

# TPS53318 Step-Down Converter Evaluation Module User's Guide



## ABSTRACT

The TPS53319EVM-136 is designed to use a regulated 12-V bus to produce a regulated 1.5-V output at up to 14 A of load current. The TPS53319EVM-136 is designed to demonstrate the TPS53319 in a typical low voltage application while providing a number of test points to evaluate the performance of the TPS53319.

## Table of Contents

|  |    |
|--|----|
| <b>1 Introduction</b> .....  | 3  |
| 1.1 Typical Applications.....                                      | 3  |
| 1.2 Features.....  | 3  |
| <b>2 Electrical Performance Specifications</b> .....               | 3  |
| <b>3 Schematic</b> .....   | 4  |
| <b>4 Test Setup</b> .....  | 5  |
| 4.1 Test Equipment.....  | 5  |
| 4.2 Recommended Test Setup.....                                    | 6  |
| <b>5 Configurations</b> .....                                      | 7  |
| 5.1 Switching Frequency Selection.....                             | 7  |
| 5.2 Soft Start Selection.....                                      | 7  |
| 5.3 Mode Selection.....  | 7  |
| 5.4 Enable Selection.....  | 7  |
| <b>6 Test Procedure</b> .....                                      | 8  |
| 6.1 Line/Load Regulation and Efficiency Measurement Procedure..... | 8  |
| 6.2 Control Loop Gain and Phase Measurement Procedure.....         | 8  |
| 6.3 List of Test Points.....                                       | 8  |
| 6.4 Equipment Shutdown.....  | 8  |
| <b>7 Performance Data and Typical Characteristic Curves</b> .....  | 9  |
| 7.1 Efficiency.....  | 9  |
| 7.2 Load Regulation.....   | 9  |
| 7.3 Line Regulation.....   | 10 |
| 7.4 Enable Turn-On/ Turn-Off.....                                  | 10 |
| 7.5 Output Ripple.....   | 11 |
| 7.6 Switching Node.....  | 11 |
| 7.7 Output Transient with Auto-skip Mode.....                      | 12 |
| 7.8 Output Transient with FCCM mode.....                           | 12 |
| 7.9 Output 0.75-V Pre-bias Turn-On.....                            | 13 |
| 7.10 Output Overcurrent and Short Circuit Protection.....          | 13 |
| 7.11 Bode plot.....  | 14 |
| 7.12 Thermal Image.....  | 14 |
| <b>8 EVM Assembly Drawing and PCB Layout</b> .....                 | 15 |
| <b>9 Bill of Materials</b> .....                                   | 23 |
| <b>10 Revision History</b> .....                                   | 23 |

## List of Figures

|  |    |
|--|----|
| Figure 3-1. TPS53319EVM-136 Schematic.....                       | 4  |
| Figure 4-1. Tip and Barrel Measurement for $V_{OUT}$ Ripple..... | 5  |
| Figure 4-2. TPS53319EVM-136 Recommended Test Setup.....          | 6  |
| Figure 7-1. Efficiency.....                                      | 9  |
| Figure 7-2. Load Regulation.....                                 | 9  |
| Figure 7-3. Line Regulation.....                                 | 10 |

|  |    |
|--|----|
| Figure 7-4. Enable Turn-On.....  | 10 |
| Figure 7-5. Enable Turn-Off.....   | 10 |
| Figure 7-6. Output Ripple.....   | 11 |
| Figure 7-7. Switching Node.....  | 11 |
| Figure 7-8. Output Transient from DCM to CCM.....  | 12 |
| Figure 7-9. Output Transient from CCM to DCM.....  | 12 |
| Figure 7-10. Output Transient with FCCM mode.....  | 12 |
| Figure 7-11. Output 0.75-V Pre-bias Turn-On.....   | 13 |
| Figure 7-12. Output Overcurrent Protection.....  | 13 |
| Figure 7-13. Output Overvoltage Protection.....  | 13 |
| Figure 7-14. Bode plot at 12Vin, 1.5V/14A.....   | 14 |
| Figure 7-15. Top Board at 12 V <sub>IN</sub> , 1.5 V/14 A, 25°C Ambient Without Airflow..... | 14 |
| Figure 8-1. TPS53319EVM-136 Top Layer Assembly Drawing.....                                  | 15 |
| Figure 8-2. TPS53319EVM-136 Bottom Assembly Drawing.....                                     | 16 |
| Figure 8-3. TPS53319EVM-136 Top Copper.....  | 17 |
| Figure 8-4. TPS53319EVM-136 Layer 2 Copper.....  | 18 |
| Figure 8-5. TPS53319EVM-136 Layer 3 Copper.....  | 19 |
| Figure 8-6. TPS53319EVM-136 Layer 4 Copper.....  | 20 |
| Figure 8-7. TPS53319EVM-136 Layer 5 Copper.....  | 21 |
| Figure 8-8. TPS53319EVM-136 Bottom Layer Copper.....   | 22 |

### List of Tables

|   |    |
|---|----|
| Table 2-1. TPS53319EVM-136 Electrical Performance Specifications..... | 3  |
| Table 5-1. Switching Frequency Selection.....                         | 7  |
| Table 5-2. Soft Start Time Selection.....                             | 7  |
| Table 5-3. MODE Selection.....  | 7  |
| Table 5-4. Enable Selection.....                                      | 7  |
| Table 6-1. The Functions of Each Test Points.....                     | 8  |
| Table 9-1. Components List.....                                       | 23 |

## 1 Introduction

The TPS53319EVM-136 evaluation module (EVM) uses the TPS53319. The TPS53319 is a D-CAP mode, 14-A synchronous buck converter with integrated MOSFETs. The device provides a fixed 1.5-V output at up to 14 A from a 12-V input bus.

### 1.1 Typical Applications

- Server/storage
- Workstations and desktops
- Telecommunication infrastructure

### 1.2 Features

The TPS53319EVM-136 features:

- 14-A DC steady state output current
- Support pre-bias output voltage start-up
- J3 for selectable switching frequency setting
- J4 for selectable soft-start time
- J5 for auto-skip and forced CCM selection
- J6 for enable function
- Convenient test points for probing critical waveforms

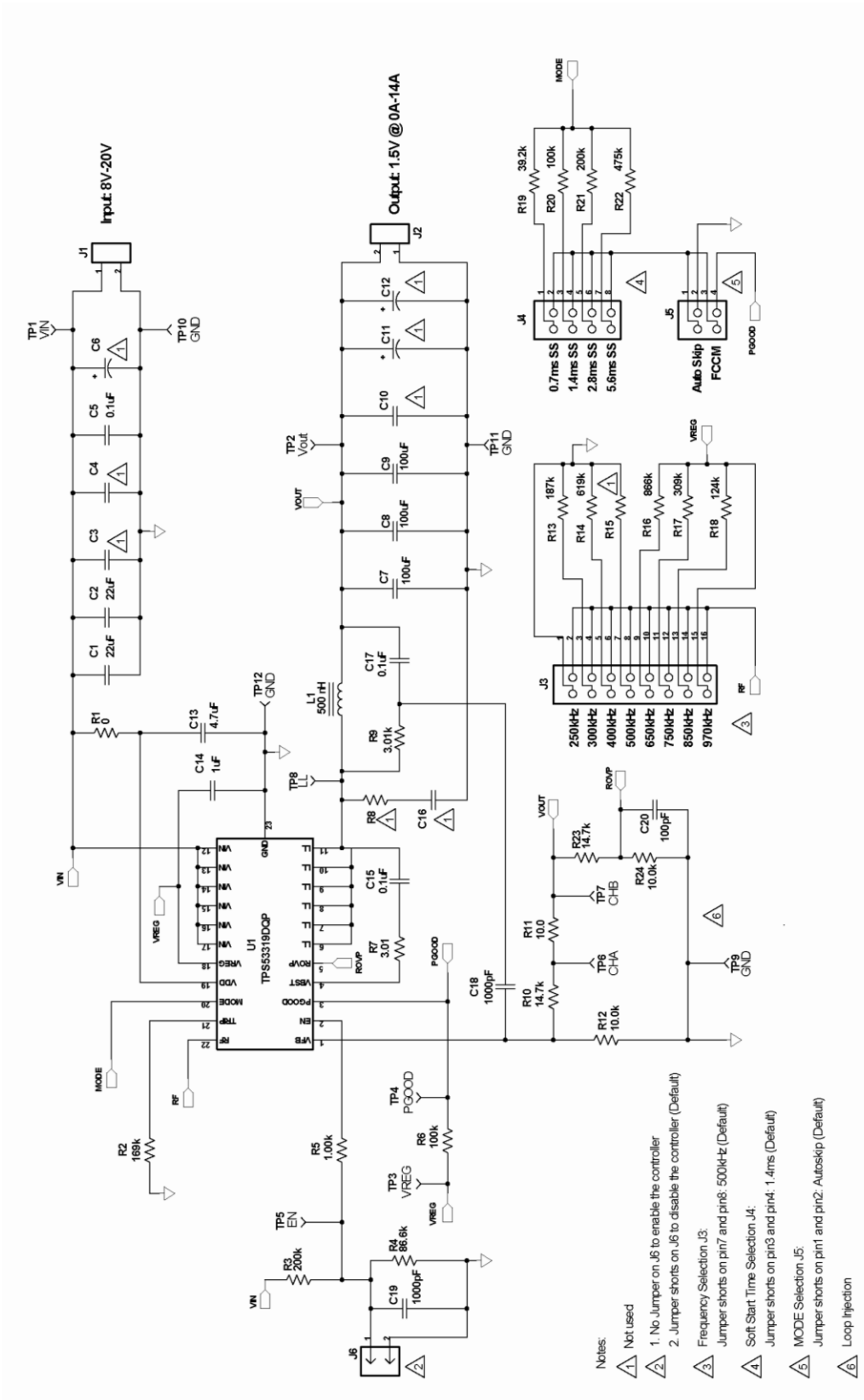
## 2 Electrical Performance Specifications

