



# 3-W STEREO AUDIO POWER AMPLIFIER WITH ADVANCED DC VOLUME CONTROL

Check for Samples : TPA6012A4

#### **FEATURES**

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- Advanced 32 Steps DC Volume Control
  - Steps From -40 dB to 18 dB
  - Fade Mode
  - -85-dB Mute Mode
- 3 W Into 3-Ω Speakers
- Differential Inputs
- Headphone Mode
- Pin-to-Pin Compatible With TPA6011A4 and TPA6013A4
- 24-Pin PowerPAD™ Package (PWP)

#### **APPLICATIONS**

- LCD Monitors
- Notebook PC
- All-in-One PC

APPLICATION CIRCUIT

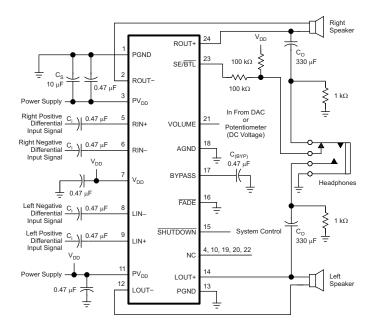
#### **DESCRIPTION**

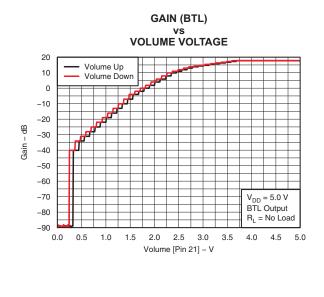
The TPA6012A4 is a stereo audio power amplifier that drives 3 W/channel of continuous RMS power into a 3- $\Omega$  load. Advanced dc volume control minimizes external components and allows BTL (speaker) volume control and SE (headphone) volume control. LCD monitors and notebook benefit from the integrated feature set that minimizes external components without sacrificing functionality.

To simplify design, the speaker volume level is adjusted by applying a dc voltage to the VOLUME terminal. To ensure a smooth transition between active and shutdown modes, a fade mode ramps the volume up and down.

The 24-pin PowerPAD™ package (PWP) enchances thermal performance.

#### DC VOLUME CONTROL





S00

Figure 1. Application Circuit and DC Volume Control

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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### **AVAILABLE OPTIONS**

т	PACKAGE
IA	24-PIN TSSOP (PWP)
-40°C to 85°C	TPA6012A4PWP

#### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted)(1)

		UNIT
V <sub>SS</sub>	Supply voltage, V <sub>DD</sub> , PV <sub>DD</sub>	–0.3 V to 6 V
$V_{I}$	Input voltage, RIN+, RIN-, LIN+,LIN-	–0.3 V to V <sub>DD</sub> +0.3 V
	Continuous total power dissipation	See Dissipation Rating Table
T <sub>A</sub>	Operating free-air temperature range	-40°C to 85°C
T <sub>J</sub>	Operating junction temperature range	-40°C to 150°C
T <sub>stg</sub>	Storage temperature range	−65°C to 85°C

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### **DISSIPATION RATING TABLE(1)**

PACKAGE	T <sub>A</sub> = 25°C	DERATING FACTOR	T <sub>A</sub> = 70°C	T <sub>A</sub> = 85°C
	POWER RATING	ABOVE T <sub>A</sub> = 25°C	POWER RATING	POWER RATING
PWP	2.7 mW	21.8 mW/°C	1.7 W	1.4 W

 All characterization is done using an external heatsink with θ<sub>SA</sub>= 25°C/W. The resulting derating factor is 22.2 mW/°C.

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#### **RECOMMENDED OPERATING CONDITIONS**

			MIN	MAX	UNIT
$V_{SS}$	Supply voltage, V <sub>DD</sub> , PV <sub>DD</sub>		4	5.5	V
V <sub>IH</sub> High-level input voltage	SE/BTL, FADE	0.8 x V <sub>DD</sub>		V	
	SHUTDOWN	2		V	
\/	Low lovel input veltage	SE/BTL, FADE		0.6 x V <sub>DD</sub>	V
V <sub>IL</sub> Low-level input voltage		SHUTDOWN		0.8	V
T <sub>A</sub>	Operating free-air temperature		-40	85	°C

#### **ELECTRICAL CHARACTERISTICS**

 $T_A = 25$ °C,  $V_{DD} = PV_{DD} = 5.5 \text{ V}$  (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
1.1/ 1	Output offset voltage (measured differentially)	$V_{DD} = 5.5 \text{ V}$ , Gain = 0 dB, SE/ $\overline{BTL} = 0 \text{ V}$		2	30	mV
V <sub>00</sub>	Output onset voltage (measured differentially)	$V_{DD} = 5.5 \text{ V}$ , Gain = 18 dB, $SE/\overline{BTL} = 0 \text{ V}$		2.6	50	mV
PSRR	Power supply rejection ratio	$V_{DD} = PV_{DD} = 4 \text{ V to } 5.5 \text{ V, Gain} = 0 \text{ dB}$		-80		dB
I <sub>IH</sub>	High-level input current (SE/BTL, FADE, SHUTDOWN, VOLUME)	$V_{DD} = PV_{DD} = 5.5 \text{ V},$ $V_{I} = V_{DD} = PV_{DD}$			1	μΑ
I <sub>IL</sub>	Low-level input current (SE/BTL, FADE, SHUTDOWN, VOLUME)	V <sub>DD</sub> = PV <sub>DD</sub> = 5 V, V <sub>I</sub> = 0 V			1	μA
I	Supply current no load	$V_{DD} = PV_{DD} = 5 \text{ V, SE/BTL} = 0 \text{ V,}$ SHUTDOWN = 2 V		6.7	9	mA
I <sub>DD</sub> Supply current, no load		$V_{DD} = PV_{DD} = 5 \text{ V, SE/BTL} = 5 \text{ V,}$ SHUTDOWN = 2 V		4.5	6	ША
I <sub>DD</sub>	Supply current, max power into a 3-Ω load	$\begin{array}{l} V_{DD}=5~V=PV_{DD},~SE/\overline{BTL}=0~V,\\ \overline{SHUTDOWN}=2~V,~R_L=3~\Omega,\\ P_O=2~W,~stereo \end{array}$		1.5		A <sub>RMS</sub>
I <sub>DD(SD)</sub>	Supply current, shutdown mode	SHUTDOWN = 0 V		10	25	μΑ

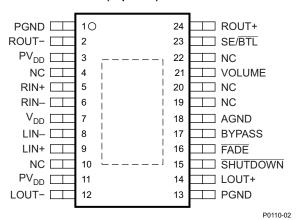
#### **OPERATING CHARACTERISTICS**

 $T_A = 25$ °C,  $V_{DD} = PV_{DD} = 5$  V,  $R_L = 3$   $\Omega$ , Gain = 6 dB, Stereo (unless otherwise noted)

	PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
		THD = 1%, $f = 1 \text{ kHz}$ , $R_L = 16 \Omega \text{ (SE)}$			195		mW
<b>D</b>	Outrat a succession	THD = 10%, f = 1 kHz, $R_L = 16 \Omega$ (SE)			235		mW
Po	Output power	THD = 1%, f = 1 kHz, $R_L = 3 \Omega$ (BTL)			2.0		10/
		THD = 10%, f = 1 kHz, V <sub>DD</sub> = 5.5 V, R <sub>L</sub> =	3 Ω (BTL)		3.2		W
THD+N	Total harmonic distortion + noise	$P_{O} = 0.9 \text{ W}, R_{L} = 8 \Omega \text{ (BTL)}, f = 20 \text{ Hz to}$	20 kHz		<0.1%		
		$P_{O} = 0.1 \text{ W}, R_{L} = 16 \Omega \text{ (SE)}, f = 20 \text{ Hz to } 20 \text{ kHz}$			0.03%		
V <sub>OH</sub>	High-level output voltage	$R_L = 8 \Omega$ , Measured between output and	V <sub>DD</sub> = 5.5 V			700	mV
V <sub>OL</sub>	Low-level output voltage	$R_L$ = 8 Ω, Measured between output and GND, $V_{DD}$ = 5.5 V				400	mV
V <sub>(Bypass)</sub>	Bypass voltage (Nominally V <sub>DD</sub> /2)	Measured at pin 17, No load, V <sub>DD</sub> = 5.5 V	1	2.65	2.75	2.85	V
	Complete single animation anti-	$f = 1 \text{ kHz}$ , Gain = 0 dB, $C_{(BYP)} = 1 \mu F$	BTL (4Ω)		-66		dB
	Supply ripple rejection ratio		SE (32Ω)		-60		dB
	Organisally		BTL		110		dB
	Crosstalk		SE		102		dB
	Noise output voltage	$f$ = 20 Hz to 20 kHz, Gain = 0 dB, $C_{(BYP)}$ = 1 $\mu F$	BTL		36		$\mu V_{RMS}$
Z <sub>I</sub>	Input impedance (see Figure 20)	VOLUME = 5 V			12		kΩ



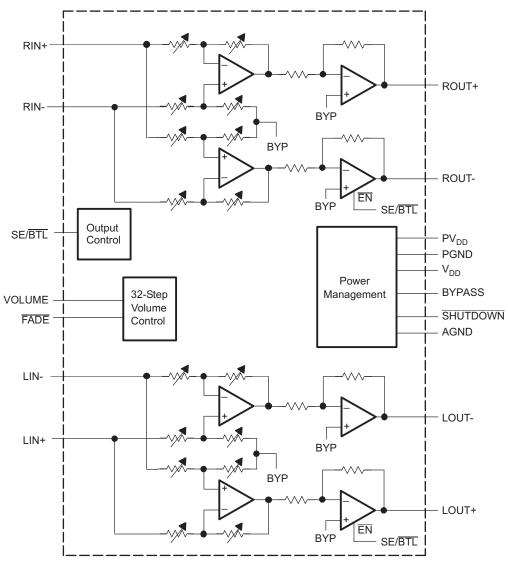
#### PWP Package (Top View)



#### **Terminal Functions**

TERMINAL			DECODINE	
NAME	NO.	I/O	DESCRIPTION	
BYPASS	17	I	Tap to voltage divider for internal mid-supply bias generator used for analog reference	
FADE	16	I	Places the amplifier in fade mode if a logic low is placed on this terminal; normal operation if a logic high is placed on this terminal.	
AGND	18	ı	Analog power supply ground	
LIN-	8		Left channel negative input for fully differential input.	
LIN+	9		Left channel positive input for fully differential input.	
LOUT-	12	0	Left channel negative audio output	
LOUT+	14	0	Left channel positive audio output.	
NC	4, 10, 19, 20, 22	-	No connection	
PGND	1, 13	_	Power ground	
$PV_{DD}$	3, 11	_	Supply voltage terminal for power stage	
RIN+	5	I	Right channel positive input for fully differential input.	
RIN-	6		Right channel negative input for fully differential input.	
ROUT-	2	0	Right channel negative audio output	
ROUT+	24	0	Right channel positive audio output	
SE/BTL	23	I	Output control. When this terminal is high, SE outputs are selected. When this terminal is low, BTL outputs are selected.	
SHUTDOWN	15	Ι	Places the amplifier in shutdown mode if a TTL logic low is placed on this terminal	
$V_{DD}$	7	1	Supply voltage terminal	
DC VOLUME	21	ı	Terminal for dc volume control. DC voltage range is 0 to V <sub>DD</sub> .	

#### **FUNCTIONAL BLOCK DIAGRAM**



NOTE: All resistor wipers are adjusted with 32 step volume control.



Table 1. DC Volume Control (BTL Mode,  $V_{DD} = 5 \text{ V})^{(1)}$ 

VOLUME	(PIN 21)	GAIN OF AMPLIFIER
FROM (V)	TO (V)	(Typ) <sup>(2)</sup>
0.00	0.26	-85
0.33	0.37	-40
0.44	0.48	-34
0.56	0.59	-31
0.67	0.70	-28
0.78	0.82	-25
0.89	0.93	-22
1.01	1.04	-19
1.12	1.16	-16
1.23	1.27	-13
1.35	1.38	-10
1.46	1.49	-7
1.57	1.60	-4
1.68	1.72	-2
1.79	1.83	0
1.91	1.94	2
2.02	2.06	4
2.13	2.17	6
2.25	2.28	8
2.36	2.39	10
2.47	2.50	11
2.58	2.61	12
2.70	2.73	13
2.81	2.83	14
2.92	2.95	14.5
3.04	3.06	15
3.15	3.17	15.5
3.26	3.29	16
3.38	3.40	16.5
3.49	3.51	17
3.60	3.63	17.5
3.71	5.00	18

<sup>(1)</sup> For other values of  $V_{DD}$ , scale the voltage values in the table by a factor of  $V_{DD}/5$ . (2) Tested in production.



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Table 2. DC Volume Control (SE Mode,  $V_{DD} = 5 \text{ V})^{(1)}$ 

VOLUME	(PIN 21)	GAIN OF AMPLIFIER
FROM (V)	TO (V)	(Тур)
0.00	0.26	-85
0.33	0.37	-46
0.44	0.48	-40
0.56	0.59	-37
0.67	0.70	-34
0.78	0.82	-31
0.89	0.93	-28
1.01	1.04	-25
1.12	1.16	-22
1.23	1.27	-19
1.35	1.38	-16
1.46	1.49	-13
1.57	1.60	-10
1.68	1.72	-8
1.79	1.83	-6 <sup>(2)</sup>
1.91	1.94	-4
2.02	2.06	-2
2.13	2.17	0 <sup>(2)</sup>
2.25	2.28	2
2.36	2.39	4
2.47	2.50	5
2.58	2.61	6 <sup>(2)</sup>
2.70	2.73	7
2.81	2.83	8
2.92	2.95	8.5
3.04	3.06	9
3.15	3.17	9.5
3.26	3.29	10
3.38	3.40	10.5
3.49	3.51	11
3.60	3.63	11.5
3.71	5.00	12

For other values of  $V_{DD}$ , scale the voltage values in the table by a factor of  $V_{DD}/5$ . Tested in production. Remaining gain steps are specified by design.



#### TYPICAL CHARACTERISTICS

Test conditions (unless otherwise noted) for typical operating performance:  $V_{DD}=5.0~V,~C_{IN}=1~\mu F,~C_{BYPASS}=1~\mu F,~T_A=27^{\circ}C,~SHUTDOWN=V_{DD}$ 

#### **Table of Graphs**

	Gain (BTL)	vs Volume voltage	Figure 1
T. 10. 11. 7	Total harmonic distortion plus poice (PTI)	vs Frequency	Figure 2, Figure 3, Figure 4
THD+N	Total harmonic distortion plus noise (BTL)	vs Output power	Figure 7, Figure 8, Figure 9
		vs Frequency	Figure 5, Figure 6
THD+N	Total harmonic distortion plus noise (SE)	vs Output power	Figure 10
		vs Output voltage	Figure 11
P <sub>D</sub>	Total power dissipation (BTL)	vs Total output power	Figure 12
P <sub>D</sub>	Total power dissipation (SE)	vs Total output power	Figure 13
	Crosstalk (BTL)	vs Frequency	Figure 14
	Crosstalk (SE)	vs Frequency	Figure 15
PSRR	Power supply rejection ratio (BTL)	vs Frequency	Figure 16
PSRR	Power supply rejection ratio (SE)	vs Frequency	Figure 17
I <sub>DD</sub>	Supply current (BTL)	vs Total output power	Figure 18
I <sub>DD</sub>	Supply current (SE)	vs Total output power	Figure 19
	Input impedance	vs Gain	Figure 20

### TOTAL HARMONIC DISTORTION + NOISE (BTL) vs FREQUENCY

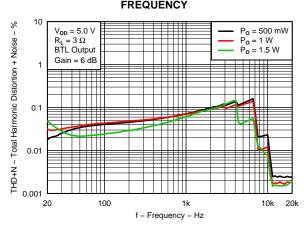


Figure 2.

