



CC2541-Q1 SimpleLink™ Bluetooth® Low Energy Wireless MCU for Automotive

1 Device Overview

1.1 Features

- RF
 - 2.4-GHz *Bluetooth* Low Energy Compliant and Proprietary RF Wireless MCU
 - Supports Data Rates of 250 kbps, 500 kbps, 1 Mbps, and 2 Mbps
 - Excellent Link Budget, Enabling Long-Range Applications Without External Front End
 - Programmable Output Power up to 0 dBm
 - Excellent Receiver Sensitivity (–94 dBm at 1 Mbps), Selectivity, and Blocking Performance
 - Suitable for Systems Targeting Compliance With Worldwide Radio Frequency Regulations: ETSI EN 300 328 and EN 300 440 Class 2 (Europe), FCC CFR47 Part 15 (US), and ARIB STD-T66 (Japan)
- Layout
 - Few External Components
 - 6 mm × 6 mm QFN-40 Package
- Low Power
 - Active-Mode RX Down to: 18.3 mA
 - Active-Mode TX (0 dBm): 18.6 mA
 - Power Mode 1 (4-μs Wake-Up): 270 μA
 - Power Mode 2 (Sleep Timer On): 1 μA
 - Power Mode 3 (External Interrupts): 0.5 μA
 - Wide Supply-Voltage Range (2 V to 3.6 V)
- Microcontroller
 - High-Performance and Low-Power 8051 Microcontroller Core With Code Prefetch
 - 256KB In-System Programmable Flash
 - 8KB of RAM With Retention in All Power Modes
 - Hardware Debug Support
 - Extensive Baseband Automation, Including Auto-Acknowledgment and Address Decoding
 - Retention of All Relevant Registers in All Power Modes
- Peripherals
 - Powerful Five-Channel DMA
 - IR Generation Circuitry
 - General-Purpose Timers (One 16-Bit, Two 8-Bit)
 - 32-kHz Sleep Timer With Capture
 - Accurate Digital RSSI Support
 - Battery Monitor and Temperature Sensor
 - 12-Bit ADC With Eight Channels and Configurable Resolution
 - AES Security Coprocessor
 - Two Powerful USARTs With Support for Several Serial Protocols
 - 23 General-Purpose I/O Pins (21 × 4 mA, 2 × 20 mA)
 - I²C interface
 - 2 I/O Pins Have LED Driving Capabilities
 - Watchdog Timer
 - Integrated High-Performance Comparator
- Development Tools
 - CC2541 Evaluation Module
 - SmartRF™ Software
 - IAR Embedded Workbench™ Available
- *Bluetooth* v4.0 Compliant Protocol Stack for Single-Mode BLE Solution
 - Complete Power-Optimized Stack, Including Controller and Host
 - GAP – Central, Peripheral, Observer, or Broadcaster (Including Combination Roles)
 - ATT / GATT – Client and Server
 - SMP – AES-128 Encryption and Decryption
 - L2CAP
 - Sample Applications and Profiles
 - Generic Applications for GAP Central and Peripheral Roles
 - Proximity, Accelerometer, Simple Keys, and Battery GATT Services
 - More Applications Supported in [BLE Software Stack](#)
 - Multiple Configuration Options
 - Single-Chip Configuration, Allowing Applications to Run on CC2541-Q1
 - Network Processor Interface for Applications Running on an External Microcontroller
 - BTool–Windows PC Application for Evaluation, Development, and Test
 - Over the Air Update Capable



1.2 Applications

- 2.4-GHz *Bluetooth* Low-Energy Systems
- Proprietary 2.4-GHz Systems
- Keyless Entry (Passive and Remote)
- Tire Pressure Monitoring
- Proximity Sensing
- Interface and Control
- Diagnostics and Maintenance
- Cable Replacement
- Sensor Nodes
- Infotainment and Media
- Smart Phone Connectivity
- Beacons

1.3 Description

The CC2541-Q1 is a power-optimized true Wireless MCU solution for both *Bluetooth* low energy and proprietary 2.4-GHz applications. This device enables the building of robust network nodes with low total bill-of-material costs. The CC2541-Q1 combines the excellent performance of a leading RF transceiver with an industry-standard enhanced 8051 MCU, in-system programmable flash memory, 8KB of RAM, and many other powerful supporting features and peripherals. The CC2541-Q1 is highly suited for systems in which ultralow power consumption is required, which is specified by various operating modes. Short transition times between operating modes further enable low power consumption.

The CC2541-Q1 comes in a 6 mm x 6 mm QFN40 package.

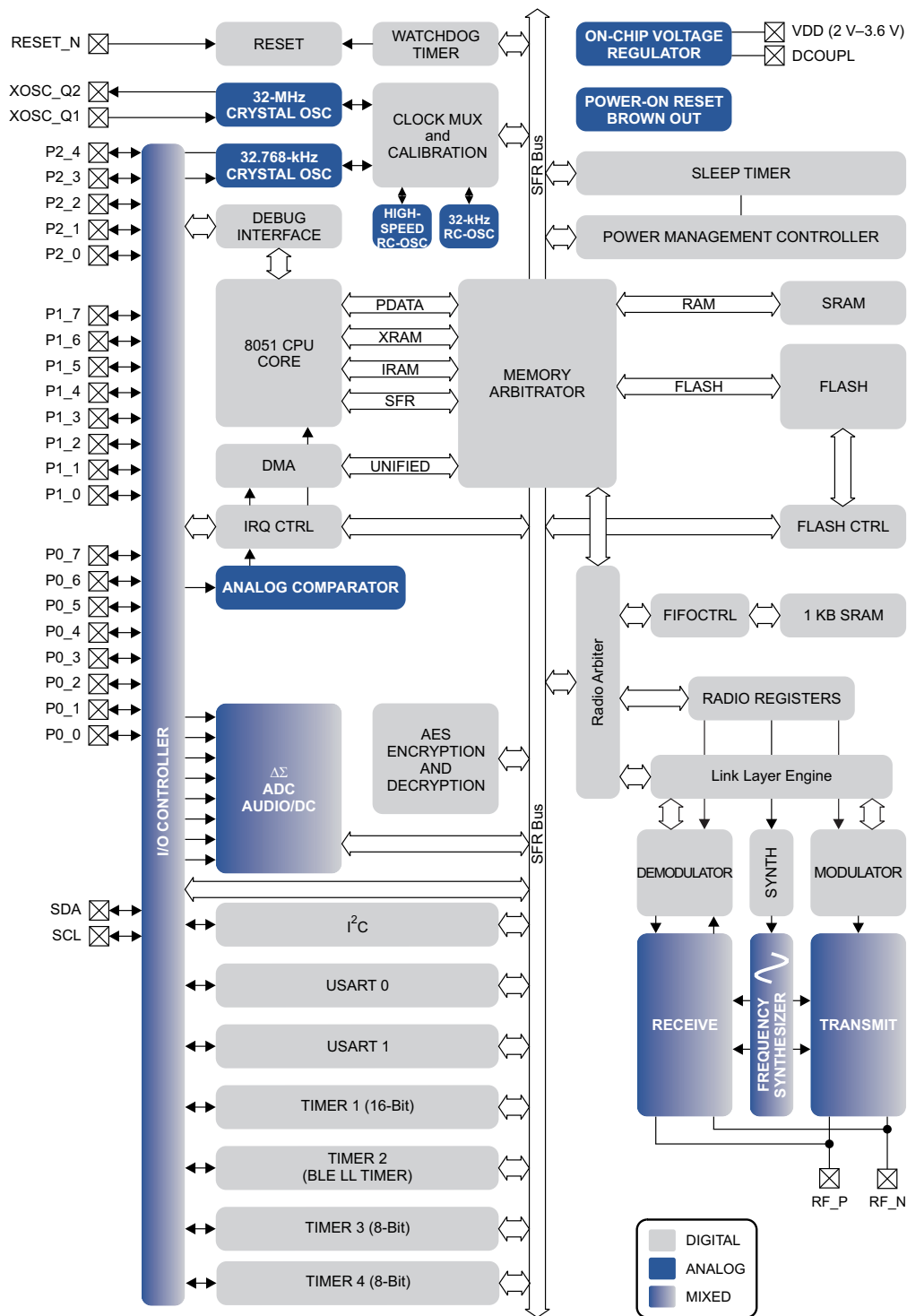
Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE
CC2541F256TRHARQ1	RHA (40)	6.00 mm × 6.00 mm
CC2541F256TRHATQ1	RHA (40)	6.00 mm × 6.00 mm

(1) For more information, see [Section 8](#), Mechanical Packaging and Orderable Information.

1.4 Functional Block Diagram

Figure 1-1 shows the CC2541-Q1 block diagram.



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Figure 1-1. Block Diagram

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2 Revision History

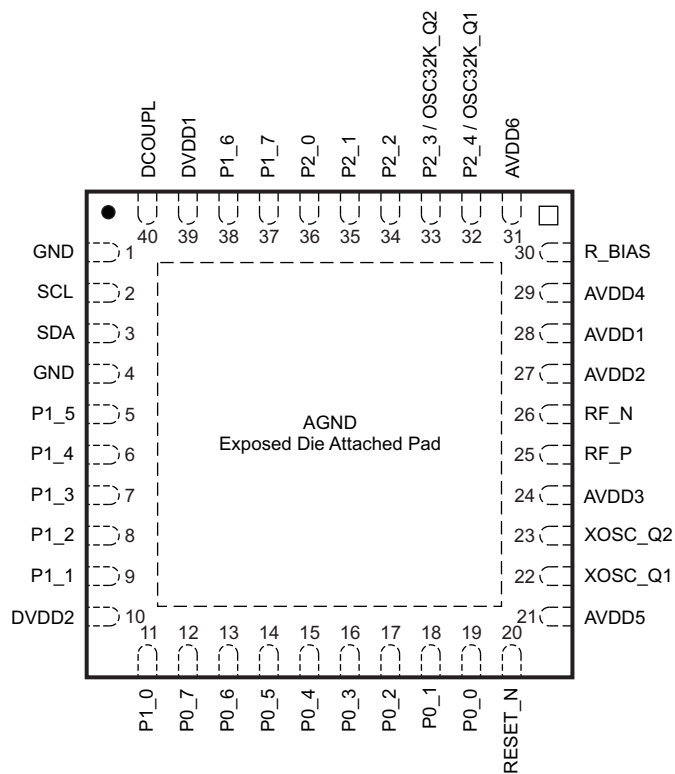
NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

DATE	REVISION	NOTES
June 2014	*	Initial release.

3 Terminal Configuration and Functions

The CC2541-Q1 pinout is shown in [Figure 3-1](#) and a short description of the pins follows.

3.1 Pin Diagram



P0076-14

NOTE: The exposed ground pad must be connected to a solid ground plane, as this is the ground connection for the chip.

