The PGA411-Q1 EVM allows users to evaluate the functionality of the PGA411-Q1 device. This user's guide describes both the hardware platform containing a sample PGA411-Q1 device, and the graphical user interface (GUI) software used to configure the functionality and diagnostics on the PGA411-Q1 resolver-to-digital interface IC. In addition to evaluating the PGA411-Q1 device, the other objective of this board is to display in the GUI the position (angle) or velocity readings from a resolver sensor.

This document also includes the EVM schematics, bill of materials, and PCB layout.

NOTE: Texas Instruments recommends using the PGA411-Q1 EVM user's guide (this document) after reading and following the steps listed in the PGA411-Q1 Evaluation Module Quick Start Guide. To download this guide, go to the product folder: www.ti.com/product/PGA411-Q1.

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1 Introduction

The PGA411-Q1 evaluation module (EVM) is a board designed for the evaluation of the PGA411-Q1 resolver-to-digital interface IC from Texas Instruments. The PGA411-Q1 EVM incorporates all required circuitry and components with the following features:

- PGA411-Q1 resolver-to-digital interface with power supply & amp
- Texas Instruments' MSP430™ microcontroller used for controlling the PGA411-Q1 device through the I/O pins and a SPI port in addition to receiving digital data in different formats
- Voltage LDO regulator, TI's TLV716P, to provide configurable V_{IO} voltages (3.3 V or 1.8 V)
- Voltage LDO regulator, TI's TPS735, for the 3.3-V MSP430
- Circuitry for interfacing general resolver sensors
- 20-MHz XTAL as PGA411-Q1 single reference clock
- Multiple test points for main analog and digital signals
- UART, JTAG, and USB connectors

Figure 1 shows the PGA411-Q1 EVM architecture, where the key components and blocks previously listed can be identified.

2 Setup and Operation

2.1 Required Equipment for Device Evaluation

The following elements are required for proper operation and to receive consistent results with this user's guide:

- A single power supply that is capable of 5-V operation and a minimum current of 0.5 A
- A computer with Windows® XP or Windows 7 and .net Framework 4.0 or later
- The PGA411-Q1 GUI
- A resolver sensor connected to the correct ports. Refer to the resolver data sheet for more information.

2.2 Initial EVM Setup

2.2.1 Installing Graphical User Interface Software

Before the PGA411-Q1 device can be evaluated the GUI software must be available on a host computer. Run the GUI installer and place the executable file in a convenient location (Desktop or c:\Texas Instruments EVM) and double click to run the application.

To download the PGA411-Q1 GUI go to www.ti.com/product/PGA411-Q1.
2.2.2 Set-Up Instructions

For set-up instructions, refer to Figure 2.

![Figure 2. PGA411-Q1 EVM](image)

**WARNING**

This EVM contains components that are sensitive to Electrostatic Discharge (ESD). Use proper laboratory techniques and equipment to minimize the chance of an ESD or EOS event.

Step 1. Set up EVM jumpers as follows:

- Confirm the J3 jumper settings (3-4) for 3.3-V VIO. This step is required for proper operation with the MSP430 device.
- Confirm the J5 jumper settings (3-5 and 4-6) to connect the exciter outputs (OEx pins) to the IEx input pins. The tracking loop inside the PGA411-Q1 device must sense the exciter outputs.
- Confirm that the J2 jumper is present to connect the internal boost supply to the supply input of the integrated exciter amplifier (VEXT).

**NOTE:** Using the integrated boost supply for the exciter amplifier is strongly recommended.

Step 2. Apply the 5-V supply to the banana connectors for \( V_{cc} \) and GND.
Step 3. Connect the USB cable to the EVM and to the PC.

**NOTE:** Power, as described in **Step 2**, must be applied before connecting the USB.

Step 4. Verify that the LED USB_RDY (D12) is on, ensuring a good connection. If it is blinking or off, unplug and replug the USB cable, and press the MCU reset, MCU_RST (S4).

Step 5. Launch the PGA411-Q1 GUI.

Step 6. Wait a few seconds after the GUI welcome screen appears. The first view should be of a block diagram which is a high level representation of the PGA411-Q1 resolver-to-digital interface and contains interactive features. The red boxes indicate controls that can be used to configure internal blocks inside the PGA411-Q1 device.

