

# INA296x –5V to 110V, Bidirectional, 1.1MHz, 8V/µs, Ultra-Precise Current Sense **Amplifier**

#### 1 Features

- Wide common-mode voltage:
  - Operational voltage: -5V to 110V
  - Survival voltage: -20V to 120V
- Bidirectional operation
- High small signal bandwidth: 1.1MHz (at all gains)
- Slew rate: 8V/µs
- Step response settling time to 1%: 1µs
- Excellent CMRR: 166dB
- Accuracy:
  - Gain error (maximum)
    - Version A: ±0.01%, ±1ppm/°C drift
    - Version B: ±0.1%, ±5ppm/°C drift
  - Offset voltage (maximum)
    - Version A: ±10µV, ±0.1µV/°C drift
    - Version B: ±150µV, ±0.5µV/°C drift
- Available gains:
  - INA296A1, INA296B1: 10V/V
  - INA296A2, INA296B2 : 20V/V
  - INA296A3, INA296B3: 50V/V
  - INA296A4, INA296B4 : 100V/V
  - INA296A5, INA296B5 : 200V/V
- Package options: SOT23-8, VSSOP-8, SOIC-8,

## 2 Applications

- 48V DC/DC Converter
- 48V battery management systems (BMS)
- Test & Measurement
- Macro remote radio unit (RRU)
- 48V rack server
- 48V merchant network & server power supply (PSU)

## 3 Description

The INA296x is an ultra-precise, bidirectional current sense amplifier that can measure voltage drops across shunt resistors over a wide common-mode range from -5V to 110V, independent of the supply voltage. The high-precision current measurement is achieved through a combination of low offset voltage (±10µV, maximum), small gain error (±0.01%, maximum) and a high DC CMRR (typical 166dB). The INA296x is not only designed for high voltage, bidirectional DC current measurements, but also for high-speed applications (such as transient detection and fast overcurrent protection) with a high signal bandwidth of 1.1MHz and fast settling time.

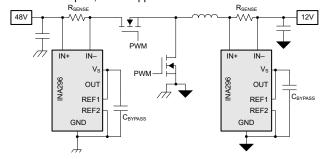
The INA296x operates from a single 2.7V to 20V supply, drawing 2.5mA of supply current. The INA296x is available in five gain options: 10V/V, 20V/V, 50V/V, 100V/V, and 200V/V. Multiple gain options allow for optimization between available shunt resistor values and wide output dynamic range requirements.

The INA296x is specified over operating temperature range of -40°C to 125°C.

## **Package Information**

PART NUMBER	PACKAGE <sup>(1)</sup>	PACKAGE SIZE <sup>(2)</sup>
	DDF (SOT-23, 8)	2.9mm × 2.8mm
INA296A INA296B	DGK (VSSOP, 8)	3mm × 4.9mm
	D (SOIC, 8)	4.9mm × 6mm

- For all available packages, see the package option addendum at the end of the data sheet.
- The package size (length × width) is a nominal value and includes pins, where applicable.



Typical Application - DC/DC Converter



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## **4 Device Comparison**

**Table 4-1. Device Comparison** 

DEVICE NAME	GAIN
INA296A1, INA296B1	10V/V
INA296A2, INA296B2	20V/V
INA296A3, INA296B3	50V/V
INA296A4, INA296B4	100V/V
INA296A5, INA296B5	200V/V

# **5 Pin Configuration and Functions**

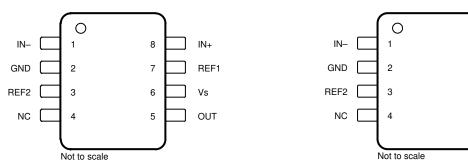


Figure 5-1. INA296x: DDF Package 8-Pin SOT-23
Top View

Figure 5-2. INA296x: D and DGK Package 8-Pin SOIC and 8-Pin VSSOP Top View

Table 5-1. Pin Functions: D, DDF and DGK Packages

	PIN	TYPE	PE DESCRIPTION	
NAME	NO.	1176	DESCRIPTION	
GND	2	Ground	Ground.	
IN+	8	Input	Current-sense amplifier positive input. For high-side applications, connect to bus-voltage side of sense resistor. For low-side applications, connect to load side of sense resistor.	
IN-	1	Input	Current-sense amplifier negative input. For high-side applications, connect to load side of sense resistor. For low-side applications, connect to ground side of sense resistor.	
NC	4	Ground	Reserved. Connect to ground.	
OUT	5	Output	Output voltage.	

IN+

REF1

۷s

OUT

7

6



Table 5-1. Pin Functions: D, DDF and DGK Packages (continued)

PIN		TYPE	DESCRIPTION		
NAME	NO.	1112	DESCRIF HON		
REF1	7	Input	Reference 1 voltage. Connect to voltage potential from 0V to $V_S$ ; see <i>Adjusting the Output With the Reference Pins</i> for connection options.		
REF2 3 Input		Input	Reference 2 voltage. Connect to voltage potential from 0V to $V_S$ ; see <i>Adjusting the Output With the Reference Pins</i> for connection options.		
Vs	6	Power	Power supply, 2.7V to 20V		



## **6 Specifications**

## **6.1 Absolute Maximum Ratings**

over operating free-air temperature range (unless otherwise noted)(1)

		MIN	MAX	UNIT
Supply voltage (V <sub>S</sub> )			22	V
Analog inputs,	Differential (V <sub>IN+</sub> ) - (V <sub>IN-</sub> )	-30	30	V
V <sub>IN+</sub> , V <sub>IN-</sub> (2)	Common-mode	-20	120	V
REF1, REF2, NC inputs		GND - 0.3	V <sub>S</sub> + 0.3	V
Output		GND - 0.3	Vs + 0.3	V
T <sub>A</sub>	Operating temperature	<b>–</b> 55	150	°C
TJ	Junction temperature		150	°C
T <sub>stg</sub>	Storage temperature	-65	150	°C

<sup>(1)</sup> Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

(2)  $V_{IN+}$  and  $V_{IN-}$  are the voltages at the IN+ and IN- pins, respectively.

## 6.2 ESD Ratings

			VALUE	UNIT
V	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/ JEDEC JS-001, all pins <sup>(1)</sup>	±2000	V
V <sub>(ESD)</sub>		Charged device model (CDM), per ANSI/ESDA/ JEDEC JS-002, all pins <sup>(2)</sup>	±1000	V

<sup>(1)</sup> JEDEC document JEP155 states that 500V HBM allows safe manufacturing with a standard ESD control process.

## **6.3 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V <sub>CM</sub>	Common-mode input range	-5	48	110	V
Vs	Operating supply range	2.7	5	20	V
T <sub>A</sub>	Ambient temperature	-40		125	°C

#### 6.4 Thermal Information

			INA296x			
THERMAL METRIC(1)		DDF (SOT23)	DGK (VSSOP)	D (SOIC)	UNIT	
		8 PINS	8 PINS	8 PINS		
$R_{\theta JA}$	Junction-to-ambient thermal resistance	129.7	167.2	122.9	°C/W	
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	58	58.9	54.7	°C/W	
$R_{\theta JB}$	Junction-to-board thermal resistance	52.6	88.9	68.8	°C/W	
$\Psi_{JT}$	Junction-to-top characterization parameter	2.3	8.1	12.2	°C/W	
$\Psi_{JB}$	Junction-to-board characterization parameter	52.3	87.4	67.5	°C/W	

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application note.

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<sup>(2)</sup> JEDEC document JEP157 states that 250V CDM allows safe manufacturing with a standard ESD control process.