Figure 3-1. RHA PACKAGE (TOP VIEW)

3.2 Pin Descriptions

Table 3-1. Pin Descriptions

PINS		TYPE	DESCRIPTION
NAME	NO.		
AVDD1	28	Power (analog)	2-V–3.6-V analog power-supply connection
AVDD2	27	Power (analog)	2-V–3.6-V analog power-supply connection
AVDD3	24	Power (analog)	2-V–3.6-V analog power-supply connection
AVDD4	29	Power (analog)	2-V–3.6-V analog power-supply connection
AVDD5	21	Power (analog)	2-V–3.6-V analog power-supply connection
AVDD6	31	Power (analog)	2-V–3.6-V analog power-supply connection
DCOUPPL	40	Power (digital)	1.8-V digital power-supply decoupling. Do not use for supplying external circuits.
DVDD1	39	Power (digital)	2-V–3.6-V digital power-supply connection
DVDD2	10	Power (digital)	2-V–3.6-V digital power-supply connection
GND	1	Ground pin	Connect to GND
GND	—	Ground	The ground pad must be connected to a solid ground plane.
GND	4	Ground pin	Connect to GND
P0_0	19	Digital I/O	Port 0.0
P0_1	18	Digital I/O	Port 0.1
P0_2	17	Digital I/O	Port 0.2
P0_3	16	Digital I/O	Port 0.3
P0_4	15	Digital I/O	Port 0.4
P0_5	14	Digital I/O	Port 0.5
P0_6	13	Digital I/O	Port 0.6
P0_7	12	Digital I/O	Port 0.7
P1_0	11	Digital I/O	Port 1.0 – 20-mA drive capability
P1_1	9	Digital I/O	Port 1.1 – 20-mA drive capability
P1_2	8	Digital I/O	Port 1.2
P1_3	7	Digital I/O	Port 1.3
P1_4	6	Digital I/O	Port 1.4
P1_5	5	Digital I/O	Port 1.5
P1_6	38	Digital I/O	Port 1.6
P1_7	37	Digital I/O	Port 1.7
P2_0	36	Digital I/O	Port 2.0
P2_1/DD	35	Digital I/O	Port 2.1 / debug data
P2_2/DC	34	Digital I/O	Port 2.2 / debug clock
P2_3/ OSC32K_Q2	33	Digital I/O, Analog I/O	Port 2.3/32.768 kHz XOSC
P2_4/ OSC32K_Q1	32	Digital I/O, Analog I/O	Port 2.4/32.768 kHz XOSC
RBIAS	30	Analog I/O	External precision bias resistor for reference current
RESET_N	20	Digital input	Reset, active-low
RF_N	26	RF I/O	Negative RF input signal to LNA during RX Negative RF output signal from PA during TX
RF_P	25	RF I/O	Positive RF input signal to LNA during RX Positive RF output signal from PA during TX
SCL	2	I ² C clock or digital I/O	Can be used as I ² C clock pin or digital I/O. Leave floating if not used. If grounded disable pull up
SDA	3	I ² C clock or digital I/O	Can be used as I ² C data pin or digital I/O. Leave floating if not used. If grounded disable pull up
XOSC_Q1	22	Analog I/O	32-MHz crystal oscillator pin 1 or external clock input
XOSC_Q2	23	Analog I/O	32-MHz crystal oscillator pin 2

4 Specifications

4.1 Absolute Maximum Ratings⁽¹⁾

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
Supply voltage	All supply pins must have the same voltage	−0.3	3.9	V
Voltage on any digital pin		−0.3	$V_{DD} + 0.3 \leq 3.9$	V
Input RF level			10	dBm

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

4.2 Handling Ratings

			MIN	MAX	UNIT
T_{stg}	Storage temperature range		−40	125	°C
V_{ESD}	Electrostatic discharge (ESD) performance:	Human Body Model (HBM), per AEC Q100-002 ⁽¹⁾	All pins	−1	1
			All pins (Excluding pins 25 and 26)	−2	2
		Charged Device Model (CDM), per AEC Q100-011		−500	500
					V

- (1) AEC Q100-002 indicates HBM stressing is done in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

4.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	NOM	MAX	UNIT
Operating ambient temperature range, T_A	−40		105	°C
Operating supply voltage	2		3.6	V

4.4 Thermal Characteristics for RHA Package

NAME	DESCRIPTION	°C/W	AIR FLOW (m/s) ⁽¹⁾
$R\theta_{JC}$	Junction-to-case (top)	16.1	0.00
$R\theta_{JB}$	Junction-to-board	5.5	0.00
$R\theta_{JA}$	Junction-to-free air	30.6	0.00
Ψ_{JT}	Junction-to-package top	0.2	0.00
Ψ_{JB}	Junction-to-board	5.4	0.00
$R\theta_{JC}$	Junction-to-case (bottom)	1.0	0.00

- (1) m/s = meters per second

4.5 Electrical Characteristics

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$, 1 Mbps, GFSK, 250-kHz deviation, **Bluetooth** low energy mode, and 0.1% BER

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
I_{core} Core current consumption	RX mode, standard mode, no peripherals active, low MCU activity		18.3		mA
	RX mode, high-gain mode, no peripherals active, low MCU activity		20.8		
	TX mode, –20 dBm output power, no peripherals active, low MCU activity		17.2		
	TX mode, 0 dBm output power, no peripherals active, low MCU activity		18.6		
	Power mode 1. Digital regulator on; 16-MHz RCOSC and 32-MHz crystal oscillator off; 32.768-kHz XOSC, POR, BOD and sleep timer active; RAM and register retention		270		μA
	Power mode 2. Digital regulator off; 16-MHz RCOSC and 32-MHz crystal oscillator off; 32.768-kHz XOSC, POR, and sleep timer active; RAM and register retention		1		
	Power mode 3. Digital regulator off; no clocks; POR active; RAM and register retention		0.5		
	Low MCU activity: 32-MHz XOSC running. No radio or peripherals. Limited flash access, no RAM access.		6.7		mA
I_{peri} Peripheral current consumption (Adds to core current I_{core} for each peripheral unit activated)	Timer 1. Timer running, 32-MHz XOSC used		90		μA
	Timer 2. Timer running, 32-MHz XOSC used		90		
	Timer 3. Timer running, 32-MHz XOSC used		60		
	Timer 4. Timer running, 32-MHz XOSC used		70		
	Sleep timer, including 32.753-kHz RCOSC		0.6		mA
	ADC, when converting		1.2		

4.6 General Characteristics

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
WAKE-UP AND TIMING					
Power mode 1 → Active	Digital regulator on, 16-MHz RCOSC and 32-MHz crystal oscillator off. Start-up of 16-MHz RCOSC		4		μs
Power mode 2 or 3 → Active	Digital regulator off, 16-MHz RCOSC and 32-MHz crystal oscillator off. Start-up of regulator and 16-MHz RCOSC		120		μs
Active → TX or RX	Crystal ESR = 16 Ω. Initially running on 16-MHz RCOSC, with 32-MHz XOSC OFF		500		μs
	With 32-MHz XOSC initially on		180		μs
RX/TX turnaround	Proprietary auto mode		130		μs
	BLE mode		150		
RADIO PART					
RF frequency range	Programmable in 1-MHz steps	2379		2496	MHz
Data rate and modulation format	2 Mbps, GFSK, 500-kHz deviation 2 Mbps, GFSK, 320-kHz deviation 1 Mbps, GFSK, 250-kHz deviation 1 Mbps, GFSK, 160-kHz deviation 500 kbps, MSK 250 kbps, GFSK, 160-kHz deviation 250 kbps, MSK				

4.7 RF Receive Section

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$, $V_{DD} = 3\text{ V}$, $f_c = 2440\text{ MHz}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
1 Mbps, GFSK, 250-kHz Deviation, Bluetooth low energy Mode, 0.1% BER					
Receiver sensitivity ⁽¹⁾⁽²⁾	High-gain mode		–94		dBm
	Standard mode		–88		
Saturation ⁽²⁾	BER < 0.1%		5		dBm
Co-channel rejection ⁽²⁾	Wanted signal –67 dBm		–6		dB
In-band blocking rejection ⁽²⁾	±1 MHz offset, 0.1% BER, wanted signal –67 dBm		–2		dB
	±2 MHz offset, 0.1% BER, wanted signal –67 dBm		26		
	±3 MHz offset, 0.1% BER, wanted signal –67 dBm		34		
	>6 MHz offset, 0.1% BER, wanted signal –67 dBm		33		
Out-of-band blocking rejection ⁽²⁾	Minimum interferer level < 2 GHz (Wanted signal –67 dBm)		–21		dBm
	Minimum interferer level [2 GHz, 3 GHz] (Wanted signal –67 dBm)		–27		
	Minimum interferer level > 3 GHz (Wanted signal –67 dBm)		–8		
Intermodulation ⁽²⁾	Minimum interferer level		–36		dBm
Frequency error tolerance ⁽³⁾	Including both initial tolerance and drift. Sensitivity better than –67dBm, 250 byte payload. BER 0.1%	–250		250	kHz
Symbol rate error tolerance ⁽⁴⁾	Maximum packet length. Sensitivity better than –67 dBm, 250 byte payload. BER 0.1%	–80		80	ppm
ALL RATES/FORMATS					
Spurious emission in RX. Conducted measurement	$f < 1\text{ GHz}$		–67		dBm
Spurious emission in RX. Conducted measurement	$f > 1\text{ GHz}$		–57		dBm

(1) The receiver sensitivity setting is programmable using a TI BLE stack vendor-specific API command. The default value is standard mode.

(2) Results based on standard-gain mode.

(3) Difference between center frequency of the received RF signal and local oscillator frequency

(4) Difference between incoming symbol rate and the internally generated symbol rate

4.8 RF Transmit Section

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$, $V_{DD} = 3\text{ V}$ and $f_c = 2440\text{ MHz}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Output power	Delivered to a single-ended 50- Ω load through a balun using maximum recommended output power setting		0		dBm
	Delivered to a single-ended 50- Ω load through a balun using minimum recommended output power setting		-20		
Programmable output power range	Delivered to a single-ended 50- Ω load through a balun using minimum recommended output power setting		20		dB
Spurious emission conducted measurement	$f < 1\text{ GHz}$		-52		dBm
	$f > 1\text{ GHz}$		-48		dBm
	Suitable for systems targeting compliance with worldwide radio-frequency regulations ETSI EN 300 328 and EN 300 440 Class 2 (Europe), FCC CFR47 Part 15 (US), and ARIB STD-T66 (Japan)				
Optimum load impedance	Differential impedance as seen from the RF port (RF_P and RF_N) toward the antenna		70 +j30		Ω

Designs with antenna connectors that require conducted ETSI compliance at 64 MHz should insert an LC resonator in front of the antenna connector. Use a 1.6-nH inductor in parallel with a 1.8-pF capacitor. Connect both from the signal trace to a good RF ground.

