

# **Frequency Foldback Current Mode PWM Controller**

#### **FEATURES**

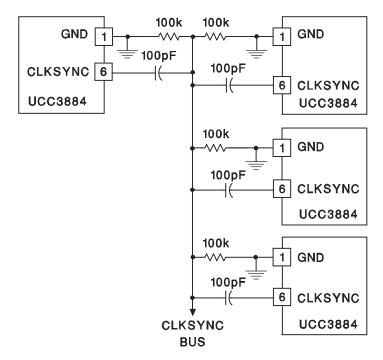
- Frequency Foldback Reduces Operating Frequency Under Fault Conditions
- Accurate Programmable Volt-Second Clamp
- Programmable Maximum Duty Cycle Clamp
- Oscillator Synchronization
- Overcurrent Protection
- Shutdown With Full Soft Start
- Wide Gain Bandwidth Amplifier (GBW > 2.5 MHz)
- Current Mode Operation
- Precision 5-V Reference

#### DESCRIPTION

The UCC3884 is a high performance current mode PWM controller intended for single ended switch mode power supplies. The chip implements a frequency foldback scheme that decreases the oscillator frequency as the output voltage falls below a programmed value. This technique decreases the average output current sourced into a low impedance load which can occur during an output short circuit or overload condition. Excessive short circuit current is more prevalent in high frequency converters where the propagation delay and switch turn-off time forces a minimum attainable duty cycle. An accurate volt-second clamp limits the duty cycle during line or load transient conditions which could otherwise saturate the transformer. The volt-second clamp may also be used with an external overvoltage protection circuit to handle fault conditions such as current sense disconnect or current transformer saturation.

The frequency foldback, volt-second clamp, cycle-by-cycle current limit, and overcurrent shutdown provide a rich set of protection features for use in peak current-mode pulse width modulators.

#### **OSCILLATOR SYNCHRONIZATION**





Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



## **ABSOLUTE MAXIMUM RATINGS**(1)

	VALUE	UNIT
Supply voltage	15	V
Output sink current	1	۸
Output source current	0.5	A
All other pins	6	V
Storage temperature	-65 TO 150	
Junction temperature	-40 TO 150	°C
Lead temperature (soldering, 10 sec)	300	

<sup>(1)</sup> Currents are positive into, negative out of the specified terminal.

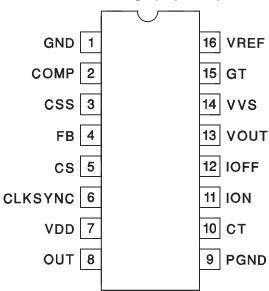
#### ORDERING INFORMATION

т	PACKAGED DEVICES <sup>(1)</sup>				
ıJ	SOP (D)	PDIP(N)			
-40°C to 85°C	UCC2884D (16)	UCC2884N (16)			
0°C to 70°C	UCC3884D (16)	UCC3884N (16)			

<sup>(1)</sup> Both the D and N packages are available taped and reeled (indicated by the TR suffix on the device type e.g., UCC2884DTR)