**Table 2-1. TPS53319EVM-136 Electrical Performance Specifications**

| PARAMETER <sup>(1)</sup>       | TEST CONDITIONS   | MIN | TYP    | MAX | UNITS |
|--------------------------------|---|-----|--------|-----|-------|
| <b>INPUT CHARACTERISTICS</b>   |   |     |        |     |       |
| Voltage range                  | $V_{IN}$  | 8   | 12     | 20  | V     |
| Maximum input current          | $V_{IN} = 8\text{ V}, I_O = 14\text{ A}$  |     | 2.874  |     | A     |
| No load input current          | $V_{IN} = 20\text{ V}, I_O = 0\text{ A}$ with auto skip mode                        |     | 0.7    |     | mA    |
| <b>OUTPUT CHARACTERISTICS</b>  |   |     |        |     |       |
| Output voltage $V_{OUT}$       |   |     | 1.5    |     | V     |
| Output voltage regulation      | Line regulation ( $V_{IN} = 8\text{ V}–20\text{ V}$ )                               |     | 0.1%   |     |       |
|                                | Load regulation ( $V_{IN} = 12\text{ V}, I_O = 0\text{ A}–14\text{ A}$ ), auto-skip |     | 1%     |     |       |
| Output voltage ripple          | $V_{IN} = 12\text{ V}, I_O = 14\text{ A}$   |     | 15     |     | mVpp  |
| Output load current            |   | 0   |        | 14  | A     |
| Output over current            |   |     | 16     |     | A     |
| <b>SYSTEMS CHARACTERISTICS</b> |   |     |        |     |       |
| Switching frequency            |   |     | 500    |     | kHz   |
| Peak efficiency                | $V_{IN} = 12\text{ V}, 1.5\text{ V}/8\text{ A}$                                     |     | 91.68% |     |       |
| Full load efficiency           | $V_{IN} = 12\text{ V}, 1.5\text{ V}/14\text{ A}$                                    |     | 90.04% |     |       |
| Operating temperature          |   |     | 25     |     | °C    |

(1) **Note:** Jumpers set to default locations. See [Section 6](#).

### 3 Schematic



**Figure 3-1. TPS53319EVM-136 Schematic**

## 4 Test Setup

### 4.1 Test Equipment

#### Voltage Source:

The input voltage source,  $V_{IN}$ , should be a 0-V to 20-V variable DC source capable of supplying 10 A<sub>DC</sub>. Connect  $V_{IN}$  to J1 as shown in [Figure 4-2](#).

#### Multimeters:

V1:  $V_{IN}$  at TP1 ( $V_{IN}$ ) and TP10 (GND). V2:  $V_{OUT}$  at TP2 ( $V_{OUT}$ ) and TP11 (GND). A1:  $V_{IN}$  input current

#### Output Load:

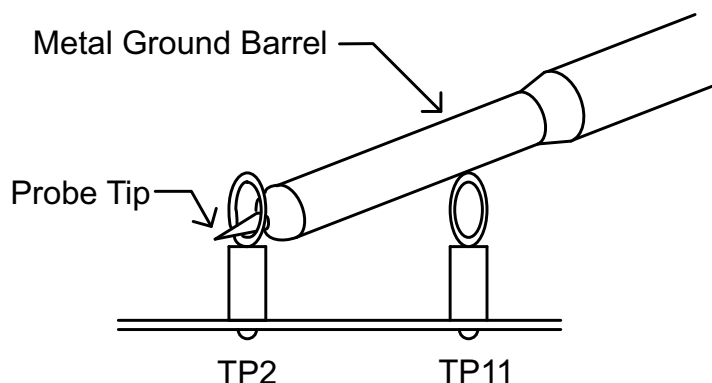
The output load should be an electronic constant resistance mode load capable of 0 A<sub>DC</sub> to 16 A<sub>DC</sub> at 1.5 V.

#### Oscilloscope:

A digital or analog oscilloscope can be used to measure the output ripple. The oscilloscope should be set for the following:

- 1-M $\Omega$  impedance
- 20-MHz bandwidth
- AC coupling
- 2- $\mu$ s/division horizontal resolution
- 20-mV/division vertical resolution

Test points TP2 and TP11 can be used to measure the output ripple voltage by placing the oscilloscope probe tip through TP2 and holding the ground barrel on TP11 as shown in [Figure 4-1](#). Using a leaded ground connection can induce additional noise due to the large ground loop.

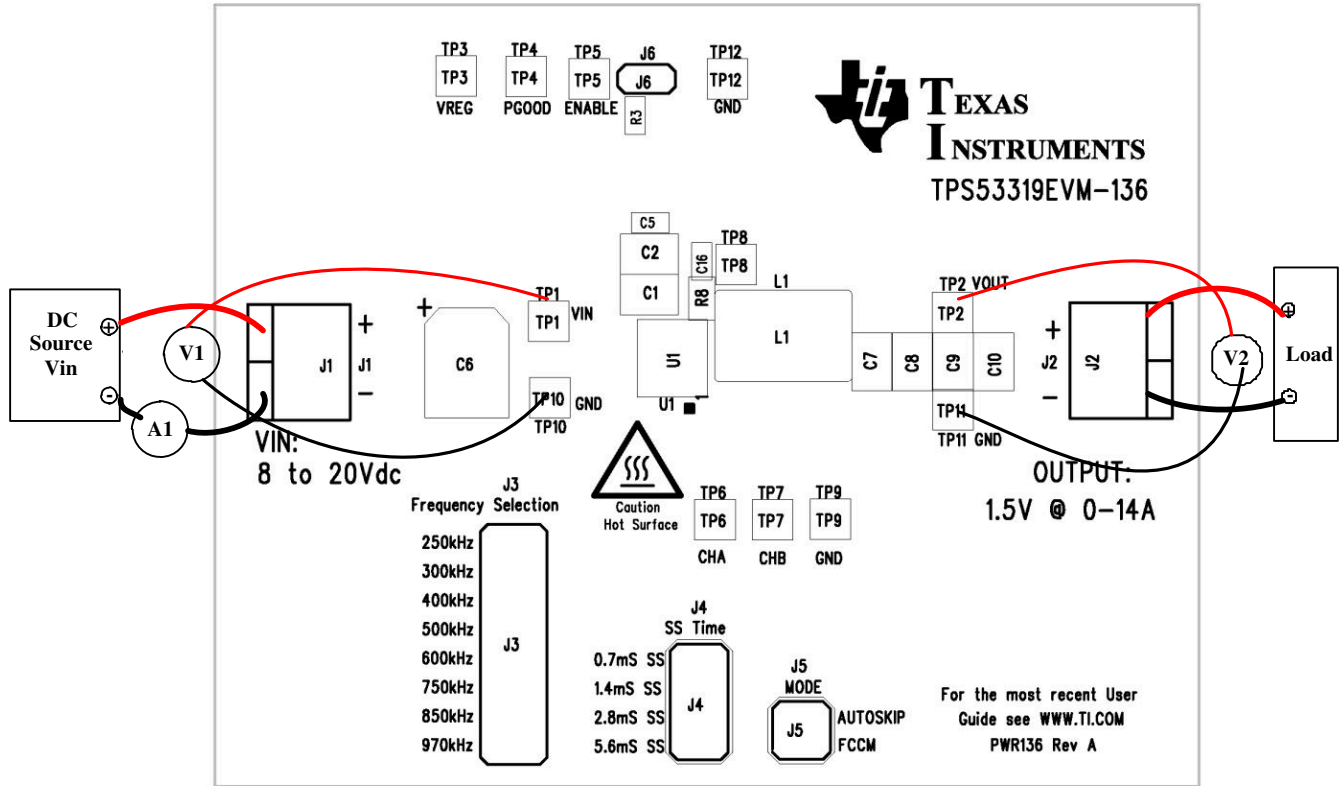


**Figure 4-1. Tip and Barrel Measurement for  $V_{OUT}$  Ripple**

#### Recommended Wire Gauge:

1.  $V_{IN}$  to J1 (12-V input):  
The recommended wire size is AWG #16 per input connection, with the total length of wire less than four feet (two feet input, two feet return).
2. J2 to LOAD:  
The minimum recommended wire size is AWG #14, with the total length of wire less than four feet (two feet output, two feet return).

## 4.2 Recommended Test Setup



**Figure 4-2. TPS53319EVM-136 Recommended Test Setup**

Figure 4-2 is the recommended test setup to evaluate the TPS53319EVM-136. Working at an ESD workstation, make sure that any wrist straps, bootstraps, or mats are connected referencing the user to earth ground before power is applied to the EVM.

### Input Connections:

1. Prior to connecting the DC input source  $V_{IN}$ , it is advisable to limit the source current from  $V_{IN}$  to 10-A maximum. Make sure  $V_{IN}$  is initially set to 0 V and connected as shown in Figure 4-2.
2. Connect a voltmeter V1 at TP1 ( $V_{IN}$ ) and TP10 (GND) to measure the input voltage.
3. Connect a current meter A1 to measure the input current.

### Output Connections

1. Connect the load to J2 and set the load to constant resistance mode to sink 0  $A_{DC}$  before  $V_{IN}$  is applied.
2. Connect a voltmeter V2 at TP2 ( $V_{OUT}$ ) and TP11 (GND) to measure the output voltage.

## 5 Configurations

All jumper selections should be made prior to applying power to the EVM. The user can configure this EVM per the following configurations.

### 5.1 Switching Frequency Selection

The switching frequency can be set by J3.

**Default setting: 500 kHz**

**Table 5-1. Switching Frequency Selection**

| JUMPER SET TO                           | RESISTOR (RF) CONNECTIONS ( $\Omega$ ) | SWITCHING FREQUENCY (kHz) |
|---|--|---------------------------|
| Top (1–2 pin shorted)                   | 0                                      | 250                       |
| 2 <sup>nd</sup> (3–4 pin shorted)       | 187 k                                  | 300                       |
| 3 <sup>rd</sup> (5–6 pin shorted)       | 619 k                                  | 400                       |
| <b>4<sup>th</sup> (7–8 pin shorted)</b> | <b>Open</b>                            | <b>500</b>                |
| 5 <sup>th</sup> (9–10 pin shorted)      | 866 k                                  | 600                       |
| 6 <sup>th</sup> (11–12 pin shorted)     | 309 k                                  | 750                       |
| 7 <sup>th</sup> (13–14 pin shorted)     | 124 k                                  | 850                       |
| Bottom (15–16 pin shorted)              | 0                                      | 970                       |

### 5.2 Soft Start Selection

The soft start time can be set by J4.