4.9 32-MHz Crystal Oscillator

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Crystal frequency			32		MHz
Crystal frequency accuracy requirement ⁽¹⁾		-40		40	ppm
ESR Equivalent series resistance		6		60	Ω
C_0 Crystal shunt capacitance		1		7	pF
C_L Crystal load capacitance		10		16	pF
Start-up time			0.25		ms
Power-down guard time	The crystal oscillator must be in power down for a guard time before it is used again. This requirement is valid for all modes of operation. The need for power-down guard time can vary with crystal type and load.	3			ms

(1) Including aging and temperature dependency, as specified by [1]

4.10 32.768-kHz Crystal Oscillator

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Crystal frequency			32.768		kHz
Crystal frequency accuracy requirement ⁽¹⁾		–40		40	ppm
ESR Equivalent series resistance			40	130	k Ω
C_0 Crystal shunt capacitance			0.9	2	pF
C_L Crystal load capacitance			12	16	pF
Start-up time			0.4		s

(1) Including aging and temperature dependency, as specified by [1]

4.11 32-kHz RC Oscillator

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Calibrated frequency ⁽¹⁾			32.753		kHz
Frequency accuracy after calibration			$\pm 0.2\%$		
Temperature coefficient ⁽²⁾			0.4		%/ $^\circ\text{C}$
Supply-voltage coefficient ⁽³⁾			3		%/V
Calibration time ⁽⁴⁾			2		ms

(1) The calibrated 32-kHz RC oscillator frequency is the 32-MHz XTAL frequency divided by 977.

(2) Frequency drift when temperature changes after calibration

(3) Frequency drift when supply voltage changes after calibration

(4) When the 32-kHz RC oscillator is enabled, it is calibrated when a switch from the 16-MHz RC oscillator to the 32-MHz crystal oscillator is performed while SLEEP_CMD.OSC32K_CALDIS is set to 0.

4.12 16-MHz RC Oscillator

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Frequency ⁽¹⁾			16		MHz
Uncalibrated frequency accuracy			$\pm 18\%$		
Calibrated frequency accuracy			$\pm 0.6\%$		
Start-up time			10		μs
Initial calibration time ⁽²⁾			50		μs

(1) The calibrated 16-MHz RC oscillator frequency is the 32-MHz XTAL frequency divided by 2.

(2) When the 16-MHz RC oscillator is enabled, it is calibrated when a switch from the 16-MHz RC oscillator to the 32-MHz crystal oscillator is performed while SLEEP_CMD.OSC_PD is set to 0.

4.13 RSSI Characteristics

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
2 Mbps, GFSK, 320-kHz Deviation, 0.1% BER and 2 Mbps, GFSK, 500-kHz Deviation, 0.1% BER					
Useful RSSI range ⁽¹⁾	Reduced gain by AGC algorithm		64		dB
	High gain by AGC algorithm		64		
RSSI offset ⁽¹⁾	Reduced gain by AGC algorithm		79		dBm
	High gain by AGC algorithm		99		
Absolute uncalibrated accuracy ⁽¹⁾			±6		dB
Step size (LSB value)			1		dB
All Other Rates/Formats					
Useful RSSI range ⁽¹⁾	Standard mode		64		dB
	High-gain mode		64		
RSSI offset ⁽¹⁾	Standard mode		98		dBm
	High-gain mode		107		
Absolute uncalibrated accuracy ⁽¹⁾			±3		dB
Step size (LSB value)			1		dB

(1) Assuming CC2541-Q1 EM reference design. Other RF designs give an offset from the reported value.

4.14 Frequency Synthesizer Characteristics

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$, $V_{DD} = 3\text{ V}$ and $f_c = 2440\text{ MHz}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Phase noise, unmodulated carrier	At ±1-MHz offset from carrier		–109		dBc/Hz
	At ±3-MHz offset from carrier		–112		
	At ±5-MHz offset from carrier		–119		

4.15 Analog Temperature Sensor

Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Output	Measured using integrated ADC, internal band-gap voltage reference, and maximum resolution		1480		12-bit
Temperature coefficient			4.5		/ 1°C
Voltage coefficient			1		0.1 V
Initial accuracy without calibration			±10		$^\circ\text{C}$
Accuracy using 1-point calibration			±5		$^\circ\text{C}$
Current consumption when enabled			0.5		mA

4.16 Comparator Characteristics

$T_A = 25^\circ\text{C}$, $V_{DD} = 3\text{ V}$. All measurement results are obtained using the CC2541-Q1 reference designs, post-calibration.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Common-mode maximum voltage			V_{DD}		V
Common-mode minimum voltage			–0.3		
Input offset voltage			1		mV
Offset vs temperature			16		$\mu\text{V}/^\circ\text{C}$
Offset vs operating voltage			4		mV/V
Supply current			230		nA
Hysteresis			0.15		mV

4.17 ADC Characteristics

$T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Input voltage	VDD is voltage on AVDD5 pin	0		VDD	V
	External reference voltage	VDD is voltage on AVDD5 pin	0		VDD	V
	External reference voltage differential	VDD is voltage on AVDD5 pin	0		VDD	V
	Input resistance, signal	Simulated using 4-MHz clock speed		197		k Ω
	Full-scale signal ⁽¹⁾	Peak-to-peak, defines 0 dBFS		2.97		V
ENOB ⁽¹⁾	Effective number of bits	Single-ended input, 7-bit setting		5.7		bits
		Single-ended input, 9-bit setting		7.5		
		Single-ended input, 10-bit setting		9.3		
		Single-ended input, 12-bit setting		10.3		
		Differential input, 7-bit setting		6.5		
		Differential input, 9-bit setting		8.3		
		Differential input, 10-bit setting		10		
		Differential input, 12-bit setting		11.5		
		10-bit setting, clocked by RCOSC		9.7		
		12-bit setting, clocked by RCOSC		10.9		
	Useful power bandwidth	7-bit setting, both single and differential		0–20		kHz
THD	Total harmonic distortion	Single ended input, 12-bit setting, –6 dBFS ⁽¹⁾		–75.2		dB
		Differential input, 12-bit setting, –6 dBFS ⁽¹⁾		–86.6		
	Signal to nonharmonic ratio	Single-ended input, 12-bit setting ⁽¹⁾		70.2		dB
		Differential input, 12-bit setting ⁽¹⁾		79.3		
		Single-ended input, 12-bit setting, –6 dBFS ⁽¹⁾		78.8		
		Differential input, 12-bit setting, –6 dBFS ⁽¹⁾		88.9		
CMRR	Common-mode rejection ratio	Differential input, 12-bit setting, 1-kHz sine (0 dBFS), limited by ADC resolution		>84		dB
	Crosstalk	Single ended input, 12-bit setting, 1-kHz sine (0 dBFS), limited by ADC resolution		>84		dB
	Offset	Midscale		–3		mV
	Gain error			0.68%		
DNL	Differential nonlinearity	12-bit setting, mean ⁽¹⁾		0.05		LSB
		12-bit setting, maximum ⁽¹⁾		0.9		
INL	Integral nonlinearity	12-bit setting, mean ⁽¹⁾		4.6		LSB
		12-bit setting, maximum ⁽¹⁾		13.3		
		12-bit setting, mean, clocked by RCOSC		10		
		12-bit setting, max, clocked by RCOSC		29		
SINAD (–THD+N)	Signal-to-noise-and-distortion	Single ended input, 7-bit setting ⁽¹⁾		35.4		dB
		Single ended input, 9-bit setting ⁽¹⁾		46.8		
		Single ended input, 10-bit setting ⁽¹⁾		57.5		
		Single ended input, 12-bit setting ⁽¹⁾		66.6		
		Differential input, 7-bit setting ⁽¹⁾		40.7		
		Differential input, 9-bit setting ⁽¹⁾		51.6		
		Differential input, 10-bit setting ⁽¹⁾		61.8		
		Differential input, 12-bit setting ⁽¹⁾		70.8		
	Conversion time	7-bit setting		20		μs
		9-bit setting		36		
		10-bit setting		68		
		12-bit setting		132		

(1) Measured with 300-Hz sine-wave input and VDD as reference.

ADC Characteristics (continued)

$T_A = 25^\circ\text{C}$ and $V_{DD} = 3\text{ V}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Power consumption			1.2		mA
Internal reference VDD coefficient			4		mV/V
Internal reference temperature coefficient			0.4		mV/10°C
Internal reference voltage			1.24		V

4.18 DC Characteristics

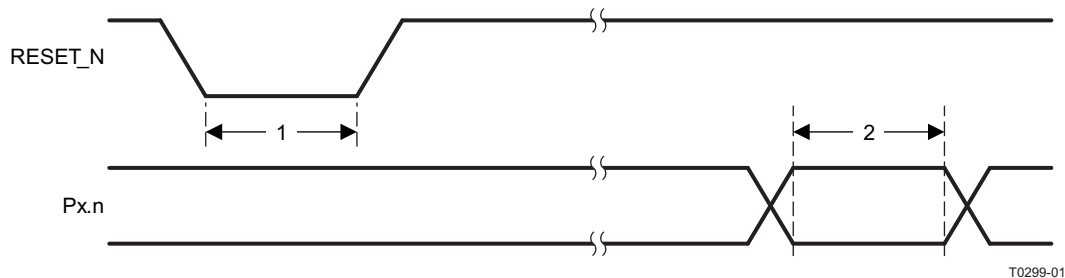
$T_A = 25^\circ\text{C}$, $V_{DD} = 3\text{ V}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Logic-0 input voltage				0.5	V
Logic-1 input voltage		2.4			V
Logic-0 input current	Input equals 0 V	–50		50	nA
Logic-1 input current	Input equals VDD	–50		50	nA
I/O-pin pullup and pulldown resistors			20		kΩ
Logic-0 output voltage, 4- mA pins	Output load 4 mA			0.5	V
Logic-1 output voltage, 4-mA pins	Output load 4 mA	2.5			V
Logic-0 output voltage, 20- mA pins	Output load 20 mA			0.5	V
Logic-1 output voltage, 20-mA pins	Output load 20 mA	2.5			V

4.19 Control Input AC Characteristics

$T_A = -40^\circ\text{C}$ to 105°C , $V_{DD} = 2\text{ V}$ to 3.6 V

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
System clock, f_{SYSCLK} $t_{\text{SYSCLK}} = 1/f_{\text{SYSCLK}}$	The undivided system clock is 32 MHz when crystal oscillator is used. The undivided system clock is 16 MHz when calibrated 16-MHz RC oscillator is used.	16		32	MHz
RESET_N low duration	See item 1, Figure 4-1 . This is the shortest pulse that is recognized as a complete reset pin request. Note that shorter pulses may be recognized but do not lead to complete reset of all modules within the chip.	1			μs
Interrupt pulse duration	See item 2, Figure 4-1 . This is the shortest pulse that is recognized as an interrupt request.	20			ns



