



TPS53317 6-A Output, D-CAP+ Mode, Synchronous Step-Down, Integrated-FET Converter for DDR Memory Termination

1 Features

- TI proprietary Integrated MOSFET and Packaging Technology
- Supports DDR Memory Termination with up to 6-A Continuous Output Source or Sink Current
- External Tracking
- Minimum External Components Count
- 1-V to 6-V Conversion Voltage
- D-CAP+™ Mode Architecture
- Supports All MLCC Output Capacitors and SP/POSCAP
- Selectable SKIP Mode or Forced CCM
- Optimized Efficiency at Light and Heavy Loads
- Selectable 600-kHz or 1-MHz Switching Frequency
- Selectable Overcurrent Limit (OCL)
- Overvoltage, Over-Temperature and Hiccup Undervoltage Protection
- Adjustable Output Voltage from 0.6 V to 2 V
- 3.5 mm × 4 mm, 20-Pin VQFN Package

2 Applications

- Memory Termination Regulator for DDR, DDR2, DDR3, DDR3L, and DDR4
- VTT Termination
- Low-Voltage Applications for 1-V to 6-V Input Rails

3 Description

The TPS53317 device is a FET-integrated synchronous buck regulator designed mainly for DDR termination. It can provide a regulated output at $\frac{1}{2} V_{DDQ}$ with both sink and source capability. The TPS53317 device employs D-CAP+™ mode operation that provides ease of use, low external component count and fast transient response. The device can also be used for other point-of-load (POL) regulation applications requiring up to 6 A. In addition, the device supports full, 6-A, output sinking current capability with tight voltage regulation.

The device features two switching frequency settings (600 kHz and 1 MHz), integrated droop support, external tracking capability, pre-bias startup, output soft discharge, integrated bootstrap switch, power good function, V5IN pin UVLO protection, and supports both ceramic and SP/POSCAP capacitors. It supports input voltages up to 6.0 V, and output voltages adjustable from 0.6 V to 2.0 V.

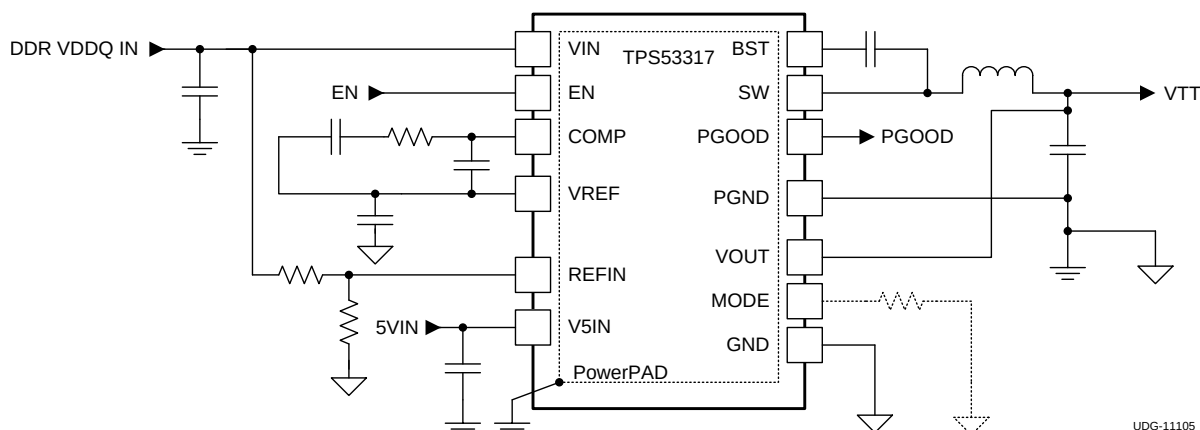
The TPS53317 device is available in the 3.5 mm × 4 mm, 20-pin, VQFN package (Green RoHS compliant and Pb free) with TI proprietary Integrated MOSFET and packaging technology and is specified from –40°C to 85°C.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS53317	VQFN (20)	3.50 mm × 4.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Application



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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision C (November 2013) to Revision D	Page
• Added <i>Pin Configuration and Functions</i> section, <i>ESD Rating</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i> , <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Layout</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section	1
• Added "SW (transient 20 ns and E = 5 μ J)" specification in Absolute Maximum Ratings table	5
• Added Figure 41	26

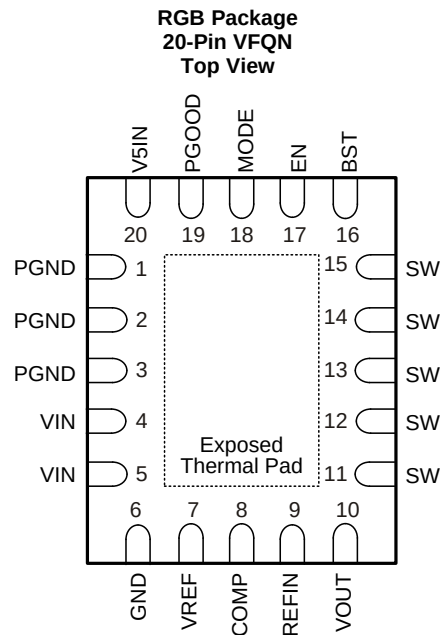
Changes from Revision B (MAY 2012) to Revision C	Page
• Added clarity to Pin Configuration and Functions table	4
• Added clarity to Internal soft-start delay time and soft-start time test conditions in Electrical Characteristics table	7
• Added Figure 17 , Figure 19 and Figure 20 in Power Sequences section	13
• Added clarity to Output Overvoltage Protection (OVP) section	15
• Changed minimum valley OCL from "is 6 A or 4 A" to "is 7.6 A or 5.4 A" in Overcurrent Limit section	15
• Changed "the absolute value of the negative OCL set point is typically -6.5 A or -4.5 A" to "the typical value of the negative OCL set point is -9.3 A or -6.5 A" in Negative OCL section	16
• Added clarity to Layout Guidelines section.	26

Changes from Revision A (JULY 2011) to Revision B	Page
• Added Memory Termination bullet in APPLICATIONS	1
• Added clarity to	1
• Added updates to Table 1	19

Changes from Original (JUNE 2011) to Revision A
Page

• Changed from "SKIP and Forced CCM" to "SKIP or Forced CCM" in FEATURES.....	1
• Changed from "600-kHz and 1-MHz Switching" to "600-kHz or 1-MHz Switching" in FEATURES	1
• Added clarity to Simplified Application drawing	1
• Changed from " $f_{SW} = 600 \text{ kHz}$ " to " $f_{SW} = 1 \text{ MHz}$ " for $t_{ON(min)}$ in EC table	7

5 Pin Configuration and Functions



Pin Functions

PIN		I/O ⁽¹⁾	DESCRIPTION
NAME	NO.		
BST	16	I	Power supply for internal high-side gate driver. Connect a 0.1- μ F bootstrap capacitor between this pin and the SW pin. A series boot resistor is optional.
COMP	8	O	Connect an R-C-C network between this pin and VREF for loop compensation.
EN	17	I	Enable pin (3.3-V logic compatible).
GND	6	–	Analog ground.
MODE	18	I	Allows selection of different operation modes. (See Table 1)
PGND	1	G	Power ground.
	2		
	3		
PGOOD	19	O	Open drain power good output. Connect pullup resistor.
REFIN	9	I	External tracking reference input. Apply voltage between 0.6 V to 2.0 V. For non-tracking mode, connect REFIN to VREF via resistor divider.
SW	11	I/O	Switching node output.
	12		
	13		
	14		
	15		
V5IN	20	I	5-V power supply for analog circuits and gate drive.
VIN	4	I	Power supply input pin.
	5		
VOUT	10	I	Output voltage monitor input pin.
VREF	7	O	2.0-V reference output. Connect a 0.22- μ F ceramic capacitor to GND.

(1) I = Input, O = Output, G = Ground

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

		MIN	MAX	UNIT
Input voltage range	BST (with respect to SW), V5IN, VIN	–0.3	7	V
	BST	–0.3	14	
	EN	–0.3	7	
	MODE, REFIN	–0.3	3.6	
	VOUT	–1	3.6	
Output voltage range	SW	–2	7	V
	SW (transient 20 ns and E = 5 μ J)	–3		
	COMP, VREF	–0.3	3.6	
	PGOOD	–0.3	7	
	PGND	–0.3	0.3	
Operating junction temperature, T _J		–40	150	°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds			300	°C
Storage temperature, T _{stg}		–55	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

		VALUE	UNIT
V _(ESD) Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±2000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 500-V HBM is possible with the necessary precautions. Pins listed as ±2000 V may actually have higher performance.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 250-V CDM is possible with the necessary precautions. Pins listed as ±500 V may actually have higher performance.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Input voltage range	BST (with respect to SW), EN, VIN	–0.1		6.5	V
	V5IN	4.5		6.5	
	BST	–0.1		13.5	
	SW	–1.0		6.5	
	VOUT, MODE, REFIN	–0.1		3.5	
Output voltage range	COMP	–0.1		3.5	V
	VREF		2		
	PGOOD	–0.1		6.5	
	PGND	–0.1		0.1	
Operating temperature range, T _A		–40		85	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS53317	UNIT
		RGB (VQFN)	
		20 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	35.5	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	39.6	°C/W
R _{θJB}	Junction-to-board thermal resistance	12.4	°C/W
ψ _{JT}	Junction-to-top characterization parameter	0.5	°C/W
ψ _{JB}	Junction-to-board characterization parameter	12.5	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	3.7	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

6.5 Electrical Characteristics

over recommended free-air temperature range, V_{V5IN} = 5.0 V, PGND = GND (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY: VOLTAGE, CURRENTS AND 5 V UVLO					
I _{VINSD}	VIN shutdown current EN = 'LO'		0.02	5	μA
V _{V5IN}	V5IN supply voltage V5IN voltage range	4.5	5.0	6.5	V
I _{V5IN}	V5IN supply current EN = 'HI', V5IN supply current, f _{SW} = 600 kHz		1.1	2	mA
I _{V5INSD}	V5IN shutdown current EN = 'LO', V5IN shutdown current		0.2	7.0	μA
V _{V5UVLO}	V5IN UVLO Ramp up; EN = 'HI'	4.20	4.37	4.50	V
V _{V5UVHYS}	V5IN UVLO hysteresis Falling hysteresis		440		mV
V _{VREFUVLO}	REF UVLO ⁽¹⁾ Rising edge of VREF, EN = 'HI'		1.8		V
V _{VREFUVHYS}	REF UVLO hysteresis ⁽¹⁾		100		mV
V _{POR5VFILT}	Reset OVP latch is reset by V5IN falling below the reset threshold	1.5	2.3	3.1	V
VOLTAGE FEEDBACK LOOP: VREF, VOUT, AND VOLTAGE GM AMPLIFIER					
V _{OUTTOL}	Output voltage accuracy	V _{REFIN} = 1 V, No droop	-1%	0%	1%
		V _{REFIN} = 0.6 V, No droop	-1%	0%	1%
V _{VREF}	VREF	I _{VREF} = 0 μA	1.98	2.00	2.02
		I _{VREF} = 50 μA	1.975	2.000	2.025
I _{REFSNK}	VREF sink current V _{VREF} = 2.05 V		2.5		mA
g _M	Transconductance		1.00		mS
V _{CM}	Common mode input voltage range ⁽¹⁾	0		2	V
V _{DM}	Differential mode input voltage	0		80	mV
I _{COMPSNK}	COMP pin maximum sinking current V _{COMP} = 2 V, (V _{REFIN} - V _{OUT}) = 80 mV		80		μA
I _{COMPSRC}	COMP pin maximum sourcing current V _{COMP} = 2 V		-80		μA
V _{OFFSET}	Input offset voltage T _A = 25°C		0		mV
R _{DSCH}	Output voltage discharge resistance		42		Ω
f _{-3dbVL}	-3dB Frequency ⁽¹⁾	4.5	6.0	7.5	MHz
CURRENT SENSE: CURRENT SENSE AMPLIFIER, OVERCURRENT AND ZERO CROSSING					
A _{CSINT}	Internal current sense gain Gain from the current of the low-side FET to PWM comparator when PWM = "OFF"	43	53	57	mV/A
I _{OCL}	Positive overcurrent limit (valley)		7.6		A
I _{OCL(neg)}	Negative overcurrent limit (valley)		-9.3		A
V _{ZXOFF}	Zero crossing comp internal offset		0		mV

(1) Ensured by design, not production tested.

