PCF8574A Remote 8-Bit I/O Expander for I²C Bus

1 Features

- Low standby-current consumption of 10µA max
- I²C to parallel-port expander
- Open-drain interrupt output
- Compatible with most microcontrollers
- Latched outputs with high-current drive capability for directly driving LEDs
- Latch-up performance exceeds 100 mA Per JESD 78, Class II

2 Applications

- Telecom shelters: filter units
- Servers
- Routers (telecom switching equipment)
- Personal computers
- Personal electronics
- Industrial automation
- Products with GPIO-Limited Processors

3 Description

This 8-bit input/output (I/O) expander for the two-line bidirectional bus (I²C) is designed for 2.5V to 6V V_{CC} operation.

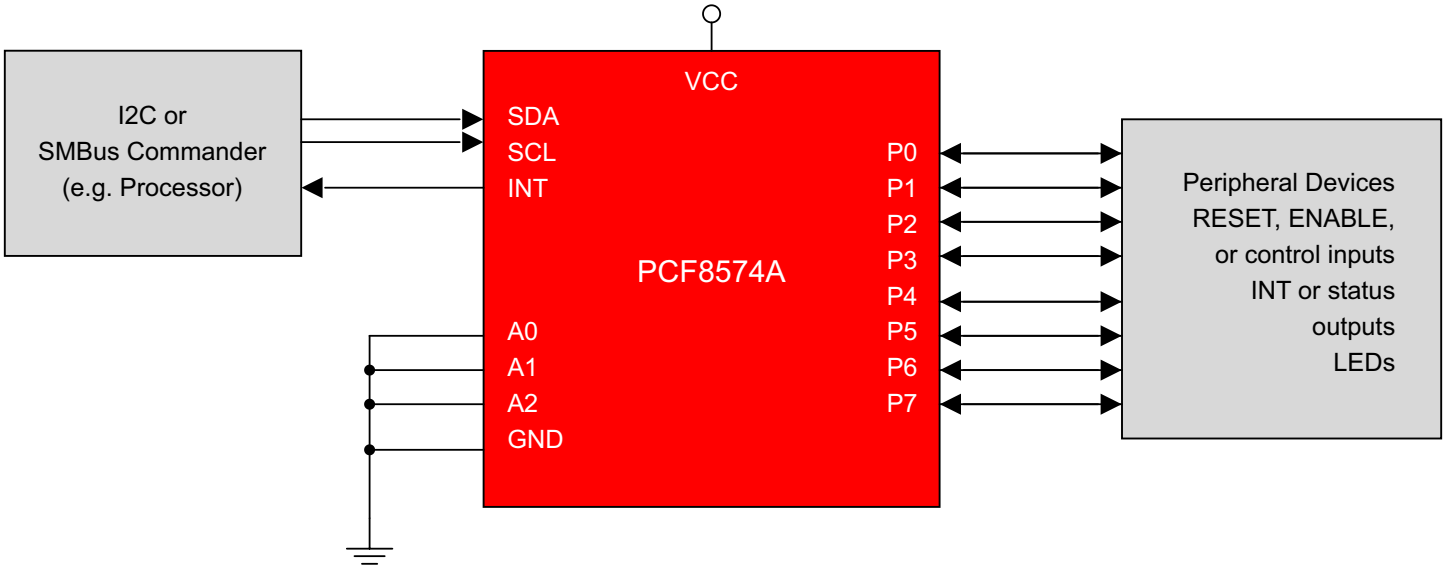
The PCF8574A device provides general-purpose remote I/O expansion for most microcontroller families via the I²C interface [serial clock (SCL), serial data (SDA)].

The device features an 8-bit quasi-bidirectional I/O port (P0–P7), including latched outputs with high-current drive capability for directly driving LEDs. Each quasi-bidirectional I/O can be used as an input or output without the use of a data-direction control signal. At power on, the I/Os are high. In this mode, only a current source to V_{CC} is active.

Device Information

PART NUMBER	PACKAGE(1)	BODY SIZE (NOM)
PCF8574A	VQFN (20)	4.50mm × 3.50mm
	PDIP (16)	19.30mm × 6.35mm
	SOIC (16)	10.30mm × 7.50mm
	TSSOP (20)	6.50mm × 4.40mm
	TVSOP (20)	5.00mm × 4.40mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.



An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.

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4 Pin Configuration and Functions

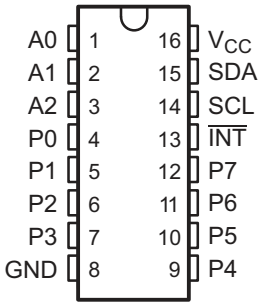

Figure 4-1. DW or N Package 16 Pins Top View

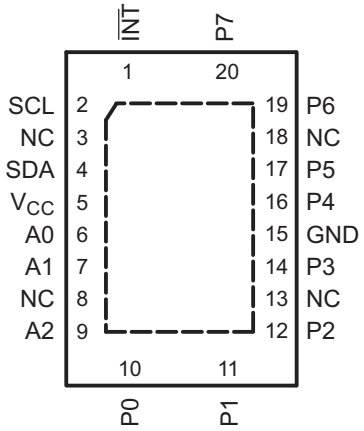

Figure 4-2. RGY Package 20 Pins Top View

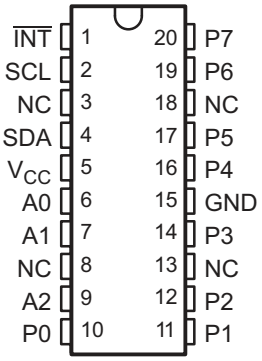

Figure 4-3. DGV or PW Package 20 Pins Top View

Table 4-1. Pin Functions

PIN				TYPE	DESCRIPTION
NAME	RGY	DGV or PW	DW or N		
A[0..2]	6, 7, 9	6, 7, 9	1, 2, 3	I	Address inputs 0 through 2. Connect directly to V_{CC} or ground. Pullup resistors are not needed.
GND	15	15	8	—	Ground
$\overline{INT}$	1	1	13	O	Interrupt output. Connect to V_{CC} through a pullup resistor.
NC	3, 8, 13, 18	3, 8, 13, 18	-	—	Do not connect
P[0..7]	10, 11, 12, 14, 16, 17, 19, 20	10, 11, 12, 14, 16, 17, 19, 20	4, 5, 6, 7, 9, 10, 11, 12	I/O	P-port input/output. Push-pull design structure.
SCL	2	2	14	I	Serial clock line. Connect to V_{CC} through a pullup resistor
SDA	4	4	15	I/O	Serial data line. Connect to V_{CC} through a pullup resistor.
V_{CC}	5	5	16	—	Voltage supply

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5 Specifications

5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

			MIN	MAX	UNIT
V_{CC}	Supply voltage range		–0.5	6.5	V
V_I	Input voltage range(2)		–0.5	V_{CC} + 0.5	V
V_O	Output voltage range(2)		–0.5	V_{CC} + 0.5	V
I_{IK}	Input clamp current	V_I < 0		–20	mA
I_{OK}	Output clamp current	V_O < 0		–20	mA
I_{OK}	Input/output clamp current	V_O < 0 or V_O > V_{CC}		±400	µA
I_{OL}	Continuous output low current	V_O = 0 to V_{CC}		50	mA
I_{OH}	Continuous output high current	V_O = 0 to V_{CC}		–4	mA
	Continuous current through V_{CC} or GND			±100	mA
T_J	Junction temperature			150	°C
T_{stg}	Storage temperature range		–65	150	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Section 5.3 is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) The input negative-voltage and output voltage ratings may be exceeded if the input and output current ratings are observed.

5.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins (1)	1000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101, all pins (2)	1500	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

5.3 Recommended Operating Conditions

		MIN	MAX	UNIT
V_{CC}	Supply voltage	2.5	6	V
V_{IH}	High-level input voltage	0.7 × V_{CC}	V_{CC} + 0.5	V
V_{IL}	Low-level input voltage	–0.5	0.3 × V_{CC}	V
I_{OH}	High-level output current		–1	mA
I_{OL}	Low-level output current		25	mA
T_A	Operating free-air temperature	–40	85	°C

5.4 Thermal Information

THERMAL METRIC(1)		PCF8574A					UNIT
		DGV	DW	N	PW	RGY	
		20 PINS	16 PINS	16 PINS	20 PINS	20 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	112.2	76.7	48.3	94.8	52.2	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	35.2	45.1	35.6	40.2	50.6	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	53.4	45.8	28.2	58.5	29.2	°C/W
ψ_{JT}	Junction-to-top characterization parameter	1.8	17.2	20.5	2.8	3.3	°C/W
ψ_{JB}	Junction-to-board characterization parameter	52.8	45.2	28.1	58.0	29.1	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	n/a	n/a	n/a	n/a	16.0	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC package thermal metrics application report.

