

System solutions for In-Vitro Diagnostics applications

Matthew Chen

IVD System engineer



Agenda

- IVD introduction and subsystems
- Key subsystems in IVD applications
 - Optical signal chain
 - · Precision optical signal chain
 - High-speed optical signal chain (Flow cytometry)
 - Motor automation & control
 - Thermo-Electric Cooling (TEC)
 - LED and laser driving
 - Liquid level sensing
 - Electro-chemical sensing
- Q&A



Design smarter, high-performance medical systems



Introduction for IVD applications

	END EQUIPMENT	CLINICAL USE	KEY TECHNOLOGY BLOCKS
	Chemistry/ Gas Analyzer	-Diabetes -Lipid Panel -Lung Function	-Electrochemical Sensing Front End -Precision Optical Signal Path
Blood/Cell/ Fluid Analysis	Hematology Analyzer/ Flow Cytometer	-Complete Blood Count (3/5 part) - Cell Analysis	-Precision Optical Signal Path -High Speed Signal Path -Impedance Method (Coulter) -Motor Automation
	Immunoassay	-Antibody/Virus -Pregnancy -Drug/Doping -Bacteria -Cardiac -Hormone	-Motor Automation -Precision Optical Signal Path
Moloculor/	Molecular Analyzer	-Virus/Bacteria Identification	-Precision Optical Signal Path -TEC Controller -Motor Automation
Molecular/ Genetic Identification	DNA Sequencer	-Genetic Sequencing -Cancer Genetics -Prenatal	-TEC Controller -Motor Automation

Applications

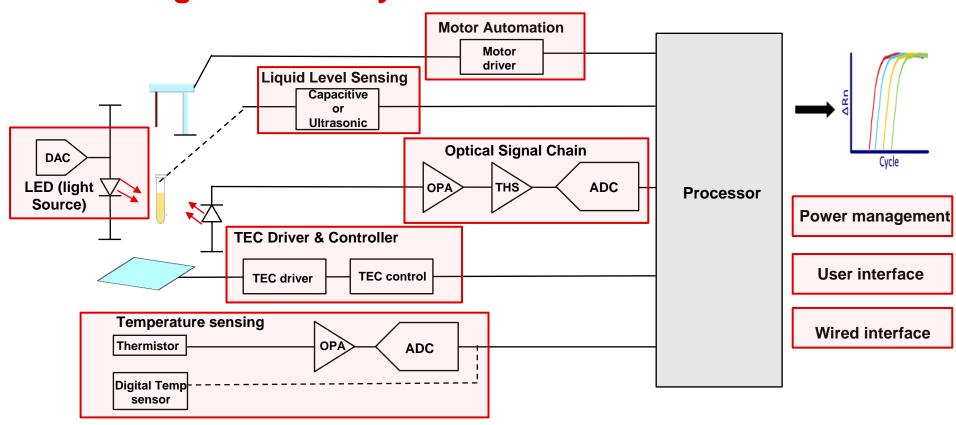
- ➤ Infectious disease detection
- Diabetes
- Tumor markers
- heart disease
- > Autoimmune disease
- Renal function

Main sub-system

- Optical signal chain
- > Thermoelectric cooling
- Liquid level sensing
- ➤ Temperature sensing
- ➤ Motor automation
- ➤ LED/LASER driver



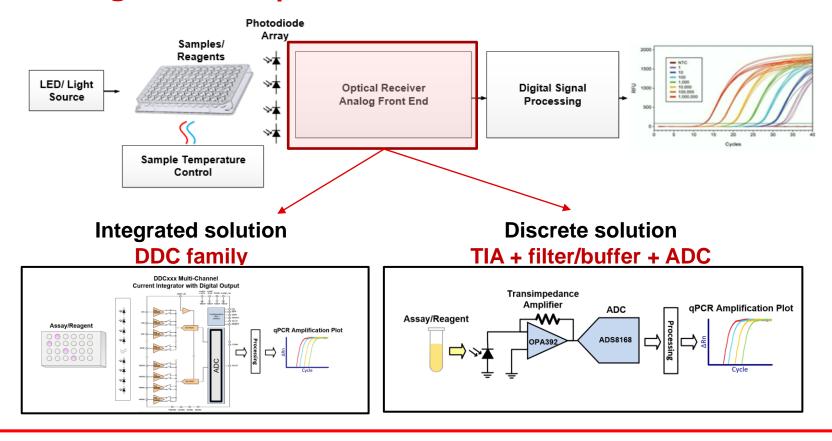
Block diagram & sub-system



Optical signal chain



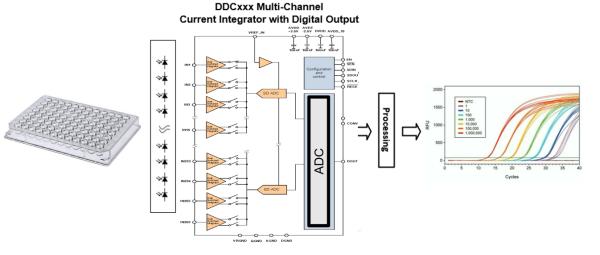
Optical signal chain | Overview



Precision Optical Receive | Integrated | solution for high sensitivity and throughput

 Integrated simultaneous amplification and sampling of 1 to 256 photodiode currents with one device

- Up to 24bit ADC
- Adjustable input gain for full scale range from 6.25pA to 3uA
- Low noise: 0.37fArms at 1SPS and 6.25pA full-scale setting

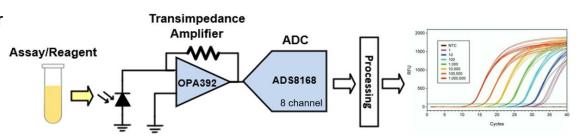


DDC/#ch	mW/ch @ KSPS	DDC/#ch	mW/ch @ KSPS
112	85 @ 3	232	10 @ 6
114	18 @ 3	264	5.5 @ 6
118	18 @ 3	1128/9	5.5 @ 6/12
316	31 @ 50	2 256 A	2.1 @ 12



Precision Optical Receive | Op-amp based discrete solution

- Discrete solution customizable for different full-scale-range and timing requirements
- OPA392: Ultra-low bias current 0.8pA(25°C)
- OPA928: Ultra-low input bias current 20 fA (tested max) at 25°C and 85°C
- ADS9110 18-bit, 2-MSPS, onechannel SAR ADC with enhanced serial peripheral interface (SPI)



Parameter	Transimpedance Amplifier	Precision ADC Optical Signal Chain	Precision ADC Temperature Sensing
GPN	<u>OPAx392</u> <u>OPA928</u> <u>THS4551</u>	ADS9110 ADS127L11 ADS7066	ADS124S06 ADS124S08
Description	 Precision, Low Vos, noise, Ibias current, Amplifiers Femtoampere Input Bias, Precision Amplifiers Low-Noise, Precision, FDA 	 18 bit, 2-MSPS, SAR 24 bit, 400-kSPS, Δ-Σ 8-Ch, 16-Bit, 250-kSPS SAR ADC 	 24-bit, 4-kSPS, 6- ch Δ-Σ ADC 24-bit, 4-kSPS, 12- ch delta-sigma ADC with PGA