Electrical Characteristics (continued)

over recommended free-air temperature range, $V_{VIN} = 5.0\text{ V}$, PGND = GND (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
PROTECTION: OVP, UVP, PGOOD, and THERMAL SHUTDOWN						
V_{PGDLL}	PGOOD deassert to lower (PGOOD → Low)	Measured at the VOUT pin wrt/ V_{REFIN}		84%		
$V_{PGHYSHL}$	PGOOD high hysteresis			8%		
V_{PGDLH}	PGOOD de-assert to higher (PGOOD → Low)	Measured at the VOUT pin wrt/ V_{REFIN}		116%		
$V_{PGHYSHH}$	PGOOD high hysteresis			-8%		
$V_{INMINPG}$	Minimum VIN voltage for valid PGOOD	Measured at the VIN pin with a 2-mA sink current on PGOOD pin. V5IN is grounded here. ⁽²⁾	0.9	1.3	1.5	V
V_{OVP}	OVP threshold	Measured at the VOUT pin wrt/ V_{REFIN}	117%	120%	123%	
V_{UVP}	UVP threshold	Measured at the VOUT pin wrt/ V_{REFIN} , device latches OFF, begins soft-stop	65%	68%	71%	
TH_{SD}	Thermal shutdown ⁽¹⁾	Latch off controller, attempt soft-stop.		145		°C
$TH_{SD(hys)}$	Thermal Shutdown hysteresis ⁽¹⁾	Controller re-starts after temperature has dropped		10		°C
DRIVERS: BOOT STRAP SWITCH						
$R_{DSONBST}$	Internal BST switch on-resistance	$I_{BST} = 10\text{ mA}$, $T_A = 25^\circ\text{C}$			10	Ω
I_{BSTLK}	Internal BST switch leakage current	$V_{BST} = 14\text{ V}$, $V_{SW} = 7\text{ V}$			1	μA
TIMERS: ON-TIME, MINIMUM OFF-TIME, SS, AND I/O TIMINGS						
$t_{ONESHOTC}$	PWM one-shot ⁽¹⁾	$V_{VIN} = 5\text{ V}$, $V_{VOUT} = 1.05\text{ V}$, $f_{SW} = 1\text{ MHz}$		210		ns
		$V_{VIN} = 5\text{ V}$, $V_{VOUT} = 1.05\text{ V}$, $f_{SW} = 600\text{ kHz}$		310		
$t_{MIN(off)}$	Minimum OFF time	$V_{VIN} = 5\text{ V}$, $V_{VOUT} = 1.05\text{ V}$, $f_{SW} = 1\text{ MHz}$, DRVL on, SW = PGND, $V_{VOUT} < V_{REFIN}$		270		ns
$t_{INT(SS)}$	Soft-start time	From V_{OUT} ramp starting to $V_{OUT} = 95\%$, default setting		1.6		ms
$t_{INT(SSDLY)}$	Internal soft-start delay time	From $V_{VREF} = 2\text{ V}$ to V_{OUT} is ready to ramp up		260		μs
t_{PGDDLY}	PGOOD startup delay time	At external tracking, the time from V_{OUT} is ready to ramp up		8		ms
$t_{PGDPDLYH}$	PGOOD high propagation delay time	50 mV over drive, rising edge	0.8	1	1.2	ms
$t_{PGDPDLYL}$	PGOOD low propagation delay time	50 mV over drive, falling edge		10		μs
t_{OVDPDY}	OVP delay time	Time from the VOUT pin out of +20% of V_{REFIN} to OVP fault		10		μs
$t_{UVDLYEN}$	Undervoltage fault enable delay	Time from EN_INT going high to undervoltage fault is ready		2		ms
		External tracking from VOUT ramp starts		8		
t_{UVPDLY}	UVP delay time	Time from the VOUT pin out of -32% of V_{REFIN} to UVP fault		256		μs
LOGIC PINS: I/O VOLTAGE AND CURRENT						
V_{PGDPD}	PGOOD pull-down voltage	PGOOD low impedance, $I_{SINK} = 4\text{ mA}$, $V_{VIN} = 4.5\text{ V}$			0.3	V
I_{PGDLKG}	PGOOD leakage current	PGOOD high impedance, forced to 5.5 V	-1	0	1	μA
V_{ENH}	EN logic high	EN, VCCP logic	2			V
V_{ENL}	EN logic low	EN, VCCP logic			0.5	V
I_{EN}	EN input current				1	μA

(2) If V_{5IN} is higher than 1.5 V, PGOOD is valid regardless of the voltage applied at VIN. This is based on bench testing.

Electrical Characteristics (continued)

over recommended free-air temperature range, $V_{VIN} = 5.0\text{ V}$, PGND = GND (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{MODETH} MODE threshold voltage ⁽³⁾	Threshold 1	80	130	180	mV
	Threshold 2	200	250	300	
	Threshold 3	370	420	470	
	Threshold 4	1.765	1.800	1.850	V
I_{MODE} MODE current			15		μA

(3) See Table 1 for descriptions of MODE parameters.

6.6 Typical Characteristics

Characterization data tested using the TPS53317EVM-750 where the external tracking input sets the output voltage and operates in non-droop mode. See SLUU642 for detailed configuration.

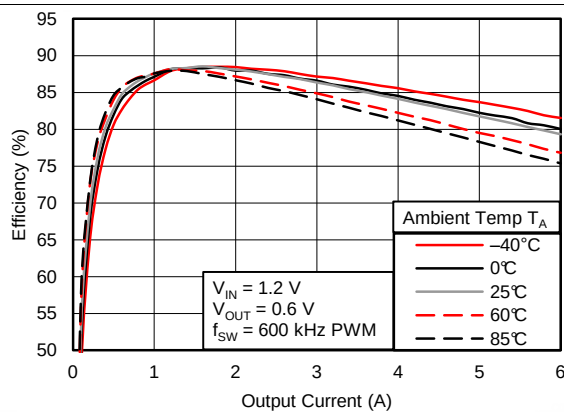


Figure 1. Efficiency vs. Output Current

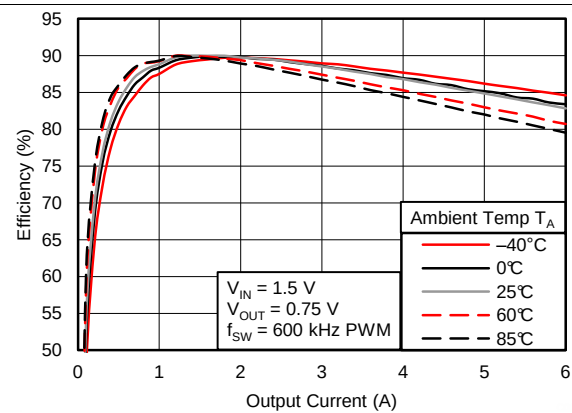


Figure 2. Efficiency vs. Output Current

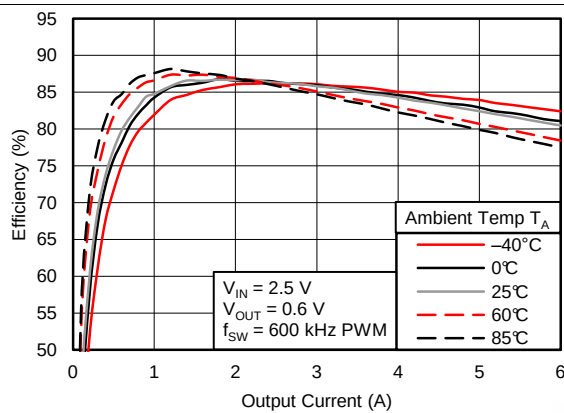


Figure 3. Efficiency vs. Output Current

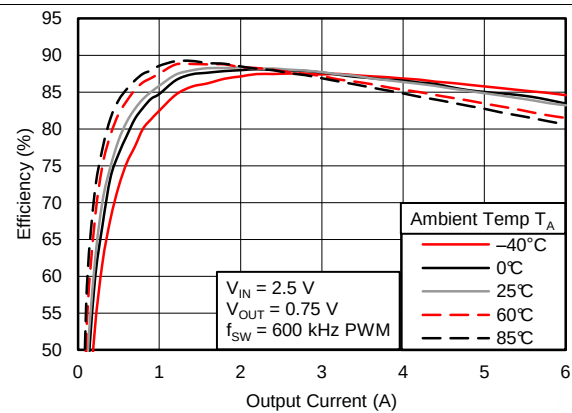


Figure 4. Efficiency vs. Output Current

Typical Characteristics (continued)

Characterization data tested using the TPS53317EVM-750 where the external tracking input sets the output voltage and operates in non-droop mode. See [SLUU642](#) for detailed configuration.