If the connection is successful, the **Connection Status** field displays **Connected** and a revision number is displayed in the **PGA411-Q1 Device** field as shown in **Figure 3**. If the connection process failed, press the S4 switch on the EVM and then press the **Reset** button in the upper left corner of the GUI (see **Figure 3**) to restart the connection.

![Figure 3. PGA411-Q1 GUI Block Diagram](image)

**NOTE:** Follow the start-up procedure carefully and ensure that board connections are correct. The power must be applied before the USB cable is plugged in. The USB_RDY LED close to the MSP430 controller should remain on continuously after connecting the USB cable and should not blink. If the device does not power up properly, the EVM status field in the GUI will display: **PGA41x-Q1 Device: Not Available** as shown in **Figure 4**. If this occurs, turn off the 5-V power supply, unplug the USB cable, and go back to **Step 2**.

![Figure 4. PGA411-Q1 Device Startup Failed](image)
2.2.2.1 EVM Switches and Jumpers Settings

Refer to Figure 2 for the locations of the switches and jumpers on the PGA411-Q1 EVM.

Table 1 lists the descriptions of the EVM switches. Table 2 lists the descriptions of the EVM jumpers.

### Table 1. Description of EVM Switches

<table>
<thead>
<tr>
<th>Switch (SW)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>S1</td>
<td>Voltage divider</td>
</tr>
<tr>
<td></td>
<td>0: This position is the default and selects the prepopulated IZx resistive divider (30 kΩ / 30 kΩ).</td>
</tr>
<tr>
<td></td>
<td>1: This position selects the user-populated IZx resistive divider (30 kΩ / external resistor value).</td>
</tr>
<tr>
<td>S2</td>
<td>Fault reset</td>
</tr>
<tr>
<td></td>
<td>This switch pulls the FAULTRES pin low when pressed. When this switch is pressed and then released, all faults from the PGA411 device are cleared.</td>
</tr>
<tr>
<td>S3</td>
<td>Device reset</td>
</tr>
<tr>
<td></td>
<td>This switch pulls the NRST pin low. This action resets the PGA411-Q1 device.</td>
</tr>
<tr>
<td>S4</td>
<td>MSP430 BSL</td>
</tr>
<tr>
<td></td>
<td>This switch resets the MSP430 microcontroller. The firmware is reloaded.</td>
</tr>
</tbody>
</table>

### Table 2. Description of EVM Jumpers

<table>
<thead>
<tr>
<th>Jumper No.</th>
<th>Function</th>
<th>State</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>J2</td>
<td>VEXT Jumper</td>
<td>Open</td>
<td>Disconnect VEXT from boost output</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Closed (Default)</td>
<td>Connect VEXT to boost output</td>
</tr>
<tr>
<td>J3</td>
<td>VIO SELECT</td>
<td>1-2</td>
<td>Do not use</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3-4 (Default)</td>
<td>VIO = 3.3 V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>5-6</td>
<td>VIO = VCC (5 V), Do not use with current EVM version. This mode is to interface PGA411-Q1 device with external microcontrollers.</td>
</tr>
<tr>
<td>J4</td>
<td>OEx Terminal</td>
<td>Pin 1</td>
<td>Exciter output 1 to resolver (OE1)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Pin 2</td>
<td>Exciter output 2 to resolver (OE2)</td>
</tr>
<tr>
<td>J5</td>
<td>OEx to IEx</td>
<td>3-5 (Default)</td>
<td>Connect OE1 to IE1 through voltage divider</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4-6 (Default)</td>
<td>Connect OE2 to IE2 through voltage divider</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other combinations</td>
<td>Do not use</td>
</tr>
<tr>
<td>J6</td>
<td>COS IZx terminal</td>
<td>Pin 1</td>
<td>Input to IZ1 external filter</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Pin 2</td>
<td>Input to IZ3 external filter</td>
</tr>
<tr>
<td>J7</td>
<td>SIN IZx terminal</td>
<td>Pin 1</td>
<td>Input to IZ2 external filter</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Pin 2</td>
<td>Input to IZ4 external filter</td>
</tr>
<tr>
<td>J10</td>
<td>Analog Connector</td>
<td>—</td>
<td>Header for analog signals</td>
</tr>
<tr>
<td>J11</td>
<td>Digital Connector</td>
<td>—</td>
<td>Header for digital signals</td>
</tr>
<tr>
<td>J15</td>
<td>USB Connector</td>
<td>—</td>
<td>Connector for USB cable</td>
</tr>
</tbody>
</table>
2.3 GUI Software

