

Literature Number: SNAP004

PLL Fundamentals

Part 4: PLL Clocking Applications

Dean Banerjee/Timothy Toroni





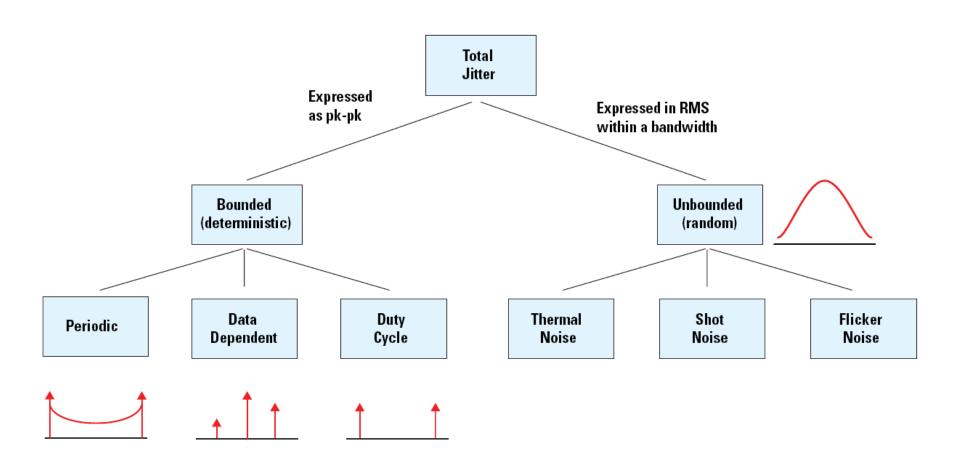
Overview

- Understanding Jitter
- Clock Cleaning Applications
- A/D Clocking Applications





The Jitter Family Tree



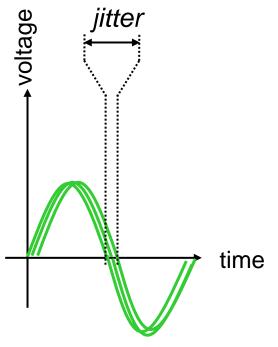


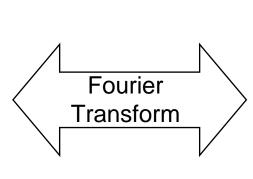




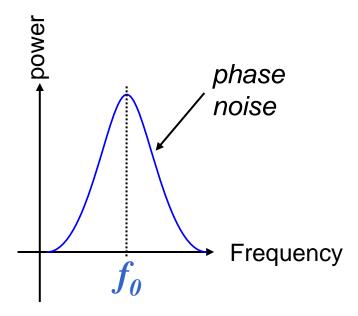
Gaussian Phase Noise Jitter

Time Domain





Frequency Domain



$$P(f) = \widetilde{V}(f)$$



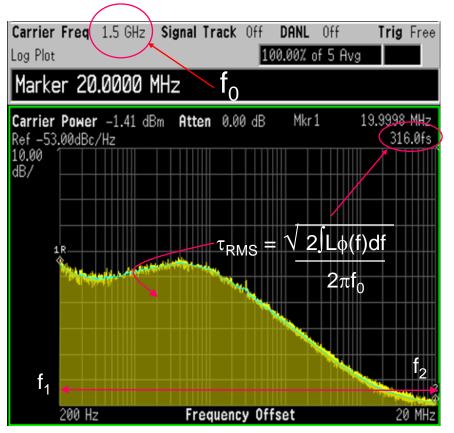


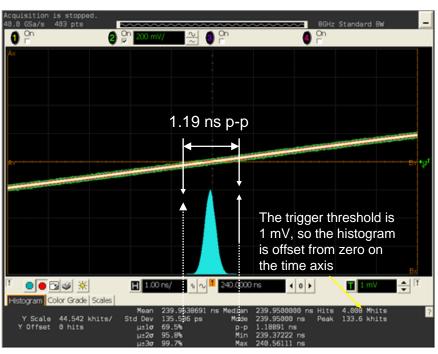


Measuring Phase Noise and Jitter

Frequency Domain Jitter Measurement

Time Domain Jitter Measurement





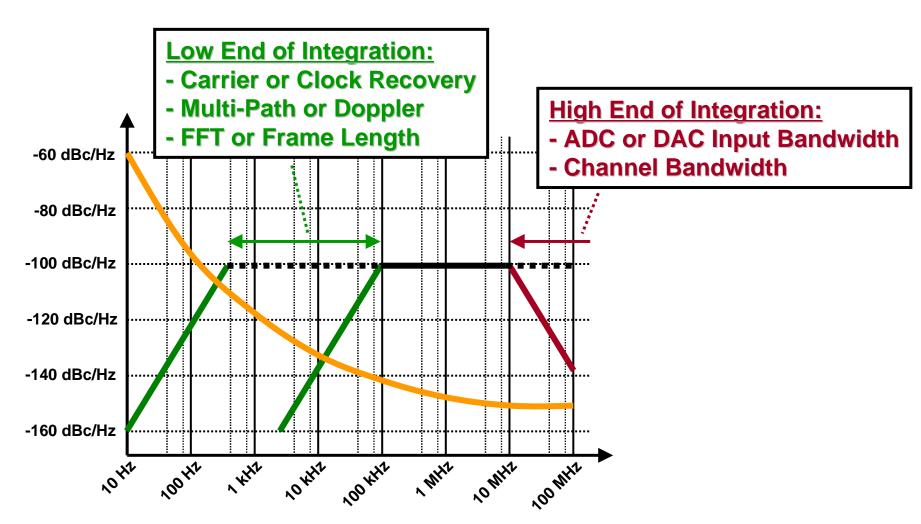
Even 40 GS oscilloscope is not recommended for measuring 316 fs of random jitter!







Jitter Integration Bandwidth





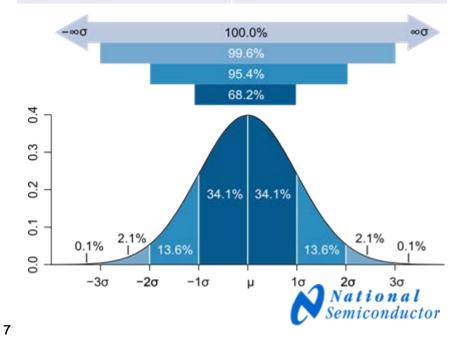


Converting from peak to peak jitter to RMS jitter or vice-versa