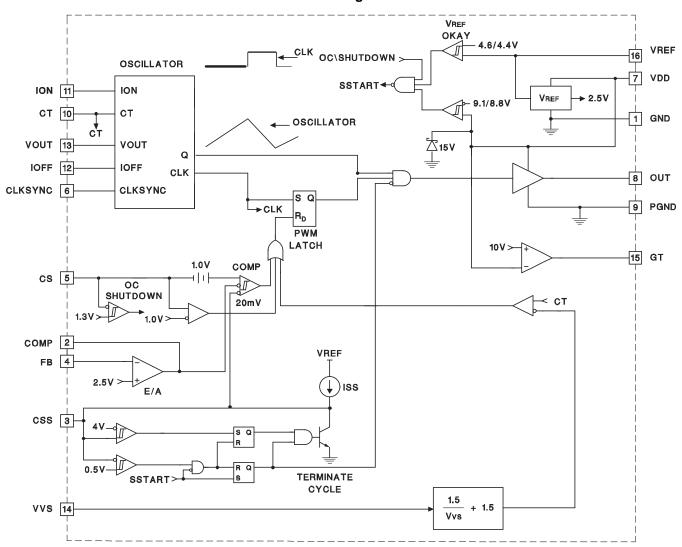
## **CONNECTION DIAGRAMS**

## N or D Package (Top View)





## **Block Diagram**





## **ELECTRICAL CHARACTERISTICS**

Unless otherwise specified, these specifications apply for  $T_A$  = -40°C to 85°C for the UCC2884, and 0°C to 70°C for the UCC3884, CT = 220 pF,  $R_{ON}$  = 53 k $\Omega$ ,  $R_{OFF}$  = 38 k $\Omega$ , VOUT = VREF, VVS = 0 V, CSS = 2.5 nF, VDD = 11 V, Output no load,  $T_A$  =  $T_J$ .

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
5-V Reference				1	
VREF	I <sub>REF</sub> = 0 mA	4.86	5	5.14	٧
Line regulation	VDD = 10 V to 12 V		1	10	>/
Load regulation	0 < I <sub>REF</sub> < 5 mA		1	20	mV
Short circuit	VREF = 0 V		15	45	mA
Oscillator					
Accuracy	$V_{OUT} = V_{REF}$	360	400	440	
Foldback frequency	VOUT = 0.75 V	200	230	260	kHz
CLKSYNC output high		4.8	5	5.2	V
CLKSYNC output low			0.0	0.4	V
CLKSYNC sink current	CLKSYNC = 1 V	1.2	2.2		
CLKSYNC source current	CLKSYNC = 3 V		-0.2	0.1	mA
CLKSYNC input threshold	CLKSYNC from 5 V to 0 V (edge detect)	2.5	3.0	3.5	V
Error Amplifier					
I <sub>B</sub>	Total bias current; regulating level	-1		1	μΑ
FB voltage	FB = COMP	2.43	2.5	2.57	V
A <sub>VO</sub>		50	90		dB
GBW	F = 100 kHz <sup>(1)</sup>	2.5	5		MHz
Output source current	FB = 2.3 V, COMP = 2.5 V	-0.6	-1.2		A
Output sink current	FB = 2.7 V, V <sub>COMP</sub> = 1 V	0.250 1			mA
V <sub>OL</sub>	I <sub>O</sub> = 100 μA		0.3	0.9	V
V <sub>OL</sub>	$I_{O} = -100 \mu A$	2.7	3.1	3.5	V
PWM					
Minimum duty cycle	FB = 3 V, CS = 0 V			0%	
Maximum duty cycle	FB = 0 V, CS = 0 V	75%	78%	81%	
Current Sense					
Input bias current (CS)				3.0	μΑ
CS shutdown threshold		1.235	1.3	1.365	V
CS shutdown hysteresis			20		mV
CS over current threshold		0.95	1	1.05	V
Current/FAULT		1			
Soft start charge current		-10	-20	-30	. ^
Soft start discharge current		10	20	30	μΑ
V <sub>OL</sub>			0	50	mV
Soft start complete threshold		3.6	4	4.4	١,,
Soft start restart threshold		0.4	0.5	0.6	V

<sup>(1)</sup> Specified by design. Not 100% tested in production.



## **ELECTRICAL CHARACTERISTICS (continued)**

Unless otherwise specified, these specifications apply for  $T_A$  = -40°C to 85°C for the UCC2884, and 0°C to 70°C for the UCC3884, CT = 220 pF,  $R_{ON}$  = 53 k $\Omega$ ,  $R_{OFF}$  = 38 k $\Omega$ , VOUT = VREF, VVS = 0 V, CSS = 2.5 nF, VDD = 11 V, Output no load,  $T_A$  =  $T_J$ .