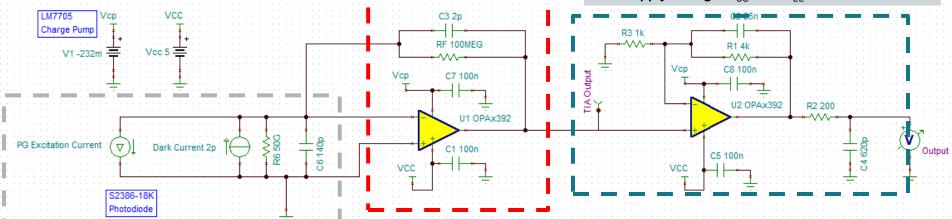


Discrete Optical Receiver | Simulation

The below simulation emphasizes the sensitivity achievable through a discrete analog front end. The circuit is optimized to given specifications. Passives can be tailored to different current level and timing requirements as shown here.

Specifications

- Excitation Pulse: 10ms pulse, 32Hz
- Total TIA Gain: 500MV/A
- Full scale current range: 9.9nA
- Lowest distinguishable current: ~0.476pA_{pk}
- Resolution: 14.27bits
- Supply Voltage: $V_{CC} = 5V V_{EE} = -0.232V$



Photodiode Model

S2386-18K Photodiode

- Low Noise Eq. Power (6.8×10-16 W/rtHz)
- Low dark current (2pA),
- Good sensitivity (0.3A/W at 500nm)

TIA

OPA2392 Precision Op Amp

- Low I_n (4.0 nV/ $\sqrt{\text{Hz}}$),
- Low I_b (Typical 10fA)

Non-Inverting Amplifier

OPA2392 Precision Op Amp

Smaller BOM using 2nd channel

Simulation on TI.com for Download



Simulation results | Sensitivity

Low optical sensitivity allows for a low Limit of Detection and high reproducibility in qPCR measurements. Sensitivity is increased through averaging of samples as well as tightening the bandwidth.

$$I_{\text{max}} = \frac{V_{\text{max_swing}}}{R_F \times G_{NIA}} = \frac{4.95V}{500M} = 9.9\text{nA}$$

Optical Sensitivity =
$$\frac{V_{n-out}}{G_{NIA}}(rms) = \frac{257.6 \text{uVrms}}{500 \text{M}} \times 6$$

= 3.09pAk(**0**. **476pApk**) [with 50 sample averaging]

G_{NIA} = Gain of Non-inverting amp

Dynamic Range =
$$\frac{9.9nA}{3.09pA}$$
 = 3.2k
= 11.6bits
(14.47bits) [with 50 sample averaging]

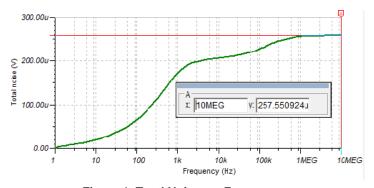


Figure 1. Total Noise vs. Frequency

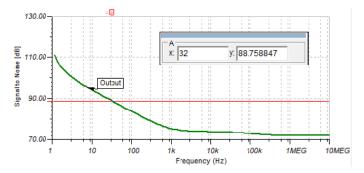


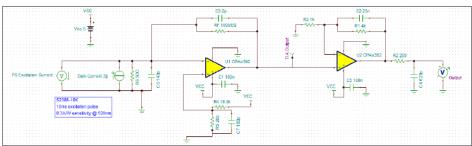
Figure 2. SNR

Simulation results | AC performance

Settling Time(to 16 bits)
$$\cong 12 \times \sqrt{\tau_{TIA}^2 + \tau_{NIA}^2} = 2.68 ms$$

$$F_{-3dB} = 670Hz$$

Phase Margin = 88.7°



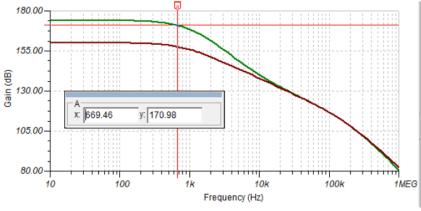


Figure 1. AC Transfer Characteristic

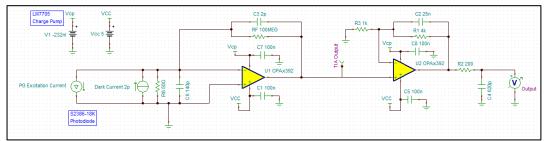
Simulation results | Accuracy

High accuracy enables good well-to-well reproducibility in qPCR measurements. Here the error is dominated by resistor gain error which can be reduced if less gain is needed or through an initial calibration

Error:

 $(\text{OPA392 } V_{OS})(\text{max}) \rightarrow 10\mu A \times 5 = \textbf{0.05}mV$ $(\text{OPA392 } I_B)(\text{max}) \rightarrow 0.8pA \times 500M = \textbf{0.4}mV$ $(\text{Dark Current})(\text{max}) \rightarrow 2pA \times 500M = \textbf{1}mV$ $(\text{Resistor Gain Error})(0.1\% \text{ tolerance}) \rightarrow \textbf{12.9}mV$

$$Accuracy = 1 - \frac{Error (worst case)}{Full Scale Range} = 1 - \frac{14.35 \text{mV}}{4.95 \text{V}} = \mathbf{0.997}$$



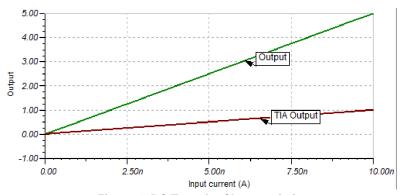


Figure 4. DC Transfer Characteristic

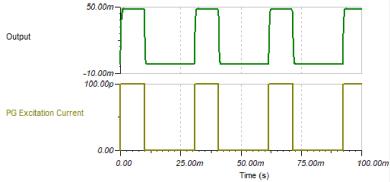
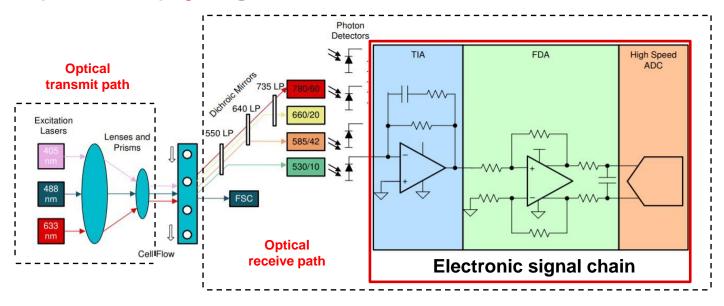


Figure 5. Transient Response 10ms 100pA pulse @32Hz

Flow Cytometry | Signal chain



- 1. Trans-Impedance Amplifiers (TIA): converts current, generated by a photodiode, into voltage that drives the FDA for a differential input ADC.
- 2. Fully Differential Amplifiers (FDA): drives single ended to differential input Analog to Digital Converter (ADC) for high precision designs.