# TOTAL HARMONIC DISTORTION + NOISE (BTL) vs FREQUENCY

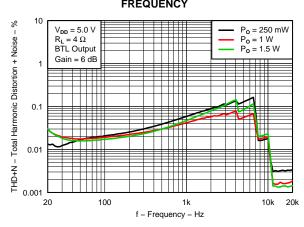


Figure 3.



### TOTAL HARMONIC DISTORTION + NOISE (BTL)

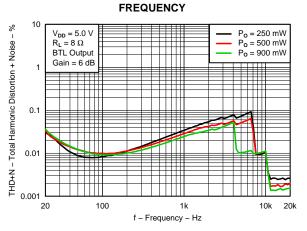


Figure 4.

# TOTAL HARMONIC DISTORTION + NOISE (SE) vs FREQUENCY

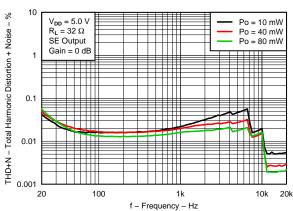


Figure 5.

### TOTAL HARMONIC DISTORTION + NOISE (SE) vs FREQUENCY

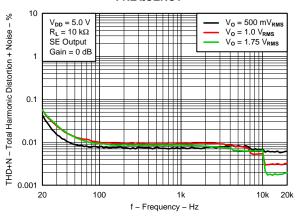


Figure 6.

### TOTAL HARMONIC DISTORTION + NOISE (BTL)

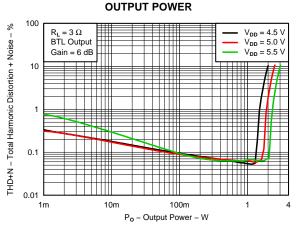


Figure 7.

# TOTAL HARMONIC DISTORTION + NOISE (BTL) vs OUTPUT POWER

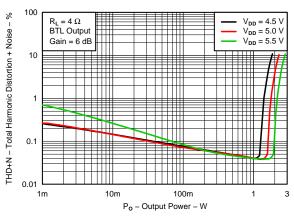


Figure 8.

### TOTAL HARMONIC DISTORTION + NOISE (BTL) vs OUTPUT POWER

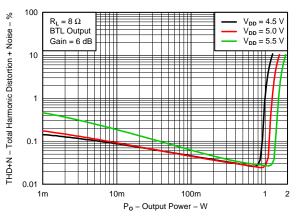


Figure 9.

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### TOTAL HARMONIC DISTORTION + NOISE (SE) vs OUTPUT POWER

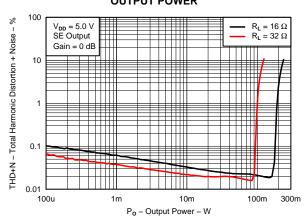


Figure 10.

### TOTAL HARMONIC DISTORTION + NOISE (SE) vs OUTPUT VOLTAGE

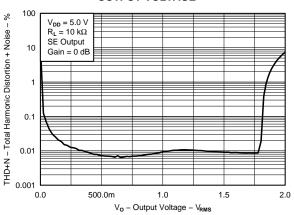


Figure 11.

### TOTAL POWER DISSIPATION (BTL) vs

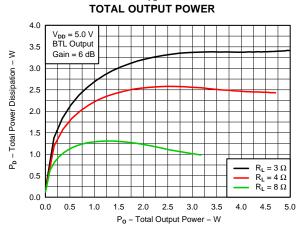


Figure 12.

### TOTAL POWER DISSIPATION (SE) vs

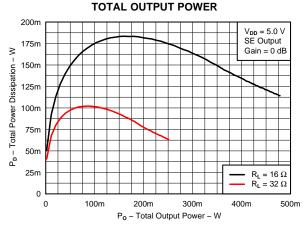


Figure 13.

**CROSSTALK (SE)** 

VS

#### CROSSTALK (BTL) vs FREQUENCY

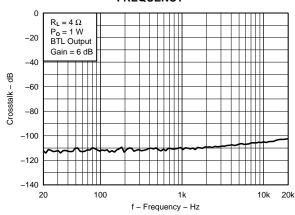
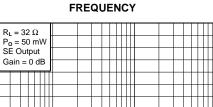


Figure 14.



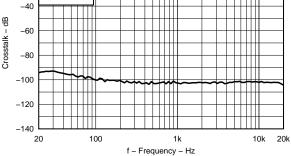


Figure 15.

0

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### POWER SUPPLY REJECTION RATIO (BTL) vs FREQUENCY

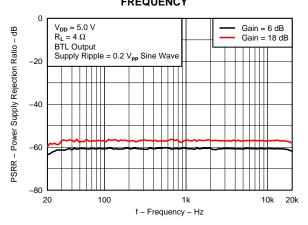


Figure 16.

### POWER SUPPLY REJECTION RATIO (SE) vs FREQUENCY

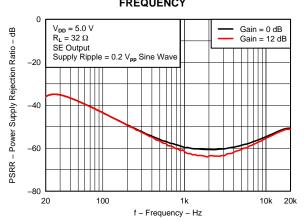


Figure 17.

# SUPPLY CURRENT (BTL) vs TOTAL OUTPUT POWER

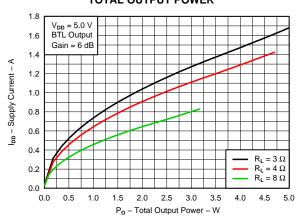


Figure 18.

### SUPPLY CURRENT (SE) vs TOTAL OUTPUT POWER

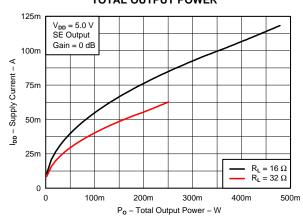


Figure 19.

#### **INPUT IMPEDANCE** vs **GAIN** 120k Differential Single-Ended 100k Input Impedance – Ω 80k 60k 40k 20k $V_{DD} = 5.0 \text{ V}$ $R_L = \text{No Load}$ -35 -30 -25 -15 -10 -5 Gain - dB

Figure 20.