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
Volt Second Clamp		·				
	VVS = 1.4 V, T <sub>A</sub> = 40°C to 85°C	50%	60%	70%		
Dutu suala	VVS = 1.4 V, T <sub>A</sub> = 0°C to 70°C	52%	57%	67%		
Duty cycle	VVS = 3.6 V, T <sub>A</sub> = -40°C to 85°C	20.5%	22.0%	25.5%		
	VVS = 3.6 V, T <sub>A</sub> = 0°C to 70°C	20.5%	22.0%	23.5%		
I <sub>B</sub>	VVS = 3.7 V	-1		1	μΑ	
Output Stage						
Output low saturation	I <sub>OUT</sub> = 100 mA		0.5	0.9		
Output law actuation	$I_{OUT} = -50 \text{ mA}$		0.5	0.9		
Output low saturation	I <sub>OUT</sub> = 200 mA <sup>(2)</sup>			1.9	V	
UVLO output low saturation	I <sub>OUT</sub> = 20 mA, VDD = 0 V		0.7	1.2	1	
Rise time	C <sub>L</sub> = 1 nF		50	70	ns	
Fall time	C <sub>L</sub> = 1 nF		30	50		
Undervoltage Lockout		1 1	,	•		
Turn-on threshold voltage		8.4	8.9	9.4	V	
Hysteresis		200	600	1000	mV	
Startup Regulator						
Regulated VDD voltage		9.5	9.5 10	10.5	V	
VDD override threshold				10.7		
Overall						
V <sub>DD</sub> range				14.5	V	
I <sub>DD</sub> (run)	f = 400 kHz	2	5	10	mA	
I <sub>DD</sub> startup current	VDD = 5.4 V	100		250	μΑ	
VDD clamp	IDD = 10 mA	12	13.5	15	V	

<sup>(2)</sup> Specified by design. Not 100% tested in production.



#### PIN DESCRIPTIONS

**CLKSYNC:** An edge triggered active low TTL signal to this pin synchronizes the oscillator to an external clock. When VOUT decreases below 3.0 V, the frequency foldback circuit is activated and the controller becomes unsynchronized. When VOUT exceeds 3.0 V, the controller resynchronizes to the external clock.

**COMP:** The output of the voltage error amplifier used for compensation. The output is clamped to 3.0 V minimum.

**CS:** Current sense input. This pin accepts a voltage proportional to converter inductor current. The voltage CS is compared to the output of the compensated error amplifier to control the on-time of the switch. Voltage mode control can be realized by driving this pin with fixed sawtooth ramp. Voltage feedforward is achieved by making the peak of this ramp proportional to the input voltage.

**CSS:** A capacitor, CSS, to ground programs the soft-start time for the power-up sequence. This function is also used when an overcurrent fault occurs. As CSS is charged, the PWM comparator uses the lowest of either the voltage at CSS or the error amplifier output voltage to determine the duty cycle. The duty cycle, therefore, slowly increases during the soft-start cycle. The faults that cause CSS to discharge and shutdown the controller are the logical OR of VREF below 4.4 V or VDD below 8.8 V. If a fault is still present when CSS is discharged below 0.5 V, the supply remains off until the fault is cleared. The soft-start time is determined by:

$$t_{SS} = 3.5 \times \frac{C_{SS}}{I_{SS}}$$

where I<sub>SS</sub> is 20 μA. A current limit terminates the present cycle. It does not generate a soft start cycle.

**CT:** A capacitor, C<sub>T</sub> to ground, is charged and discharged creating the oscillator waveform. This waveform varies between 1.5 V and 3.5 V. The operating frequency is determined by:

$$f = \frac{4.4}{CT \times \left(\frac{R_{ON}}{1.5} + \frac{R_{OFF}}{3.5}\right)}$$

The ratio of the time duration of the positive sloped portion of the CT voltage waveform to the period gives the maximum duty cycle.

**FB:** The inverting input of the voltage amplifier used to sense the output voltage. The non-inverting input of the error amplifier is internally connected to 2.5 V.

