

ABSTRACT

The LAUNCHXL-F2800157 is a low-cost development board for the Texas Instruments C2000™ Real-Time Microcontroller series of F280015x devices. The LAUNCHXL-F2800157 is designed around the TMS320F2800157 real-time MCU and highlights the control, analog, and communications peripherals, as well as the integrated nonvolatile memory. The LaunchPad™ development kit also features two independent BoosterPack XL expansion connectors (80-pins), on-board Controller Area Network (CAN) transceiver supporting both standard CAN (DCAN) and CAN-FD (MCAN), two 5 V encoder interface (eQEP) connectors, power-domain isolation, and an on-board XDS110 debug probe.

Figure 1-1 highlights the key features of the F280015x LaunchPad.

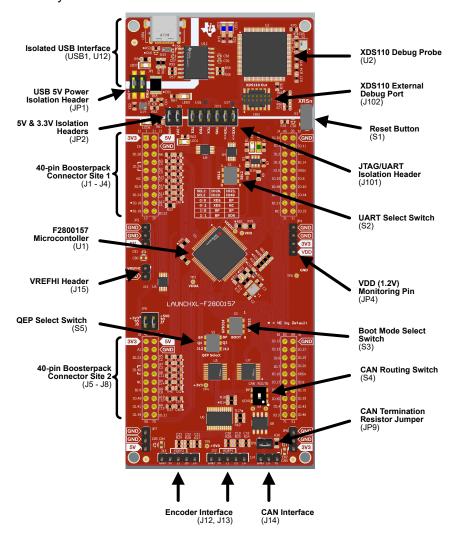


Figure 1-1. LAUNCHXL-F2800157 LaunchPad™ Board Overview

Table of Contents

1 Board Overview	3
1.1 Kit Contents	
1.2 Features	3
1.3 Specifications	3
1.4 Using the F280015x LaunchPad	4
1.5 BoosterPacks	5
1.6 Hardware Revisions	5
2 Software Development	6
2.1 Software Tools and Packages	6
2.2 F280015x LaunchPad Demo Program	6
2.3 Programming and Running Other Software on the F280015x LaunchPad	
3 Hardware Description	g
3.1 Functional Description and Connections	10
3.2 Debug Interface	14
3.3 Alternate Routing	
4 Board Design	
4.1 Schematic	
4.2 PCB Layout	
4.3 BOM	
4.4 LAUNCHXL-F2800157 Board Dimensions	
5 Frequently Asked Questions	
6 References	
6.1 Reference Documents.	
6.2 Other TI Components Used in This Design	
7 Revision History	24
Line of Pinana	
List of Figures	_
Figure 1-1. LAUNCHXL-F2800157 LaunchPad™ Board Overview	
Figure 2-1. LaunchPad XDS110 COM Port	
Figure 2-2. LaunchPad Demo Serial Terminal - TI Logo	
Figure 2-3. LaunchPad Demo Serial Terminal - ADC Sampling	
Figure 3-1. F280015x LaunchPad™ Development Kit Block Diagram	
Figure 3-2. LaunchPad Power Distribution Diagram	
Figure 3-3. LaunchPad Power Plane DiagramFigure 4-1. Top Signal - Layer 1	
Figure 4-1. 10p Signal - Layer 1	
Figure 4-3. PWR - Layer 3	
Figure 4-4. Bottom Signal - Layer 4	
Figure 4-5. F280015x LaunchPad Dimensions and Component Locations	
Figure 5-1. Target Configuration Advanced Options	
Figure 5-2 Target Configuration Included in the Demo Project	
Figure 5-2. Target Configuration Included in the Demo Project	
List of Tables	23
List of Tables Table 1-1. LAUNCHXL-F2800157 Specifications	23
List of Tables Table 1-1. LAUNCHXL-F2800157 Specifications	3
List of Tables Table 1-1. LAUNCHXL-F2800157 Specifications	3 5
List of Tables Table 1-1. LAUNCHXL-F2800157 Specifications	
List of Tables Table 1-1. LAUNCHXL-F2800157 Specifications. Table 1-2. Featured BoosterPacks for the F280015x LaunchPad. Table 3-1. Power Domain Shunts. Table 3-2. Power LED Indication Descriptions. Table 3-3. Boot Select Switch Table - S3.	
List of Tables Table 1-1. LAUNCHXL-F2800157 Specifications	

Trademarks

C2000[™], LaunchPad[™], BoosterPack [™], NexFET[™], and Code Composer Studio[™] are trademarks of Texas Instruments.

All trademarks are the property of their respective owners.

www.ti.com Board Overview

1 Board Overview

1.1 Kit Contents

The F280015x Series LaunchPad[™] Development Kit contains these items:

- C2000 F280015x Series LaunchPad development board (LAUNCHXL-F2800157)
- USB Type-A male to USB Type-C[™] male cable
- Pinout Map

1.2 Features

The F280015x LaunchPad has these features:

- C2000 Series F2800157SPN (80-pin) microcontroller:
- On-board XDS110 debug probe
- Two user-controlled LEDs
- · One microcontroller reset switch
- Selectable power domains:
 - USB (isolated)
 - BoosterPack [™] plug-in module
 - External power supply
- · CAN connector with on-board CAN transceiver
 - Supports both standard CAN (DCAN) and CAN-FD (MCAN)
 - Jumper to easily connect and disconnect CAN termination resistor
- · Two independent Enhanced Quadrature Encoder Pulse (QEP)-based encoder connectors
- Two independent BoosterPack XL standard connectors (80-pins) featuring stackable headers to maximize expansion through the BoosterPack ecosystem

1.3 Specifications

Table 1-1 summarizes the F280015x LaunchPad specifications.

