User's Guide LP87725Q1EVM Evaluation Module



ABSTRACT

The LP87725-Q1 device is designed to meet the power management requirements of the AWR, IWR and other MMICs in various automotive and industrial radar applications. The device has three step-down DC/DC converters, a LDO regulator and a load switch. The LDO is powered externally and intended for Ethernet device core supply. The load switch is intended to cut off the 3.3 V IO supply during the sensor sleep mode The device is controlled by an I2C serial interface and by enable signal. The step-down DC/DC converters support programmable switching frequency of 17.6 MHz, 8.8 MHz or 4.4 MHz and have low noise across wide frequency range which enables LDO-free power design with minimal or no additional passive filtering. LP87725-Q1 device offers flexible external component selection to optimize the design in terms of performance or cost. The features of the device target safety-relevant applications with system-safety requirements up to ASIL-B level.

This user's guide provides instructions to power-up and evaluate LP87725-Q1 device using the LP87725Q1EVM evaluation module (EVM) and software user interface (LP87725-Q1 GUI). By default LP87725Q1EVM has LP87725101RAGRQ1 device OTP version (17.6 MHz), but this EVM can also be used to evaluate another OTP device from LP8772x-Q1 product family.



CAUTION Hot surface. Contact can cause burns. Do not touch!

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1 Top View with Basic External Connections

Figure 1-1 shows the top view of the EVM along with basic connections. By default, EVM is configured to power-up through VBAT supply via onboard 12 V VIN to 3.3 V VOUT preregulator. EVM can also be powered through external 3.3 V supply or through USB port. Please refer to Table 3-2 for the right jumper configuration for each power supply input.

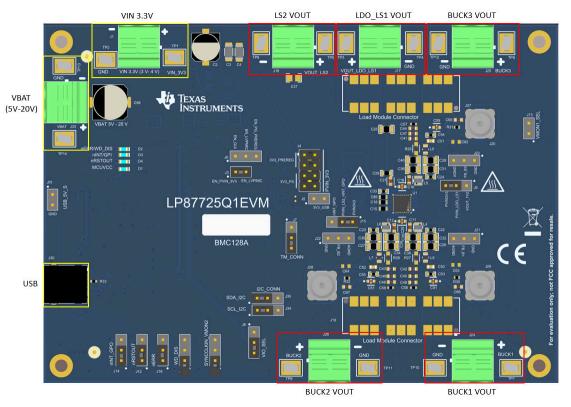


Figure 1-1. EVM Board Top View with Basic Connections and Default Jumpers



2 Input, Output Voltages, and Load Current Requirements

LP87725-Q1 device works with 3.3 V input supply and supply is internally monitored for undervoltage (UV) and overvoltage (OV) conditions, therefore, keep the input supply voltage within range specified in Table 2-1 to avoid input supply UV/OV detection.

- If the VBAT/preregulator path is used (default configuration), then the input supply to the device is already regulated to 3.3 V.
- If an external 3.3 V supply is used, then verify that input supply voltage is always within the recommended voltage range and drop across supply path must be considered.
- If the EVM is configured to work with USB supply, then regulators must not be loaded.

 Table 2-1 lists the input and output voltage for each regulator and the maximum load current requirements. Refer

 to LP87725-Q1 device data sheet for more information about device electrical characteristics and the features.

	Table 2 11 mpat and Catpat Voltageo, and Load	e all elle l'équiler	
Regulator Name	Input Supply Voltage at PMIC Supply Pin	Output Voltage	Maximum Load Current
BUCK1	3.1 V - 3.49 V	1.8 V	3.5 A
BUCK2	3.1 V - 3.49 V	1.0 V	3.5 A
BUCK3	3.1 V - 3.49 V	1.2 V	3.5 A
LDO_LS1	3.1 V - 3.49 V	1.0 V	0.6 A
LS2	3.1 V - 3.49 V	3.1 V - 3.49 V	0.4 A

Table 2-1 li	nnut and O	utnut Voltagos	and Load C	urrent Pea	uiromonte
	nput and O	utput Voltages	, anu Loau G	unent Req	unements

If all the regulators are loaded with maximum load current simultaneously, then PMIC and PCB can become hot. Make sure that PMIC junction temperature does not exceed 150 °C.

3 Jumpers and Connectors

LP87725Q1EVM has many terminal blocks, jumpers and test points to offer certain flexibility to help users to verify the EVM according to their application conditions. However, the EVM is pre-configured with default jumper settings and users can power-up the regulators without the need of jumper modifications. Setting these jumpers correctly for the correct function of the EVM is important. Table 3-1 lists all the terminal blocks on the EVM and Table 3-2 lists the jumpers and their functionality. All the terminal blocks are marked with polarity and Pin 1 of test points / jumpers are marked with white dot for identification purpose. To understand more about the jumper functionality, see the schematic diagrams in Section 6.1.

Terminal Block Number	Terminal Block Name	Description	
J1	VIN 3.3 V	3.3 V External Input Voltage	
J17	VOUT_LDO_LS1	Terminal block for LDO, LS1 Output	
J18	VOUT_LS2	Terminal block for LS2 Output	
J24	BUCK1	Terminal block for BUCK1 Output	
J25	BUCK3	Terminal block for BUCK3 Output	
J26	BUCK2	Terminal block for BUCK2 Output	
J30	J30	USB Connector	
J33	VBAT	5 V - 20 V Input	