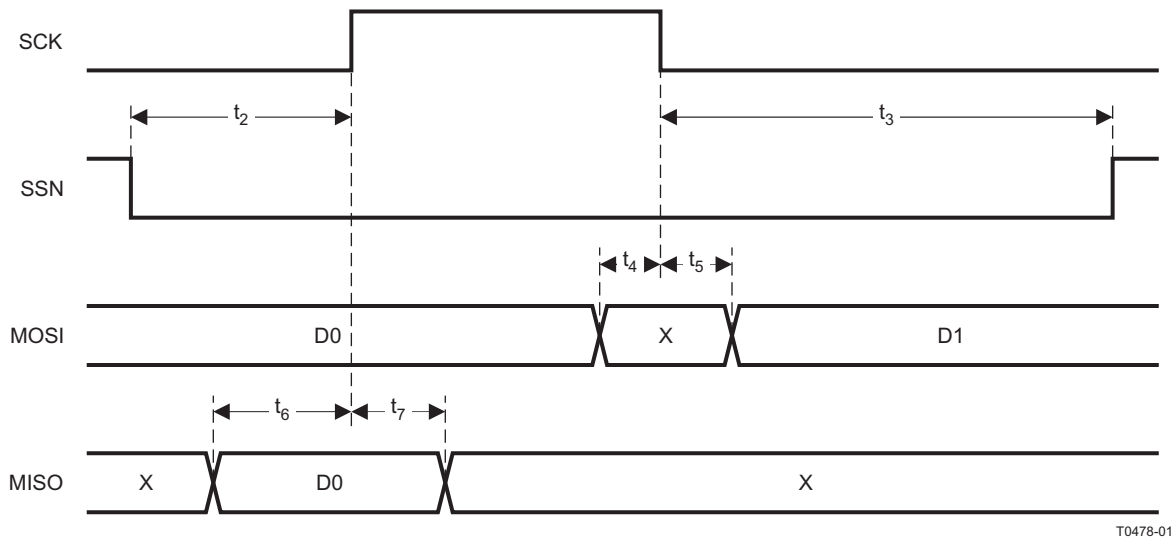
T0299-01

Figure 4-1. Control Input AC Characteristics

4.20 SPI AC Characteristics

$T_A = -40^{\circ}\text{C}$ to 105°C , $V_{DD} = 2\text{ V}$ to 3.6 V

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
t_1	SCK period	Master, RX and TX	250			ns
		Slave, RX and TX	250			
	SCK duty cycle	Master		50%		
t_2	SSN low to SCK	Master	63			ns
		Slave	63			
t_3	SCK to SSN high	Master	63			ns
		Slave	63			
t_4	MOSI early out	Master, load = 10 pF			7	ns
t_5	MOSI late out	Master, load = 10 pF			10	ns
t_6	MISO setup	Master	90			ns
t_7	MISO hold	Master	10			ns
	SCK duty cycle	Slave		50%		ns
t_{10}	MOSI setup	Slave	35			ns
t_{11}	MOSI hold	Slave	10			ns
t_9	MISO late out	Slave, load = 10 pF			95	ns
Operating frequency		Master, TX only			8	MHz
		Master, RX and TX			4	
		Slave, RX only			8	
		Slave, RX and TX			4	



T0478-01

Figure 4-2. SPI Master AC Characteristics

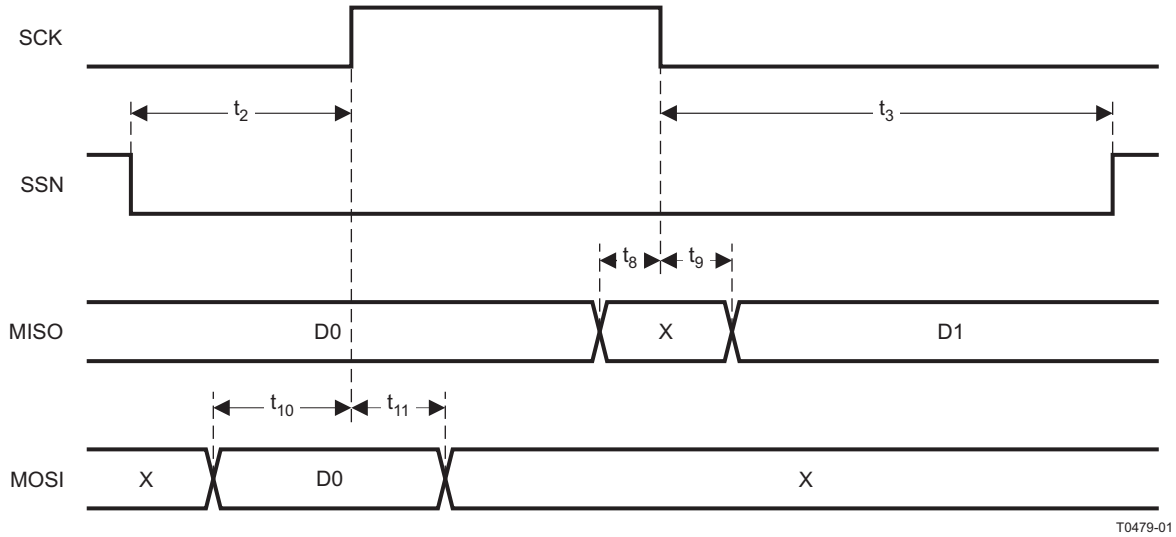


Figure 4-3. SPI Slave AC Characteristics

4.21 Debug Interface AC Characteristics

$T_A = -40^{\circ}\text{C}$ to 105°C , $V_{DD} = 2\text{ V}$ to 3.6 V

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$f_{\text{clk_dbg}}$	Debug clock frequency (see Figure 4-4)			12	MHz
t_1	Allowed high pulse on clock (see Figure 4-4)	35			ns
t_2	Allowed low pulse on clock (see Figure 4-4)	35			ns
t_3	EXT_RESET_N low to first falling edge on debug clock (see Figure 4-6)	167			ns
t_4	Falling edge on clock to EXT_RESET_N high (see Figure 4-6)	83			ns
t_5	EXT_RESET_N high to first debug command (see Figure 4-6)	83			ns
t_6	Debug data setup (see Figure 4-5)	2			ns
t_7	Debug data hold (see Figure 4-5)	4			ns
t_8	Clock-to-data delay (see Figure 4-5)	Load = 10 pF		30	ns

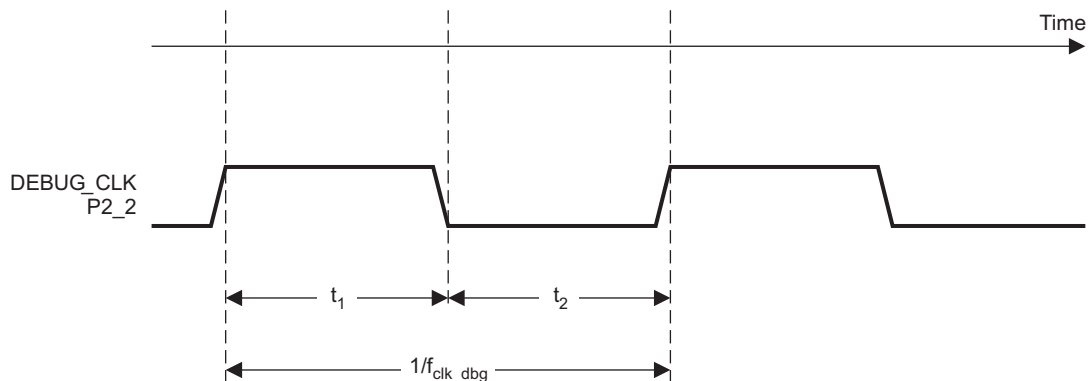
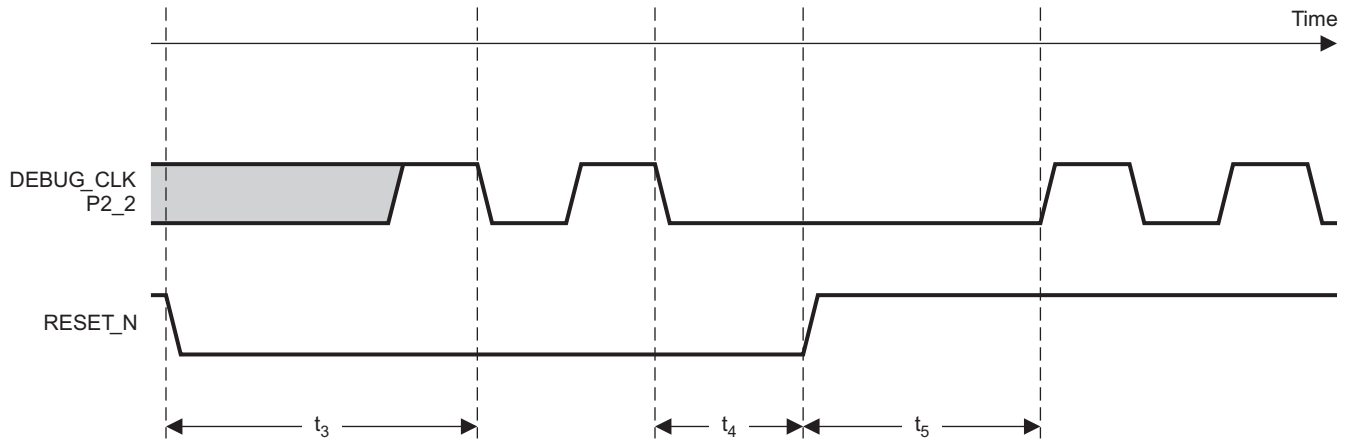


Figure 4-4. Debug Clock – Basic Timing



T0437-01

Figure 4-5. Debug Enable Timing

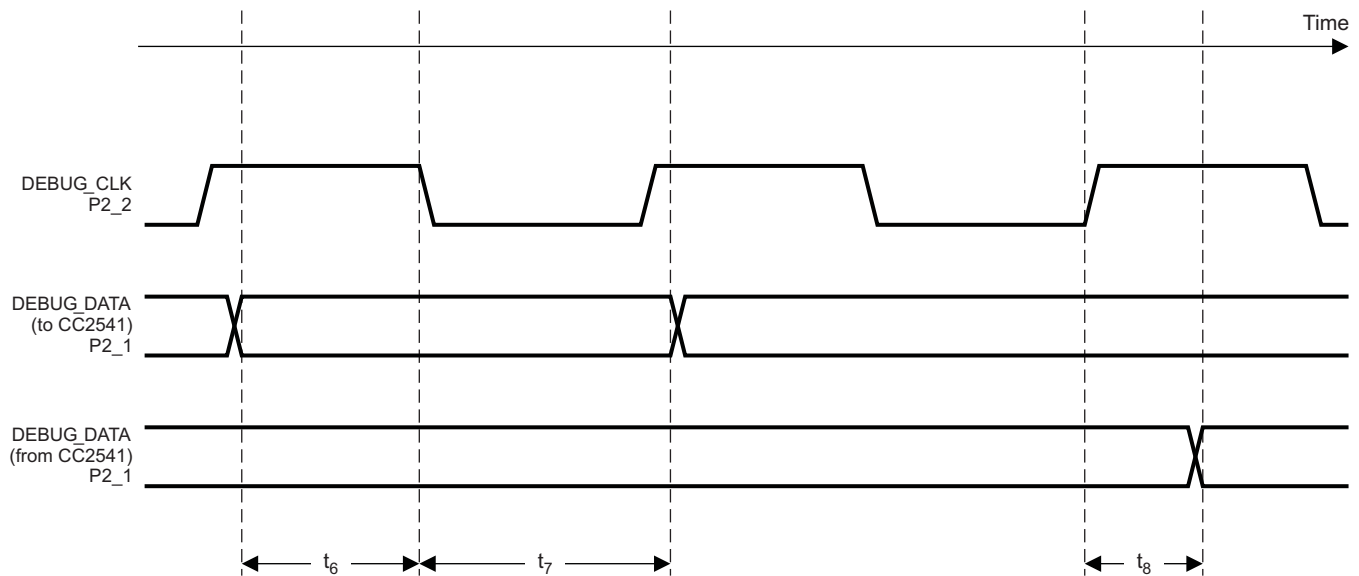


Figure 4-6. Data Setup and Hold Timing

4.22 Timer Inputs AC Characteristics

$T_A = -40^\circ\text{C}$ to 105°C , $V_{DD} = 2\text{ V}$ to 3.6 V

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input capture pulse duration	Synchronizers determine the shortest input pulse that can be recognized. The synchronizers operate at the current system clock rate (16 MHz or 32 MHz).	1.5			t_{SYSCLK}