Table 1-1. LAUNCHXL-F2800157 Specifications

Parameter	Value
Board Supply Voltage	 5 V_{DC} from one of the following sources: USB Connector (USB101) - USB Type-C[™] cable connected to PC or other compatible power source. BoosterPack 1 BoosterPack 2 Auxiliary power connectors
Dimensions	5.5 in x 2.3 in x .425 in (13.97 cm x 5.84 cm x 10.8 mm) (L x W x H)
Break-out Power Output	3.3 V _{DC} to BoosterPacks, limited by output of TPS7A3701 LDO. This 3.3-V plane is shared with on-board components. Total output power limit of TPS7A3701 is 1 Amp.
Assumed Operating Conditions	This kit is assumed to run at standard room conditions. The EVM can run at approximately standard ambient temperature and pressure (SATP) with moderate-to-low humidity.



Board Overview Www.ti.com

1.3.1 External Power Supply or Accessory Requirements

Nominal Output Voltage: 5 VDC Maximum Output Current: 3 A

Efficiency Level V

Note

TI recommends using an external power supply or power accessory **that** complies with applicable regional safety standards such as (by example) UL, CSA, VDE, CCC, PSE, and so on.

1.4 Using the F280015x LaunchPad

The recommended steps for using the F280015x LaunchPad are:

- 1. Follow the instructions in Section 2.2 to begin running the LaunchPad demo program. Within just a few minutes, you can control and monitor the F280015x LaunchPad with the pre-programmed quick start application. Additionally, the FAQ section included in this document can be helpful if there are any issues that can quickly be addressed.
- 2. **Experiment with BoosterPacks.** This development kit conforms to the latest revision of the BoosterPack pinout standard. This development kit has two independent BoosterPack sites to enable a variety of expansion opportunities, such as two boosterpacks being used simultaneously. For more information about the TI LaunchPad and BoosterPack standard, see the TI LaunchPad web page at http://www.ti.com/launchpad.
- 3. Take the first step towards developing your own control applications. The F280015x LaunchPad is supported by the C2000Ware development package. After C2000Ware is installed, look for \f280015x\examples\launchxl_f2800157 in the installation directory to find the pre-configured example applications for this board. Any of the other examples found within the \f280015x\examples directory can be used with minor modifications to run on the LaunchPad as well. For more details about software development, see Section 2.
 - For applications, features and benefits information, see the C2000 F280015x Real-Time Microcontrollers.
 - b. Check out this technical article featuring C2000 Real-Time Microcontrollers about how developers can take advantage of the scalability and sustainability benefits these devices bring.
- 4. Customize and integrate the hardware to align to your end application. This development kit can be used as a reference for building your own custom boards and circuits based on C2000 F280015x series microcontrollers. The LaunchPad also functions as a foundation for expansion with custom BoosterPacks and other circuits. This document can serve as a starting point for such projects.
- 5. **Get Trained.** Review and download hours of written and video training materials on C2000 Real-time Microcontrollers and related LaunchPads.
 - a. See Getting Started With C2000™ Real-Time Control Microcontrollers (MCUs)
 - b. See the TI Training and Videos page
 - c. See the C2000 Academy page

www.ti.com Board Overview

1.5 BoosterPacks

The LAUNCHXL-F2800157 provides a simple and inexpensive way to develop applications with the F280015x series microcontroller. BoosterPacks are pluggable add-on boards for the LaunchPad ecosystem that follow a pin-out standard created by Texas Instruments. The TI and third-party ecosystem of BoosterPacks greatly expands the peripherals and potential applications that you can explore with the F280015x LaunchPad.

Some examples of BoosterPacks that are compatible with the F280015x LaunchPad are listed in Table 1-2. Note that this is not an exhaustive list of hardware supported BoosterPacks.

Table 1-2. Featured BoosterPacks for the F280015x LaunchPad

BoosterPack/Board	Application and Usage
BOOSTXL-3PHGANINV	Features a 48-V/10-A three-phase GaN inverter with precision in-line shunt-based phase current sensing for accurate control of precision drives such as servo drives.
BOOSTXL-DRV8323RS BOOSTXL-DRV8323RH	DRV8323RS/H Three-Phase, 15A smart gate driver with buck, shunt amps (SPI or Hardware Interface) Evaluation Module.
DRV8353RS-EVM	15A, 3-phase brushless DC drive stage based on the DRV8353RS gate driver and CSD19532Q5B NexFET™ power MOSFETs.
DRV8316REVM	DRV8316REVM provides three half-H-bridge integrated MOSFET drivers for driving a three-phase brushless DC (BLDC) motor with 8-A Peak current drive, for 12-V/24-V DC rails or battery powered applications.
BOOSTXL-BUCKCONV	Digital Power Buck Converter BoosterPack for learning the basics of digital power control with C2000 microcontrollers. The buck converter power stage supports dynamic loads and converts an external 9-VDC power supply to a configurable DC output voltage.
BOOSTXL-POSMGR	PositionManager BoosterPack is a flexible low voltage platform intended for evaluating interfaces to absolute encoders and analog sensors like resolvers and SinCos transducers.
BOOSTXL-SHARP128	Sharp® 128x128 Memory LCD and microSD Card BoosterPack, controlled using SPI. Display sensor readings, time, graphics, or other information using the LCD screen.

Note

Software support for the BoosterPacks and boards listed varies.