## **6.5 Electrical Characteristics**

 $\underline{\text{at T}_{\text{A}} = 25 \text{ °C, V}_{\text{S}} = 5\text{V, V}_{\text{SENSE}} = \text{V}_{\text{IN+}} - \text{V}_{\text{IN-}}, \text{V}_{\text{CM}} = \text{V}_{\text{IN-}} = 48\text{V, and V}_{\text{REF1}} = \text{V}_{\text{REF2}} = \text{V}_{\text{S}} \text{ / 2 (unless otherwise noted) }$ 

at 1 <sub>A</sub> 2	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
INPUT						
V <sub>CM</sub>	Common-mode input range <sup>(1)</sup>	V <sub>IN+</sub> , V <sub>IN-</sub> = -5V to 110V, V <sub>SENSE</sub> = 0mV T <sub>A</sub> = -40°C to 125°C	-5		110	V
		V <sub>IN+</sub> , V <sub>IN-</sub> = -5V to 110V, V <sub>SENSE</sub> = 0mV T <sub>A</sub> = -40°C to 125°C, INA296A	150	166		
CMRR	Common-mode rejection ratio, input- referred	$V_{IN+}$ , $V_{IN-} = -5V$ to 110V, $V_{SENSE} = 0$ mV $T_A = -40$ °C to 125°C, INA296B	120	130		dB
		f = 50kHz		105		
		V <sub>SENSE</sub> = 0mV, INA296A1		±5	±20	
		V <sub>SENSE</sub> = 0mV, INA296A2		±3	±15	
$V_{os}$	Offset voltage, input-referred	V <sub>SENSE</sub> = 0mV, INA296A3, INA296A4		±3	±10	μV
		V <sub>SENSE</sub> = 0mV, INA296A5		±2	±8	
		V <sub>SENSE</sub> = 0mV, INA296B		±25	±150	
		T <sub>A</sub> = -40°C to 125°C, INA296A1		±50	±250	
	Offset voltage drift, input-referred	T <sub>A</sub> = -40°C to 125°C, INA296A2		±30	±150	nV/°C
dV <sub>os</sub> /dT		T <sub>A</sub> = -40°C to 125°C, INA296A3, INA296A4, INA296A5		±20	±100	
		T <sub>A</sub> = -40°C to 125°C, INA296B		±100	±500	
	Power-supply rejection ratio, input- referred	$V_S = 2.7V \text{ to } 20V, V_{SENSE} = 0\text{mV}, \\ V_{REF1} = V_{REF2} = 1V, \\ T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C, INA296A1}$		±0.2	±1	μV/V
		$V_S = 2.7V \text{ to } 20V, V_{SENSE} = 0\text{mV}, V_{REF1} = V_{REF2} = 1V, T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C}, INA296A2$		±0.1	±0.75	
PSRR		$V_S$ = 2.7V to 20V, $V_{SENSE}$ = 0mV, $V_{REF1}$ = $V_{REF2}$ = 1V, $T_A$ = -40°C to 125°C, INA296A3, INA296A4, INA296A5		±0.06	±0.5	
		$V_S = 2.7V \text{ to } 20V, V_{SENSE} = 0\text{mV}, \\ V_{REF1} = V_{REF2} = 1V, \\ T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C, INA296B}$		±1	±10	
I <sub>B</sub>	Input bias current	I <sub>B+</sub> , I <sub>B-</sub> , V <sub>SENSE</sub> =0mV	25	35	45	μA
	Reference input range		0		Vs	V
OUTPUT						
		A1, B1 Devices		10		V/V
		A2, B2 Devices		20		V/V
G	Gain	A3, B3 Devices		50		V/V
		A4, B4 Devices		100		V/V
		A5, B5 Devices		200		V/V



at  $T_A = 25$  °C,  $V_S = 5V$ ,  $V_{SENSE} = V_{IN+} - V_{IN-}$ ,  $V_{CM} = V_{IN-} = 48V$ , and  $V_{REF1} = V_{REF2} = V_S / 2$  (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
		(GND + 50mV) < V <sub>OUT</sub> < (V <sub>S</sub> - 200mV), INA296A1, INA296A2, INA296A3	±0.002	±0.01	
	Gain Error	(GND + 50mV) < V <sub>OUT</sub> < (V <sub>S</sub> - 200mV), INA296A4, INA296A5	±0.003	±0.015	%
C		(GND + 50mV) < V <sub>OUT</sub> < (V <sub>S</sub> - 200mV), INA296B	±0.02	±0.1	
G <sub>ERR</sub>		T <sub>A</sub> = -40°C to +125°C, INA296A1, INA296A2, INA296A3	±0.05	±1	
	Gain Error Drift	T <sub>A</sub> = -40°C to +125°C, INA296A4, INA296A5	±0.1	±2	ppm/°C
		T <sub>A</sub> = -40°C to +125°C, INA296B	±0.2	±5	
	Non-Linearity Error		±0.001		%
	Maximum Capacitive Load	No sustained oscillations, No isolation resistor	1		nF
VOLTAC	GE OUTPUT				
	Swing to V <sub>S</sub> Power Supply Rail	$R_L = 10k\Omega$ to GND, $T_A = -40^{\circ}\text{C}$ to +125°C	V <sub>S</sub> - 0.07	V <sub>S</sub> - 0.2	V
	Swing to Ground	$R_L$ = 10k $\Omega$ to GND, $V_{SENSE}$ = 0mV, $V_{REF1}$ = $V_{REF2}$ = 0V, $V_{A}$ = -40°C to +125°C	8	20	mV
REFERE	ENCE INPUT				
		V <sub>REF1</sub> = V <sub>REF2</sub> = 0.5V to 4.5V, T <sub>A</sub> = -40°C to +125°C, INA296A1,	±1	±2.5	
RVRR	Reference voltage rejection ratio, input- referred	V <sub>REF1</sub> = V <sub>REF2</sub> = 0.5V to 4.5V, T <sub>A</sub> = -40°C to +125°C, INA296A2, INA296A3, INA296A4, INA296A5	±0.5	±1.5	μV/V
		V <sub>REF1</sub> = V <sub>REF2</sub> = 0.5V to 4.5V, T <sub>A</sub> = -40°C to +125°C, INA296B	±10	±20	
		$\begin{split} &V_{OUT} =  (V_{REF1} + V_{REF2})  \ / \ 2 \ at \ V_{SENSE} \\ = &0 mV, \\ &V_{REF1} = V_S, \ V_{REF2} = GND \\ &V_{REF1} = GND, \ V_{REF2} = V_S \\ &T_A = -40 ^{\circ}C \ to \ +125 ^{\circ}C, \ INA296A1, \\ &INA296A2, \end{split}$	±0.002	±0.005	
	Reference divider accuracy	$\begin{split} &V_{OUT} =  (V_{REF1} + V_{REF2})  \ / \ 2 \ at \ V_{SENSE} \\ = &0 mV, \\ &V_{REF1} = V_S, \ V_{REF2} = GND \\ &V_{REF1} = GND, \ V_{REF2} = V_S \\ &T_A = -40^{\circ}C \ to \ +125^{\circ}C, \ INA296A3, \\ &INA296A4, \ INA296A5 \end{split}$	±0.002	±0.01	%
		$V_{OUT} =  (V_{REF1} + V_{REF2})  / 2 \text{ at } V_{SENSE}$ =0mV, $V_{REF1} = V_S, V_{REF2} = GND$ $V_{REF1} = GND, V_{REF2} = V_S$ $T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C, INA296B}$	±0.02	±0.15	
FREQU	ENCY RESPONSE				
BW	Bandwidth	All Gains, -3dB Bandwidth	1.1		MHz
		$V_{\text{IN+}}$ , $V_{\text{IN-}}$ = 48V, $V_{\text{OUT}}$ = 0.5V to 4.5V, Output settles to 0.5%	1.5		μs
	Settling time	$V_{\text{IN+}}$ , $V_{\text{IN-}}$ = 48V, $V_{\text{OUT}}$ = 0.5V to 4.5V, Output settles to 1%	1		μs
		$V_{\text{IN+}}$ , $V_{\text{IN-}}$ = 48V, $V_{\text{OUT}}$ = 0.5V to 4.5V, Output settles to 5%	0.5		μs
SR	Slew Rate	Rising	8		V/µs

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at  $T_A = 25$  °C,  $V_S = 5V$ ,  $V_{SENSE} = V_{IN+} - V_{IN-}$ ,  $V_{CM} = V_{IN-} = 48V$ , and  $V_{REF1} = V_{REF2} = V_S / 2$  (unless otherwise noted)

