







**TPS61377** SLVSH38 - NOVEMBER 2023

# TPS61377 23-V<sub>IN</sub>, 25-V<sub>OUT</sub>, 6-A, Synchronous Boost Converter with Programmable Peak Current Limit

### 1 Features

Wide input voltage and output voltage range

 Input voltage range: 2.9 V to 23 V Output voltage range: 4.5 V to 25 V

Programmable peak current limit from 1.5 A to 6 A

Switching frequency

 TPS61377: 650 kHz - TPS613771: 1.2 MHz

High efficiency and power capability

6 A peak switching current limit

- Low-side FET: 50 mΩ, High-side FET: 40 mΩ

- Up to 95.3% efficiency at  $V_{IN} = 9 \text{ V}$ ,  $V_{OUT} = 16$ V, and  $I_{OLIT} = 2.0 A$ 

- Up to 96.0% efficiency at  $V_{IN}$  = 12 V,  $V_{OUT}$  = 24 V, and  $I_{OUT} = 1.5 A$ 

Extend the system operating time

Typical 70 µA quiescent current

Maximum 1.25 µA shutdown current

- Selectable auto PFM and forced PWM mode

Safety and robust operation features

Output overvoltage protection

Cycle-by-cycle overcurrent protection

Thermal shutdown

Precise EN/UVLO threshold

External loop compensation

2.5-mm × 2.0-mm HotRod™ Lite VQFN package

# 2 Applications

- 3.3  $V_{\text{IN}},\,5\,V_{\text{IN}}$  to 12  $V_{\text{OUT}},\,24\,\,V_{\text{OUT}}$  power conversion
- Industrial power systems
- **Appliances**

# 3 Description

The TPS61377 is a high-voltage synchronous boost converter with a  $50\text{-m}\Omega$  low-side power switch and a 40-mΩ high-side rectifier switch to provide a high efficiency and small size solution. The TPS61377 has a wide input voltage range of 2.9 V to 23 V and the output voltage covers up to 25 V with 6-A switching current capability.

The TPS61377 uses an adaptive constant off-time peak current control topology to regulate the output voltage. Under moderate to heavy load condition, the TPS61377 operates in pulse width modulation (PWM) mode. At light load, the device has two operating modes that can be selected via the MODE pin. One is pulse frequency modulation (PFM) mode to improve light-load efficiency, and the other is forced PWM mode to avoid audible noise and other application problems caused by low switching frequency.

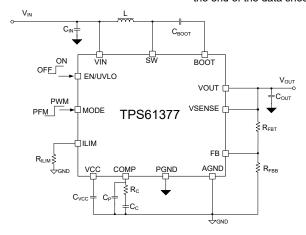
The TPS61377 implements a soft-start function and a programmable peak switching current limit function. The TPS61377 also provides output overvoltage protection, cycle-by-cycle overcurrent protection, and thermal shutdown protection.

The TPS61377 offers a very small solution size with a 2.5-mm × 2.0-mm HotRod™ Lite VQFN package.

#### **Device Information**

PART NUMBER	PACKAGE <sup>(1)</sup>	BODY SIZE (NOM)		
TPS61377	VQFN (13)	2.5 mm × 2.0 mm		
TPS613771	VQFN (13)	2.5 mm × 2.0 mm		

For all available packages, see the orderable addendum at the end of the data sheet.



**Typical Application Circuit** 



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# **4 Device Comparison Table**

PART NUMBER	FREQUENCY
TPS61377	650 kHz
TPS613771	1.2 MHz



# **5 Pin Configuration and Functions**

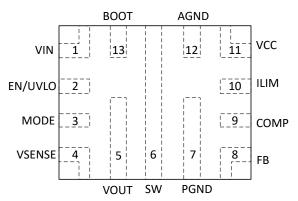


Figure 5-1. 13-Pin RYH VQFN Package (Top View)

**Table 5-1. Pin Functions** 

PII	N	I/O	DESCRIPTION	
NAME	NUMBER	1/0	DESCRIPTION	
VIN	1	I	IC power supply input	
EN/UVLO	2	I	Enable logic input and programmable input voltage undervoltage lockout (UVLO) input. Logic high level enables the device. Logic low level disables the device and turns it into shutdown mode. The converter start-up and shutdown levels can be programmed by connecting this pin to the supply voltage through a resistor divider. This pin must not be left floating and must be terminated.	
MODE	3	I	Operating mode selection pin for the device in light load condition. When this pin is logic the device operates in auto PFM mode. When this pin is logic high, the device operates forced PWM mode.	
VSENSE	4	I	Output voltage sense	
VOUT	5	PWR	Boost converter output	
SW	6	PWR	The switching node pin of the converter. It is connected to the drain of the internal low-side power MOSFET and the source of the internal high-side power MOSFET.	
PGND	7	PWR	Power ground of the IC	
FB	8	I	Output voltage feedback pin. Connect to the center tap of a resistor divider to program the output voltage.	
COMP	9	0	Output of the internal error amplifier. Connect the loop compensation network between this pin and the AGND pin.	
ILIM	10	1	Programmable switch peak current limit. An external resistor must be connected between this pin and the AGND pin.	
VCC	11	0	Output of the internal regulator. A ceramic capacitor of more than 1 $\mu F$ is required between this pin and AGND.	
AGND	12	PWR	Analog ground of the IC	
воот	13	0	Power supply for high side MOSFET gate driver. A ceramic capacitor of 0.47 $\mu F$ to 1 $\mu F$ must be connected between this pin and the SW pin.	



# **6 Specifications**

# 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

		MIN	MAX	UNIT
Voltage range at terminals <sup>(2)</sup>	VIN, EN/UVLO	-0.3	25	V
	SW, VOUT, VSENSE	-0.3	30	V
	BOOT	-0.3	SW + 6	V
	MODE, FB, ILIM, VCC, COMP	-0.3	6	V
T <sub>J</sub> <sup>(3)</sup>	Operating junction temperature	-40	150	°C
T <sub>stg</sub>	Storage temperature	-65	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
- (2) All voltage values are with respect to network ground terminal.
- (3) High junction temperatures degrade operating lifetime. Operating lifetime is de-rated for junction temperatures greater than 125°C.

# 6.2 ESD Ratings

			VALUE	UNIT
V (1)	V <sub>(ESD)</sub> (1) Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(2)</sup>	±2000	V
V <sub>(ESD)</sub> (1)	Liectiostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(3)</sup>	±750	'

- (1) Electrostatic discharge (ESD) to measure device sensitivity and immunity to damage caused by assembly line electrostatic discharges into the device.
- (2) Level listed above is the passing level per ANSI, ESDA, and JEDEC JS-001. JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 500-V HBM is possible with the necessary precautions
- (3) Level listed above is the passing level per EIA-JEDEC JESD22-C101. JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 250-V CDM is possible with the necessary precautions.

#### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V <sub>IN</sub>	Input voltage	2.9		23	V
V <sub>OUT</sub>	Output voltage	4.5		25	V
L	Inductance, effective value	2.2	4.7	10	μH
Cı	Input capacitance, effective value		10		μF
Co	Output capacitance, effective value	10		2000	μF
T <sub>J</sub>	Operating junction temperature	-40		125	°C

## 6.4 Thermal Information

		TPS61377	
	THERMAL METRIC <sup>(1)</sup>	VQFN	UNIT
		13 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	64.9	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	50.4	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	15.4	°C/W
ΨЈТ	Junction-to-top characterization parameter	1.3	°C/W
ΨЈВ	Junction-to-board characterization parameter	15.1	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

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Product Folder Links: TPS61377



# **6.5 Electrical Characteristics**

 $T_{J} = -40$  to 125°C, L = 4.7  $\mu$ H,  $V_{IN} = 5$  V and  $V_{OUT} = 12$  V. Typical values are at  $T_{J} = 25$ °C, (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER SU	PPLY					
/ <sub>IN</sub>	Input voltage range		2.9		23	V
/IN_UVLO		V <sub>IN</sub> rising		2.8	2.9	V
/IN_UVLO	VIN under voltage lockout threshold	V <sub>IN</sub> falling		2.6	2.7	V
IN HYS	VIN UVLO hysteresis	-		200		mV
 Q	Quiescent current into V <sub>OUT</sub> pin	IC enabled, no load, no switching V <sub>IN</sub> =2.9V to 5.25V, V <sub>OUT</sub> = 25 V, V <sub>FB</sub> = V <sub>REF</sub> + 0.1 V		70	100	μA
Q	Quiescent current into V <sub>OUT</sub> pin	IC enabled, no load, no switching $V_{IN}$ = 5.5 V to 23 V, $V_{OUT}$ = 25 V, $V_{FB}$ = $V_{REF}$ + 0.1 V		2	8	μA
Q	Quiescent current into V <sub>IN</sub> pin	IC enabled, no load, no switching V <sub>IN</sub> =2.9V to 5.25V, V <sub>FB</sub> = V <sub>REF</sub> + 0.1 V		1.5	2	μA
Q	Quiescent current into V <sub>IN</sub> pin	IC enabled, no load, no switching V <sub>IN</sub> = 5.5 V to 23 V, V <sub>FB</sub> = V <sub>REF</sub> + 0.1 V		70	100	μA
CC_UVLO	VCC UVLO threshold	V <sub>CC</sub> rising		2.75		V
/cc_HYS	VCC UVLO hysteresis	V <sub>CC</sub> hysteresis		160		mV
/cc	VCC regulation	I <sub>VCC</sub> = 4 mA, V <sub>OUT</sub> = 12 V		4.80		V
SD	Shutdown current into V <sub>IN</sub> pin	IC disabled, V <sub>IN</sub> = 2.9 V to 23 V, EN = GND			1.25	μA
SW_LKG	Leakage current into SW	IC disabled, VOUT = 0 V, SW = 25 V,T <sub>J</sub> up to 85°C			2	uA
VOUT_LKG	Leakage current into VOUT	IC disabled, VOUT = 25 V, SW = 0 V,TJ up to 85°C			2	μA
B_LKG	Leakage current into FB	IC disabled, T <sub>J</sub> up to 85°C			16	nA
OUTPUT VO	DLTAGE					
OVP	Output over-voltage protection threshold	V <sub>IN</sub> = 3.3 V, V <sub>OUT</sub> rising	26.5	27.5	28.6	V
OVP_HYS	Output over-voltage protection hysteresis	V <sub>IN</sub> = 3.3 V, OVP threshold		0.9		V
OLTAGE F	REFERENCE					
/ <sub>REF</sub>	Reference Voltage at FB pin	T <sub>J</sub> = -40 to 125°C	0.985	1	1.015	V
OWER SW	VITCH					
R <sub>DS(on)</sub>	Low-side MOSFET on resistance	V <sub>CC</sub> = 4.85 V		50		mΩ
R <sub>DS(on)</sub>	High-side MOSFET on resistance	V <sub>CC</sub> = 4.85 V		40		mΩ
URRENT I	LIMIT				I	
_IM_SW	Peak switching current limit FPWM	$R_{LIM} = 14.4 \text{ k}\Omega$	5.0	6.0	7.0	Α
LIM_SW	Peak switching current limit Auto PFM	R <sub>LIM</sub> = 14.4 kΩ	5.0	6.0	7.0	Α
LIM_SW	Peak switching current limit FPWM	R <sub>LIM</sub> = 57.6 kΩ	1.3	1.5	1.7	Α
LIM_SW	Peak switching current limit Auto PFM	R <sub>LIM</sub> = 57.6 kΩ	1.3	1.5	1.7	Α
	FREQUENCY					
sw	TPS61377 Switching frequency	V <sub>IN</sub> =2.9V to 23V, V <sub>OUT</sub> = 4.5V to 25V	500	650	800	kHz
sw	TPS613771 Switching frequency	V <sub>IN</sub> =2.9V to 23V, V <sub>OUT</sub> = 4.5V to 25V	1000	1200	1400	kHz
SS	Soft-start time	, 601 211221		4		ms
OFF min	Minimum off time			120		ns
ON_min	Minimum on time			75		ns
RROR AM						
SINK	COMP pin sink current			20		uA
SOURCE	COMP pin source current			20		uA
CCLPH	COMP pin high clamp voltage			1.78		V
	COMP pin high clamp voltage			0.55		V
CCLPL G <sub>mEA</sub>	Error amplifier trans conductance			240		uS
		T		/40		115