4.23 Typical Characteristics

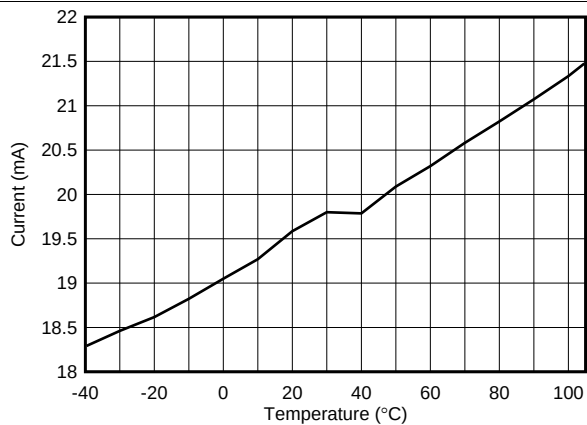


Figure 4-7. RX Current vs Temperature

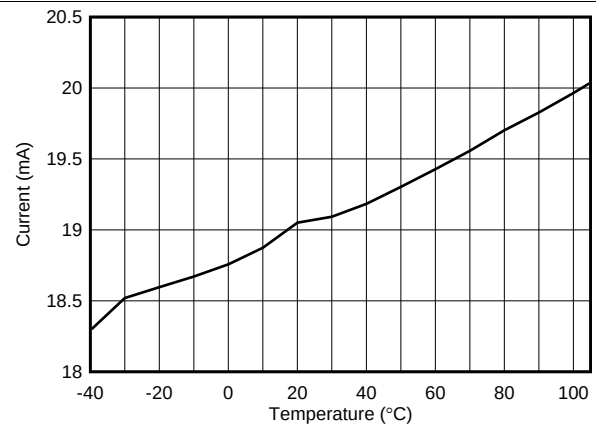


Figure 4-8. TX Current vs Temperature

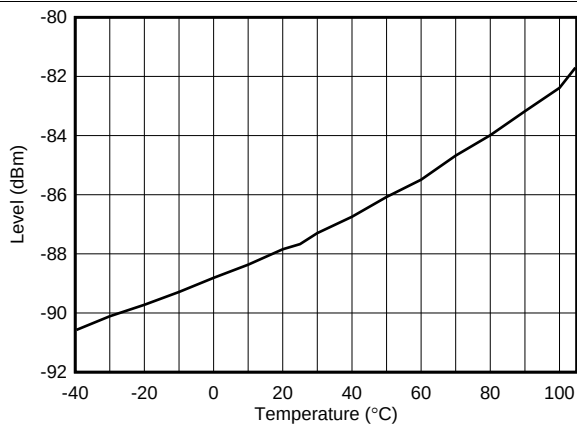


Figure 4-9. RX Sensitivity vs Temperature

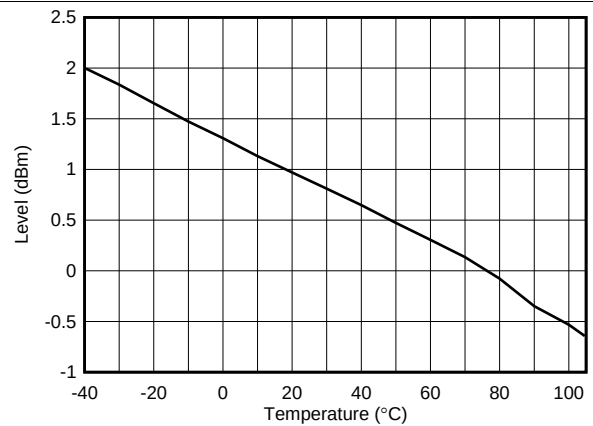


Figure 4-10. TX Power vs Temperature

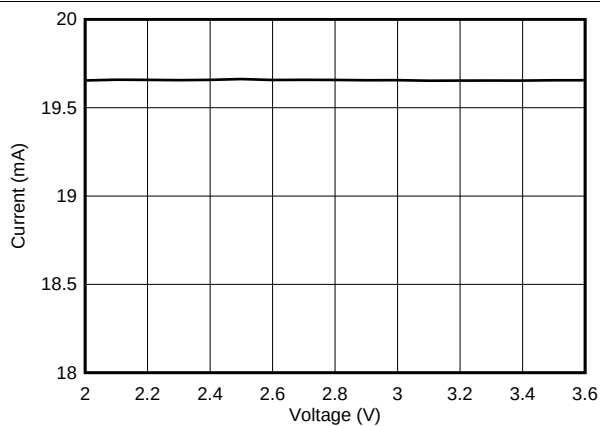


Figure 4-11. RX Current vs Supply Voltage

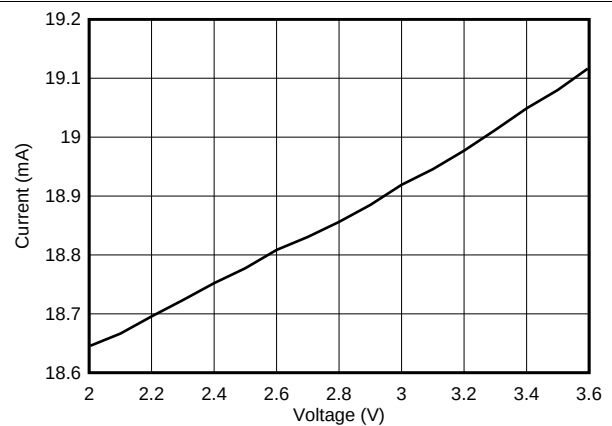


Figure 4-12. TX Current vs Supply Voltage

Typical Characteristics (continued)

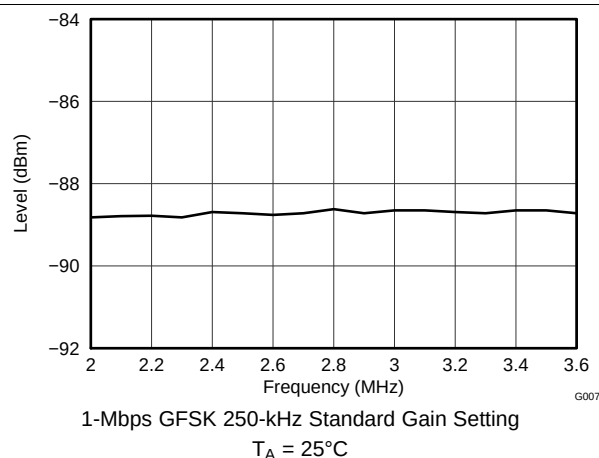


Figure 4-13. RX Sensitivity vs Supply Voltage

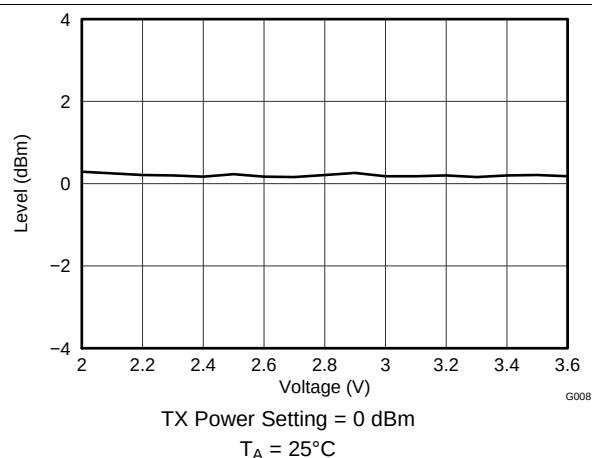


Figure 4-14. TX Power vs Supply Voltage

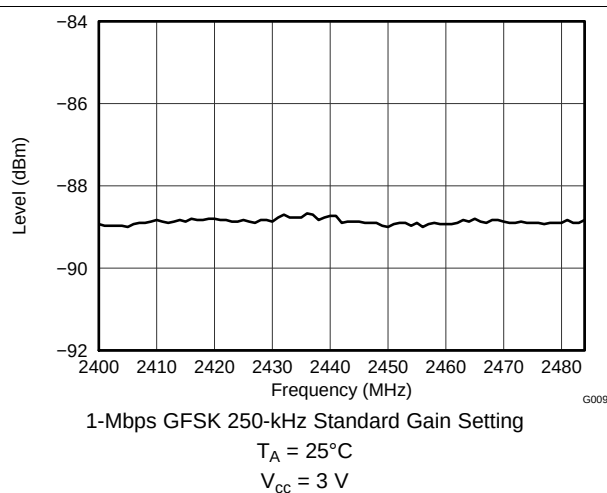


Figure 4-15. RX Sensitivity vs Frequency

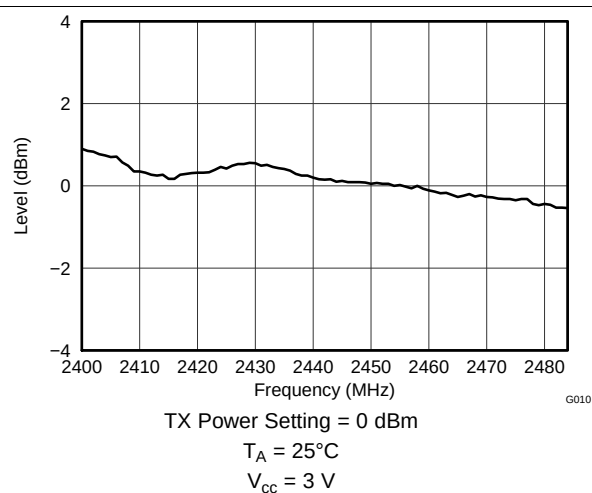


Figure 4-16. TX Power vs Frequency

Table 4-1. Output Power⁽¹⁾⁽²⁾

TX POWER Setting	Typical Output Power (dBm)
0xE1	0
0xD1	-2
0xC1	-4
0xB1	-6
0xA1	-8
0x91	-10
0x81	-12
0x71	-14
0x61	-16
0x51	-18
0x41	-20

- (1) Measured on Texas Instruments CC2541-Q1 EM reference design with $T_A = 25^\circ\text{C}$, $V_{DD} = 3\text{ V}$ and $f_c = 2440\text{ MHz}$. See [SWRU191](#) for recommended register settings.
- (2) 1 Mbps, GFSK, 250-kHz deviation, *Bluetooth* low energy mode, 1% BER

5 Detailed Description

5.1 Functional Block Diagram

A block diagram of the CC2541-Q1 is shown in Figure 5-1. The modules can be roughly divided into one of three categories: CPU-related modules; modules related to power, test, and clock distribution; and radio-related modules. In the following subsections, a short description of each module is given.