Optical signal chain | High speed TIA selection

Sensor	Frequency Range	Capacitance Range	Current Range	Feedback Resistor Range at 2Vpp	Approx. GBW Range	Example Transimpedance Amplifiers (TIA)
PD	100kHz – 5000MHz	0.5pF-200pF	10nA-100μA	10kΩ- 100MΩ	10MHz- 100GHz	OPA855: Low Noise, 8GHz, Decompensated Bipolar-Input Amplifier OPA857: Low Noise, Fast Recovery Time, 6.8GHz,
APD	10MHz - 1000MHz	1pF-150pF	100nA-1mA	1kΩ- 10MΩ	100MHz- 10GHz	Integrated TIA with Gain Control OPA858: Low Noise, 5.5GHz, Decompensated FET-Input Amplifier
PMT	100MHz – 500MHz	0.1nF-10nF	10μΑ-100μΑ	10kΩ- 100kΩ	1GHz- 100GHz	OPA818: Low Noise, High Voltage, 2.7GHz, Decompensated FET-Input Amplifier OPA657: High Precision, High Output Current, 1.6GHz, Decompensated FET-Input Amplifier
SiPM	1MHz – 100MHz	50pF-1nF	1μΑ-10mA	100Ω- 1MΩ	100MHz- 10GHz	OPA856: Low Noise, Wide Output Swing, 1.1GHz, Bipolar-Input Amplifier LMH32401: Programmable gain, Differential Output ADC driver, Integrated TIA, Ambient Light Cancellation, 100mA Protection Clamp, 450MHz (1, 4 Channels, Q100 Option) OPA656: High Precision, High Output Current, 230MHz, FET-Input Amplifier OPA810: Low noise, RRIO, High Output Current, 70MHz, FET-Input Amplifier (1, 2 Channels) OPA607: High Precision, 50MHz, RRO, Decompensated CMOS Amplifier (1, 2 Channels) OPA320: High Precision, 20MHz, RRIO, Zero-Crossover, CMOS Amplifier (1, 2 Channels)



Optical signal chain High speed summary

Block diagram/schematic

Flow Cytometry Front End FDA High TIA Excitation Speed Lasers ADC

Design challenge/problem statement

- The main signal chain design considerations in Flow Cytometer systems are the SNR of the TIA stage, ADC SNR, and ADC Sample Rate.
- The system Dynamic Detection Range(DNR) is limited by the combined SNR of the signal chain. In most systems this needs to be above 80dB to be effective.
- The ADC sample rate determines the peak detection error of the system.
 ADC's with sample rates above 75MSPS are needed to achieve <1% error for common input pulses.

Key Device + Collaterals

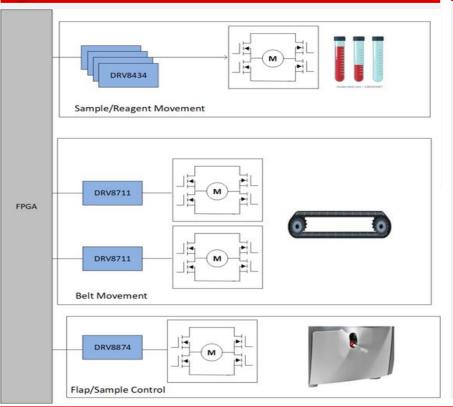
	1~2CH Devices	4~16CH TI devices
GPN	<u>OPA855</u> , <u>OPA320</u> <u>THS4551</u> , <u>ADC3683</u>	<u>LMH32404</u> / <u>OPA2607</u> <u>OPA2320</u> / <u>THS4552</u> <u>ADC3443</u>
Description	TIA + FDA + 1~2 channel, 65~80 MSPS, 16~18 bit ADCs	TIA + FDA + 4~16 channel, 65~125 MSPS, 14~16-bit ADCs
Technical resources	 Flow Cytometry Signal Chain Photodiode TI Design Why use oversampling 	Understanding JESD204B Subclasses and Deterministic Latency

Motor automation



Motor automation Motor driver overview

⊕ Application: Motor Driver



Products

Brushed motor drivers:

- Products: DRV8873, DRV8874, DRV8256
- Integration of current sense resistors, leading to BOM, space, cost reduction
- Dedicated IPROPI pin to feedback current to the MCU
- Pin-2-pin scalability across current (3.5A-6A)

Stepper/Dual motor drivers:

- Products: DRV8452, DRV8462, DRV8461, DRV8434/A/S, DRV8845/49
- Integration of current sense resistors, leading to BOM, space, cost reduction
- Smart Tune, Silent Step, and High microstepping enabling Smooth quiet motion
- Pin-2-pin scalability across current and voltage (3.5A-6A; 35V-50V)
- · Stall Detection

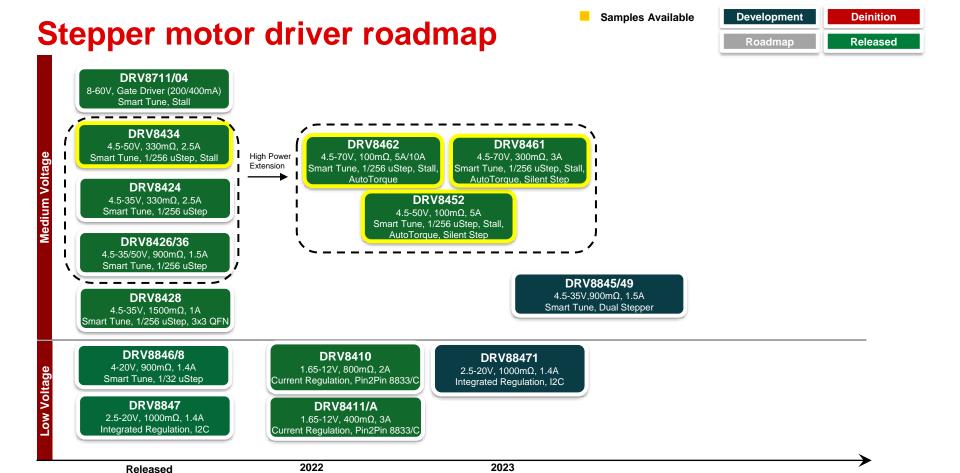
Quad Half bridges:

- Integration of current sense resistors, leading to BOM, space, cost reduction
- · Individual control and monitor of 4 channels

Gate Drivers:

- Products: DRV8711, DRV8701
- · Thermally enhanced packaging
- Adjustable gate drive
- Stall Detection