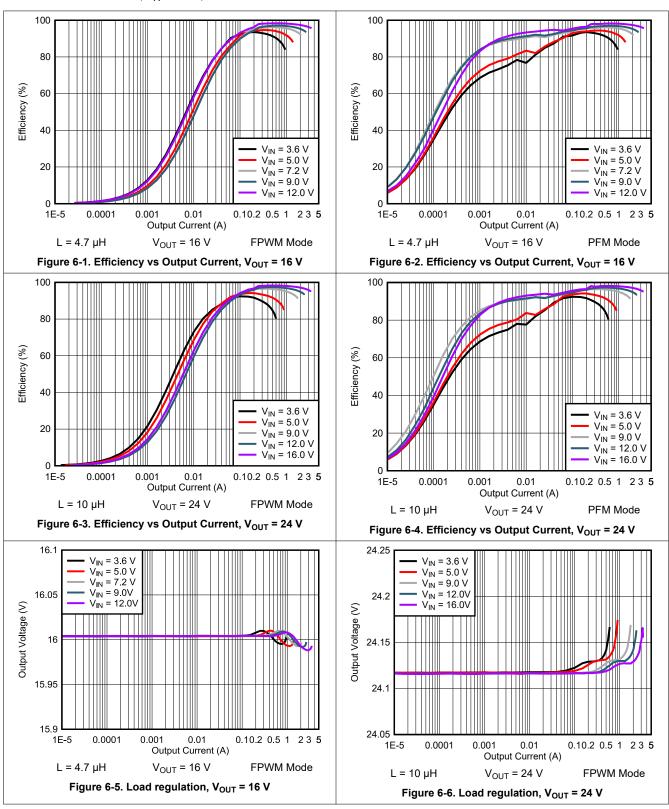
 $T_J$  = -40 to 125°C, L = 4.7  $\mu$ H,  $V_{IN}$  = 5 V and  $V_{OUT}$  = 12 V. Typical values are at  $T_J$  = 25°C, (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>EN_H</sub>	EN Logic high threshold				0.812	V
V <sub>EN_L</sub>	EN Logic low threshold		0.36			V
V <sub>EN_L</sub>	EN threshold hysteresis			120		mV
V <sub>UVLO</sub>	UVLO rising threshold		0.788	0.813	0.835	V
I <sub>UVLO_HYS</sub>	Sourcing current at the EN/UVLO pin		1.75	2	2.25	μΑ
V <sub>MODE_H</sub>	MODE pins Logic high threshold				0.84	V
V <sub>MODE_L</sub>	MODE pins Logic Low threshold		0.36			V
R <sub>DOWN</sub>	MODE pins internal pull down resistor			800		kΩ
THERMAL S	SHUTDOWN					
t <sub>SD_R</sub>	Thermal shutdown rising threshold	T <sub>J</sub> rising		150		°C
t <sub>SD_F</sub>	Thermal shutdown falling threshold	T <sub>J</sub> falling		130		°C



# 6.6 Typical Characteristics

TPS61377 Fsw= 650 kHz, T<sub>A</sub> = 25°C, unless otherwise noted.

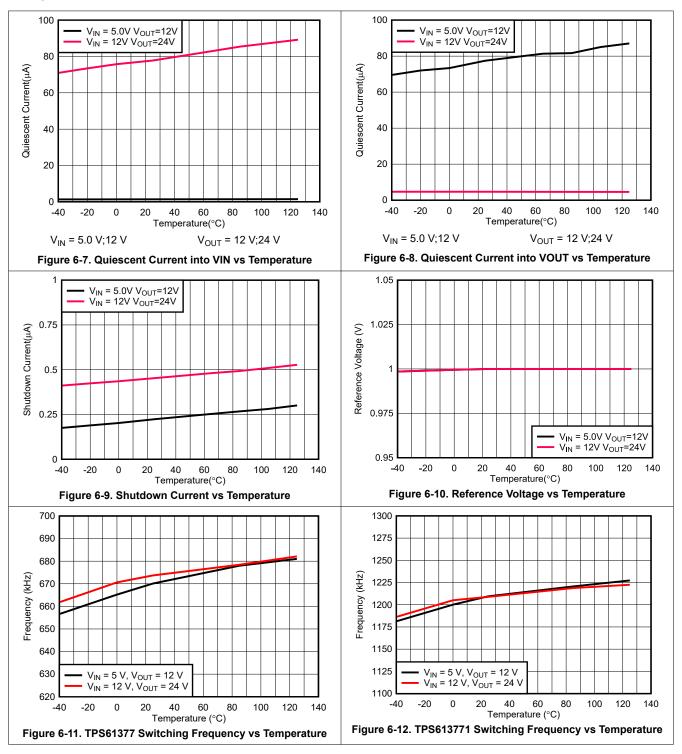


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# 6.6 Typical Characteristics (continued)



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# 7 Detailed Description

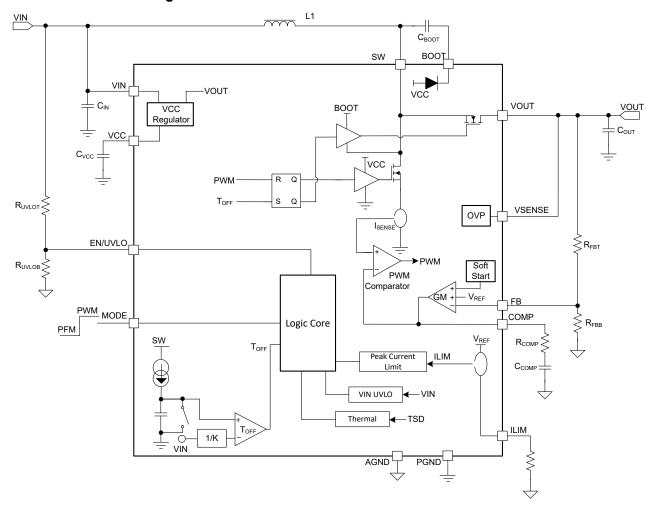
## 7.1 Overview

The TPS61377 is a fully-integrated high voltage synchronous boost converter with a low side 50 m $\Omega$  power switch and a 40 m $\Omega$  high side rectifier switch to provide a high efficiency and small size solution. The TPS61377 has a wide input voltage range of 2.9 V to 23 V, and can delivery up to 25 V output voltage with a peak switching current of typical 6 A. The peak switching current is programmable by a resistor connected between the ILIM pin and GND.

The TPS61377 uses the adaptive constant off-time peak current control topology to regulate the output voltage. Under moderate to heavy load condition, the TPS61377 operates in pulse width modulation (PWM) mode. As with conventional adaptive off-time converters, the device varies the off-time as a function of input and output voltage to maintain a near constant frequency. At light load, the device has two operating modes that can be selected via the MODE pin. When the MODE pin is low, the device operates in pulse frequency modulation (PFM) mode to improve light load efficiency. The off-time is modulated by the feedback loop and is extended as the load becoms lighter. When the MODE pin is high, the device operates in forced PWM mode to avoid audible noise and other application problems caused by low switching frequency. The TPS61377 uses external loop compensation, giving the flexibility to use different inductors and output capacitors.

The TPS61377 implements a soft-start function and provides output overvoltage protection, cycle-by-cycle overcurrent protection, and thermal shutdown protection.

## 7.2 Functional Block Diagram





## 7.3 Feature Description

# 7.3.1 VCC Power Supply

The internal LDO of TPS61377 outputs a regulated voltage of 4.8 V with 10-mA output current capability. When the input voltage at the VIN pin is below 5.25 V, the internal LDO is powered by the VOUT pin, when the input voltage at the VIN pin is above 5.5 V, the internal LDO is powered by the VIN pin. A ceramic capacitor is connected between the VCC pin and AGND pin to stabilize the VCC voltage and also decouples the noise on the VCC pin. The value of this ceramic capacitor should be above 1  $\mu$ F. A ceramic capacitor with an X7R or X5R grade dielectric with a voltage rating higher than 10 V is recommended.