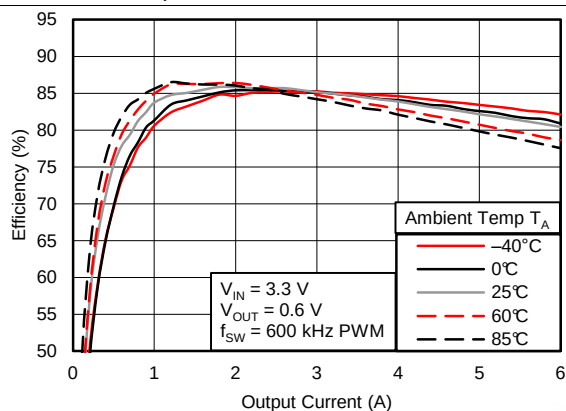


Figure 5. Efficiency vs. Output Current

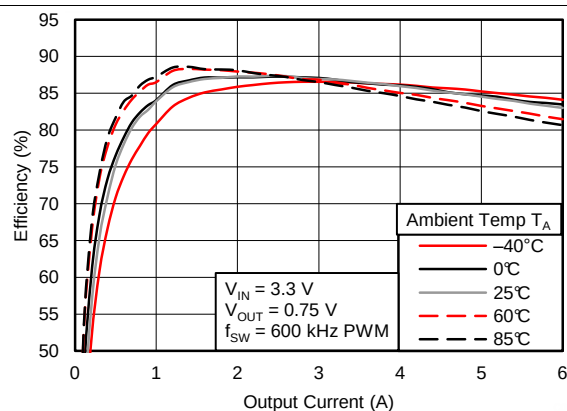


Figure 6. Efficiency vs. Output Current

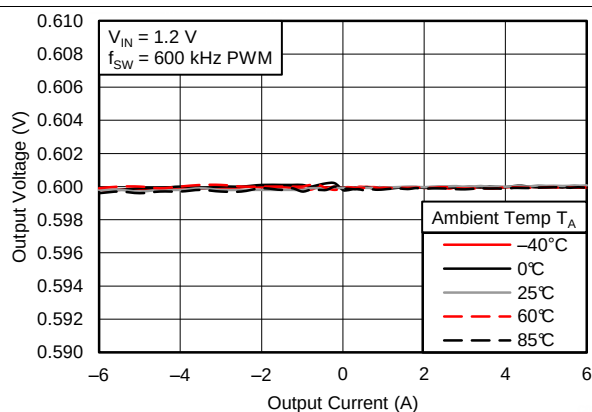


Figure 7. Load Regulation

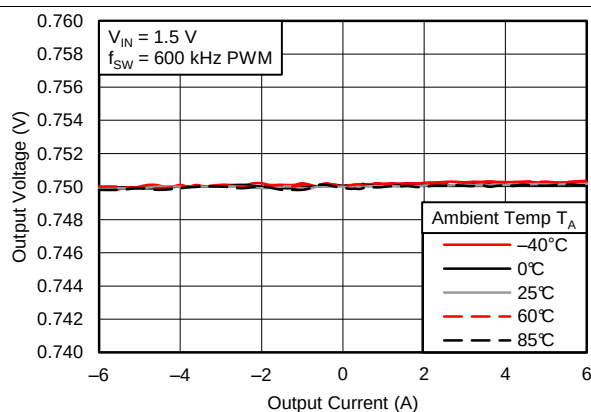


Figure 8. Load Regulation

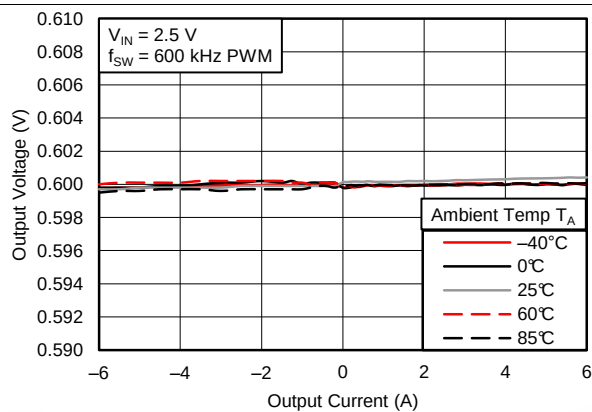


Figure 9. Load Regulation

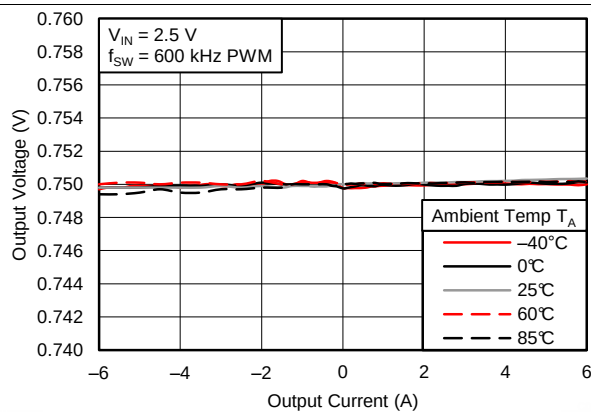
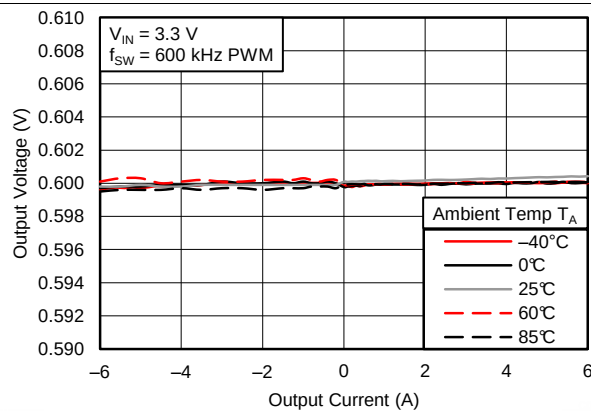
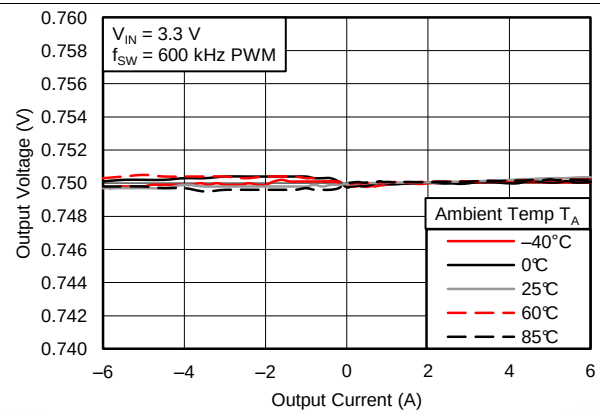
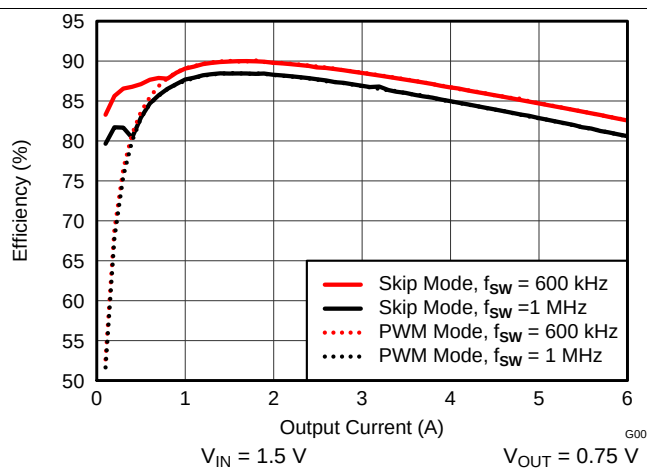
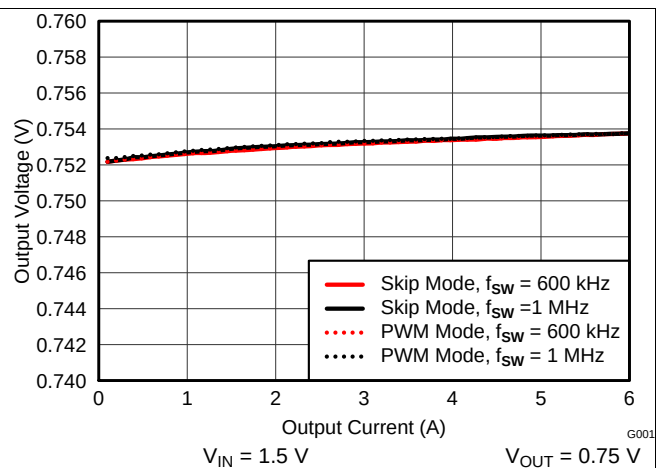
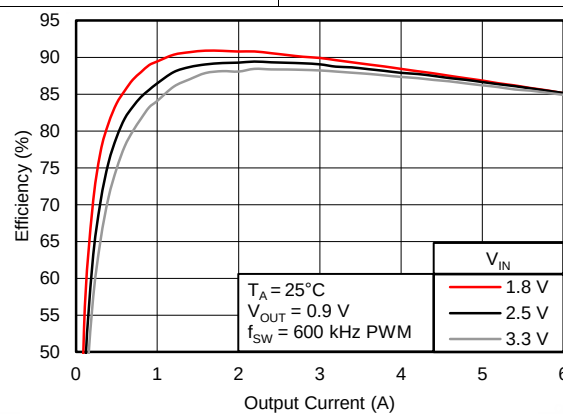


Figure 10. Load Regulation

Typical Characteristics (continued)

Characterization data tested using the TPS53317EVM-750 where the external tracking input sets the output voltage and operates in non-droop mode. See [SLUU642](#) for detailed configuration.


Figure 11. Load Regulation

Figure 12. Load Regulation

Figure 13. Efficiency vs Output Current

Figure 14. Load Regulation

Figure 15. Efficiency vs. Output Current

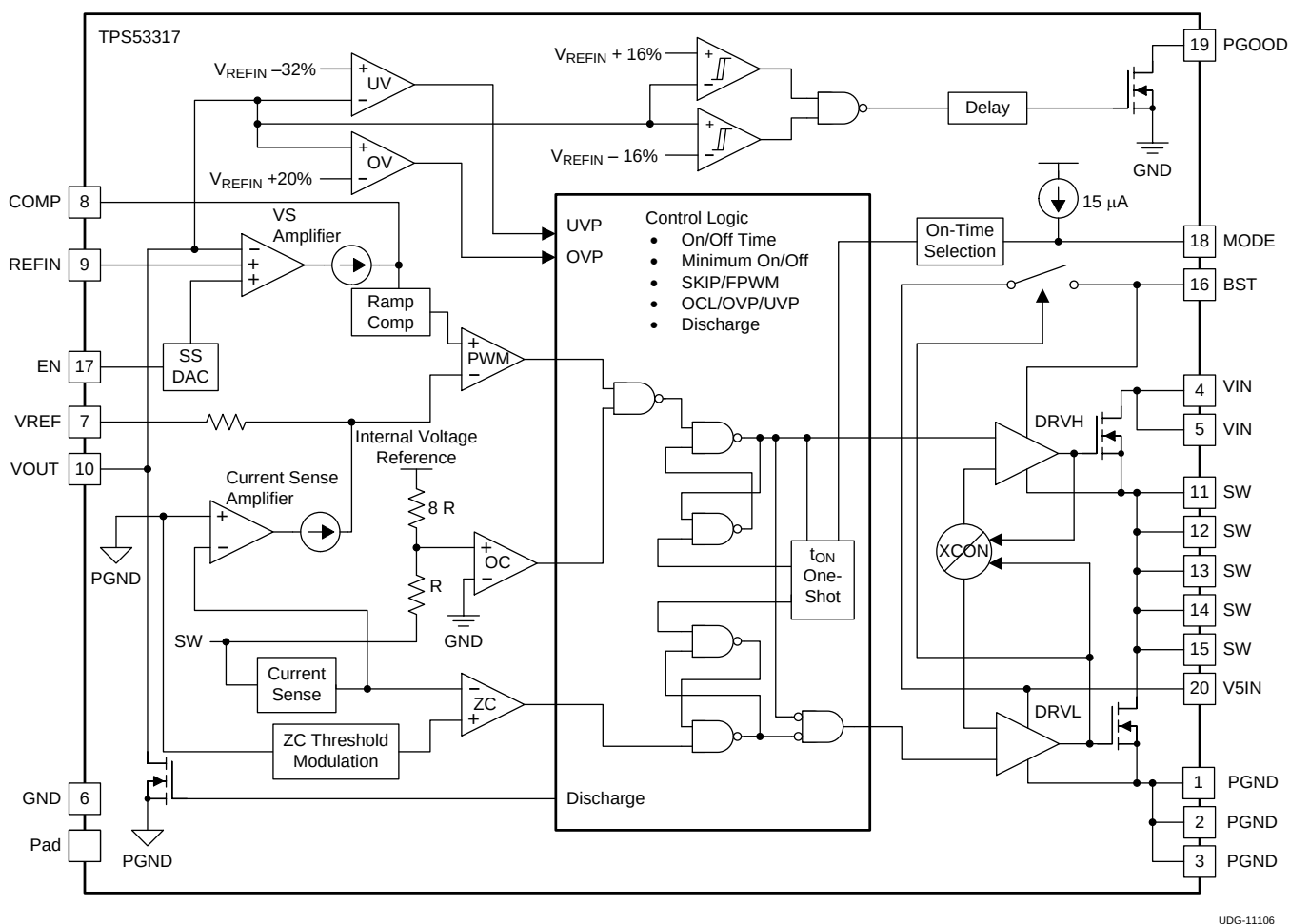
7 Detailed Description

7.1 Overview

The TPS53317 device is a D-CAP+™ mode adaptive on-time converter. Integrated high-side and low-side FETs support a maximum of 6-A DC output current. The converter automatically operates in discontinuous conduction mode (DCM) to optimize light-load efficiency. Multiple switching frequencies are provided to enable optimization of the power train for the cost, size and efficiency requirements of the design (see [Table 1](#)).

In adaptive on-time converters, the controller varies the on-time as a function of input and output voltage to maintain a nearly constant frequency during steady-state conditions. In conventional constant on-time converters, each cycle begins when the output voltage crosses to a fixed reference level. However, in the TPS53317 device, the cycle begins when the current feedback reaches an error voltage level which is the amplified difference between the reference voltage and the feedback voltage.

7.2 Functional Block Diagram

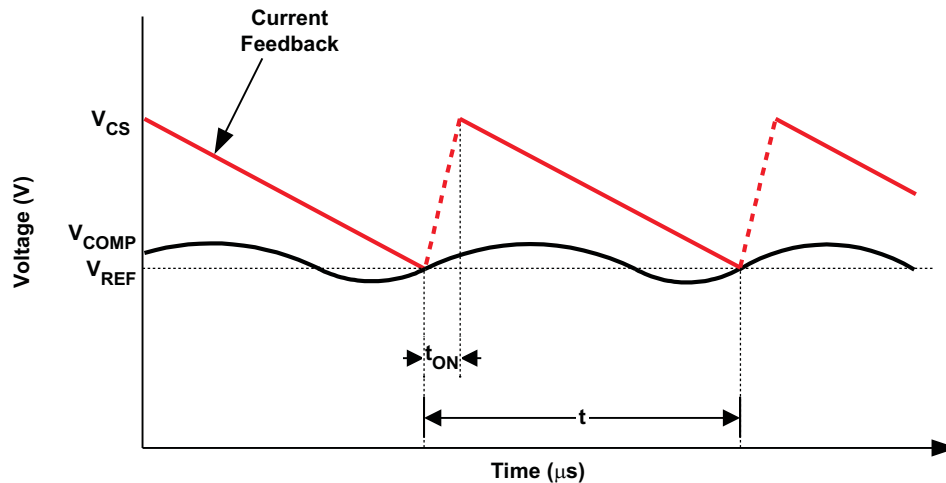


7.3 Feature Description

7.3.1 PWM Operation

Referring to [Figure 16](#), in steady state, continuous conduction mode, the converter operates in the following way.

Starting with the condition that the top FET is off and the bottom FET is on, the current feedback (V_{CS}) is higher than the error amplifier output (V_{COMP}). V_{CS} falls until it hits V_{COMP} , which contains a component of the output ripple voltage. V_{CS} is not directly accessible by measuring signals on pins of TPS53317 device. The PWM comparator senses where the two waveforms cross and triggers the on-time generator.



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Figure 16. D-CAP+™ Mode Basic Waveforms

The current feedback is an amplified and filtered version of the voltage between PGND and SW during low-side FET on-time. The device also provides a single-ended differential voltage (V_{OUT}) feedback to increase the system accuracy and reduce the dependence of circuit performance on layout.

7.3.2 PWM Frequency and Adaptive On-Time Control

In general, the on-time (at the SW node) can be estimated by [Equation 1](#).

$$t_{ON} = \frac{V_{OUT}}{V_{IN}} \times \frac{1}{f_{SW}}$$

where

- f_{SW} is the frequency selected by the connection of the MODE pin (1)

The on-time pulse is sent to the top FET. The inductor current and the current feedback rises to peak value. Each ON pulse is latched to prevent double pulsing. Switching frequency settings are shown in [Table 1](#).

7.3.3 Light-Load Power Saving Features

The TPS53317 device has an automatic pulse-skipping mode to provide excellent efficiency over a wide load range. The converter senses inductor current and prevents negative flow by shutting off the low-side gate driver. This saves power by eliminating re-circulation of the inductor current. Further, when the bottom FET shuts off, the converter enters discontinuous mode, and the switching frequency decreases, thus reducing switching losses as well.

The device also provides a special light-load power saving feature, called ripple reduction. Essentially, it reduces the on-time in SKIP mode to effectively reduce the output voltage ripple associated with using an all MLCC capacitor output power stage design.

Feature Description (continued)

7.3.4 Power Sequences

7.3.4.1 Non-Tracking Startup

The TPS53317 device can be configured for non-tracking application. When non-tracking is configured, output voltage is regulated to the REFIN voltage which taps off the voltage dividers from the 2-V reference voltage. Either the EN pin or the V5IN pin can be used to start up the device. The device uses internal voltage servo DAC to provide a 1.6-ms soft-start time during soft-start initialization. (See [Figure 18](#).)