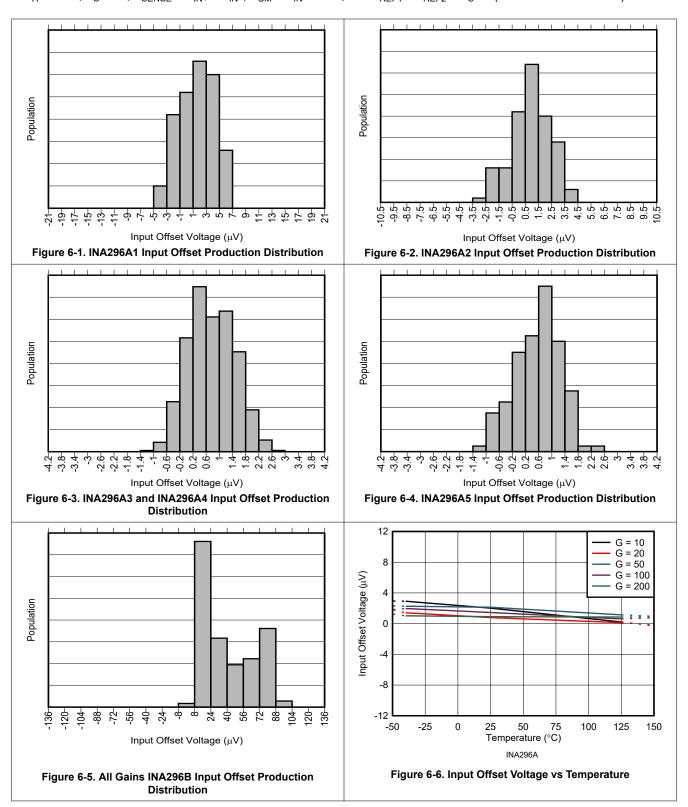
	PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
NOISE	(Input referred)				
		A1, B1 Devices	62		
		A2, B2 Devices	49		
	Voltage noise density	A3, B3 Devices	39		nV/√Hz
		A4, B4 Devices	36		
		A5, B5 Devices	28		
POWE	ER SUPPLY				
Vs	Supply Voltage		2.7	20	V
		V <sub>SENSE</sub> = 0mV	2.5	3	mA
IQ	Quiescent current	$V_{SENSE} = 0$ mV, $T_A = -40$ °C to +125°C		3.2	mA
TEMP	ERATURE				
T <sub>A</sub>	Specified Range		-40	125	°C

<sup>(1)</sup> Common-mode voltage at both  $V_{IN+}$  and  $V_{IN-}$  must not exceed the specified common-mode input range.

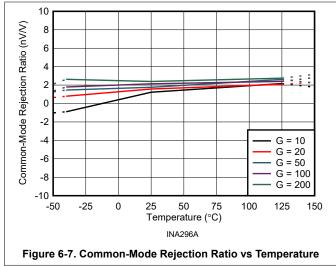


## 6.6 Typical Characteristics

at  $T_A = 25$ °C,  $V_S = 5$ V,  $V_{SENSE} = V_{IN+} - V_{IN-}$ ,  $V_{CM} = V_{IN-} = 48$ V, and  $V_{REF1} = V_{REF2} = V_S$  / 2 (unless otherwise noted)

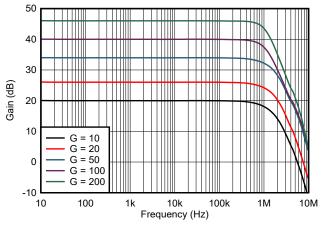


at  $T_A = 25$ °C,  $V_S = 5$ V,  $V_{SENSE} = V_{IN+} - V_{IN-}$ ,  $V_{CM} = V_{IN-} = 48$ V, and  $V_{REF1} = V_{REF2} = V_S$  / 2 (unless otherwise noted)



Common-Mode Rejection Ratio (dB) 160 140 120 100 80 60 40 10 100 10M 1 100k 1M 1k 10k Frequency (Hz) INA296A

Figure 6-8. Common-Mode Rejection Ratio vs Frequency



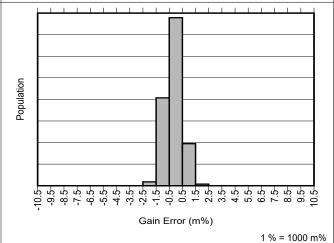
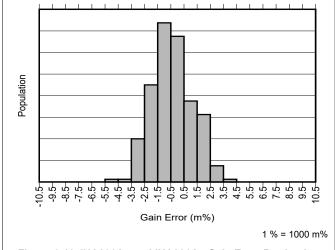


Figure 6-9. Gain vs Frequency

Figure 6-10. INA296A1, INA296A2 and INA296A3 Gain Error Production Distribution



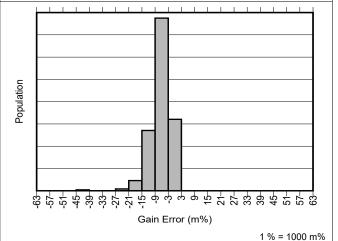
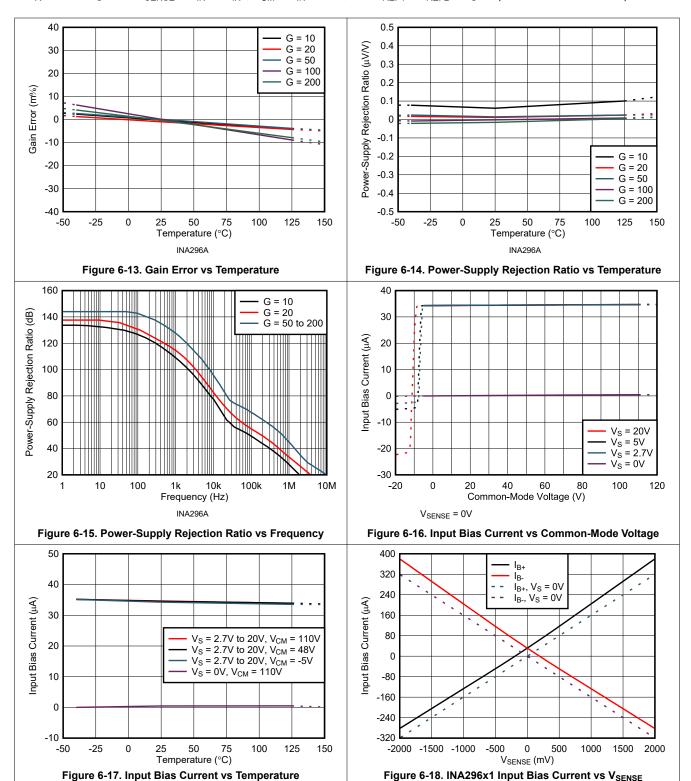


Figure 6-11. INA296A4 and INA296A5 Gain Error Production Distribution

Figure 6-12. All Gains INA296B Gain Error Production
Distribution

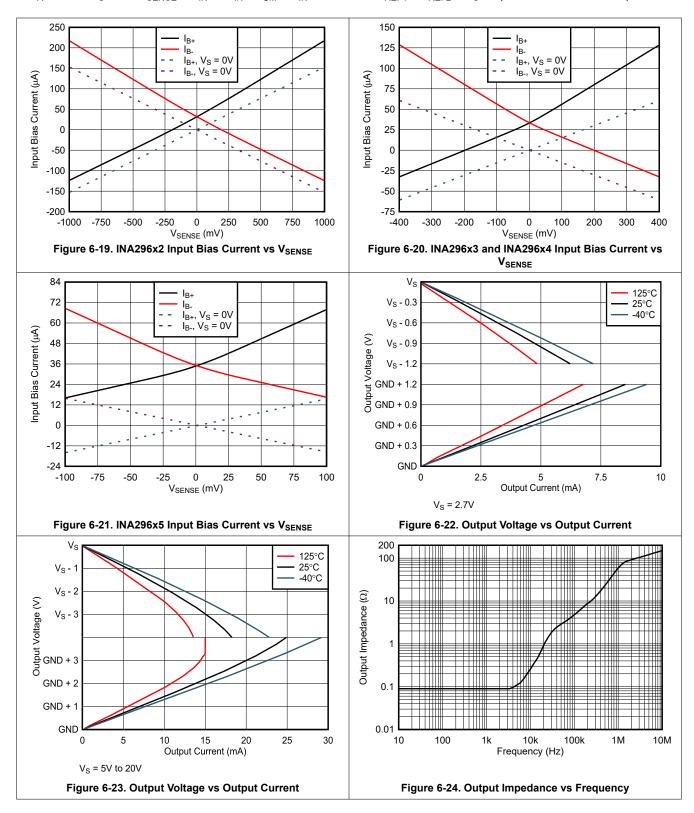


at  $T_A = 25$ °C,  $V_S = 5$ V,  $V_{SENSE} = V_{IN+} - V_{IN-}$ ,  $V_{CM} = V_{IN-} = 48$ V, and  $V_{REF1} = V_{REF2} = V_S$  / 2 (unless otherwise noted)



