSL (DMT) Downstream MTPR @ V_S = ±2.5 V

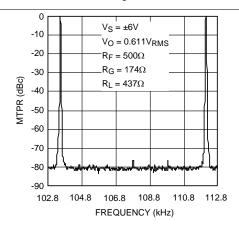


Figure 27. Full Rate ADSL (DMT) Upstream MTPR $@V_S = \pm 6 V$

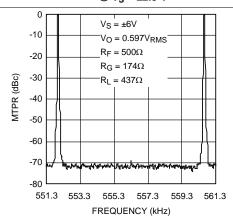


Figure 28. Full Rate ADSL (DMT) Downstream MTPR @ V_S = +6 V



7 Parameter Measurement Information

7.1 Test Circuits

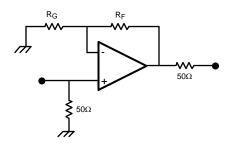


Figure 29. Non-Inverting Amplifier

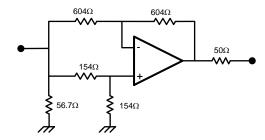


Figure 30. CMRR

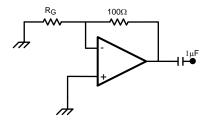


Figure 31. Voltage Noise R_G = 1 Ω for f \leq 100 kHz, R_G = 20 Ω for f > 100 kHz

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Test Circuits (continued)

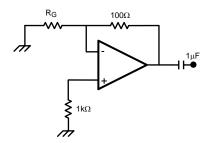


Figure 32. Current Noise R_G = 1 Ω for f \leq 100 kHz, R_G = 20 Ω for f > 100 kHz

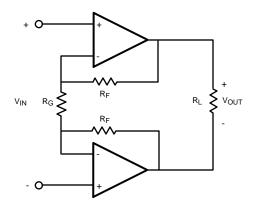


Figure 33. Multitone Power Ratio, R $_{\text{F}}$ = 500 $\Omega,$ R $_{\text{G}}$ = 174 $\Omega,$ R $_{\text{L}}$ = 437 Ω



8 Detailed Description

8.1 Overview

The LMH6622 is a dual high speed voltage operational amplifier specifically optimized for low noise. The LMH6622 operates from ± 2.5 V to ± 6 V in dual supply mode and from ± 5 V to ± 12 V in single supply configuration.

8.2 Functional Block Diagram

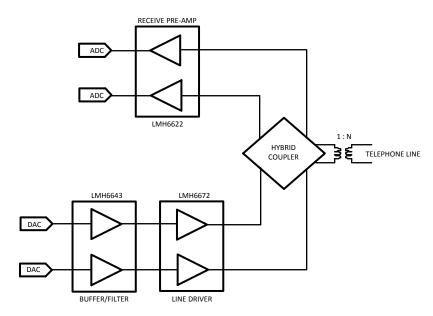


Figure 34. xDSL Analog Front End

8.3 Feature Description

- 4.5 V to 12 V supply range
- · Large linear output current of 90 mA
- Excellent harmonic distortion of 90 dBc

8.4 Device Functional Modes

- · Single or dual supplies
- Traditional voltage feedback topology for maximum flexibility

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9 Application and Implementation

9.1 DSL Receive Channel Applications

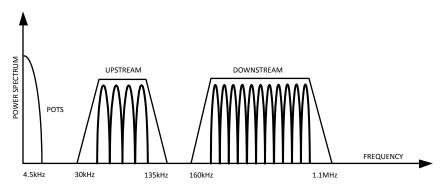


Figure 35. ADSL Signal Description

The LMH6622 is a dual, wideband operational amplifier designed for use as a DSL line receiver. In the receive band of a Customer Premises Equipment (CPE) ADSL modem it is possible that as many as 255 Discrete Multi-Tone (DMT) QAM signals will be present, each with its own carrier frequency, modulation, and signal level. The ADSL standard requires a line referred noise power density of -140 dBm/Hz within the CPE receive band of 100 KHz to 1.1 MHz. The CPE driver output signal will leak into the receive path because of full duplex operation and the imperfections of the hybrid coupler circuit. The DSL analog front end must incorporate a receiver pre-amp which is both low noise and highly linear for ADSL-standard operation. The LMH6622 is designed for the twin performance parameters of low noise and high linearity.