In a non-tracking application, the output voltage is determined by the resistive divider between the VREF pin and the REFIN pin.

$$V_{OUT} = V_{REF} \times \frac{R2}{R1+R2} \quad (2)$$

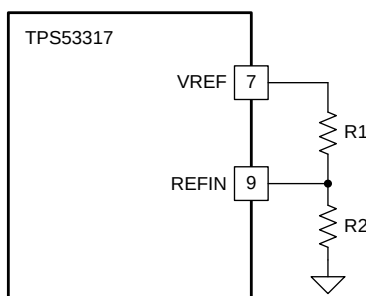


Figure 17. Non-Tracking Configuration

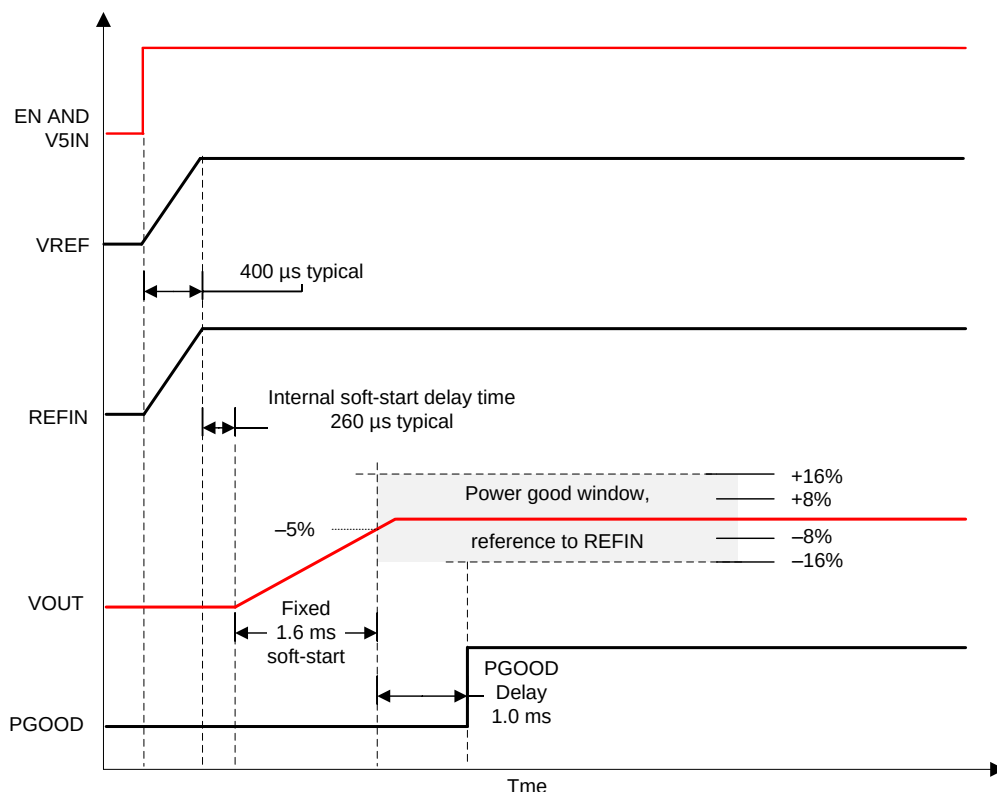


Figure 18. Non-Tracking Startup Timing

Feature Description (continued)

7.3.4.2 Tracking Startup

The TPS53317 device can also be configured for tracking application. When tracking configuration is desired, output voltage is also regulated to the REFIN voltage which comes from an external power source. In order for the device to differentiate between a non-tracking configuration or a tracking configuration, there is a minimum delay time of 260 μ s required between the time when VREF reaches 2 V to the time when the REFIN pin voltage can be applied, in order for the device to track properly (see Figure 21). The valid REFIN voltage range is between 0.6 V and 2 V.

In a tracking application, the output voltage should be one half of the VDDQ voltage. VDDQ can be VIN or it can be an additional voltage rail. Thus, R1= R2 both in Figure 19 and Figure 20.

$$V_{OUT} = \frac{1}{2} \times V_{VDDQ} \quad (3)$$

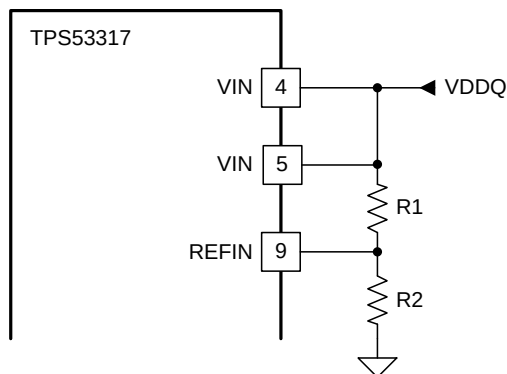


Figure 19. Tracking Configuration 1

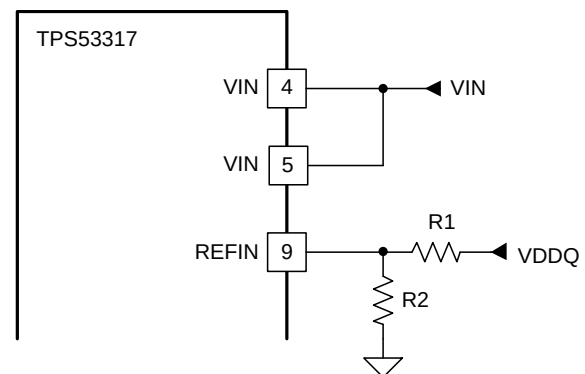


Figure 20. Tracking Configuration 2

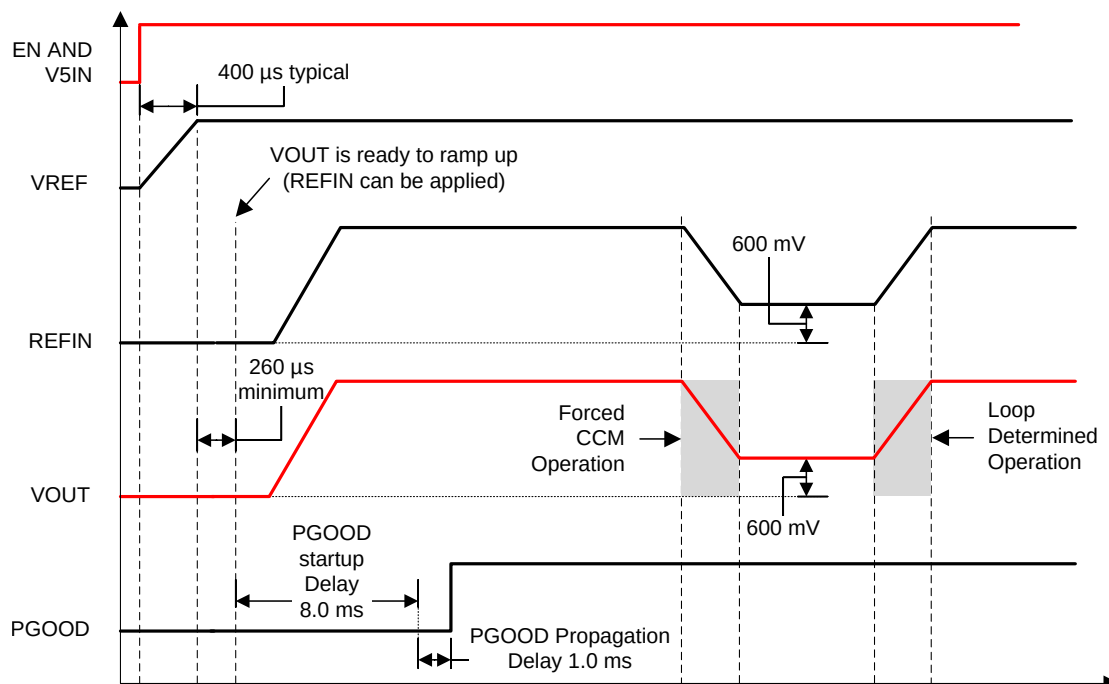


Figure 21. Tracking Startup Timing

Select PWM mode for an application that requires external tracking, because the output voltage can not be decreased during a no-load condition when the device operates in SKIP mode.

Feature Description (continued)

7.3.5 Protection Features

The TPS53317 device offers many features to protect the converter power train as well as the system electronics.

7.3.5.1 5-V Undervoltage Protection (UVLO)

The TPS53317 device continuously monitors the voltage on the V5IN pin to ensure that the voltage level is high enough to bias the device properly and to provide sufficient gate drive potential to maintain high efficiency. The converter starts with approximately 4.3 V and has a nominal 440 mV of hysteresis. If the 5-V UVLO limit is reached, the converter transitions the phase node into an off function, and the converter remains in the off state until the device is reset by cycling the 5-V supply until the 5-V POR is reached (2.3-V nominal). The power input does not have a UVLO function.

7.3.5.2 Power Good Signals

The TPS53317 device has one open-drain *power good* (PGOOD) pin. During startup, there is a 1-ms power good high propagation delay. The PGOOD pin de-asserts as soon as the EN pin is pulled low or an undervoltage condition on V5IN or any other fault is detected.

7.3.5.3 Output Overvoltage Protection (OVP)

In addition to the power good function described above, the TPS53317 device has additional OVP and UVP thresholds and protection circuits.

An OVP condition is detected when the output voltage is approximately $120\% \times V_{REFIN}$. In this case, the converter de-asserts the PGOOD signals and performs the overvoltage protection function. During OVP, the low-side FET is always on before triggering a negative overcurrent. When a negative OC is also tripped, the low-side FET is no longer continuously on, and pulsed signals are generated to limit the negative inductor current. When the VOUT pin voltage drops below 400 mV, the low-side FET turns off and the converter latches off. The converter remains in the off state until the device is reset by cycling the 5-V supply until the 5-V POR is reached (2.3-V nominal) or when the EN pin is toggled off and on.

7.3.5.4 Output Undervoltage Protection (UVP)

Output undervoltage protection works in conjunction with the current protection described in the [Overcurrent Protection](#) and [Overcurrent Limit](#) sections. If the output voltage drops below 68% of V_{REFIN} , after approximately a 250-μs delay, the device stops switching and enters hiccup mode. After a hiccup waiting time, a restart is attempted. If the fault condition is not cleared, hiccup mode operation may continue indefinitely.

7.3.5.5 Overcurrent Protection

Both positive and negative overcurrent protection are provided in the TPS53317 device.

- Overcurrent Limit (OCL)
- Negative OCL

7.3.5.5.1 Overcurrent Limit

If the sensed current value is above the OCL setting, the converter delays the next ON pulse until the current drops below the OCL limit. Current limiting occurs on a pulse-by-pulse basis. The device uses a valley current limiting scheme where the DC OCL trip point is the OCL limit plus half of the inductor ripple current. The typical valley OCL threshold is 7.6 A or 5.4 A (depending on mode selection). The average output current limit calculation is shown in [Equation 4](#).

During the overcurrent protection event, the output voltage droops if the duty cycle cannot satisfy output voltage requirements and continues to droop until the UVP limit is reached. Then, the converter de-asserts the PGOOD pin, and then enters hiccup mode after a 250-μs delay. The converter remains in hiccup mode until the fault is cleared.

$$I_{OCL(dc)} = I_{OCL(valley)} + \frac{1}{2} \times I_{P-P} \quad (4)$$

Feature Description (continued)

7.3.5.2 Negative OCL

The negative OCL circuit acts when the converter is sinking current from the output capacitor(s). The converter continues to act in a *valley* mode, the typical value of the negative OCL set point is -9.3 A or -6.5 A (depending on mode selection).

7.3.6 Thermal Protection

The TPS53317 device has an internal temperature sensor. When the temperature reaches a nominal 145°C , the device shuts down until the temperature decreases by approximately 10°C , when the converter restarts.

7.4 Device Functional Modes

7.4.1 Non-Droop Configuration

The TPS53317 device can be configured as a non-droop solution. The benefit of a non-droop approach is that load regulation is flat, therefore, in a system where tight DC tolerance is desired, the non-droop approach is recommended. For the Intel system agent application, non-droop is recommended as the standard configuration.

The non-droop approach can be implemented by connecting a resistor and a capacitor between the COMP and the VREF pins. The purpose of the type II compensation is to obtain high DC feedback gain while minimizing the phase delay at unity gain cross over frequency of the converter.

The value of the resistor (R_C) can be calculated using the desired unity gain bandwidth of the converter, and the value of the capacitor (C_C) can be calculated by knowing where the zero location is desired. The capacitor C_P is optional, but recommended. Its appropriate capacitance value can be calculated using the desired pole location.