**GND:** The ground pin internally used for all the amplifiers and as the return for all resistor and capacitor connections to the UCC3884.

**GT:** Used to drive an external depletion-mode MOSFET for the housekeeping power supply. The MOSFET is turned off when the bootstrap winding voltage exceeds 10 V. There is 300 mV of hysteresis around the 10-V, turn-off voltage to prevent oscillation. See Typical Application.

**IOFF:** A resistor,  $R_{OFF}$ , to ground, programs the discharge current of the timing capacitor  $C_T$ . This is a variable discharge current which determines the negative slope of the oscillator voltage waveform at CT. The discharge time is dependent on the voltage at the VOUT pin. The discharge current is given by:

$$I_{OFF} = \frac{VOUT}{R_{OFF}}$$

The VOUT pin is internally clamped to 3.5 V maximum.



**ION:** A resistor,  $R_{ON}$ , to ground programs the charge current of the timing capacitor,  $C_T$ , which generates the positive slope of the oscillator waveform. The charge time is constant and corresponds to the maximum output on-time at OUT. The charge current equation is:

$$I_{ON} = \frac{1.5V}{R_{ON}}$$

When required the linear positive slope of the C<sub>T</sub> voltage could be buffered and used to provide slope compensation into the CS pin.

**OUT:** The output of the controller. The peak source current is 0.5 A and the peak sink current is 1.0 A. The faults listed under the CSS description turn off this output.

**PGND:** The power ground pin is used as the return for the output transistor drive stage.

**VDD:** The input voltage of the chip. A low ESR and ESL ceramic capacitor from this pin to GND should be used to bypass internal switching transients.

**VOUT:** This pin accomplishes frequency foldback by controlling the discharge current for the oscillator CT capacitor. A dc voltage proportional to the output voltage is connected to this pin. To startup with zero output voltage the user should tie a resistor between VREF and VOUT. The value depends on the lowest desired operating frequency. When VOUT decreases below 3.5 V the frequency decreases by reducing the discharge current  $I_{OFF}$ . When VOUT increases, the frequency increases by increasing the discharge current. The maximum operating frequency occurs when VOUT = 3.5 V. The  $C_T$  charge time is constant to assure a maximum output duty cycle. This pin must be above 3.0 V to allow synchronization to occur.

**VREF:** This pin is the output of the 5-V regulated reference. Bypass this pin with a low ESR and ESL ceramic capacitor (e.g.,  $0.47 \mu F$ ).

**VVS:** Provides a programmable duty cycle clamp which is dependent upon the input voltage. A resistor divider network reduces the input voltage supplied to VVS. The device determines the reciprocal of the voltage at VVS and scales the result. The voltage is then compared to the oscillator waveform to clamp the duty cycle. The purpose of this clamp is to reduce the likelihood of saturating the isolation transformer during unusual line or load conditions.



#### **APPLICATION INFORMATION**

## **Theory of Operation**

The UCC3884 current-mode PWM controller contains a programmable oscillator which includes the ability to synchronize multiple PWMs. The positive and negative sloped portions of the oscillator waveform (measured at CT), have time intervals that are set by external resistors at ION and IOFF. The operating frequency is inversely proportional to the timing capacitor. The negative sloped portion of the oscillator waveform is extended in time as the measured output voltage decreases providing protection during output faults. The power supply output voltage and the voltage from VREF are fed back to VOUT. When the output voltage decreases, the voltage at VOUT also decreases. As VOUT decreases below 3.5 V, the operating frequency decreases. This reduction in frequency allows the duty cycle to decrease below what the CS to OUT delay would otherwise permit. This is referred to as frequency foldback. An output short circuit or overload causes the converter to enter the frequency foldback mode. Synchronization to other controllers can only occur during normal operation, that is, when VOUT is greater than 3.0 V.

GT is provided to turn off an external depletion-mode MOSFET after startup when the bootstrap winding exceeds 10 V. This depletion-mode MOSFET is used in the housekeeping section of the converter to simplify startup biasing circuitry. The amplifier that drives this MOSFET has 300 mV of hysteresis to avoid oscillation during power up.