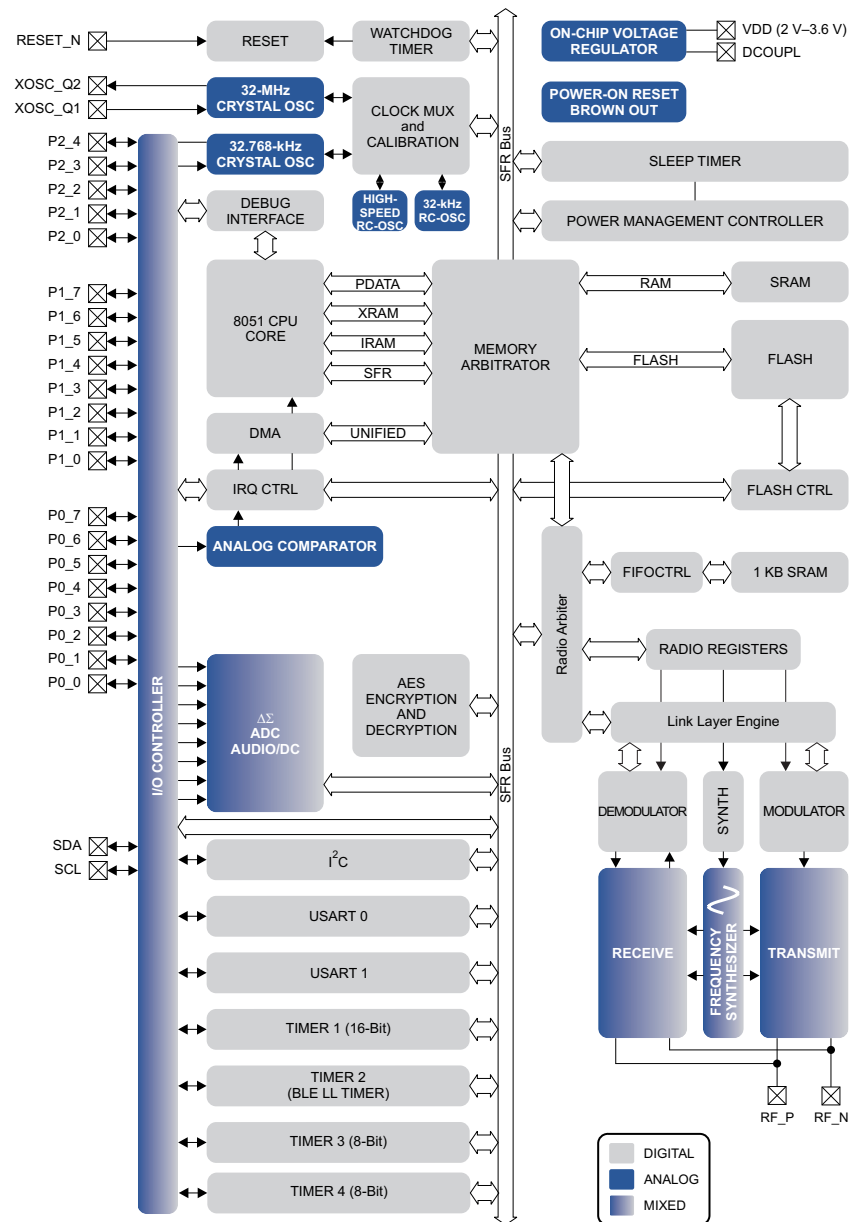


Figure 5-1. CC2541-Q1 Block Diagram

5.2 Block Descriptions

A block diagram of the CC2541-Q1 is shown in Figure 5-1. The modules can be roughly divided into one of three categories: CPU-related modules; modules related to power, test, and clock distribution; and radio-related modules. In the following subsections, a short description of each module is given.

5.2.1 CPU and Memory

The **8051 CPU core** is a single-cycle 8051-compatible core. It has three different memory access busses (SFR, DATA, and CODE/XDATA), a debug interface, and an 18-input extended interrupt unit.

The **memory arbiter** is at the heart of the system, as it connects the CPU and DMA controller with the physical memories and all peripherals through the SFR bus. The memory arbiter has four memory-access points, access of which can map to one of three physical memories: an SRAM, flash memory, and XREG/SFR registers. It is responsible for performing arbitration and sequencing between simultaneous memory accesses to the same physical memory.

The **SFR bus** is drawn conceptually in [Figure 5-1](#) as a common bus that connects all hardware peripherals to the memory arbiter. The SFR bus in the block diagram also provides access to the radio registers in the radio register bank, even though these are indeed mapped into XDATA memory space.

The **8-KB SRAM** maps to the DATA memory space and to parts of the XDATA memory spaces. The SRAM is an ultralow-power SRAM that retains its contents even when the digital part is powered off (power mode 2 and mode 3).

The **256 KB flash block** provides in-circuit programmable non-volatile program memory for the device, and maps into the CODE and XDATA memory spaces.

5.2.2 Peripherals

Writing to the flash block is performed through a **flash controller** that allows page-wise erasure and 4-bitwise programming. See User Guide for details on the flash controller.

A versatile five-channel **DMA controller** is available in the system, accesses memory using the XDATA memory space, and thus has access to all physical memories. Each channel (trigger, priority, transfer mode, addressing mode, source and destination pointers, and transfer count) is configured with DMA descriptors that can be located anywhere in memory. Many of the hardware peripherals (AES core, flash controller, USARTs, timers, ADC interface, etc.) can be used with the DMA controller for efficient operation by performing data transfers between a single SFR or XREG address and flash/SRAM.

Each CC2541-Q1 contains a unique 48-bit IEEE address that can be used as the public device address for a *Bluetooth* device. Designers are free to use this address, or provide their own, as described in the *Bluetooth* specification.

The **interrupt controller** services a total of 18 interrupt sources, divided into six interrupt groups, each of which is associated with one of four interrupt priorities. I/O and sleep timer interrupt requests are serviced even if the device is in a sleep mode (power modes 1 and 2) by bringing the CC2541-Q1 back to the active mode.

The **debug interface** implements a proprietary two-wire serial interface that is used for in-circuit debugging. Through this debug interface, it is possible to erase or program the entire flash memory, control which oscillators are enabled, stop and start execution of the user program, execute instructions on the 8051 core, set code breakpoints, and single-step through instructions in the code. Using these techniques, it is possible to perform in-circuit debugging and external flash programming elegantly.

The **I/O controller** is responsible for all general-purpose I/O pins. The CPU can configure whether peripheral modules control certain pins or whether they are under software control, and if so, whether each pin is configured as an input or output and if a pullup or pulldown resistor in the pad is connected. Each peripheral that connects to the I/O pins can choose between two different I/O pin locations to ensure flexibility in various applications.

The **sleep timer** is an ultralow-power timer that can either use an external 32.768-kHz crystal oscillator or an internal 32.753-kHz RC oscillator. The sleep timer runs continuously in all operating modes except power mode 3. Typical applications of this timer are as a real-time counter or as a wake-up timer to get out of power mode 1 or mode 2.

A built-in **watchdog timer** allows the CC2541-Q1 to reset itself if the firmware hangs. When enabled by software, the watchdog timer must be cleared periodically; otherwise, it resets the device when it times out.

Timer 1 is a 16-bit timer with timer/counter/PWM functionality. It has a programmable prescaler, a 16-bit period value, and five individually programmable counter/capture channels, each with a 16-bit compare value. Each of the counter/capture channels can be used as a PWM output or to capture the timing of edges on input signals. It can also be configured in IR generation mode, where it counts timer 3 periods and the output is ANDed with the output of timer 3 to generate modulated consumer IR signals with minimal CPU interaction.

Timer 2 is a 40-bit timer. It has a 16-bit counter with a configurable timer period and a 24-bit overflow counter that can be used to keep track of the number of periods that have transpired. A 40-bit capture register is also used to record the exact time at which a start-of-frame delimiter is received/transmitted or the exact time at which transmission ends. There are two 16-bit output compare registers and two 24-bit overflow compare registers that can be used to give exact timing for start of RX or TX to the radio or general interrupts.

Timer 3 and timer 4 are 8-bit timers with timer/counter/PWM functionality. They have a programmable prescaler, an 8-bit period value, and one programmable counter channel with an 8-bit compare value. Each of the counter channels can be used as PWM output.

USART 0 and USART 1 are each configurable as either an SPI master/slave or a UART. They provide double buffering on both RX and TX and hardware flow control and are thus well suited to high-throughput full-duplex applications. Each USART has its own high-precision baud-rate generator, thus leaving the ordinary timers free for other uses. When configured as SPI slaves, the USARTs sample the input signal using SCK directly instead of using some oversampling scheme, and are thus well-suited for high data rates.

The **AES encryption/decryption core** allows the user to encrypt and decrypt data using the AES algorithm with 128-bit keys. The AES core also supports ECB, CBC, CFB, OFB, CTR, and CBC-MAC, as well as hardware support for CCM.