Figure 22 shows the basic implementation of the non-droop mode using the device

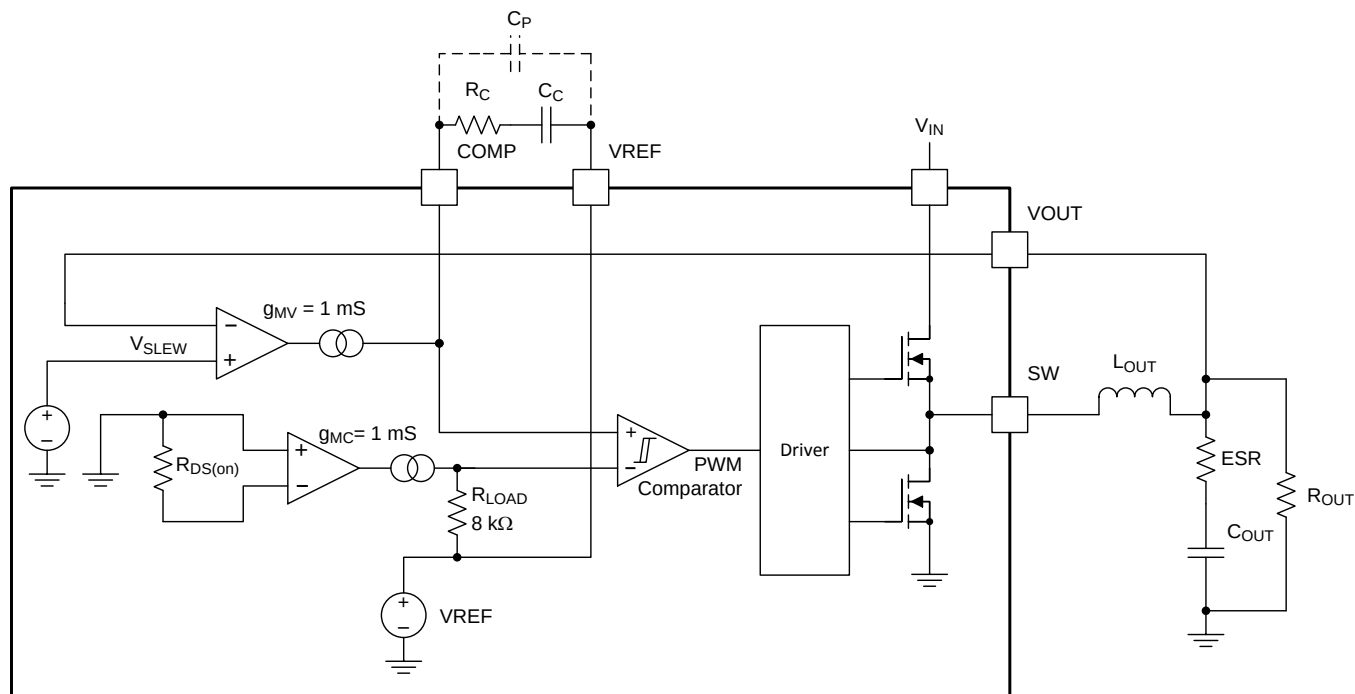
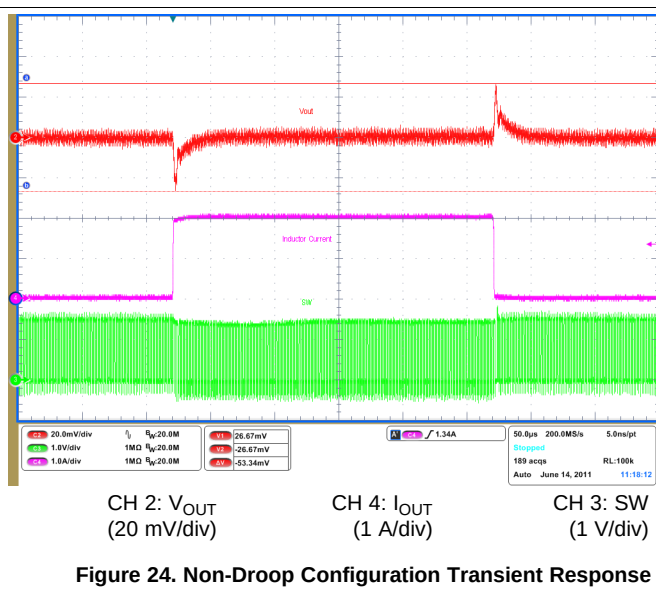
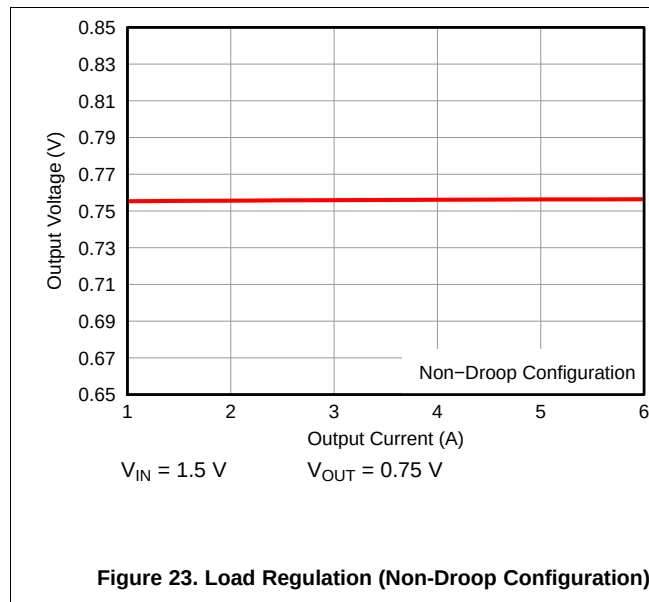


Figure 22. Non-Droop Mode Basic Implementation

Device Functional Modes (continued)

Figure 23 shows the load regulation using non-droop configuration.

Figure 24 shows the transient response of the device using non-droop configuration, where $C_{OUT} = 3 \times 47 \mu\text{F}$. The applied step load is from 0 A to 2 A.



7.4.2 Droop Configuration

The terminology for droop is the same as *load line* or *voltage positioning* as defined in the Intel CPU V_{CORE} specification. Based on the actual tolerance requirement of the application, load-line set points can be defined to maximize either cost savings (by reducing output capacitors) or power reduction benefits.

Accurate droop voltage response is provided by the finite gain of the droop amplifier. The equation for droop voltage is shown in Equation 5.

$$V_{DROOP} = \frac{A_{CSINT} \times I_{OUT}}{R_{DROOP} \times g_M}$$

where

- low-side on-resistance is used as the current sensing element
 - A_{CSINT} is a constant, which nominally is 53 mV/A.
 - I_{OUT} is the DC current of the inductor, or the load current
 - R_{DROOP} is the value of resistor from the COMP pin to the VREF pin
 - g_M is the transconductance of the droop amplifier with nominal value of 1 mS
- (5)

Equation 6 can be used to easily derive R_{DROOP} for any load line slope/droop design target.

$$R_{LOAD_LINE} = \frac{V_{DROOP}}{I_{OUT}} = \frac{A_{CSINT}}{R_{DROOP} \times g_M} \therefore R_{DROOP} = \frac{A_{CSINT}}{R_{LOAD_LINE} \times g_M}$$

(6)

Device Functional Modes (continued)

In applications where the DC and the AC tolerances are not separated, (meaning that there is no strict DC tolerance requirement) the droop method can be used.

Table 1. Mode Definitions

MODE	MODE RESISTANCE (kΩ)	LIGHT-LOAD POWER SAVING MODE	SWITCHING FREQUENCY (f _{sw})	OVERCURRENT LIMIT (OCL) VALLEY (A)
1	0	SKIP	600 kHz	7.6
2	12		600 kHz	5.4
3	22		1 MHz	5.4
4	33		1 MHz	7.6
5	47	PWM	600 kHz	7.6
6	68		600 kHz	5.4
7	100		1 MHz	5.4
8	OPEN		1 MHz	7.6

Figure 27 shows the load regulation of the 1.5-V rail using an R_{DROOP} value of 6.8 kΩ.

Figure 28 shows the transient response of the TPS53317 device using droop configuration and C_{OUT} = 3 × 47 μF. The applied step load is from 0 A to 2 A.

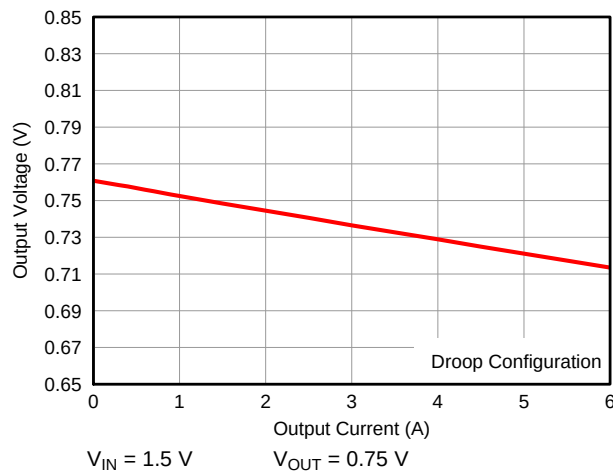


Figure 27. Load Regulation (Droop Configuration)

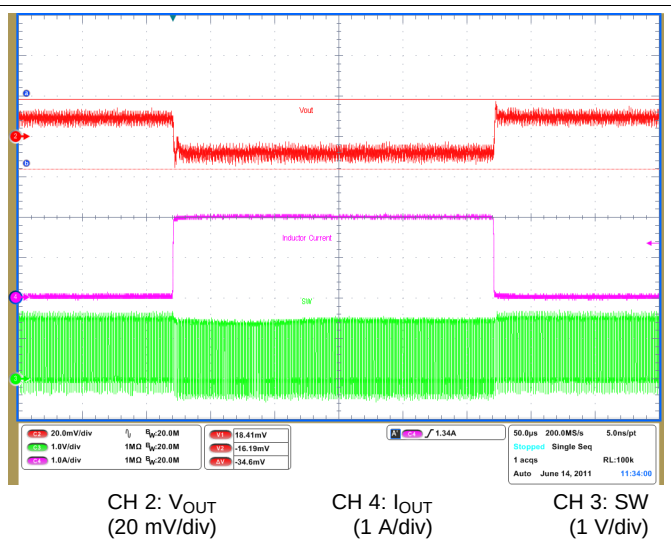


Figure 28. Droop Configuration Transient Response

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The TPS53317 device is a FET-integrated synchronous buck regulator designed mainly for DDR termination. It can provide a regulated output at $\frac{1}{2}$ VDDQ with both sink and source capability. The device employs D-CAP+ mode operation that provides ease-of-use, low external component count and fast transient response.

8.2 Typical Applications

8.2.1 DDR4 SDRAM Application

This DDR4 application requires a tight load tolerance, fast transient response, and sinking current capability, the design uses a non-droop PWM configuration.

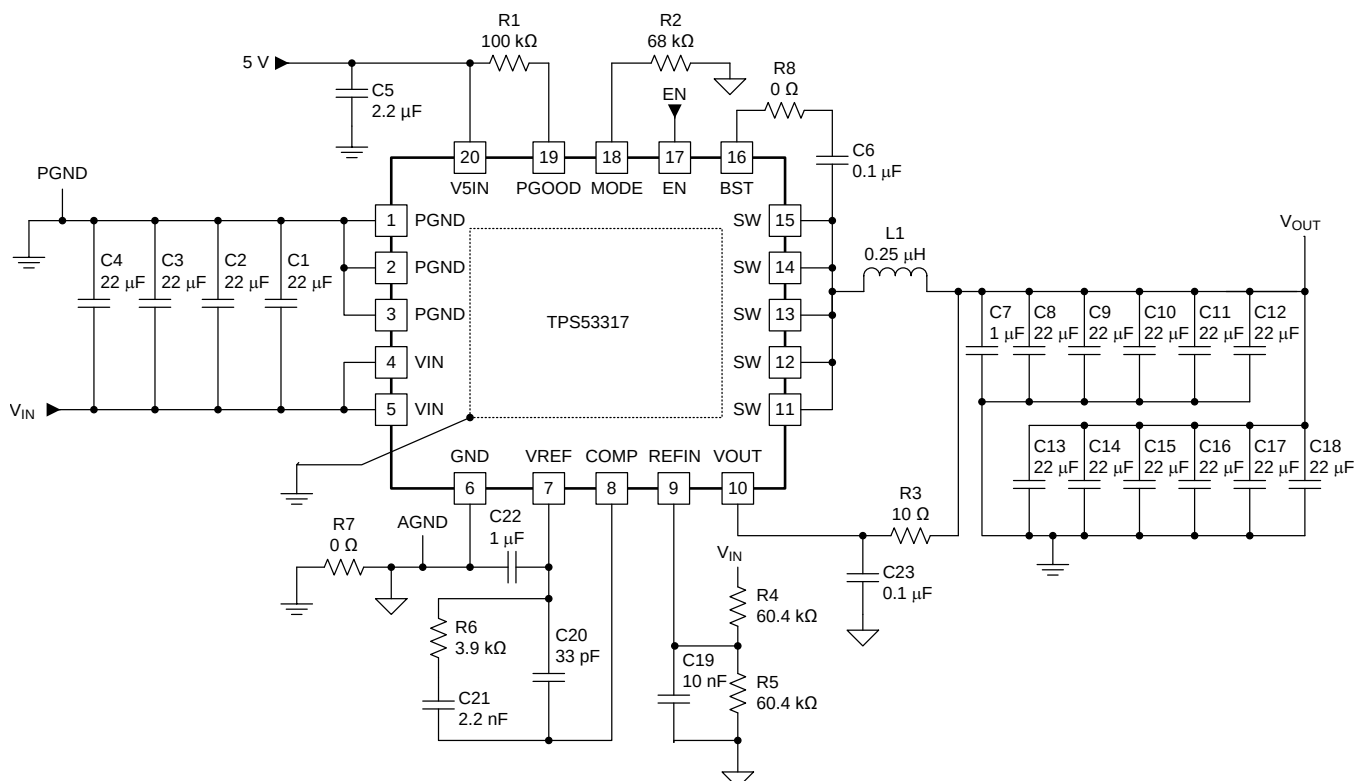


Figure 29. DDR4 SDRAM Application

8.2.1.1 Design Requirements

- Input voltage : $V_{IN} = 1.2$ V
- Output voltage: $V_{OUT} = 0.6$ V
- Maximum load step size of 3 A @ slew rate 7 A/μs (–1.5 A to 1.5 A)
- DC +AC + Ripple voltage regulation limit at sense point: ± 42 mV (0.642 V overshoot, 0.558 V undershoot)
- Maximum load: $I_{MAX} = 2.5$ A

Typical Applications (continued)

8.2.1.2 Detailed Design Procedure

8.2.1.2.1 Step 1. Determine Configuration

Because this DDR4 application requires a tight load tolerance, fast transient response, and sinking current capability, the design uses a non-droop PWM configuration. Choose 600-kHz switching frequency due to the duty cycle and minimum off-time of the device, and set an overcurrent (OC) valley limit of 5.4 A due to the maximum load requirement of 2.5 A. Referring to [Table 1](#) select an R_{MODE} value of 68 k Ω .