**Default setting: 1.4ms**

**Table 5-2. Soft Start Time Selection**

| Jumper set to                           | R <sub>MODE</sub> Connections( $\Omega$ ) | Soft Start Time(ms) |
|---|---|---------------------|
| Top(1-2 pin shorted)                    | 39.2k                                     | 0.7                 |
| <b>2<sup>nd</sup> (3-4 pin shorted)</b> | 100k                                      | 1.4                 |
| 3 <sup>rd</sup> (5-6 pin shorted)       | 200k                                      | 2.8                 |
| Bottom(7-8 pin shorted)                 | 475k                                      | 5.6                 |

### 5.3 Mode Selection

The MODE can be set by J5.

**Default setting: Auto Skip**

**Table 5-3. MODE Selection**

| Jumper set to           | MODE Selection   |
|-------------------------|------------------|
| Top(1-2 pin shorted)    | <b>Auto Skip</b> |
| Bottom(3-4 pin shorted) | Forced CCM       |

### 5.4 Enable Selection

The controller can be enabled and disabled by J6.

**Default setting: Jumper shorts on J6 to disable the controller**

**Table 5-4. Enable Selection**

| Jumper set to              | Enable Selection              |
|----------------------------|-------------------------------|
| <b>Jumper shorts on J6</b> | <b>Disable the controller</b> |
| No Jumper shorts on J6     | Enable the controller         |

## 6 Test Procedure

### 6.1 Line/Load Regulation and Efficiency Measurement Procedure

1. Set up EVM as described in [Section 4](#) and [Figure 4-2](#).
2. Ensure Load is set to constant resistance mode and to sink 0Adc
3. Ensure all jumpers configuration settings per section 5.
4. Ensure the jumper provided in the EVM shorts on J6 before Vin is applied.
5. Increase Vin from 0V to 12V. Using V1 to measure input voltage.
6. Remove the jumper on J6 to enable the controller.
7. Use V2 to measure Vout voltage.
8. Vary Load from 0-14Adc, Vout should be remain in load regulation.
9. Vary Vin from 8V to 20V, Vout should remain in line regulation.
10. Put the jumper on J6 to disable the controller.
11. Decrease Load to 0A
12. Decrease Vin to 0V.

### 6.2 Control Loop Gain and Phase Measurement Procedure

TPS53319EVM-136 contains a 10Ω series resistor in the feedback loop for loop response analysis.

1. Set up EVM as described in [Section 4](#) and [Figure 4-2](#).
2. Connect isolation transformer to test points marked TP6 and TP7.
3. Connect input signal amplitude measurement probe (channel A) to TP6. Connect output signal amplitude measurement probe (channel B) to TP7.
4. Connect ground lead of channel A and channel B to TP9.
5. Inject around 20mV or less signal through the isolation transformer.
6. Sweep the frequency from 100Hz to 1MHz with 10Hz or lower post filter. The control loop gain and phase margin can be measured.
7. Disconnect isolation transformer from bode plot test points before making other measurements (Signal injection into feedback may interfere with accuracy of other measurements).

### 6.3 List of Test Points

**Table 6-1. The Functions of Each Test Points**

| Test Points | Name  | Description                |
|-------------|-------|----------------------------|
| TP1         | VIN   | Controller input           |
| TP2         | Vout  | Output Voltage             |
| TP3         | VREG  | 5V LDO output              |
| TP4         | PGOOD | Power Good                 |
| TP5         | EN    | Enable                     |
| TP6         | CHA   | Input A for loop injection |
| TP7         | CHB   | Input B for loop injection |
| TP8         | LL    | Switching node             |
| TP9         | GND   | Ground                     |
| TP10        | GND   | Ground                     |
| TP11        | GND   | Ground                     |
| TP12        | GND   | Ground                     |

### 6.4 Equipment Shutdown

1. Shut down the load.
2. Shut down  $V_{IN}$ .



## 7 Performance Data and Typical Characteristic Curves

Figure 7-1 through Figure 7-15 present typical performance curves for TPS53319EVM-136.