Mid Voltage Stepper/Dual Brushed DC

Device Feature	DRV8452	DRV8462/1	DRV8428	DRV8436	DRV8425	DRV8434	DRV8434A/S	DRV8811	DRV8812	DRV8886/AT	DRV8884	DRV8880	DRV8818	DRV8824
		, i		DRV8426		DRV8424	DRV8889-Q1		DRV8813	·	DRV8885	DRV8881		DRV8825
	New High Po	wer Steppers		D	RV84XX P2P FAN	1ILY					OLD GEN	1		
Supply Voltage (V) (abs. max)	50	65	35	50 35	35	50 35	50 45	38	45 45	40	40 40	50 50	35	47 45
Output FS Current (A)	5	5 3	1.0	1.5	2.0	2.5	2.5 1.5	1.9	1.6 2.5	2.0	1.0 1.5	2.0 2.0	2.5	1.6 2.5
RDSon (HS+LS) Ω	0.1	0.1 0.3	1.5	0.9	0.5	0.3	0.3 0.9	1.0	1.0 0.4	0.5	1.4 0.8	0.6 0.6	0.37	0.4
Microstepping	1/256	1/256	1/256	1/256	1/256	1/256	1/256	1/8	-	1/16	1/16	1/16 -	1/8	1/32 1/32
Interface Control	STEP/DIR PWM PH/EN SPI	STEP/DIR PWM PH/EN SPI	STEP/DIR PWM PH/EN	STEP/DIR PWM PH/EN	STEP/DIR PWM PH/EN	STEP/DIR PWM PH/EN	STEP/DIR	STEP/DIR	PH/EN	STEP/DIR	STEP/DIR STEP/DIR	STEP/DIR PWM PH/EN	STEP/DIR	STEP/DIR
Auto Torque	✓	>	1	1	-	-	-	-	1	1	-	-	-	-
Silent Step	✓	>	1	-	-	-	-	-	1	1	-	-	-	-
Automatic Microstepping	~	*	-	-	-	-	-	-	-	-	-	-	-	-
Custom Microstepping	✓	*	-	-	-	-	-	-	-	-	-	-	-	-
Stall Detection	✓	✓	-	-	-	-	✓	-	-	-	-	-	-	-
Smart Tune	✓	✓	✓	✓	✓	✓	✓	-	-	✓	-	✓	-	-
Integrated current sensing	✓	✓	✓	✓	✓	✓	✓	-	-	✓	✓	-	-	-
Packages	HTSSOP DDW	DDW DDV	HTSSOP (16pin) TSOT (16pin) QFN (16pin)	HTSSOP (28pin,) QFN (24pin)	HTSSOP (28pin) QFN (24pin)	HTSSOP (28pin) QFN (24pin)	HTSSOP (28,24 pin) QFN (24pin)	HTSSOP (28pin)	HTSSOP (28pin)	HTSSOP (24pin) QFN (28pin)	HTSSOP (24pin) QFN (28pin)	HTSSOP (28pin) QFN (28pin)	HTSSOP (28pin)	HTSSOP (28pin) QFN (28pin)
Package sizes	HTSSOP (7.7x4.4mm) DDV (14x6.1 mm)	DDV (14x6.1 mm) DDW (14x6.1 mm)	HTSSOP (5x4.4mm) TSOT (4.2x3.2mm) QFN (3x3mm)	HTSSOP (7.7x4.4mm) QFN (4x4mm)	HTSSOP (7.7x4.4mm) QFN (4x4mm)	HTSSOP (7.7x4.4mm) QFN (4x4mm)	HTSSOP (7.7x4.4mm) QFN (4x4mm)	HTSSOP (9.7x4.4mm)	HTSSOP (9.7x4.4mm)	HTSSOP (7.8x4.4mm) QFN (5.5x3.5mm)	HTSSOP (7.8x4.4mm) QFN (5.5x3.5mm)	HTSSOP (9.7x4.4mm) QFN (5.5x3.5mm)	HTSSOP (9.7x4.4mm)	HTSSOP (9.7x6.4mm) QFN (5.5x3.5mm)



DRV8452, DRV8462, DRV8461

High-powered integrated stepper family with industry leading power efficiency, precision, and noise levels

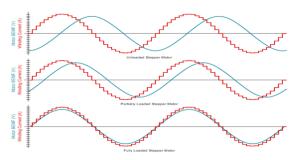
Power Efficiency and Density

Power Efficiency

- ✓ Auto torque: Improves system efficiency and thermal performance
- ✓ Standstill Power Saving Mode: User programmable stand still current automatically saving power during standstill

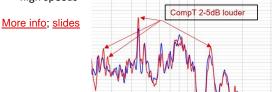
Power Density

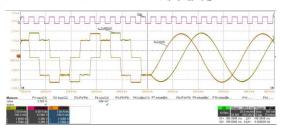
- ✓ Integration: Eliminates all passive components needed with external FETs reducing BOM cost and size
- \checkmark Integrated 100mΩ power FET: low d/s On resistance with the ability to drive from 1-10A at ambient temperature



Silent Motor Rotation

- Silent Step Low-noise decay modes: Removes noise due to PWM switching at standstill and low speeds
- ✓ Automatic microstepping: interpolates STEP pulses to generate 1/256 microstepping current waveform. Decreases audible noise and reduces MCU overhead.
- Custom microstepping: customizable microstepping table for smooth output torque
- ✓ Smart tune: Innovative decay algorithm to quite operations at high speeds





Flexibility and Protection

- ✓ Integrated current sensing and regulation: reduce design complexity and BOM cost
- Stall Detection: Sensorless stall detection eliminates end switches decreasing cost and reliability
- ✓ P2P scalability across voltages and current:
 - ✓ Scale across voltage and current ranges with P2P devices – DRV8461, DRV8452, DRV8462
 - ✓ P2P compatible with DRV84xx PWP
- ✓ Current Sense Accuracy to ± 5%
- ✓ nFault pin: Allows for advanced diagnostics
- ✓ **Indexer output:** Allows angle/position tracking
- ✓ **nHome pin:** Indicates indexer home position
 - ✓ Allows sensorless homing
- ✓ Comprehensive Protection: UVLO, CPUV, OCP, OL, OTSD, OTW



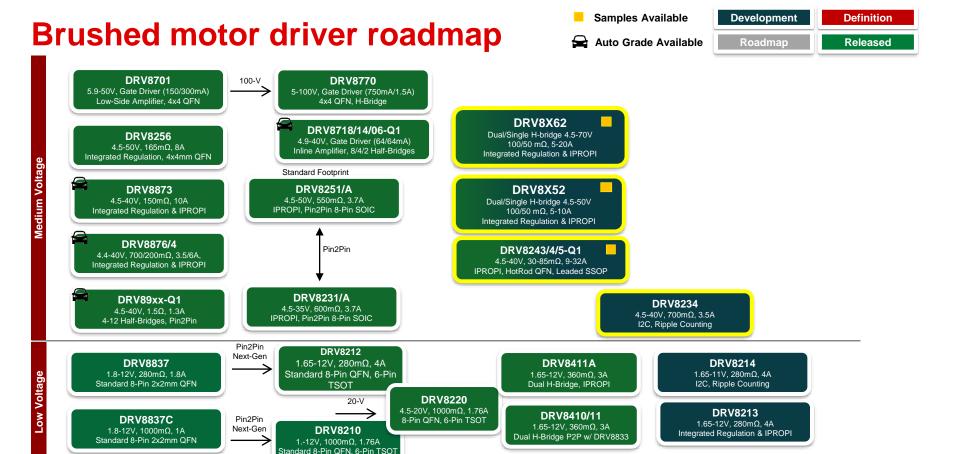
14 x 6.1mm, 44-pin, HTSSOP package (DDW, bottom EP)