8.2.1.2.2 Step 2. Select Inductor

Smaller inductor values have better transient performance but higher ripple and lower efficiency. High values have the opposite characteristics. It is common practice to limit the ripple current to 30% to 50% of the maximum current. Choose 50% to allow use of a smaller inductor for faster transient performance.

$$\Delta I_{P-P} = 2.5 \text{ A} \times 0.5 = 1.25 \text{ A} \quad (7)$$

$$L = \frac{1}{f_{SW} \times \Delta I_{P-P}} \times V_{OUT} \times (1 - D)$$

where

- D = duty cycle (8)

Because this device operates in DCAP+ mode, the frequency and duty cycle vary based on the input voltage, the output voltage and load. With a 2.5-A load, a 1.2-V input voltage and 0.60 V output voltage, f_{SW} is experimentally measured at approximately 800 kHz and duty cycle of 0.55. Therefore L is calculated as shown in [Equation 10](#).

$$L = \frac{1}{(800 \text{ kHz} \times 1.25 \text{ A})} \times 0.6 \text{ V} \times 0.45 = 0.270 \text{ } \mu\text{H} \quad (9)$$

Choose the closest standard value, 0.25 μH .

8.2.1.2.3 Step 3. Determine Output Capacitance

Use [Equation 10](#) to calculate the output capacitance for a desired maximum overshoot.

$$C_{OUT(min),OS} = \frac{\Delta I_{OUT}^2 \times L}{2 \times V_{OUT} \times V_{OS}}$$

where

- $C_{OUT(min),OS}$ is the minimum output capacitance for a desired overshoot
- ΔI_{OUT} is the maximum output current change in the application
- V_{OUT} = desired output voltage
- V_{OS} is the desired output voltage change due to overshoot (10)

Choose a value of 30 mV to account for normal output voltage ripple.

$$C_{OUT(min),OS} = \frac{(3 \text{ A})^2 \times 0.25 \text{ } \mu\text{H}}{2 \times 0.6 \text{ V} \times 0.03 \text{ V}} = 62.5 \text{ } \mu\text{F} \quad (11)$$

Use [Equation 12](#) to calculate the necessary output capacitance for a desired maximum undershoot.

$$C_{OUT(min),US} = \frac{\Delta I_{OUT}^2 \times L \times \left(\frac{V_{OUT}}{V_{IN}} \times t_{SW} + t_{MIN(off)} \right)}{2 \times V_{OUT} \times V_{US} \times \left(\frac{V_{IN} - V_{OUT}}{V_{IN}} \times t_{SW} - t_{MIN(off)} \right)}$$

where

- $C_{OUT(min),US}$ is the minimum output capacitance for a desired undershoot
- V_{US} is the desired output voltage change due to overshoot
- t_{SW} is the period of switch node
- $t_{MIN(off)}$ is the minimum off-time (270 ns) (12)

Typical Applications (continued)

Again, choose 30 mV to account for normal output voltage ripple.

$$C_{OUT(min),US} = \frac{(3A)^2 \times 0.25 \mu H \times \left(\frac{0.6V}{1.2V} \times \frac{1}{800 kHz} + 270 ns \right)}{2 \times 0.6V \times 0.03V \times \left(\frac{1.2V - 0.6V}{1.2V} \times \frac{1}{800 kHz} - 270 ns \right)} = 157.6 \mu F \quad (13)$$

The undershoot requirements determine, so there must be a minimum of 157.6 μF . Because this is a DDR application where size is also a consideration, this design uses only ceramic capacitors. To account for voltage de-rating of capacitors and provide additional margin, this design includes eleven 22- μF output capacitors.

8.2.1.2.4 Step 4. Input Capacitance

This design requires sufficient input capacitance to filter the input current from the host source. Use [Equation 14](#) to calculate the necessary input capacitance.

$$C_{IN(min)} = I_{out} \times \frac{D \times (1 - D)}{\Delta V_{IN(P-P)} \times f_{SW}}$$

where

- $\Delta V_{IN(P-P)}$ is the desired input voltage ripple (typically 1% of the input voltage) (14)

$$C_{IN(min)} = 2.5 A \times \frac{0.55 \times (1 - 0.55)}{12 mV \times 800 kHz} = 64.45 \mu F \quad (15)$$

As with the output capacitance selection, this design accounts for voltage de-rating of capacitors and provides additional margin, using four 22- μF input capacitors.

8.2.1.2.5 Step 5. Compensation Network

In order to achieve stable operation, the crossover frequency should be less than 1/5 of the switching frequency.

$$f_{CO} = \frac{1}{2\pi} \times \frac{g_M}{C_{OUT}} \times \frac{R_C}{R_S} = 80 kHz$$

where

- $R_S = 53 m\Omega$ (16)

Account for capacitor de-rating here and set the value of C_{OUT} to 160 μF , so that [Equation 17](#) is true.

$$R_C = \frac{f_{CO} \times R_S \times 2\pi \times C_{OUT}}{g_M} = \frac{80 kHz \times 53 m\Omega \times 2\pi \times 160 \mu F}{1 mS} = 4.26 k\Omega \quad (17)$$

Choose an R_C value of 3.9 $k\Omega$. Determine C_C by choosing the value of the zero created by R_C and C_C . Using the relationship described in [Equation 18](#).

$$f_z = \frac{f_{CO}}{5} = \frac{1}{2\pi \times R_C \times C_C} \quad (18)$$

[Equation 18](#) yields a C_C value of 2.55 nF. Choose the closest common capacitor value of 2.2 nF. To determine a value for C_P , first consider the relationship described in [Equation 19](#).

$$f_p = \frac{1}{2\pi \times R_C \times \frac{C_C \times C_P}{C_C + C_P}} \approx \frac{1}{2\pi \times R_C \times C_P} \quad (19)$$

Because $C_C \gg C_P$, set the pole to be two times the switching frequency as described in [Equation 20](#).

$$C_P \cong \frac{1}{2\pi \times R_C \times 2f_{SW}} = \frac{1}{2\pi \times 3.9 k\Omega \times 2 \times 800 kHz} = 25.5 pF \quad (20)$$

To boost the gain margin, set C_P to 33 pF.

Typical Applications (continued)

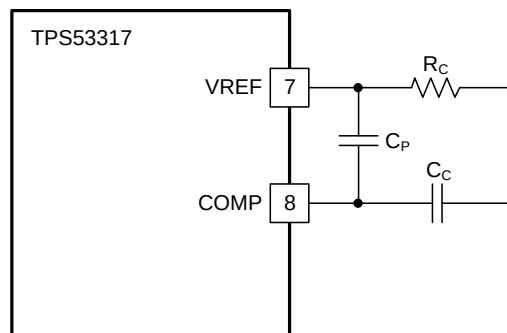


Figure 30. Compensation Network Circuit

8.2.1.2.6 Peripheral Component Selection

As described in Table 1, connect a 0.22- μ F capacitor from the VREF pin to GND and connect a 0.1- μ F bootstrap capacitor from the SW pin to the BST pin. Because the PGOOD pin is open drain, connect a pullup resistor between it and the 5-V rail.

8.2.1.3 Application Curves

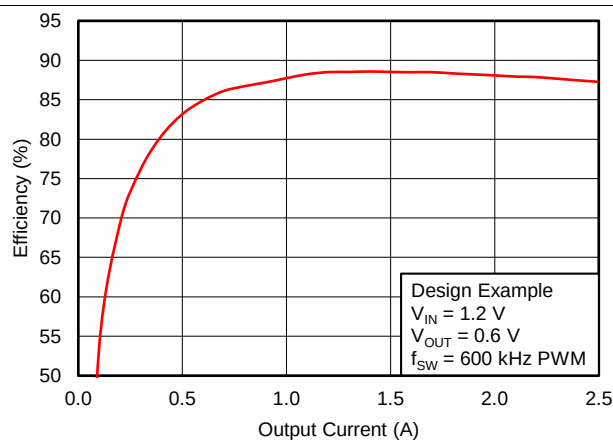


Figure 31. Efficiency

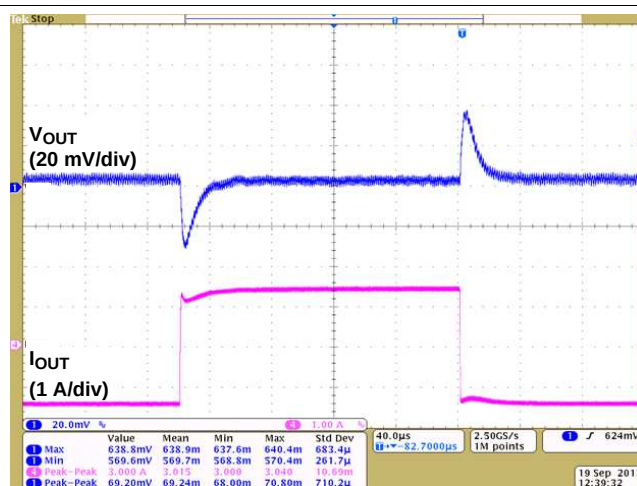


Figure 32. Load Transient

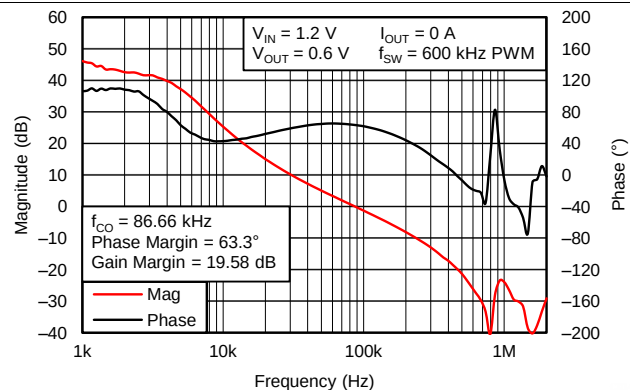


Figure 33. Bode Plot, No Load

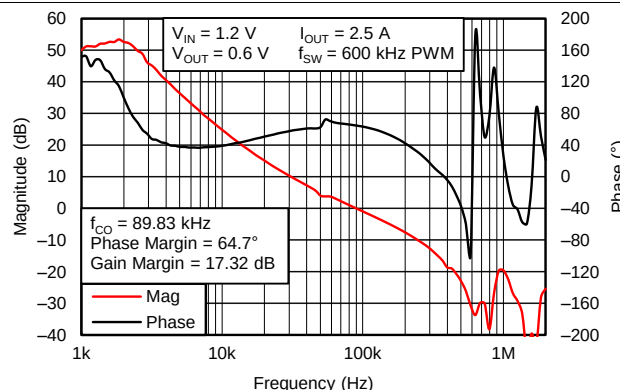
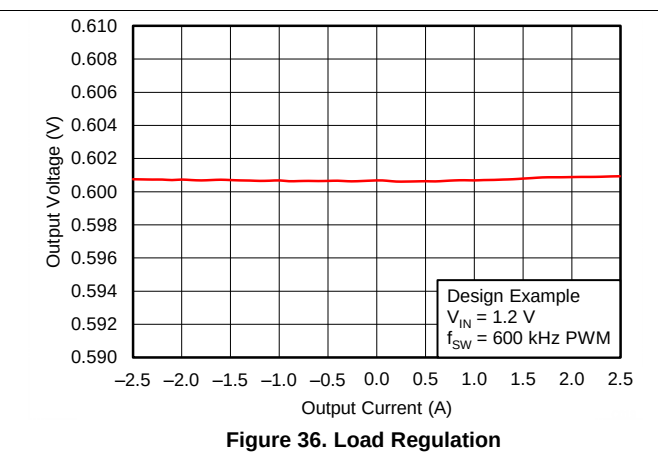
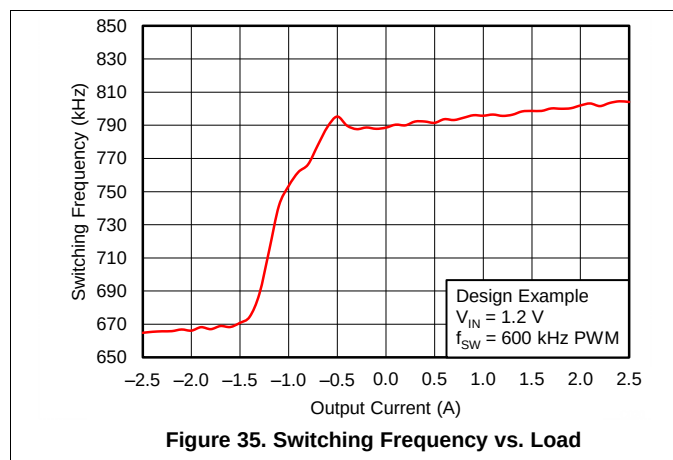


Figure 34. Bode Plot, Full Load

Typical Applications (continued)