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5.5 Electrical Characteristics

over recommended operating free-air temperature range (unless otherwise noted)

		TEST CONDITIONS			VCC	MIN	TYP(1)	MAX	UNIT
V_{IK}	Input diode clamp voltage	I_I = –18 mA			2.5 V to 6 V	–1.2			V
V_{POR}	Power-on reset voltage	$V_I = V_{CC}$ or GND,	I_O = 0		6 V		1.3	2.4	V
I_{OH}	P port	V_O = GND			2.5 V to 6 V	-310		-30	µA
I_{OHT}	P port transient pullup current	High during acknowledge, V_{OH} = GND			2.5 V		–1		mA
I_{OL}	SDA	V_O = 0.4 V			2.5 V to 6 V	3			mA
	P port	V_O = 1 V			5 V	10	25		
	$\overline{INT}$	V_O = 0.4 V			2.5 V to 6 V	1.6			
I_I	SCL, SDA	$V_I = V_{CC}$ or GND			2.5 V to 6 V			±5	µA
	$\overline{INT}$							±5	
	A0, A1, A2							±5	
I_{IHL}	P port	-250mV < Vi < GND			2.5 V to 6 V			±400	µA
I_{CC}	Operating mode	$V_I = V_{CC}$ or GND,	I_O = 0,	f_{SCL} = 100 kHz	6 V		40	100	µA
	Standby mode	$V_I = V_{CC}$ or GND,	I_O = 0				2.5	10	
C_i	SCL	$V_I = V_{CC}$ or GND			2.5 V to 6 V		1.5	7	pF
C_{io}	SDA	$V_{IO} = V_{CC}$ or GND			2.5 V to 6 V		3	7	pF
	P port						4	10	

(1) All typical values are at V_{CC} = 5 V, T_A = 25°C.

5.6 I²C Interface Timing Requirements

over recommended operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
f_{scl}	I²C clock frequency			100	kHz
t_{sch}	I²C clock high time		4		µs
t_{scl}	I²C clock low time		4.7		µs
t_{sp}	I²C spike time			70	ns
t_{sds}	I²C serial data setup time		250		ns
t_{sdh}	I²C serial data hold time		0		ns
t_{icr}	I²C input rise time			1	µs
t_{icf}	I²C input fall time			0.3	µs
t_{ocf}	I²C output fall time (10-pF to 400-pF bus)			300	ns
t_{buf}	I²C bus free time between stop and start		4.7		µs
t_{sts}	I²C start or repeated start condition setup		4.7		µs
t_{sth}	I²C start or repeated start condition hold		4		µs
t_{sps}	I²C stop condition setup		4		µs
t_{vd}	Valid data time	SCL low to SDA output valid		3.4	µs
C_b	I²C bus capacitive load			400	pF

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5.7 Switching Characteristics

over recommended operating free-air temperature range, $C_L \leq 100$ pF (unless otherwise noted)

PARAMETER		FROM (INPUT)	TO (OUTPUT)	MIN	MAX	UNIT
t_{pv}	Output data valid	SCL	P port		4	µs
t_{su}	Input data setup time	P port	SCL	0		µs
t_h	Input data hold time	P port	SCL	4		µs
t_{iv}	Interrupt valid time	P port	$\overline{INT}$		4	µs
t_{ir}	Interrupt reset delay time	SCL	$\overline{INT}$		4	µs

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5.8 Typical Characteristics

T_A = 25°C (unless otherwise noted)

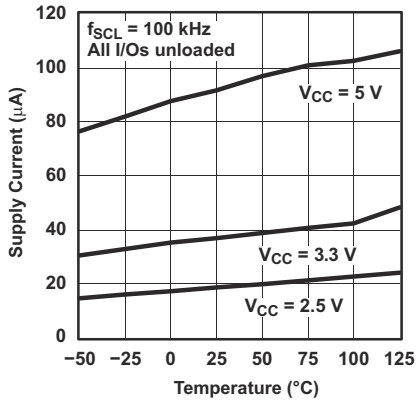

Figure 5-1. Supply Current vs Temperature

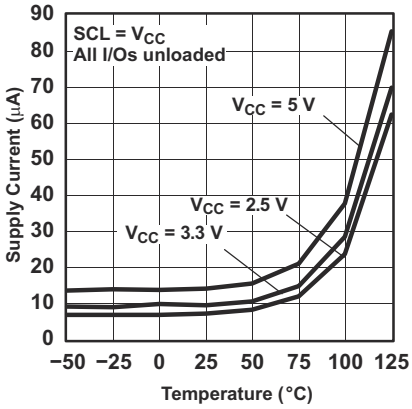

Figure 5-2. Standby Supply Current vs Temperature

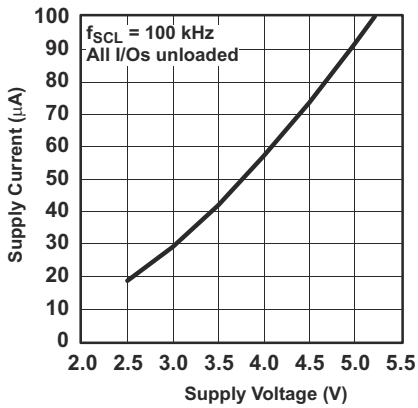

Figure 5-3. Supply Current vs Supply Voltage

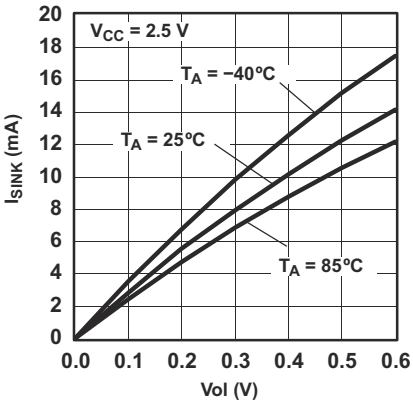

Figure 5-4. I/O Sink Current vs Output Low Voltage

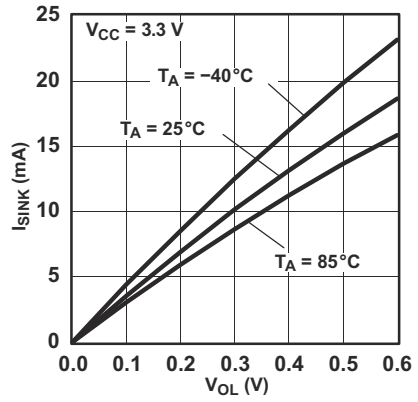

Figure 5-5. I/O Sink Current vs Output Low Voltage

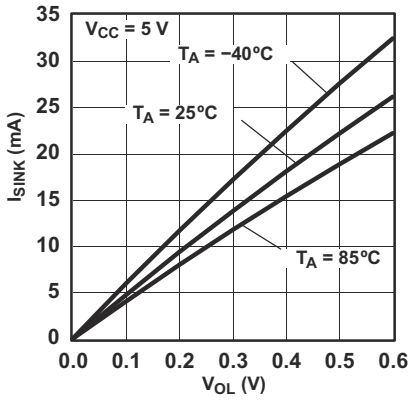

Figure 5-6. I/O Sink Current vs Output Low Voltage

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5.8 Typical Characteristics (continued)

T_A = 25°C (unless otherwise noted)