2.3.1 PGA41x-Q1 GUI Main Screen

Figure 5 shows the default starting screen of the PGA41x-Q1 GUI. If the EVM is connected properly, the screen should display the values that follow for the EVM Status fields, as described in Step 5 in Section 2.2.2:

- USB Controller: USB2ANY I/F Found
- USB Firmware: 2.6.5.53 (this value is designed for Revision B of the EVM) (1)
- Connection Status: Connected
- PGA41x-Q1 Device: Revision: v10.1

The default GUI view is the block diagram of the PGA411-Q1 resolver-to-digital interface IC and contains interactive features. All boxes in red, as shown in Figure 5, are controls that can be configured. These boxes indicate the default values of the PGA411-Q1 device after power on. The configurable elements in this block diagram include:

- Internal boost voltage control
  - Boost output voltage from 10 to 17 V
- Exciter amplifier
  - Exciter frequency (10 to 20 kHz)
  - Exciter amplitude (4 V_{RMS} or 7 V_{RMS})
  - Exciter amplifier gain (1.15 to 1.9 V/V)
  - Common-mode offset (0.5 to 2 V)

Use a scope probe on the test points next to exciter connection, J4, to view changes to these blocks instantaneously. The optimum values depend on the characteristics of the resolver sensor that is used.

- Analog front end (AFE)
  - COS gain and SIN gain from 0.75 to 3.5 V/V.
  - Diagnostic values for detection thresholds on the AFE amplifiers. These values include both the high and low thresholds.

The optimum AFE settings depend on the signal levels from the resolver outputs (sine and cosine). Observe these signals on the test points next to the J6 and J7 jumpers when configuring the AFE.

**NOTE:** Both gains must match to achieve better accuracy on the angle estimation.

- **Read Angle** button
  When pressed, the angle (in degrees) is displayed, if the resolver sensor is rotated and read again, the value should update.

- BMODE0 which is the control bit for 10-bit and 12-bit modes
  Higher precision is achieved by changing the resolution from 10 bits to 12 bits by checking the BMODE0 box. The new angle reading should have more digits of precision.

- Control bit for the FAULTRES pin
  To ignore faults, ensure that the FAULTRES pin is set to low. To set this pin low, uncheck the box.

**NOTE:** Toggling the FAULTRES pin with a fault condition still present causes the PGA411-Q1 device to go into normal operation, which may cause damage to the PGA411-Q1 device. This is most likely to occur with high current short circuits on the exciter amplifier.

Ignoring the faults is only recommended for initial evaluation.

---

(1) This version is the latest at the time this user guide was generated.
2.3.2 Device State

The Device State menu (see Figure 6) supports two device states: NORMAL and DIAGNOSTICS. This menu displays the current device state. Click on the down arrow for the dropdown menu to select a new state. This menu always displays the current device state, therefore serving as a confirmation that the device transitioned to the new state correctly.

NOTE: The data sheet includes a detailed description on why and how to change between these states. Some of the controls in the PGA411-Q1 GUI interactive block diagram change states, from NORMAL to DIAGNOSTIC in a hidden manner to make the configuration changes (for example, changing the exciter sine-wave amplitude from $4 \text{ V}_{\text{RMS}}$ to $7 \text{ V}_{\text{RMS}}$). See Section 2.3.4 for more details.
2.3.3 Pin Configuration and Fault Register Status

The Pin Configuration window (see Figure 7) displays the current status of the digital input and output pins. The input pins of the PGA411-Q1 device are shown in Figure 7 on the left-side (below the Update button) in the GUI, where the low or high values will be driven by the MSP430. Select the status of the nine digital-input pins by clicking on the appropriate button (INPUT-HIZ, OUT-LOW, or OUT-HIGH). The MSP430 device then switches the connected I/O pin to the selected value.

The output pins of the PGA411-Q1 device are displayed to the right of the group of input pins. This section displays the current status of the output pins with logic low equal to 0 and logic high equal to 1. For example if the FAULT pin changes to HIGH the GUI displays a 1 in the field which is then highlighted in red.

The Fault Status tab on the right-side of the Pin Configuration window displays the current status of the device registers which report any fault in the system. The following sections provide more details on the fault status registers.