### 7.1 Efficiency

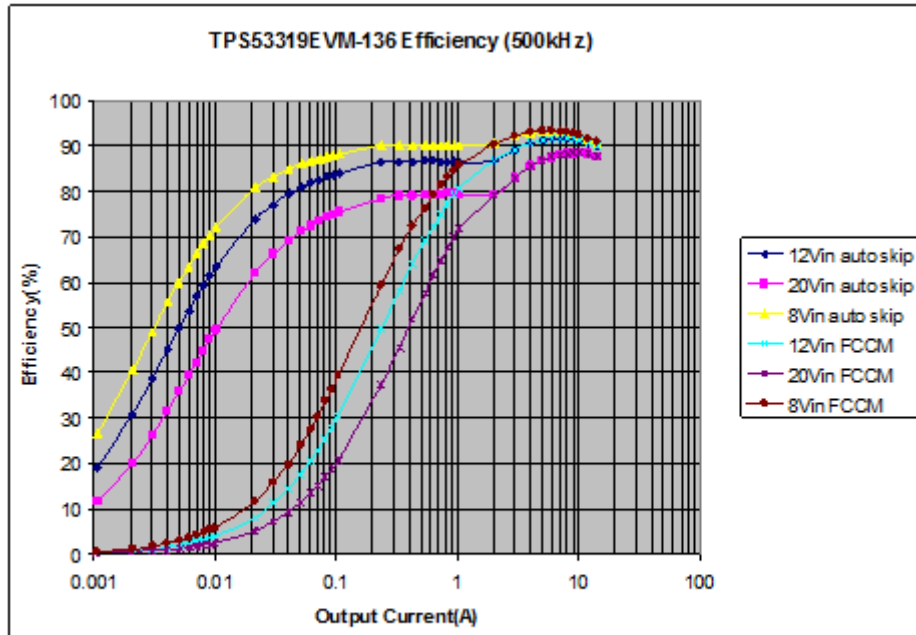


Figure 7-1. Efficiency

### 7.2 Load Regulation

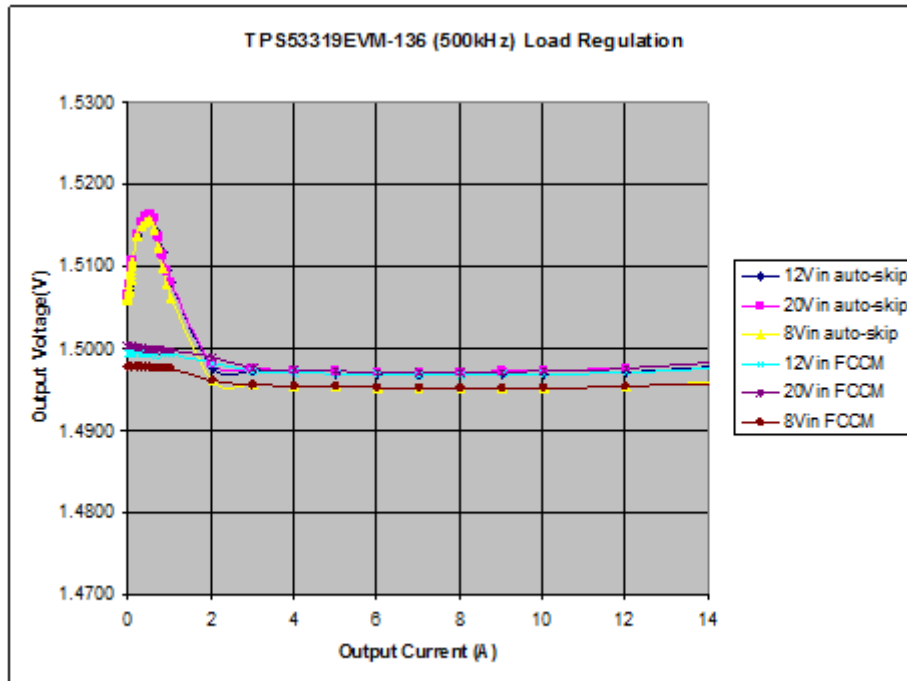


Figure 7-2. Load Regulation

### 7.3 Line Regulation

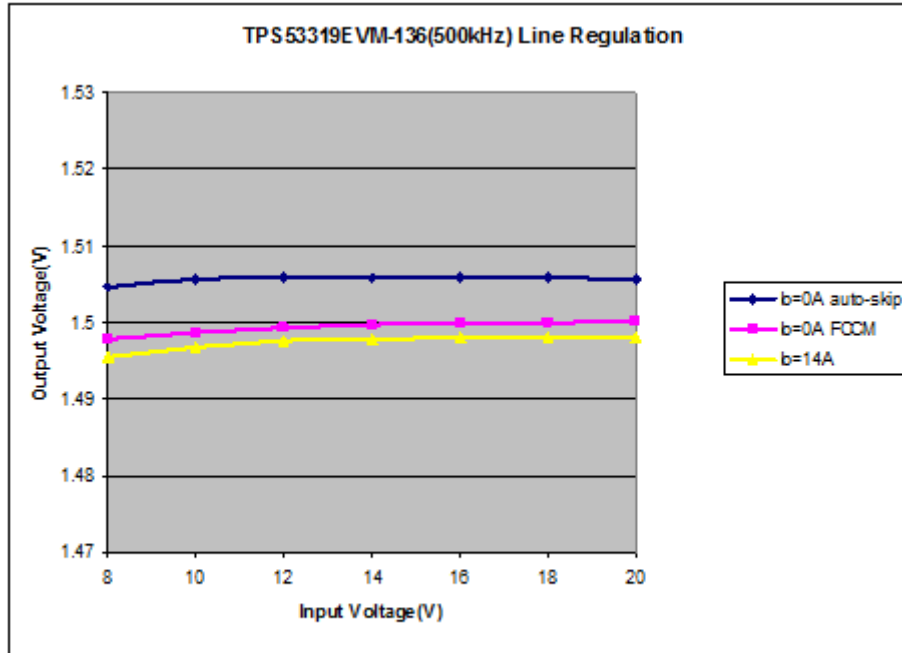


Figure 7-3. Line Regulation

### 7.4 Enable Turn-On/ Turn-Off

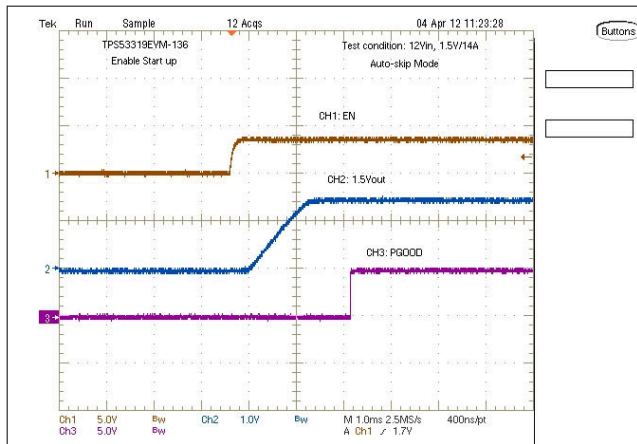


Figure 7-4. Enable Turn-On

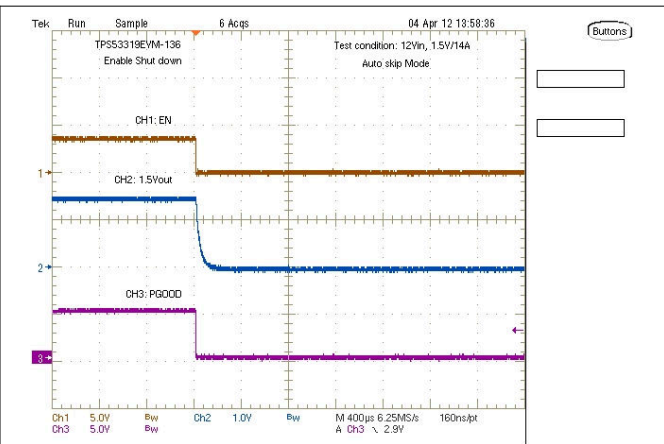


Figure 7-5. Enable Turn-Off

## 7.5 Output Ripple

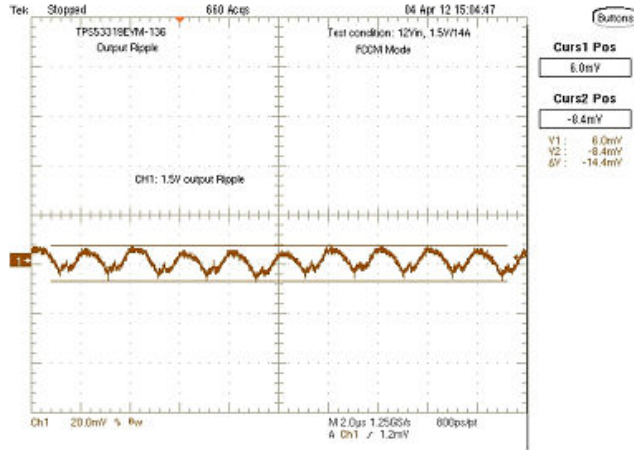


Figure 7-6. Output Ripple

## 7.6 Switching Node

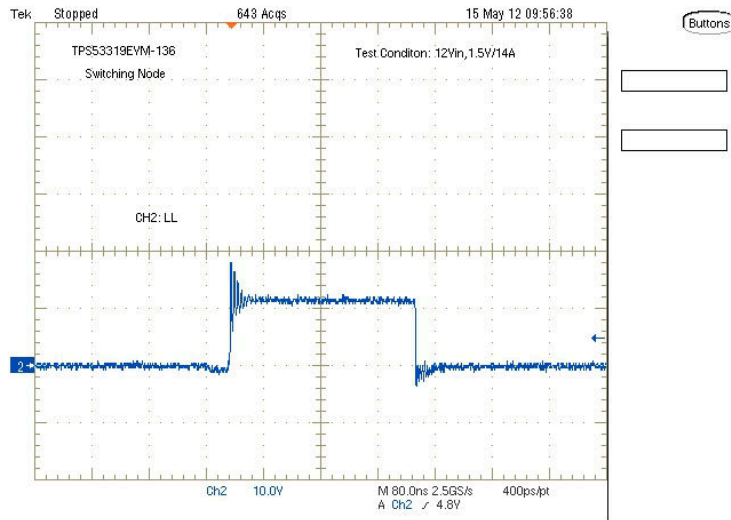


Figure 7-7. Switching Node

### 7.7 Output Transient with Auto-skip Mode

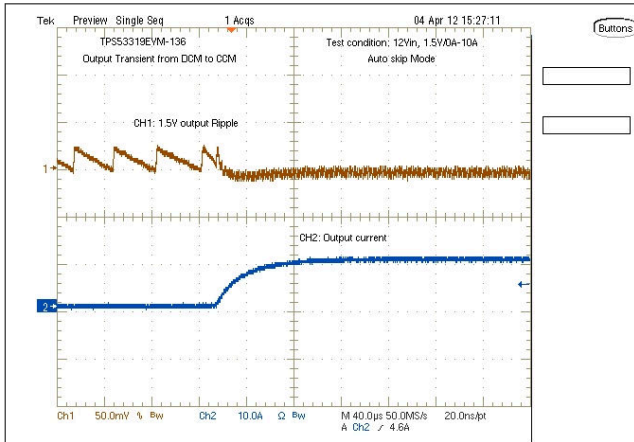


Figure 7-8. Output Transient from DCM to CCM

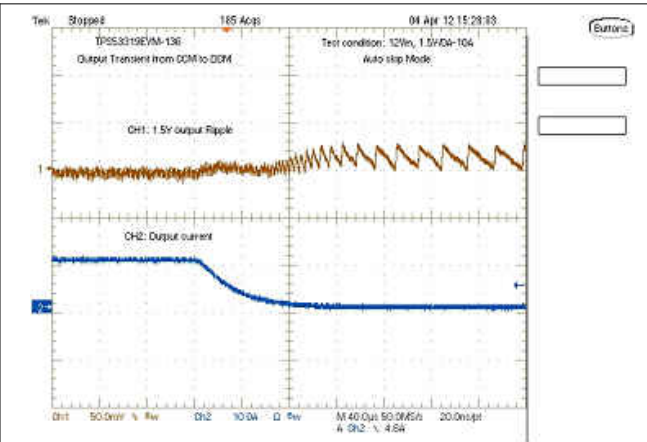


Figure 7-9. Output Transient from CCM to DCM

### 7.8 Output Transient with FCCM mode

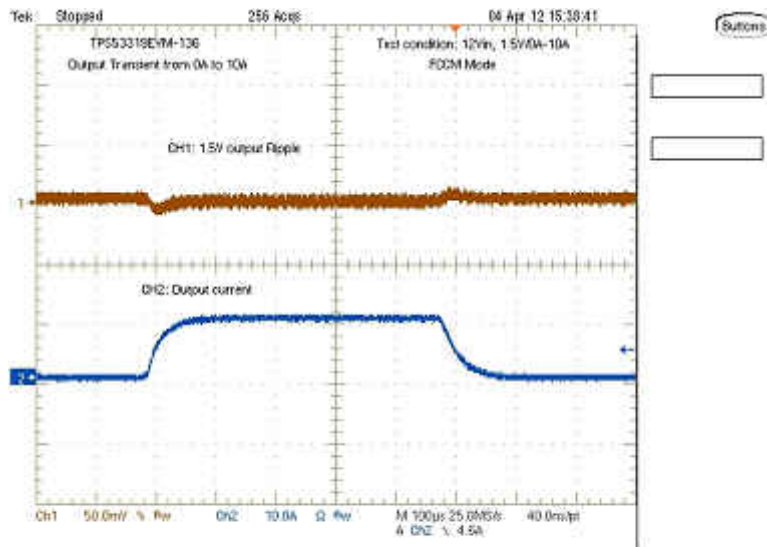