- Multiplier is how many standard deviations are included on a standard distribution
- (400 fs RMS) (14.059) = 5.6 ps p-p jitter
 - with 1 bit error in every 10¹² bits.
- (10 ps p-p jitter) / (15.883) = 630 fs RMS jitter
 - with 1 bit error in every 10¹⁵ bits.

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BER	Multiplier
1:10 ⁴	7.438
1:10 ⁶	9.507
1:10 ⁹	11.996
1:10 ¹¹	13.412
1:10 ¹²	14.069
1:10 ¹⁵	15.883



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Clock Cleaners

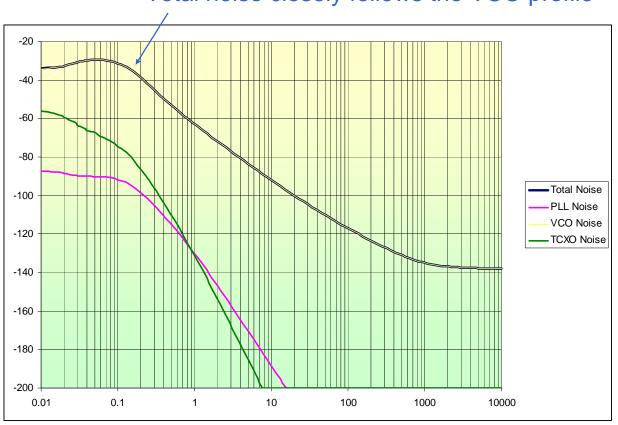
- Takes a dirty clock and a PLL with a narrow loop bandwidth to clean this up
- A PLL with a narrow loop bandwidth can be thought of as a tunable filter with a very narrow passband
 - How else could you filter noise at 10 kHz offset from a 400 MHz carrier?
- VCO noise is important for this kind of appicatoin





Narrow loop band width example

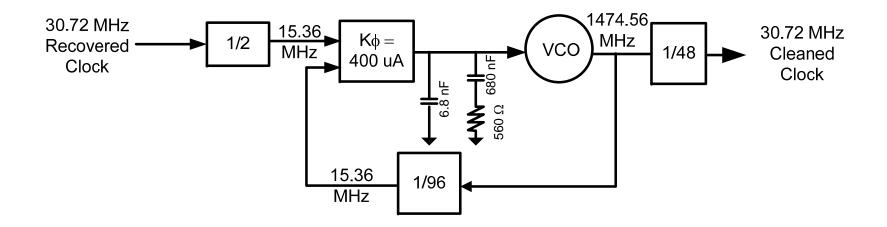
Total noise closely follows the VCO profile







