Errata

MSP430F6749A Microcontroller



ABSTRACT

This document describes the known exceptions to the functional specifications (advisories).

Table of Contents

1 Functional Advisories	2
2 Preprogrammed Software Advisories	<mark>2</mark>
3 Debug Only Advisories	
4 Fixed by Compiler Advisories	
5 Nomenclature, Package Symbolization, and Revision Identification	
5.1 Device Nomenclature	
5.2 Package Markings	4
5.3 Memory-Mapped Hardware Revision (TLV Structure)	
6 Advisory Descriptions	
7 Revision History	



1 Functional Advisories

Advisories that affect the device's operation, function, or parametrics.

✓ The check mark indicates that the issue is present in the specified revision.

	ر د	, B
Errata Number	Re	Rev
ADC39	✓	✓
ADC42	✓	✓
ADC69	✓	✓
AES1	✓	✓
AUXPMM2	1	✓
COMP10	✓	✓
CPU36	✓	✓
CPU37	✓	✓
CPU46	✓	✓
CPU47	✓	1
DMA4		\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
DMA7	✓	✓
DMA9		✓
DMA10	✓	✓
LCDB6	1	✓
PMM11	✓	✓
PMM12	✓	✓
PMM14	✓	✓
PMM15	✓	✓
PMM18	✓	✓
PMM20	✓	✓
PMM26	✓	✓
PORT15	✓	✓
PORT19	✓	✓
PORT26	1	✓
SD3	✓	✓
SYS16	✓	1
UCS11	✓	✓
USCI36	✓	✓
USCI37	✓	1
USCI41	✓	1
USCI42	✓	√
USCI47	✓	✓
USCI50	✓	√

2 Preprogrammed Software Advisories

Advisories that affect factory-programmed software.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev C	Rev B
BSL7	1	✓

www.ti.com Debug Only Advisories

Errata Number	Rev C	Rev B
BSL14	✓	✓

3 Debug Only Advisories

Advisories that affect only debug operation.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev C	Rev B
EEM17	✓	✓
EEM19	✓	✓
EEM23	✓	✓
JTAG26	✓	✓
JTAG27	✓	✓

4 Fixed by Compiler Advisories

Advisories that are resolved by compiler workaround. Refer to each advisory for the IDE and compiler versions with a workaround.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev C	Rev B
CPU21	✓	✓
CPU22	✓	✓
CPU40	✓	✓

Refer to the following MSP430 compiler documentation for more details about the CPU bugs workarounds.

TI MSP430 Compiler Tools (Code Composer Studio IDE)

- MSP430 Optimizing C/C++ Compiler: Check the --silicon_errata option
- MSP430 Assembly Language Tools

MSP430 GNU Compiler (MSP430-GCC)

- MSP430 GCC Options: Check -msilicon-errata= and -msilicon-errata-warn= options
- MSP430 GCC User's Guide

IAR Embedded Workbench

• IAR workarounds for msp430 hardware issues



5 Nomenclature, Package Symbolization, and Revision Identification

The revision of the device can be identified by the revision letter on the Package Markings or by the HW_ID located inside the TLV structure of the device.

5.1 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all MSP MCU devices. Each MSP MCU commercial family member has one of two prefixes: MSP or XMS. These prefixes represent evolutionary stages of product development from engineering prototypes (XMS) through fully qualified production devices (MSP).

XMS – Experimental device that is not necessarily representative of the final device's electrical specifications

MSP - Fully qualified production device

Support tool naming prefixes:

X: Development-support product that has not yet completed Texas Instruments internal qualification testing.

null: Fully-qualified development-support product.

XMS devices and X development-support tools are shipped against the following disclaimer:

"Developmental product is intended for internal evaluation purposes."

MSP devices have been characterized fully, and the quality and reliability of the device have been demonstrated fully. Tl's standard warranty applies.

Predictions show that prototype devices (XMS) have a greater failure rate than the standard production devices. TI recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the temperature range, package type, and distribution format.

5.2 Package Markings

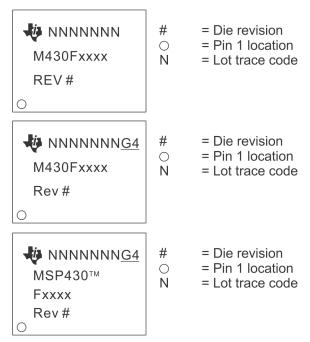
PEU128 QFP (PEU), 128 Pin



= Die revision
O = Pin 1 location
N = Lot trace code

PZ100 LQFP (PZ) 100 Pin





NOTE: Package marking with "TM" applies only to devices released after 2011.

5.3 Memory-Mapped Hardware Revision (TLV Structure)

Die Revision	TLV Hardware Revision
Rev C	12h
Rev B	10h

Further guidance on how to locate the TLV structure and read out the HW_ID can be found in the device User's Guide.

6 Advisory Descriptions

ADC39 ADC Module

Category Functional

Function Erroneous ADC10 results in extended sample mode

Description If the extended sample mode is selected (ADC10SHP = 0) and the ADC10CLK is

asynchronous to the SHI signal, the ADC10 may generate erroneous results.

Workaround 1) Use the pulse sample mode (ADC10SHP=1)

OR

2) Use a synchronous clock for ADC10 and the SHI signal.

ADC42 ADC Module

Category Functional

Function ADC stops converting when successive ADC is triggered before the previous conversion

ends

Description Subsequent ADC conversions are halted if a new ADC conversion is triggered while ADC

is busy. ADC conversions are triggered manually or by a timer. The affected ADC modes

are:

- sequence-of-channels

- repeat-single-channel

- repeat-sequence-of-channels (ADC12CTL1.ADC12CONSEQx)

In addition, the timer overflow flag cannot be used to detect an overflow

(ADC12IFGR2.ADC12TOVIFG).