Figure 7-10. Output Transient with FCCM mode

### 7.9 Output 0.75-V Pre-bias Turn-On

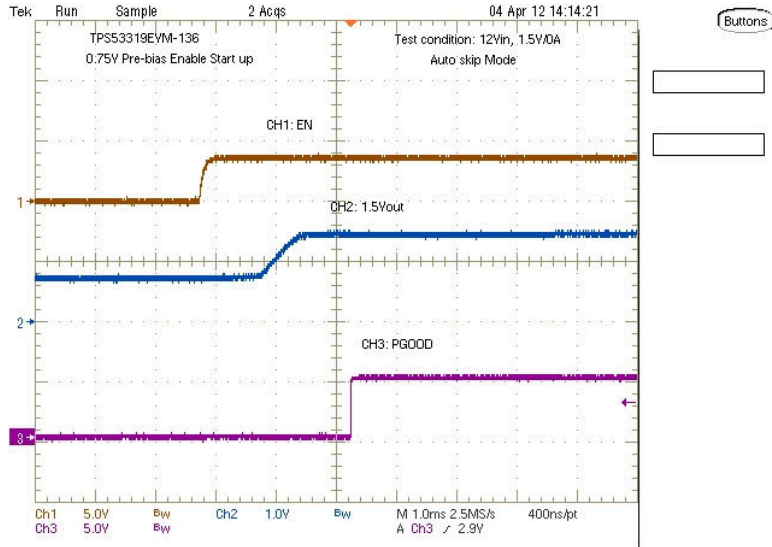


Figure 7-11. Output 0.75-V Pre-bias Turn-On

### 7.10 Output Overcurrent and Short Circuit Protection

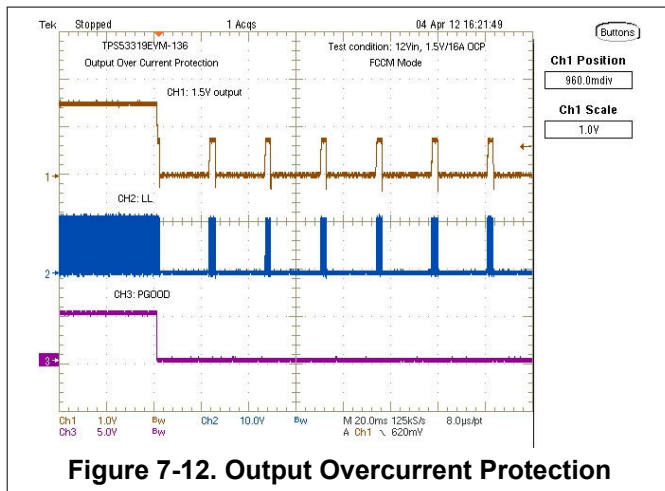


Figure 7-12. Output Overcurrent Protection

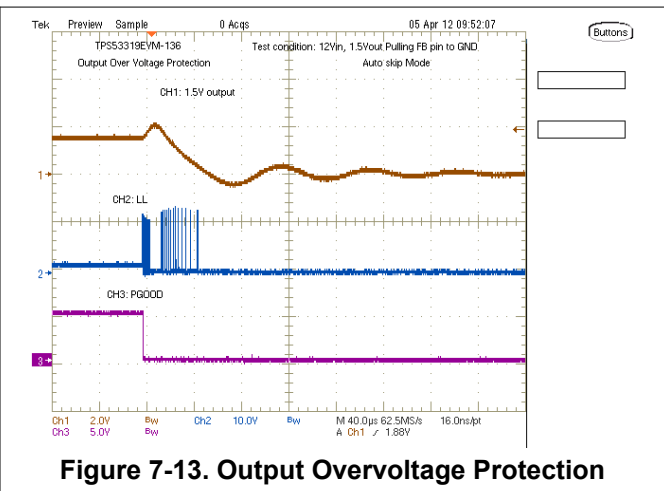


Figure 7-13. Output Overvoltage Protection

## 7.11 Bode plot

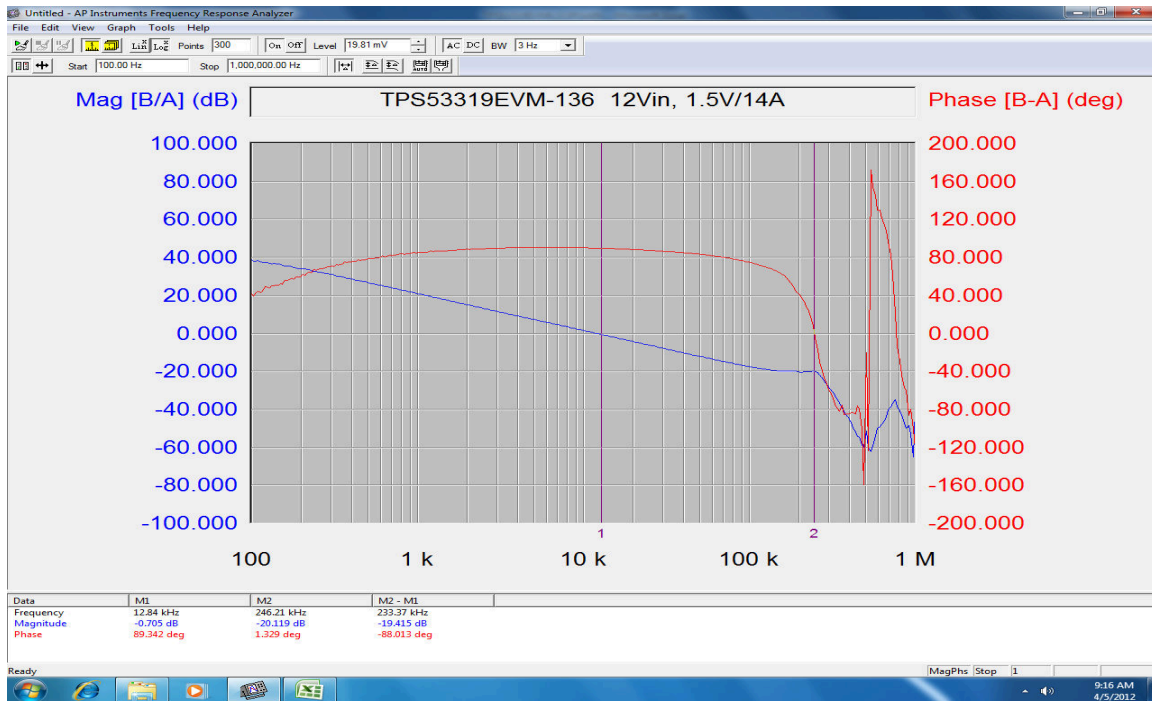


Figure 7-14. Bode plot at 12Vin, 1.5V/14A

## 7.12 Thermal Image

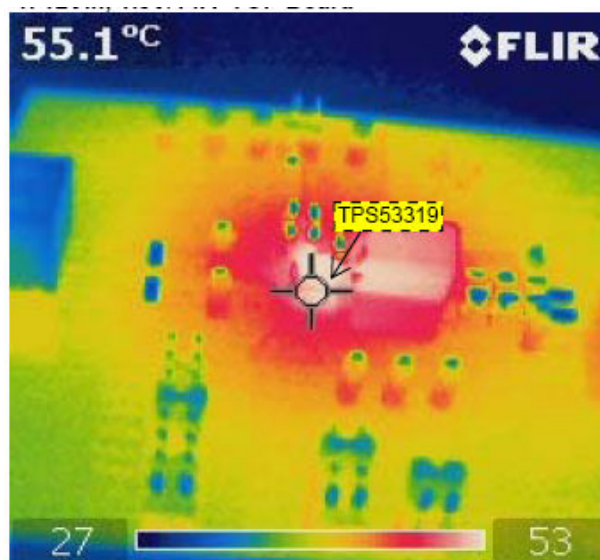


Figure 7-15. Top Board at 12 V<sub>IN</sub>, 1.5 V/14 A, 25°C Ambient Without Airflow

## 8 EVM Assembly Drawing and PCB Layout

Figure 8-1 through Figure 8-8 show the design of the TPS53319EVM-136 printed circuit board. The EVM has been designed using a 6-layer, 2-oz copper circuit board.