Table 3-1. Terminal Blocks



Jumper/Connector Number	Jumper/Connector Name	Configuration	Description
		Option 1: Pin 2 and 3	Pull down resistor on nERR/WD_DIS pin enables Q&A watchdog during the PMIC power-up. For this to be effective, J7 must be closed on Pin 2/3.
J2	WD_DIS	Option 2: Pin 1 and 2	nERR/WD_DIS pin is pulled up to VIO.
		Open (default)	Neither Q&A watchdog enabled during the PMIC power-up nor nERR/WD_DIS pin is pulled up to VIO
J3		Closed (Default)	Connects PMIC ENABLE pin to PVIN_Bx pins (PVIN_3V3) and device gets enabled as soon as 3.3 V is generated/ applied
00	EN_PVIN_3V3	Open	If PMIC needs to be enabled through USB/GUI or through pre-regulator PGOOD signal, then this jumper must be kept open
J4	PVIN_3V3	Option 1: Pins 1/3 and 2/4 3V3_PREREG (Default)	PVIN_3V3 connected to preregulator output. J4-Option-2 must be open and J5 must be open.
	_	Option 2: Pins 5/7 and 6/8 3V3_PS	PVIN_3V3 connected to external 3.3V supply (J1). J4-Option-1 must be open and J5 must be open.
		Open (Default)	Either option from J4 must be used.
J5	3V3_USB	Closed	PMIC input supply (PVIN_3V3) is generated from USB supply. J4 jumpers must be open if this jumper is closed.
	EN_LVPMIC	Option 1: Open (Default)	PMIC Enable signal from 3.3 V Input. J3 must be closed
J6		Option 2: Pins 1 and 2	PMIC Enable signal path from GUI interface. J3 must be open if this option is used
		Option 3: Pins 2 and 3	PMIC Enable signal path from pre-regulator PGOOD signal. J3 must be open if this option is used
10		Pins 1 and 2	3.3 V supply generated from USB supply
J8	VIO_SEL	Pins 2 and 3 (Default)	3.3 V VIO supply generated from PVIN3V3
J9	J9 PVIN_LDO_LS1		Input to the LDO_LS1 is taken from BUCK3 and 1.2 V is supplied as a result.
			Input to the LDO_LS1 is taken from PVIN3V3 (3.3 V)
J10	SYNCCLK/VMON2	Pin 1 and 2	VOUT_LS2/ VMON2/ SYNCCLK pin connected to MCU clock port (used for testing external clock input signal)
510	STINCOLINY WIDINZ	Pin 2 and 3	Input 1.2 V from BUCK3 and flexibility to change voltage through voltage resistor divider to VMON2
		Pins 1 and 2 (Default)	Connects PMIC nRSTOUT signal to MCU port directly
J12	nRSTOUT	Pins 2 and 3	Connects PMIC nRSTOUT signal to MCU port through level shifter
J13 VMON1_SE	VMON1 SEL	Closed	VMON1 reference voltage generated from voltage divider from BUCK1 (1.8 V) supply
	_	Open (Default)	PMIC is not connected to monitor VMON1
J14	nINT/GPIO	Pins 1 and 2 (Default)	Connects PMIC nINT or GPIO signal to MCU port directly. This is valid only if J15 is closed on Pin 2 and 3.
		Pins 2 and 3	Connects PMIC nINT or GPIO signal to MCU port through level shifter.This is valid only if J15 is closed on Pin 2 and 3
		Pins 1 and 2 (Default)	LS2 is input supply connected to PVIN3V3 (3.3 V)
J15	PVIN_LS2/nINT/GPIO	Pins 2 and 3	nINT or GPIO signals connected to J14 which connects to either MCU port directly or through level shifter depending on J14 jumper selection.

Table 3-2. Configuration Jumpers



Jumper/Connector Number	Jumper/Connector Name	Configuration	Description
		Pins 1 and 2	Connects PMIC nERR/WD_DIS signal to MCU port directly
J16	nERR	Pins 2 and 3	Connects PMIC nERR/WD_DIS signal to MCU port through level shifter (series resistors must be mounted if this option is used)
		Pins 1 and 2 (Default)	Connects PMIC SCL_I2C signal to MCU SCL_I2C port directly
J34		Pins 2 and 3	Connects PMIC SCL_I2C signal to MCU SCL_I2C port through a level shifter (series resistors need to be mounted if this option is used)
J35	120_00111	Pins 1 and 2 (Default)	Connects PMIC SDA_I2C signal to MCU SDA_I2C port directly
	Pins 2 and 3	Connects PMIC SDA_I2C signal to MCU SDA_I2C port through a level shifter (series resistors need to be mounted if this option is used)	

Table 3-2. Configuration Jumpers (continued)

3.1 Test Points

Table 3-3 lists all the available connectors on the EVM.

Connector Number	Connector Name	Description
J9/J15	PVIN3V3	Can be used to test or measure the input voltage of the PMIC
J19	Load Module Connector	Connector placeholder for PMICLOADBOARDEVM for doing load transient testing
J20	Load Module Connector	Connector placeholder for PMICLOADBOARDEVM for doing load transient testing
J21	FB_B1	Test point to measure the BUCK1 feedback signal
J22	FB_B2	Test point to measure the BUCK2 feedback signal
J23	FB_B3	Test point to measure the BUCK3 feedback signal
J27	J27	SMA connector for BUCK3 noise measurement
J28	J28	SMA connector for BUCK2 noise measurement
J29	J29	SMA connector for BUCK1 noise measurement
J31	USB_5V_S	Test point to measure 5 V supply from USB cable

Table 3-3. Test Points on the EVM



4 Getting Started

In default configuration of EVM, connecting +12 V and GND to the VBAT terminal block (J33) powers up the EVM. While loading the regulators, make sure that input power supply has sufficient current source capabilities to prevent supply voltage collapse due to current limiting.

EVM can also be powered through external 3.3 V input supply or through USB power by modifying jumper settings on the EVM. Table 4-1 describes the jumper settings for different supply options.

Power Source	Input Voltage Range	Jumpers		
VBAT	5 V - 20 V	Both 3V3_PREREG jumpers on J4 (Default option). Leave J5 open.		
Vin 3.3 V	3.1 V - 3.49 V	Remove 3V3_PREREG jumpers on J4 and place them on 3V3_PS position on J4. With this configuration, do not apply power to VBAT terminal. Leave J5 open.		
USB	5 V USB cable	J5, 3V3_USB. With this option, jumpers on J4 must be removed.		

The LP87725Q1EVM does not require any specific power-down sequence. The EVM can be powered down by turning off the power supply or by toggling the EN Pin off in the GUI, if the GUI control signal is used to enable/disable the device. Refer to Table 3-2 and GUI for more information about configuring jumpers and using GUI.

4.1 GUI

Texas Instruments provides a simple to use LP87725-Q1 GUI tool to enable, configure, and evaluate the various features of the LP87725-Q1 device on the EVM. Please refer to the GUI *README.md* file in the GUI tool's *Help->View README.md* tab for a more detailed description of this tool.

The GUI runs on most PC platforms and requires a USB port for connecting the EVM to the host computer. The EVM USB connector is type-C and a type-A to type-C cable is provided along with the EVM to connect to the host computer. EVM gets automatically connected to the GUI after the USB cable is connected and manual assignment of COM port is not necessary. If *Hardware not Connected* displays on the bottom left of the GUI, clicking *Click to connect to hardware* icon next re-establish the connection. The GUI uses the ACCtrl COM port which can be found from the device manager of the operating system.

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4.2 GUI Installation and Working with GUI

The GUI can be found here and the GUI can be run in browser or can be installed to the computer. Figure 4-1 shows the default interface of GUI. Please refer to the *README.md* file in the GUI tool for a complete guide on how to use the tool.