Workaround

1. For manual trigger mode (ADC12CTL0.ADC12SC), ensure each ADC conversion is completed by first checking ADC12CTL1.ADC12BUSY bit before starting a new

conversion.

2. For timer trigger mode (ADC12CTL1.ADC12SHP), ensure the timer period is greater

than the ADC sample and conversion time.

To recover the conversion halt:

1. Disable ADC module (ADC12CTL0.ADC12ENC = 0 and ADC12CTL0.ADC12ON = 0)

2. Re-enable ADC module (ADC12CTL0.ADC12ON = 1 and ADC12CTL0.ADC12ENC =

1)

3. Re-enable conversion

ADC69 ADC Module

Category Functional

Function ADC stops operating if ADC clock source is changed from SMCLK to another source

while SMCLKOFF = 1.



www.ti.com Advisory Descriptions

Description

When SMCLK is used as the clock source for the ADC (ADC12CTL1.ADC12SSELx = 11) and CSCTL4.SMCLKOFF = 1, the ADC will stop operating if the ADC clock source is changed by user software (e.g. in the ISR) from SMCLK to a different clock source. This issue appears only for the ADC12CTL1.ADC12DIVx settings /3/5/7. The hang state can be recovered by PUC/POR/BOR/Power cycle.

Workaround

1. Set CSCTL4.SMCLKOFF = 0 before switch ADC clock source.

OR

2. Only use ADC12CTL1.ADC12DIVx as /1, /2, /4, /6, /8

AES1 AES Module

Category Functional

Function Ongoing AES operation cannot be aborted by writing to AESAXIN

Description Writing to AESAXIN register when AESASTAT.AESBUSY bit is set does abort the ongoing

AES operation or set the AESACTL0.AESERRFG bit.

Workaround Always let AES operation run to completion (i.e. do not abort). Ignore the encryption/

decryption output if AESAXIN is written when AESASTAT.AESBUSY is set.

AUXPMM2 AUXPMM Module

Category Functional

Function Latch-up in AUXPMM

Description Lat

Latch-up current can appear at the AUXPMM module supply pins in the following two scenarios:

Scenario 1: When the AUXPMM is configured for hardware- or software-controlled switching and the module switches from DVCC to AUXVCC2, latch-up current can appear at AUXVCC2 at the switching point defined by SVSMHCTL.SVSMHRRL (or AUXCTL2.AUX0LVLx). The probability for this event to occur depends on:

- a) Operating temperature (higher temperatures increase probability)
- b) External AUXVCC2 voltage level (higher voltages increase probability)
- c) SVSMHRRL level (lower levels increase probability) defining the switching level in hardware-controlled mode
- d) AUX0LVLx level (lower levels increase probability) defining the switching level in software-controlled mode (applicable to DVCC only)

Scenario 2: When a battery is connected to DVCC, AUXVCC1 or AUXVCC2 as the first voltage supply, due to the low internal resistance of the battery a very fast rise time is seen by the AUXPMM and latch-up current can appear at the connected supply if:

a) Rise times are in the range of 140 kV/s (faster rise times increase probability)

b) Device operates at temperatures of 75 deg C and above (higher temperatures increase probability)

The latch-up current disappears after complete power cycles of all supply sources.

Workaround

For scenario 1:

- Increase SVSMRRL to a level above maximum external voltage expected on AUXVCC2. SVSMRRL = 6 or 7 (requires VCORE level of 3) is applicable for AUXVCC2 of up to maximum voltage, 3.58V, while a lower SVSMRRL setting can be selected if a lower voltage (e.g. 3.3V) is expected on AUXVCC2.



Or

- Connect all 3 supplies via 3 external diodes to DVCC and realize the switching externally without using the internal AUXPMM switches. See application report "Implementation of a Three-Phase Electronic Watt-Hour Meter Using the MSP430F471xx" for details.

Or

- Use AUXVCC1 instead of AUXVCC2 for backup supply

For scenario 2:

Limit the supply voltage ramp up time through a series resistor (e.g. 10 Ohm) in the critical supply path. Side effects such as voltage dips due to high current consumption of the device need to be considered.

BSL7 BSL Module

Category Software in ROM

Function BSL does not start after waking up from LPMx.5

Description When waking up from LPMx.5 mode, the BSL does not start as it does not clear the Lock

I/O bit (LOCKLPM5 bit in PM5CTL0 register) on start-up.

Workaround 1. Upgrade the device BSL to the latest version (see Creating a Custom Flash-Based

Bootstrap Loader (BSL) Application Note - SLAA450 for more details)

OR

2. Do not use LOCKLPM5 bit (LPMx.5) if the BSL is used but cannot be upgraded.

BSL14 BSL Module

Category Software in ROM

Function BSL request to unlock the JTAG

Description The feature in the BSL to keep the JTAG unlocked by setting the bit

BSL_REQ_JTAG_OPEN in the return value has been disabled in this device.

Workaround None

COMP10 COMP Module

Category Functional

Function Comparator port output toggles when entering or leaving LPM3/LPM4

Description The comparator port pin output (CECTL1.CEOUT) erroneously toggles when device

enters or leaves LPM3/LPM4 modes under the following conditions:

1) Comparator is disabled (CECTL1.CEON = 0)

AND

2) Output polarity is enabled (CECTL1.CEOUTPOL = 1)

AND



3) The port pin is configured to have CEOUT functionality.

For example, if the CEOUT pin is high when the device is in Active Mode, CEOUT pin becomes low when the device enters LPM3/LPM4 modes.