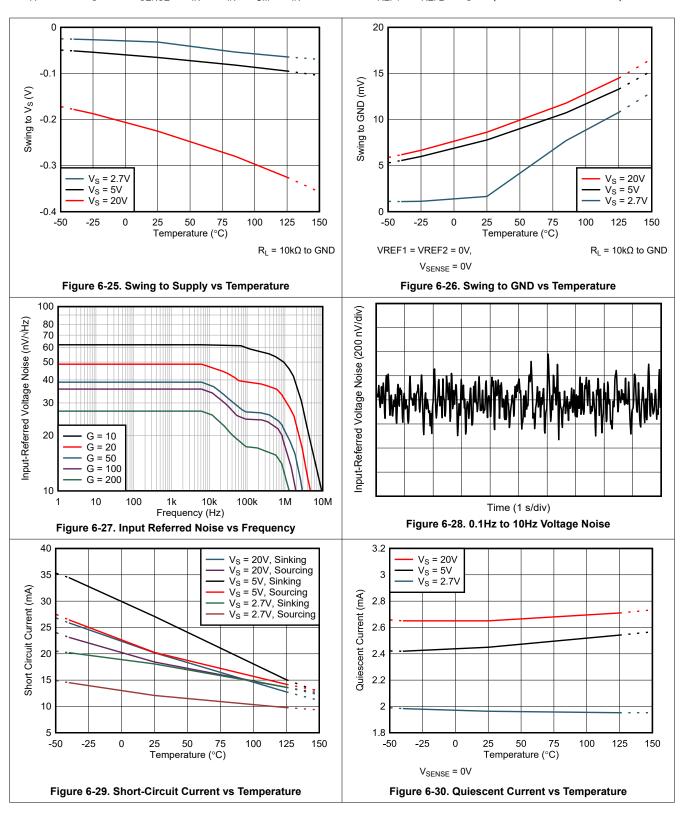


at  $T_A = 25$ °C,  $V_S = 5$ V,  $V_{SENSE} = V_{IN+} - V_{IN-}$ ,  $V_{CM} = V_{IN-} = 48$ V, and  $V_{REF1} = V_{REF2} = V_S / 2$  (unless otherwise noted)



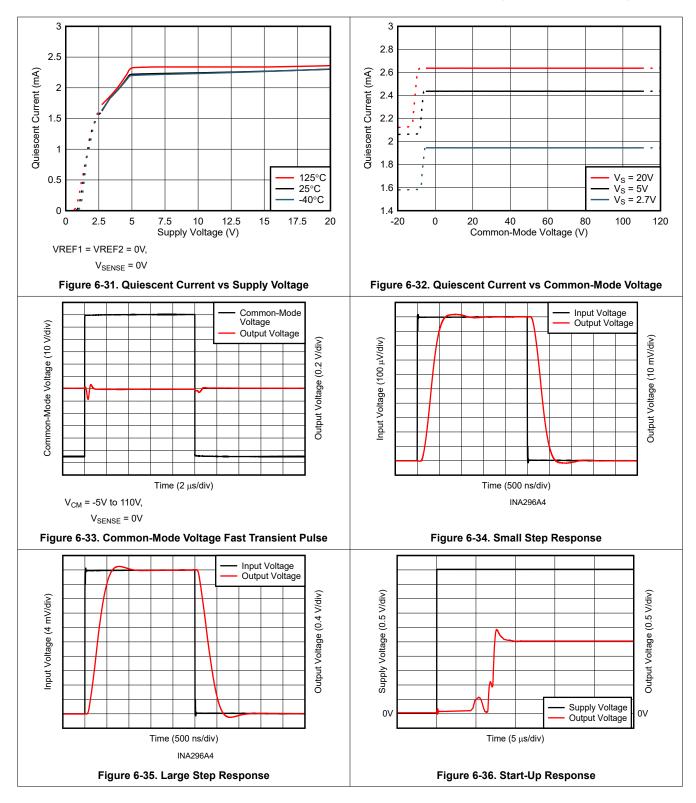


at  $T_A$  = 25°C,  $V_S$  = 5V,  $V_{SENSE}$  =  $V_{IN+}$  –  $V_{IN-}$ ,  $V_{CM}$  =  $V_{IN-}$  = 48V, and  $V_{REF1}$  =  $V_{REF2}$  =  $V_S$  / 2 (unless otherwise noted)



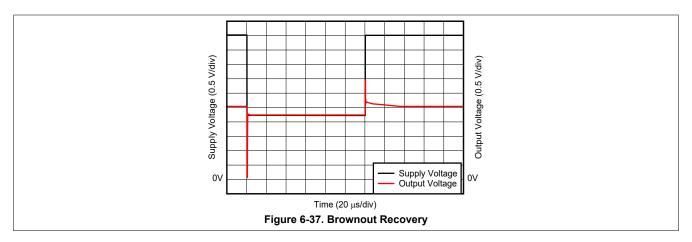


at  $T_A = 25$ °C,  $V_S = 5$ V,  $V_{SENSE} = V_{IN+} - V_{IN-}$ ,  $V_{CM} = V_{IN-} = 48$ V, and  $V_{REF1} = V_{REF2} = V_S / 2$  (unless otherwise noted)





at  $T_A = 25$ °C,  $V_S = 5$ V,  $V_{SENSE} = V_{IN+} - V_{IN-}$ ,  $V_{CM} = V_{IN-} = 48$ V, and  $V_{REF1} = V_{REF2} = V_S$  / 2 (unless otherwise noted)

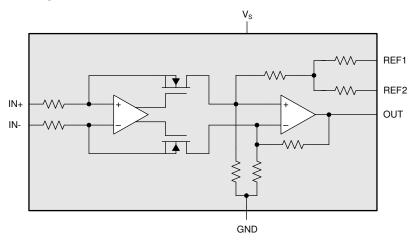


## 7 Detailed Description

#### 7.1 Overview

The INA296x is a high-side, inline, or low-side bidirectional, high-speed current-sense amplifier that offers a wide common-mode range, precision zero-drift topology, excellent common-mode rejection ratio (CMRR) and fast slew rate. Different gain versions are available to optimize the output dynamic range based on the application. The INA296x is designed using an architecture that enables low bias currents of 35μA with a specified common-mode voltage range from –5V to 110V with signal bandwidths up to 1.1MHz.

## 7.2 Functional Block Diagram



## 7.3 Feature Description

#### 7.3.1 Amplifier Input Common-Mode Signal

The INA296x supports large input common-mode voltages from -5V to 110V. The internal topology of the INA296x allows the common-mode range to exceed the power-supply voltage ( $V_S$ ). This allows for the INA296x to be used for low-side, inline, and high-side current-sensing applications that extend beyond the supply range of 2.7V to 20V.

#### 7.3.1.1 Input-Signal Bandwidth

The INA296x is available with several gain options including 10V/V, 20V/V, 50V/V, 100V/V, and 200V/V. The unique multistage design enables the amplifier to achieve high bandwidth of 1.1MHz at all gains. This high bandwidth provides the throughput and fast response that is required for the rapid detection and processing of over-current events.

### 7.3.1.2 Low Input Bias Current

The INA296x inputs draw 35µA (typical) bias current per input pin at common-mode voltages as high as 110V, which enables precision current sensing on applications that require lower current leakage. Unlike many high voltage current sense amplifiers whose input bias currents are proportional to the common-mode voltage, the input bias current of the INA296x remains constant over the entire common-mode voltage range.

### 7.3.1.3 Low V<sub>SENSE</sub> Operation

The INA296x features high performance operation across the entire valid  $V_{SENSE}$  range. The zero-drift input architecture of the INA296x provides the low offset voltage and low offset drift needed to measure low  $V_{SENSE}$  levels accurately across the wide operating temperature of  $-40^{\circ}$ C to  $+125^{\circ}$ C. Low  $V_{SENSE}$  operation is particularly beneficial when using low ohmic shunts for low current measurements, as power losses across the shunt are significantly reduced.

#### 7.3.1.4 Wide Fixed Gain Output

The INA296x maximum gain error is  $\pm 0.01\%$  at room temperature, with a maximum drift of  $\pm 1$  ppm/°C over the full temperature range of -40°C to 125°C. The INA296x is available in multiple gain options of 10V/V, 20V/V,

50V/V, 100V/V, and 200V/V, which the system designer must select based on the desired signal-to-noise ratio and other system requirements, such as the dynamic current range and full-scale output voltage target.