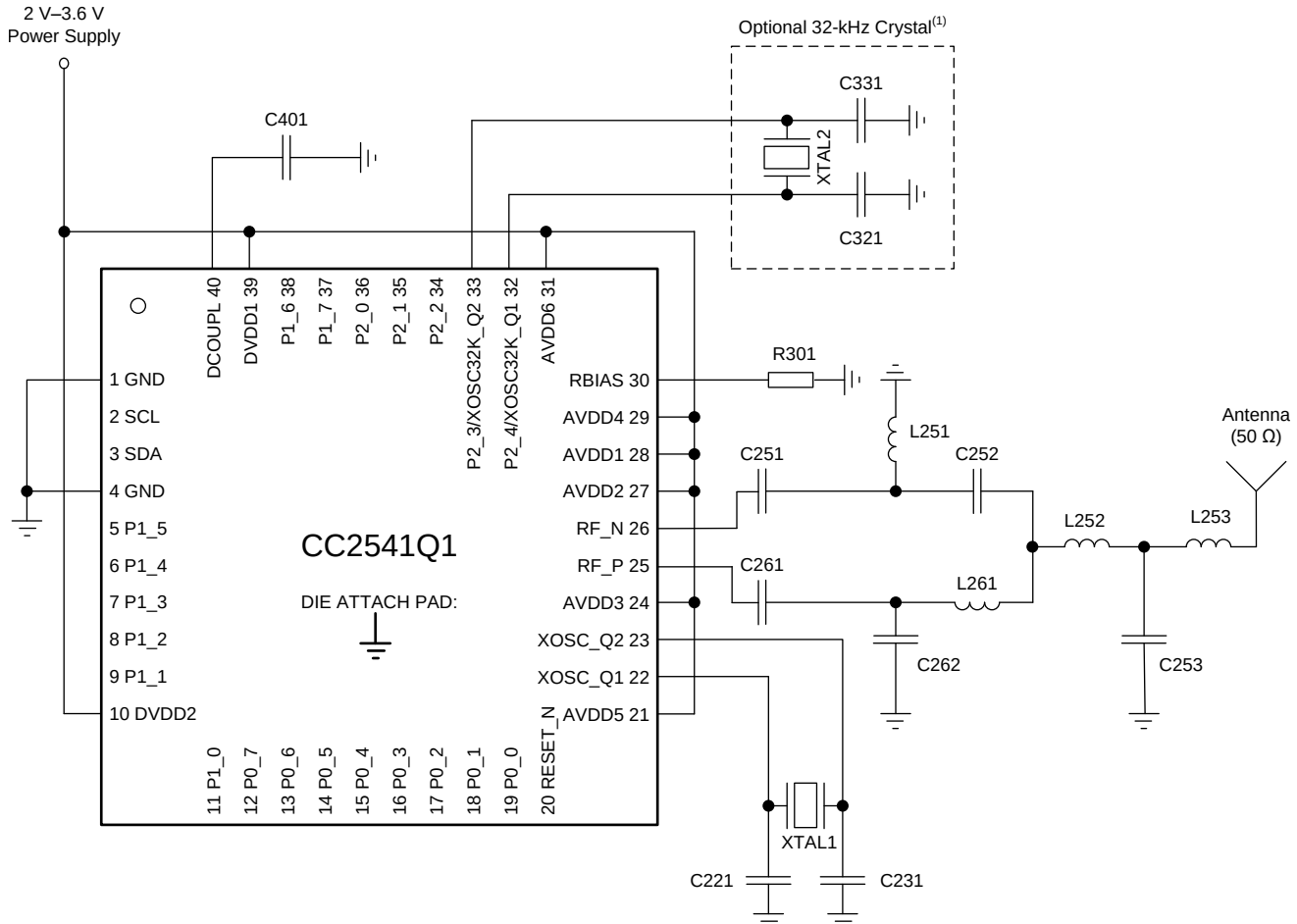
The **ADC** supports 7 to 12 bits of resolution with a corresponding range of bandwidths from 30-kHz to 4-kHz, respectively. DC and audio conversions with up to eight input channels (I/O controller pins) are possible. The inputs can be selected as single-ended or differential. The reference voltage can be internal, AVDD, or a single-ended or differential external signal. The ADC also has a temperature-sensor input channel. The ADC can automate the process of periodic sampling or conversion over a sequence of channels.

The **I²C** module provides a digital peripheral connection with two pins and supports both master and slave operation. I²C support is compliant with the NXP I²C specification version 2.1 and supports standard mode (up to 100 kbps) and fast mode (up to 400 kbps). In addition, 7-bit device addressing modes are supported, as well as master and slave modes.

The ultralow-power **analog comparator** enables applications to wake up from PM2 or PM3 based on an analog signal. Both inputs are brought out to pins; the reference voltage must be provided externally. The comparator output is connected to the I/O controller interrupt detector and can be treated by the MCU as a regular I/O pin interrupt.

6 Application Information

Few external components are required for the operation of the CC2541-Q1. A typical application circuit is shown in Figure 6-1.



(1) 32-kHz crystal is mandatory when running the BLE protocol stack in low-power modes, except if the link layer is in the standby state (Vol. 6 Part B Section 1.1 in [1]).

NOTE: Different antenna alternatives will be provided as reference designs.

Power supply decoupling capacitors are not shown. Digital I/O not connected

Figure 6-1. CC2541-Q1 Application Circuit

Table 6-1. Overview of External Components (Excluding Supply Decoupling Capacitors)

Component	Description	Value
C401	Decoupling capacitor for the internal 1.8-V digital voltage regulator	1 μ F
R301	Precision resistor $\pm 1\%$, used for internal biasing	56 k Ω

6.1 Input/Output Matching

When using an unbalanced antenna such as a monopole, a balun should be used to optimize performance. The balun can be implemented using low-cost discrete inductors and capacitors. See reference design, CC2541-Q1EM, for recommended balun.

6.2 Crystal

An external 32-MHz crystal, XTAL1, with two loading capacitors (C221 and C231) is used for the 32-MHz crystal oscillator. See [Section 4.9](#) for details. The load capacitance seen by the 32-MHz crystal is given by:

$$C_L = \frac{1}{\frac{1}{C_{221}} + \frac{1}{C_{231}}} + C_{\text{parasitic}} \quad (1)$$

XTAL2 is an optional 32.768-kHz crystal, with two loading capacitors (C321 and C331) used for the 32.768-kHz crystal oscillator. The 32.768-kHz crystal oscillator is used in applications where both very low sleep-current consumption and accurate wake-up times are needed. The load capacitance seen by the 32.768-kHz crystal is given by:

$$C_L = \frac{1}{\frac{1}{C_{321}} + \frac{1}{C_{331}}} + C_{\text{parasitic}} \quad (2)$$

A series resistor may be used to comply with the ESR requirement.

6.3 On-Chip 1.8-V Voltage Regulator Decoupling

The 1.8-V on-chip voltage regulator supplies the 1.8-V digital logic. This regulator requires a decoupling capacitor (C471) for stable operation.

6.4 Power-Supply Decoupling and Filtering

Proper power-supply decoupling must be used for optimum performance. The placement and size of the decoupling capacitors and the power supply filtering are very important to achieve the best performance in an application. TI provides a compact reference design that should be followed very closely.

7 Device and Documentation Support

7.1 Documentation Support

7.1.1 Related Documentation

1. *Bluetooth*® Core Technical Specification document, version 4.0
http://www.bluetooth.com/SiteCollectionDocuments/Core_V40.zip
2. CC253x System-on-Chip Solution for 2.4-GHz IEEE 802.15.4 and ZigBee® Applications/CC2541-Q1 System-on-Chip Solution for 2.4-GHz *Bluetooth* low energy Applications ([SWRU191](#))
3. Current Savings in CC254x Using the TPS62730 ([SWRA365](#)).

7.1.1.1 Additional Information

Texas Instruments offers a wide selection of cost-effective, low-power RF solutions for proprietary and standard-based wireless applications for use in industrial and consumer applications. Our selection includes RF transceivers, RF transmitters, RF front ends, and System-on-Chips as well as various software solutions for the sub-1- and 2.4-GHz frequency bands.

In addition, Texas Instruments provides a large selection of support collateral such as development tools, technical documentation, reference designs, application expertise, customer support, third-party and university programs.

The Low-Power RF E2E Online Community provides technical support forums, videos and blogs, and the chance to interact with fellow engineers from all over the world.

With a broad selection of product solutions, end application possibilities, and a range of technical support, Texas Instruments offers the broadest low-power RF portfolio. We make RF easy!

For more information on low-power RF, see [Section 7.1.1.2](#), [Section 7.1.1.3](#), and [Section 7.1.1.4](#).

7.1.1.2 Texas Instruments Low-Power RF Website

- Forums, videos, and blogs
- RF design help
- E2E interaction

Join us today at www.ti.com/lprf-forum.

7.1.1.3 Texas Instruments Low-Power RF Developer Network

Texas Instruments has launched an extensive network of low-power RF development partners to help customers speed up their application development. The network consists of recommended companies, RF consultants, and independent design houses that provide a series of hardware module products and design services, including:

- RF circuit, low-power RF, and ZigBee® design services
- Low-power RF and ZigBee module solutions and development tools
- RF certification services and RF circuit manufacturing

Need help with modules, engineering services or development tools?

Search the Low-Power RF Developer Network tool to find a suitable partner.

www.ti.com/lprfnetwork

7.1.1.4 Low-Power RF eNewsletter

The Low-Power RF eNewsletter keeps you up-to-date on new products, news releases, developers' news, and other news and events associated with low-power RF products from TI. The Low-Power RF eNewsletter articles include links to get more online information.

Sign up today on

www.ti.com/lprfnewsletter

7.2 Trademarks

SimpleLink is a trademark of Texas Instruments.

Bluetooth is a registered trademark of Bluetooth SIG, Inc..

ZigBee is a registered trademark of ZigBee Alliance.

All other trademarks are the property of their respective owners.

7.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

7.4 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

8 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
CC2541F256TRHARQ1	Active	Production	VQFN (RHA) 40	2500 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2541Q1 F256
CC2541F256TRHARQ1.A	Active	Production	VQFN (RHA) 40	2500 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2541Q1 F256
CC2541F256TRHATQ1	Active	Production	VQFN (RHA) 40	250 SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2541Q1 F256
CC2541F256TRHATQ1.A	Active	Production	VQFN (RHA) 40	250 SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2541Q1 F256

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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OTHER QUALIFIED VERSIONS OF CC2541-Q1 :

- Catalog : [CC2541](#)