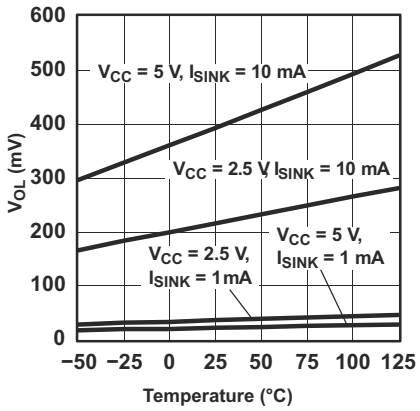

Figure 5-7. I/O Output Low Voltage vs Temperature

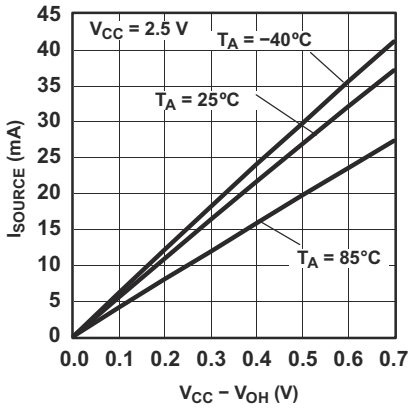

Figure 5-8. I/O Source Current vs Output High Voltage

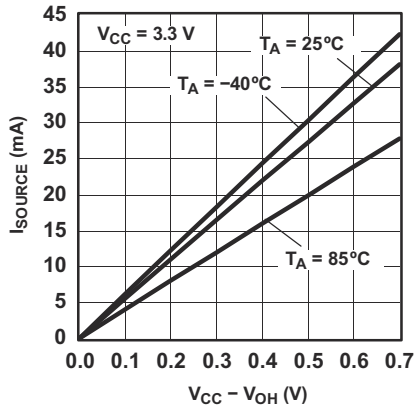

Figure 5-9. I/O Source Current vs Output High Voltage

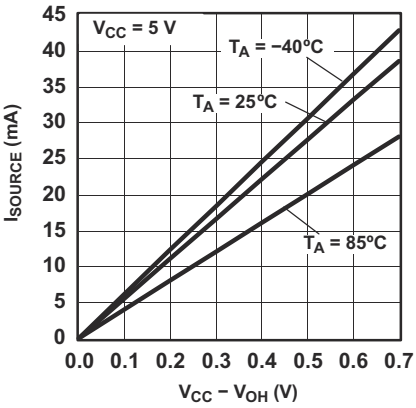

Figure 5-10. I/O Source Current vs Output High Voltage

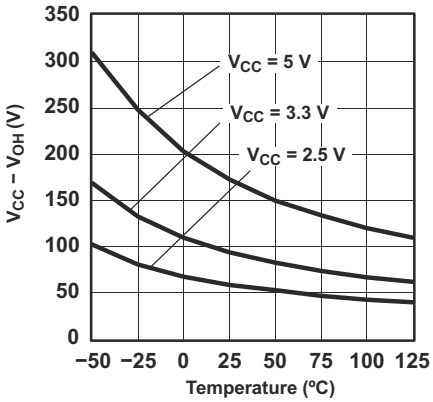

Figure 5-11. I/O High Voltage vs Temperature

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6 Parameter Measurement Information