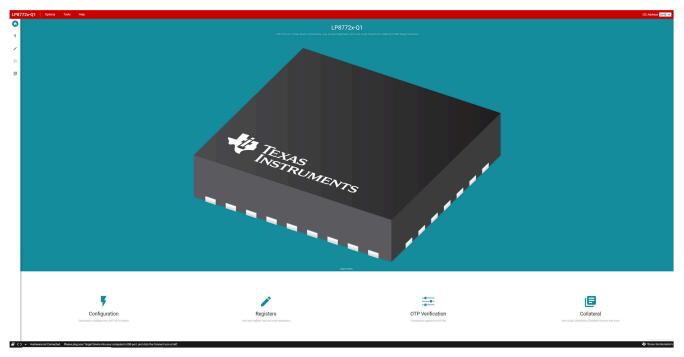


Figure 4-1. GUI Front Page

The EVM can be configured in the configuration page as shown in Figure 4-2. By default, all the configuration registers are locked and CRC protected. Clicking the *Unlock registers* check box on the Configuration Page automatically writes REGISTER_LOCK_STATUS =0x9B to unlock the configuration registers for write operation. CRC can be disabled by writing CONFIG_CRC_EN = 0h through Console window (Options \rightarrow Show Console) or GUI Register Map Page. For example, output voltages, startup and shutdown delays and peak current limits can be changed for each buck converter.



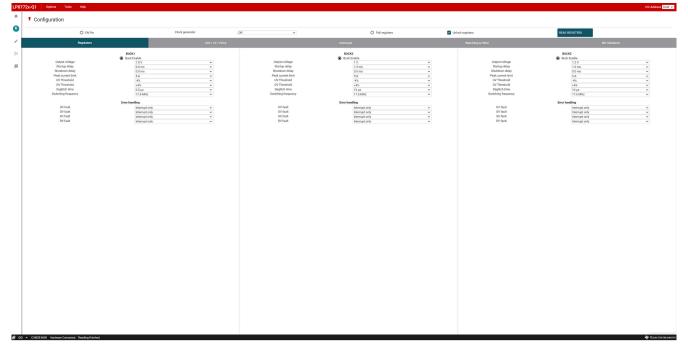


Figure 4-2. GUI Configuration Page

In the register map page shown in Figure 4-3, registers can be read or written to.

Register Map										Add	to Read Off	V READ RED	STER READ ALL REDISTE	sa were example were an economic immedia
learch Registers by name or address (0x)												C Search I	Rtfields 🔽 Show Bits	
									Rits					FIELD VIEW
	Register Name		Address	Value	7	ő	5	4		3	2	1	0	DEV_REV
EVICE														DEVICE / DEV_REV / TI_DEVICE_ID[7:0]
V9A_V9C		0	0x01	0x96	1	0	0	1		0	1	1	0	Device / Devidev / T(Device_D)/U
WM,000E,1			Dx02	0x00	0	0	0	0		0	0	0	0	ralize
WM_0006_2			0x03	0x00	0	0	0	0		0	0	0	0	
AANUFACTURING_VER			0x04	0x00	0	0	0	0		0	0	0	0	
SM_COMMAND_REG			0x05	0x00	0	0	0	0		0	0	0	0	
LOCK_EN_CTRL			0x06	0x7F		1	1	1		1	1	1	1	
ECOV_ENT_CONTROL			0x07	0x00								0	0	
ISM_START_REG			Dx08	0x00									0	
EGISTERLLOCK			0x09	0x01									1	
CRATCH_PAD_RDG_1			Ou0A	0x00	0	0	0	0		0	0	0	0	
ICRATCH_PAD_REG_2			0x08	0x00	0	0	0	0		0	0	0	0	
ICRATCH_PAD_REG_3			0x0C	0x00	0	0	0	0		0	0	0	0	
ICPATCH_PAD_RDG_4			0x00	0x00	0	0	0	0		0	0	0	0	
VD_ANSWER_REG			DxOE	0x00	0	0	0	0		0	0	0	0	
VD_ENABLE_REG			0x0F	0x03								1	1	
MO_MODE_REG			Dx10	0x00							0	0	0	
IUCKL_VOUT			0x11	0x20			1	0		1	1	0	1	
IUCK2_VOUT			0x12	0x05			0	0		0	1	0	1	
NCK3,VOUT			0x13	Geor			0	0		1	1	1	1	
DOLLS1_VMON1_POLLEVEL			0x14	0x10	0	0	0	1		0	0	0	0	
32_VMON2_PG_LEVEL			0x15	0x70		1	1	1		0	0	0	0	
OCA_PG_LEVEL			0x16	0x70		1	1	1		0	0	0	0	
NOK1_MON_CONF			0x17	0x57	0	1	0	1		0	1	1	1	
NCK2_MON_COMP			0x18	0x57	0	1	0	1		0	1	1	1	
SUCK3_MON_COMP			0x19	0x57	0	1	0	1		0	1	1	1	
DO_LS1_VMON1_MON_CONF			0x1A	0xF4	1	1	1	1		0	1	0	0	
52, VMON2, MON, CONF			0x18	0xA4	1	0	1	0		0	1	0	0	
LK_CONF			0x1C	0x05	0	0	0	0		0	1	0	1	
NTERFACE_CONF			0x1D	0x20	0	0	1	0		1	1	0	1	
UNC_COMP			0x1E	0x40		1	0	0		0	0	0	0	
CCA_MON_CONF			0x1F	0xFB	1	1	1	1		1	0	1	1	
NKK,LDO,LS1,VMON1,DESLIT			0x20	OxEB	1	1	1	0		1	0	0	0	
SUCK1_SEQUENCE			0x21	0x00	0	0	0	0		0	0	0	0	
UCH2_SEQUENCE			0x22	0x03	0	0	0	0		0	0	1	1	
NUCKO, SEQUENCE			0x23	0x02	0	0	0	0		0	o	1	0	
DOLLS1_VMON1_SEQUENCE			0x24	0x04	0	0	0	0		0	1	0	0	
s2_vMon2_SEQUENCE			0x25	0x01	0	0	0	0		0	0	0	1	
PO_SEQUENCE			0126	0x09	0	0	0	0		1	0	0	1	
eksTouT_SEQUENCE			0x27	0x09	0	0	0	0		1	0	0	1	
ES,OV,COMF			0x28	0x00	0	0	0	0		0	0	0	0	
EG,UY,COMP			0x29	0x00	0	0	0	0		0	0	0	0	
E0_SC_COMF			0x2A	0x00	0	0	0	0		0	0	0	0	
CCA_LS2_VMON2_0V_CONF			0x28	0x80	1	0	0	0		0	0	0	0	
CCA_LS2_WMON2_UV_CONF			0x20	0x00	0	0	0	0		0	0	0	0	
AASK_BUCK1_2			0x2D	0x00	0	0	0	0		0	0	0	0	
AASK_BUCK3_LD0_LS1_VMONT			0x28	0x00	0	0	0	0		0	0	0	0	
MASK_LS2_VMON2			0x2F	0x00						0	0	0	0	
AASK_VOCA			0x30	0x00								0	0	
MASK_STARTUP			0x31	0x00								0	0	
ALOY LODG			6-97	0.00				0						*

Figure 4-3. GUI Register Map Page



5 Watchdog Configuration

This section provides the basic overview of the I2C based Q&A watchdog algorithm implemented on the EVM. Please refer LP87725-Q1 device data sheet for more detailed information about device watchdog functionality. The watchdog requires specific answers from the host MCU in specific time intervals to detect correct operation of the MCU. On the EVM, MSP432 MCU is used as a host MCU.