8.2.2 DDR3 SDRAM Application

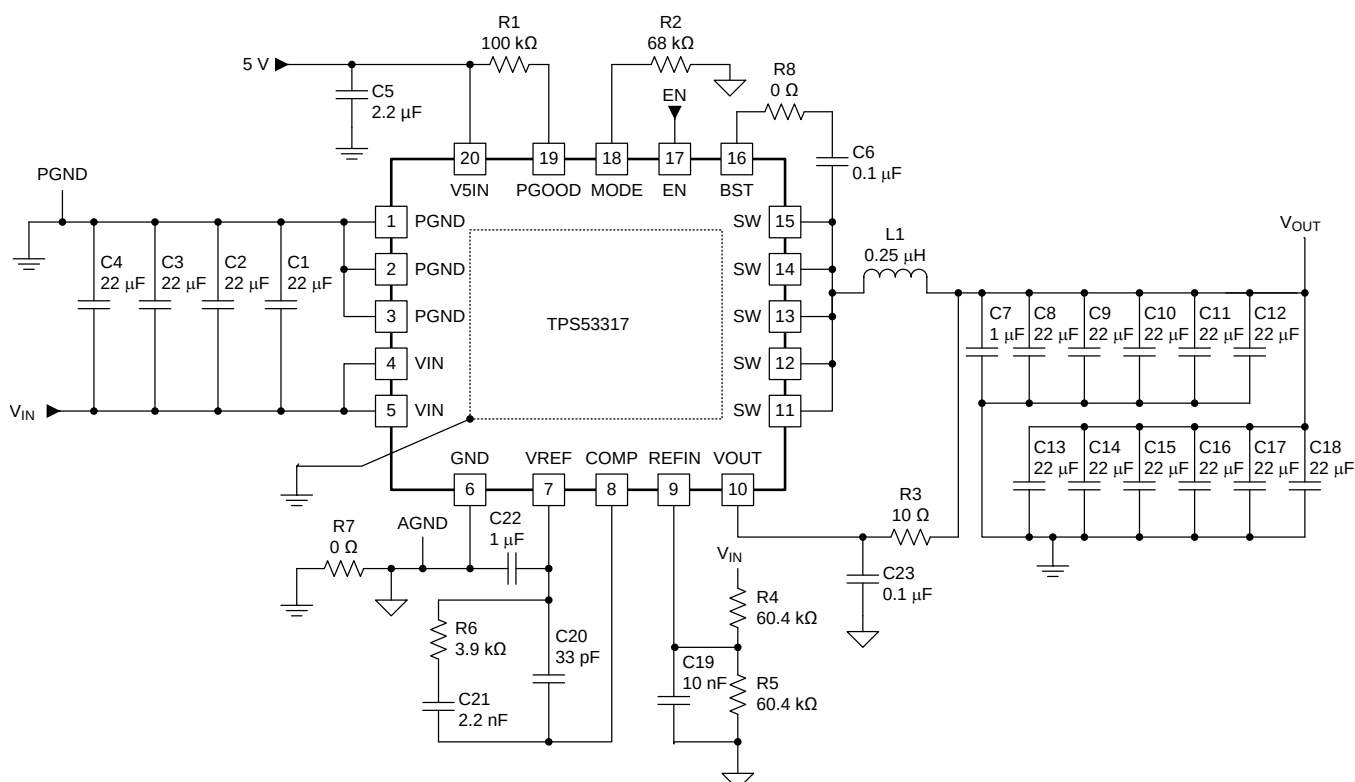


Figure 37. Typical Application Schematic, DDR3

8.2.2.1 Design Requirements

- $V_{IN} = 1.5 \text{ V}$
- $V_{OUT} = 0.75 \text{ V}$

Typical Applications (continued)

8.2.3 Non-Tracking Point-of-Load (POL) Application

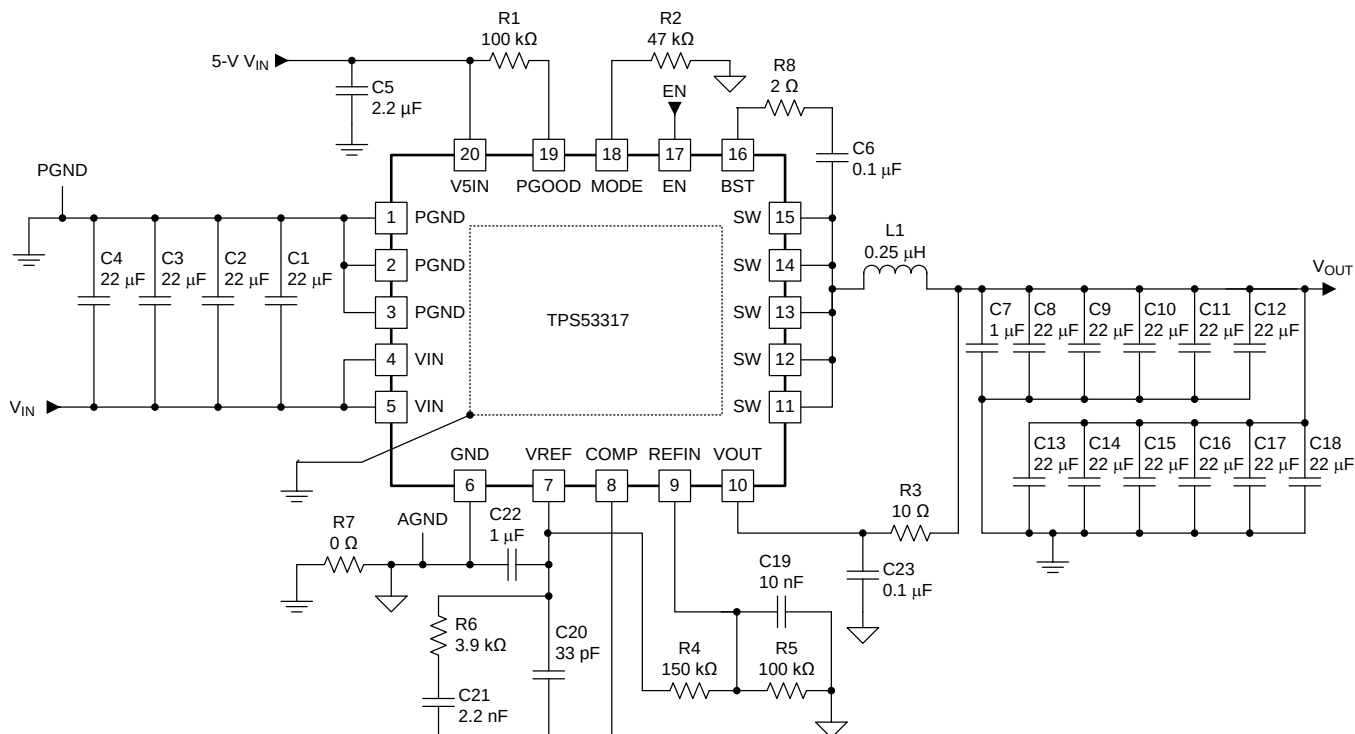
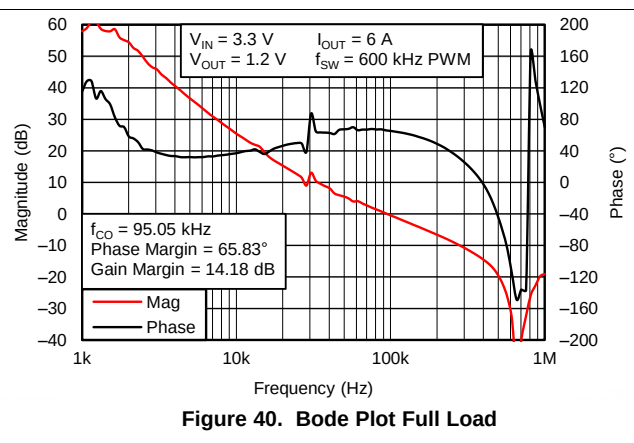
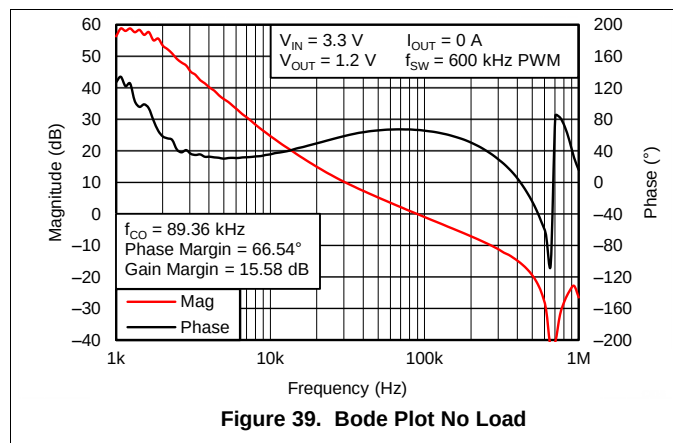


Figure 38. Typical Application Schematic, Non-Tracking Point-of-Load (POL)

8.2.3.1 Design Requirements

- $V_{IN} = 3.3 \text{ V}$
- $V_{OUT} = 1.2 \text{ V}$

8.2.3.2 Application Curves



9 Power Supply Recommendations

This device operates from an input voltage supply between 1 V and 6 V. This device requires a separate 5-V power supply for analog circuits and gate drive. Use the proper bypass capacitors for both the input supply and the 5-V supply in order to filter noise and to ensure proper device operation.

10 Layout

10.1 Layout Guidelines

Stable power supply operation depends on proper layout. Follow these guidelines for an optimized PCB layout.

- Connect PGND pins to the thermal pad underneath the device. Use four vias to connect the thermal pad to internal ground planes.
- Place VIN, V5IN and VREF decoupling capacitors as close to the device as possible.
- Use wide traces for the VIN, PGND and SW pins. These nodes carry high current and also serve as heat sinks.
- Place feedback and compensation components as close to the device as possible.
- Place COMP and VOUT analog signal traces away from noisy signals (SW, BST).
- The GND pin should connect to the PGND in only one place, through a via or a 0-Ω resistor.

10.2 Layout Example

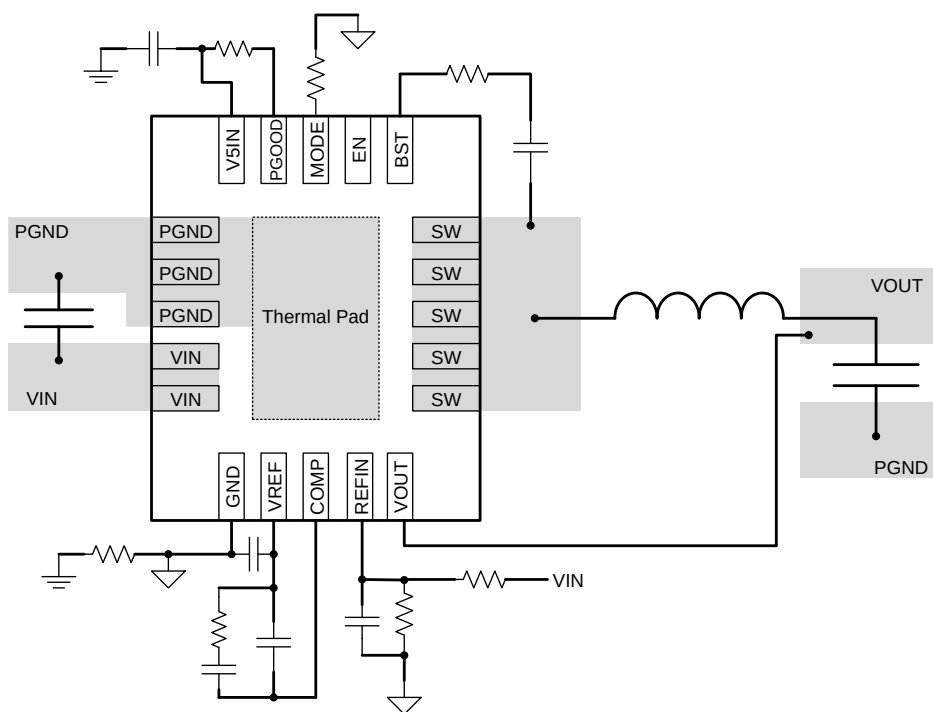


Figure 41. TPS53317 Board Layout

11 Device and Documentation Support

11.1 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.2 Trademarks

D-CAP+, D-CAP+, E2E are trademarks of Texas Instruments.
All other trademarks are the property of their respective owners.