Users can also design their own BoosterPacks for the F280015x LaunchPad. Make sure that compatibility requirements are met by referencing the signal pin mapping in the *LAUNCHXL-F2800157 LaunchPad Kit Pinout Map* or LAUNCHXL-F2800157 Schematic.

1.6 Hardware Revisions

This section contains an abbreviated revision history of the LAUNCHXL-F2800157 as well as known issues with each revision.

1.6.1 Revision A

The first production revision of the LAUNCHXL-F2800157 was released in July 2023. This revision can be identified by the "MCU110A" silkscreen labeling on the back side of the EVM between the BoosterPack Connector site 1 towards the top of the board.

Issues and concerns that have been identified on the EVM are listed below:

Known issues:

No issues to report at this time of initial release.

Special notes and considerations to be aware of:

Nothing to report at this time of initial release.

Software Development www.ti.com

2 Software Development

This section provides general information about software development, as well as instructions for programming the LaunchPad. Software tools and packages for C2000 real-time controllers, like the F280015x, are listed in the C2000 Evaluation & Development page.

2.1 Software Tools and Packages

Code Composer Studio (CCS) is a free integrated development environment (IDE) that supports TI Microcontroller and Embedded Processors portfolio. Code Composer Studio™ (CCS) IDE provides a feature rich environment for developing, programming, and debugging code on the C2000 family of MCUs.

C2000WARE is a repository of device-specific drivers, bit-field support files, libraries, peripheral examples, utilities, hardware files, and documentation for C2000 MCUs. C2000WARE provides a solid foundation to begin development and evaluation of the F280015x device on the LAUNCHXL-F2800157 and minimize software development time.

Software Development Kits (SDKs) are provided to make it easy to evaluate C2000 MCUs within specific system use cases and reduce overall development time. The Motor Control SDK (C2000WARE-MOTORCONTROL-SDK) is targeted for various motor control applications, such as industrial drives. The Digital Power SDK (C2000WARE-DIGITALPOWER-SDK) is targeted for digital power system development for various AC-DC, DC-DC and DC-AC power supply applications.

SysConfig is a powerful graphical user interface tool which configures the C2000 Real-Time Control MCUs and auto-generates embedded software, visualization diagrams, and debug artifacts. C2000 real-time MCUs can be easily initialized through SysConfig, and device configuration errors are caught by the tool. The LAUNCHXL-F2800157 is directly supported in the SysConfig tool and the standardized BoosterPack peripherals can easily be configured with a few clicks. As the C2000 device's pinmux is configured, the corresponding LaunchPad header pins are visualized, allowing for streamlined prototyping and debugging.

2.2 F280015x LaunchPad Demo Program

The LAUNCHXL-F2800157 includes a TMSF2800157SPN device pre-programmed with a demo program. When the LaunchPad is powered on the demo program begins with an LED blink sequence on LED4 and LED5. After a few seconds the device switches into an ADC sampling mode.

Every 1 second, the ADC samples pin ADCINA6 and the sampled value is represented as follows: If the sample is above mid-scale (2048), the red LED4 illuminates. If the sample is below mid-scale, the green LED5 illuminates.

In addition to the LED indicators, ADC sample results are also displayed on your PC through the USB/UART connection. To view the UART information on your PC, first determine the COM port associated with the LaunchPad. To do this in Windows open the *Device Manager*. Look for an entry under Ports (COM and LPT) titled "XDS110 Class Application/User UART (COM**X**)", where **X** is a number. Remember this number for when you open a serial terminal.

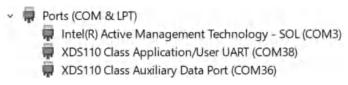


Figure 2-1. LaunchPad XDS110 COM Port

The demo application UART data was tested using PuTTY, which is a free and open-source terminal emulator. To view the UART data in a serial terminal program open the COM port found using the Windows *Device Manager* with the following settings.

115200 Baud, 8 data bits, no parity, 1 stop bit.

After properly opening the serial port in your serial terminal, reset the LaunchPad by pressing the S1 reset button and observe the serial terminal to see the TI logo in ASCII art.



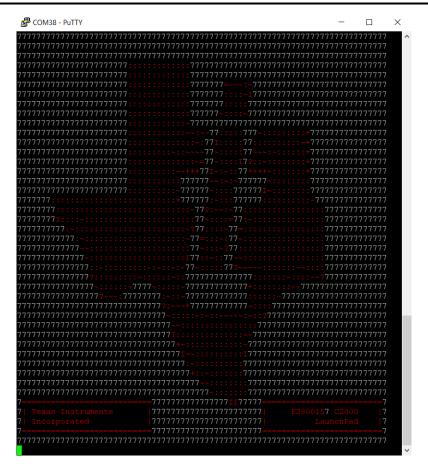


Figure 2-2. LaunchPad Demo Serial Terminal - TI Logo

After a few moments, the ADC value sampled on the ADCINA6 pin appears in the bottom right corner of the terminal and be updated each second. Using a jumper wire connect the ADCINA6 header to a 3.3V, GND, or other 0-3.3V signal to see the on-screen value change.



Figure 2-3. LaunchPad Demo Serial Terminal - ADC Sampling

Software Development www.ti.com

2.3 Programming and Running Other Software on the F280015x LaunchPad

The software packages described in Section 2.1 include example projects that can be loaded and run on the F280015x LaunchPad. If you installed the C2000WARE software to the default installation path of C:\ti\c2000\C2000Ware_<version>, you can find driverLib based example applications in C:\ti\c2000\C2000Ware_<version>\examples\F280015x. The on-board XDS110 is used with the On-Chip Flash Programmer tool to program applications to the F280015x LaunchPad.