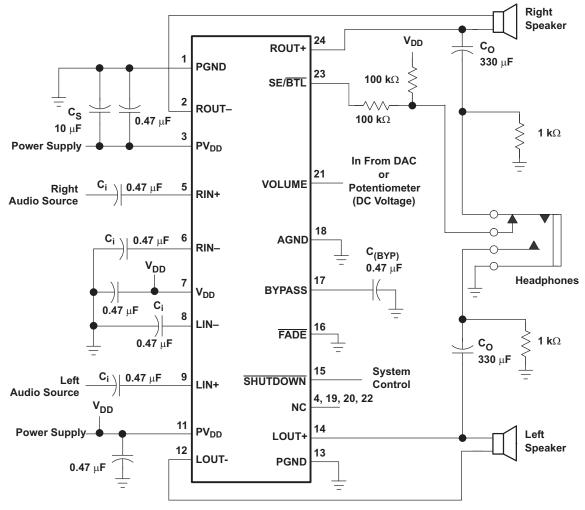
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#### APPLICATION INFORMATION

#### **SELECTION OF COMPONENTS**

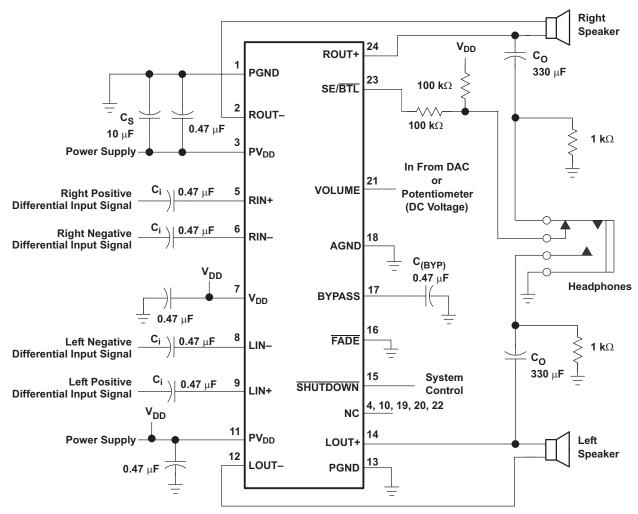
Figure 21 and Figure 22 are schematic diagrams of typical LCD monitor application circuits.



A. A 0.47-µF ceramic capacitor should be placed as close as possible to the IC. For filtering lower-frequency noise signals, a larger electrolytic capacitor of 10 µF or greater should be placed near the audio power amplifier.

Figure 21. Typical TPA6012A4 Application Circuit Using Single-Ended Inputs





A. A 0.1-µF ceramic capacitor should be placed as close as possible to the IC. For filtering lower-frequency noise signals, a larger electrolytic capacitor of 10 µF or greater should be placed near the audio power amplifier.

Figure 22. Typical TPA6012A4 Application Circuit Using Differential Inputs

#### SE/BTL OPERATION

The ability of the TPA6012A4 to easily switch between BTL and SE modes is one of its most important cost saving features. This feature eliminates the requirement for an additional headphone amplifier in applications where internal stereo speakers are driven in BTL mode but external headphone or speakers <u>must</u> be accommodated. Internal to the TPA6012A4, two separate amplifiers drive OUT+ and OUT—. The SE/BTL input controls the operation of the follower amplifier that drives LOUT— and ROUT—. When SE/BTL is held low, the amplifier is on and the TPA6012A4 is in the BTL mode. When SE/BTL is held high, the OUT— amplifiers are in a high output impedance state, which configures the TPA6012A4 as an SE driver from LOUT+ and ROUT+. IDD is reduced by approximately one-third in SE mode. Control of the SE/BTL input can be from a logic-level CMOS source or, more typically, from a resistor divider network as shown in Figure 23. The trip level for the SE/BTL input can be found in the *recommended operating conditions* table.



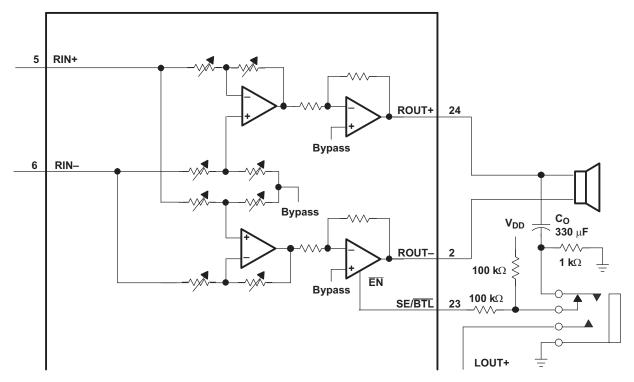


Figure 23. TPA6012A4 Resistor Divider Network Circuit

Using a 1/8-in. (3,5 mm) stereo headphone jack, the control switch is closed when no plug is inserted. When closed the  $100\text{-k}\Omega/1\text{-k}\Omega$  divider pulls the SE/BTL input low. When a plug is inserted, the  $1\text{-k}\Omega$  resistor is disconnected and the SE/BTL input is pulled high. When the input goes high, the OUT– amplifier is shut down causing the speaker to mute (open-circuits the speaker). The OUT+ amplifier then drives through the output capacitor,  $C_o$ , into the headphone jack.

#### **SHUTDOWN MODES**

The TPA6012A4 employs a shutdown mode of operation designed to reduce supply current ( $I_{DD}$ ) to the absolute minimum level during periods of nonuse for power conservation. The SHUTDOWN input terminal should be held high during normal operation when the amplifier is in use. Pulling SHUTDOWN low causes the outputs to mute and the amplifier to enter a low-current state,  $I_{DD}$  = 20  $\mu$ A. SHUTDOWN should never be left unconnected because amplifier operation would be unpredictable.

INPUTS <sup>(1)</sup>		AMPLIFIER STATE
SE/BTL	SHUTDOWN	OUTPUT
X	Low	Mute
Low	High	BTL
High	High	SE

Table 3. SE/BTL and Shutdown Functions

(1) Inputs should never be left unconnected.

#### **FADE OPERATION**

For design flexibility, a fade mode is provided to slowly ramp up the amplifier gain when coming out of shutdown mode and conversely ramp the gain down when going into shutdown. This mode provides a smooth transition between the active and shutdown states and virtually eliminates any pops or clicks on the outputs.

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When the  $\overline{\text{FADE}}$  input is a logic low, the device is placed into fade-on mode. A logic high on this pin places the amplifier in the fade-off mode. The voltage trip levels for a logic low  $(V_{IL})$  or logic high  $(V_{IH})$  can be found in the recommended operating conditions table.

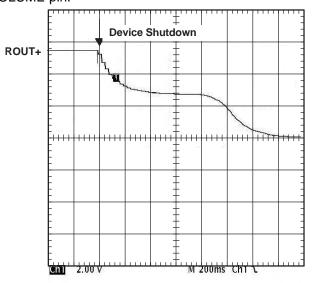
When a logic low is applied to the FADE pin and a logic low is then applied on the SHUTDOWN pin, the channel gain steps down from gain step to gain step at a rate of two clock cycles per step. With a nominal internal clock frequency of 58 Hz, this equates to 34 ms (1/29 Hz) per step. The gain steps down until the lowest gain step is reached. The time it takes to reach this step depends on the gain setting prior to placing the device in shutdown. For example, if the amplifier is in the highest gain mode of 18 dB, the time it takes to ramp down the channel gain is 1.05 seconds. This number is calculated by taking the number of steps to reach the lowest gain from the highest gain, or 31 steps, and multiplying by the time per step, or 34 ms.

After the channel gain is stepped down to the lowest gain, the amplifier begins discharging the bypass capacitor from the nominal voltage of  $V_{DD}/2$  to ground. This time is dependent on the value of the bypass capacitor. For a 0.47- $\mu$ F capacitor that is used in the application diagram in Figure 21, the time is approximately 500 ms. This time scales linearly with the value of bypass capacitor. For example, if a 1- $\mu$ F capacitor is used for bypass, the time period to discharge the capacitor to ground is twice that of the 0.47- $\mu$ F capacitor, or 1 second. Figure 22 below is a waveform captured at the output during the shutdown sequence when the part is in fade-on mode. The gain is set to the highest level and the output is at  $V_{DD}$  when the amplifier is shut down.