14 x 6.1mm, 44-pin, HTSSOP package (DDV, top EP)

9.7 x 4.4mm, 28-pin, HTSSOP package (PWP)





Released

Brushed motor technology

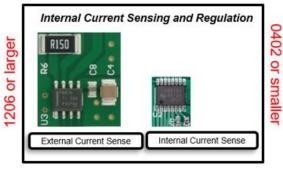
Integrated Current sensing

Eliminates large current sense resistors while providing accurate current regulation and current feedback

Benefits

- BOM reduction: Removed sense resistors and feedback amplifier <u>used to send</u> information back to MCU
 - ✓ Up to 3-5c savings per board
- ✓ Power management: No power loss over the sense resistor
- Easy design: Hassle-free layout with no sense routing

More info – video, tech doc



Devices offered with this feature:

- DRV8231A
- DRV8251A
- DRV8876
- DRV8874
- DRV8873

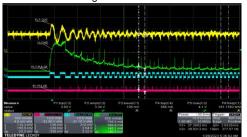
DRV8870 vs DRV8876

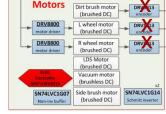
Ripple Counting

Ripple counting is a sensor-less approach to monitor DC motor position/speed

Benefits

- BOM reduction: Removes need for encoders, limit switches, hall sensors, accelerometer, magnets, and optical sensors <u>used for detecting wheel position and</u> obstacle avoidance
 - ✓ Up to \$1 BOM savings
- Reliability: Can diagnose if the motor is jammed in an intermediate position
- Easy design: Reduces assembly complexity and improves reliability by removing sensors and magnets





Ripple counting with FPGA solution

Eliminate encoders

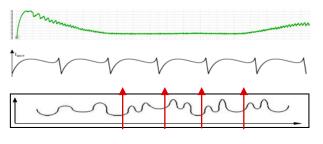
Devices offered with this feature:

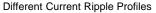
- DRV8234
- DRV8214

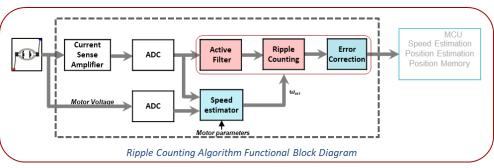


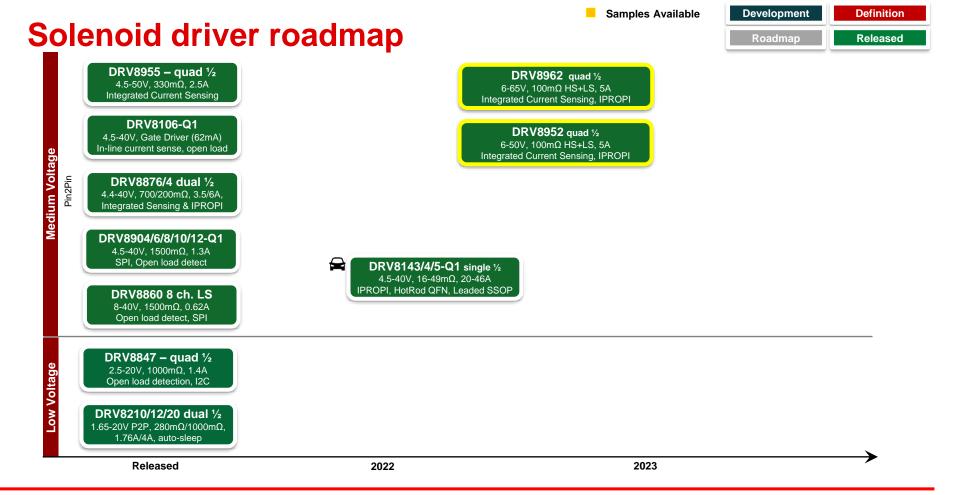
Objective of ripple counting

- Ripple counting provides a sensor-less approach to monitoring motor position/speed
 - Detects motor stall conditions or end-of-travel
 - Replaces encoders, limit switches, Hall sensors, accelerometer, and optical sensors
- In DC motors, commutation is done using commutators & brushes to activate right coil at right time
 - As brushes move from commutator ring to ring, they short-circuit adjacent commutator rings for a brief time
 - Results in momentary spike in current waveform → ripple
 - Counting these ripples gives estimate for positional movement of the motor
- Ripple Counting Challenges
 - Widely varying common-mode DC component due to inrush/stall/load & line transients, PWMing, Direction change
 - Due to Motor geometry, out of phase commutation can cause multiple ripples per commutation
 - Ripple peak current magnitude might change with average motor current, operating voltage, winding resistance
 - Varying Ripple envelops/shapes due to brush tear/shift, motor Ageing



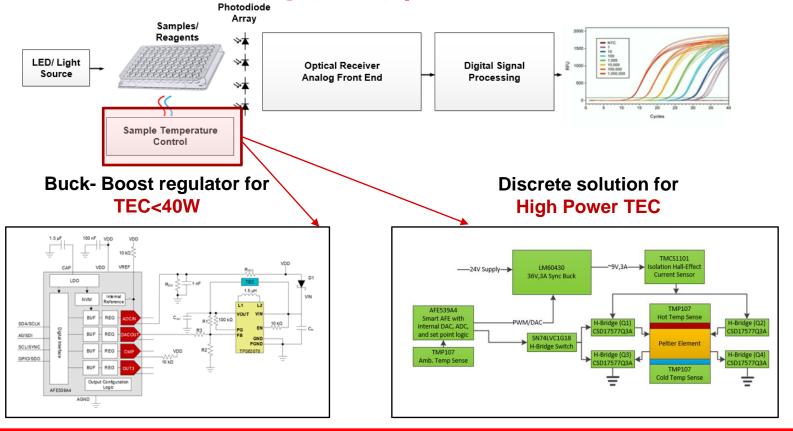




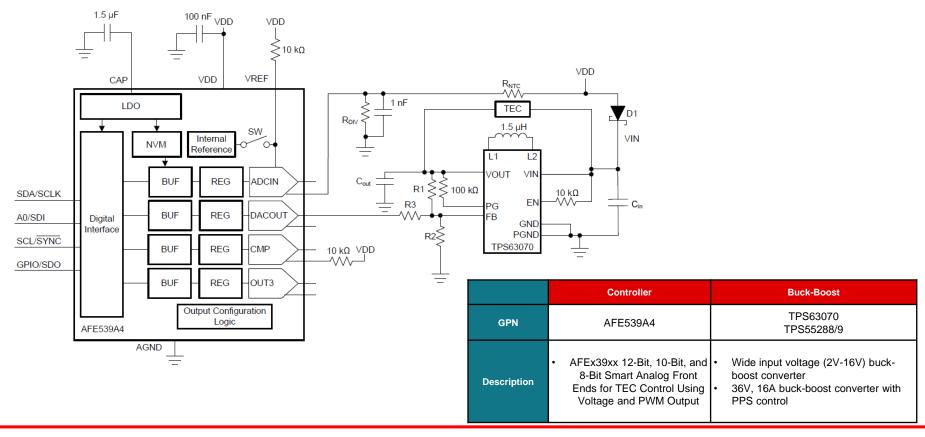


Thermo-Electric Cooling (TEC)