#### 7.3.1.5 Wide Supply Range

The INA296x operates with a wide supply range from 2.7V to 20V. While the input common-mode voltage range of the INA296x is independent of the supply voltage, the output voltage is bound by the supply voltage applied to the device. The output voltage can range from as low as 20mV to as high as 200mV below the supply voltage.

#### 7.4 Device Functional Modes

## 7.4.1 Adjusting the Output With the Reference Pins

Figure 7-1 shows a test circuit for reference-divider accuracy. The INA296x output is configurable to allow for unidirectional or bidirectional operation.

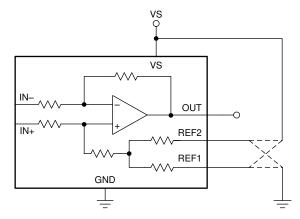


Figure 7-1. Test Circuit For Reference Divider Accuracy

The output voltage is set by applying a voltage or voltages to the reference voltage inputs, REF1 and REF2. The reference inputs are connected to an internal gain network. There is no operational difference between the two reference pins. The resistor network connected to the two reference pins are designed with ultra-precision and matching. Output is set accurately at the mid-point voltage between the voltages applied to reference voltage inputs, when current-sense input voltage is 0V as shown in Equation 1. In most bidirectional applications, one reference input is connected to the positive supply and the other reference input is connected to the negative supply (GND pin) to set the output voltage to mid-supply.

$$V_{OUT} = G \times (V_{IN} + V_{IN}) + \frac{V_{REF1} + V_{REF2}}{2}$$
 (1)

#### 7.4.2 Reference Pin Connections for Unidirectional Current Measurements

Unidirectional operation allows current measurements through a resistive shunt in one direction. For unidirectional operation, connect the device reference pins together and then to the negative rail (see the Ground Referenced Output section) or the positive rail (see the VS Referenced Output section). The required differential input polarity depends on the reference input setting. The amplifier output moves away from the referenced rail proportional to the current passing through the external shunt resistor. If the amplifier reference pins are connected to the positive rail, then the input polarity must be negative to move the amplifier output down (towards ground). If the amplifier reference pins are connected to ground, then the input polarity must be positive to move the amplifier output up (towards supply).

The following sections describe how to configure the output for unidirectional operation cases.

## 7.4.2.1 Ground Referenced Output

When using the INA296x in a unidirectional mode with a ground referenced output, both reference inputs are connected to ground. This configuration takes the output to ground when there is a 0V differential at the input (see Figure 7-2).

Product Folder Links: INA296A INA296B

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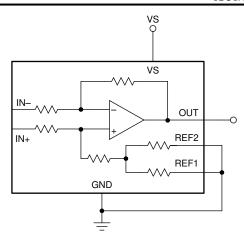


Figure 7-2. Ground Referenced Output

#### 7.4.2.2 VS Referenced Output

Unidirectional mode with a VS referenced output is configured by connecting both reference pins to the positive supply. Use this configuration for circuits that require power up and stabilization of the amplifier output signal and other control circuitry before power is applied to the load (see Figure 7-3).

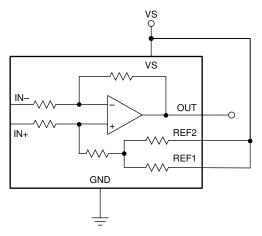


Figure 7-3. VS Referenced Output

#### 7.4.3 Reference Pin Connections for Bidirectional Current Measurements

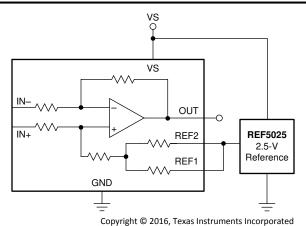
The INA296x measures the differential voltage developed by current flowing through a resistor, commonly referred to as a current-sensing resistor or a current-shunt resistor. The INA296x can operate in either a unidirectional or bidirectional mode based on the voltage potential placed on the reference pins.

The linear range of the output stage is limited to how close the output voltage can approach ground as well the supply voltage as described in the *Specifications*. The selection of the current-sensing resistor along with the current range to be measured, selection of the gain option, as well as the voltage applied to the reference pins must be selected to keep the INA296x within the linear region of operation.

#### 7.4.3.1 Output Set to External Reference Voltage

Connecting both pins together and then to a reference voltage results in an output voltage equal to the reference voltage for the condition of shorted input pins or a 0V differential input. Figure 7-4 shows this configuration. The output voltage decreases below the reference voltage when the IN+ pin is negative relative to the IN- pin and increases when the IN+ pin is positive relative to the IN- pin. This technique is the most accurate way to bias the output to a precise voltage.





-----

## Figure 7-4. External Reference Output

#### 7.4.3.2 Output Set to Mid-Supply Voltage

By connecting one reference pin to VS and the other to the GND pin, Figure 7-5 shows that the output is set at half of the supply voltage when there is no differential input. This method creates a ratiometric offset to the supply voltage, where the output voltage remains at VS / 2 for 0V applied to the inputs.

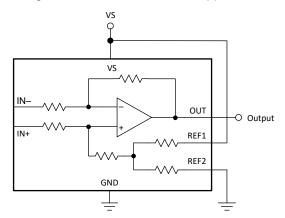


Figure 7-5. Mid-Supply Voltage Output

#### 7.4.3.3 Output Set to Mid-External Reference

In this case, Figure 7-6 shows how an external reference can divided by two by connecting one REF pin to ground and the other REF pin to the reference.

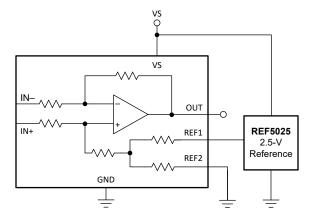


Figure 7-6. Mid-External Reference Output

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#### 7.4.3.4 Output Set Using Resistor Divider

The INA296x reference pins allow for the mid-point of the output voltage to be adjusted for system circuitry connections to analog to digital converters (ADCs) or other amplifiers. The reference pins are designed to be connected directly to supply, ground, or a low-impedance reference voltage. The reference pins can be connected together and biased using a resistor divider to achieve a custom output voltage. If the amplifier is used in this configuration, as shown in Figure 7-7, use the output as a differential signal with respect to the resistor divider voltage. Use of the amplifier output as a single-ended signal in this configuration is not recommended because the internal impedance shifts can adversely affect device performance specifications. If single-ended measurement is required, TI recommends to use an external op amp to buffer the resistor divider voltage (see Figure 7-8).

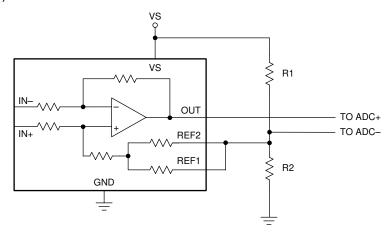


Figure 7-7. Setting the Reference Using a Resistor Divider

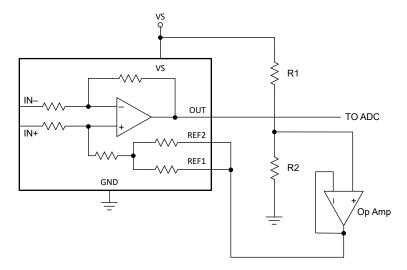


Figure 7-8. Setting the Reference Using a Resistor Divider and an Op Amp buffer

### 7.4.4 High Signal Throughput

With a bandwidth of 1.1MHz at a gain of 20V/V and a slew rate of 8V/ $\mu$ s, the INA296x is specifically designed for detecting and protecting applications from fast inrush currents. As shown in Table 7-1, the INA296x responds in less than 1 $\mu$ s for a system measuring a 75A threshold on a 2m $\Omega$  shunt.