During operation, the device provides a question for the MCU and the MCU calculates the required 32-bit answer. This answer is split into four answer bytes: Answer-3, Answer-2, Answer-1 and Answer-0. The MCU writes these answer bytes one byte at a time into WD_ANSWER[7:0] from the I2C.

A good event occurs when the MCU sends the correct answer-bytes calculated for the current question in the correct watchdog window and in the correct sequence. This sequence is visualized in Figure 5-1

A bad event occurs when one of the events that follows occur:

- The MCU sends the correct answer-bytes, but not in the correct watchdog window.
- The MCU sends incorrect answer-bytes.
- · The MCU returns correct answer-bytes, but in the incorrect sequence.

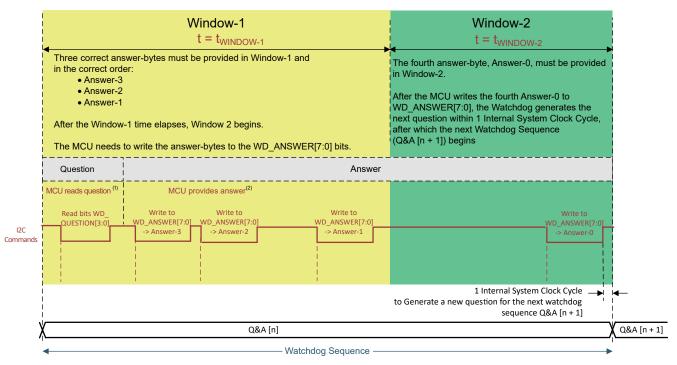


Figure 5-1. Watchdog Sequence in Q&A Mode

In GUI, there are two sections in configuration tab for watchdog configurability. Figure 5-2 illustrates the watchdog validation section in GUI, where the delays between the WD Answers can be configured and watchdog status for different interrupts and errors can be observed. And if required status can be cleared through clear buttons available next to the each status. In the other watchdog configuration section, watchdog can be enabled or disabled along with other watchdog configurable parameters as shown in Figure 5-3. For further information on watchdog configuration, refer to the data sheet of LP87725-Q1 for watchdog section.



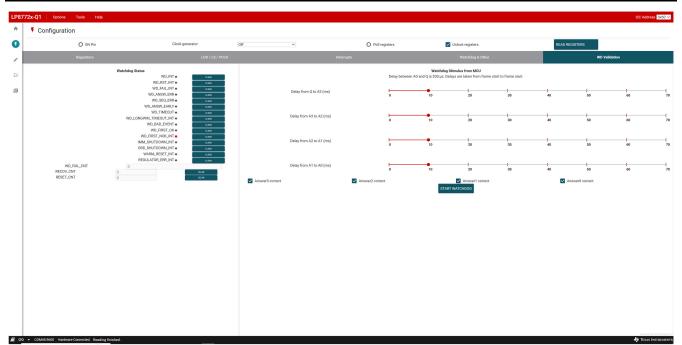


Figure 5-2. GUI Watchdog Validation Configuration

O EN Pin	Clock generator	off v	O Poll registers	Unlock registers	READ REGISTERS
Regulators	LDO/LS/VC	CCA	Interrupts	Watchdog & Other	WD Validation
Watchdog.config @ Watchdog.back Peturn to bioxperiado @ Yatchdog.nest entry @ Yatchdog.nest entry @ Yatchdog. @ Jat Ferst @ Wolfwart @ UW Windown 1 50.1555	w ble 5.44 ms v 55.0175 ms v	External clock frequency	Larapit Person de activitation Person de activitati	Valdadge J elited Maddie for HISTOUT suppo- INSTOUT object golarity vNHT function	Enable internal pull up for pBSTOUT

Figure 5-3. GUI Watchdog Configuration



6 Schematics, Layout and BOM

This section contains the schematics, layout and the bill of materials for the LP87725Q1EVM.

6.1 Schematic Diagram

This section includes images of the EVM schematics and different layers of the layout.

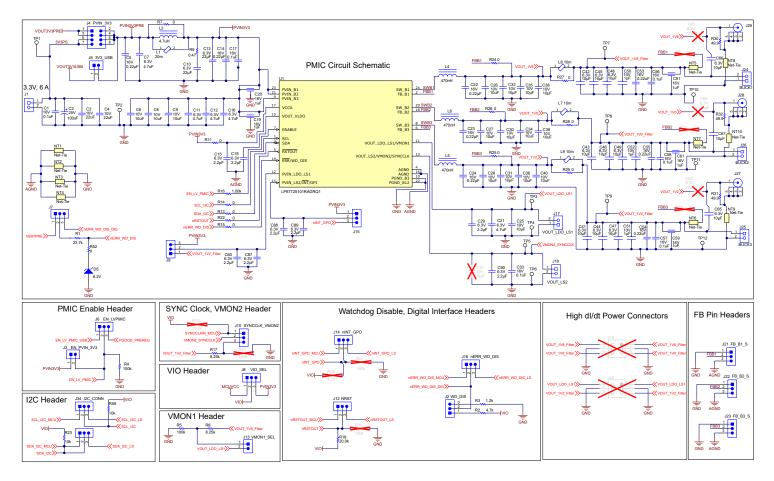
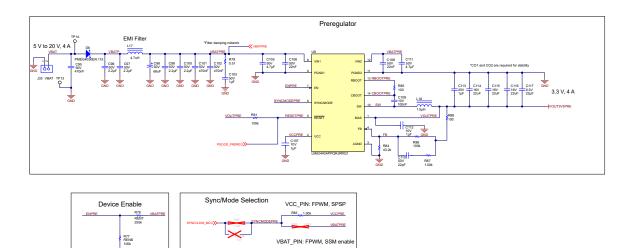
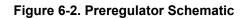


Figure 6-1. PMIC Schematic







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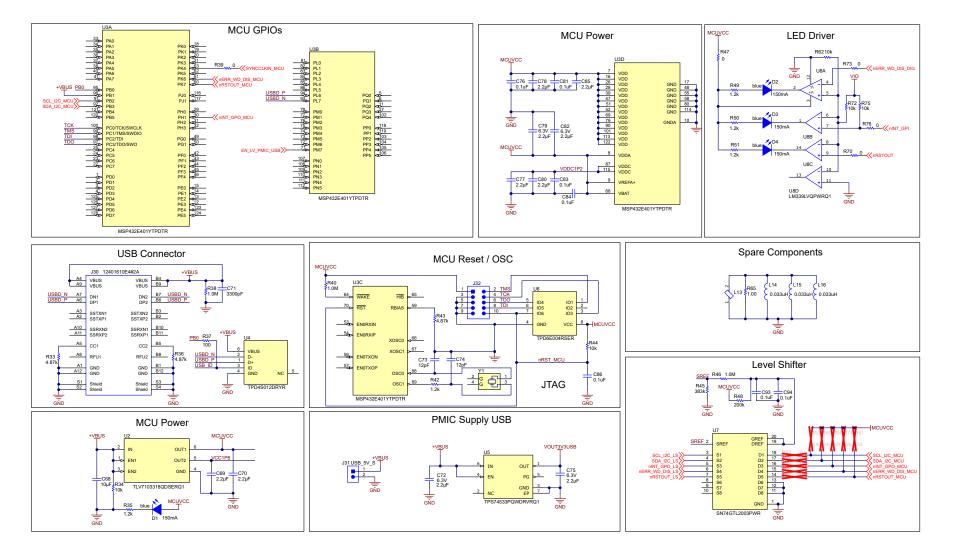