The display updates each time the Update button is pressed. To automatically update this page, check the Enable box under the Auto Update section and select an update period in 1-s increments.

![Figure 7. Pin Configuration Screen](image-url)
2.3.4 Memory Map

The memory map is used to read and write to all of the device registers. The Memory Map window (see Figure 8) includes the register name, hex value for all 16 bits, and individual bit values.

A change to a register value occurs in one of two ways. The first way is bit by bit. To change a register value in this way, click in the text field of the bit number that will change. If this text field displays a 0, click the text field to toggle the value to 1 (see Figure 9). To update more bits, repeat the procedure. The second way to update a bit is with the hex value. Click on the hex value under the REG column (see Figure 10) and type the new HEX value.

In each case, after updating the register values the row should become highlighted in yellow, which indicates that the change has not yet been programmed to the PGA411-Q1 device.

To program the new register values into the device, click on the Write Selected button to updated only the highlighted registers. Click on the Write All buttons to modify all registers at one time.

NOTE: The device must be in diagnostics mode to write to the majority of registers. Refer to the PGA411-Q1 data sheet for the entire list of registers.

The primary buttons at the bottom of this window are defined as follows:

Read Selected — After selecting the register by clicking on the register name while holding the CTRL key for multiple selection, use this button to read all of the selected registers.

Write Selected — After selecting the register by clicking on the register name while holding the CTRL key for multiple selection, use this button to write to all of the selected registers.

Read All — Use this button to read all of the registers and to update the register values in the table.

Write All — Use this button to write the current values listed in the table to all of the registers, including those that were not modified.

ZERO GRID — Use this button to set all registers to zero.

DESELECT GRID — Use this button to remove all selections from the grid.

SAVE GRID — Use this button to save the contents of the grid to a text file. This option is useful for reusing register settings that were predefined.

LOAD GRID — Use this button to load the grid with the contents of a text file.
Figure 8. Memory Map

Figure 9. Bit Selection

Figure 10. Hex Selection (REG)
2.3.4.1 Search Box and Register Descriptions on UTILITIES Tab

The bottom of the GUI includes a useful tool to search the contents of each register. For example, to find the register that sets the exciter amplifier mode to $7 \, \text{V}_{\text{RMS}}$, type 7V in the Search Registers text field and click on the Search button. Next, a list of all registers that include any description containing the keyword 7V displays below the search box.

Click on the corresponding register value inside the memory map to view the register description on the UTILITIES tab on the right-hand side of the GUI. If DEV_PHASE_REG is selected, the UTILITIES tab displays that bits 11-10 set the exciter mode (EXTMODE). The value for $7 \, \text{V}_{\text{RMS}}$ is 01. Refer to Figure 11.

In the same UTILITIES tab, the bottom-section of the tab includes a numeric base converter with hex, decimal, and binary modes.

![Figure 11. Search Box and Register Descriptions](image)
2.3.5 Data Monitor

The Data Monitor window (see Figure 12) plots the output angle or velocity information and provides access to a Demo mode that shows the angle and velocity in an instrument cluster display. The fields and buttons on this window are described as follows:

**Data Capture Source** — This field selects between SPI register read, USB, or UART burst reading.

*NOTE:* The UART mode requires additional hardware setup which is not included in the EVM package. For evaluation purposes, the UART mode is not required.

**Data Monitor** — Use this field to select either the angle or velocity to plot.

**Resolution** — Use this field to select the resolution to export the data as.

**Record Length** — Use this field to select the number of data samples to plot on the graph.

**Loop** — If checked, when the graph fills up, selecting this checkbox clears the current graph and begin a new graph.

**RUN** — This button starts reading the angle or velocity data.

**Clear Plot** — This button clears the plot.

**Export Data** — This button exports the data to a .txt file in comma separated value (CSV) format.

![Figure 12. Data Monitor](image)

*NOTE:* The GUI was designed to support three modes of reading data from the PGA411-Q1 device. The collected samples could have some non-linearity when using the GUI to read the angle registers. If a delay occurs in the waveform on the Data Monitor window when reading the angle value, the delay is because of SPI. The EVM can support faster data capture by omitting the USB-to-SPI circuit (using MSP430) and connecting the controller directly to the digital pins available on the board. For evaluation purposes, TI recommends using SPI.
Demo — Use this button to access the high resolution instrument cluster Display for instantaneous angle and velocity display. Click on the ESC button on the keyboard to exit this mode. Refer to Figure 13.