Table 7-1. Response Time

	PARAMETER	EQUATION	INA296x AT V <sub>S</sub> = 5V
G	Gain		20V/V
I <sub>MAX</sub>	Maximum current		100A



Table 7-1. Response Time (continued)

	PARAMETER	EQUATION	INA296x AT V <sub>S</sub> = 5V
I <sub>Threshold</sub>	Threshold current		75A
R <sub>SENSE</sub>	Current sense resistor value		2mΩ
V <sub>OUT_MAX</sub>	Output voltage at maximum current	V <sub>OUT_MAX</sub> = I <sub>MAX</sub> × R <sub>SENSE</sub> × G	4V
V <sub>OUT_THR</sub>	Output voltage at threshold current	V <sub>OUT_THR</sub> = I <sub>THR</sub> × R <sub>SENSE</sub> × G	3V
SR	Slew rate		8V/µs
T <sub>response</sub>	Output response time	T <sub>response</sub> = V <sub>OUT_THR</sub> / SR	< 1µs

## 8 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

## 8.1 Application Information

The INA296x amplifies the voltage developed across a current-sensing resistor as current flows through the resistor to the load. The wide input common-mode voltage range and high common-mode rejection of the INA296x make the device usable over a wide range of voltage rails while still maintaining an accurate current measurement.

#### 8.1.1 R<sub>SENSE</sub> and Device Gain Selection

The accuracy of any current-sense amplifier is maximized by choosing the largest current-sense resistor value possible. A larger value sense resistor maximizes the differential input signal for a given amount of current flow and reduces the error contribution of the offset voltage. However, there are practical limits as to how large the current-sense resistor value can be in a given application because of the physical dimensions of the package, package construction, and maximum power dissipation. Equation 2 gives the maximum value for the current-sense resistor for a given power dissipation budget:

$$R_{SENSE} < \frac{PD_{MAX}}{I_{MAX}^2} \tag{2}$$

#### where:

- PD<sub>MAX</sub> is the maximum allowable power dissipation in R<sub>SENSE</sub>.
- I<sub>MAX</sub> is the maximum current that flows through R<sub>SENSE</sub>.

An additional limitation on the size of the current-sense resistor and device gain is due to the power-supply voltage,  $V_S$ , and device swing-to-rail limitations. To make sure that the current-sense signal is properly passed to the output, both positive and negative output swing limitations must be examined. Equation 3 provides the maximum values of  $R_{SENSE}$  and GAIN to keep the device from exceeding the positive swing limitation.

$$I_{MAX} \times R_{SENSE} \times GAIN < V_{SP}$$
 (3)

#### where:

- I<sub>MAX</sub> is the maximum current that flows through R<sub>SENSE</sub>.
- · GAIN is the gain of the current-sense amplifier.
- V<sub>SP</sub> is the positive output swing of the device as specified in the Specifications.

To avoid positive output swing limitations when selecting the value of R<sub>SENSE</sub>, there is always a trade-off between the value of the sense resistor and the gain of the device under consideration. If the sense resistor selected for the maximum power dissipation is too large, then selecting a lower gain device is possible to avoid positive swing limitations.

The negative swing limitation places a limit on how small the sense resistor value can be for a given application. Equation 4 provides the limit on the minimum value of the sense resistor.

$$I_{MIN} \times R_{SENSE} \times GAIN > V_{SN}$$
 (4)

where:



- I<sub>MIN</sub> is the minimum current that flows through R<sub>SENSE</sub>.
- GAIN is the gain of the current-sense amplifier.
- V<sub>SN</sub> is the negative output swing of the device as specified in the Specifications.

Table 8-1 shows an example of the different results obtained from using five different gain versions of the INA296x. From the table data, the highest gain device allows a smaller current-shunt resistor and decreased power dissipation in the element.

			RESULTS AT V <sub>S</sub> = 5V							
PARAMETER		EQUATION	A1, B1 DEVICES	A2, B2 DEVICES	A3, B3 DEVICES	A4, B4 DEVICES	A5, B5 DEVICES			
G	Gain		10V/V	20V/V	50V/V	100V/V	200V/V			
V <sub>SENSE</sub>	Ideal differential input voltage	V <sub>SENSE</sub> = V <sub>OUT</sub> / G	500mV	250mV	100mV	50mV	25mV			
R <sub>SENSE</sub>	Current sense resistor value	R <sub>SENSE</sub> = V <sub>SENSE</sub> / I <sub>MAX</sub>	50mΩ	25mΩ	10mΩ	5mΩ	2.5mΩ			
P <sub>SENSE</sub>	Current-sense resistor power dissipation	R <sub>SENSE</sub> × I <sub>MAX</sub> 2	5W	2.5W	1W	0.5W	0.25W			

(1) Design example with 10A full-scale current with maximum output voltage set to 5V.

## 8.2 Typical Application

The INA296x is a bidirectional, current-sense amplifier capable of measuring currents through a resistive shunt with common-mode voltages from –5 V to +110 V.

#### 8.2.1 Current Sensing in a Solenoid Application

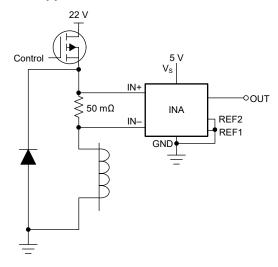


Figure 8-1. Solenoid Drive Application Circuit

#### 8.2.1.1 Design Requirements

In this example application, the common-mode voltage ranges from 0V to 22V. The maximum sense current is 1.25A, and a 5V supply is available for the INA296x. Following the design guidelines from  $R_{SENSE}$  and Device Gain Selection, a  $R_{SENSE}$  of  $50m\Omega$  and a gain of 20V/V are selected to provide good output dynamic range. Table 8-2 lists the design setup for this application.

Table 8-2. Design Parameters

	<u> </u>					
DESIGN PARAMETERS	EXAMPLE VALUE					
Power supply voltage	5V					
Common mode voltage range	0V to 22V					
Maximum sense current	1.25A					
R <sub>SENSE</sub> resistor	50mΩ					
Gain option	20V/V					

Product Folder Links: INA296A INA296B

#### 8.2.1.2 Detailed Design Procedure

The INA296x is designed to measure current in a typical solenoid application. The INA296x measures current across the  $50m\Omega$  shunt that is placed at the output in series with solenoid. The INA296x measures the differential voltage across the shunt resistor, and the signal is internally amplified with a gain of 20V/V. The output of the INA296x is connected to the analog-to-digital converter (ADC) of an MCU to digitize the current measurements.

Solenoid loads are highly inductive and are often prone to failure. Solenoids are often used for position control, precise fluid control, and fluid regulation. Measuring real-time current on the solenoid continuously can indicate premature failure of the solenoid, which can lead to a faulty control loop in the system. Measuring high-side current also indicates if there are any ground faults on the solenoid or the FETs that can be damaged in an application. The INA296x, with high bandwidth and slew rate, can be used to detect fast overcurrent conditions to prevent the solenoid damage from short-to-ground faults.

#### 8.2.1.3 Application Curve



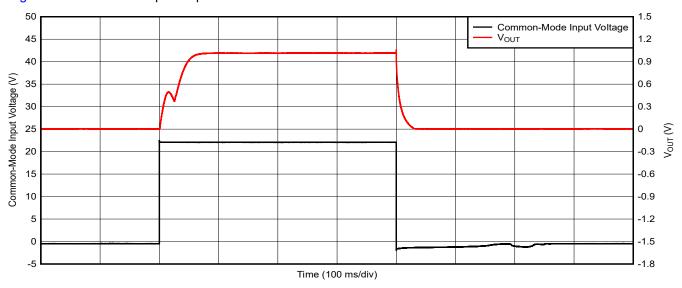


Figure 8-2. Solenoid Control Current Response

### 8.3 Power Supply Recommendations

The INA296x makes accurate measurements beyond the connected power-supply voltage ( $V_S$ ) because the inputs (IN+ and IN-) can operate anywhere between -5V and 110V independent of  $V_S$ . For example, with the  $V_S$  power supply equal to 5V, the common-mode voltage of the measured shunt can be as high as 110V.

## 8.3.1 Power Supply Decoupling

Place the power-supply bypass capacitor as close to the supply and ground pins as possible. TI recommends a bypass capacitor value of 0.1µF. Additional decoupling capacitance can be added to compensate for noisy or high-impedance power supplies.

### 8.4 Layout

#### 8.4.1 Layout Guidelines

Attention to good layout practices is always recommended.

• Connect the input pins to the sensing resistor using a Kelvin or 4-wire connection. This connection technique makes sure that only the current-sensing resistor impedance is detected between the input pins. Poor routing of the current-sensing resistor commonly results in additional resistance present between the input pins.



Given the very low ohmic value of the current sense resistor, any additional high-current carrying impedance can cause significant measurement errors.