An accurate programmable volt-second technique clamps the duty cycle. The duty cycle limit is inversely proportional to input voltage and a resistor divider network is used to program the proportionality constant. At a given input voltage and constant load, under closed loop control, the operating duty cycle is a fixed value. The volt-second clamp duty cycle may then be set somewhat higher than this operating duty cycle. For other input voltages, the volt-second clamp still exceeds the steady state operating duty cycle. This allows normal closed loop operation of the converter. It is during a load transient (a fault such as a momentary short circuit) as the error amplifier increases the duty cycle, that when the volt-second clamp accurately limits the maximum volt-seconds. This ensures that the transformer does not saturate during a fault which can fail the power supply. After the fault is removed the converter resumes closed loop control.

CSS is provided which allows the UCC3884 to be disabled with an external transistor. The increasing pulse width at OUT during soft start should be programmed to be less than the pulse width of the duty cycle limit that the frequency foldback circuitry creates. The frequency foldback circuit will be in effect during soft start since the output voltage fed back to VOUT is less than 3.5 V. Designing the circuit in this fashion allows a proper startup sequence.

The current sense feedback pin has an overcurrent protection feature which forces a soft start cycle only if the device is not currently in a soft-start cycle. A 1-V bias at the PWM comparator's non-inverting input and a reset dominant PWM latch permit zero duty cycle operation.

The error amplifier has a wide gain-bandwidth product and its non-inverting input is internally set to 2.5 VDC.



#### Oscillator

The oscillator has charge and discharge currents programmed with resistors to ground from ION and IOFF respectively, as seen on the Oscillator Block Diagram.(Figure 1). This generates a linear sawtooth waveform on CT. Frequency foldback is accomplished by the level shifted output voltage controlling the VOUT voltage which decreases the discharge current and the frequency.

Synchronization is accomplished by coupling the fastest oscillator CLKSYNC signal as shown on the Oscillator Synchronization Diagram (Figure 2). The fastest (master) CLKSYNC pin couples a negative pulse into the slower (slave) CLKSYNC pins forcing the slaves' CT pins to quickly discharge as shown on the Oscillator Waveform diagram (Figure 3).

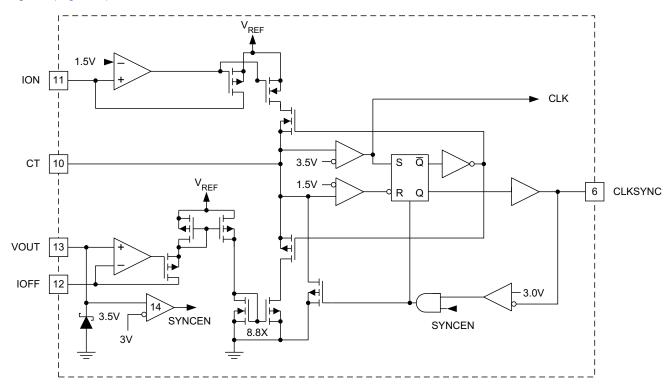


Figure 1. UCC3884 Oscillator



## **Synchronization Techniques**

The following explains two synchronization techniques:

- 1. **Initially Undefined Master** If the user does not care which unit is the master, then the oscillator frequencies are designed as accurate as necessary and one unit becomes the master and synchronize the remaining units. The user never knows exactly which unit will be the master upon power up.
- 2. User-Defined Master If the user does care which unit is the master, a unit should be identified as the master, and the frequency and maximum duty cycle clamp should be programmed accordingly. The ROFF resistor which programs the slave units oscillator discharge ramp should be between 50% and 100% of the ROFF resistor which programs the master. This ensures that if a slave unit tries to synchronize the master, the master frequency will still be faster than the slave frequency and the master synchronizes all the remaining units.