![Figure 13. DEMO Screen](image)

**NOTE:**
The velocity resolution is limited to 500 rpm.

To properly read the velocity, calibrate the system by clicking the Calibrate button. For detailed information, refer to Troubleshooting Guide for PGA411-Q1 (SLAA687).

If the fault sign appears in the demo mode (in the form of a warning sign), refer to Section 2.3.6 to clear the faults.

**NOTE:**
Unlocking the EEPROM device functionality found under the general tab is not currently available in the current version of the PGA411-Q1 EVM GUI. This functionality will be added in a future version.
2.3.6 Fault Status

The *Fault Status* tab (see Figure 14) displays the status of the PGA411-Q1 fault bits. Click the *Update* button to refresh the display the current fault status. This tab can be configured to automatically update by selecting the *Enable* checkbox in the *Auto Update* section and setting the update period in 1-s increments.

The PGA411-Q1 device detects a fault in the system when any bit or group of bits displays a 1 and the color of the text field changes to red. Placing the mouse cursor on top of the status bit displays a text box with information on the fault, as shown in Figure 14.

![Figure 14. Fault Status](image)

**NOTE:** Make sure the FAULTRES pin is HIGH to view the faults (see Section 2.3.1).

If the auto update option is enabled, only the SFAULT may appear because faults are cleared when read. The SFAULT gives the state of the fault pin.
3 EVM Evaluation Examples

3.1 EVM Checks for Proper Operation

3.1.1 Fault Triggered at Startup

The resolver setup may trigger faults because of specific requirements on voltage or current. To understand the primary cause, ignore the faults and continue with the initial evaluation.

If a fault appears when the GUI is first executed after properly connecting the device EVM as recommended in Section 2.2.2, the PGA411-Q1 device can be set to ignore the faults. Setting the device to ignore these faults can occur in two different ways:

• Using the PGA411-Q1 block diagram
  Set the FAULTRES pin to low by unchecking the box in the block diagram as shown in Figure 15.

• Using the Pin Configuration tab
  Set the FAULTRES bit low by clicking the OUT-LOW button as shown in Figure 16. This setting allows for further evaluation of the resolver EVM.

NOTE: Toggling the FAULTRES pin with a fault condition still present causes the PGA411-Q1 device to go into normal operation, which may cause damage to the PGA411-Q1 device. This is most likely to occur with high current short circuits on the exciter amplifier.

Ignoring the faults is only recommended for initial evaluation.

Figure 15. FAULTRES Change in Block Diagram
3.1.2 Changing Exciter Signal Pre-Amplifier Gain

Changing the exciter amplifier gain can occur using the PGA411-Q1 block diagram as explained in Section 2.3.1; however, this section focuses on same procedure using the Memory Map tab which is more descriptive of how a controller interfaces with the PGA411-Q1 device for this type of operation.

In the preamplifier block, the amplification level of the exciter signal can be adjusted while the common mode voltage is defined by the voltage at the COMAFE pin (typically 2.5 V). The preamplifier gain is selectable though the EXTOUT_GL[15:12] bits in the DEV_OVUV1 register and affects both the preamplifier ORS output and power amplifier output. For more information, refer to the PGA411-Q1 data sheet, SLASE76.

Step 1. In the GUI, select the Memory Map tab. This section is the primary form of control for the device registers. For the bit definitions, see the PGA411-Q1 data sheet. The Information box on the right-side of the window also displays the bit definitions.

Step 2. Change the state of the device to DIAGNOSTICS mode. Refer to Figure 19 and Section 2.3.2.

Step 3. Probe pins COMAFE to check the 2.5-V pin voltage and use a differential probe on the OE1 and OE2 pins. Figure 17 shows these test-point locations on the board.

OE1 — OE1 is the positive output of the exciter amplifier.

OE2 — OE2 is the negative output of the exciter amplifier.
Figure 17. Test Points for Exciter Outputs and Common Mode Voltage
Step 4. Connect the scope probe to OE1 and compare this waveform to the one shown in Figure 18. In this waveform, the peak-to-peak voltage of the differential voltage output of the exciter is 11.12 V_{pp}.

**Figure 18. OE1-OE2 Differential Output from the Exciter**

Step 5. Click on the DEV_OVUV1 address inside the register map as shown in Figure 19. Text should appear in the Information box on the UTILITIES tab. This box displays information regarding the bits in the DEV_OVUV1 address.