DSL Receive Channel Applications (continued)

Applications ranging from +5 V to +12 V or ±2.5 V to ±6 V are fully supported by the LMH6622. In Figure 36, the LMH6622 is used as an inverting summing amplifier to provide both received pre-amp channel gain and driver output signal cancellation, that is, the function of a hybrid coupler.

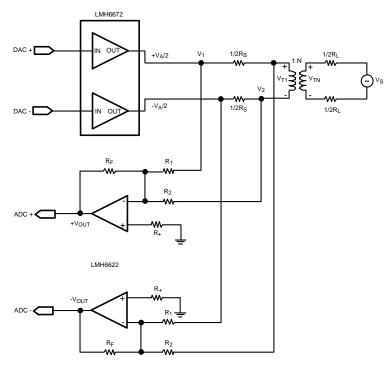


Figure 36. ADSL Receive Applications Circuit

The two R_S resistors are used to provide impedance matching through the 1:N transformer.

$$R_S = \frac{R_L}{N^2}$$

where

R_L is the impedance of the twisted pair line

The resistors R_2 and R_F are used to set the receive gain of the pre-amp. The receive gain is selected to meet the ADC full-scale requirement of a DSL chipset.

Resistor R_1 and R_2 along with R_F are used to achieve cancellation of the output driver signal at the output of the receiver.

Since the LMH6622 is configured as an inverting summing amplifier, VOLIT is found to be,

$$V_{OUT} = -R_F \left[\frac{V_1}{R_1} + \frac{V_2}{R_2} \right] \tag{2}$$

The expression for V_1 and V_2 can be found by using superposition principle.

When $V_S = 0$,

$$V_1 = \frac{1}{2}V_A$$
 and $V_2 = -\frac{1}{4}V_A$ (3)

When $V_A = 0$,

$$V_1 = 0$$
 and $V_2 = -\frac{1}{2}V_{T1}$ (4)

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DSL Receive Channel Applications (continued)

Therefore,

$$V_1 = \frac{1}{2}V_A$$
 and $V_2 = -\frac{1}{4}V_A - \frac{1}{2}V_{T1}$ (5)

And then,

$$V_{OUT} = -R_F \left[\frac{V_A}{2R_1} - \frac{V_A}{4R_2} - \frac{V_{T1}}{2R_2} \right]$$
 (6)

Setting $R_1 = 2^*R_2$ to cancel unwanted driver signal in the receive path, then we have

$$V_{OUT} = \frac{R_F}{2R_2} V_{T1} \tag{7}$$

We can also find that,

$$V_{TN} = \frac{1}{2} V_S \text{ and } V_{T1} = \frac{1}{N} V_{TN} = \frac{1}{2N} V_S$$
 (8)

And then

$$V_{OUT} = \frac{R_F}{4NR_2} V_S \tag{9}$$

In conclusion, the peak-to-peak voltage to the ADC would be,

$$2 V_{OUT} = \frac{R_F}{2NR_2} V_S \tag{10}$$

9.2 Receive Channel Noise Calculation

The circuit of Figure 36 also has the characteristic that it cancels noise power from the drive channel.

The noise gain of the receive pre-amp is found to be:

$$A_{n} = 1 + \frac{R_{F}}{R_{1}/R_{2}} \tag{11}$$

Noise power at each of the output of LMH6622:

$$e_0^2 = A_n^2 [V_n^2 + i_{non-inv}^2 R_+^2 + 4kT R_+] + i_{inv}^2 R_F^2 + 4kT R_F A_n$$

where

- V_n is the Input referred voltage noise
- in is the Input referred current noise
- inon-inv is the Input referred non-inverting current noise
- i_{inv} is the Input referred inverting current noise
- k is the Boltzmann's constant, K = 1.38 x 10⁻²³
- · T is the Resistor temperature in k
- R₊ is the source resistance at the non-inverting input to balance offset voltage, typically very small for this
 inverting summing applications (12)

For a voltage feedback amplifier,

$$i_{inv} = i_{non-inv} = i_n \tag{13}$$

Therefore, total output noise from the differential pre-amp is:

$$e^{2}_{TotalOutput} = 2 e^{2}_{0}$$
 (14)

The factor '2' appears here because of differential output.