SCAN25100 + LMK03000 Setup



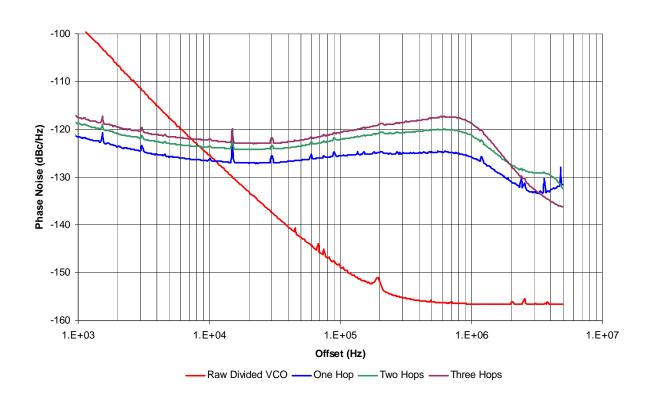
This example is taken from application note 1734







Clock Cleaning Example with LMK03000

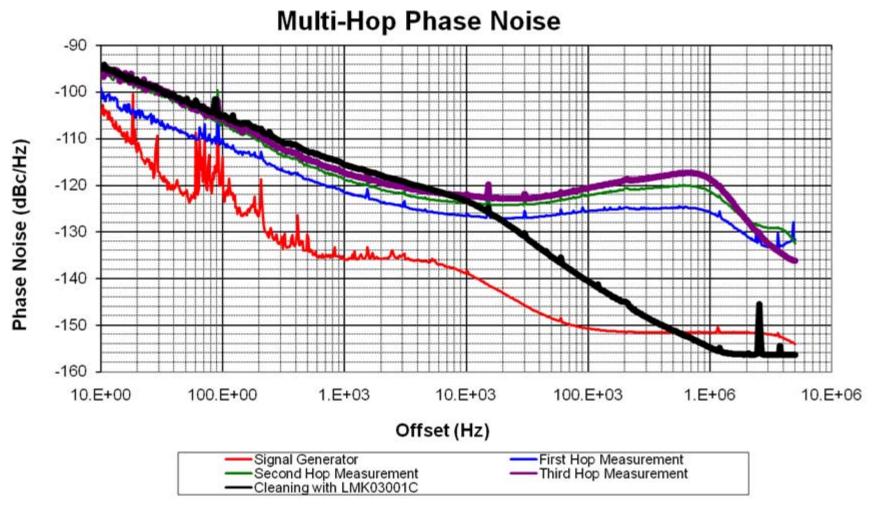








SERDES - Recovered Clock Cleaning







Overview

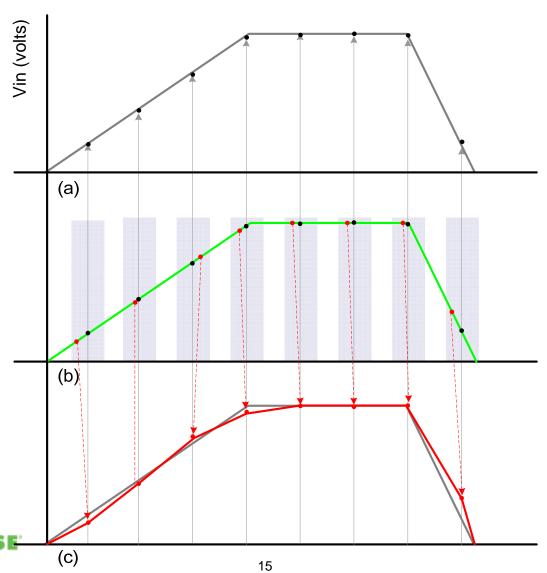
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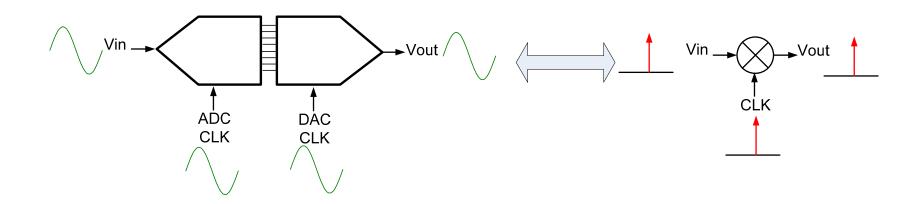
Distortion in a sampled waveform