When a logic high is placed on the  $\overline{SHUTDOWN}$  pin and the  $\overline{FADE}$  pin is still held low, the device begins the start-up process. The bypass capacitor will begin charging. Once the bypass voltage reaches the final value of  $V_{DD}/2$ , the gain increases from the lowest gain level to the gain level set by the dc voltage applied to the VOLUME pin.

In the fade-off mode, the output of the amplifier immediately drops to  $V_{DD}/2$  and the bypass capacitor begins a smooth discharge to ground. When shutdown is released, the bypass capacitor charges up to  $V_{DD}/2$  and the channel gain returns immediately to the value on the VOLUME terminal. Figure 23 below is a waveform captured at the output during the shutdown sequence when the part is in the fade-off mode. The gain is set to the highest level, and the output is at  $V_{DD}$  when the amplifier is shut down.

The power-up sequence is different from the shutdown sequence and the voltage on the FADE pin does not change the power-up sequence. Upon a power-up condition, the TPA6012A4 begins in the lowest gain setting and steps up every 2 clock cycles until the final value is reached as determined by the dc voltage applied to the VOLUME pin.



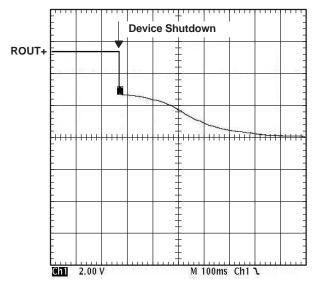


Figure 24. Shutdown Sequence in the Fade-on Mode

Figure 25. Shutdown Sequence in the Fade-off Mode

#### **VOLUME OPERATION**

The VOLUME pin controls the BTL volume when driving speakers, and the SE volume when driving headphones. This pin is controlled with a dc voltage, which should not exceed  $V_{DD}$ .

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The output volume increases in discrete steps as the dc voltage increases and decreases in discrete steps as the dc voltage decreases. There are a total of 32 discrete gain steps of the amplifier and range from –85 dB to 18 dB for BTL operation and –85 dB to 12 dB for SE operation.

Table 1 and Table 2 show a range of voltages for each gain step. There is a gap in the voltage between each gain step. This gap represents the hysteresis about each trip point in the internal comparator. The hysteresis ensures that the gain control is monotonic and does not oscillate from one gain step to another. If a potentiometer is used to adjust the voltage on the control terminals, the gain increases as the potentiometer is turned in one direction and decreases as it is turned back the other direction. The trip point, where the gain actually changes, is different depending on whether the voltage is increased or decreased as a result of the hysteresis about each trip point. The gaps in Table 1 and Table 2 can also be thought of as indeterminate states where the gain could be in the next higher gain step or the lower gain step depending on the direction the voltage is changing. If using a DAC to control the volume, set the voltage in the middle of each range to ensure that the desired gain is achieved.

A pictorial representation of the typical volume control can be found in Figure 26. The graph focuses on three gain steps with the trip points defined in Table 1 for BTL gain. The dotted line represents the hysteresis about each gain step.

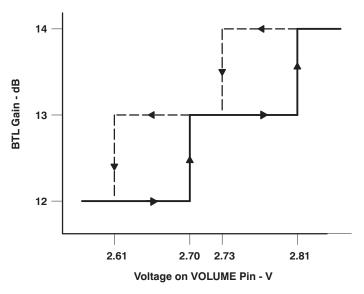


Figure 26. DC Volume Control Operation

#### **INPUT RESISTANCE**

Each gain setting is achieved by varying the input resistance of the amplifier, which can range from its smallest value to over six times that value. As a result, if a single capacitor is used in the input high-pass filter, the -3 dB or cutoff frequency also changes by over six times.

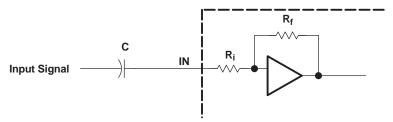


Figure 27. Resistor on Input for Cut-Off Frequency

The input resistance at each gain setting is given in Figure 20.

The -3-dB frequency can be calculated using Equation 1.

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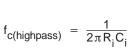


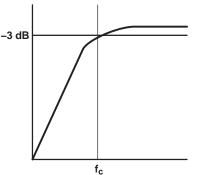
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$$f_{-3 \text{ dB}} = \frac{1}{2\pi \text{ CR}_{i}} \tag{1}$$

#### INPUT CAPACITOR, C1

In the typical application an input capacitor  $C_I$  is required to allow the amplifier to bias the input signal to the proper dc level for optimum operation. In this case,  $C_I$  and the input impedance of the amplifier  $R_I$  form a high-pass filter with the corner frequency determined in Equation 2.





(2)

The value of  $C_l$  is important to consider as it directly affects the bass (low frequency) performance of the circuit. Consider the example where  $R_l$  is 70 k $\Omega$  and the specification calls for a flat-bass response down to 40 Hz. Equation 2 is reconfigured as Equation 3.

$$C_{i} = \frac{1}{2\pi R_{i} f_{c}} \tag{3}$$

In this example,  $C_1$  is 56.8 nF, so one would likely choose a value in the range of 56 nF to 1  $\mu$ F. A further consideration for this capacitor is the leakage path from the input source through the input network  $C_1$  and the feedback network to the load. This leakage current creates a dc offset voltage at the input to the amplifier that reduces useful headroom, especially in high gain applications. For this reason, a low-leakage tantalum or ceramic capacitor is the best choice. When polarized capacitors are used, the positive side of the capacitor should face the amplifier input in most applications as the dc level there is held at  $V_{DD}/2$ , which is likely higher than the source dc level. Note that it is important to confirm the capacitor polarity in the application.

#### POWER SUPPLY DECOUPLING, C(S)

The TPA6012A4 is a high-performance CMOS audio amplifier that requires adequate power supply decoupling to ensure the output total harmonic distortion (THD) is as low as possible. Power supply decoupling also prevents oscillations for long lead lengths between the amplifier and the speaker. The optimum decoupling is achieved by using two capacitors of different types that target different types of noise on the power supply leads. For higher frequency transients, spikes, or digital hash on the line, a good low equivalent-series-resistance (ESR) ceramic capacitor, typically 0.1  $\mu$ F placed as close as possible to the device  $V_{DD}$  lead, works best. For filtering lower-frequency noise signals, a larger aluminum electrolytic capacitor of 10  $\mu$ F or greater placed near the audio power amplifier is recommended.

#### MIDRAIL BYPASS CAPACITOR, C(BYP)

The midrail bypass capacitor  $C_{(BYP)}$  is the most critical capacitor and serves several important functions. During start-up or recovery from shutdown mode,  $C_{(BYP)}$  determines the rate at which the amplifier starts up. The second function is to reduce noise produced by the power supply caused by coupling into the output drive signal. This noise is from the midrail generation circuit internal to the amplifier, which appears as degraded PSRR and THD+N.

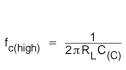
Bypass capacitor  $C_{(BYP)}$  values of 0.47- $\mu F$  to 1- $\mu F$  ceramic or tantalum low-ESR capacitors are recommended for the best THD and noise performance. For the best pop performance, choose a value for  $C_{(BYP)}$  that is equal to or greater than the value chosen for  $C_{\rm l}$ . This ensures that the input capacitors are charged up to the midrail voltage before  $C_{(BYP)}$  is fully charged to the midrail voltage.