Follow these steps to program example applications onto the F280015x LaunchPad development kit using the on-board XDS110 debug probe:

- 1. Install Code Composer Studio (CCS) on a PC running Microsoft Windows.
- 2. Connect the USB-A cable plug in to an available USB port on the PC and plug the USB Type-C™ plug to the port (USB101) on the F280015x LaunchPad.
- 3. Verify the following LEDs are illuminated:
 - a. LED7, at the top left of the board, indicating 5 V USB power.
 - b. LED0 indicating 3.3 V power to the XDS110 debug probe.
 - c. LED1 indicating 3.3 V power to the F2800157 MCU.
- 4. Install Windows XDS110 and Virtual COM Port drivers if prompted. Installation instructions can be found at XDS110 Product Page.
- 5. Run CCS on the PC.
- Import a F280015x project from C2000WARE, or another installed software package, into the CCS workspace.
- 7. Add the _LAUNCHXL_F2800157 predefined symbol to the imported DriverLib example project for the software to use relevant F280015x LaunchPad signals.
 - a. Open the projects Properties \rightarrow Expand the *Build* tab \rightarrow Expand the *C2000 Compiler* tab \rightarrow Select *Predefined Symbol* \rightarrow Add *LAUNCHXL F2800157* pre-define NAME.
- 8. Right click the project name and select Rebuild Project in CCS.
- Launch the LAUNCHXL-F2800157 Target Configuration file and connect to the F280015x device. Make sure
 that the Target Configuration file is configured to use the 2-pin cJTAG advanced configuration. For additional
 details, see Frequently Asked Questions.
- 10. Click 'Load Program' and select the program's binary to load. The binary is loaded onto the device and can now be run and debugged.

www.ti.com Hardware Description

3 Hardware Description

The F280015x LaunchPad includes a F2800157SPN MCU that is designed for advanced real-time control applications. A large number of these peripherals are made available to users using the on-board accessories and the BoosterPack connectors. This section explains how those peripherals operate and interface to the MCU.

Figure 3-1 shows a high-level block diagram of the F280015x LaunchPad.

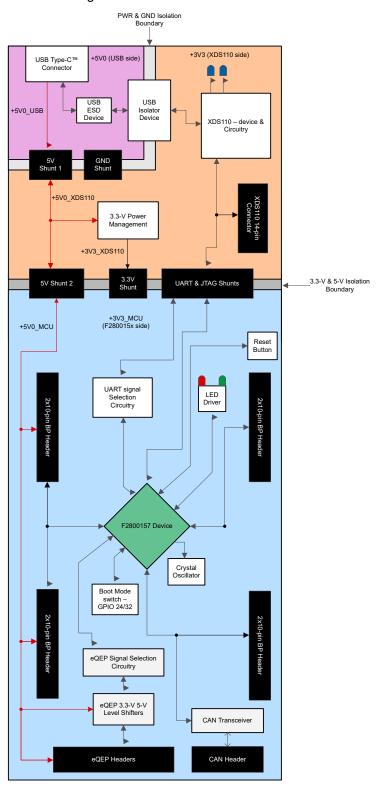


Figure 3-1. F280015x LaunchPad™ Development Kit Block Diagram

Hardware Description www.ti.com

3.1 Functional Description and Connections

3.1.1 Microcontroller

The TMS320F2800157SPN is a 32-bit floating-point microcontroller with 256-KB Flash memory, 36-KB RAM, and operates at 120 MHz. The TMS320F2800157SPN includes advanced control peripherals, differentiated analog, and various communications peripherals. The device has been optimized for high-performance real-time control applications. For more details, see *TMS320F280015x Real-Time Microcontrollers*.

Most of the microcontroller signals are routed to 0.1 inch (2.54 mm) pitch headers laid out to comply with the TI BoosterPack standards, with a few exceptions. The F280015x MCU internal multiplexer allows different peripheral functions to be assigned to each of the general-purpose input/output (GPIO) pins. The multiplexing options can be found in the device-specific data sheet. When adding external circuitry, consider the additional load on the development board's power rails.

The F280015x LaunchPad is factory-programmed with a quick start demo program. The quick start program resides in the on-chip Flash memory and executes each time power is applied, unless the application has been replaced with a user program. For details on the LaunchPad's demo program, see Section 2.2.

3.1.2 Power Domains

The F280015x LaunchPad has several power domains that can be connected or isolated from each other with removable shunts. The different 3.3-V and 5-V power domains are described in Figure 3-2 and Figure 3-3.

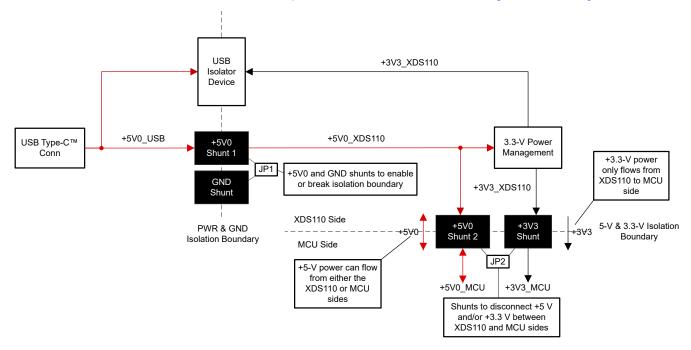


Figure 3-2. LaunchPad Power Distribution Diagram

ww.ti.com Hardware Description

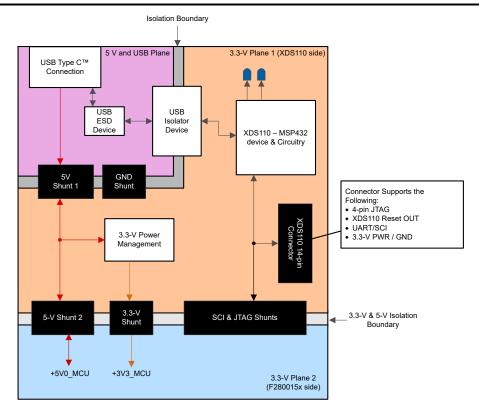


Figure 3-3. LaunchPad Power Plane Diagram

Table 3-1 describes the usage of the different removable shunts on the LaunchPad board.