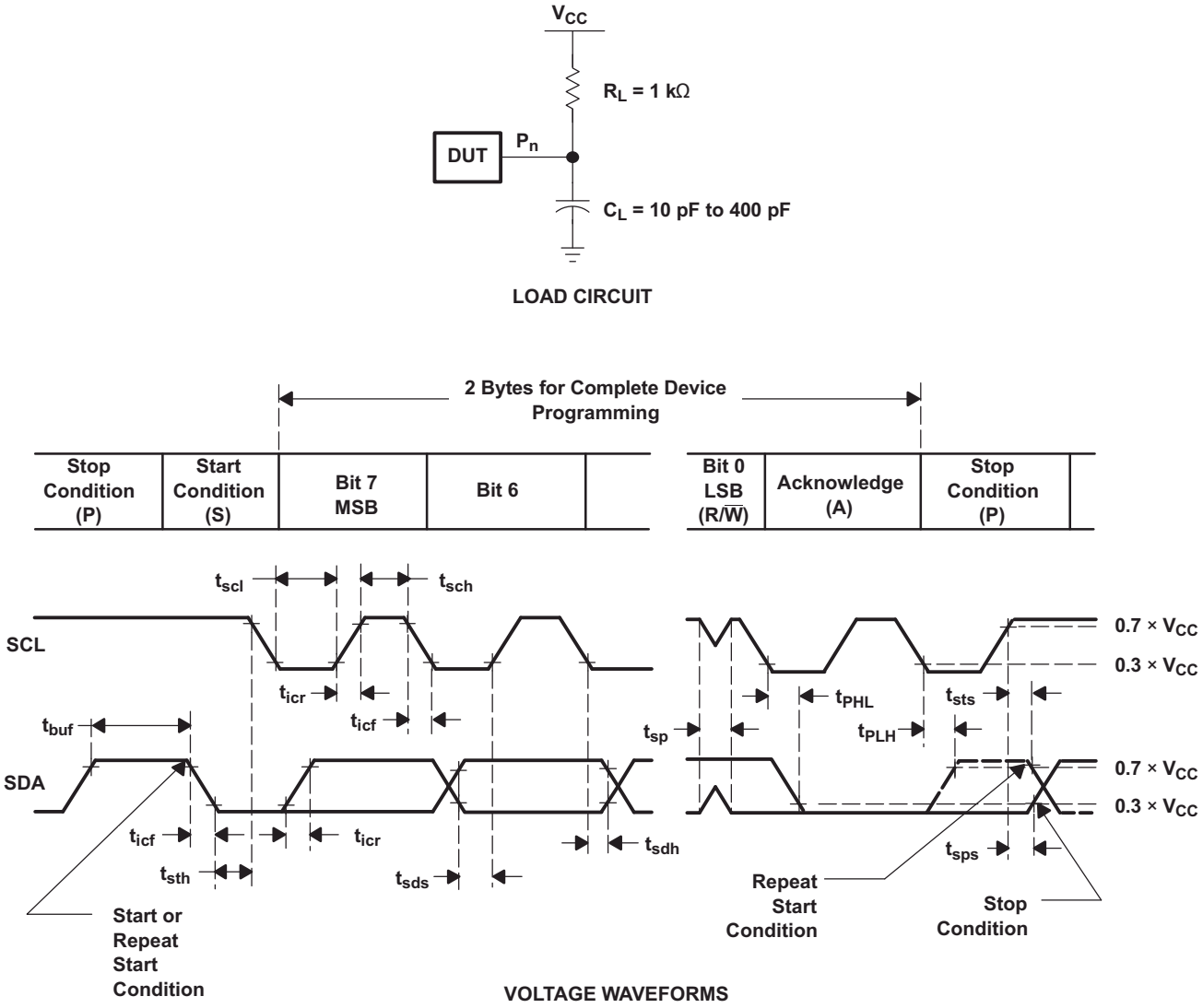

Figure 6-1. I²C Interface Load Circuit and Voltage Waveforms

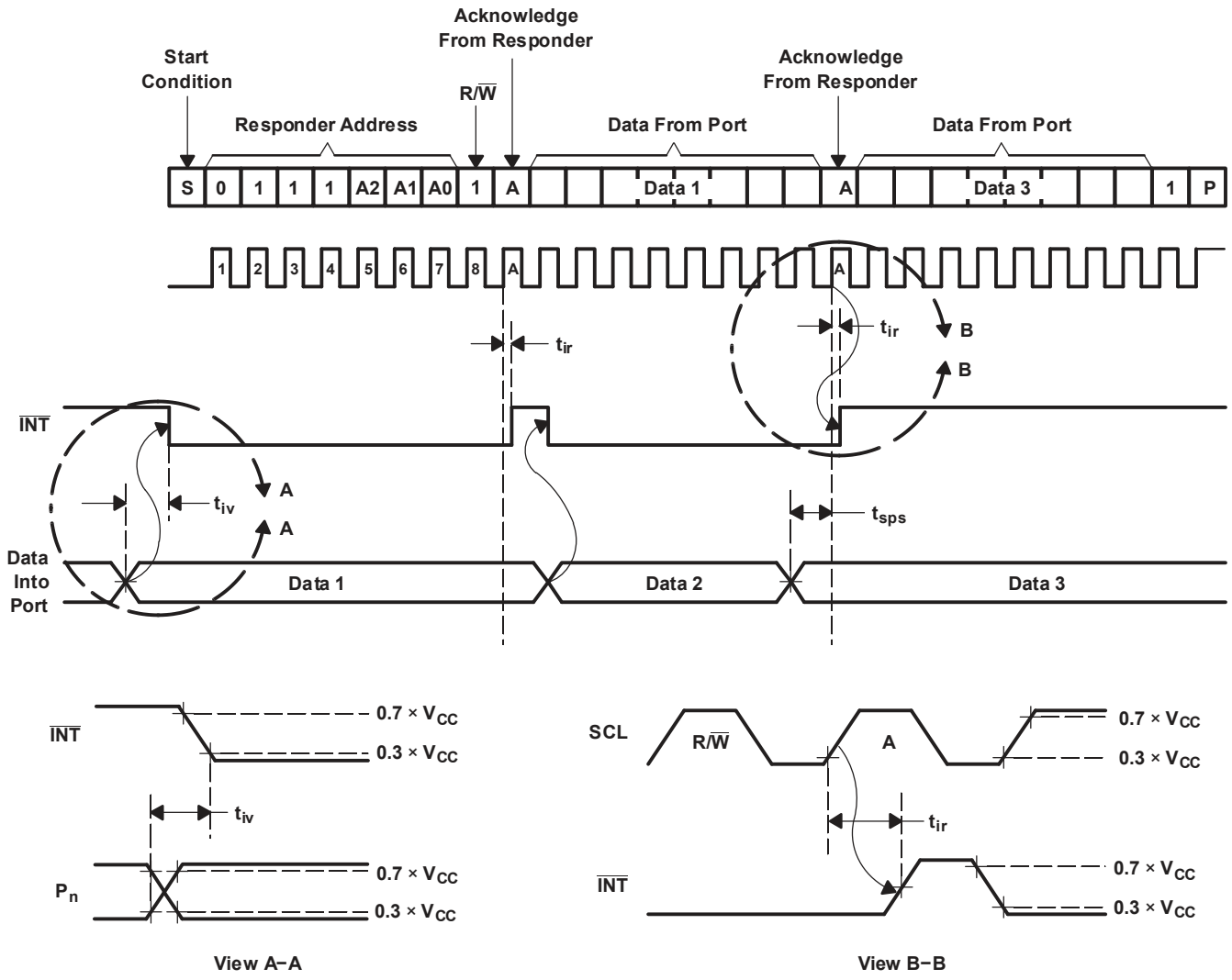

Figure 6-2. Interrupt Voltage Waveforms

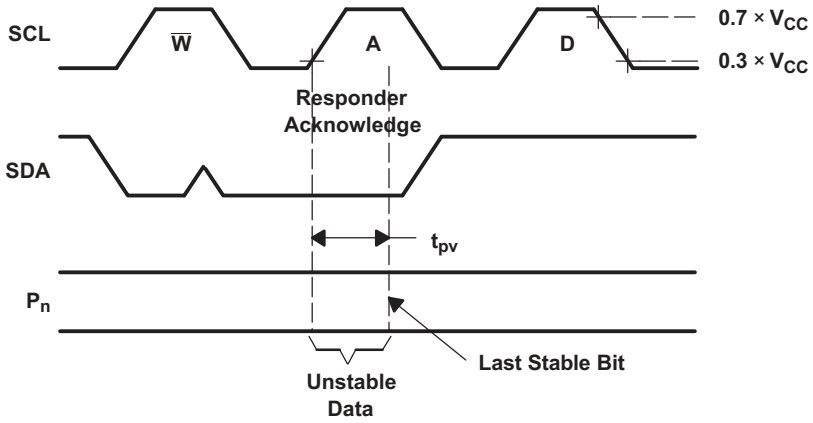

Figure 6-3. I²C Write Voltage Waveforms

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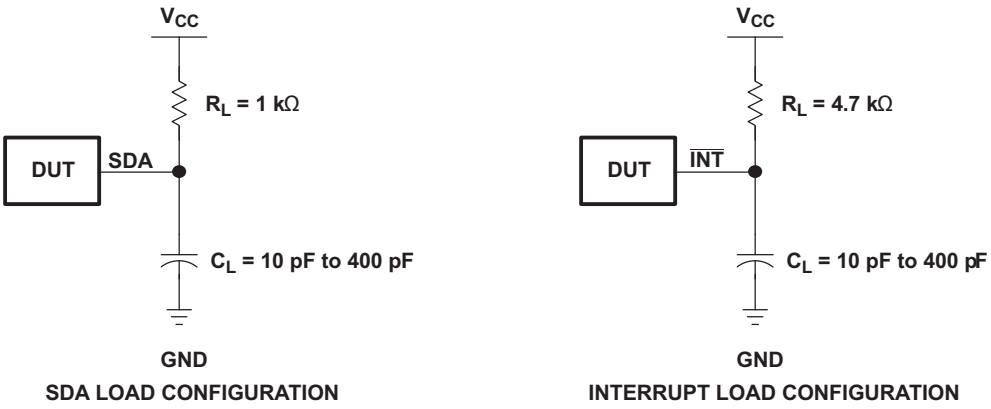


Figure 6-4. Load Circuits

7 Detailed Description

7.1 Overview

The PCF8574A device provides general-purpose remote I/O expansion for most microcontroller families via the I^2C interface [serial clock (SCL), serial data (SDA)].

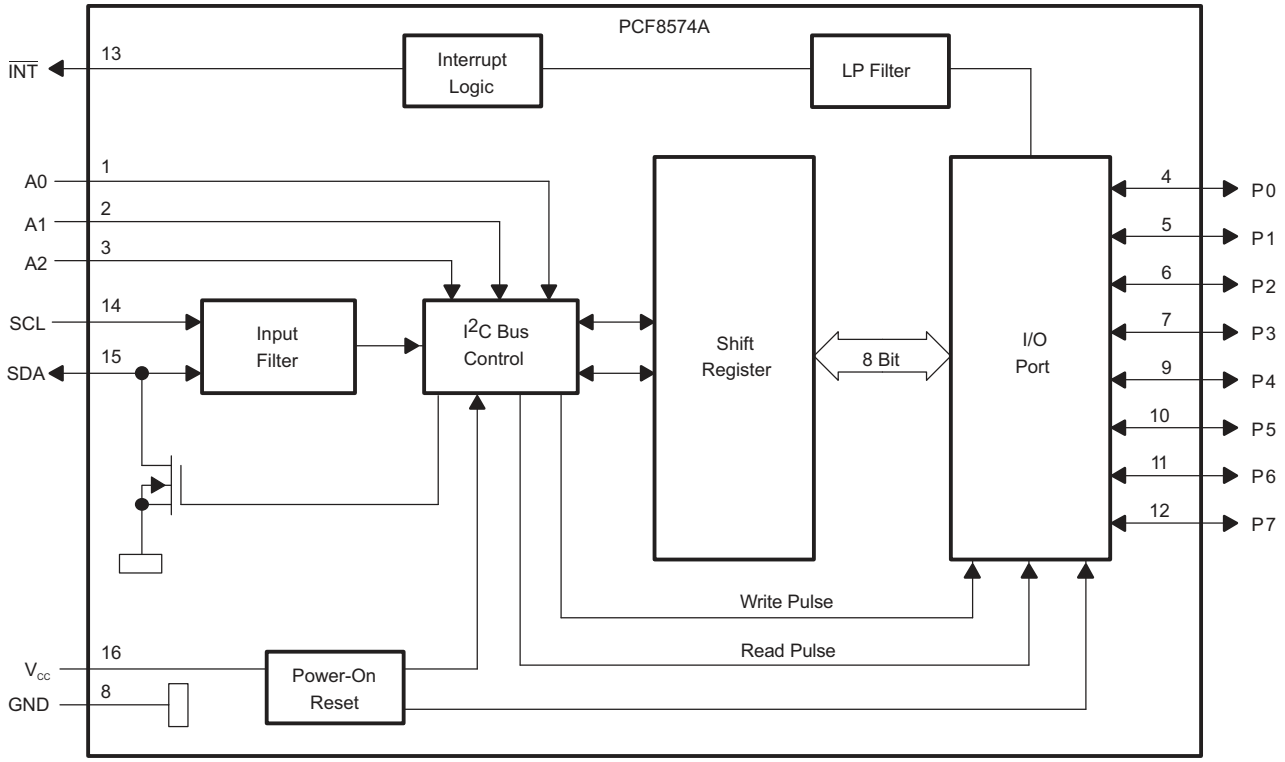
The device features an 8-bit quasi-bidirectional I/O port (P0–P7), including latched outputs with high-current drive capability for directly driving LEDs. Each quasi-bidirectional I/O can be used as an input or output without the use of a data-direction control signal. At power on, the I/Os are high. In this mode, only a current source to V_{CC} is active. An additional strong pullup to V_{CC} allows fast rising edges into heavily loaded outputs. This device turns on when an output is written high and is switched off by the negative edge of SCL. The I/Os should be high before being used as inputs.

The PCF8574A device provides an open-drain output ($\overline{INT}$) that can be connected to the interrupt input of a microcontroller. An interrupt is generated by any rising or falling edge of the port inputs in the input mode. After time, t_{iv}, $\overline{INT}$ is valid. Resetting and reactivating the interrupt circuit is achieved when data on the port is changed to the original setting or data is read from, or written to, the port that generated the interrupt. Resetting occurs in the read mode at the acknowledge bit after the rising edge of the SCL signal, or in the write mode at the acknowledge bit after the high-to-low transition of the SCL signal. Interrupts that occur during the acknowledge clock pulse can be lost (or be very short) due to the resetting of the interrupt during this pulse. Each change of the I/Os after resetting is detected and, after the next rising clock edge, is transmitted as $\overline{INT}$. Reading from, or writing to, another device does not affect the interrupt circuit.

By sending an interrupt signal on this line, the remote I/O can inform the microcontroller if there is incoming data on its ports without having to communicate via the I^2C bus. Therefore, the PCF8574A device can remain a simple responder device.

7.2 Functional Block Diagram

7.2.1 Simplified Block Diagram of Device



Pin numbers shown are for the DW and N packages.