• Place the power-supply bypass capacitor as close to the device power supply and ground pins as possible. The recommended value of this bypass capacitor is 0.1µF. Additional decoupling capacitance can be added to compensate for noisy or high-impedance power supplies.

## 8.4.2 Layout Examples

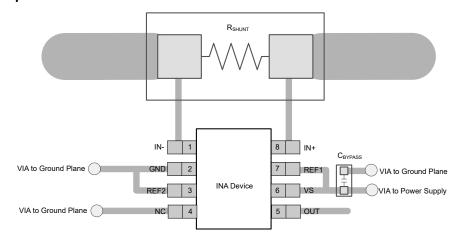


Figure 8-3. INA296x SOT-23 (DDF), SOIC (D) and VSSOP (DGK) Package Recommended Layout



## 9 Device and Documentation Support

## 9.1 Documentation Support

#### 9.1.1 Related Documentation

For related documentation see the following: Texas Instruments, INA296EVM, EVM user's guide

## 9.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 9.3 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

#### 9.4 Trademarks

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## 9.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 9.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

#### 10 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

## Changes from Revision C (October 2023) to Revision D (December 2024)

Page

- Updated the number format for tables, figures, and cross-references throughout the document.......
- Deleted DGS package information throughout the document; this package is available in automotive only.....1

#### Changes from Revision B (July 2023) to Revision C (October 2023)

Page

Deleted the preview note from D package from package information table and throughout the data sheet......1

## Changes from Revision A (August 2022) to Revision B (July 2023)

Page

Added DGS package in recommended layout examples......24



Cł	hanges from Revision * (March 2022) to Revision A (August 2022)	Page
•	Changed data sheet status from Advanced Information to Production Data	1

## 11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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## **PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
INA296A1IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SA3
INA296A1IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SA3
INA296A1IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TUB
INA296A1IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TUB
INA296A1IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A1
INA296A1IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A1
INA296A2IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SB3
INA296A2IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SB3
INA296A2IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TVB
INA296A2IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TVB
INA296A2IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A2
INA296A2IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A2
INA296A3IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SC3
INA296A3IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SC3
INA296A3IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TWB
INA296A3IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TWB
INA296A3IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A3
INA296A3IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A3
INA296A4IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SD3
INA296A4IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SD3
INA296A4IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TXB
INA296A4IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TXB
INA296A4IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A4
INA296A4IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A4
INA296A5IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SE3
INA296A5IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SE3
INA296A5IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TZB
INA296A5IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2TZB
INA296A5IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A5





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Orderable part number	Status (1)	Material type	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
INA296A5IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296A5
INA296B1IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SF3
INA296B1IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SF3
INA296B1IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U1B
INA296B1IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U1B
INA296B1IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B1
INA296B1IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B1
INA296B2IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SG3
INA296B2IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SG3
INA296B2IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U2B
INA296B2IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U2B
INA296B2IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B2
INA296B2IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B2
INA296B3IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SH3
INA296B3IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SH3
INA296B3IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U3B
INA296B3IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U3B
INA296B3IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B3
INA296B3IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B3
INA296B4IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SI3
INA296B4IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SI3
INA296B4IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U4B
INA296B4IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U4B
INA296B4IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B4
INA296B4IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B4
INA296B5IDDFR	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SJ3
INA296B5IDDFR.B	Active	Production	SOT-23-THIN (DDF)   8	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	2SJ3
INA296B5IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U5B
INA296B5IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2U5B
INA296B5IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B5
INA296B5IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I296B5

## PACKAGE OPTION ADDENDUM

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- (1) Status: For more details on status, see our product life cycle.
- (2) Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.
- (3) RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.
- (4) Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.
- (5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.
- (6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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#### OTHER QUALIFIED VERSIONS OF INA296A, INA296B:

Automotive: INA296A-Q1, INA296B-Q1

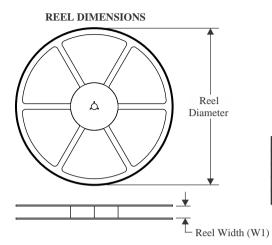
NOTE: Qualified Version Definitions:

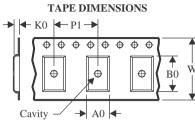
Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects



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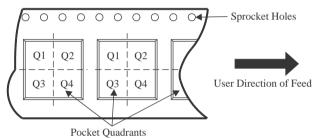
## TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadran
INA296A1IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296A1IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296A1IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
INA296A2IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296A2IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296A2IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
INA296A3IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296A3IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296A3IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
INA296A4IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296A4IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296A4IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1



# PACKAGE MATERIALS INFORMATION

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Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
INA296A5IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296A5IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296A5IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
INA296B1IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296B1IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296B1IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
INA296B2IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296B2IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296B2IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
INA296B3IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296B3IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296B3IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
INA296B4IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296B4IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296B4IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
INA296B5IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.15	3.1	1.55	4.0	8.0	Q3
INA296B5IDDFR	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
INA296B5IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA296B5IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1



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\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
INA296A1IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296A1IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296A1IDR	SOIC	D	8	2500	353.0	353.0	32.0
INA296A2IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296A2IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296A2IDR	SOIC	D	8	2500	340.5	336.1	25.0
INA296A3IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296A3IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296A3IDR	SOIC	D	8	2500	353.0	353.0	32.0
INA296A4IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296A4IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296A4IDR	SOIC	D	8	2500	353.0	353.0	32.0
INA296A5IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296A5IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296A5IDR	SOIC	D	8	2500	340.5	336.1	25.0
INA296B1IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296B1IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296B1IDR	SOIC	D	8	2500	353.0	353.0	32.0



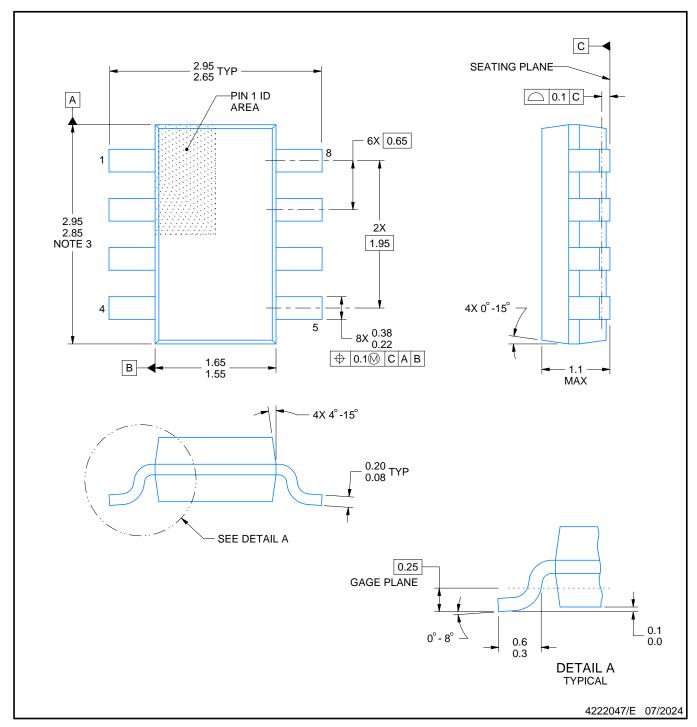
## **PACKAGE MATERIALS INFORMATION**

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Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
INA296B2IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296B2IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296B2IDR	SOIC	D	8	2500	353.0	353.0	32.0
INA296B3IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296B3IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296B3IDR	SOIC	D	8	2500	353.0	353.0	32.0
INA296B4IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296B4IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296B4IDR	SOIC	D	8	2500	353.0	353.0	32.0
INA296B5IDDFR	SOT-23-THIN	DDF	8	3000	213.0	191.0	35.0
INA296B5IDDFR	SOT-23-THIN	DDF	8	3000	210.0	185.0	35.0
INA296B5IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
INA296B5IDR	SOIC	D	8	2500	353.0	353.0	32.0



PLASTIC SMALL OUTLINE



## NOTES:

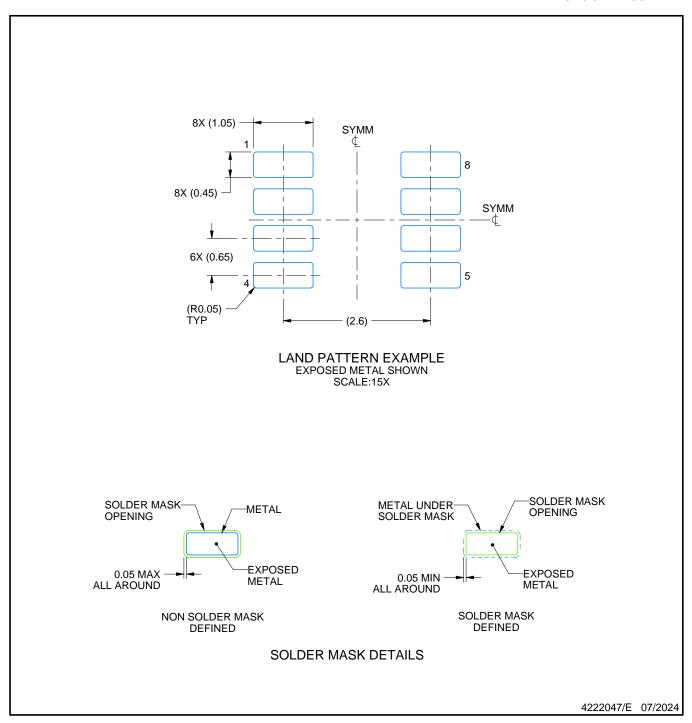
- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.