**Figure 19. DEV_OVUV Register**

Bits Relevant to Exciter Amplifier Gain

Step 6. Click the b14 and b13 bits to change the value inside the cell. To change the exciter preamplifier gain from 1.5 V/V to 1.85 V/V, update the value of bits b15 through b12 to 1110 and write this register to the PGA411-Q1 device using the Write Selected button as explained in Section 2.3.4.1. New bit values appear as shown in Figure 20.
Figure 20. Exciter Amplifier Gain Change Using Memory Map

Step 7. As shown in Figure 21, the amplitude of the waveform increased to approximately 13 V which corresponds with the new programmed gain of the exciter amplifier.

NOTE: This example provides a step-by-step guide on how to change key parameters on the PGA411-Q1 device using the memory map functionality.

For support questions, go to TI's E2E™ online community, e2e.ti.com.

4 Schematics, Bill of Materials, and Layout

This section provides a detailed description of the schematic, bill of materials (BOM), and layout.
4.1 Schematics

Figure 22. EVM Schematic
Figure 23. Schematic—Digital Interface
# 4.2 Bill of Materials

## Table 3. BOM

<table>
<thead>
<tr>
<th>Designator</th>
<th>Quantity</th>
<th>Value</th>
<th>Description</th>
<th>Package Reference</th>
<th>Part Number</th>
<th>Manufacturer</th>
<th>Alternate Part Number</th>
<th>Alternate Manufacturer</th>
</tr>
</thead>
<tbody>
<tr>
<td>PCB1</td>
<td>1</td>
<td></td>
<td>Printed Circuit Board</td>
<td></td>
<td>HV1L26</td>
<td>Any</td>
<td></td>
<td></td>
</tr>
<tr>
<td>C1, C2, C3</td>
<td>3</td>
<td>10µF</td>
<td>CAP, TA, 10 µF, 25 V, ±10%, 0.3 D, SMD</td>
<td>6032-28</td>
<td>TPSC106K025R0300</td>
<td>AVX</td>
<td></td>
<td></td>
</tr>
<tr>
<td>C4, C5, C7, C9, C11</td>
<td>5</td>
<td>0.1µF</td>
<td>CAP, CERM, 0.1 µF, 50 V, ±10%, X7R, 0603</td>
<td>0603</td>
<td>C0603C104K5RACTU</td>
<td>Kemet</td>
<td></td>
<td></td>
</tr>
<tr>
<td>C6</td>
<td>1</td>
<td>10µF</td>
<td>CAP, TA, 10 µF, 50 V, ±10%, 0.3 D, SMD</td>
<td>7343-43</td>
<td>T495X106K050ATE300</td>
<td>Kemet</td>
<td></td>
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<td>Ferrite Bead, 1000Ω at 100 MHz, 0.3 A, 0805</td>
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<td>Switch, Slide, 4PDT,TH</td>
<td>Switch, 4P27, 15x18x9.4 mm</td>
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<td>TP76, TP77, TP78, TP79, TP80, TP81, TP82, TP83, TP84</td>
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<td>1-MHz, Micro-Power, Low-Noise, RRIO,1.8 V CMOS OPERATIONAL AMPLIFIER Precision Value Line Series, D0008A</td>
<td>D0008A</td>
<td>OPA2313DR</td>
<td>Texas Instruments</td>
<td>OPA2313D</td>
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<td>Dual 150mA, Low Iq LDO regulator, DPG0006A</td>
<td>DPG0006A</td>
<td>TLV7163318PDQR</td>
<td>Texas Instruments</td>
<td>TLV7163318P Q7</td>
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<td>U3</td>
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<td>PGA411PAP,..</td>
<td>PAP0064M</td>
<td>PGA411PAP</td>
<td>Texas Instruments</td>
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<td>U4, U5, U6, U7, U8</td>
<td>5</td>
<td>8-BIT DUAL-SUPPLY BUS TRANSCEIVER with CONFIGURABLE VOLTAGE TRANSLATION AND 3-STATE OUTPUT, DGV0024A</td>
<td>DGV0024A</td>
<td>SN74LVC8T245DGVR</td>
<td>Texas Instruments</td>
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<td>U9</td>
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<td>PN0080A</td>
<td>MSP430F5529IPN</td>
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<td>DRB0008A</td>
<td>TPS73533DRB</td>
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<td>Y1</td>
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<td>Crystal, 20.000MHz, 8pF, SMD</td>
<td>Crystal, 11.4x4.3x3.8mm</td>
<td>NX3225QA-20MHZ-STD-CRA-1</td>
<td>NDK</td>
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<td>Y2</td>
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<td>Crystal, 24.000MHz, 20pF, SMD</td>
<td>Crystal, 11.4x4.3x3.8mm</td>
<td>ECS-240-20-5PX-TR</td>
<td>ECS Inc.</td>
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<td>C10</td>
<td>0</td>
<td>0.01µF</td>
<td>CAP, CERM, 0.01 µF, 50 V, ±5%, 0805</td>
<td>0805</td>
<td>08055C103JAT2A</td>
<td>AVX</td>
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<td>C14, C20, C22, C23</td>
<td>0</td>
<td>51pF</td>
<td>CAP, CERM, 51 pF, 50 V, ±5%, C0G/NP0, 0603</td>
<td>0603</td>
<td>GMR1885C1H510JA01D</td>
<td>MuRata</td>
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<td>D2</td>
<td>0</td>
<td>5.1V</td>
<td>Diode, Zener, 5.1 V, 500 mw, SOD-123</td>
<td>SOD-123</td>
<td>MMS2521B-7-F</td>
<td>Diodes Inc.</td>
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<td>FID1, FID2, FID3, FID4, FID5, FID6</td>
<td>0</td>
<td></td>
<td>Fiducial mark. There is nothing to buy or mount.</td>
<td>N/A</td>
<td>N/A</td>
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<td>R14</td>
<td>0</td>
<td>0</td>
<td>RES, 0, 5%, 0.333 W, 0805</td>
<td>0805</td>
<td>CRCW060500020E4HP</td>
<td>Vishay-Dale</td>
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<td>R22, R23, R31, R32</td>
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<td>100</td>
<td>RES, 100, 1%, 0.25 W, TH</td>
<td>1/4W Resistor</td>
<td>CMF50100R0050FHEB</td>
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<td>R24, R34</td>
<td>0</td>
<td>4.99k</td>
<td>RES, 4.99 k, 0.1%, 0.1 W, 0603</td>
<td>0603</td>
<td>RT0603BRD074K99L</td>
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<td>R35</td>
<td>0</td>
<td>50</td>
<td>RES, 50, 1%, 0.1 W, 0603</td>
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<td>CRCW06050050R0FKEA</td>
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### Table 3. BOM (continued)