11.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.4 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
DPA02257RGBR	Active	Production	VQFN (RGB) 20	3000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	53317
TPS53317RGBR	Active	Production	VQFN (RGB) 20	3000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	53317
TPS53317RGBR.A	Active	Production	VQFN (RGB) 20	3000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	53317
TPS53317RGBT	Active	Production	VQFN (RGB) 20	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	53317
TPS53317RGBT.A	Active	Production	VQFN (RGB) 20	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	53317

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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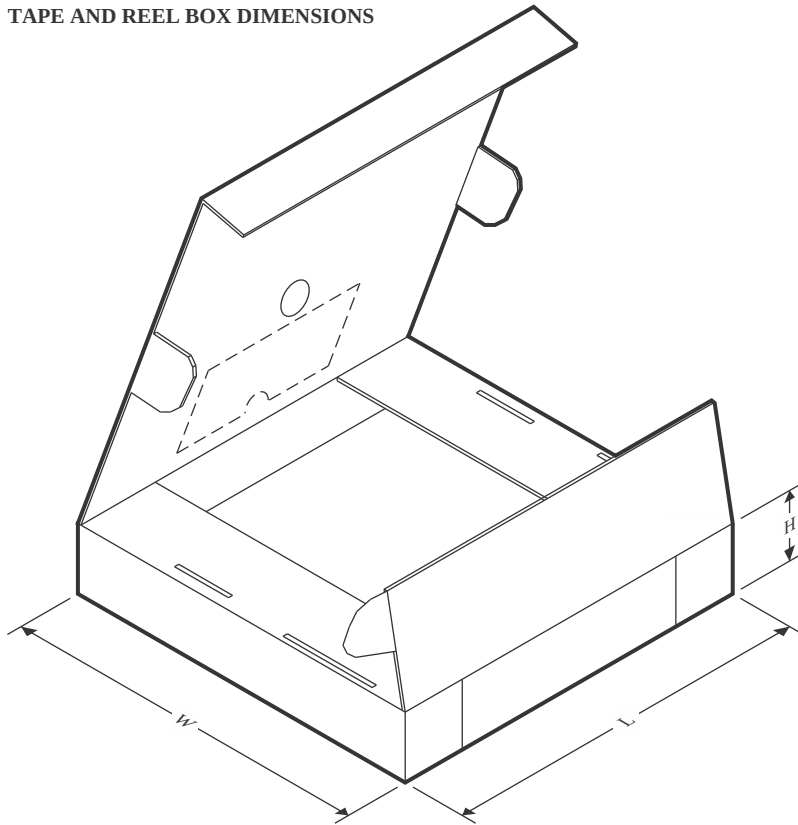
TAPE AND REEL INFORMATION



*All dimensions are nominal

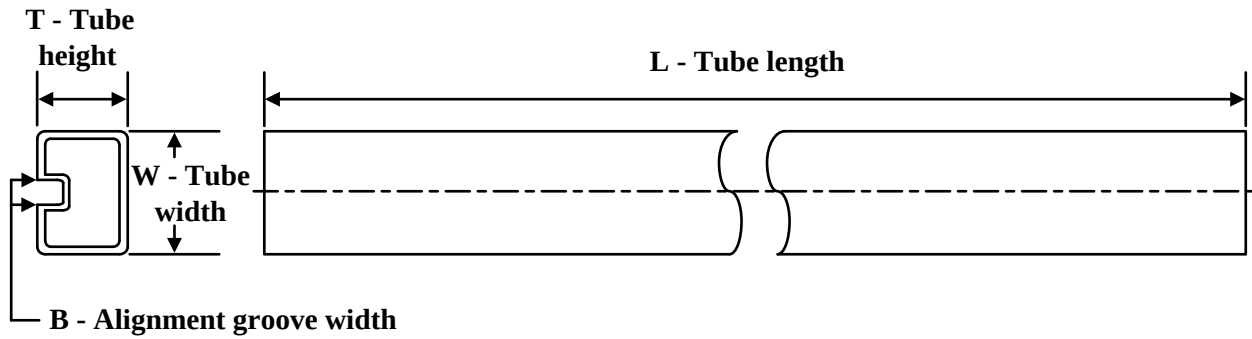
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS53317RGBR	VQFN	RGB	20	3000	330.0	12.4	3.8	4.3	1.5	8.0	12.0	Q1
TPS53317RGBT	VQFN	RGB	20	250	180.0	12.4	3.8	4.3	1.5	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS53317RGBR	VQFN	RGB	20	3000	552.0	346.0	36.0
TPS53317RGBT	VQFN	RGB	20	250	210.0	185.0	35.0

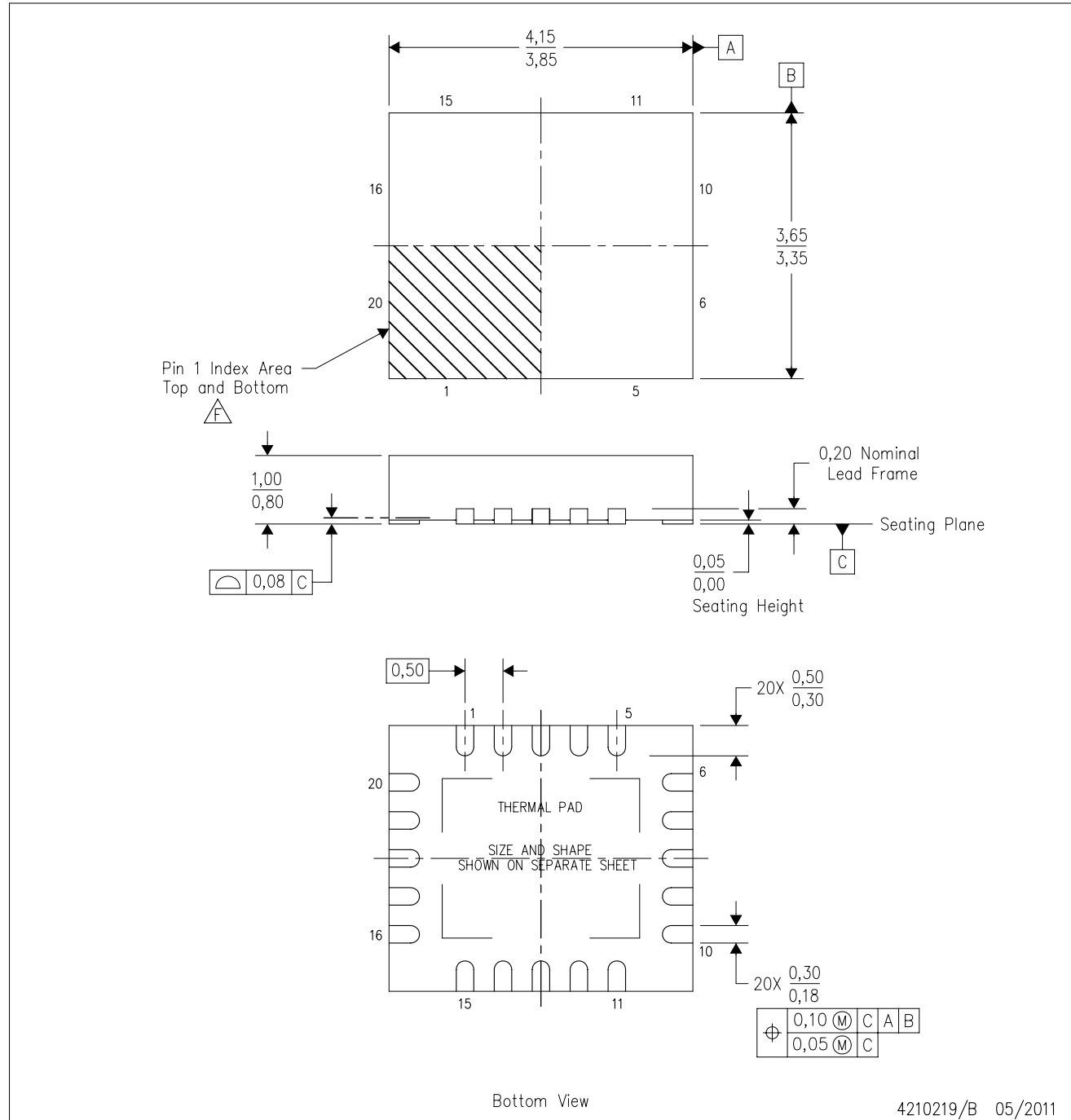
TUBE


*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
DPA02257RGBR	RGB	VQFN	20	3000	381.5	5	2250	0
TPS53317RGBR	RGB	VQFN	20	3000	381.5	5	2250	0
TPS53317RGBR.A	RGB	VQFN	20	3000	381.5	5	2250	0

RGB (R-PVQFN-N20)

PLASTIC QUAD FLATPACK NO-LEAD



4210219/B 05/2011

- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
 - B. This drawing is subject to change without notice.
 - C. QFN (Quad Flatpack No-Lead) package configuration.
 - D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
 - E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
 - F. Pin 1 identifiers are located on both top and bottom of the package and within the zone indicated. The Pin 1 identifiers are either a molded, marked, or metal feature.

THERMAL PAD MECHANICAL DATA

RGB (R-PVQFN-N20)

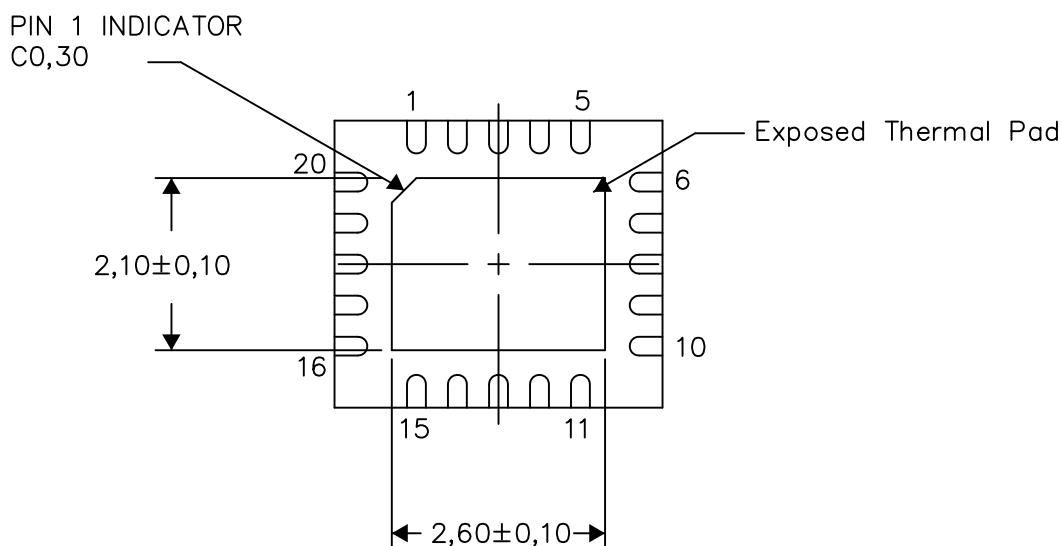
PLASTIC QUAD FLATPACK NO-LEAD

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



Bottom View

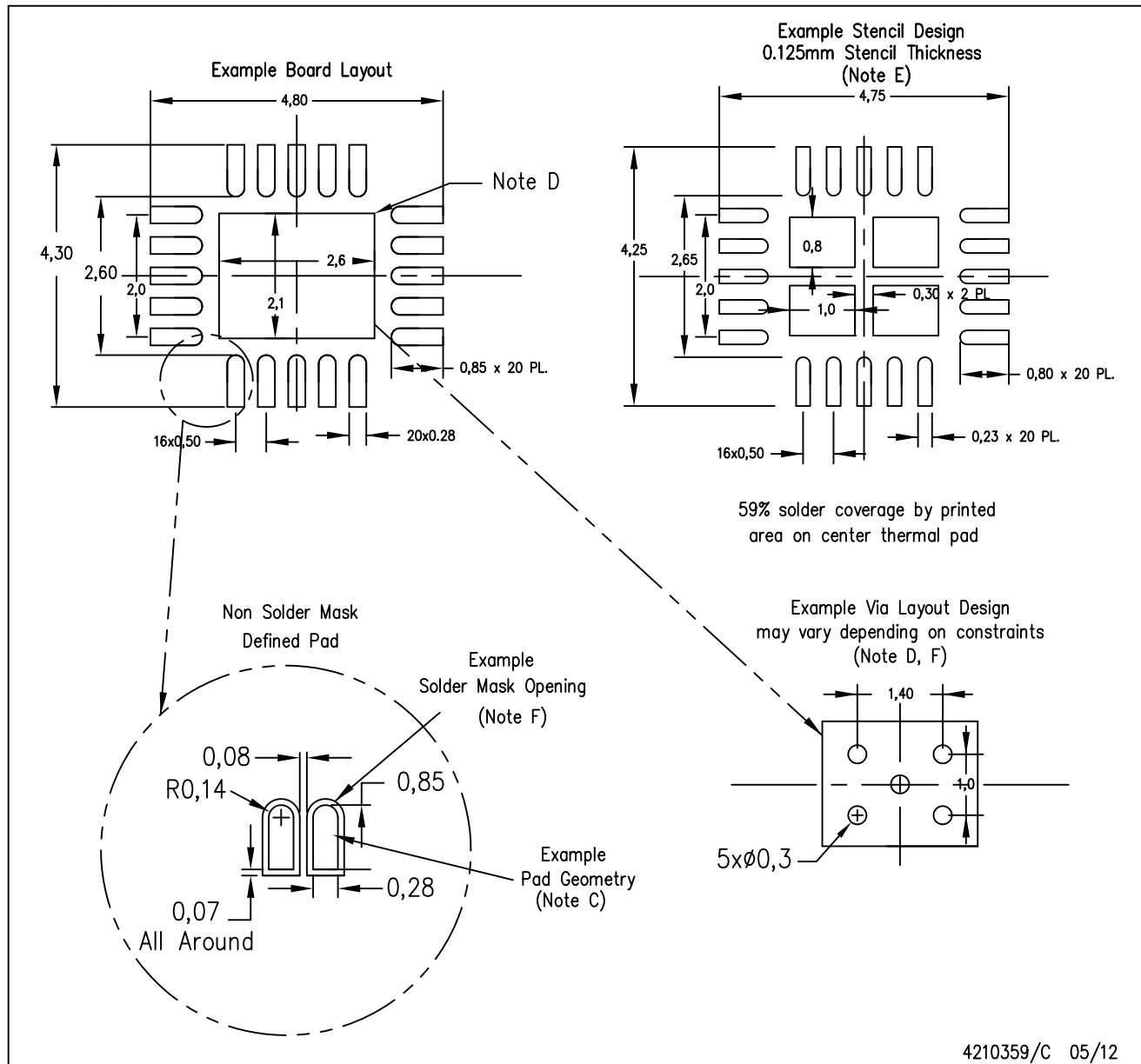
Exposed Thermal Pad Dimensions

4210242/C 05/12

NOTE: All linear dimensions are in millimeters

RGB (R-PVQFN-N20)

PLASTIC QUAD FLATPACK NO-LEAD



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Publication IPC-7351 is recommended for alternate designs.
 - D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <<http://www.ti.com>>.
 - E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
 - F. Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.

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