PLASTIC SMALL OUTLINE

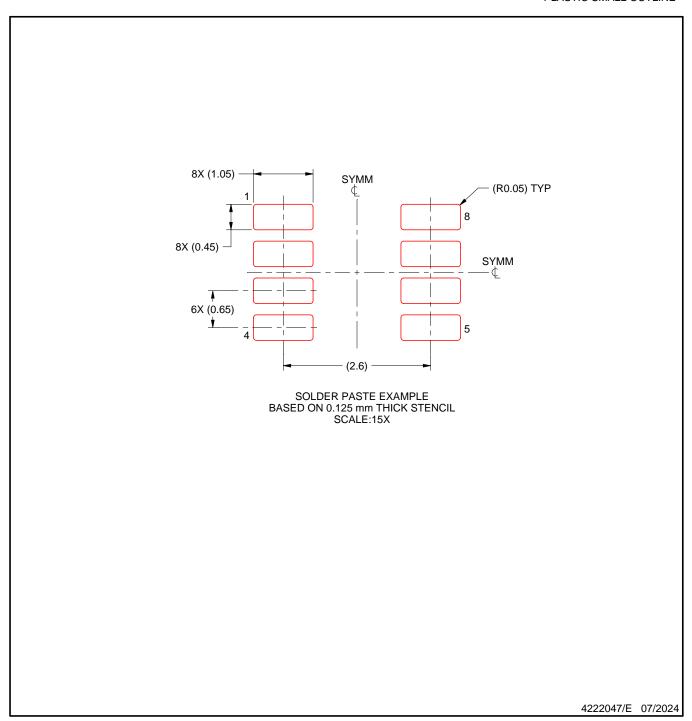


NOTES: (continued)

- 4. Publication IPC-7351 may have alternate designs.
- 5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



PLASTIC SMALL OUTLINE



NOTES: (continued)

- 6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 7. Board assembly site may have different recommendations for stencil design.





SMALL OUTLINE INTEGRATED CIRCUIT



## NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE INTEGRATED CIRCUIT



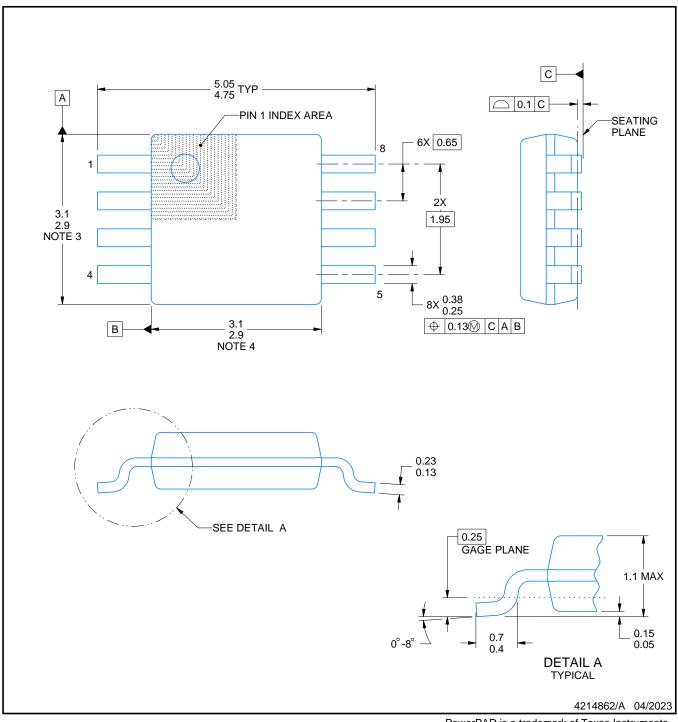
NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.





SMALL OUTLINE PACKAGE



#### NOTES:

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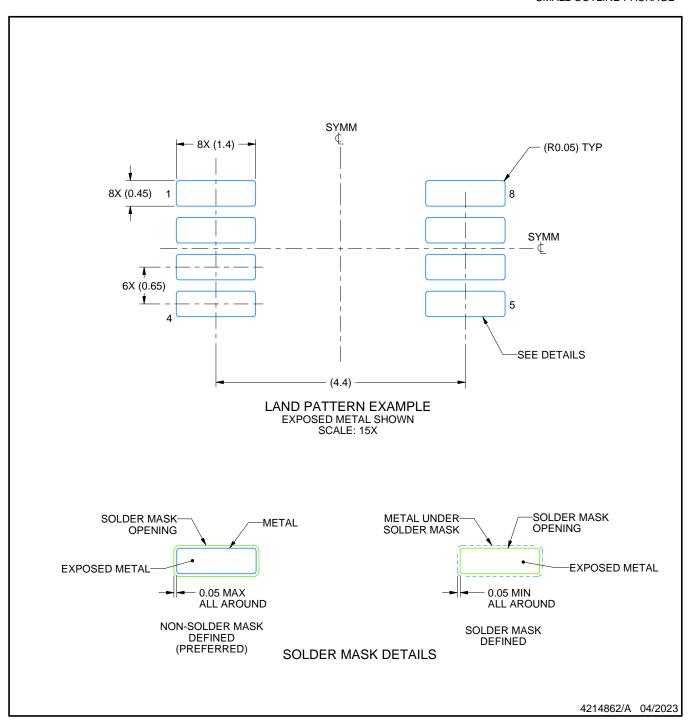
- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187.



SMALL OUTLINE PACKAGE

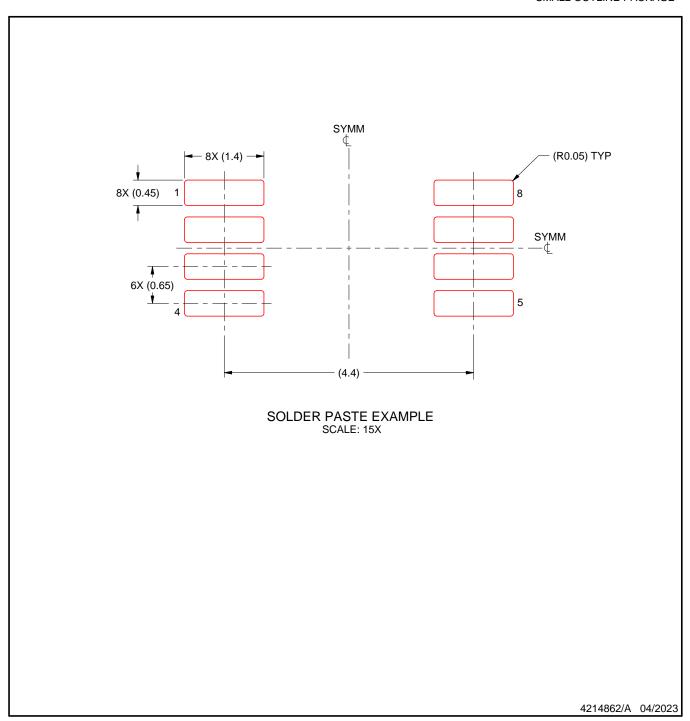


NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.
- 9. Size of metal pad may vary due to creepage requirement.



SMALL OUTLINE PACKAGE



NOTES: (continued)

- 11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 12. Board assembly site may have different recommendations for stencil design.



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