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<th>Designator</th>
<th>Quantity</th>
<th>Value</th>
<th>Description</th>
<th>Package Reference</th>
<th>Part Number</th>
<th>Manufacturer</th>
<th>Alternate Part Number</th>
<th>Alternate Manufacturer</th>
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<td>R39, R40, R41, R42, R43</td>
<td>0</td>
<td>33</td>
<td>RES, 33, 5%, 0.0625 W, Resistor Array - 8x1</td>
<td>Resistor Array - 8x1</td>
<td>EXB-2HV330JV</td>
<td>Panasonic</td>
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<td>R77</td>
<td>0</td>
<td>0</td>
<td>RES, 0, 5%, 0.1 W, 0603</td>
<td>0603</td>
<td>RC0603JR-070RL</td>
<td>Yageo America</td>
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<td>TP1, TP2, TP3, TP4, TP5, TP6, TP7, TP8, TP9, TP10, TP11, TP12, TP13, TP14, TP15, TP16, TP17, TP18, TP19, TP20, TP21, TP22, TP23, TP24, TP25, TP26, TP27, TP28, TP29, TP30, TP31, TP32, TP33, TP34, TP35, TP36, TP37, TP38, TP39, TP40, TP41, TP42, TP43, TP44, TP45, TP46, TP47, TP48, TP49, TP50, TP51, TP52, TP53, TP54, TP55, TP56, TP57, TP58, TP59, TP60, TP61, TP62, TP63, TP64</td>
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<td>Black</td>
<td>Test Point, Miniature, Black, TH</td>
<td>Black Miniature Testpoint</td>
<td>5001</td>
<td>Keystone</td>
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4.3 Layout and Component Placement

Figure 24. Top-Side Layout

Figure 25. Bottom-Side Layout
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