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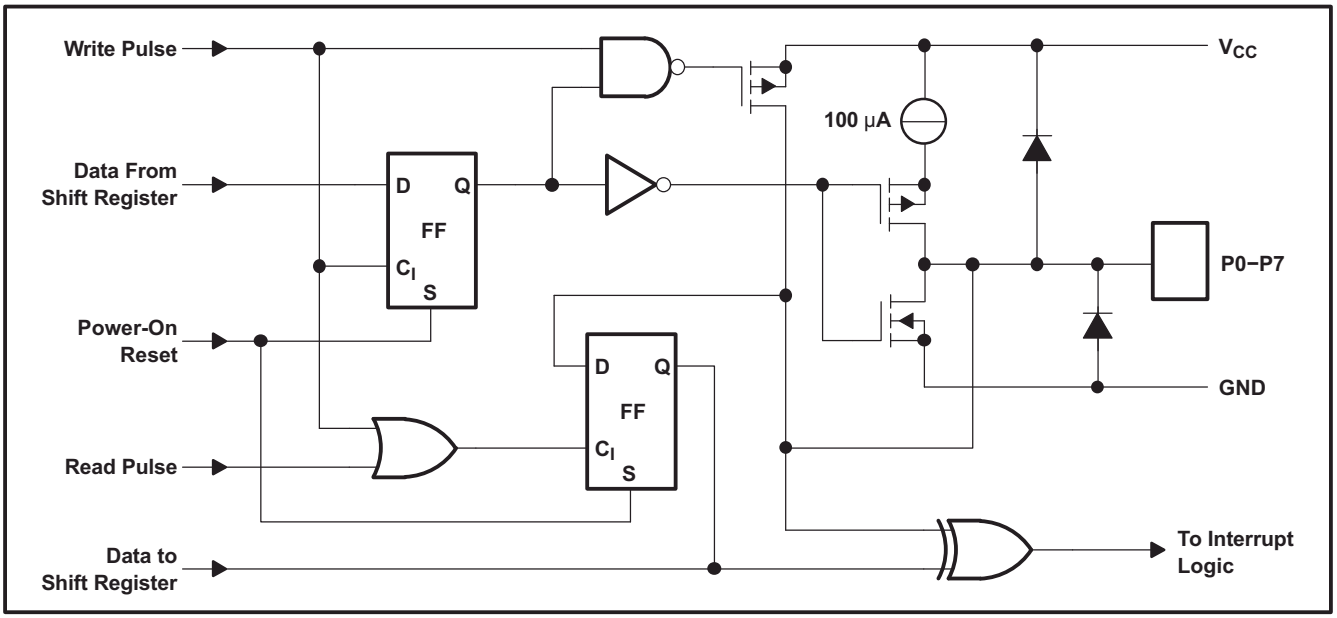
7.2.2 Simplified Schematic Diagram of Each P-Port Input/Output



7.3 Feature Description

7.3.1 I²C Interface

I²C communication with this device is initiated by a commander sending a start condition, a high-to-low transition on the SDA I/O while the SCL input is high. After the start condition, the device address byte is sent, most-significant bit (MSB) first, including the data direction bit (R/ $\overline{W}$). This device does not respond to the general call address. After receiving the valid address byte, this device responds with an acknowledge, a low on the SDA I/O during the high of the acknowledge-related clock pulse. The address inputs (A0–A2) of the responder device must not be changed between the start and the stop conditions.

The data byte follows the address acknowledge. If the R/ $\overline{W}$ bit is high, the data from this device are the values read from the P port. If the R/ $\overline{W}$ bit is low, the data are from the commander, to be output to the P port. The data byte is followed by an acknowledge sent from this device. If other data bytes are sent from the commander, following the acknowledge, they are ignored by this device. Data are output only if complete bytes are received and acknowledged. The output data will be valid at time, t_{pv}, after the low-to-high transition of SCL and during the clock cycle for the acknowledge.

A stop condition, a low-to-high transition on the SDA I/O while the SCL input is high, is sent by the commander.

7.3.2 Interface Definition

BYTE	BIT							
	7 (MSB)	6	5	4	3	2	1	0 (LSB)
I²C responder address	L	H	H	H	A2	A1	A0	R/ $\overline{W}$
I/O data bus	P7	P6	P5	P4	P3	P2	P1	P0

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7.3.3 Address Reference

INPUTS			I²C BUS responder 8-BIT READ ADDRESS	I²C BUS responder 8-BIT WRITE ADDRESS
A2	A1	A0		
L	L	L	113 (dec), 71 (hex)	112 (dec), 70 (hex)
L	L	H	115 (dec), 73 (hex)	114 (dec), 72 (hex)
L	H	L	117 (dec), 75 (hex)	116 (dec), 74 (hex)
L	H	H	119 (dec), 77 (hex)	118 (dec), 76 (hex)
H	L	L	121 (dec), 79 (hex)	120 (dec), 78 (hex)
H	L	H	123 (dec), 7B (hex)	122 (dec), 7A (hex)
H	H	L	125 (dec), 7D (hex)	124 (dec), 7C (hex)
H	H	H	127 (dec), 7F (hex)	126 (dec), 7E (hex)

7.4 Device Functional Modes

Figure 7-1 and Figure 7-2 show the address and timing diagrams for the write and read modes, respectively.

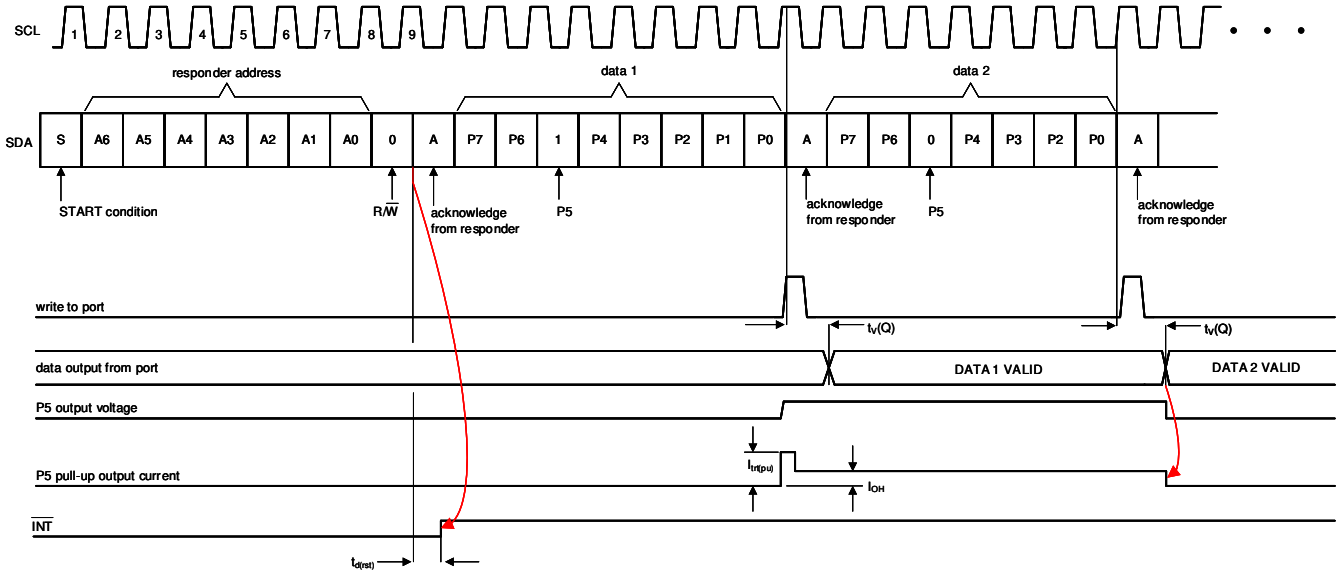

Figure 7-1. Write Mode (Output)