## 7.3.2 Enable and Programmable UVLO

The TPS61377 has a dual function enable and UVLO circuit. When the input voltage at the VIN pin is above the input UVLO rising threshold of 2.8 V typical and the EN/UVLO pin is pulled above the rising threshold, the TPS61377 is enabled and starts switching. The EN/UVLO pin has an accurate UVLO voltage threshold to support programmable input under-voltage lockout with hysteresis. A hysteresis current I<sub>UVLO\_HYS</sub> is sourced out of the EN/UVLO pin to provide hysteresis that prevents on/off chattering in the presence of input voltage noise. By using resistor divider as shown in Figure 7-1, the turn on threshold can be calculated by using Equation 1.

$$V_{IN(UVLO\_ON)} = V_{UVLO} \times \left(1 + \frac{R1}{R2}\right) \tag{1}$$

where

V<sub>UVLO</sub> is the UVLO threshold of 0.813 V at the EN/UVLO pin

The hysteresis between the UVLO turn on threshold and turn off threshold is set by the upper resistor in the EN/UVLO resistor divider and is given by Equation 2

$$\Delta V_{IN(UVLO)} = I_{UVLO\ HYS} \times R1 \tag{2}$$

where

I<sub>UVLO</sub> is the sourcing current from the EN/UVLO pin when the voltage at the EN/UVLO pin is above V<sub>UVLO</sub>

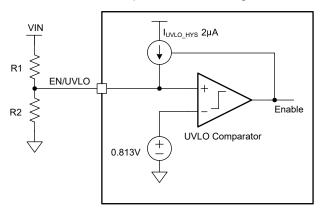


Figure 7-1. Programmable UVLO with Resistor Divider at EN/UVLO Pin

#### 7.3.3 Soft Start

The TPS61377 has a 4 ms soft start function to prevent high inrush current during start-up. When the EN/UVLO pin is pulled high, the internal soft-start capacitor is charged with a constant current. During this time, the soft-start capacitor voltage is compared with the internal reference (1.0 V). The lower one is fed into the internal positive input of the error amplifier. The output of the error amplifier (which determines the inductor peak current value) ramps up slowly as the soft-start capacitor voltage goes up. The soft-start phase is completed after the soft-start capacitor voltage exceeds the internal reference, which takes 4 ms from 0 V to 1.0 V. When the EN/UVLO pin is pulled low, the voltage of the soft-start capacitor is discharged to ground.

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# 7.3.4 Switching Frequency

The TPS61377 uses adaptive constant off-time peak current control topology to regulate the output voltage. Under moderate to heavy load conditions, the TPS61377 operates in pulse width modulation (PWM) mode. The switching frequency in PWM mode is 650 kHz (1.2 MHz for TPS613771). At light load, the converter can either operate in PFM mode or in forced PWM mode according to the mode selected.

#### 7.3.5 Programmable Inductor Peak Current Limit

The TPS61377 adopts a cycle-by-cycle peak switching current limit function internally. The low-side switch is turned off as soon as the switch peak current triggers the limit threshold. The peak switching current limit can be set by a resistor from the ILIM pin to ground. The relationship between the peak current limit and the resistor is shown in Equation 3.

$$I_{PEAK} = 0.54V \times \frac{160k}{R_{LIM}} \tag{3}$$

where

- R<sub>LIM</sub> is the resistance between the ILIM pin and the AGND pin.
- I<sub>PEAK</sub> is the typical peak switching current limit.

For instance, the peak switching current is 5.4 A typical if the  $R_{LIM}$  is 16 k $\Omega$ . ILIM pin cannot be left floating or connected to VCC.

#### 7.3.6 Shut Down

When the input voltage is below the UVLO threshold or the EN/UVLO pin is pulled low, the TPS61377 is in shutdown mode and all the functions are disabled.

## 7.3.7 Overvoltage Protection

If the output voltage at the VSENSE pin is detected above 27.5 V (typ), the TPS61377 stops switching immediately until the voltage at the VSENSE pin drops the hysteresis value lower than the output overvoltage protection threshold. This function prevents overvoltage on the output and secures the circuits connected to the output from excessive overvoltage.

### 7.3.8 Thermal Shutdown

A thermal shutdown is implemented to prevent damages due to excessive heat and power dissipation. Typically, the thermal shutdown happens at a junction temperature of 150°C. When the thermal shutdown is triggered, the device stops switching until the junction temperature falls below typically 130°C, then the device starts switching again.

#### 7.4 Device Functional Modes

#### 7.4.1 Operation

The TPS61377 operates at a quasi-constant frequency pulse width modulation (PWM) in moderate-to-heavy load condition. Based on the VIN to VOUT ratio, a circuit predicts the required off-time of the switching cycle. At the beginning of each switching cycle, the low-side N-MOSFET switch is turned on, and the inductor current ramps up to a peak current that is determined by the output of the internal error amplifier. After the peak current is reached, the current comparator trips. It turns off the low-side N-MOSFET switch and the inductor current goes through the body diode of the high-side N-MOSFET in a dead-time duration. After the dead-time duration, the high-side N-MOSFET switch is turned on. Since the output voltage is higher than the input voltage, the inductor current decreases. The high-side switch is not turned off until the off-time is reached. After a short dead-time duration, the low-side switch turns on again and the switching cycle is repeated. At light load, the TPS61377 implements two operating modes, PFM mode and forced PWM mode, to meet different application requirements. The operating mode is set by the status of the MODE pin. When the MODE pin is logic high, the device operates in forced PWM mode. When the MODE pin is logic low, the device operates in PFM mode.



#### 7.4.2 Forced PWM Mode

In forced PWM mode, the TPS61377 keeps the switching frequency unchanged at light load. When the load current decreases, the output of the internal error amplifier decreases as well to keep the inductor peak current down, delivering less power from input to output. When the output current further reduces, the current through the inductor decreases to zero during the off-time. The high-side N-MOSFET is not turned off even if the current through the MOSFET is zero. Thus, the inductor current changes its direction after it runs to zero. The power flow is from output side to input side. The efficiency is low in this mode. But with the fixed switching frequency, there is no audible noise and other problems which might be caused by low switching frequency at light load.

#### 7.4.3 Auto PFM Mode

In auto PFM mode, the TPS61377 provides a seamless transition from PWM to PFM operation with smooth on-time/off-time (SOO) mode and enables automatic pulse-skipping mode that provides excellent efficiency over a wide load range. As load current decreasing or VIN rising, the output of the internal error amplifier decreases to lower the inductor peak current, delivering less power to the load. When the output of the error amplifier goes down and reaches a threshold of about 500-mA peak current, the output of the error amplifier is clamped at this value and does not decrease any more, the TPS61377 extends its off-time of the switching period to deliver less energy to the output and regulate the output voltage to the target.