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9.3 Differential Analog-to-Digital Driver

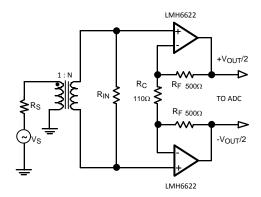


Figure 37. Circuit for Differential A/D Driver

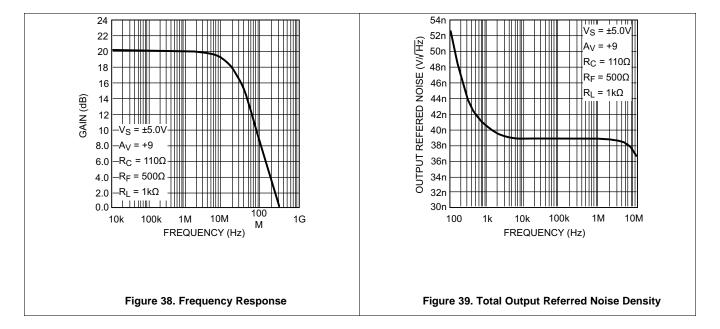
The LMH6622 is a low noise, low distortion high speed operational amplifier. The LMH6622 comes in either SOIC-8 or VSSOP-8 packages. Because two channels are available in each package the LMH6622 can be used as a high dynamic range differential amplifier for the purpose of driving a high speed analog-to-digital converter. Driving a 1 k Ω load, the differential amplifier of Figure 37 provides 20 dB gain, a flat frequency response up to 6 MHz, and harmonic distortion that is lower than 80 dBc. This circuit makes use of a transformer to convert a single-ended signal to a differential signal. The input resistor R_{IN} is chosen by the following equation,

$$R_{IN} = \frac{1}{N^2} R_S \tag{15}$$

The gain of this differential amplifier can be adjusted by R_{C} and R_{F} ,

$$A_{V} = 2 \frac{R_{F}}{R_{C}} \tag{16}$$

See Figure 38 and Figure 39 below for plots related to the discussion of Figure 37.



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9.4 Typical Application

See Figure 40 for application circuit.

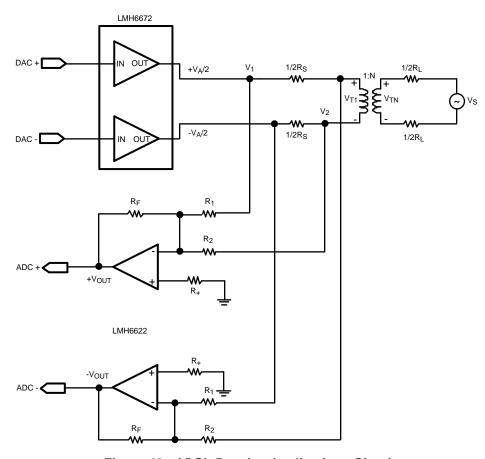


Figure 40. ADSL Receive Applications Circuit

9.4.1 Design Requirements

All normal precautions / considerations with Op Amps apply

9.4.2 Detailed Design Procedure

- Use power supply decoupling capacitors close to supply pins
- Beware of junction temperature rise at elevated ambient temperature and / or heavy output(s) load current especially at higher supply voltages
- Ground plane near sensitive input pins can be removed to minimize parasitic capacitance

9.4.3 Application Curves

See Figure 38 and Figure 39.



10 Power Supply Recommendations

10.1 Driving Capacitive Load

Capacitive Loads decrease the phase margin of all op amps. The output impedance of a feedback amplifier becomes inductive at high frequencies, creating a resonant circuit when the load is capacitive. This can lead to overshoot, ringing and oscillation. To eliminate oscillation or reduce ringing, an isolation resistor can be placed between the load and the output. In general, the bigger the isolation resistor, the more damped the pulse response becomes. For initial evaluation, a 50 Ω isolation resistor is recommended.