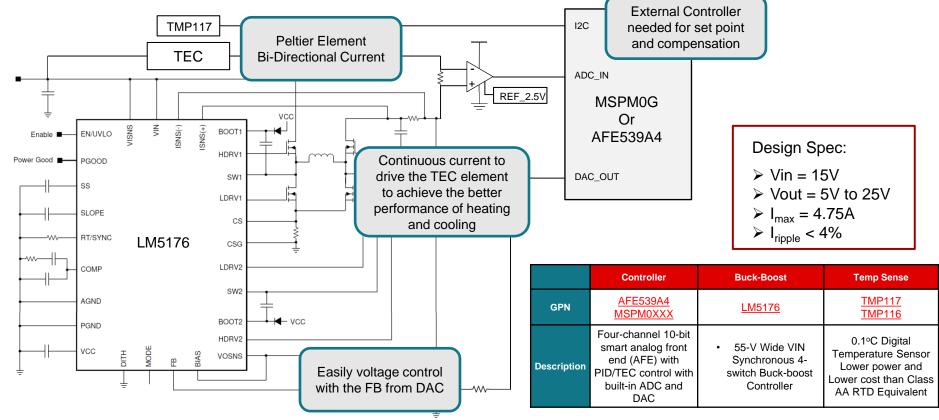
Thermo-Electric cooling (TEC) | Solution overview



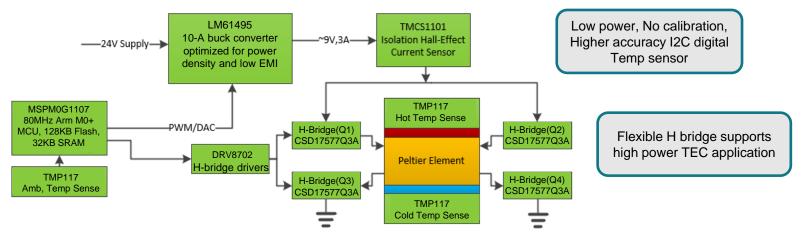
Thermo-Electric Cooling (TEC) | Smart AFE + buck boost converter



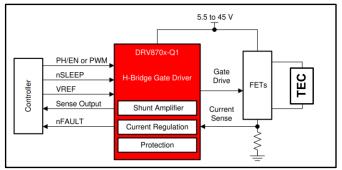
Thermo-Electric Cooling (TEC) | Buck-Boost regulator



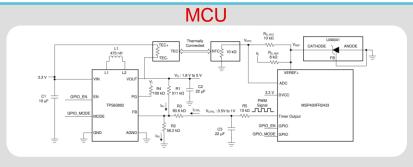
Thermo-Electric Cooling (TEC) | Discrete H-bridge driver

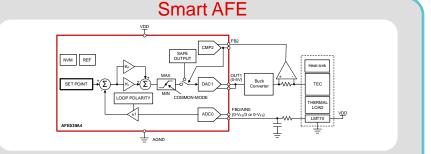


	Driver	Current Sense	Temp Sense
GPN	<u>DRV8702</u>	INA260 TMCS1101	<u>TMP117</u>
Description	H-bridge motor drivers w/ low-pass filter to deliver high-efficiency bi- polar drive	Precision Current and Power Monitor With Low-Drift, Precision Integrated Shunt	0.1°C Digital Temperature Sensor Lower power and Lower cost than Class AA RTD Equivalent



PID control | Smart AFE vs MCU





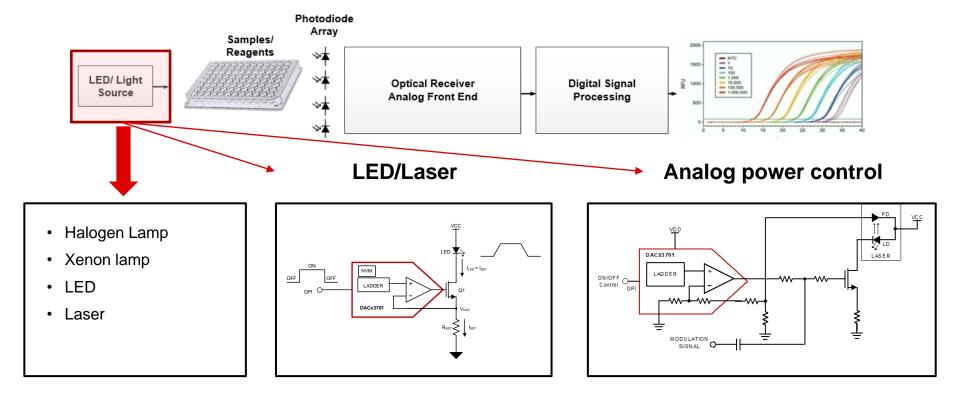
MCU-based PID control is suitable where the loop architecture needs to be highly flexible. These designs can handle complex control applications although the systems lack portability across designs due to software designed for specific processors.

Smart AFEs integrate PI control suitable for slow control loops like heating, cooling etc. These designs integrate the control loop while keeping the power converter outside thus making the system design modular, portable, and scalable. The smart AFEs can also work alongside MCUs to accept setpoints while controlling the loop autonomously.