Shunt Identifier

Usage Description

JP1, +5V0

Connects the +5-V power from the USB-C connector (+5V0_USB) to the +5-V power on the XDS110 side of the board (+5V0_XDS110). Bridges the power and ground isolations between the two board sides.

JP1, GND

Connects the board Ground on the isolated USB-C connector side of the board (USB_GND) to the rest of the board ground (GND). Bridges the power and ground isolations between the two board sides.

JP2, +5V0

Connects the +5-V power on the XDS110 side of the board (+5V0_XDS110) to the +5-V power on the F2800157 side of the board (+5V0_MCU).

JP2, +3V3

Connects the +3.3-V power on the XDS110 side of the board (+3V3_XDS110) to the +3.3-V power on the F2800157 side of the board (+3V3_MCU).

Table 3-1. Power Domain Shunts

3.1.3 LEDs

Power indicator LEDs (red) are included on the F280015x LaunchPad board. Table 3-2 shows descriptions of each LED.

Two user LEDs are provided on the board: LED4 (red) and LED5 (green). These user LEDs are connected to GPIO20 and GPIO22 of the F2800157, respectively. The signals are connected to the SN74LVC2G07DBVR LED driver IC and are connected in an active-low configuration; that is, drive the GPIO low to turn on the LED and high to turn the LED off. These LEDs are dedicated for use by the software application.

Two blue LEDs, LED2 and LED3, are connected to the XDS110 debug probe. These indicate debugger activity and are not controllable by any application software.

Hardware Description www.ti.com

Table 3-2. Power LED Indication Descriptions

LED Number	Indication Description
LED7	+5-V power from the USB Type-C™ connector
LED0	+3.3-V power on the XDS110 side of the PCB
LED1	+3.3-V power on the F280015x side of the PCB
LED6	+5 V-power on the F280015x side of the PCB

3.1.4 Encoder Connectors

The F280015x LaunchPad includes two headers, J12 and J13, which are used for connecting linear or rotary incremental encoders. These headers take the 5-V input signals that are stepped down to 3.3 V and wired to the F2800157 MCU. These signals are connected to the eQEP modules on the device when switch S5 is set appropriately, see Table 3-5. Each header has the EQEPA, EQEPB, and EQEPI signals available for each eQEP module (1 and 2) as well as pins for GND and 5 V.

3.1.5 Controller Area Network (CAN)

The F280015x LaunchPad includes a connector (J14) for a Controller Area Network (CAN). GPIO4 and GPIO5 are routed from the F2800157PN to J14 through the on-board CAN Transceiver. Both standard CAN and CAN-FD Mux options exist on these F280015x device pins. Switch S4 is used to route GPIO4 and GPIO5 to either the CAN transceiver and connector or the boosterpack headers. The F280015x LaunchPad also features a jumper (JP9) that can be used to easily connect and disconnect the CAN termination resistor. For more details, see Section 3.3.4.

3.1.6 Boot Modes

The F2800157 boot ROM contains bootloading software that executes every time the device is powered on or reset. Two pins, GPIO24 and GPIO32, are wired to the Boot Select switch (S3). By default, both pins are set HIGH (1) so the device boots from Flash, see Table 3-3. For more information on the F280015x boot modes, see *TMS320F280015x Real-Time Microcontrollers*.

Table 3-3. Boot Select Switch Table - S3

Mode GPIO24 (LEFT)

Boot Mode	GPIO24 (LEFT)	GPIO32 (RIGHT)
Boot from Parallel GPIO	0	0
Boot from SCI / Wait boot	0	1
Boot from CAN	1	0
Boot from Flash (default)	1	1

3.1.7 BoosterPack Sites

The F280015x LaunchPad features two fully independent BoosterPack XL connectors. Both BoosterPack sites 1 and 2 are compliant with the BoosterPack standard. To expand the functions available to the user on this LaunchPad, some signals are also routed to alternate locations on the board. These alternate routes can be selected by manipulating the on-board switches or by adding and removing 0-ohm resistors. This is described in Section 3.3.

The GPIO pin numbers as well as the BoosterPack compliant features can be viewed in the LAUNCHXL-F2800157 LaunchPad Kit Pinout Map. Each GPIO has multiple functions available through the F280015x device GPIO mux. Some specific functions have been listed in the Pinout Map; the full GPIO mux table can be found in TMS320F280015x Real-Time Microcontrollers.

All of the analog signals (denoted ADCIN) of the F280015x MCU are routed to the J1/J3 and J5/J7 BoosterPack headers on the left side of the board. Close to the respective BoosterPack header each ADC input signal has component pads for a series resistor and parallel capacitor to create an RC filter. By default, a 0-ohm resistor is populated and the capacitor is left unpopulated. Users can populate these components with specific values to filter out noise arriving at the device ADC input.

www.ti.com Hardware Description

3.1.8 Analog Voltage Reference Header

The analog subsystem of the F280015x allows for flexible voltage reference sources. The ADC modules are referenced to the VREFHIx and VREFLOx pin voltages. VREFHIx can either be driven externally or can be generated by an internal bandgap voltage reference. An external voltage can be supplied to header J15 as an external voltage source for VREFHIx. Note that there is no signal conditioning circuitry in place for the voltage reference. For best performance, some additional circuitry can be required.