Figure 6-3. MCU Schematic



6.2 PCB Layer Diagram

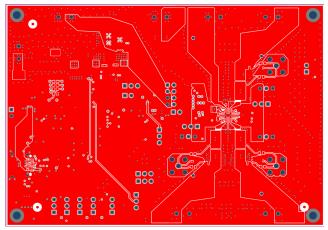


Figure 6-4. Layout of Top Layer, Layer 1

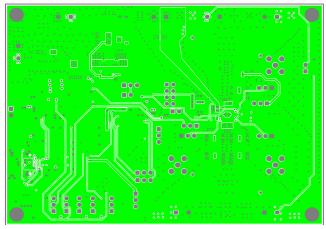


Figure 6-6. Layout of Signal Layer 1, Layer 3

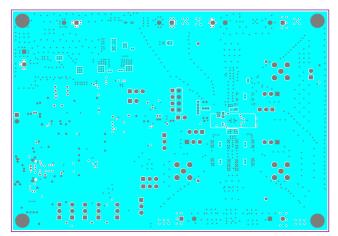


Figure 6-8. Layout of Ground Layer 2, Layer 5

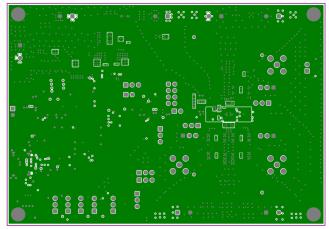


Figure 6-5. Layout of Ground layer 1, Layer 2

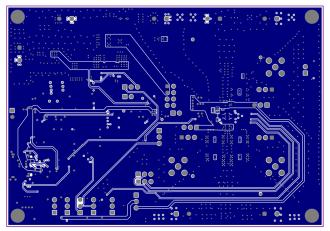


Figure 6-7. Layout of Signal Layer 2, Layer 4

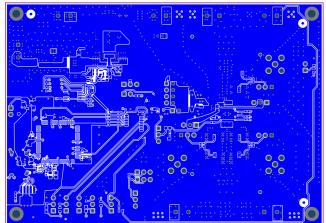


Figure 6-9. Layout of Bottom Layer, Layer 6



6.3 Bill of Materials

Table 6-1 lists all the components on the EVM.

Table 6-1. Bill of Materials

Designator	Quantity	Description	Part Number	Manufacturer
!PCB1	1	Printed Circuit Board	BMC128	Any
C1, C17, C33, C56, C57, C58, C76, C81, C83, C84, C86, C93, C94	13	CAP, CERM, 0.1 uF, 16 V, +/- 10%, X7R, 0402	GCM155R71C104KA55D	MuRata
C2	1	CAP, Polymer Hybrid, 100 uF, 25 V, +/- 20%, 30 ohm, 6.3x7.7 SMD	EEHZC1E101XP	Panasonic
C3, C4	2	CAP, CERM, 22 uF, 10 V, +/- 10%, X7R, AEC- Q200 Grade 1, 1206	GCM31CR71A226KE02L	MuRata
C5, C14, C22, C23, C24	5	CAP, CERM, 0.22 μF, 16 V,+/- 10%, X7R, AEC-Q200 Grade 1, 0402	GCM155R71C224KE02D	MuRata
C6, C8, C9, C25, C26, C27, C28, C30, C31, C32, C34, C35, C36, C38, C39, C40, C68	17	CAP, CERM, 10 uF, 10 V, +/- 10%, X7R, 0805	GCM21BR71A106KE22L	MuRata
C7, C11, C12, C16, C21	5	Cap Ceramic Multilayer 4.7 uF 6.3 V DC 10% SMD Paper T/R	GCJ188C70J475KE02J	Murata
C10, C13, C117	3	CAP, CERM, 22 μF, 6.3 V,+/- 20%, X7T, AEC- Q200 Grade 1, 0805	CGA4J1X7T0J226M	TDK
C15, C18, C29, C60, C87, C88, C89, C90	8	CAP, CERM, 2.2 µF, 6.3 V,+/- 10%, X7R, 0603	GCM188R70J225KE22J	MuRata
C19, C20, C59, C61, C91	5	3 Terminals Low ESL Chip Multilayer Ceramic Capacitors for Automotive	NFM18HC105C1C3D	Murata
C41, C42, C43, C44, C45, C46, C47, C48, C49, C65, C66, C67	12	Chip Multilayer Ceramic Capacitors for Automotive	GCM188D70J106ME36D	Murata
C50, C51, C52, C107, C112	5	CAP CER 0603 1UF 10 V X7R 10%	C0603C105K8RACAUTO	KEMET
C53, C54, C55	3	CAP, CERM, 0.22 uF, 16 V, +/- 10%, X7R, 0402	GRM155R71C224KA12D	MuRata
C69, C70, C72, C75, C77, C78, C79, C80, C82, C85	10	CAP, CERM, 2.2 uF, 6.3 V, +/- 10%, X7R, AEC-Q200 Grade 1, 0603	GCM188R70J225KE22D	MuRata
C71	1	CAP, CERM, 3300 pF, 50 V, +/- 10%, X7R, 0603	C0603C332K5RACTU	Kemet
C73, C74	2	CAP, CERM, 12 pF, 50 V,+/- 5%, C0G/NP0, AEC-Q200 Grade 1, 0402	CGA2B2C0G1H120J050BA	ТДК
C95, C101, C102	3	CAP, CERM, 0.47 uF, 50 V, +/- 10%, X7R, AEC-Q200 Grade 1, 0603	CGA3E3X7R1H474K080AE	TDK
C96, C97, C99, C100	4	CAP, CERM, 2.2 uF, 50 V, +/- 10%, X7R, AEC- Q200 Grade 1, 0805	CGA4J3X7R1H225K125AB	TDK
C98	1	CAP, Polymer Hybrid, 68 uF, 50 V, +/- 20%, 30 ohm, 8x10 SMD	EEHZA1H680P	Panasonic
C103	1	CAP, CERM, 1 uF, 50 V, +/- 10%, X7R, 0603	UMK107AB7105KA-T	Taiyo Yuden
C105, C111	2	CAP, CERM, 4.7 μF, 50 V,+/- 20%, X7R, AEC- Q200 Grade 1, 1210	UMK325B7475MMHT	Taiyo Yuden
C106, C108	2	CAP, CERM, 0.022 uF, 50 V, +/- 10%, X7R, 0402	GRM155R71H223KA12D	MuRata
C109	1	CAP, CERM, 0.1 uF, 10 V, +/- 10%, X7R, 0603	C0603X104K8RACTU	Kemet
C110	1	C0603 22 pF X7R 30 ppm/°C 10.00% 50 V	C0603C220K5RACAUTO	KEMET
C113	1	CAP, CERM, 1 uF, 25 V, +/- 10%, X7R, 0805	C0805C105K3RACTU	Kemet