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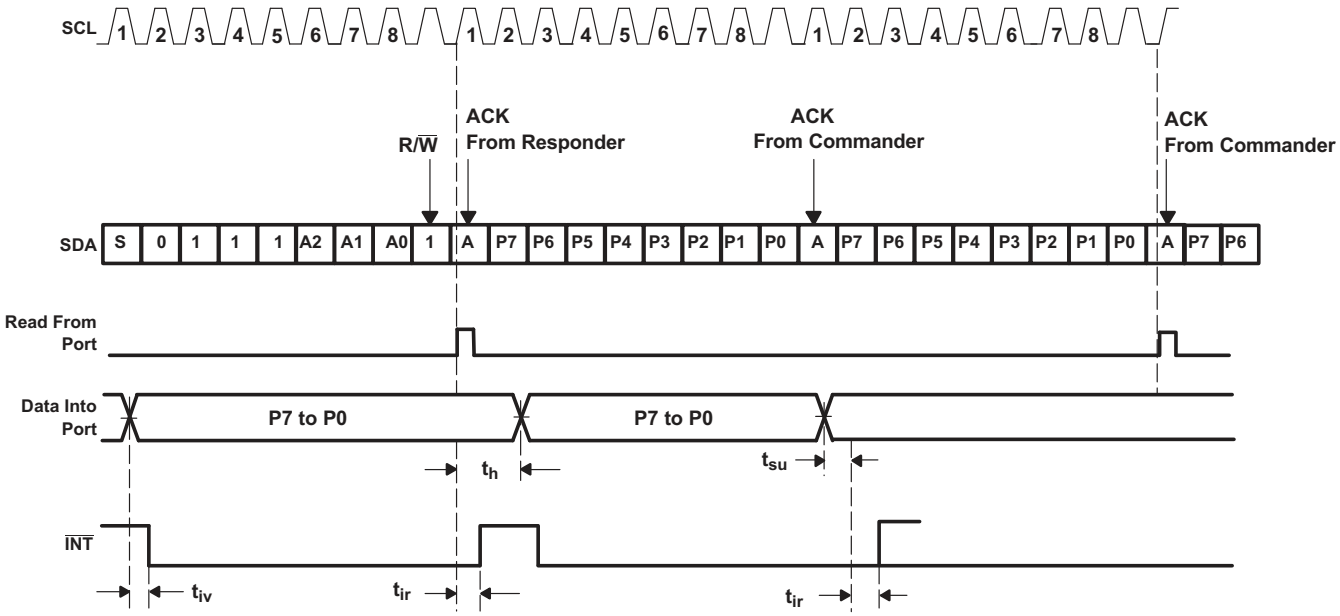


A. A low-to-high transition of SDA while SCL is high is defined as the stop condition (P). The transfer of data can be stopped at any moment bya stop condition. When this occurs, data present at the latest ACK phase is valid (output mode). Input data is lost.

Figure 7-2. Read Mode (Input)

8 Application Information Disclaimer

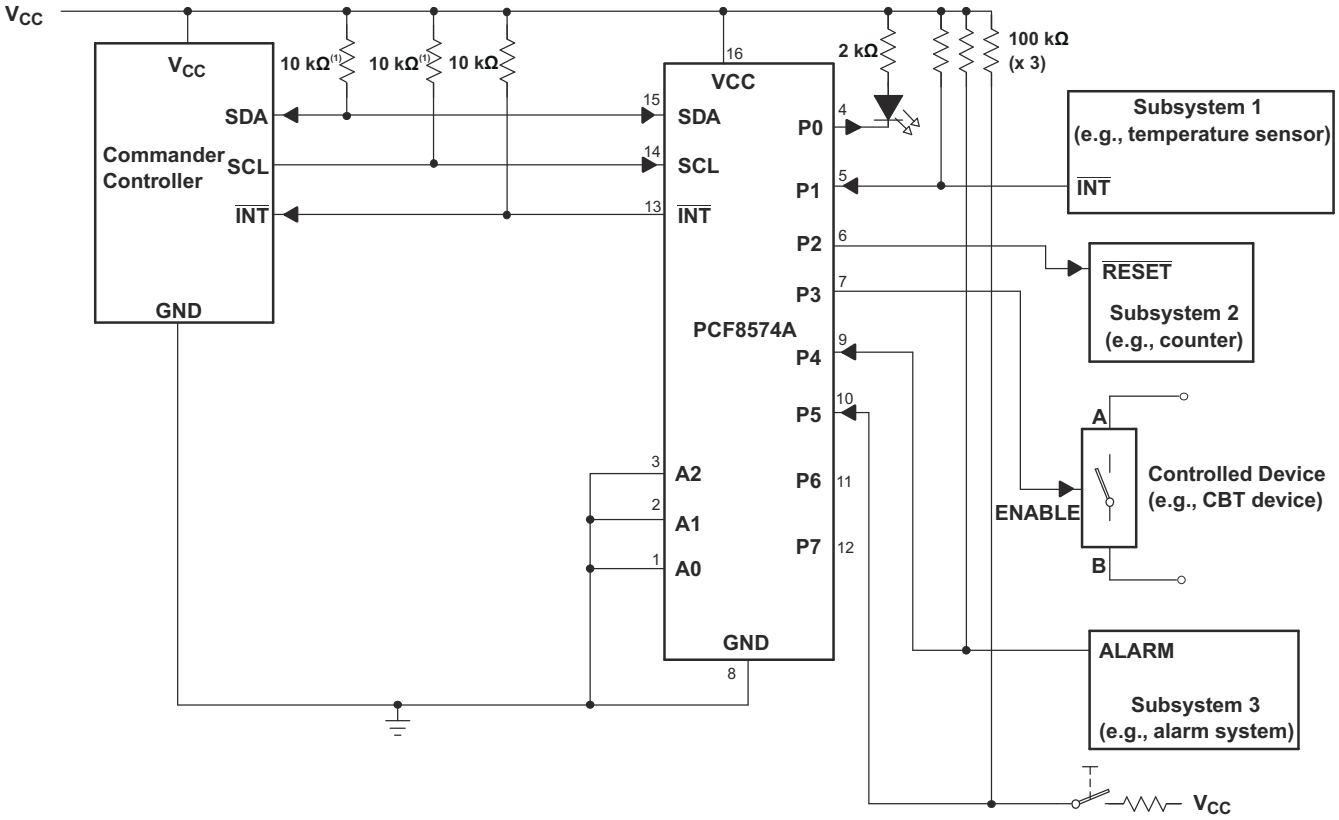
Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

Figure 8-1 shows an application in which the PCF8574A device can be used.

8.2 Typical Application



A. The SCL and SDA pins must be pulled up to V_{CC} because if SCL and SDA are pulled up to an auxiliary power supply that could be powered on while V_{CC} is powered off, then the supply current, I_{CC}, will increase as a result.
B. Device address is configured as 0111000 for this example.
C. P0, P2, and P3 are configured as outputs.
D. P1, P4, and P5 are configured as inputs.
E. P6 and P7 are not used and must be configured as outputs.

Figure 8-1. Application Schematic

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8.2.1 Design Requirements

8.2.1.1 Minimizing I_{CC} When I/Os Control LEDs

When the I/Os are used to control LEDs, normally they are connected to V_{CC} through a resistor as shown in Figure 8-10. For a P-port configured as an input, I_{CC} increases as V_I becomes lower than V_{CC}. The LED is a diode, with threshold voltage V_T, and when a P-port is configured as an input the LED will be off but V_I is a V_T drop below V_{CC}.

For battery-powered applications, it is essential that the voltage of P-ports controlling LEDs is greater than or equal to V_{CC} when the P-ports are configured as input to minimize current consumption. Figure 8-2 shows a high-value resistor in parallel with the LED. Figure 8-3 shows V_{CC} less than the LED supply voltage by at least V_T. Both of these methods maintain the I/O V_I at or above V_{CC} and prevents additional supply current consumption when the P-port is configured as an input and the LED is off.

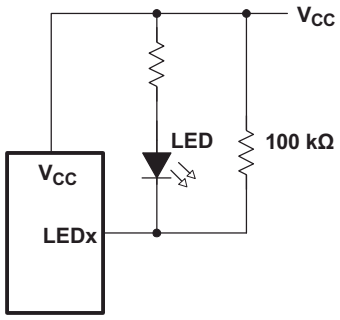

Figure 8-2. High-Value Resistor in Parallel With LED

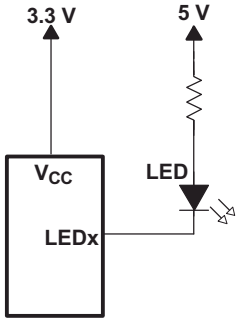

Figure 8-3. Device Supplied by a Lower Voltage

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8.2.2 Detailed Design Procedure

The pull-up resistors, R_P, for the SCL and SDA lines need to be selected appropriately and take into consideration the total capacitance of all responders on the I^2C bus. The minimum pull-up resistance is a function of V_{CC}, $V_{OL,(max)}$, and I_{OL}:

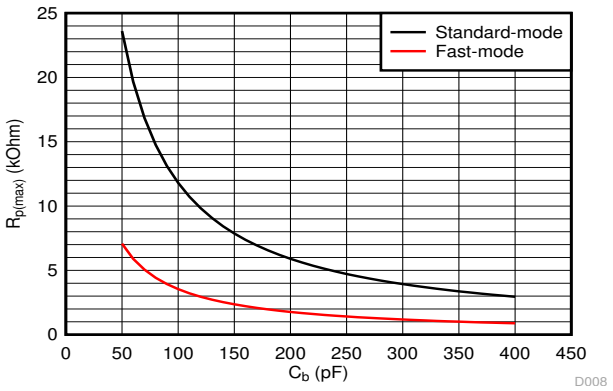
$$R_{p(min)} = \frac{V_{CC} - V_{OL(max)}}{I_{OL}} \quad (1)$$

The maximum pull-up resistance is a function of the maximum rise time, t_r (300 ns for fast-mode operation, f_{SCL} = 400 kHz) and bus capacitance, C_b:

$$R_{p(max)} = \frac{t_r}{0.8473 \times C_b} \quad (2)$$

The maximum bus capacitance for an I^2C bus must not exceed 400 pF for standard-mode or fast-mode operation. The bus capacitance can be approximated by adding the capacitance of the PCF8574A device, C_i for SCL or C_{io} for SDA, the capacitance of wires/connections/traces, and the capacitance of additional responders on the bus.