3.1.9 Other Headers and Jumpers

The LaunchPad has multiple jumpers to select different power sources for the board. This LaunchPad also provides a way to isolate the connected USB from the device, allowing for safe operation and debugging in higher voltage applications.

3.1.9.1 USB Isolation Block

JP1 is provided to enable isolation between the device and the connected USB in higher-voltage applications. The area of isolation is defined by the white outline in the upper-left corner of the LaunchPad. JP1 has two removable shunts to separate the GND and 5 V power of the USB region and the XDS110 and F280015x MCU region of the LaunchPad. By default, both shunts are populated and the power is supplied by the connected USB, meaning that the USB is not isolated from the XDS110 and F280015x MCU regions. If power isolation is desired, remove the supplied shunts from JP1. In this configuration, one of the two external power options below are required:

- An external 5-V supply to power the 3.3 V LDO (TPS7A3701), which provides 3.3 V to the XDS110 and F280015x MCU regions of the board.
- An external 3.3-V supply to power the XDS110 and F280015x MCU regions of the board.

Some applications do not require 5 V to be supplied to the MCU region. In an isolated power application with JP1 shunts removed, supplying 5 V to the XDS110 and F280015x MCU regions is optional.

3.1.9.2 BoosterPack Site 2 Power Isolation

JP8 is included to isolate 3.3 V and 5 V from the BoosterPack site 2 headers. This can be required if two BoosterPacks are simultaneously connected to the LaunchPad and both provide power to the LaunchPad. If this is the case, power can be isolated by removing the shunts on JP8 and there is no contention between the two BoosterPacks.

3.1.9.3 Alternate Power

Additional jumpers are provided outside of the BoosterPack connector for additional external power connections for 3.3 V or 5 V. These can be used to supply an external board or for powering the LaunchPad with an external supply. When using these connection points, make sure that no other power supplies are connected.

- **JP4 and JP6** are provided as extra connection points for a 3.3-V supply to be connected to the LaunchPad.
- JP5 and JP7 are provided as extra connection points for a 5-V supply to be connected to the LaunchPad.

CAUTION

The F280015x LaunchPad features a VDD pin located on header JP4 that can only be used to monitor the voltage of the 1.2-V VDD rail of the TMS320F2800157PN device. This pin can not be used to supply power to an external device nor connected to an external supply.

Hardware Description www.ti.com

3.2 Debug Interface

3.2.1 XDS110 Debug Probe

The F280015x LaunchPad includes an on-board XDS110 Debug Probe. The XDS110 allows for the programming and debugging of the F2800157 using Code Composer Studio (CCS) IDE, or any other supported tool chains. In the default configuration, the XDS110 is only wired to support 2-pin cJTAG mode. This uses only the TMS and TCK JTAG pins and allows the TDI and TDO pins of the F280015x device to be reallocated for other application needs. TDI and TDO are available on GPIO35 and GPIO37. These pins are not routed to the debug probe by default, but can be connected by populating resistors R34 and R36.

3.2.2 XDS110 Output

The connector J102 is provided to debug an external target with the on-board XDS110 debug probe. This connector allows the LaunchPad to be used as a stand-alone XDS110 debug probe. For mating connector and cable, see Samtec FFSD or equivalent.

If the LaunchPad is being used in this manner, make sure that all of the jumpers are removed from J101. This isolates the JTAG signals from going to the F2800157 MCU. The UART TX and RX signals from the XDS110 device are also included on this connector.

3.2.3 Virtual COM Port

When plugged into a USB host, the XDS110 enumerates as both a debugger and a virtual COM port. J101 allows the user to connect the SCI UART from the F2800157 to the debug probe to be passed on to the USB host. By default, the F280015x SCIA maps to the virtual COM port of the XDS110 using GPIO28 and GPIO29. Alternately, GPIO23 and GPIO40 can be used for SCIB. This is accomplished by manipulating the on-board switch S2. For the appropriate switch settings, see Section 3.3.2.

3.3 Alternate Routing

3.3.1 Overview

The F2800157 MCU is a very versatile device in a mid-size package. To balance compatibility with BoosterPack standards, as well as showcasing the versatility of the F2800157, some complexity was added to the design. Most features aligning with the BoosterPack standard are available by default. The additional functions are configured using switches or static resistors that can be added or removed. This section covers the alternate functions and how to enable them. Note that by enabling certain alternate features, standard BoosterPack functionality can be lost. The switches and resistors are configured such that it is not possible to connect multiple functions to the same header.

3.3.2 UART Routing

This LaunchPad allows for one of two sets of pins to be used for the SCIA UART routed to the virtual COM port of the XDS110. By default, GPIO28 (SCIA_RX) and GPIO29 (SCIA_TX) are routed to the virtual COM port and not available on the BoosterPack connector. Alternately, GPIO23 (SCIB_RX) and GPIO40 (SCIB_TX) can be routed to the virtual COM port. When UART functionality is not needed at the virtual COM port, the GPIOs can be routed to the BoosterPack connectors for BoosterPack standard functions.

The routing destination of these signal pairs are selected using the on-board switch S2, as described in Table 3-4.