With SOO mode, the TPS61377 keeps the output voltage equal to the setting voltage in PFM mode. In addition, the output voltage ripple is much smaller at light load due to low peak current. Refer to Figure 7-2.

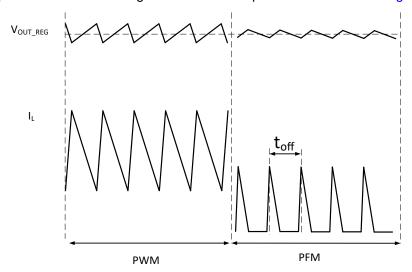


Figure 7-2. Auto PFM Mode Diagram



# 8 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

## 8.1 Application Information

The TPS61377 is designed for output voltages up to 25 V with a peak switching current limit of 6 A typical. The TPS61377 operates at a quasi-constant frequency pulse width modulation (PWM) under moderate to heavy load conditions. At light load, the converter can operate in either PFM mode or forced PWM mode, depending on the mode selected. The PFM mode provides high efficiency over the entire load range, while the PWM mode can avoid the acoustic noise as the switching frequency is fixed. The converter uses the adaptive constant off-time peak current control scheme, which provides excellent transient line and load response with minimal output capacitance. The TPS61377 can operate with different inductor and output capacitor combinations by adjusting the external loop compensation.

# 8.2 Typical Application

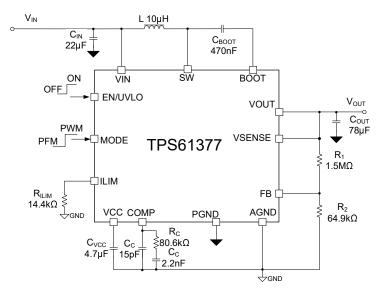


Figure 8-1. TPS61377 9-V to 16-V V<sub>IN</sub> ;24V V<sub>OUT</sub> 1.5-A Output Converter

## 8.2.1 Design Requirements

**Table 8-1. Design Parameters** 

DESIGN PARAMETERS	EXAMPLE VALUES
Input voltage range	9 V to 16 V
Output voltage	24 V
Output voltage ripple	100 mV peak to peak
Output current rating	1.5 A
Operating frequency	650 kHz



## 8.2.2 Detailed Design Procedure

# 8.2.2.1 Setting Output Voltage

The output voltage is set by an external resistor divider (R1, R2 in the Figure 8-1 circuit diagram). For the best accuracy, R2 should be smaller than 500 k $\Omega$  to ensure the current flowing through R2 is at least 100 times larger than the FB pin leakage current. Changing R2 to lower value increases the immunity against noise injection. Changing R2 to higher values reduces the quiescent current to achieve higher efficiency at light load.

The value of R1 is then calculated as:

$$R_1 = \frac{(V_{OUT} - V_{REF}) \times R_2}{V_{REF}}$$
(4)

#### 8.2.2.2 Inductor Selection

The selection of the inductor affects the steady state of the power supply operation, transient behavior, loop stability, and boost converter efficiency, the inductor is the most important component in switching power regulator design. The three most important specifications to the performance of the inductor are the inductance value, DC resistance, and saturation current.

The TPS61377 is designed to work with inductor values between 2.2  $\mu$ H and 10  $\mu$ H. A 2.2  $\mu$ H inductor is typically available in a smaller or lower-profile package, while a 10- $\mu$ H inductor produces lower inductor current ripple. If the boost output current is limited by the peak current protection of the IC, using a inductor with bigger inductance can maximize the output current capability of the converter.

Inductance values can be ±20% or even ±30% of the value at 0 A bias. When the inductor current approaches saturation level, its inductance can decrease 20% to 35% from the value at 0-A bias current, depending on how the inductor vendor defines saturation current. When selecting an inductor, make sure its rated current, especially the saturation current, is larger than boost converter peak current under all operating conditions.

Normally, it is advisable that the inductor peak-to-peak current is less than 40% of the average inductor current at maximum output current. Follow Equation 5 to Equation 7 to calculate the average, peak and ripple current of the inductor. To calculate the current in the worst case, use the minimum input voltage, maximum output voltage, and maximum load current of the application. To leave enough design margin, TI recommends using the minimum switching frequency, the inductance with -30% tolerance, and a low power conversion efficiency for the calculation.

In a boost regulator, calculate the inductor DC current as in Equation 5.

$$I_{DC} = \frac{V_{OUT} \times I_{OUT}}{V_{IN} \times \eta}$$
 (5)

where

- V<sub>OUT</sub> is the output voltage of the boost regulator.
- I<sub>OUT</sub> is the output current of the boost regulator.
- V<sub>IN</sub> is the input voltage of the boost regulator.
- n is the power conversion efficiency.

Calculate the inductor current peak-to-peak ripple as in Equation 6.

$$I_{PP} = \frac{1}{L \times (\frac{1}{V_{OUT} - V_{IN}} + \frac{1}{V_{IN}}) \times f_{SW}}$$
(6)

where

- I<sub>PP</sub> is the inductor peak-to-peak ripple.
- · L is the inductor value.

- $f_{SW}$  is the switching frequency.
- V<sub>OUT</sub> is the output voltage.
- V<sub>IN</sub> is the input voltage.

Therefore, the peak current, I<sub>Lpeak</sub>, seen by the inductor is calculated with Equation 7.

$$I_{Lpeak} = I_{DC} + \frac{I_{PP}}{2} \tag{7}$$

It is important that the peak current does not exceed the inductor saturation current.

For a given physical inductor size, increasing inductance usually results in an inductor with lower saturation current. The total losses of the coil consists of the DC resistance (DCR) loss and the following frequencydependent loss:

- The losses in the core material (magnetic hysteresis loss, especially at high switching frequencies)
- Additional losses in the conductor from the skin effect (current displacement at high frequencies)
- Magnetic field losses of the neighboring windings (proximity effect)

For a certain inductor, the larger current ripple (smaller inductor) generates the higher DC and also the frequency-dependent loss. Usually, a data sheet of an inductor does not provide the core loss information. If needed, consult the inductor vendor for detailed information. An inductor with lower DCR is basically recommended for higher efficiency. However, it is usually a tradeoff between the loss and foot print. The table below lists some recommended inductors.

PART NUMBER	L (µH)	DCR TYP (mΩ)	SATURATION CURRENT (A)	SIZE (L × W × H mm)	VENDOR <sup>(1)</sup>		
XGL5050-222ME	2.2	6.8	10.7	5.28 x 5.48 x 5.1	Coilcraft		
XGL5050-472ME	4.7	13.9	7.0	5.28 x 5.48 x 5.1	Coilcraft		
XGL6060-103ME	10	18.5	7.3	6.51 x 6.71 x 6.1	Coilcraft		
XGL4020-222ME	2.2	19.5	6.2	4.0 x 4.0 x 2.1	Coilcraft		
XGL4020-472ME	4.7	43	4.1	4.0 x 4.0 x 2.1	Coilcraft		
XGL4020-822ME	8.2	71	3.2	4.0 x 4.0 x 2.1	Coilcraft		

Table 8-2. Recommended Inductors

(1) See the Third-party Products Disclaimer.