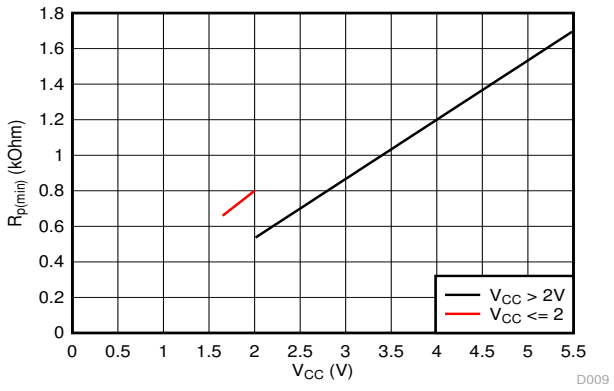
8.2.3 Application Curves



Standard-mode (f_{SCL}= 100 kHz, t_r = 1 µs)

Fast-mode (f_{SCL}= 400 kHz, t_r= 300 ns)

Figure 8-4. Maximum Pull-Up Resistance ($R_{p(max)}$) vs Bus Capacitance (C_b)



V_{OL} = 0.2*V_{CC}, I_{OL} = 2 mA when V_{CC} ≤ 2 V

V_{OL} = 0.4 V, I_{OL} = 3 mA when V_{CC} > 2 V

Figure 8-5. Minimum Pull-Up Resistance ($R_{p(min)}$) vs Pull-Up Reference Voltage (V_{CC})

8.3 Power Supply Recommendations

8.3.1 Power-On Reset Requirements

In the event of a glitch or data corruption, PCF8574A can be reset to its default conditions by using the power-on reset feature. Power-on reset requires that the device go through a power cycle to be completely reset. This reset also happens when the device is powered on for the first time in an application.

The two types of power-on reset are shown in Figure 8-6 and Figure 8-7.

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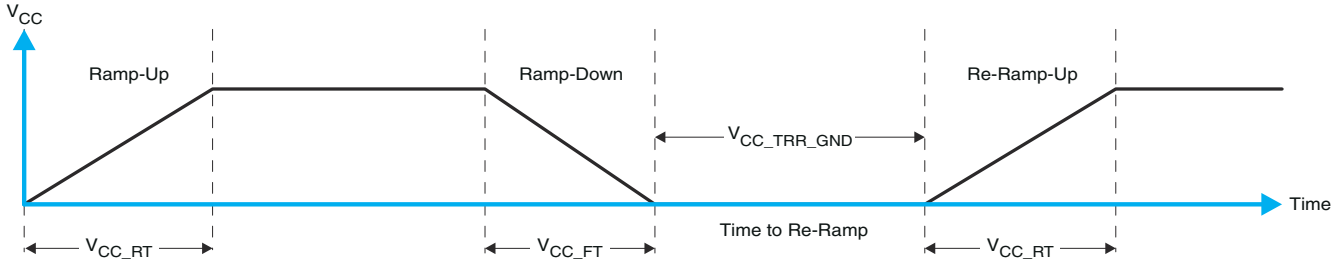

Figure 8-6. V_{CC} is Lowered Below 0.2 V or 0 V and Then Ramped Up to V_{CC}

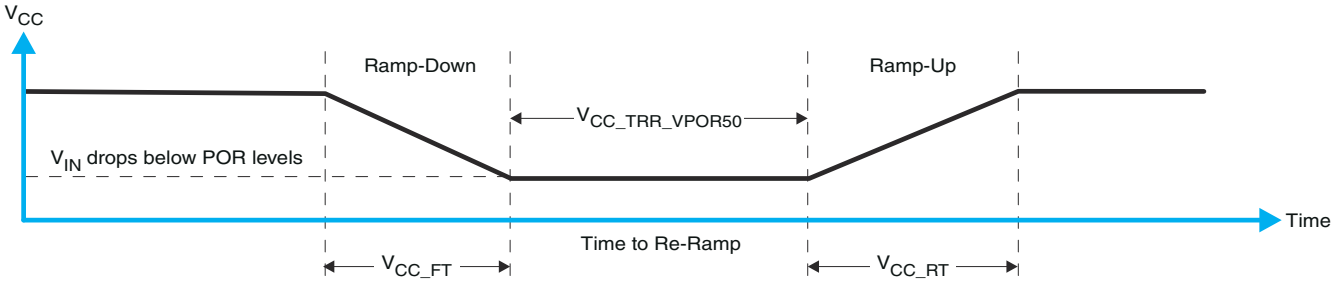

Figure 8-7. V_{CC} is Lowered Below the POR Threshold, Then Ramped Back Up to V_{CC}

Table 8-1 specifies the performance of the power-on reset feature for PCF8574A for both types of power-on reset.

Table 8-1. Recommended Supply Sequencing and Ramp Rates (1)

PARAMETER			MIN	TYP	MAX	UNIT
V_{CC_FT}	Fall rate	See Figure 8-6	1		100	ms
V_{CC_RT}	Rise rate	See Figure 8-6	0.01		100	ms
$V_{CC\_TRR\_GND}$	Time to re-ramp (when V_{CC} drops to GND)	See Figure 8-6	0.001			ms
$V_{CC\_TRR\_POR50}$	Time to re-ramp (when V_{CC} drops to V_{POR_MIN} – 50 mV)	See Figure 8-7	0.001			ms
V_{CC_GH}	Level that V_{CCP} can glitch down to, but not cause a functional disruption when V_{CCX_GW} = 1 µs	See Figure 8-8			1.2	V
V_{CC_GW}	Glitch width that will not cause a functional disruption when V_{CCX_GH} = 0.5 × V_{CCx}	See Figure 8-8				µs
V_{PORF}	Voltage trip point of POR on falling V_{CC}		0.99		1.28	V
V_{PORR}	Voltage trip point of POR on fising V_{CC}		1.190		1.410	V

(1) T_A = –40°C to 85°C (unless otherwise noted)

Glitches in the power supply can also affect the power-on reset performance of this device. The glitch width (V_{CC_GW}) and height (V_{CC_GH}) are dependent on each other. The bypass capacitance, source impedance, and device impedance are factors that affect power-on reset performance. Figure 8-8 and Table 8-1 provide more information on how to measure these specifications.

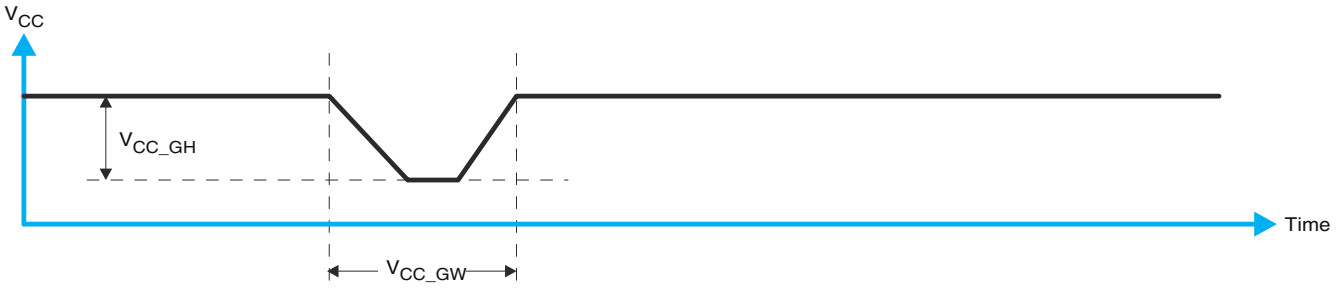

Figure 8-8. Glitch Width and Glitch Height

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V_{POR} is critical to the power-on reset. V_{POR} is the voltage level at which the reset condition is released and all the registers and the I^2C/SMBus state machine are initialized to their default states. The value of V_{POR} differs based on the V_{CC} being lowered to or from 0. Figure 8-9 and Table 8-1 provide more details on this specification.