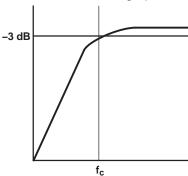
### TEXAS INSTRUMENTS

(4)

#### OUTPUT COUPLING CAPACITOR, C(C)

In the typical single-supply SE configuration, an output coupling capacitor  $C_{(C)}$  is required to block the dc bias at the output of the amplifier, thus preventing dc currents in the load. As with the input coupling capacitor, the output coupling capacitor and impedance of the load form a high-pass filter governed by Equation 4.





The main disadvantage, from a performance standpoint, is the load impedances are typically small, which drives the low-frequency corner higher, degrading the bass response. Large values of  $C_{(C)}$  are required to pass low frequencies into the load. Consider the example where a  $C_{(C)}$  of 330  $\mu F$  is chosen and loads vary from 4  $\Omega$ , 8  $\Omega$ , 32  $\Omega$ , 10 k $\Omega$ , and 47 k $\Omega$ . Table 4 summarizes the frequency response characteristics of each configuration.

Table 4. Common Load Impedances vs Low Frequency
Output Characteristics in SE Mode

R <sub>L</sub>	C <sub>(C)</sub>	LOWEST FREQUENCY
4 Ω	330 µF	120 Hz
8 Ω	330 µF	60 Hz
32 Ω	330 µF	15 Hz
10,000 Ω	330 µF	0.05 Hz
47,000 Ω	330 µF	0.01 Hz

As Table 4 indicates, most of the bass response is attenuated into a 4- $\Omega$  load, an 8- $\Omega$  load is adequate, headphone response is good, and drive into line level inputs (a home stereo for example) is exceptional.

#### **USING LOW-ESR CAPACITORS**

Low-ESR capacitors are recommended throughout this applications section. A real (as opposed to ideal) capacitor can be modeled simply as a resistor in series with an ideal capacitor. The voltage drop across this resistor minimizes the beneficial effects of the capacitor in the circuit. The lower the equivalent value of this resistance, the more the real capacitor behaves like an ideal capacitor.

#### **BRIDGE-TIED LOAD vs SINGLE-ENDED LOAD**

Figure 28 shows a Class-AB audio power amplifier (APA) in a BTL configuration. The TPA6012A4 BTL amplifier consists of two Class-AB amplifiers driving both ends of the load. There are several potential benefits to this differential drive configuration, but, initially consider power to the load. The differential drive to the speaker means that as one side is slewing up, the other side is slewing down, and vice versa. This in effect doubles the voltage swing on the load as compared to a ground referenced load. Plugging 2 x  $V_{O(PP)}$  into the power equation, where voltage is squared, yields 4x the output power from the same supply rail and load impedance (see Equation 5).

(5)



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$$V_{(rms)} = \frac{V_{O(PP)}}{2\sqrt{2}}$$
  
Power =  $\frac{V_{(rms)}^2}{R_L}$ 

 $V_{DD}$ 

Figure 28. Bridge-Tied Load Configuration

In a typical computer sound channel operating at 5 V, bridging raises the power into an 8-Ω speaker from a singled-ended (SE, ground reference) limit of 250 mW to 1 W. In sound power that is a 6-dB improvement, which is loudness that can be heard. In addition to increased power there are frequency response concerns. Consider the single-supply SE configuration shown in Figure 29. A coupling capacitor is required to block the dc offset voltage from reaching the load. These capacitors can be quite large (approximately 33 μF to 1000 μF), so they tend to be expensive, heavy, occupy valuable PCB area, and have the additional drawback of limiting low-frequency performance of the system. This frequency limiting effect is due to the high-pass filter network created with the speaker impedance and the coupling capacitance and is calculated with Equation 6.

$$f_{(c)} = \frac{1}{2\pi R_L C_C} \tag{6}$$

For example, a 68-μF capacitor with an 8-Ω speaker would attenuate low frequencies below 293 Hz. The BTL configuration cancels the dc offsets, which eliminates the need for the blocking capacitors. Low-frequency performance is then limited only by the input network and speaker response. Cost and PCB space are also minimized by eliminating the bulky coupling capacitor.

Product Folder Link(s): TPA6012A4

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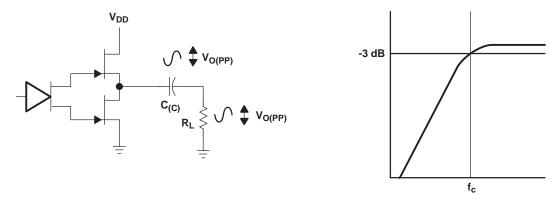


Figure 29. Single-Ended Configuration and Frequency Response

Increasing power to the load does carry a penalty of increased internal power dissipation. The increased dissipation is understandable considering that the BTL configuration produces 4x the output power of the SE configuration. Internal dissipation versus output power is discussed further in the *crest factor and thermal considerations* section.

#### SINGLE-ENDED OPERATION

In SE mode (see Figure 29), the load is driven from the primary amplifier output for each channel (OUT+).

The amplifier switches single-ended operation when the SE/BTL terminal is held high. This puts the negative outputs in a high-impedance state, and effectively reduces the amplifier's gain by 6 dB.

#### BTL AMPLIFIER EFFICIENCY

Class-AB amplifiers are inefficient. The primary cause of these inefficiencies is voltage drop across the output stage transistors. There are two components of the internal voltage drop. One is the headroom or dc voltage drop that varies inversely to output power. The second component is due to the sinewave nature of the output. The total voltage drop can be calculated by subtracting the RMS value of the output voltage from  $V_{DD}$ . The internal voltage drop multiplied by the RMS value of the supply current ( $I_{DD}$ rms) determines the internal power dissipation of the amplifier.

An easy-to-use equation to calculate efficiency starts out as being equal to the ratio of power from the power supply to the power delivered to the load. To accurately calculate the RMS and average values of power in the load and in the amplifier, the current and voltage waveform shapes must first be understood (see Figure 30).

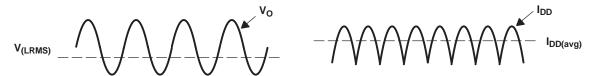


Figure 30. Voltage and Current Waveforms for BTL Amplifiers

Although the voltages and currents for SE and BTL are sinusoidal in the load, currents from the supply are very different between SE and BTL configurations. In an SE application the current waveform is a half-wave rectified shape, whereas in BTL it is a full-wave rectified waveform. This means RMS conversion factors are different. Keep in mind that for most of the waveform both the push and pull transistors are not on at the same time, which supports the fact that each amplifier in the BTL device only draws current from the supply for half the waveform. The following equations are the basis for calculating amplifier efficiency.