### 8.2.2.3 Bootstrap Capacitor Selection

The bootstrap capacitor between the BOOT and SW pin supplies the gate current to charge the high-side FET device gate during the turn on of each cycle. The gate current also supplies charge for the bootstrap capacitor. The recommended value of the bootstrap capacitor is 0.47 μF to 1 μF. C<sub>BOOT</sub> must be a good quality, low-ESR ceramic capacitor located at the pins of the device to minimize potentially damaging voltage transients caused by trace inductance. A value of 0.47 µF was selected for this design example.

#### 8.2.2.4 Input Capacitor Selection

Multilayer ceramic capacitors are an excellent choice for the input decoupling of the step-up converter since they have extremely low ESR and are available in small footprints. Input capacitors must be located as close as possible to the device. While a 22-µF input capacitor or equivalent is sufficient for the most applications, larger values can be used to reduce input current ripple.

Take care when using only ceramic input capacitors. When a ceramic capacitor is used at the input and the power is being supplied through long wires, such as from a wall adapter, a load step at the output can induce ringing at the VIN pin. This ringing can couple to the output and be mistaken as loop instability or can even damage the device. Additional "bulk" capacitor (electrolytic or tantalum) in this circumstance, must be placed between C<sub>IN</sub> and the power source lead to reduce ringing that can occur between the inductance of the power source leads and C<sub>IN</sub>.



# 8.2.2.5 Output Capacitor Selection

The output capacitor is mainly selected to meet the requirements at load transient or steady state. The loop is compensated for the output capacitor selected. The output ripple voltage is related to the equivalent series resistance (ESR) of the capacitor and its capacitance. Assuming a capacitor with zero ESR, the minimum capacitance needed for a given ripple can be calculated by Equation 8:

$$C_{OUT} = \frac{I_{OUT} \times (V_{OUT} - V_{IN})}{f_{SW} \times \Delta V \times V_{OUT}}$$
(8)

#### where

- C<sub>OUT</sub> is the output capacitor
- I<sub>OUT</sub> is the output current
- V<sub>OUT</sub> is the output voltage
- V<sub>IN</sub> is the input voltage
- Δ<sub>V</sub> is the output voltage ripple required
- f<sub>SW</sub> is the switching frequency

The additional output ripple component caused by ESR is calculated by Equation 9:

$$\Delta V_{ESR} = I_{Lpeak} \times R_{ESR} \tag{9}$$

#### where

- ΔV<sub>ESR</sub> is the output voltage ripple caused by ESR
- · R<sub>ESR</sub> is the resistor in series with the output capacitor

For the ceramic capacitor, the ESR ripple can be neglected. However, for the tantalum or electrolytic capacitors, it must be considered if used.

The minimum ceramic output capacitance needed to meet a load transient requirement can be estimated using Equation 10:

$$C_{OUT} = \frac{\Delta I_{STEP}}{2\pi \times f_{BW} \times \Delta V_{TRAN}}$$
(10)

#### where

- ΔI<sub>STEP</sub> is the transient load current step
- ΔV<sub>TRAN</sub> is the allowed voltage dip for the load current step
- $f_{\rm BW}$  is the control loop bandwidth (that is, the frequency where the control loop gain crosses zero)

Take care when evaluating the derating of a ceramic capacitor under the DC bias. Ceramic capacitors can derate by as much as 70% of the capacitance at the respective rated voltage. Therefore, enough margins on the voltage rating must be considered to ensure adequate capacitance at the required output voltage.

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### 8.2.2.6 Loop Stability

The TPS61377 requires external compensation, which allows the loop response to be optimized for each application. The COMP pin is the output of the internal error amplifier. An external compensation network, comprised of resistor  $R_{\rm C}$ , and ceramic capacitors  $C_{\rm C}$  and  $C_{\rm P}$ , is connected to the COMP pin.

The power stage small signal loop response of constant off-time (COT) with peak current control can be modeled by Equation 11.

$$G_{PS}(S) = K_{COMP} \times \frac{R_O \times (1-D)}{2} \times \frac{\left(1 + \frac{S}{2\pi f_{ESRZ}}\right) \times \left(1 - \frac{S}{2\pi f_{RHPZ}}\right)}{1 + \frac{S}{2\pi f_P}}$$

$$(11)$$

where

- D is the switching duty cycle.
- R<sub>O</sub> is the output load resistance.
- K<sub>COMP</sub> is power stage trans-conductance (inductor peak current / comp voltage), which is 6.5 A/V.

$$f_{\mathsf{P}} = \frac{2}{2\pi \times \mathsf{R}_{\mathsf{O}} \times \mathsf{C}_{\mathsf{O}}} \tag{12}$$

where

C<sub>O</sub> is effective output capacitance.

$$f_{\mathsf{ESRZ}} = \frac{1}{2\pi \times \mathsf{R}_{\mathsf{ESR}} \times \mathsf{C}_{\mathsf{O}}} \tag{13}$$

where

R<sub>ESR</sub> is the equivalent series resistance of the output capacitor.

$$f_{\text{RHPZ}} = \frac{R_{\text{O}} \times (1 - D)^2}{2\pi \times L} \tag{14}$$

The COMP pin is the output of the internal transconductance amplifier. Equation 15 shows the small signal transfer function of compensation network.

$$Gc(S) = \frac{G_{EA} \times R_{EA} \times V_{REF}}{V_{OUT}} \times \frac{\left(1 + \frac{S}{2 \times \pi \times f_{COMZ}}\right)}{\left(1 + \frac{S}{2 \times \pi \times f_{COMP1}}\right)\left(1 + \frac{S}{2 \times \pi \times f_{COMP2}}\right)}$$
(15)

where

- G<sub>FA</sub> is the transconductance of the amplifier, which is 240 uS.
- $R_{EA}$  is the output resistance of the amplifier, which is 100 M $\Omega$ .
- V<sub>REF</sub> is the reference voltage at the FB pin.
- V<sub>OUT</sub> is the output voltage.
- $f_{\text{COMP1}}$ ,  $f_{\text{COMP2}}$  are the frequency of the poles of the compensation network.
- f<sub>COMZ</sub> is the zero's frequency of the compensation network.



The next step is to choose the loop crossover frequency,  $f_{\rm C}$ . The higher frequency that the loop gain stays above zero before crossing over, the faster the loop response is. It is generally accepted that the loop gain cross over no higher than the lower of either 1/10 of the switching frequency,  $f_{\rm SW}$ , or 1/5 of the RHPZ frequency,  $f_{\rm RHPZ}$ .