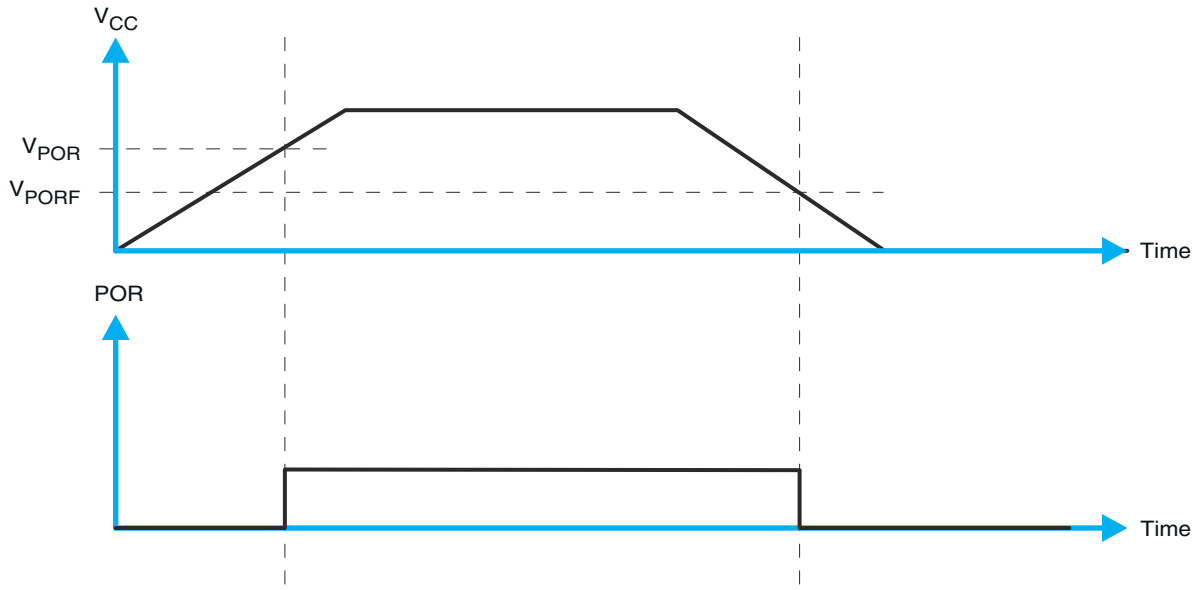

Figure 8-9. V_{POR}

8.4 Layout

8.4.1 Layout Guidelines

For printed circuit board (PCB) layout of PCF8574A, common PCB layout practices should be followed but additional concerns related to high-speed data transfer such as matched impedances and differential pairs are not a concern for I2C signal speeds.

In all PCB layouts, it is a best practice to avoid right angles in signal traces, to fan out signal traces away from each other upon leaving the vicinity of an integrated circuit (IC), and to use thicker trace widths to carry higher amounts of current that commonly pass through power and ground traces. By-pass and de-coupling capacitors are commonly used to control the voltage on the V_{CC} pin, using a larger capacitor to provide additional power in the event of a short power supply glitch and a smaller capacitor to filter out high-frequency ripple. These capacitors should be placed as close to the PCF8574A device as possible. These best practices are shown in Figure 8-10.

For the layout example provided in Figure 8-10, it would be possible to fabricate a PCB with only 2 layers by using the top layer for signal routing and the bottom layer as a split plane for power (V_{CC}) and ground (GND). However, a 4 layer board is preferable for boards with higher density signal routing. On a 4 layer PCB, it is common to route signals on the top and bottom layer, dedicate one internal layer to a ground plane, and dedicate the other internal layer to a power plane. In a board layout using planes or split planes for power and ground, vias are placed directly next to the surface mount component pad which needs to attach to VCC or GND and the via is connected electrically to the internal layer or the other side of the board. Vias are also used when a signal trace needs to be routed to the opposite side of the board, but this technique is not demonstrated in Figure 8-10.

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8.4.2 Layout Example

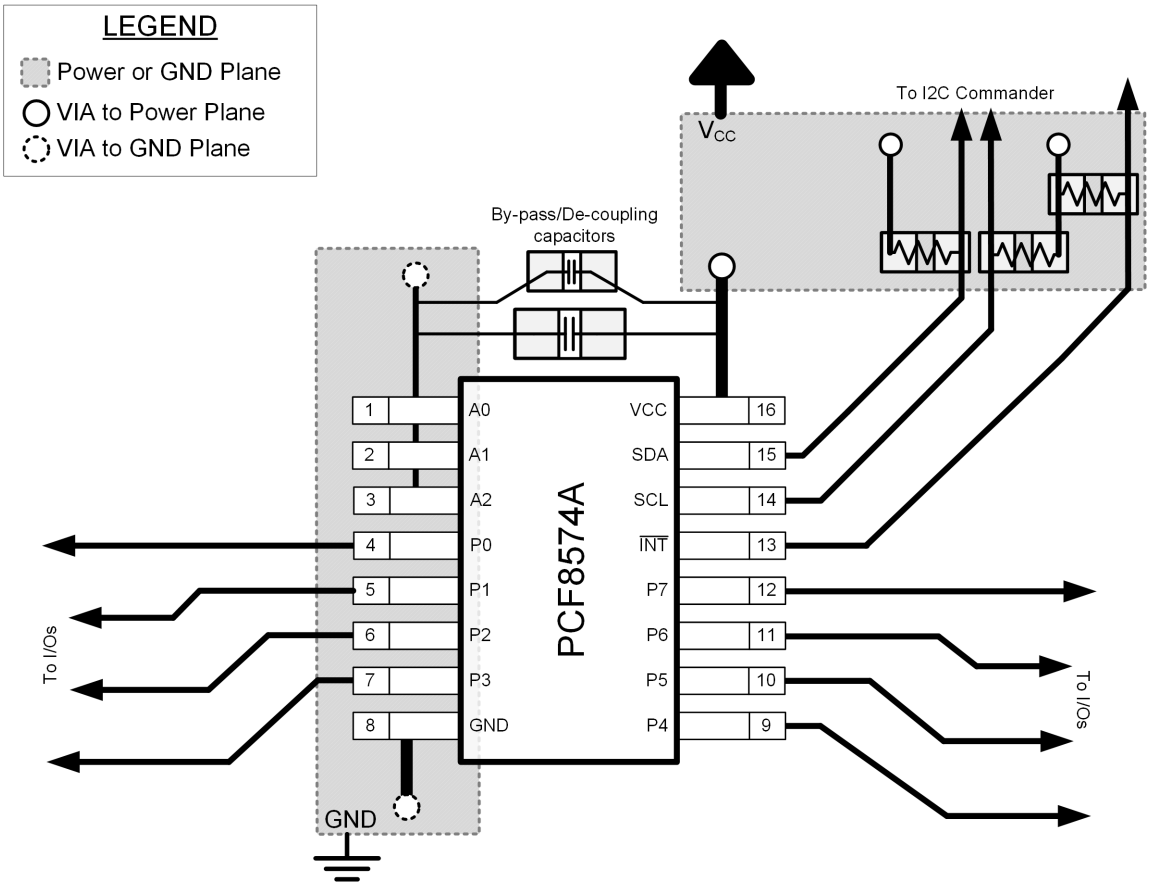

Figure 8-10. Layout Example for PCF8574A

9 Device and Documentation Support

9.1 Documentation Support

9.1.1 Glossary

SLYZ022 — *TI Glossary.*

This glossary lists and explains terms, acronyms and definitions.

9.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

9.3 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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9.5 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

9.6 Glossary

TI Glossary	This glossary lists and explains terms, acronyms, and definitions.

10 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision G (August 2021) to Revision H (September 2024)	Page
• Update *Absolute Max Voltage* from 7V to 6.5V	4
• Update *Thermal Information* for RGY, PW, and DW packages	4
• Update I_{OH} polarity and increase limit from -300µA to -310µA	5
• Removed footnote #2 from *Electrical Characteristics*	5
• Updated I_{IHL} test condition	5
• Changed Spike filter limit from 100ns to 70ns max	5
• Updated VPORF and VPORR values	18

Changes from Revision F (January 2015) to Revision G (August 2021)	Page
• Globally changed instances of legacy terminology to commander and responder where mentioned	1
• Changed Figure 6-2 Responder address from: S0100 To: S0111	9
• Changed Figure 7-1	14
• Changed Note B from: configured as 0100000to: configured as 0111000	16

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11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser based versions of this data sheet, refer to the left hand navigation.

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