SEL1 (Left)	SEL2 (Right)	GPIO28/29	GPIO23/40
0	0	XDS110 COM Port	BP Headers
0	1	XDS110 COM Port	No Connect
1	0	BP Headers	BP Headers
1	1	BP Headers	XDS110 COM Port

Table 3-4. SCI UART Select Table - S2

www.ti.com Hardware Description

3.3.3 EQEP Routing

The LaunchPad has the ability to connect to two independent linear or rotary encoders through the F280015x on-chip eQEP interfaces: Header J12 is connected to eQEP1 and header J13 is connected to eQEP2. By default, this connection is not active and the GPIOs are routed to the BoosterPack connectors. The 5 V eQEP input signals from the J12 and J13 connectors are stepped down through a TI SN74LVC8T245 Level Translator (U13) to 3.3 V. The signals are then routed through TI SN74LV4053A Triple 2-Channel Analog Multiplexer/ Demultiplexer ICs (U11/U14). Switch S5 controls the select inputs of the ICs to configure the eQEP signal destinations to be either the J12/J13 connectors or BoosterPack headers, as described in Table 3-5.

Table 3-5. QEP Select Table - S5

QEP1 SEL (LEFT)	QEP2 SEL (RIGHT)	QEP1 Signals (GPIO20/21/43)	QEP2 Signals (GPIO14/33/26)
0 (down)	0 (down)	J12	J13
0 (down)	1 (up)	J12	BP Headers
1 (up)	0 (down)	BP Headers	J13
1 (up)	1 (up)	BP Headers	BP Headers

3.3.4 CAN Routing

The LaunchPad can be connected to a CAN bus through J14. GPIO4 and GPIO5 are routed to the on-board TI TCAN332DR 3.3V CAN Transceiver, U15. By setting S4 to DOWN (on), GPIO4 and GPIO5 are routed to the transceiver. If S4 is set to UP (off), the GPIOs are routed to the BoosterPack connectors (default case).

3.3.5 X1/X2 Routing

The F2800157 crystal oscillator output signal, X2, is multiplexed with GPIO18 and the crystal oscillator input, X1, is multiplexed with GPIO19. By default, the Launchpad uses an on-board crystal oscillator, Y2, as the clock source for the on-chip Phase-Locked Loop (PLL) that requires both X1 and X2 signals of the MCU. To balance the requirement of having cleanly routed oscillator signals and bringing all possible GPIOs to the BoosterPack connectors, both GPIO18/X2 and GPIO19/X1 can be routed to the BoosterPack connectors through 0 Ω resistors. If GPIO18 or GPIO19 are needed at the BoosterPack connectors, the on-chip zero-pin oscillators must be used as the clock source for the on-chip PLL. For more information on the X1/X2 configurations, see TMS320F280015x $Real-Time\ Microcontrollers$.

If GPIO18 functionality is needed at the BoosterPack Connector:

- 1. Remove R10 to separate GPIO18 from Y2.
- 2. Populate R12 to connect GPIO18 to the BoosterPack connector

If GPIO19 functionality is needed at the BoosterPack Connector:

- 1. Remove R11 to separate GPIO19 from Y2.
- 2. Populate R13 to connect GPIO19 to the BoosterPack connector.

3.3.6 PWM DAC

The LaunchPad provides two PWM DAC signals at the BoosterPack headers using GPIO22 (BP pin 30) and GPIO31 (BP pin 70) buffered outputs through U18. The intended purpose of the PWM DAC signals are to utilize PWMs of the F280015x device as digitial-to-analog converters (DAC). This method involves low-pass filtering the PWM signal to remove the high-frequency components and ideally leave only the DC component. For more information, see *Using PWM Output as a Digital-to-Analog Converter on a TMS320F280x Digital Signal Control*.

By default, GPIO22 and GPIO31 are connected to the U18 dual buffer through 0-ohm resistors R78 and R83 for the PWM DAC outputs. These resistors can be removed to disconnect the signals from U18 and PWM DAC pins as needed.

Board Design www.ti.com

4 Board Design

The entire LAUNCHXL-F2800157 design files are available for download at this link: LAUNCHXL-F2800157 design files.

4.1 Schematic

The LaunchPad's schematic can be found at this link: LAUNCHXL-F2800157 Schematic.

4.2 PCB Layout

The layout source files for the LAUNCHXL-F2800157 are included in the LAUNCHXL-F2800157 design files download.