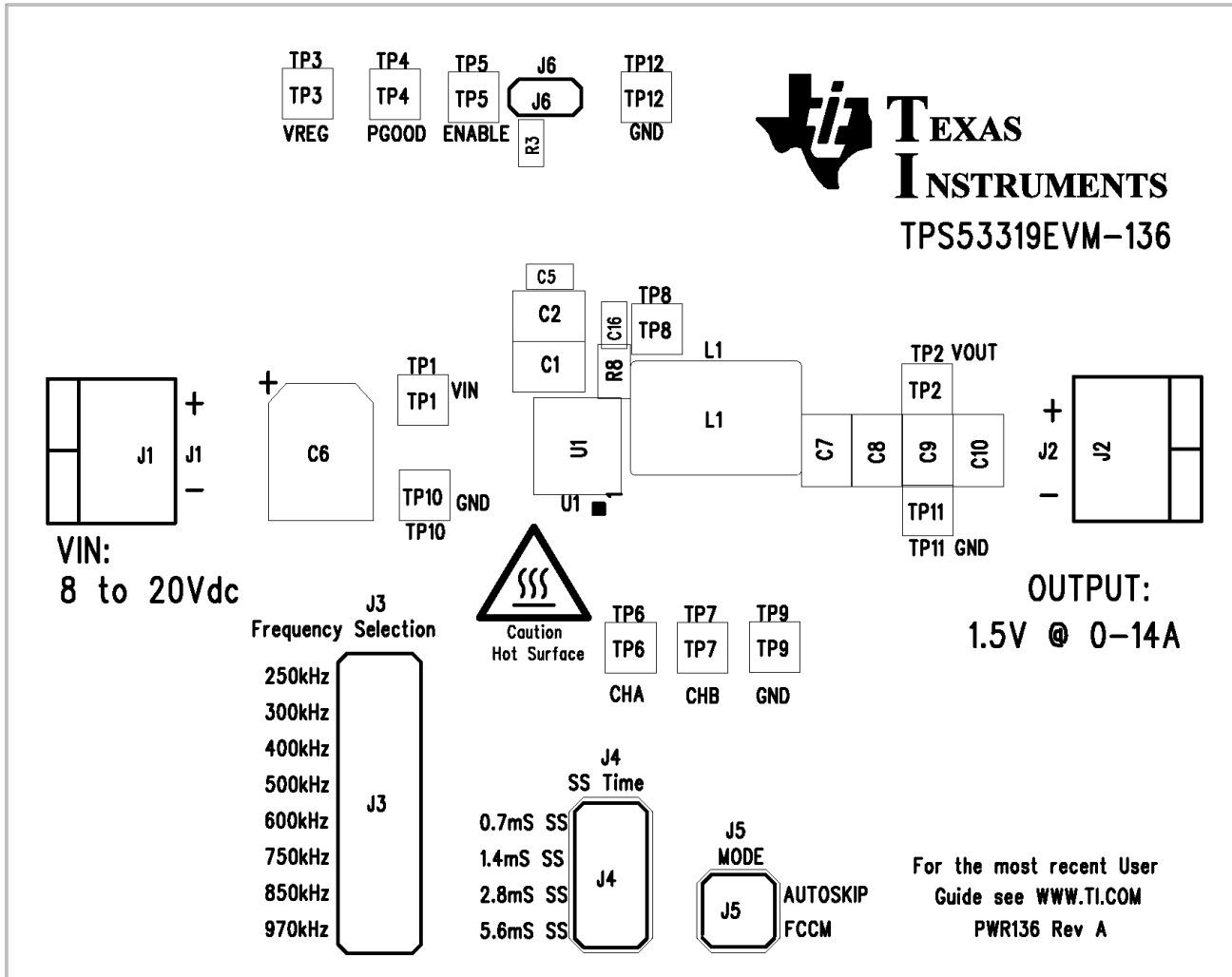
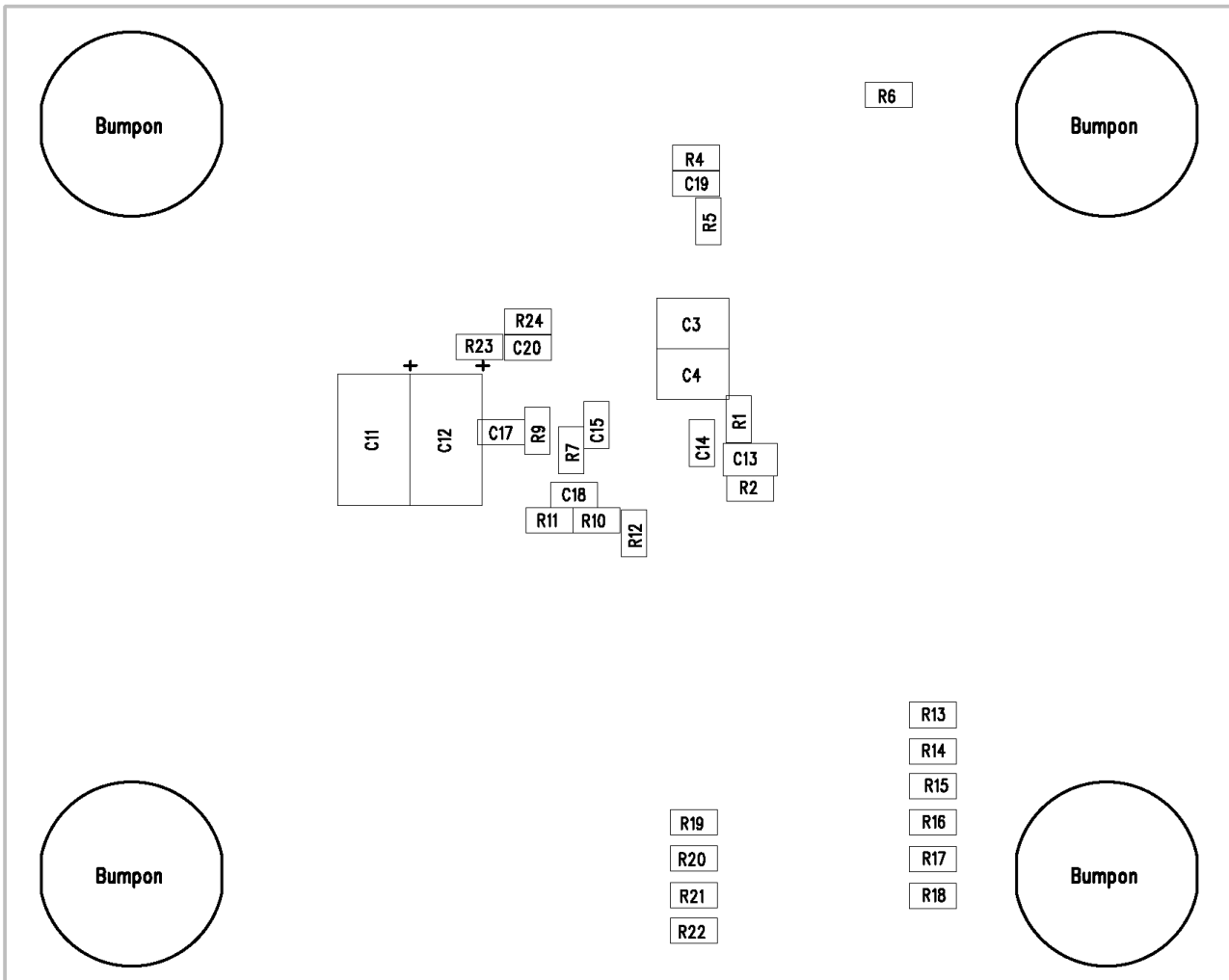
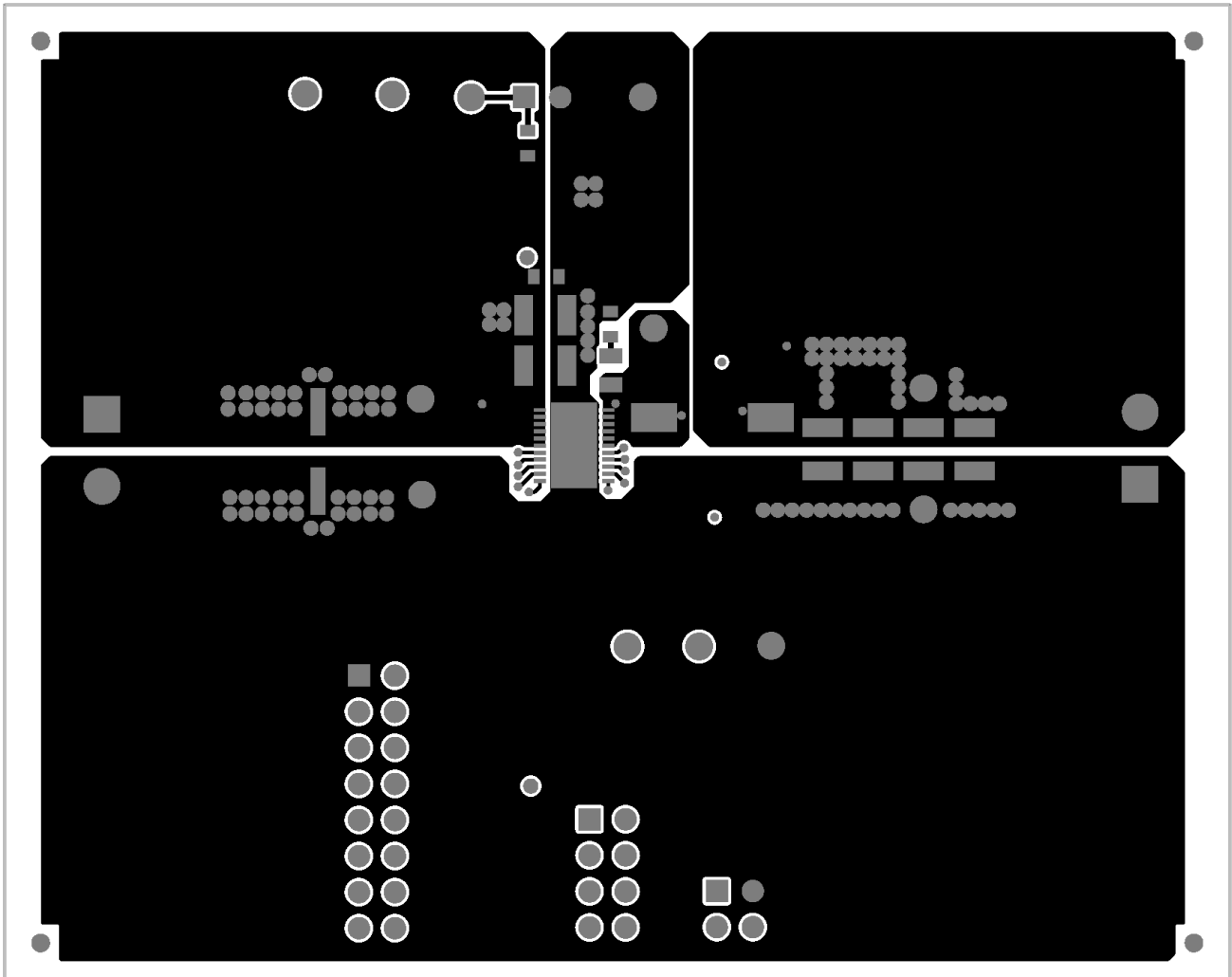