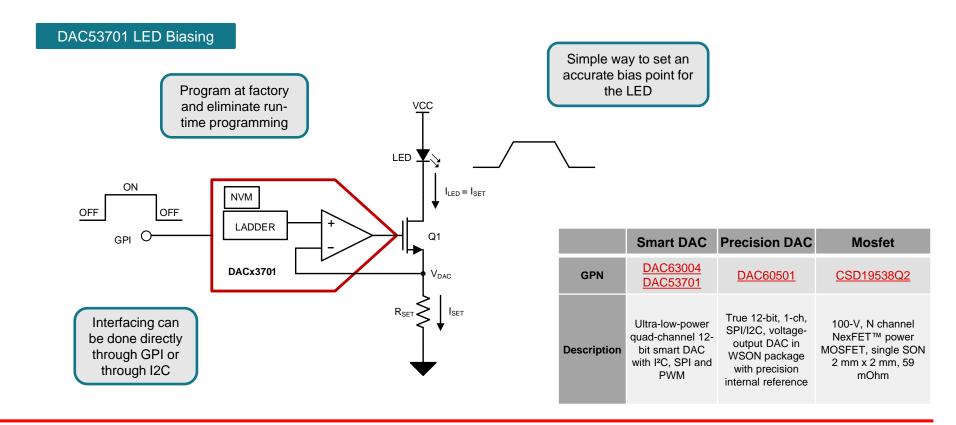
LED / Laser driver



LED / Laser driver | Solution overview



LED / Laser driver

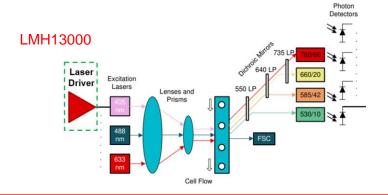


LED / Laser driver | High Speed laser diver LMH13000

Features

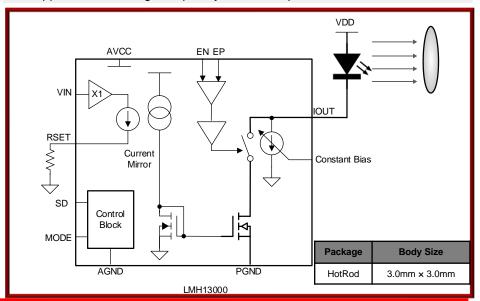
- Adjustable IOUT current for power and λ : 0.1A to 5 A
- Adjustable output frequency: DC to 250 MHz
 - Use EP & EN for creating square wave / narrow pulses / DC
- Supply Range: AVCC = 3 5V , VDD = 18V
- **IOUT Temp Drift:** < 0.5% between 40C to125C
- IOUT Noise: < 0.5 % of IOUT value.

Applications



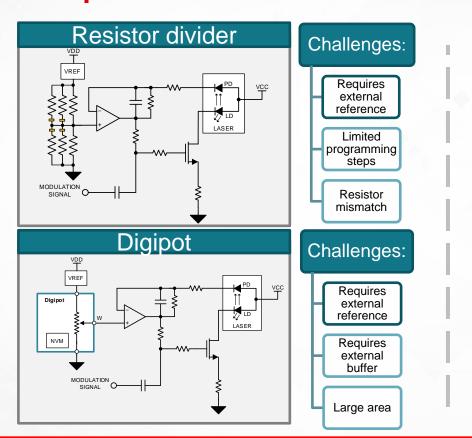
Benefits

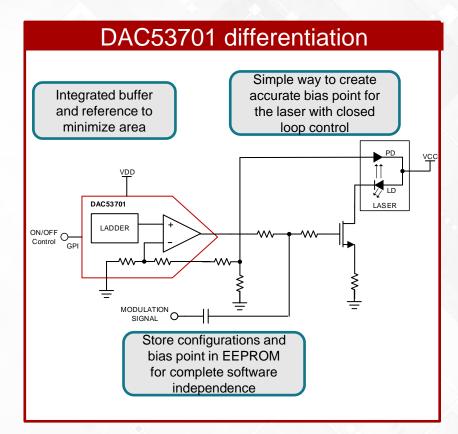
- Simplified Current Pulse generation using LMH13000
- Precise peak current control in pulsed / square wave / DC operation
- Integrated constant bias generator for achieving fixed DC current at IOUT
- · Supports DC and High frequency current output



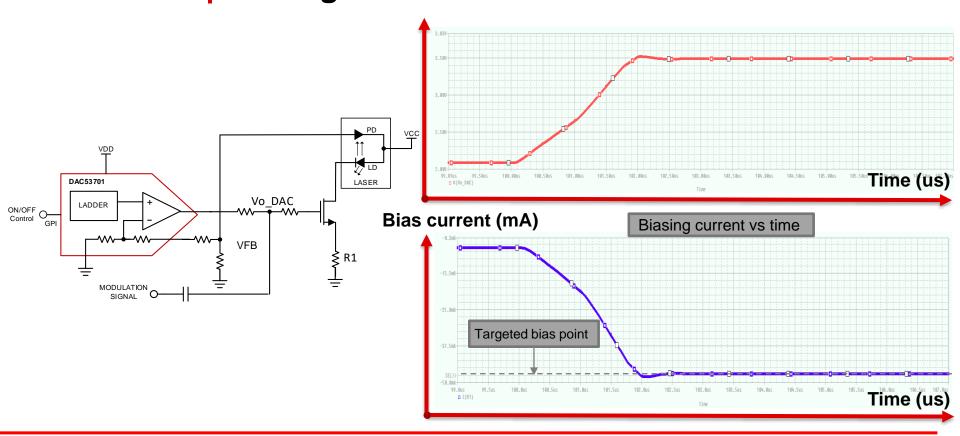


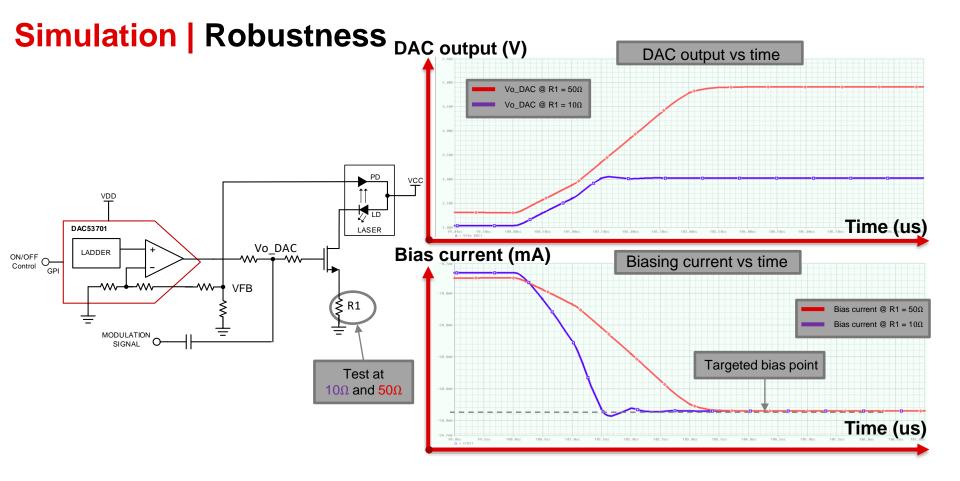
APC | Differentiation





Simulation | Biasing

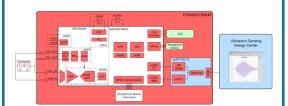




Liquid level sensing

Liquid level sensing | Solution overview

MSP430FR5/604x



Supported Frequencies: 133kHz – 2.5MHz

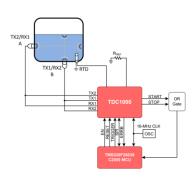
Device: AFE+MCU

Voltage range: 2.2V – 3.6V

Output: TOF

Current Consumption: 3μA @ 1SPS (Water) **Other Features:** Low Energy Accelerator, Full-MCU, 6.5dB – 30.8dB PGA, 30nA Shutdown