11 Layout

11.1 Layout Guidelines

11.1.1 Circuit Layout Considerations

Texas Instruments suggests the copper patterns on the evaluation boards listed below as a guide for high frequency layout. These boards are also useful as an aid in device testing and characterization. As is the case with all high-speed amplifiers, accepted-practice R_{F} design technique on the PCB layout is mandatory. Generally, a good high frequency layout exhibits a separation of power supply and ground traces from the inverting input and output pins. Parasitic capacitances between these nodes and ground will cause frequency response peaking and possible circuit oscillations (see SNOA367, Application Note OA-15, for more information). High quality chip capacitors with values in the range of 1000 pF to 0.1 μF should be used for power supply bypassing. One terminal of each chip capacitor is connected to the ground plane and the other terminal is connected to a point that is as close as possible to each supply pin as allowed by the manufacturer's design rules. In addition, a tantalum capacitor with a value between 4.7 μF and 10 μF should be connected in parallel with the chip capacitor. Signal lines connecting the feedback and gain resistors should be as short as possible to minimize inductance and microstrip line effect. Input and output termination resistors should be impedance matched to the corresponding load termination.

Symmetry between the positive and negative paths in the layout of differential circuitry should be maintained so as to minimize the imbalance of amplitude and phase of the differential signal.

DEVICE	PACKAGE	EVALUATION BOARD P/N
LMH6622MA	SOIC-8	LMH730036
LMH6622MM	VSSOP-8	LMH730123

Component value selection is another important parameter in working with high speed/high performance amplifiers. Choosing external resistors that are large in value compared to the value of other critical components will affect the closed loop behavior of the stage because of the interaction of these resistors with parasitic capacitances. These parasitic capacitors could either be inherent to the device or be a by-product of the board layout and component placement. Moreover, a large resistor will also add more thermal noise to the signal path. Either way, keeping the resistor values low will diminish this interaction. On the other hand, choosing very low value resistors could load down nodes and will contribute to higher overall power dissipation and worse distortion.



11.2 Layout Examples

11.2.1 SOIC Layout Example

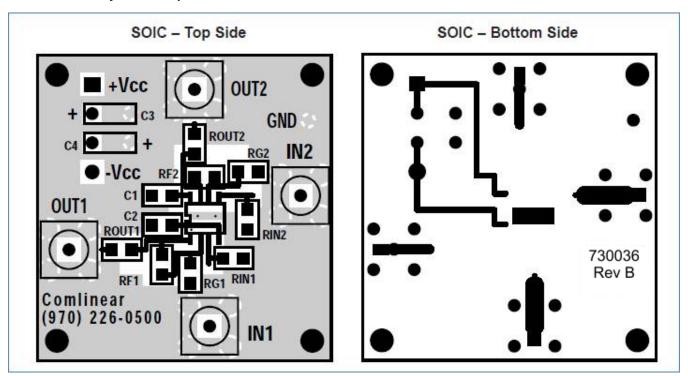


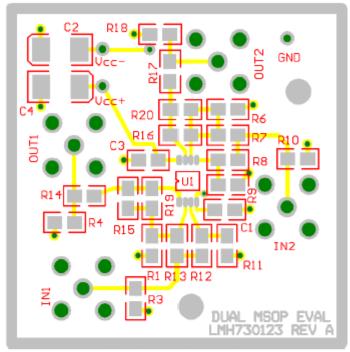
Figure 41. LMH6622 Layout Example - SOIC

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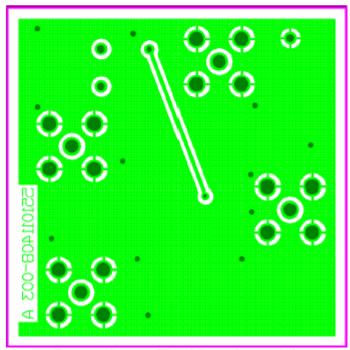


Layout Examples (continued)

11.2.2 VSSOP Layout Example



Top Layer (2x scale)



Bottom Layer (Top View, 2x scale)

Figure 42. LMH6622 Layout Example - VSSOP

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12 Device and Documentation Support

12.1 Trademarks

All trademarks are the property of their respective owners.