Figure 8-1. TPS53319EVM-136 Top Layer Assembly Drawing

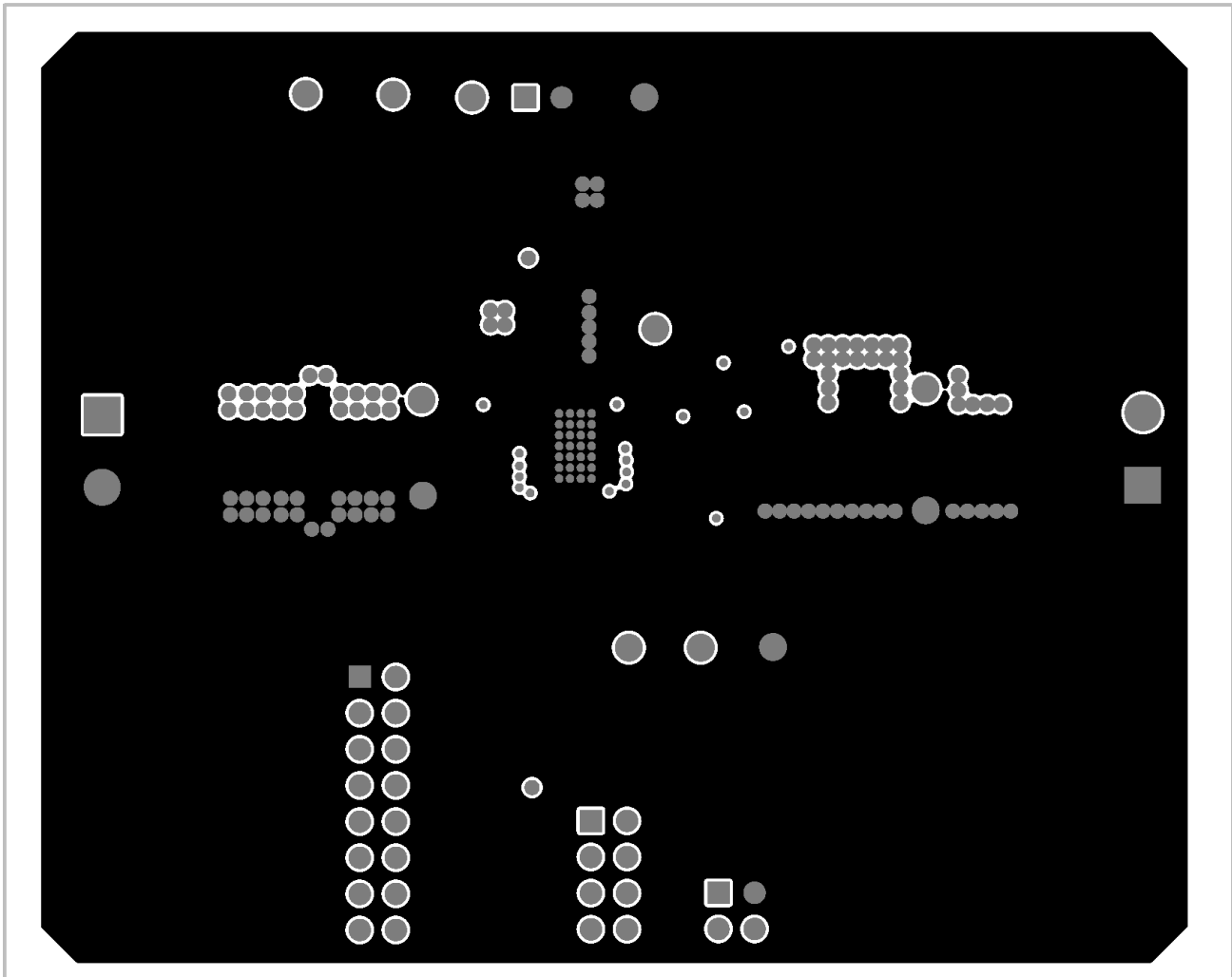


**Figure 8-2. TPS53319EVM-136 Bottom Assembly Drawing**

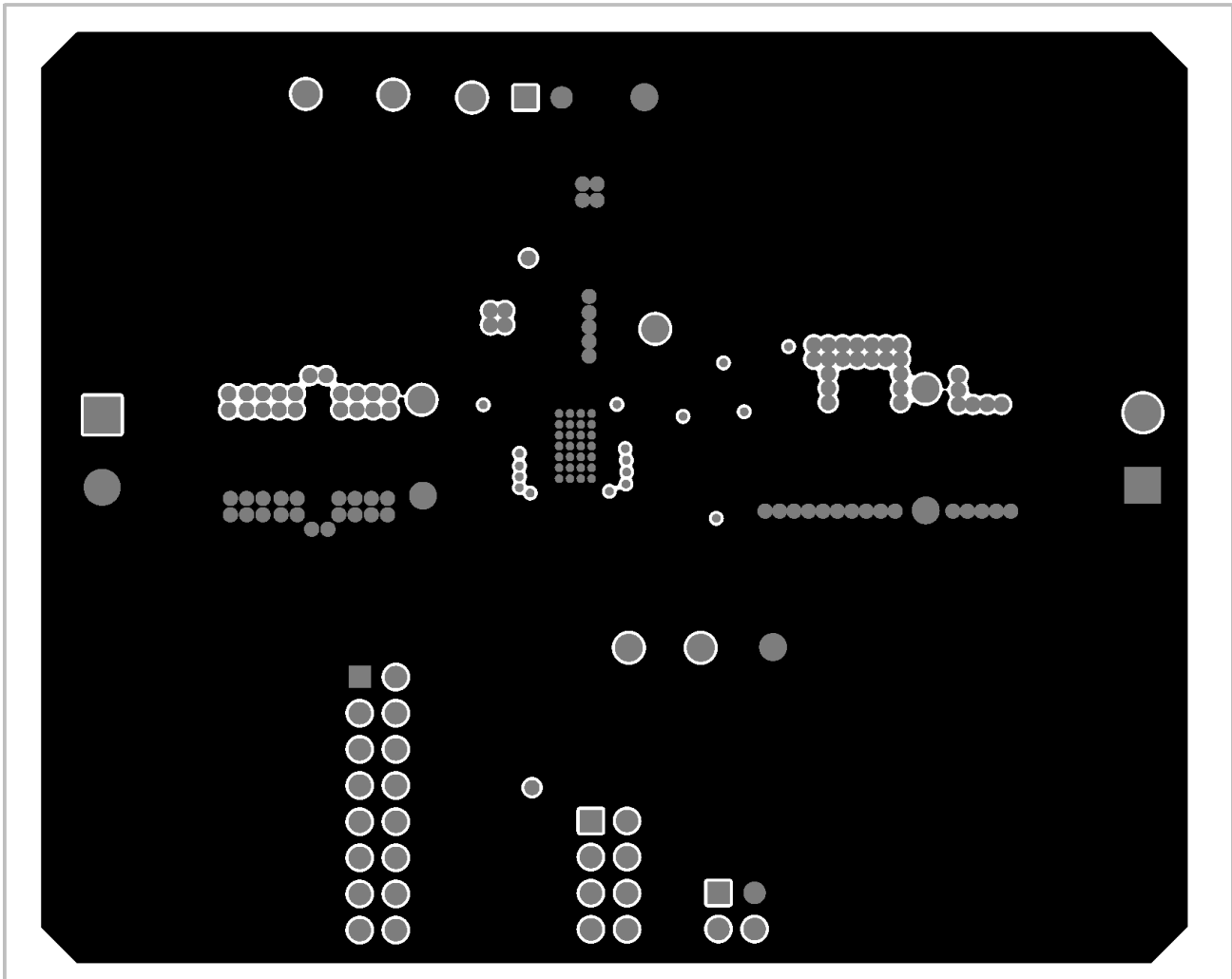




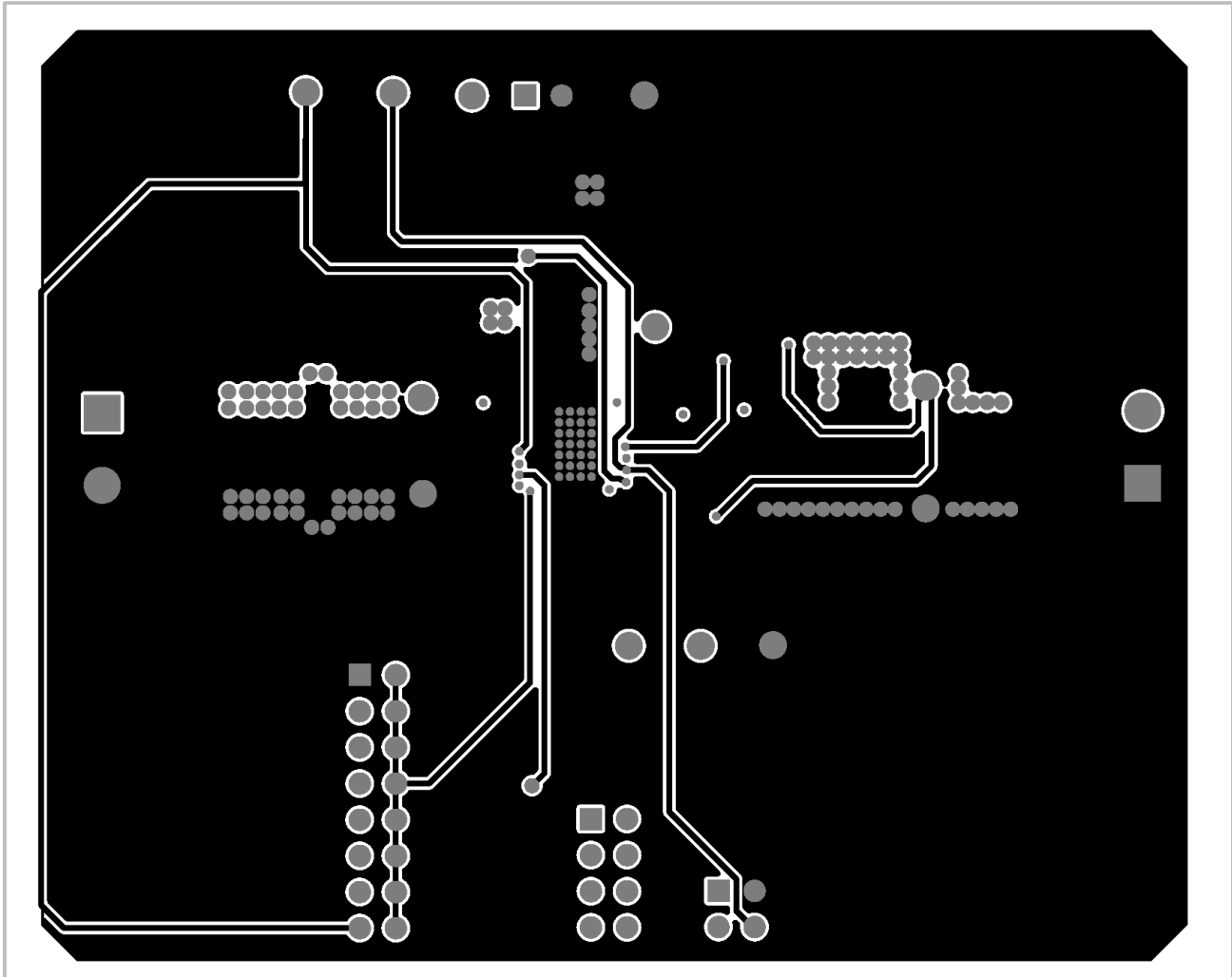
**Figure 8-3. TPS53319EVM-136 Top Copper**