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Efficiency of a BTL amplifier 
$$= \frac{P_L}{P_{SUP}}$$

Where:

$$P_L = \frac{V_L rms^2}{R_L}$$
, and  $V_{LRMS} = \frac{V_P}{\sqrt{2}}$ , therefore,  $P_L = \frac{V_P^2}{2R_L}$ 

and 
$$P_{SUP} = V_{DD}I_{DD}avg$$
 and  $I_{DD}avg = \frac{1}{\pi}\int_0^{\pi} \frac{V_P}{R_L} \sin(t) dt = \frac{1}{\pi} \times \frac{V_P}{R_L} \left[\cos(t)\right]_0^{\pi} = \frac{2V_P}{\pi R_L}$ 

$$P_{SUP} = \frac{2 V_{DD} V_{P}}{\pi R_{L}}$$
 (7)

substituting P<sub>L</sub> and P<sub>SUP</sub> into Equation 7,

Efficiency of a BTL amplifier 
$$=\frac{\frac{V_P^2}{2 R_L}}{\frac{2 V_{DD} V_P}{\pi R_I}} = \frac{\pi V_P}{4 V_{DD}}$$

Where:

$$V_P = \sqrt{2 P_I R_I}$$

Therefore, 
$$\eta_{BTL} \ = \ \frac{\pi \ \sqrt{2 \ P_L \ R_L}}{4 \ V_{DD}}$$

P<sub>I</sub> = Power delivered to load P<sub>SUP</sub> = Power drawn from power supply V<sub>LRMS</sub> = RMS voltage on BTL load  $R_1$  = Load resistance

V<sub>P</sub> = Peak voltage on BTL load I<sub>DD</sub>avg = Average current drawn from the power supply V<sub>DD</sub> = Power supply voltage η<sub>BTL</sub> = Efficiency of a BTL amplifier

Table 5 employs Equation 8 to calculate efficiencies for four different output power levels. Note that the efficiency of the amplifier is quite low for lower power levels and rises sharply as power to the load is increased resulting in a nearly flat internal power dissipation over the normal operating range. Note that the internal dissipation at full output power is less than in the half power range. Calculating the efficiency for a specific system is the key to proper power supply design. For a stereo 1-W audio system with 8-Ω loads and a 5-V supply, we get an

Table 5. Efficiency vs Output Power in 5-V, 8-Ω BTL Systems

efficiency of 0.628. Total output power is 2-W. Thus the maximum draw on the power supply is almost 3.25 W.

OUTPUT POWER (W)	EFFICIENCY (%)	PEAK VOLTAGE (V)	INTERNAL DISSIPATION (W)
0.25	31.4	2.00	0.55
0.50	44.4	2.83	0.62
1.00	62.8	4.00	0.59
1.25	70.2	4.47 <sup>(1)</sup>	0.53

(1) High peak voltages cause the THD to increase.

(8)



A final point to remember about Class-AB amplifiers (either SE or BTL) is how to manipulate the terms in the efficiency equation to utmost advantage when possible. Note that in equation 8,  $V_{DD}$  is in the denominator. This indicates that as  $V_{DD}$  goes down, efficiency goes up.

#### **CREST FACTOR AND THERMAL CONSIDERATIONS**

Class-AB power amplifiers dissipate a significant amount of heat in the package under normal operating conditions. A typical music CD requires 12 dB to 15 dB of dynamic range, or headroom above the average power output, to pass the loudest portions of the signal without distortion. In other words, music typically has a crest factor between 12 dB and 15 dB. When determining the optimal ambient operating temperature, the internal dissipated power at the average output power level must be used. From the data sheet graph (Figure 5.), one can see that when the TPA6012A4 is operating from a 5-V supply into a  $4-\Omega$  speaker at 1% THD, that output power is 1.5-W so maximum instantaneous output power is 3-W. Use equation 9 to convert watts to dB.

$$P_{dB} = 10Log \frac{P_W}{P_{ref}} = 10Log \frac{3W}{1W} = 5 dB$$
 (9)

Subtracting the headroom restriction to obtain the average listening level without distortion yields:

5  dB - 15  dB = -10  dB	(15-dB crest factor)
5  dB - 12  dB = -7  dB	(12-dB crest factor)
5  dB - 9  dB = -4  dB	(9-dB crest factor)
5 dB - 6 dB = -1 dB	(6-dB crest factor)
5 dB - 3 dB = 2 dB	(3-dB crest factor)

To convert dB back into watts use equation 10.

This is valuable information to consider when attempting to estimate the heat dissipation requirements for the amplifier system. Comparing the worst case, which is 1.5 W of continuous power output with a 3-dB crest factor, against 12-dB and 15-dB applications significantly affects maximum ambient temperature ratings for the system. Using the power dissipation curves for a 5-V,  $4-\Omega$  system, the internal dissipation in the TPA6012A4 and maximum ambient temperatures is shown in Table 6.



Table 6. TPA6012A4 Power Rating, 5-V, 4-Ω Stereo

PEAK OUTPUT POWER (W)	AVERAGE OUTPUT POWER	POWER DISSIPATION (W/Channel)	MAXIMUM AMBIENT TEMPERATURE
3	1500 mW (3 dB)	1.26	37°C
3	750 mW (6 dB)	1.20	42°C
3	380 mW (9 dB)	1.00	59°C
3	190 mW (12 dB)	0.79	79°C
3	95 mW (15 dB)	0.60	96°C <sup>(1)</sup>
3	48 mW (18 dB)	0.44	110°C <sup>(1)</sup>

(1) Package limited to 85°C ambient.

Table 7. TPA6012A4 Power Rating, 5-V, 8-Ω Stereo

PEAK OUTPUT POWER (W)	AVERAGE OUTPUT POWER	POWER DISSIPATION (W/Channel)	MAXIMUM AMBIENT TEMPERATURE
2.2	1100 mW (3-dB crest factor)	0.57	99°C <sup>(1)</sup>
2.2	876 mW (4-dB crest factor)	0.61	95°C <sup>(1)</sup>
2.2	440 mW (7-dB crest factor)	0.62	95°C <sup>(1)</sup>
2.2	220 mW (10-dB crest factor)	0.53	103°C <sup>(1)</sup>

#### (1) Package limited to 85°C ambient.

The maximum dissipated power  $(P_{D(max)})$  is reached at a much lower output power level for an 8- $\Omega$  load than for a 4- $\Omega$  load. As a result, this simple formula for calculating  $P_{D(max)}$  may be used for an 8- $\Omega$  application.

$$P_{D(max)} = \frac{2V_{DD}^2}{\pi^2 R_L} \tag{11}$$

However, in the case of a 4- $\Omega$  load, the  $P_{D(max)}$  occurs at a point well above the normal operating power level. The amplifier may therefore be operated at a higher ambient temperature than required by the  $P_{D(max)}$  formula for a 4- $\Omega$  load.

The maximum ambient temperature depends on the heat-sinking ability of the PCB system. The derating factor for the N package with an external heatsink is shown in the *dissipation rating table*. Use Equation 12 to convert this to  $\theta_{\text{IA}}$ .

$$\theta_{JA} = \frac{1}{\text{Derating Factor}} = \frac{1}{0.0222} = 45^{\circ}\text{C/W}$$
(12)

To calculate maximum ambient temperatures, first consider that the numbers from the dissipation graphs are per channel, so the dissipated power needs to be doubled for two channel operation. Given  $\theta_{JA}$ , the maximum allowable junction temperature, and the total internal dissipation, the maximum ambient temperature can be calculated using Equation 13. The maximum recommended junction temperature for the TPA6012A4 is 150°C. The internal dissipation figures are taken from the Power Dissipation vs Output Power graphs.

$$T_A Max = T_J Max - \theta_{JA} P_D$$
  
= 150 - 45 (0.6 x 2) = 96°C(15-dB crest factor) (13)

#### NOTE

Internal dissipation of 0.6 W is estimated for a 2-W system with 15-dB crest factor per channel.

Table 6 and Table 7 show that some applications require no airflow to keep junction temperatures in the specified range. The TPA6012A4 is designed with thermal protection that turns the device off when the junction temperature surpasses 150°C to prevent damage to the IC. Table 6 and Table 7 were calculated for maximum listening volume without distortion. When the output level is reduced the numbers in the table change significantly. Also, using  $8-\Omega$  speakers increases the thermal performance by increasing amplifier efficiency.