Workaround

When the comparator is disabled, ensure at least one of the following:

1) Output inversion is disabled (CECTL.CEOUTPOL = 0)

OR

2) Change pin configuration from CEOUT to GPIO with output low.

CPU21

CPU Module

Category

Compiler-Fixed

Function

Using POPM instruction on Status register may result in device hang up

Description

When an active interrupt service request is pending and the POPM instruction is used to set the Status Register (SR) and initiate entry into a low power mode, the device may hang up.

Workaround

None. It is recommended not to use POPM instruction on the Status Register.

Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	Not affected	
TI MSP430 Compiler Tools (Code Composer Studio)	v4.0.x or later	User is required to add the compiler or assembler flag option below silicon_errata=CPU21
MSP430 GNU Compiler (MSP430-GCC)	MSP430-GCC 4.9 build 167 or later	

CPU22

CPU Module

Category

Compiler-Fixed

Function

Indirect addressing mode with the Program Counter as the source register may produce unexpected results

Description

When using the indirect addressing mode in an instruction with the Program Counter (PC) as the source operand, the instruction that follows immediately does not get executed. For example in the code below, the ADD instruction does not get executed.

mov @PC, R7 add #1h, R4

Workaround

Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	Not affected	



IDE/Compiler	Version Number	Notes
TI MSP430 Compiler Tools (Code Composer Studio)	v4.0.x or later	User is required to add the compiler or assembler flag option below silicon_errata=CPU22
MSP430 GNU Compiler (MSP430-GCC)	MSP430-GCC 4.9 build 167 or later	

CPU36 CPU Module

Category Functional

Function PC corruption when single-stepping through flash erase

Description When single-stepping over code that initiates an INFOD Flash memory erase, the

program counter is corrupted.

Workaround None.

NOTE: This erratum applies to debug mode only.

CPU37 CPU Module

Category Functional

Function Wrong program trace display in the debugger while using conditional jump instructions

Description The state storage window displays an incorrect sequence of instructions when:

1. Conditional jump instructions are used to form a software loop

AND

2. A false condition on the jump breaks out of the loop

In such cases the trace buffer incorrectly displays the first instruction of the loop as the instruction that is executed immediately after exiting the loop.

Example:

Actual Code: mov #4,R4

LABEL mov #1,R5

dec R4 jnz LABEL mov #2,R6 nop

State Storage Window Displays:

LABEL mov #1,R5

dec R4 jnz LABEL mov #1,R5 nop

Workaround None



Note: This erratum affects the trace buffer display only. It does not affect code execution in debugger or free run mode

CPU Module CPU₄0

Category Compiler-Fixed

Function PC is corrupted when executing jump/conditional jump instruction that is followed by

instruction with PC as destination register or a data section

Description If the value at the memory location immediately following a jump/conditional jump

> instruction is 0X40h or 0X50h (where X = don't care), which could either be an instruction opcode (for instructions like RRCM, RRAM, RLAM, RRUM) with PC as destination

register or a data section (const data in flash memory or data variable in

RAM), then the PC value is auto-incremented by 2 after the jump instruction is executed; therefore, branching to a wrong address location in code and leading to wrong program

For example, a conditional jump instruction followed by data section (0140h).

@0x8012 Loop DEC.W R6

@0x8014 DEC.W R7

@0x8016 JNZ Loop

@0x8018 Value1 DW 0140h

Workaround

In assembly, insert a NOP between the jump/conditional jump instruction and program code with instruction that contains PC as destination register or the data section.

Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	IAR EW430 v5.51 or later	For the command line version add the following information Compiler:hw_workaround=CPU40 Assembler:-v1
TI MSP430 Compiler Tools (Code Composer Studio)	v4.0.x or later	User is required to add the compiler or assembler flag option below silicon_errata=CPU40
MSP430 GNU Compiler (MSP430-GCC)	Not affected	

PU	Module
	PU

Category Functional

Function POPM peforms unexpected memory access and can cause VMAIFG to be set

Description When the POPM assembly instruction is executed, the last Stack Pointer increment is

> followed by an unintended read access to the memory. If this read access is performed on vacant memory, the VMAIFG will be set and can trigger the corresponding interrupt (SFRIE1.VMAIE) if it is enabled. This issue occurs if the POPM assembly instruction is

performed up to the top of the STACK.

Workaround If the user is utilizing C, they will not be impacted by this issue. All TI/IAR/GCC pre-built

libraries are not impacted by this bug. To ensure that POPM is never executed up to the



memory border of the STACK when using assembly it is recommended to either

- 1. Initialize the SP to
- a. TOP of STACK 4 bytes if POPM.A is used
- b. TOP of STACK 2 bytes if POPM.W is used

OR

2. Use the POPM instruction for all but the last restore operation. For the last restore operation use the POP assembly instruction instead.

For instance, instead of using:

POPM.W #5,R13

Use:

POPM.W #4,R12 POP.W R13

Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	Not affected	C code is not impacted by this bug. User using POPM instruction in assembler is required to implement the above workaround manually.
TI MSP430 Compiler Tools (Code Composer Studio)	Not affected	C code is not impacted by this bug. User using POPM instruction in assembler is required to implement the above workaround manually.
MSP430 GNU Compiler (MSP430-GCC)	Not affected	C code is not impacted by this bug. User using POPM instruction in assembler is required to implement the above workaround manually.

CPU47 CPU Module

Category

Functional

Function

An unexpected Vacant Memory Access Flag (VMAIFG) can be triggered

Description

An unexpected Vacant Memory Access Flag (VMAIFG) can be triggered, if a PC-modifying instruction (e.g. - ret, push, call, pop, jmp, br) is fetched from the last addresses (last 4 or 8 byte) of a memory (e.g.- FLASH, RAM, FRAM) that is not contiguous to a higher, valid section on the memory map.