**Figure 8-4. TPS53319EVM-136 Layer 2 Copper**



**Figure 8-5. TPS53319EVM-136 Layer 3 Copper**



**Figure 8-6. TPS53319EVM-136 Layer 4 Copper**

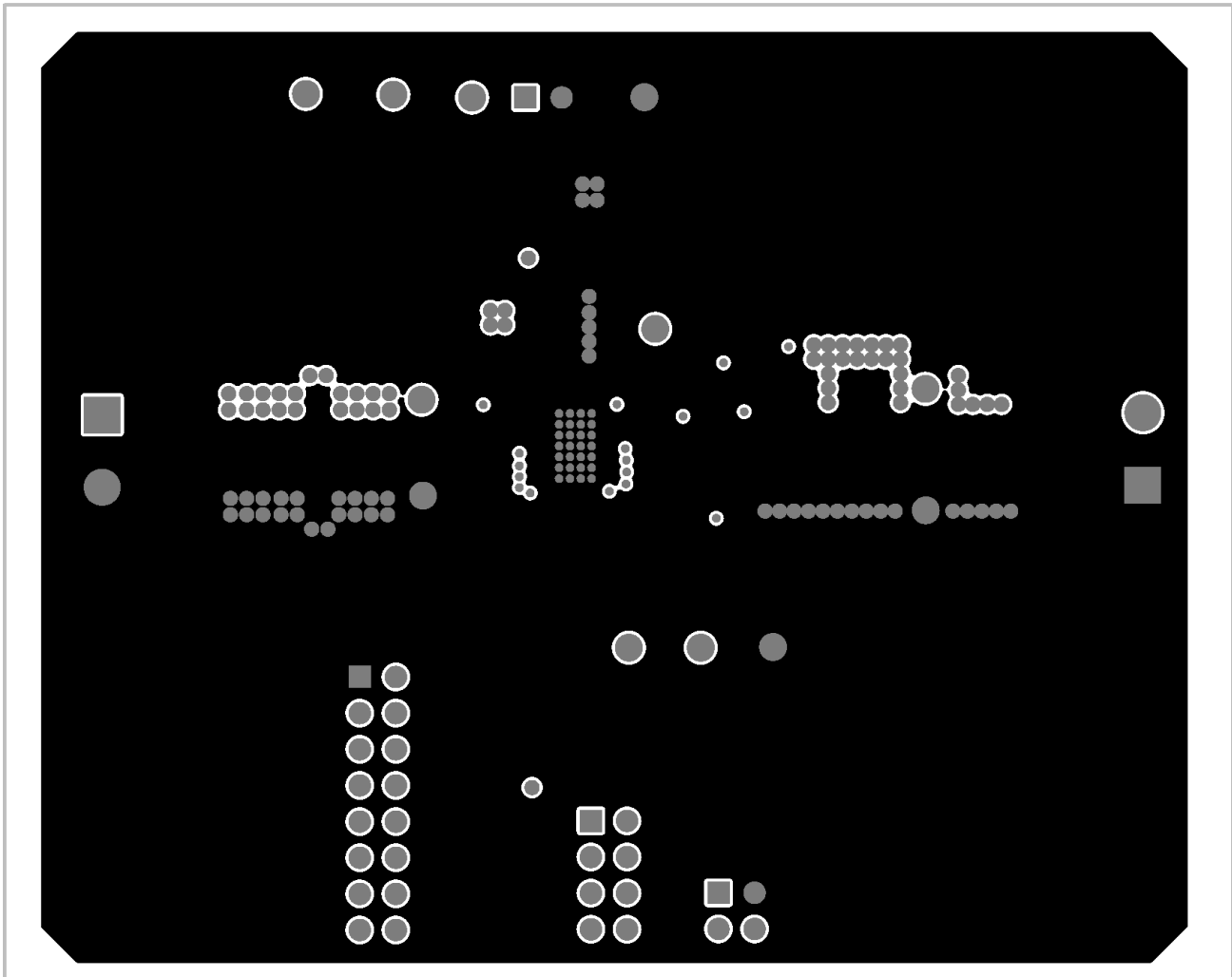
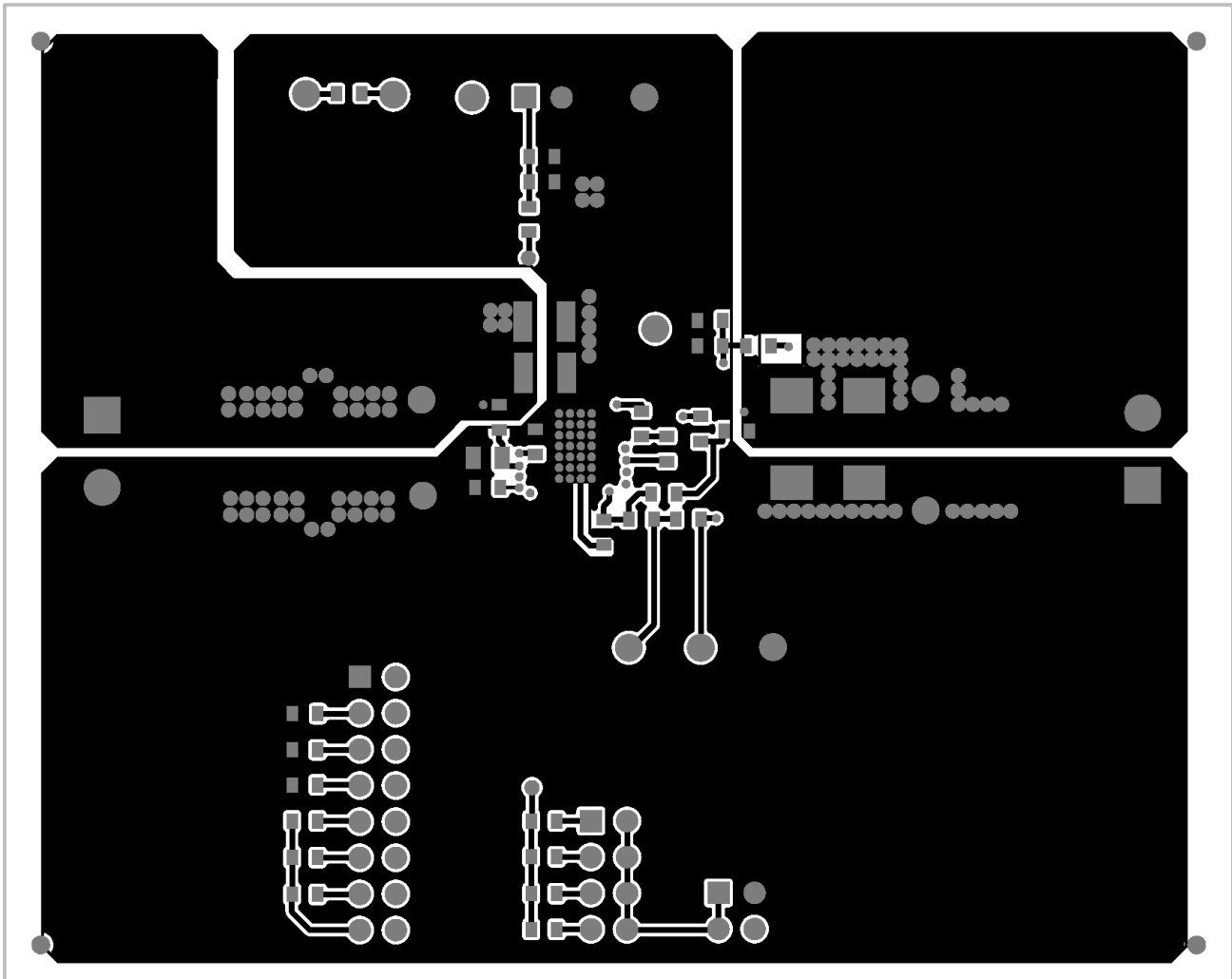


Figure 8-7. TPS53319EVM-136 Layer 5 Copper



**Figure 8-8. TPS53319EVM-136 Bottom Layer Copper**

## 9 Bill of Materials

Table 9-1 list the EVM components according to the schematic shown in Figure 3-1.

**Table 9-1. Components List**

| QTY. | RefDes       | Description  | MFR   | Part Number   |
|------|--------------|--|-------|---------------|
| 2    | C1, C2       | Capacitor, Ceramic, 22 $\mu$ F, 25 V, X5R, 20%, 1210                                       | STD   | STD           |
| 3    | C7, C8, C9   | Capacitor, Ceramic, 100 $\mu$ F, 6.3 V, X5R, 20%, 1210                                     | STD   | STD           |
| 1    | C13          | Capacitor, Ceramic, 4.7 $\mu$ F, 25 V, X5R, 20%, 0805                                      | STD   | STD           |
| 1    | C14          | Capacitor, Ceramic, 1 $\mu$ F, 50 V, X7R, 10%, 0603  | STD   | STD           |
| 2    | C18, C19     | Capacitor, Ceramic, 1000 pF, 50 V, X7R, 10%, 0603  | STD   | STD           |
| 3    | C5, C15, C17 | Capacitor, Ceramic, 0.1 $\mu$ F, 50 V, X7R, 10%, 0603                                      | STD   | STD           |
| 1    | C20          | Capacitor, Ceramic, 100 pF, 50 V, X7R, 10%, 0603   | STD   | STD           |
| 1    | L1           | Inductor, SMT, 500 nH $\pm$ 15%, 17 A, DCR: 0.29 m $\Omega$ $\pm$ 10%, 7 mm $\times$ 11 mm | Delta | HCB1175-501TI |
| 1    | R1           | Resistor, Chip, 0, 1/16W, 1%, 0603   | STD   | STD           |
| 1    | R7           | Resistor, Chip, 3.01, 1/16W, 1%, 0603  | STD   | STD           |
| 2    | R10, R23     | Resistor, Chip, 14.7 k, 1/16W, 1%, 0603  | STD   | STD           |
| 1    | R11          | Resistor, Chip, 10, 1/16W, 1%, 0603  | STD   | STD           |
| 1    | R13          | Resistor, Chip, 187 k, 1/16W, 1%, 0603   | STD   | STD           |
| 1    | R14          | Resistor, Chip, 619 k, 1/16W, 1%, 0603   | STD   | STD           |
| 1    | R16          | Resistor, Chip, 866 k, 1/16W, 1%, 0603   | STD   | STD           |
| 1    | R17          | Resistor, Chip, 309 k, 1/16W, 1%, 0603   | STD   | STD           |
| 1    | R18          | Resistor, Chip, 124 k, 1/16W, 1%, 0603   | STD   | STD           |
| 1    | R19          | Resistor, Chip, 39.2 k, 1/16W, 1%, 0603  | STD   | STD           |
| 1    | R2           | Resistor, Chip, 169 k, 1/16W, 1%, 0603   | STD   | STD           |
| 1    | R22          | Resistor, Chip, 475 k, 1/16W, 1%, 0603   | STD   | STD           |
| 2    | R3, R21      | Resistor, Chip, 200 k, 1/16W, 5%, 0603   | STD   | STD           |
| 1    | R4           | Resistor, Chip, 86.6 k, 1/16W, 1%, 0603  | STD   | STD           |
| 1    | R5           | Resistor, Chip, 1.00 k, 1/16W, 1%, 0603  | STD   | STD           |
| 2    | R6, R20      | Resistor, Chip, 100 k, 1/16W, 1%, 0603   | STD   | STD           |
| 1    | R9           | Resistor, Chip, 3.01 k, 1/16W, 1%, 0603  | STD   | STD           |
| 2    | R12, R24     | Resistor, Chip, 10.0 k, 1/16W, 1%, 0603  | STD   | STD           |
| 1    | U1           | IC, 14-A synchronous buck converter with integrated MOSFETs, DQP-22                        | TI    | TPS53319DQP   |

## 10 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

| Changes from Revision * (May 2012) to Revision A (December 2021)                                       | Page |
|--|------|
| • Updated the numbering format for tables, figures, and cross-references throughout the document. .... | 3    |
| • Updated the user's guide title.....  | 3    |

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