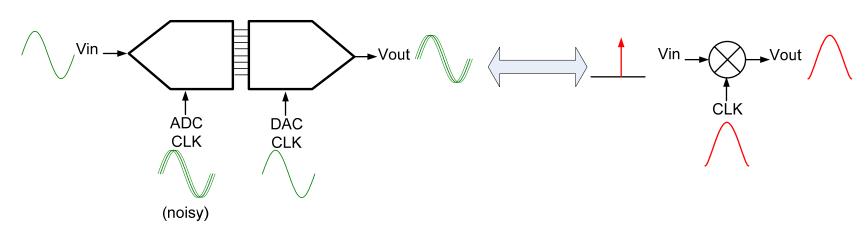






Sampling is analogous to mixing



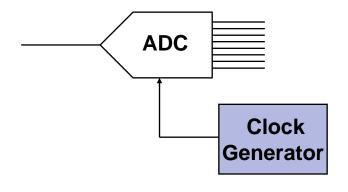








Sampling jitter



Distribution of the sampled voltage value due to sampling jitter.

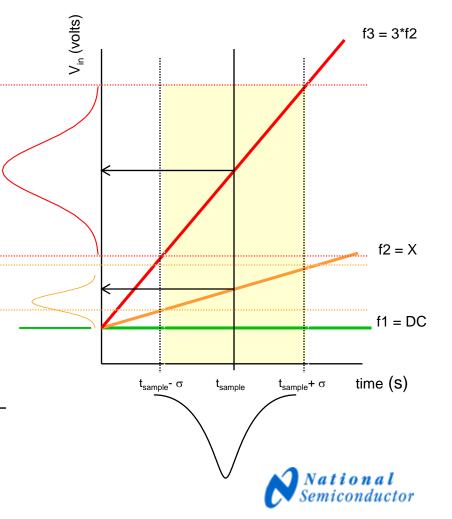
Sampling jitter has two components:

- 1. Jitter on the sampling clock
- Aperture jitter from the ADC.

Because they are uncorrelated, these jitters are combined as the root sum square:

 $\sigma = \sqrt{\sigma_{ADC}^2 + \sigma_{CLK}^2}$





SNR as a function of Sample clock jitter

Assuming a sinusoidal input for V_{in} we have,

$$v(t) = V_0 \sin 2\pi f t$$

Differentiating with respect to time yields the signal slope,

$$\frac{dv}{dt} = 2\pi f V_o \cos 2\pi f t$$

Taking the RMS value,

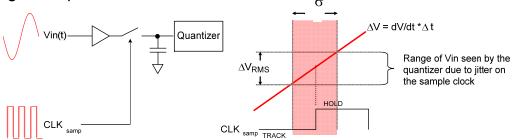
$$\frac{dv}{dt}_{rms} = \frac{2\pi f V_o}{\sqrt{2}} = \frac{\Delta V_{RMS}}{\sigma}$$

Therefore, the RMS error voltage due to jitter is

$$\Delta V_{RMS} = \frac{2\pi f V_0 \sigma}{\sqrt{2}}$$

Signal to noise ratio (SNR) is defined by,

$$SNR = 20 \log_{10} \left[\frac{signal}{noise} \right] = 20 \log_{10} \left[\frac{V_o / \sqrt{2}}{\Delta V_{rms}} \right]$$



Therefore, the SNR component due to jitter is:

$$SNR_{jitter} = 20 log_{10} \left[\frac{1}{2\pi f_{max} \sigma} \right]$$

Why do we care about SNR?

$$C = B \cdot \log_2(1 + SNR)_{\substack{National \\ Semiconductor}}$$

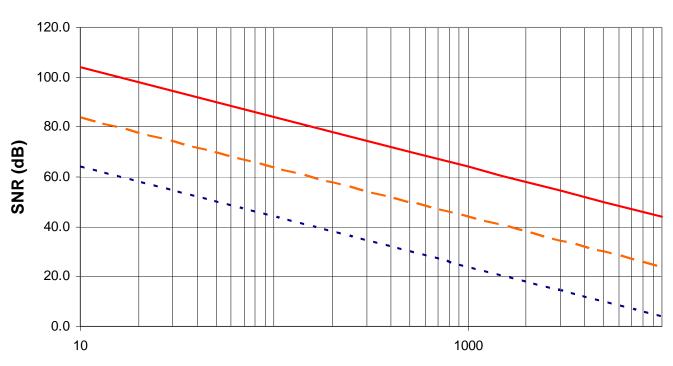




Applications Example

Data Converter Clocking (5)

SNR vs. Fin for Different Jitter Values



Input Frequency Fin (MHz)





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