In debug mode using breakpoints the last 8 bytes are affected.

In free running mode the last 4 bytes are affected.

www.ti.com Advisory Descriptions

Workaround

Workaround

Edit the linker command file to make the last 4 or 8 bytes of affected memory sections unavailable, to avoid PC-modifying instructions on these locations.

Remaining instructions or data can still be stored on these locations.

DMA4 DMA Module

Category Functional

Function Corrupted write access to 20-bit DMA registers

Description When a 20-bit wide write to a DMA address register (DMAxSA or DMAxDA) is interrupted

by a DMA transfer, the register contents may be unpredictable.

1. Design the application to guarantee that no DMA access interrupts 20-bit wide accesses to the DMA address registers.

OR

2. When accessing the DMA address registers, enable the Read Modify Write disable bit (DMARMWDIS = 1) or temporarily disable all active DMA channels (DMAEN = 0).

OR

3. Use word access for accessing the DMA address registers. Note that this limits the values that can be written to the address registers to 16-bit values (lower 64K of Flash).

DMA7 DMA Module

Category Functional

Function DMA request may cause the loss of interrupts

Description If a DMA request starts executing during the time when a module register containing an

interrupt flags is accessed with a read-modify-write instruction, a newly arriving interrupt from the same module can get lost. An interrupt flag set prior to DMA execution would not

be affected and remain set.

Workaround

1. Use a read of Interrupt Vector registers to clear interrupt flags and do not use read-

modify-write instruction.

OR

2. Disable all DMA channels during read-modify-write instruction of specific module

registers containing interrupts flags while these interrupts are activated.

DMA9 DMA Module

Category Functional

Function DMA stops transferring bytes unexpectedly

Description When the DMA is configured to transfer bytes from the eUSCI A or eUSCI B transmit

or receive buffers, the transmit or receive triggers (TXIFG and RXIFG) may not be seen by the DMA module and the transfer of the bytes is missed. Once the first byte in a transfer sequence is missed, all the following bytes are missed as well. All eUSCI_A modes (UART, SPI, and IrDA) and all eUSCI_B modes (SPI and I2C) are affected.



Workaround

1) Use Interrupt Service Routines to transfer data to and from the eUSCI_A or eUSCI_B. OR

2) When using DMA channel 0 for transferring data to and from the eUSCI_A or eUSCI_B, use DMA channel 2 (lower priority than DMA channel 0) to read the same register of the eUSCI_A or eUSCI_B that DMA channel 0 is working with. Use the same USCI IFG (e.g. UCA0RXIFG) as trigger source for these both DMA channels.

DMA10 DMA Module

Category Functional

Function DMA access may cause invalid module operation

DescriptionThe peripheral modules MPY, CRC, USB, RF1A and FRAM controller in manual mode

can stall the CPU by issuing wait states while in operation. If a DMA access to the module occurs while that module is issuing a wait state, the module may exhibit undefined

behavior.

Workaround Ensure that DMA accesses to the affected modules occur only when the modules are

not in operation. For example with the MPY module, ensure that the MPY operation is

completed before triggering a DMA access to the MPY module.

EEM17 EEM Module

Category Debug

Function Wrong Breakpoint halt after executing Flash Erase/Write instructions

Description Hardware breakpoints or Conditional Address triggered breakpoints on instructions that

follow Flash Erase/Write instructions, stops the debugger at the actual Flash Erase/Write instruction even though the flash erase/write operation has already been executed. The hardware/conditional address triggered breakpoints that are placed on either the next two single opcode instructions OR the next double opcode instruction that follows the Flash

Erase/Write instruction are affected by this erratum.

Workaround None. Use other conditional/advanced triggered breakpoints to halt the debugger right

after Flash erase/write instructions.

Note

This erratum affects debug mode only.

EEM19 EEM Module

Category Debug

Function DMA may corrupt data in debug mode

Description When the DMA is enabled and the device is in debug mode, the data written by the DMA

may be corrupted when a breakpoint is hit or when the debug session is halted.

Workaround This erratum has been addressed in MSPDebugStack version 3.5.0.1. It is also available

in released IDE EW430 IAR version 6.30.3 and CCS version 6.1.1 or newer.

If using an earlier version of either IDE or MSPDebugStack, do not halt or use breakpoints

during a DMA transfer.



Note

This erratum applies to debug mode only.

EEM23 EEM Module

Category Debug

Function EEM triggers incorrectly when modules using wait states are enabled

Description When modules using wait states (USB, MPY, CRC and FRAM controller in manual mode)

are enabled, the EEM may trigger incorrectly. This can lead to an incorrect profile counter value or cause issues with the EEMs data watch point, state storage, and breakpoint

functionality.

Workaround None.

Note

This erratum affects debug mode only.

JTAG26 JTAG Module

Category Debug

Function LPMx.5 Debug Support Limitations

Description

The JTAG connection to the device might fail at device-dependent low or high supply voltage levels if the LPMx.5 debug support feature is enabled. To avoid a potentially unreliable debug session or general issues with JTAG device connectivity and the resulting bad customer experience Texas Instruments has chosen to remove the LPMx.5 debug support feature from common MSP430 IDEs including TIs Code Composer Studio 6.1.0 with msp430.emu updated to version 6.1.0.7 and IARs Embedded Workbench 6.30.2, which are based on the MSP430 debug stack MSP430.DLL 3.5.0.1 http://www.ti.com/tool/MSPDS

TI plans to re-introduce this feature in limited capacity in a future release of the debug stack by providing an IDE override option for customers to selectively re-activate LPMx.5 debug support if needed. Note that the limitations and supply voltage dependencies outlined in this erratum will continue to apply.