Table 6-1. Bill of Materials (continued)							
Designator	Quantity	Description	Part Number	Manufacturer			
C114, C115, C116	3	CAP, CERM, 22 uF, 16 V, +/- 20%, X7R, AEC- Q200 Grade 1, 1210	CGA6P1X7R1C226M250AC	TDK			
D1, D2, D3, D4	4	LED, Blue, SMD	LB Q39G-L2N2-35-1	OSRAM			
D5	1	Diode, Zener, 8.2 V, 500 mW, AEC-Q101, SOD-123	DDZ8V2CQ-7	Diodes Inc.			
D6	1	Diode, Schottky, 40 V, 3 A, AEC-Q101, SOD-123W	PMEG4030ER,115	Nexperia			
H1, H4, H5, H7	4		FC2058-440-A	Fascomp			
H2, H3, H6, H8	4	MACHINE SCREW PAN PHILLIPS 4-40	9900	Keystone			
J1, J17, J18, J24, J25, J26, J33	7	Terminal Block, 5 mm, 2x1, R/A, TH	1792863	Phoenix Contact			
J2, J6, J7, J8, J9, J10, J12, J14, J15, J16, J21, J22, J23, J34, J35	15	Header, 100 mil, 3x1, Gold, TH	HTSW-103-07-G-S	Samtec			
J3, J5, J13, J31	4	Header, 100 mil, 2x1, Gold, TH	HTSW-102-07-G-S	Samtec			
J4	1	Header, 2.54 mm, 4x2, Gold, TH	TSW-104-08-L-D	Samtec			
J27, J28, J29	3	SMA Jack, Straight, 50 Ohm, Gold, TH	SMA-J-P-H-ST-TH1	Samtec			
J30	1	Receptacle, 0.5 mm, USB TYPE C, R/A, SMT	12401610E4#2A	Amphenol Canada			
J32	1	Header (Shrouded), 1.27 mm, 5x2, Gold, SMT	FTSH-105-01-F-DV-K	Samtec			
L1	1	100 Ohms @ 100 MHz 1 Power Line Ferrite Bead 0805 (2012 Metric) 4 A 20 mOhm	MPZ2012S101ATD25	TDK			
L2, L17	2	Inductor, Shielded, Composite, 4.7 uH, 4.5 A, 0.0401 ohm, SMD	XAL4030-472MEB	Coilcraft			
L4, L5, L6	3	Inductor, 470 nH, 4 A, 0.025 ohm, SMD	VCTD20161B-R47MS6	Cyntec			
L7, L8, L9, L13	4	30 Ohms @ 100 MHz 1 Power Line Ferrite Bead 0805 (2012 Metric) 6 A 10 mOhm	MPZ2012S300ATD25	TDK			
L14, L15, L16	3	Fixed Inductor 0.033 uH 30% 4.7 A 9 mOhm 0603	TFM160810ALTA33NNTAA	TDK			
L18	1	Inductor, Shielded, Metal Composite, 1.5 µH, 5.8 A, 0.019 ohm, SMD	74438356015	Wurth Elektronik			
LBL1	1		THT-14-423-10	Brady			
R1	1	23.7 kOhms ±0.1% 0.1W, 1/10W Chip Resistor 0603 (1608 Metric) Automotive AEC- Q200 Thin Film	ERA-3AEB2372V	Panasonic Electronic Components			
R2	1	RES, 4.7 k, 5%, 0.1 W, AEC-Q200 Grade 0, 0603	CRCW06034K70JNEA	Vishay-Dale			
R3, R35, R42, R49, R50, R51	6	RES, 1.2 k, 5%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW04021K20JNED	Vishay-Dale			
R4, R5, R77, R81, R86	5	RES, 100 k, 1%, 0.1 W, 0603	RC0603FR-07100KL	Yageo			
R7, R27, R28, R29	4	RES 0 OHM JUMPER 1/4W 0603	HCJ0603ZT0R00	Stackpole Electronics			
R8, R17	2	RES, 8.25 k, 1%, 0.1 W, AEC-Q200 Grade 0, 0603	CRCW06038K25FKEA	Vishay-Dale			
R9	1	RES, 0.47, 1%, 0.1 W, AEC-Q200 Grade 0, 0603	ERJ-3RQFR47V	Panasonic			
R11	1	RES, 0, 0%, 0.2 W, AEC-Q200 Grade 0, 0402	CRCW04020000Z0EDHP	Vishay-Dale			
R13, R14, R15, R22, R47, R52, R70, R73, R76	9	RES, 0, 5%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW04020000Z0ED	Vishay-Dale			
R16	1	RES, 1.00 k, 0.1%, 0.063 W, AEC-Q200 Grade 0, 0402	ERA-2APB102X	Panasonic			
R18	1	RES, 20.0 k, 1%, 0.1 W, AEC-Q200 Grade 0, 0603	CRCW060320K0FKEA	Vishay-Dale			