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#### PACKAGING INFORMATION

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/	MSL rating/	Op temp (°C)	Part marking
	(1)	(2)			(3)	Ball material	Peak reflow		(6)
						(4)	(5)		
TPA6012A4PWP	Active	Production	HTSSOP (PWP)   24	60   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	TPA6012
TPA6012A4PWP.B	Active	Production	HTSSOP (PWP)   24	60   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	TPA6012
TPA6012A4PWPR	Active	Production	HTSSOP (PWP)   24	2000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	TPA6012
TPA6012A4PWPR.B	Active	Production	HTSSOP (PWP)   24	2000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	TPA6012

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

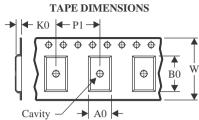
<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

#### **PACKAGE MATERIALS INFORMATION**

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#### TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPA6012A4PWPR	HTSSOP	PWP	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1

**PACKAGE MATERIALS INFORMATION** 

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#### \*All dimensions are nominal

Device	Device Package Type		Pins	SPQ	Length (mm)	Width (mm)	Height (mm)	
TPA6012A4PWPR	HTSSOP	PWP	24	2000	353.0	353.0	32.0	

#### **PACKAGE MATERIALS INFORMATION**

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#### **TUBE**



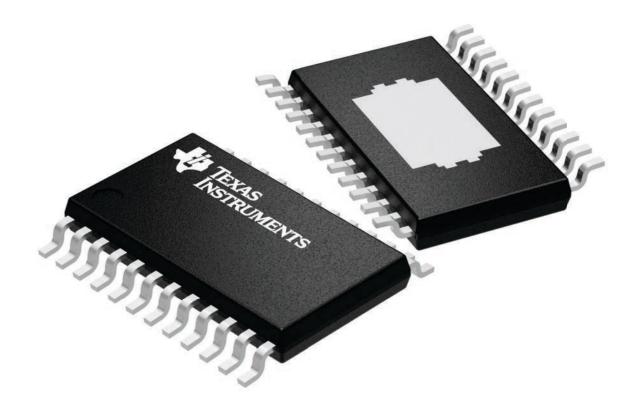
#### \*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
TPA6012A4PWP	PWP	HTSSOP	24	60	530	10.2	3600	3.5
TPA6012A4PWP.B	PWP	HTSSOP	24	60	530	10.2	3600	3.5

4.4 x 7.6, 0.65 mm pitch

PLASTIC SMALL OUTLINE

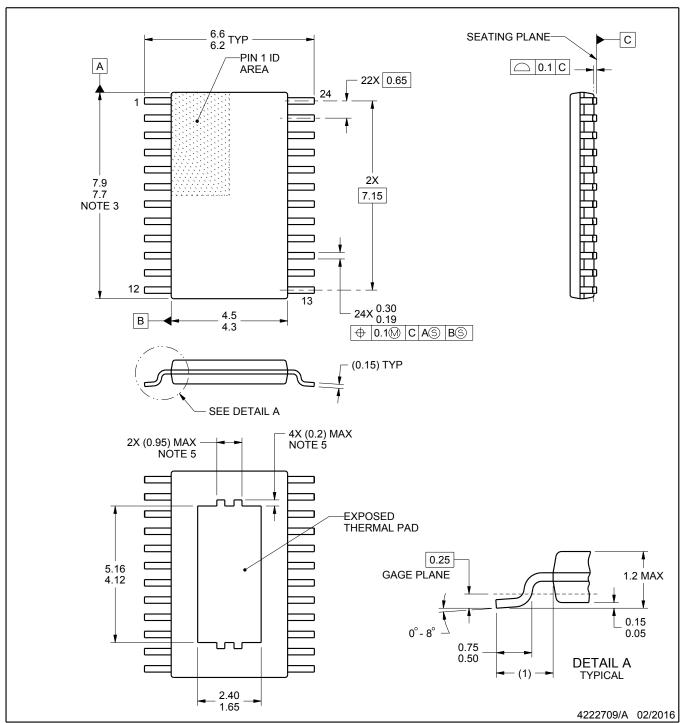
This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



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#### PowerPAD™ TSSOP - 1.2 mm max height

PLASTIC SMALL OUTLINE



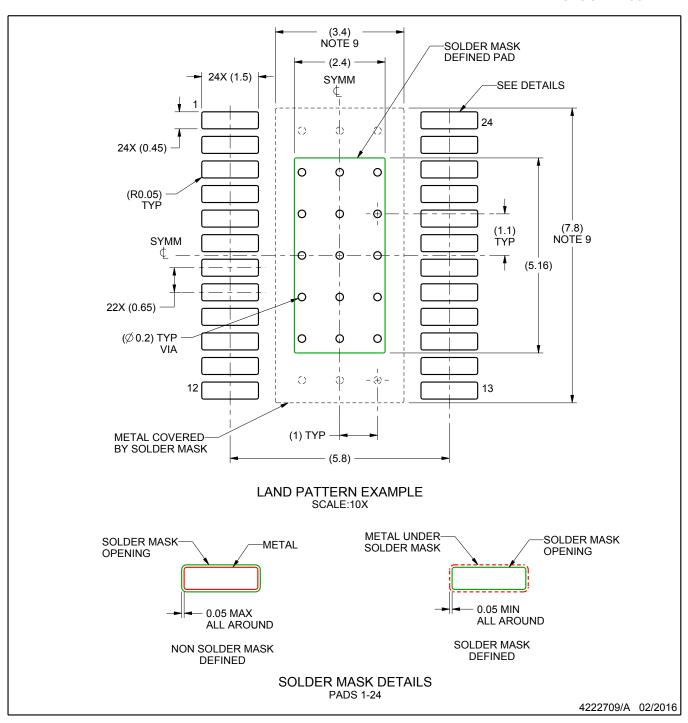
#### NOTES:

PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
- exceed 0.15 mm per side.
  4. Reference JEDEC registration MO-153.
- 5. Features may not be present and may vary.



PLASTIC SMALL OUTLINE

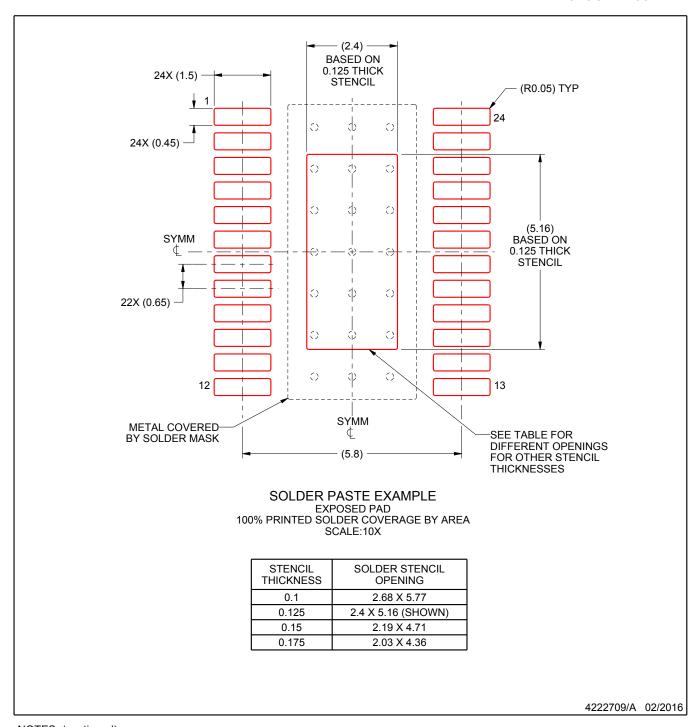


NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature numbers SLMA002 (www.ti.com/lit/slma002) and SLMA004 (www.ti.com/lit/slma004).
- 9. Size of metal pad may vary due to creepage requirement.



PLASTIC SMALL OUTLINE



NOTES: (continued)

- 10. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 11. Board assembly site may have different recommendations for stencil design.



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