For additional information on how the LPMx.5 debug support is handled within the MSP430 IDEs including possible workarounds on how to debug applications using LPMx.5 without toolchain support refer to Code Composer Studio User's Guide for MSP430 chapter F.4 and IAR Embedded Workbench User's Guide for MSP430 chapter 2.2.5.

Workaround

- 1. If LPMx.5 debug support is deemed functional and required in a given scenario:
- a) Do not update the IDE to continue using a previous version of the debug stack such as MSP430.DLL v3.4.3.4.

OR

b) Roll back the debug stack by either performing a clean re-installation of a previous version of the IDE or by manually replacing the debug stack with a prior version such as MSP430.DLL v3.4.3.4 that can be obtained from http://www.ti.com/tool/MSPDS.

Workaround



2. In case JTAG connectivity fails during the LPMx.5 debug mode, the device supply voltage level needs to be raised or lowered until the connection is working.

Do not enable the LPMx.5 debug support feature during production programming.

JTAG Module JTAG27

Category Debug

Function Unintentional code execution after programming via JTAG/SBW

The device can unintentionally start executing code from uninitialized RAM addresses **Description** 0x0006 or 0x0008 after being programming via the JTAG or SBW interface. This can result in unpredictable behavior depending on the contents of the address location.

> 1. If using programming tools purchased from TI (MSP-FET, LaunchPad), update to CCS version 6.1.3 later or IAR version 6.30 or later to resolve the issue.

2. If using the MSP-GANG Production Programmer, use v1.2.3.0 or later.

3. For custom programming solutions refer to the specification on MSP430 Programming Via the JTAG Interface User's Guide (SLAU320) revision V or newer and use MSPDebugStack v3.7.0.12 or later.

For MSPDebugStack (MSP430.DLL) in CCS or IAR, download the latest version of the development environment or the latest version of the MSPDebugStack

NOTE: This only affects debug mode.'

LCDB Module LCDB6

Category Functional

Function LCD outputs may be corrupted by modifying register fields VLCDx and/or LCDCPEN of

LCDCVCTL register while LCDON (LCDCCTL0) is set

Description Writing to VLCDx and/or LCDCPEN register bits in LCDCVCTL register while LCDC

is enabled (LCDON = '1' in LCDCCTL0 register) may corrupt the LCD output due to

incorrect start-up of LCD-controller and internal voltage generation.

Workaround Do not modify VLCDx and/or LCDCPEN bits in LCDCVCTL register while LCDON = '1'

PMM Module

Category Functional

Function MCLK comes up fast on exit from LPM3 and LPM4

Description The DCO exceeds the programmed frequency of operation on exit from LPM3 and LPM4 for up to 6 us. This behavior is masked from affecting code execution by default:

SVSL and SVML run in normal-performance mode and mask CPU execution for 150 us on wakeup from LPM3 and LPM4. However ,when the low-side SVS and the SVM are disabled or are operating in full-performance mode (SVMLE= 0 and SVSLE= 0, or SVMLFP= 1 and SVSLFP= 1) AND MCLK is sourced from the internal DCO running over 4 MHz, 7 MHz,11 MHz,or 14 MHz at core voltage levels 0, 1, 2, and 3, respectively, the mask lasts only 2 us. MCLK is, therefore, susceptible to run out of spec for 4 us.

PMM11

www.ti.com Advisory Descriptions

Workaround

Set the MCLK divide bits in the Unified Clock System Control 5 Register (UCSCTL5) to divide MCLK by two prior to entering LPM3 or LPM4 (set DIVMx= 001). This prevents MCLK from running out of spec when the CPU wakes from the low-power mode. Following the wakeup fromthe low-power mode, wait 32, 48, 80, or 100 cycles for core voltage levels 0, 1, 2, and 3, respectively, before resetting DIVM xto zero and running MCLK at full speed [for example, __delay_cycles(100)]

PMM12 PMM Module

Category Functional

Function SMCLK comesup fast on exit from LPM3 and LPM4

Description The DCO exceeds the programmed frequency of operationon exit from LPM3 and LPM4

for up to 6 us. When SMCLK is sourced by the DCO, it is not masked on exit from LPM3 or LPM4. Therefore, SMCLK exceeds the programmed frequency of operation on exit from LPM3 and LPM4 for up to 6 us. The increased frequency has the potential to change the expected timing behavior of peripherals that select SMCLK as the clock source.

Workaround - Use XT2 as the SMCLK oscillator source instead of the DCO

or

- Do not disable the clock request bit for SMCLKREQEN in the Unified Clock System Control 8 Register (UCSCTL8). This means that all modules that depend on SMCLK to operate successfully should be halted or disabled before entering LPM3 or LPM4. If the increased frequency prevents the proper function of an affected module, wait 32, 48, 80 or 100 cycles for core voltage levels 0, 1, 2, or 3, respectively, before re-enabling the module. (for example, __delay_cycles(100)

PMM14 PMM Module

Category Functional

Function Increasing the core level when SVS/SVM low side is configured in full-performance mode

causes device reset

Description When the SVS/SVM low side is configured in full performance mode

(SVSMLCTL.SVSLFP = 1), the setting time delay for the SVS comparators is ~2us. When increasing the core level in full-performance mode; the core voltage does not settle to the new level before the settling time delay of the SVS/SVM comparator expires. This results

in a device reset.

Workaround When increasing the core level; enable the SVS/SVM low side in normal mode

(SVSMLCTL.SVSLFP=0). This provides a settling time delay of approximately 150us allowing the core sufficient time to increase to the expected voltage before the delay

expires.