12.2 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

12.3 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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PACKAGING INFORMATION

Orderable part number	Status	Material type	Package Pins	Package qty Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
	. ,	()			(-)	(4)	(5)		(-)
LMH6622MA/NOPB	Active	Production	SOIC (D) 8	95 TUBE	Yes	SN	Level-1-260C-UNLIM	-40 to 85	LMH66 22MA
LMH6622MA/NOPB.A	Active	Production	SOIC (D) 8	95 TUBE	Yes	SN	Level-1-260C-UNLIM	-40 to 85	LMH66 22MA
LMH6622MAX/NOPB	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 85	LMH66 22MA
LMH6622MAX/NOPB.A	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 85	LMH66 22MA
LMH6622MM/NOPB	Active	Production	VSSOP (DGK) 8	1000 SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 85	A80A
LMH6622MM/NOPB.A	Active	Production	VSSOP (DGK) 8	1000 SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 85	A80A
LMH6622MMX/NOPB	Active	Production	VSSOP (DGK) 8	3500 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 85	A80A
LMH6622MMX/NOPB.A	Active	Production	VSSOP (DGK) 8	3500 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 85	A80A

⁽¹⁾ Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

⁽²⁾ Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

⁽⁴⁾ Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.



PACKAGE OPTION ADDENDUM

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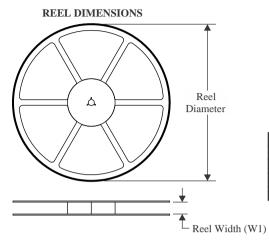
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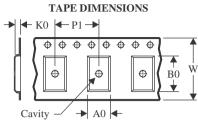
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

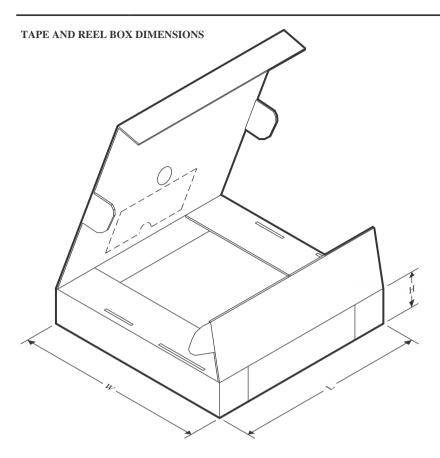
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMH6622MAX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1
LMH6622MM/NOPB	VSSOP	DGK	8	1000	177.8	12.4	5.3	3.4	1.4	8.0	12.0	Q1
LMH6622MMX/NOPB	VSSOP	DGK	8	3500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1

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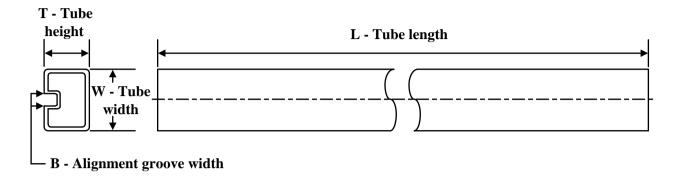
*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMH6622MAX/NOPB	SOIC	D	8	2500	367.0	367.0	35.0
LMH6622MM/NOPB	VSSOP	DGK	8	1000	208.0	191.0	35.0
LMH6622MMX/NOPB	VSSOP	DGK	8	3500	367.0	367.0	35.0

PACKAGE MATERIALS INFORMATION

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TUBE



*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
LMH6622MA/NOPB	D	SOIC	8	95	495	8	4064	3.05
LMH6622MA/NOPB.A	D	SOIC	8	95	495	8	4064	3.05



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.





SMALL OUTLINE PACKAGE



NOTES:

PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

 2. This drawing is subject to change without notice.

 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187.



SMALL OUTLINE PACKAGE



NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.
- 9. Size of metal pad may vary due to creepage requirement.



SMALL OUTLINE PACKAGE



NOTES: (continued)

- 11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 12. Board assembly site may have different recommendations for stencil design.



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