Then set the value of  $R_C$ ,  $C_C$ , and  $C_P$  (in Figure 8-1) by following these equations.

$$R_{C} = \frac{2\pi \times V_{OUT} \times C_{O} \times f_{C}}{(1-D) \times V_{REF} \times G_{EA} \times K_{COMP}}$$
(16)

where

•  $f_{\rm C}$  is the selected crossover frequency.

The value of  $C_C$  can be set by Equation 17.

$$C_{C} = \frac{R_{O} \times C_{O}}{2R_{C}} \tag{17}$$

The value of  $C_P$  can be set by Equation 18.

$$C_{P} = \frac{R_{ESR} \times C_{O}}{R_{C}}$$
(18)

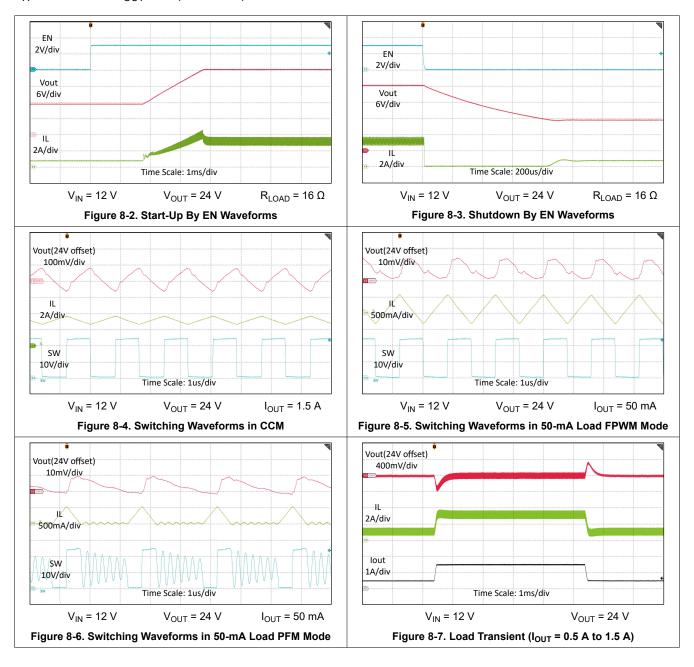
If the calculated value of C<sub>P</sub> is less than 10 pF, it can be left open.

Designing the loop for greater than 45° of phase margin and greater than 10-dB gain margin eliminates output voltage ringing during the line and load transient.



# 8.2.3 Application Curves

 $T_A$  = 25°C, Total  $C_{OUT}$  = 78  $\mu$ F, L = 10  $\mu$ H, EVM-based , unless otherwise noted.

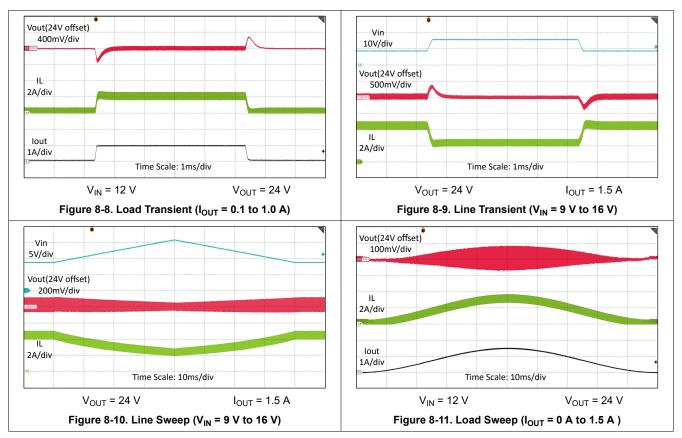


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## 8.2.3 Application Curves (continued)



# 8.3 Power Supply Recommendations

The device is designed to operate from an input voltage supply range between 2.9 V to 23 V. This input supply must be well regulated. If the input supply is located more than a few inches from the converter, additional bulk capacitor can be required in addition to the ceramic bypass capacitors. A typical choice is an electrolytic or tantalum capacitor with a value of 47  $\mu$ F.

#### 8.4 Layout

#### 8.4.1 Layout Guidelines

As for all switching power supplies, especially those running at high switching frequency and high current, layout is an important design step. If the layout is not carefully done, the regulator can suffer from instability and noise problems. To maximize efficiency, switching rise and fall times are very fast. To prevent radiation of high-frequency noise (for example, EMI), proper layout of the high-frequency switching path is essential. Minimize the length and area of all traces connected to the SW pin, and always use a ground plane under the switching regulator to minimize interplane coupling.

The input capacitor needs to be close to the VIN pin and PGND pin in order to reduce the I<sub>input</sub> supply ripple.

The power paths of VOUT, output capacitor and PGND should be as small as possible, in order to reduce parasitic inductance.

The layout should also be done with well consideration of the thermal as this is a high power density device. The SW, VOUT and PGND pins that improves the thermal capabilities of the package should be soldered with the large polygon, using thermal vias underneath the SW pin could improve thermal performance.



# 8.4.2 Layout Example

The bottom layer is a large ground plane connected to the PGND plane and AGND plane on top layer by vias.

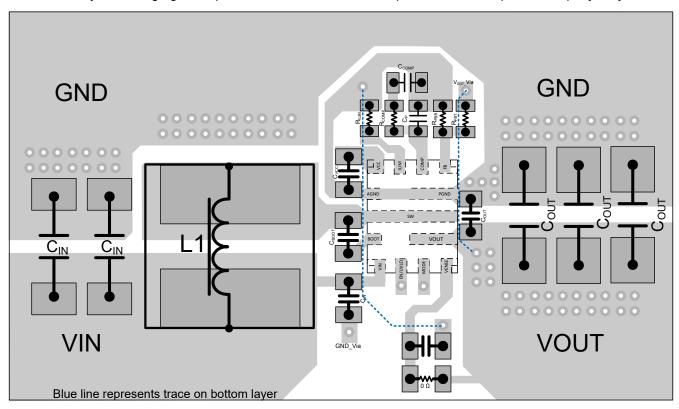


Figure 8-12. Layout Example



#### 8.4.2.1 Thermal Considerations

The maximum IC junction temperature should be restricted to  $125^{\circ}$ C under normal operating conditions. Calculate the maximum allowable dissipation,  $P_{D(max)}$ , and keep the actual power dissipation less than or equal to  $P_{D(max)}$ . The maximum-power-dissipation limit is determined using Equation 19.

$$P_{D(max)} = \frac{125 - T_A}{R_{\theta JA}} \tag{19}$$

#### where

- T<sub>A</sub> is the maximum ambient temperature for the application.
- $R_{\theta JA}$  is the junction-to-ambient thermal resistance given in the *Thermal Information* table.