PMM15 PMM Module

Category Functional

Function Device may not wake up from LPM2, LPM3, or LPM4

DescriptionDevice may not wake up from LPM2, LPM3 or LMP4 if an interrupt occurs within 1

us after the entry to the specified LPMx; entry can be caused either by user code or automatically (for example, after a previous ISR is completed). Device can be recovered

Advisory Descriptions www.ti.com

> with an external reset or a power cycle. Additionally, a PUC can also be used to reset the failing condition and bring the device back to normal operation (for example, a PUC caused by the WDT).

This effect is seen when:

- A write to the SVSMHCTL and SVSMLCTL registers is immediately followed by an LPM2, LPM3, LPM4 entry without waiting the requisite settling time ((PMMIFG.SVSMLDLYIFG = 0 and PMMIFG.SVSMHDLYIFG = 0)).

or

The following two conditions are met:

- The SVSL module is configured for a fast wake-up or when the SVSL/SVML module is turned off. The affected SVSMLCTL register settings are shaded in the following table.

	SVSLE	SVSLMD	SVSLFP	AM, LPM0/1 SVSL state	Manual SVSMLACE = 0 LPM2/3/4 SVSL State	Automatic SVSMLACE = 1 LPM2/3/4 SVSL State	Wakeup Time LPM2/3/4
SVSL	0	X	Х	OFF	OFF	OFF	twake-up fast
	1	0	0	Normal	OFF	OFF	twake-up slow
	1	0	1	Full Performance	OFF	OFF	twake-up fast
	1	1	0	Normal	Normal	OFF	twake-up slow
	1	1	1	Full Performance	Full Performance	Normal	twake-up fast
SVML	SVMLE	SVMLFP		AM, LPM0/1 SVML state	Manual SVSMLACE = 0 LPM2/3/4 SVML State	Automatic SVSMLACE = 1 LPM2/3/4 SVML State	Wakeup Time LPM2/3/4
	0	X		OFF	OFF	OFF	twake-up fast
	1	0		Normal	Normal	OFF	twake-up slow
	1	1		Full Performance	Full Performance	Normal	twake-up fast

and

-The SVSH/SVMH module is configured to transition from Normal mode to an OFF state when moving from Active/LPM0/LPM1 into LPM2/LPM3/LPM4 modes. The affected SVSMHCTL register settings are shaded in the following table.

	SVSHE	SVSHMD	SVSHFP	AM, LPM0/1 SVSH state	Manual SVSMHACE = 0 LPM2/3/4 SVSH State	Automatic SVSMHACE = 1 LPM2/3/4 SVSH State
	0	х	х	OFF	OFF	OFF
SVSH	1	0	0	Normal	OFF	OFF
	1	0	1	Full Performance	OFF	OFF
	1	1	0	Normal	Normal	OFF
	1	1	1	Full Performance	Full Performance	Normal
	SVMHE	CVB		AM, LPM0/1 SVMH	Manual SVSMHACE = 0	Automatic SVSMHACE = 1
	SVIVIHE	SVIV	MHFP state	state	LPM2/3/4 SVMH State	LPM2/3/4 SVMH State
SVMH	0	,	(OFF	OFF	OFF
	1	0		Normal	Normal	OFF
	1	1	ı	Full Performance	Full Performance	Normal

Workaround

Any write to the SVSMxCTL register must be followed by a settling delay (PMMIFG.SVSMLDLYIFG = 0 and PMMIFG.SVSMHDLYIFG = 0) before entering LPM2, LPM3, LPM4.

and

1. Ensure the SVSx, SVMx are configured to prevent the issue from occurring by the



following:

- Configure the SVSL module for slow wake up (SVSLFP = 0). Note that this will increase the wakeup time from LPM2/3/4 to twakeupslow (~150 us).

or

- Do not configure the SVSH/SVMH such that the modules transition from Normal mode to an OFF state on LPM entry and ensure SVSH/SVMH is in manual mode. Instead force the modules to remain ON even in LPMx. Note that this will cause increased power consumption when in LPMx.

Refer to the MSP430 Driver Library(MSPDRIVERLIB) for proper PMM configuration functions.

Use the following function, PMM15Check (void), to determine whether or not the existing PMM configuration is affected by the erratum. The return value of the function is 1 if the configuration is affected, and 0 if the configuration is not affected.

```
unsigned char PMM15Check (void)
{
// First check if SVSL/SVML is configured for fast wake-up
if ( (!(SVSMLCTL & SVSLE)) || ((SVSMLCTL & SVSLE) && (SVSMLCTL & SVSLFP)) ||
(!(SVSMLCTL & SVMLE)) || ((SVSMLCTL & SVMLE) && (SVSMLCTL & SVMLFP))) |
{
// Next Check SVSH/SVMH settings to see if settings are affected by PMM15
if ((SVSMHCTL & SVSHE) && (!(SVSMHCTL & SVSHFP)))
{
if ( (!(SVSMHCTL & SVSHMD)) || ((SVSMHCTL & SVSHMD) &&
(SVSMHCTL & SVSMHACE)) )
return 1; // SVSH affected configurations
}
if ((SVSMHCTL & SVMHE) && (!(SVSMHCTL & SVMHFP)) && (SVSMHCTL &
SVSMHACE))
return 1; // SVMH affected configurations
}
return 0; // SVS/M settings not affected by PMM15
}
```

2. If fast servicing of interrupts is required, add a 150us delay either in the interrupt service routine or before entry into LPM3/LPM4.

PMM18 PMM Module

Category

Functional

Function

PMM supply overvoltage protection falsely triggers POR

Description

The PMM Supply Voltage Monitor (SVM) high side can be configured as overvoltage protection (OVP) using the SVMHOVPE bit of SVSMHCTL register. In this mode a POR should typically be triggered when DVCC reaches ~3.75V.