Table 6-1. Bill of Materials (continued)							
Designator	Quantity	Description	Part Number	Manufacturer			
R23, R34, R44, R59, R62, R72, R75	7	RES, 10 k, 5%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW040210K0JNED	Vishay-Dale			
R24, R25, R26, R39	4	RES, 0, 5%, 0.1 W, AEC-Q200 Grade 0, 0402	ERJ-2GE0R00X	Panasonic			
R30, R31, R32	3	RES, 49.9, 1%, 0.063 W, AEC-Q200 Grade 0, 0402	RMCF0402FT49R9	Stackpole Electronics Inc			
R33, R36, R43	3	RES, 4.87 k, 1%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW04024K87FKED	Vishay-Dale			
R37	1	RES, 100, 5%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW0402100RJNED	Vishay-Dale			
R38, R40, R46	3	RES, 1.0 M, 5%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW04021M00JNED	Vishay-Dale			
R45	1	RES, 383 k, 1%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW0402383KFKED	Vishay-Dale			
R48	1	RES, 200 k, 5%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW0402200KJNED	Vishay-Dale			
R65	1	RES, 1.00, 1%, 0.1 W, 0603	RC0603FR-071RL	Yageo			
R78	1	RES, 255 k, 1%, 0.1 W, 0603	RC0603FR-07255KL	Yageo			
R79	1	RES, 0.51, 1%, 0.25 W, 0805	CRM0805-FX-R510ELF	Bourns			
R83	1	RES, 1.00 k, 1%, 0.1 W, 0603	RC0603FR-071KL	Yageo			
R84	1	RES, 43.2 k, 1%, 0.1 W, AEC-Q200 Grade 0, 0603	CRCW060343K2FKEA	Vishay-Dale			
R85	1	RES, 100, 5%, 0.1 W, AEC-Q200 Grade 0, 0603	CRCW0603100RJNEA	Vishay-Dale			
R87	1	RES, 1.00 k, 1%, 0.1 W, 0603	ERJ-3EKF1001V	Panasonic			
R88	1	RES, 100, 1%, 0.1 W, 0603	RC0603FR-07100RL	Yageo			
SH-J1, SH-J2, SH-J3, SH-J4, SH-J5, SH-J6, SH-J7, SH-J8, SH-J9, SH-J10, SH-J11, SH- J12, SH-J13, SH-J14	14	Shunt, 100 mil, Gold plated, Black	881545-2	TE Connectivity			
TP1, TP2, TP3, TP4, TP5, TP6, TP7, TP8, TP9, TP10, TP11, TP12, TP13, TP14	14	Test Point, Compact, SMT	5016	Keystone			
U1	1	Three Buck Converters, one Linear Regulator and one Load Switch for AWR and IWR Radar Sensors, VQFN-HR24	LP87725101RAGRQ1	Texas Instruments			
U2	1	Automotive Catalog, Dual, 200 mA, Low-IQ Low-Dropout Regulator for Portable Devices, DSE0006A (WSON-6)	TLV7103318QDSERQ1	Texas Instruments			
U3	1	MSP432E401YTPDT, PDT0128A (TQFP-128)	MSP432E401YTPDTR	Texas Instruments			
U4	1	4-Channel USB ESD Solution with Power Clamp, DRY0006A (USON-6)	TPD4S012DRYR	Texas Instruments			
U5	1	Linear Voltage Regulator IC 1 Output 500 mA 6-WSON (2x2)	TPS74533PQWDRVRQ1	Texas Instruments			
U6	1	Low-Capacitance 6-Channel +/-15 kV ESD Protection Array for High-Speed Data Interfaces, RSE0008A (UQFN-8)	TPD6E004RSER	Texas Instruments			
U7	1	8-BIT BIDIRECTIONAL LOW-VOLTAGE TRANSLATOR, PW0020A (TSSOP-20)	SN74GTL2003PWR	Texas Instruments			
U8	1	Automotive 5.5-V low-voltage standard quad- channel comparator with 1-microsecond delay 14-TSSOP -40 to 125	LM339LVQPWRQ1	Texas Instruments			
U9	1	Automotive 4 A Low Noise Synchronous Buck Regulators, RJR0014A (VQFN-HR-14)	LM62440APPQRJRRQ1	Texas Instruments			

Table 6-1. Bill of Materials (continued)						
Designator	Quantity	Description	Part Number	Manufacturer		
Y1	1	Crystal, 25 MHz, 20 ppm, AEC-Q200 Grade 1, SMD	ECS-250-12-33Q-JES-TR	ECS Inc.		
C37	0	CAP, CERM, 10 uF, 10 V, +/- 10%, X7R, 0805	GCM21BR71A106KE22L	MuRata		
C62, C63, C64	0	Chip Multilayer Ceramic Capacitors for Automotive	GCM188D70J106ME36D	Murata		
C104	0	CAP, CERM, 1000 pF, 50 V, +/- 10%, X7R, 0603	C0603C102K5RACTU	Kemet		
J19, J20	0	Receptacle, 2.5 mm, 3x2, Gold, SMT	6651712-1	TE Connectivity		
R6, R12, R20, R53, R54, R55, R56, R57	0	RES, 0, 5%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW04020000Z0ED	Vishay-Dale		
R10	0	RES, 20.0 k, 1%, 0.1 W, AEC-Q200 Grade 0, 0603	CRCW060320K0FKEA	Vishay-Dale		
R19, R21, R41	0	RES, 100 k, 1%, 0.1 W, 0603	RC0603FR-07100KL	Yageo		
R58	0	RES, 4.7 k, 5%, 0.1 W, AEC-Q200 Grade 0, 0603	CRCW06034K70JNEA	Vishay-Dale		
R61, R63, R66, R68, R74	0	RES, 10 k, 5%, 0.063 W, AEC-Q200 Grade 0, 0402	CRCW040210K0JNED	Vishay-Dale		
R80, R82	0	RES, 1.00 k, 1%, 0.1 W, 0603	RC0603FR-071KL	Yageo		

7 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision * (November 2023) to Revision A (January 2024)				
•	Updated Abstract			
	Updated Table 2-1			
	Updated Table 4-1			
	Updated Figure 5-1			

STANDARD TERMS FOR EVALUATION MODULES

- 1. Delivery: TI delivers TI evaluation boards, kits, or modules, including any accompanying demonstration software, components, and/or documentation which may be provided together or separately (collectively, an "EVM" or "EVMs") to the User ("User") in accordance with the terms set forth herein. User's acceptance of the EVM is expressly subject to the following terms.
 - 1.1 EVMs are intended solely for product or software developers for use in a research and development setting to facilitate feasibility evaluation, experimentation, or scientific analysis of TI semiconductors products. EVMs have no direct function and are not finished products. EVMs shall not be directly or indirectly assembled as a part or subassembly in any finished product. For clarification, any software or software tools provided with the EVM ("Software") shall not be subject to the terms and conditions set forth herein but rather shall be subject to the applicable terms that accompany such Software
 - 1.2 EVMs are not intended for consumer or household use. EVMs may not be sold, sublicensed, leased, rented, loaned, assigned, or otherwise distributed for commercial purposes by Users, in whole or in part, or used in any finished product or production system.
- 2 Limited Warranty and Related Remedies/Disclaimers:
 - 2.1 These terms do not apply to Software. The warranty, if any, for Software is covered in the applicable Software License Agreement.
 - 2.2 TI warrants that the TI EVM will conform to TI's published specifications for ninety (90) days after the date TI delivers such EVM to User. Notwithstanding the foregoing, TI shall not be liable for a nonconforming EVM if (a) the nonconformity was caused by neglect, misuse or mistreatment by an entity other than TI, including improper installation or testing, or for any EVMs that have been altered or modified in any way by an entity other than TI, (b) the nonconformity resulted from User's design, specifications or instructions for such EVMs or improper system design, or (c) User has not paid on time. Testing and other quality control techniques are used to the extent TI deems necessary. TI does not test all parameters of each EVM. User's claims against TI under this Section 2 are void if User fails to notify TI of any apparent defects in the EVMs within ten (10) business days after delivery, or of any hidden defects with ten (10) business days after the defect has been detected.
 - 2.3 TI's sole liability shall be at its option to repair or replace EVMs that fail to conform to the warranty set forth above, or credit User's account for such EVM. TI's liability under this warranty shall be limited to EVMs that are returned during the warranty period to the address designated by TI and that are determined by TI not to conform to such warranty. If TI elects to repair or replace such EVM, TI shall have a reasonable time to repair such EVM or provide replacements. Repaired EVMs shall be warranted for the remainder of the original warranty period. Replaced EVMs shall be warranted for a new full ninety (90) day warranty period.