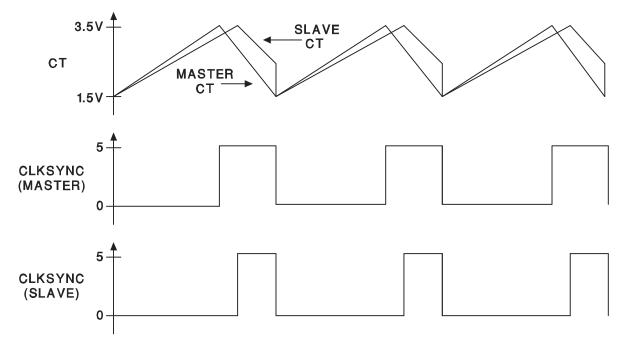


Figure 2. Oscillator Waveforms



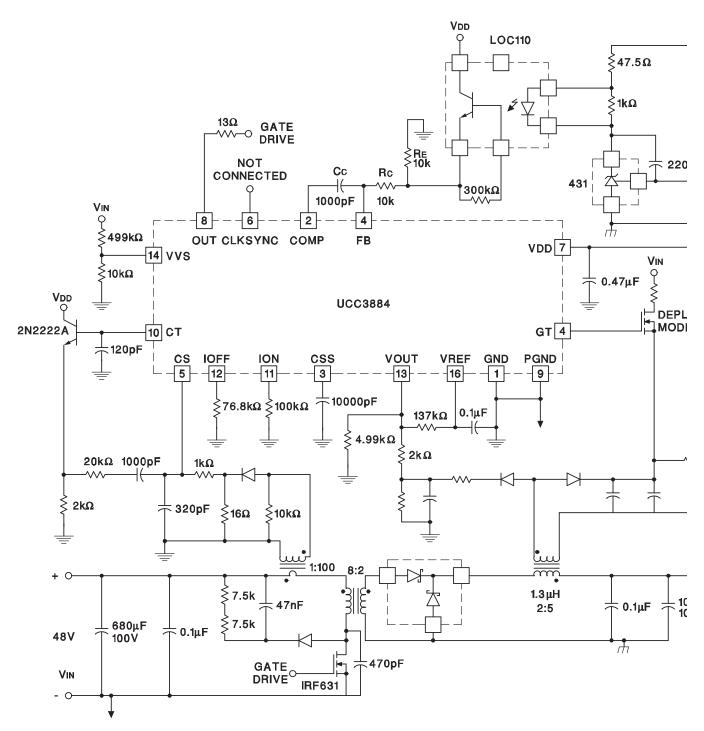


Figure 3. Typical Application

www.ti.com 11-Nov-2025

#### PACKAGING INFORMATION

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
UCC3884D	Active	Production	SOIC (D)   16	40   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	0 to 70	UCC3884D
UCC3884D.A	Active	Production	SOIC (D)   16	40   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	0 to 70	UCC3884D

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

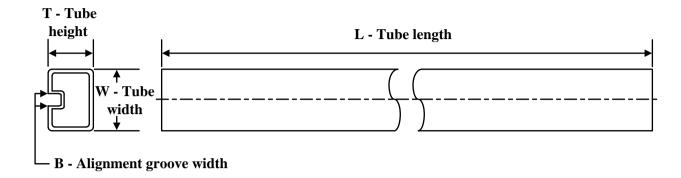
<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

# **PACKAGE MATERIALS INFORMATION**

www.ti.com 23-May-2025

## **TUBE**



### \*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
UCC3884D	D	SOIC	16	40	507	8	3940	4.32
UCC3884D.A	D	SOIC	16	40	507	8	3940	4.32

# D (R-PDS0-G16)

## PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AC.



### IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you fully indemnify TI and its representatives against any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale, TI's General Quality Guidelines, or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products. Unless TI explicitly designates a product as custom or customer-specified, TI products are standard, catalog, general purpose devices.

TI objects to and rejects any additional or different terms you may propose.

Copyright © 2025, Texas Instruments Incorporated

Last updated 10/2025