If the OVP feature of SVM high side is enabled going into LPM234, the SVM might trigger at DVCC voltages below 3.6V (~3.5V) within a few ns after wake-up. This can falsely cause an OVP-triggered POR. The OVP level is temperature sensitive during fail scenario and decreases with higher temperature (85 degC ~3.2V).

Workaround

Use automatic control mode for high-side SVS & SVM (SVSMHCTL.SVSMHACE=1). The SVM high side is inactive in LPM2, LPM3, and LPM4.

PMM Module **PMM20**

Category **Functional**

Function Unexpected SVSL/SVML event during wakeup from LPM2/3/4 in fast wakeup mode

Description If PMM low side is configured to operate in fast wakeup mode, during wakeup from LPM2/3/4 the internal VCORE voltage can experience voltage drop below the corresponding SVSL and SVML threshold (recommendation according to User's Guide)

leading to an unexpected SVSL/SVML event. Depending on PMM configuration, this

event triggers a POR or an interrupt.

Note

As soon the SVSL or the SVML is enabled in Normal performance mode the device is in slow wakeup mode and this erratum does not apply. In addition, this erratum has sporadic characteristic due to an internal asynchronous circuit. The drop of Vcore does not have an impact on specified device performance.

Workaround

If SVSL or SVML is required for application (to observe external disruptive events at Vcore pin) the slow wakeup mode has to be used to avoid unexpected SVSL/SVML events. This is achieved if the SVSL or the SVML is configured in "Normal" performance mode (not disabled and not in "Full" Performance Mode).

PMM Module **PMM26**

Category **Functional**

Function Device lock-up if RST pin pulled low during write to SVSMHCTL or SVSMLCTL

Description Device results in lock-up condition under one of the two scenarios below:

> 1) If RST pin is pulled low during write access to SVSMHCTL, with the RST/NMI pin is configured to reset function and is pulled low (reset event) the device will stop code execution and is continuously held in reset state. RST pin is no longer functional. The only way to come out of the lock-up situation is a power cycle.

2) If RST pin is pulled low during write access to SVSMLCTL and only if the code that checks for SVSMLDLYIFG==1 is implemented without a timeout. The device will be stuck in the polling loop polling since SVSMLDLYIFG will never be cleared.

Workaround

Follow the sequence below to prevent the lock-up for both use cases:

1) Disable RST pin reset function and switch to NMI before access SVSMHCTL or SVSMLCTL.

then

OR

2) Activate NMI interrupt and handle reset events in this time by SW (optional if reset functionality required during access SVSMHCTL or SVSMLCTL)

3) Enable RST pin reset function after access to SVSMHCTL or SVSMLCTL

To prevent lock-up caused by use case #2 a timeout for the SVSMLDLYIFG flag check should be implemented to 300us.

PORT Module PORT15



www.ti.com Advisory Descriptions

Category Functional

Function In-system debugging causes the PMALOCKED bit to be always set

Description The port mapping controller registers cannot be modified when single-stepping or halting

at break points between a valid password write to the PMAPWD register and the expected lock of the port mapping (PMAP) registers. This causes the PMAPLOCKED bit to remain

set and not clear as expected.

Note: This erratum only applies to in-system debugging and is not applicable when

operating in free-running mode.

Workaround Do not single step through or place break points in the port mapping configuration section

of code.

PORT19 PORT Module

Category Functional

Function Port interrupt may be missed on entry to LPMx.5

Description If a port interrupt occurs within a small timing window (~1MCLK cycle) of the device entry

into LPM3.5 or LPM4.5, it is possible that the interrupt is lost. Hence this interrupt will not

trigger a wakeup from LPMx.5.

Workaround None

PORT26 PORT Module

Category Functional

Function Incorrect values for P1.1 / P1.2 input pins during power-up

Description If P1.1/P1.2 is pulled up externally to DVCC during power-up the logical HIGH value might

not be read correct by the device (ZERO is read instead of ONE).

Workaround 1) Switch the P1.1/P1.2 Port to logical ZERO after power cycle by:

a) Switch critical GPIO to output-low (with series resistance to limit current) or

b) Remove external pull up connection to pull GPIO via internal pull-down

OR

2) Use different GPIOs (not P1.1 & P1.2)

OR

3) Change the polarity of the logical check in SW (enable internal pull-up resistor for the

GPIO and pull the external pin to DVSS)

SD3 SD Module

Category Functional

Function Incorrect conversion result in twos complement mode when -VFS is applied

Description When the SD converter is configured in twos complement mode with left or right

alignment and any OSR setting, applying the -VFS voltage at the input will result in an

erroneous output.



Workaround None.

SYS16 SYS Module

Category Functional

Function Fast Vcc ramp after device power up may cause a reset

Description At initial power-up, after Vcc crosses the brownout threshold and reaches a constant

level, an abrupt ramp of Vcc at a rate dV/dT > 1V/100us can cause a brownout condition to be incorrectly detected even though Vcc does not fall below the brownout threshold.

This causes the device to undergo a reset.

Workaround Use a controlled Vcc ramp to power up the device.

UCS11 UCS Module

Category Functional

Function Modifying UCSCTL4 clock control register triggers an additional erroneous clock request

Description Changing the SELM/SELS/SELA bits in the UCSCTL4 register will correctly configure the

respective clock to use the intended clock source but might also erroneously set XT1/XT2 fault flag if the crystals are not present at XT1/XT2 or not configured in the application firmware. If the NMI interrupt for the OFIFG is enabled, an unintentional NMI interrupt will

be triggered and needs to be handled.