WARNING

Evaluation Kits are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems.

User shall operate the Evaluation Kit within TI's recommended guidelines and any applicable legal or environmental requirements as well as reasonable and customary safeguards. Failure to set up and/or operate the Evaluation Kit within TI's recommended guidelines may result in personal injury or death or property damage. Proper set up entails following TI's instructions for electrical ratings of interface circuits such as input, output and electrical loads.

NOTE:

EXPOSURE TO ELECTROSTATIC DISCHARGE (ESD) MAY CAUSE DEGREDATION OR FAILURE OF THE EVALUATION KIT; TI RECOMMENDS STORAGE OF THE EVALUATION KIT IN A PROTECTIVE ESD BAG.

3 Regulatory Notices:

3.1 United States

3.1.1 Notice applicable to EVMs not FCC-Approved:

FCC NOTICE: This kit is designed to allow product developers to evaluate electronic components, circuitry, or software associated with the kit to determine whether to incorporate such items in a finished product and software developers to write software applications for use with the end product. This kit is not a finished product and when assembled may not be resold or otherwise marketed unless all required FCC equipment authorizations are first obtained. Operation is subject to the condition that this product not cause harmful interference to licensed radio stations and that this product accept harmful interference. Unless the assembled kit is designed to operate under part 15, part 18 or part 95 of this chapter, the operator of the kit must operate under the authority of an FCC license holder or must secure an experimental authorization under part 5 of this chapter.

3.1.2 For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant:

CAUTION

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

FCC Interference Statement for Class A EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.
- 3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210 or RSS-247

Concerning EVMs Including Radio Transmitters:

This device complies with Industry Canada license-exempt RSSs. Operation is subject to the following two conditions:

(1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Concerning EVMs Including Detachable Antennas:

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur

- 3.3 Japan
 - 3.3.1 Notice for EVMs delivered in Japan: Please see http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_01.page 日本国内に 輸入される評価用キット、ボードについては、次のところをご覧ください。

https://www.ti.com/ja-jp/legal/notice-for-evaluation-kits-delivered-in-japan.html

3.3.2 Notice for Users of EVMs Considered "Radio Frequency Products" in Japan: EVMs entering Japan may not be certified by TI as conforming to Technical Regulations of Radio Law of Japan.

If User uses EVMs in Japan, not certified to Technical Regulations of Radio Law of Japan, User is required to follow the instructions set forth by Radio Law of Japan, which includes, but is not limited to, the instructions below with respect to EVMs (which for the avoidance of doubt are stated strictly for convenience and should be verified by User):

- 1. Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
- 2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
- 3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

【無線電波を送信する製品の開発キットをお使いになる際の注意事項】 開発キットの中には技術基準適合証明を受けて

いないものがあります。 技術適合証明を受けていないもののご使用に際しては、電波法遵守のため、以下のいずれかの 措置を取っていただく必要がありますのでご注意ください。

- 1. 電波法施行規則第6条第1項第1号に基づく平成18年3月28日総務省告示第173号で定められた電波暗室等の試験設備でご使用 いただく。
- 2. 実験局の免許を取得後ご使用いただく。
- 3. 技術基準適合証明を取得後ご使用いただく。
- なお、本製品は、上記の「ご使用にあたっての注意」を譲渡先、移転先に通知しない限り、譲渡、移転できないものとします。 上記を遵守頂けない場合は、電波法の罰則が適用される可能性があることをご留意ください。 日本テキサス・イ

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東京都新宿区西新宿6丁目24番1号

西新宿三井ビル

- 3.3.3 Notice for EVMs for Power Line Communication: Please see http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_02.page 電力線搬送波通信についての開発キットをお使いになる際の注意事項については、次のところをご覧くださ い。https://www.ti.com/ja-jp/legal/notice-for-evaluation-kits-for-power-line-communication.html
- 3.4 European Union
 - 3.4.1 For EVMs subject to EU Directive 2014/30/EU (Electromagnetic Compatibility Directive):

This is a class A product intended for use in environments other than domestic environments that are connected to a low-voltage power-supply network that supplies buildings used for domestic purposes. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

4 EVM Use Restrictions and Warnings:

- 4.1 EVMS ARE NOT FOR USE IN FUNCTIONAL SAFETY AND/OR SAFETY CRITICAL EVALUATIONS, INCLUDING BUT NOT LIMITED TO EVALUATIONS OF LIFE SUPPORT APPLICATIONS.
- 4.2 User must read and apply the user guide and other available documentation provided by TI regarding the EVM prior to handling or using the EVM, including without limitation any warning or restriction notices. The notices contain important safety information related to, for example, temperatures and voltages.
- 4.3 Safety-Related Warnings and Restrictions:
 - 4.3.1 User shall operate the EVM within TI's recommended specifications and environmental considerations stated in the user guide, other available documentation provided by TI, and any other applicable requirements and employ reasonable and customary safeguards. Exceeding the specified performance ratings and specifications (including but not limited to input and output voltage, current, power, and environmental ranges) for the EVM may cause personal injury or death, or property damage. If there are questions concerning performance ratings and specifications, User should contact a TI field representative prior to connecting interface electronics including input power and intended loads. Any loads applied outside of the specified output range may also result in unintended and/or inaccurate operation and/or possible permanent damage to the EVM and/or interface electronics. Please consult the EVM user guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative. During normal operation, even with the inputs and outputs kept within the specified allowable ranges, some circuit components may have elevated case temperatures. These components include but are not limited to linear regulators, switching transistors, pass transistors, current sense resistors, and heat sinks, which can be identified using the information in the associated documentation. When working with the EVM, please be aware that the EVM may become very warm.
 - 4.3.2 EVMs are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems. User assumes all responsibility and liability for proper and safe handling and use of the EVM by User or its employees, affiliates, contractors or designees. User assumes all responsibility and inability to ensure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard. User assumes all responsibility and liability for any improper or unsafe handling or use of the EVM by User or its employees, affiliates, contractors or designees.
- 4.4 User assumes all responsibility and liability to determine whether the EVM is subject to any applicable international, federal, state, or local laws and regulations related to User's handling and use of the EVM and, if applicable, User assumes all responsibility and liability for compliance in all respects with such laws and regulations. User assumes all responsibility and liability for proper disposal and recycling of the EVM consistent with all applicable international, federal, state, and local requirements.
- 5. Accuracy of Information: To the extent TI provides information on the availability and function of EVMs, TI attempts to be as accurate as possible. However, TI does not warrant the accuracy of EVM descriptions, EVM availability or other information on its websites as accurate, complete, reliable, current, or error-free.
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