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product

GENERIC PACKAGE VIEW

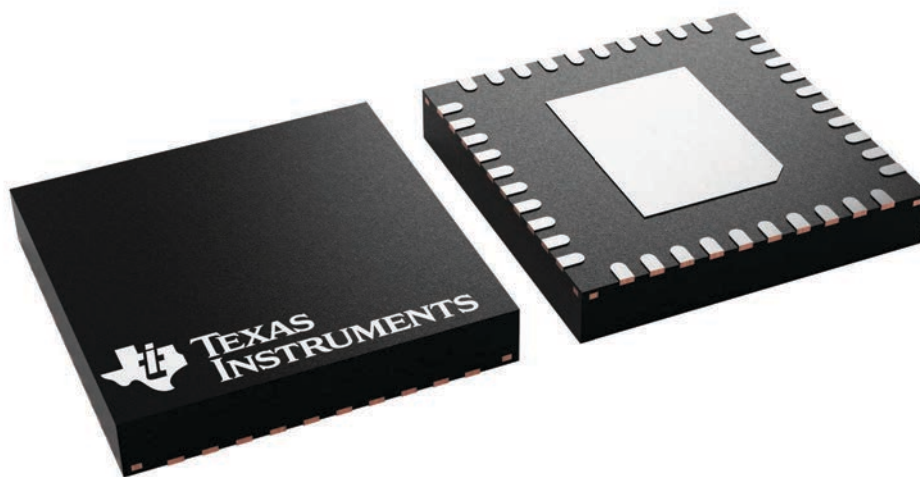
RHA 40

VQFN - 1 mm max height

6 x 6, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD

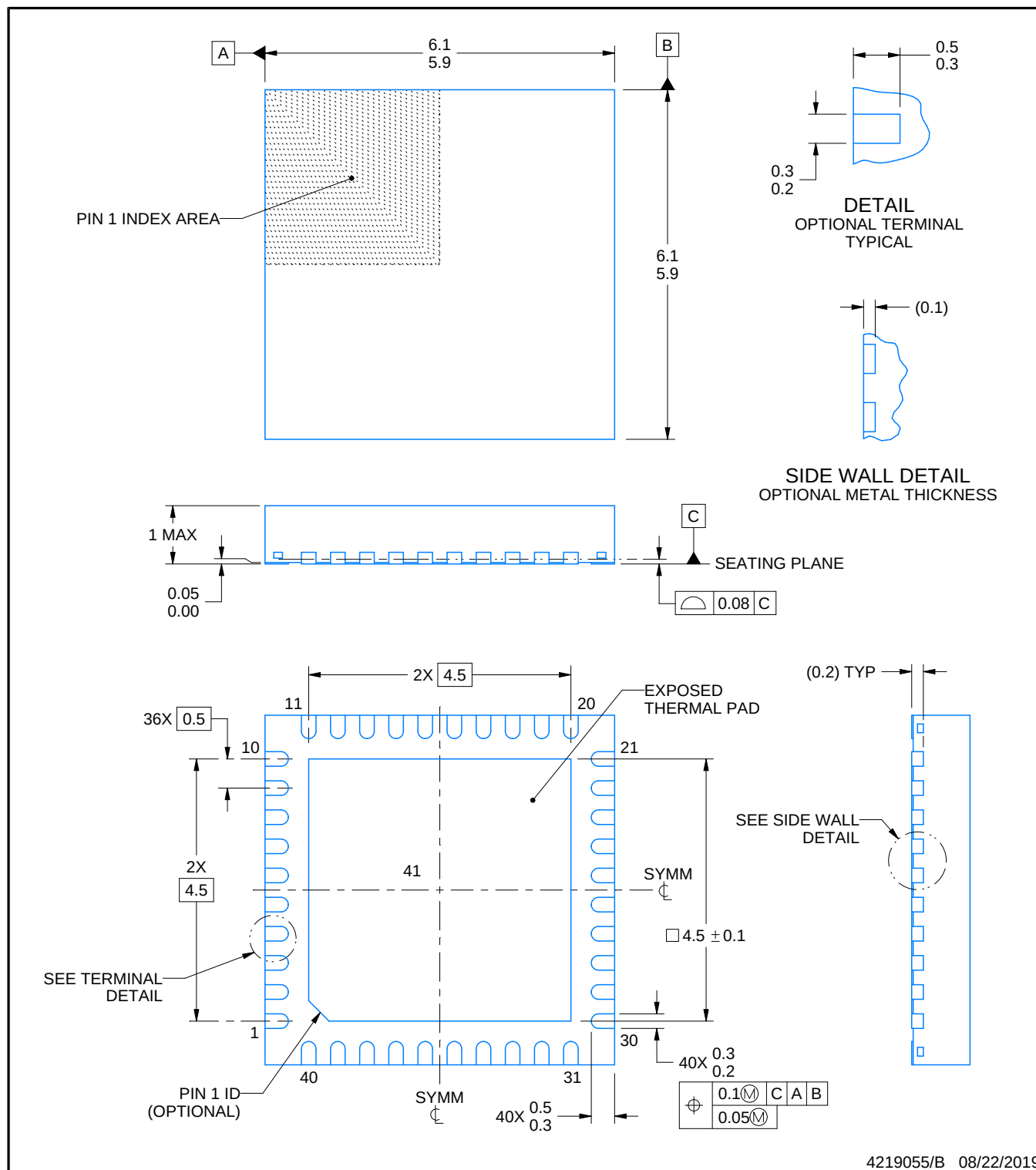
This image is a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.





VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD

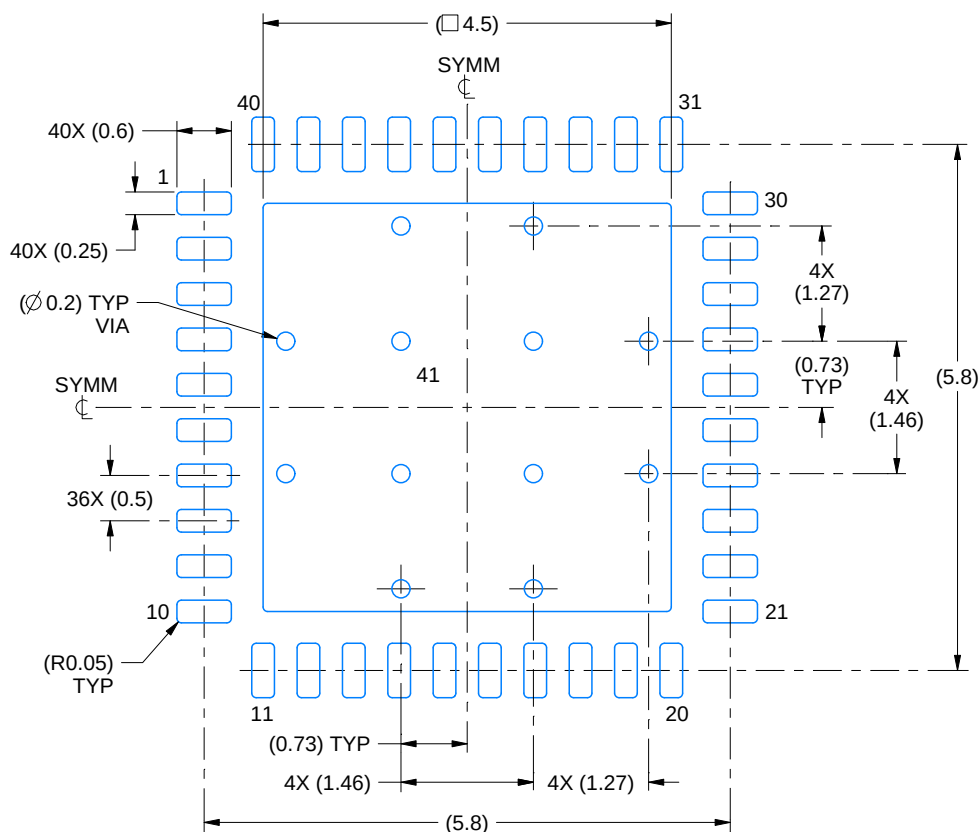


1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

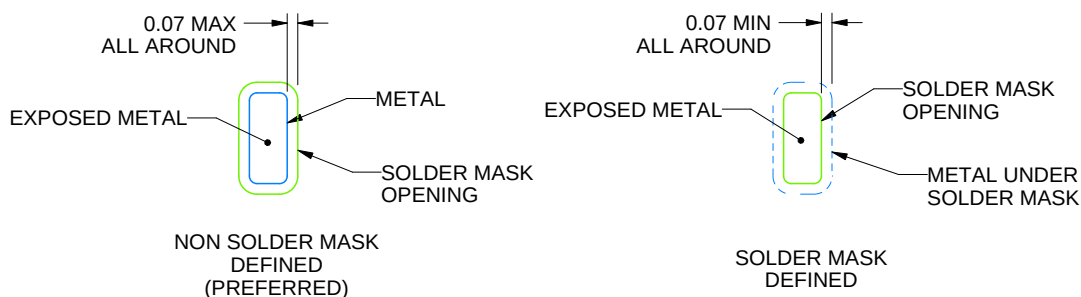
RHA0040H

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:12X



SOLDER MASK DETAILS

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NOTES: (continued)

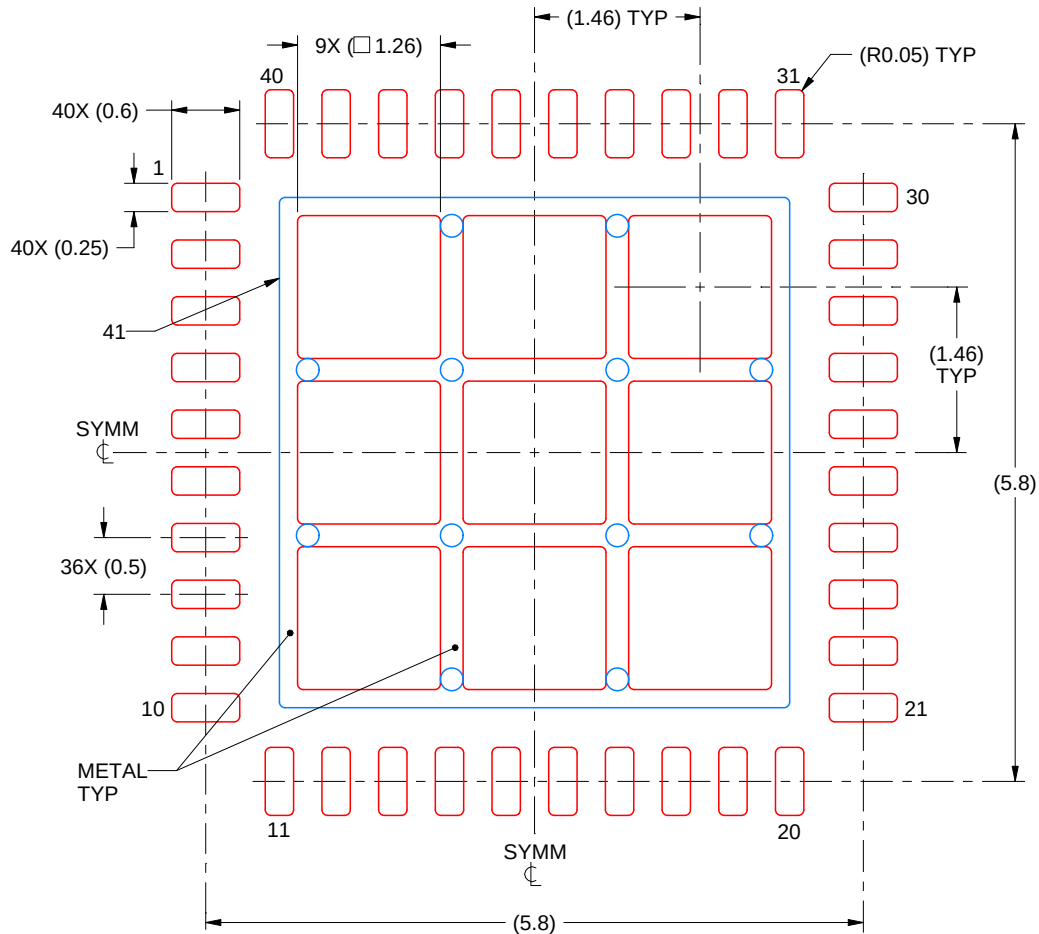
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

EXAMPLE STENCIL DESIGN

RHA0040H

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 41:
70% PRINTED SOLDER COVERAGE BY AREA
SCALE:15X

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NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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Last updated 10/2025