Note

The XT1/XT2 fault flag can be set regardless of which SELM/SELS/SELA bit combinations are being changed.

Workaround Clear all the fault flags in UCSCTL7 register once after changing any of the SELM/SELS/

SELA bits in the UCSCTL4 register.

If OFIFG-NMI is enabled during clock switching, disable OFIFG-NMI interrupt during changing the SELM/SELS/SELA bits in the UCSCTL4 register to prevent unintended NMI. Alternatively it can be handled accordingly (clear falsely set fault flags) in the Interrupt

Service Routine to ensure proper OFIFG clearing.

USCI36 USCI Module

Category Functional

Function UCLKI not usable in I2C master mode

Description When EUSCIB is configured as I2C Master with the external UCLKI as clock source, the

UCLKI signal is not available and cannot be used to source I2C clock.

Workaround Use LFXTCLK via ACLK or HFXTCLK via SMCLK as clock source (BRCLK) for I2C in

master mode with external clock source.

USCI37 USCI Module

Category Functional

Function Reading RXBUF during an active I2C communication might result in unintended bus

stalls.

www.ti.com Advisory Descriptions

Description

The falling edge of SCL bus line is used to set an internal RXBUF-written flag register, which is used to detect a potential RXBUF overflow. If this flag is cleared with a read access from the RXBUF register during a falling edge of SCL, the clear condition might be missed. This could result in an I2C bus stall at the next received byte.

Workaround

(1) Execute two consecutive reads of RXBUF, if t_{SCL} > 4 x t_{MCLK}.

or

(2) Provoke an I2C bus stall before reading RXBUF. A bus stall can be verified by checking if the clock line low status indicator bit UCSCLLOW is set for at least three USCI bit clock cycles i.e. 3 x t_{BitClock}.

USCI41

USCI Module

Category

Functional

Function

UCBUSY bit of eUSCIA module might not work reliable when device is in SPI mode.

Description

When eUSCIA is configured in SPI mode, the UCBUSY bit might get stuck to 1 or start toggling after transmission is completed. This happens in all four combinations of Clock Phase and Clock Polarity options (UCAxCTLW0.UCCKPH & UCAxCTLW0.UCCKPL bits) as well as in Master and Slave mode. There is no data loss or corruption. However the UCBUSY cannot be used in its intended function to check if transmission is completed. Because the UCBUSY bit is stuck to 1 or toggles, the clock request stays enabled and this adds additional current consumption in low power mode operation.

Workaround

For correct functional implementation check on transmit or receive interrupt flag UCTXIFG/UCRXIFG instead of UCBUSY to know if the UCAxTXBUF buffer is empty or ready for the next complete character.

To reduce the additional current it is recommended to either reset the SPI module (UCAxCTLW0.UCSWRST) in the UCBxCTLW0 or send a dummy byte 0x00 after the intended SPI transmission is completed.

USCI42

USCI Module

Category

Functional

Function

UART asserts UCTXCPTIFG after each byte in multi-byte transmission

Description

UCTXCPTIFG flag is triggered at the last stop bit of every UART byte transmission, independently of an empty buffer, when transmitting multiple byte sequences via UART.

The erroneous UART behavior occurs with and without DMA transfer.

Workaround

None.

USCI47

USCI Module

Category

Functional

Function

eUSCI SPI slave with clock phase UCCKPH = 1

Description

The eUSCI SPI operates incorrectly under the following conditions:

1. The eUSCI A or eUSCI B module is configured as a SPI slave with clock phase mode UCCKPH = 1

AND



2. The SPI clock pin is not at the appropriate idle level (low for UCCKPL = 0, high for UCCKPL = 1) when the UCSWRST bit in the UCxxCTLW0 register is cleared.

If both of the above conditions are satisfied, then the following will occur: eUSCI_A: the SPI will not be able to receive a byte (UCAxRXBUF will not be filled and UCRXIFG will not be set) and SPI slave output data will be wrong (first bit will be missed and data will be shifted).

eUSCI_B: the SPI receives data correctly but the SPI slave output data will be wrong (first byte will be duplicated or replaced by second byte).

Workaround

Use clock phase mode UCCKPH = 0 for MSP SPI slave if allowed by the application.

OR

The SPI master must set the clock pin at the appropriate idle level (low for UCCKPL = 0, high for UCCKPL = 1) before SPI slave is reset (UCSWRST bit is cleared).

OR

For eUSCI_A: to detect communication failure condition where UCRXIFG is not set, check both UCRXIFG and UCTXIFG. If UCTXIFG is set twice but UCRXIFG is not set, reset the MSP SPI slave by setting and then clearing the UCSWRST bit, and inform the SPI master to resend the data.

USCI50 USCI Module

Category

Functional

Function

Data may not be transmitted correctly from the eUSCI when operating in SPI 4-pin master mode with UCSTEM = 0

Description

When the eUSCI is used in SPI 4-pin master mode with UCSTEM = 0 (STE pin used as an input to prevent conflicts with other SPI masters), data that is moved into UCxTXBUF while the UCxSTE input is in the inactive state may not be transmitted correctly. If the eUSCI is used with UCSTEM = 1 (STE pin used to output an enable signal), data is transmitted correctly.

Workaround

When using the STE pin in conflict prevention mode (UCSTEM = 0), only move data into UCxTXBUF when UCxSTE is in the active state. If an active transfer is aborted by UCxSTE transitioning to the master-inactive state, the data must be rewritten into UCxTXBUF to be transferred when UCxSTE transitions back to the master-active state.

www.ti.com Revision History

7 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from	April 24, 2019 to May 19, 2021	

Page

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2022, Texas Instruments Incorporated