TDC1000



Supported Frequencies: 31.25kHz – 4MHz

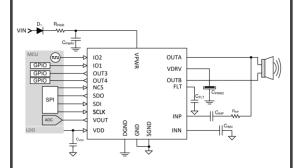
Device: AFE

Voltage range: 2.7V – 5.5V **Output:** Start/Stop Signals

Current Consumption: 1.8µA @ 2SPS Other Features: Temp Sense Interface for 2

RTDs, 0dB -21dB PGA

TUSS4470



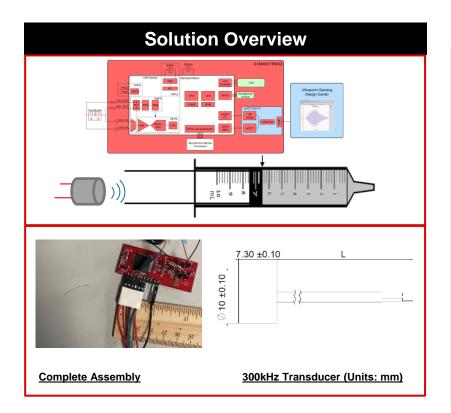
Supported Frequencies: 40kHz - 1MHz

Device: AFE

Voltage range: 5V - 36V

Output: Demodulated Echo Envelope Current Consumption: 1.7mA Standby Other Features: Up to 86dB of gain, LNA, configurable Band-pass filter, Log amplifier.

Liquid level sensing | µm distance sensing for dosing (Ultrasonic)



Key Spec of the Ultrasound solution

- ✓ Sub to 50µm Distance sensing accuracy
 - <0.004mL Steps with a 10mm diameter plunger
- ✓ Because a full MCU is used, this solution can be used as main processor or co-processor to control other peripherals
- ✓ Possibility to multiplex several sensor nodes

Parameter	Value
Power Consumption	49µW / Sample
Response time	7ms

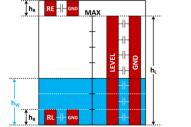


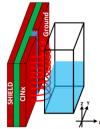
Distance Sensing Demo

Liquid level sensing | Capacitive level sensing

What is Capacitive Level Sensing

As a dielectric liquid is introduced between the electrodes of the capacitor, the capacitance changes proportionately and liquid level can be determined. Tl's solution incorporates <u>an</u> <u>active shield</u> to further stabilize the measurements and maximize the SNR.





$$Level = h_{RL} \frac{C_{level} - C_{level}(0)}{C_{RL} - C_{RE}}$$

Reference Design

Video Series:

- <u>Liquid-level sensing using the FDC1004EVM</u>
 Technical Articles:
- A novel approach for capacitive based liquid level sensing

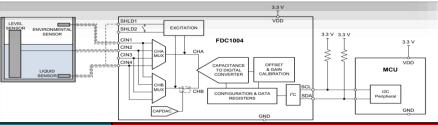


Reference Design

 TIDA-00317 Capacitive-Based Liquid Level

Capacitive Technology Benefit

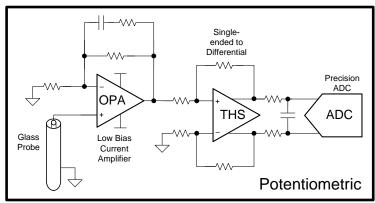
- ✓ Contactless solution can be prone to rust
- ✓ Low cost and highly flexible system design
- ✓ Accurate liquid height resolution (<1mm)</p>
- ✓ Can implement using a flex PCB

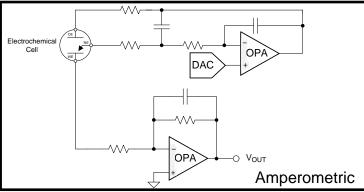


Part Number	Description
FDC1004	 4-Channel Capacitance-to-Digital Converter for Capacitive Sensing Solutions
FDC2212/4	 28-Bit,12-Bit Capacitance-to-Digital Converter for Proximity and Level Sensing Applications
FDC2112/4	- 13.3 ksps (FDC2112, FDC2114)- 4.08 ksps (FDC2212, FDC2214)

Electrochemical sensing

Electrochemical sensing | solution overview





<u>Design Challenge</u>: Accurate detection of low voltages and currents to measure blood gases, pH and electrolytes using Potentiometric and Amperometric measurements.

Solution: A low noise and high accuracy (including low Ibias and drifts) analog front ends are essential for accuracy & reliability. The OPA192 is used to measure low currents (100uA-100nA) for the Amperometric measurement.

Parameter	Low Offset and Bias Current Amplifiers	Fully Differential Amplifiers	Precision Analog- to-Digital Converters	Digital-to-Analog Converters
GPN	OPA391 OPA140 OPA928	<u>THP210</u> <u>THS4551</u>	ADS127L01 ADS127L11 ADS8900B	DAC60501 DAC70501 DAC80501
Description	Low I _B , Low noise precision amplifiers	Low noise, fast transient response FDAs	Wide Bandwidth, High Resolution ADCs	Small 12–16 bit DACs with multiple channel options
MPM Collateral	 In-Vitro Diagnostics EERD Sensor Front Ends 			

In-Vitro Diagnostics Resources on Tl.com

Precision Optical	High Speed Optical	Impedance Spectroscopy
 <u>Designing signal chains for portable</u> <u>diagnostics</u> 	High speed ADCs and Amplifiers for Flow Cytometry	Impedance Spectroscopy Simulation (Differential)
 Achieving faster, more accurate patient diagnoses with molecular test technology OPA928 Product Page Resolution-Boosting ADS7066 Using Programmable Averaging Filter 	 Flow Cytometry PSPICE Simulation Photodiode Amplifier Design Why Oversample when Undersampling can do the Job? Understanding JESD204B Subclasses and Deterministic Latency 	Impedance Spectroscopy Simulation (Single-Ended)
Thermoelectric Cooling	Electrochemical Sensing	Motor Automation
 Driving a Peltier Element (TEC) Reference Design Low Power TEC Driver Reference Design Bidirectional TEC Driver Design for 40-W TEC Closed-Loop TEC Control Circuit Using a Voltage-Output Smart AFE and DC/DC 	Compensate Transimpedance Amplifiers Intuitively (Rev. A) Micropower Electrochemical Gas Sensor Amplifier Reference Design (Rev. B) ADS127L01 Product Page Fundamentals of Precision ADC Noise Analysis	 DRV8462 Product Page Methods to Configure Current Regulation for Brushed and Stepper Motors (Rev. B) How to Reduce Audible Noise in Stepper Motors Sensorless Stall Detection With the DRV8889-Q1



© Copyright 2023 Texas Instruments Incorporated. All rights reserved.

This material is provided strictly "as-is," for informational purposes only, and without any warranty.

Use of this material is subject to TI's **Terms of Use**, viewable at TI.com

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2023, Texas Instruments Incorporated