The TPS61377 comes in a thermally-enhanced VQFN package. The real junction-to-ambient thermal resistance of the package greatly depends on the PCB type, layout, and thermal pad connection. Using thick PCB copper enhances the thermal performance. Using more vias connects the ground plate on the top layer and bottom layer around the IC without solder mask also improves the thermal capability.



# 9 Device and Documentation Support

## 9.1 Device Support

# 9.1.1 Third-Party Products Disclaimer

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### 9.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

# 9.3 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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# 9.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 9.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

#### 10 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

DATE	REVISION	NOTES		
November 2023	*	Initial release.		



# 11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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#### PACKAGING INFORMATION

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/	MSL rating/	Op temp (°C)	Part marking
	(1)	(2)			(3)	Ball material	Peak reflow		(6)
						(4)	(5)		
TPS613771RYHR	Active	Production	VQFN-HR (RYH)   13	3000   LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	3771
TPS613771RYHR.A	Active	Production	VQFN-HR (RYH)   13	3000   LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	3771
TPS61377RYHR	Active	Production	VQFN-HR (RYH)   13	3000   LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	1377
TPS61377RYHR.A	Active	Production	VQFN-HR (RYH)   13	3000   LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	1377

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

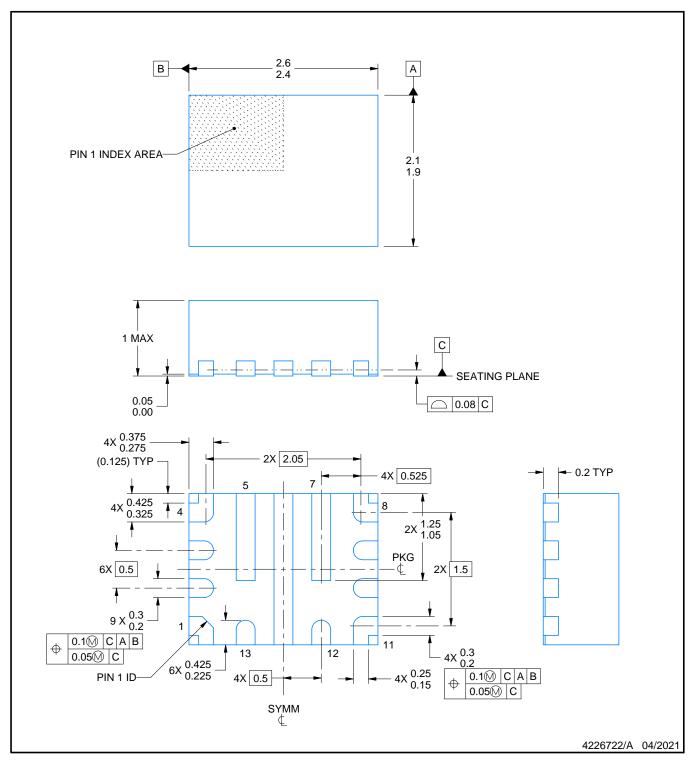
<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.



PLASTIC QUAD FLATPACK - NO LEAD

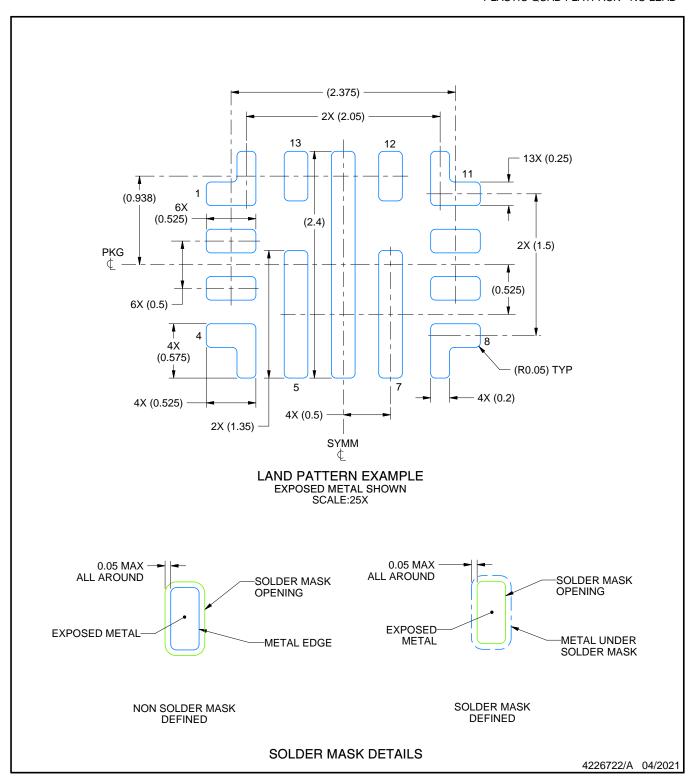


#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.



PLASTIC QUAD FLATPACK - NO LEAD

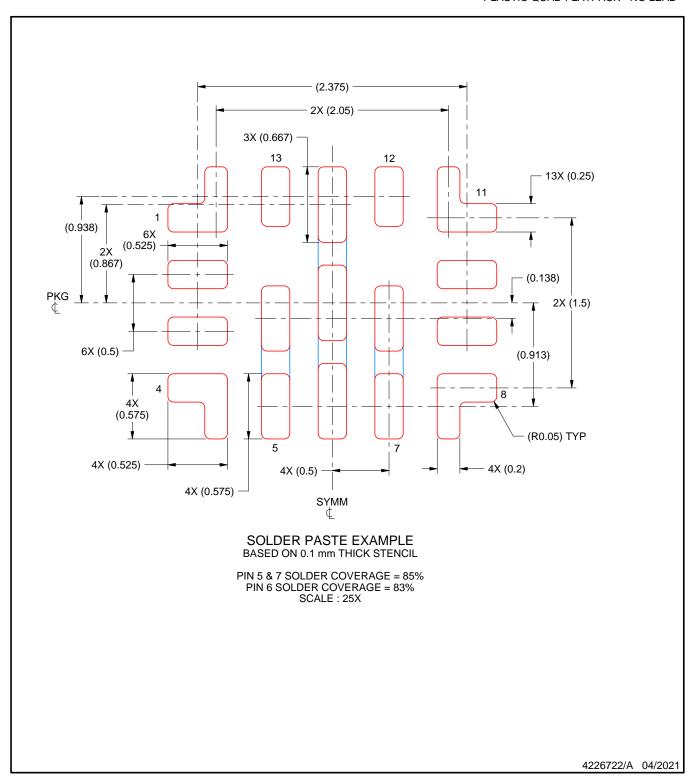


NOTES: (continued)

- 3. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 4. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

5. For alternate stencil design recommendations, see IPC-7525 or board assembly site preference.



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