www.ti.com Board Design

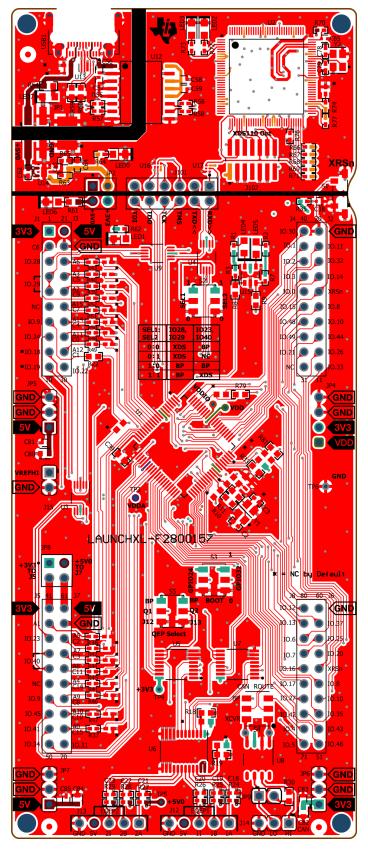


Figure 4-1. Top Signal - Layer 1

Board Design Www.ti.com

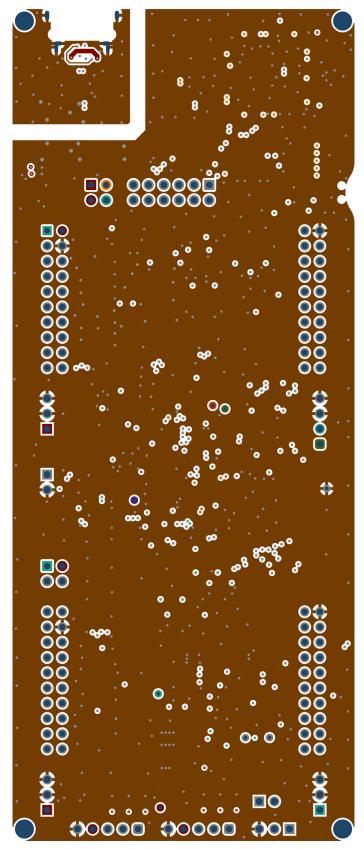


Figure 4-2. GND - Layer 2

www.ti.com Board Design

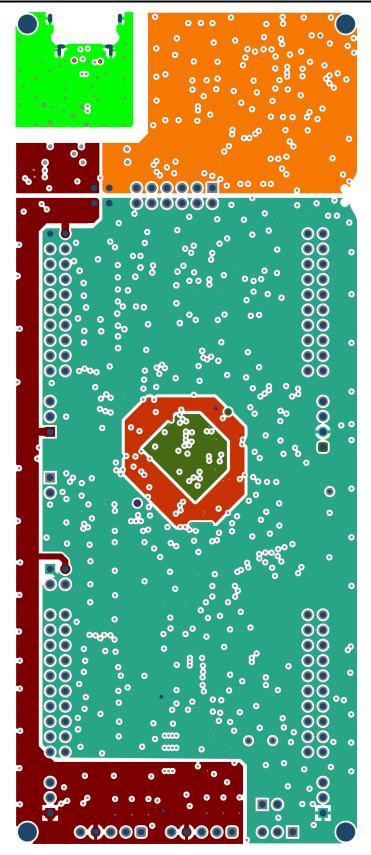


Figure 4-3. PWR - Layer 3

Board Design www.ti.com

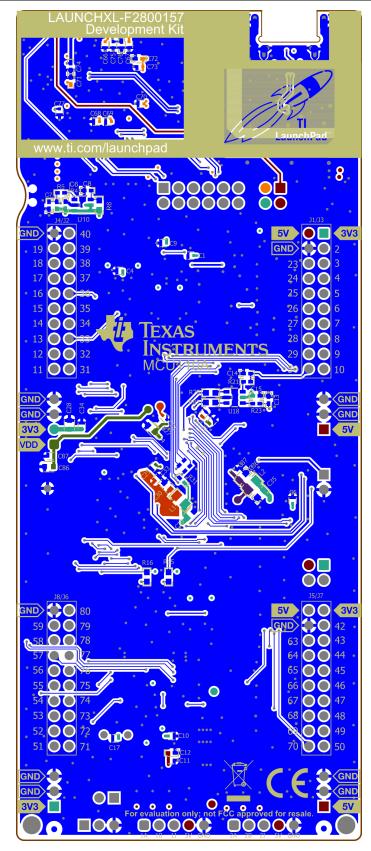


Figure 4-4. Bottom Signal - Layer 4

www.ti.com Board Design

4.3 BOM

The BOM for the LAUNCHXL-F2800157 is included in the LAUNCHXL-F2800157 design files download.

4.4 LAUNCHXL-F2800157 Board Dimensions

Figure 4-5 is a dimensional drawing of the F280015x LaunchPad that shows the location of selected features of the board as well as the component locations.

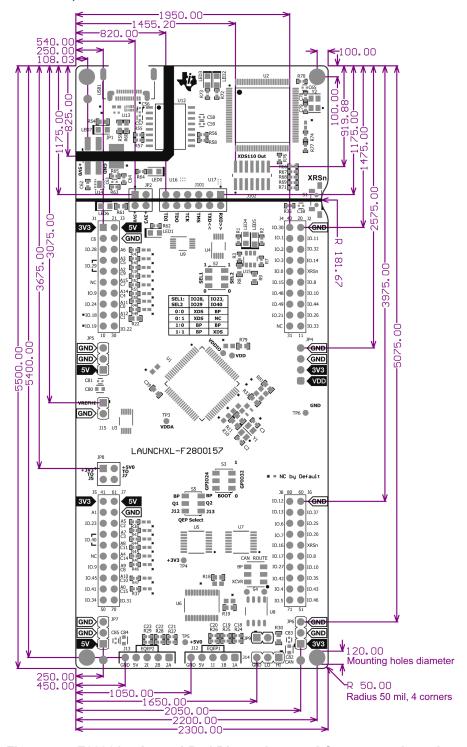


Figure 4-5. F280015x LaunchPad Dimensions and Component Locations



5 Frequently Asked Questions

- 1. Can other programming and debug tools (such as an XDS200 debug probe) be used with the F280015x LaunchPad?
 - a. The F280015x LaunchPad utilizes an on-board XDS110 debug probe in a 2-pin cJTAG configuration. cJTAG only uses the TMS and TCK pins of the debug probe. TDI and TDO are present on J101 and can be connected to a debug probe through jumper wires, if necessary.
- 2. What versions of Code Composer Studio™ IDE can be used to develop software for the F280015x LaunchPad?
 - a. The on-board XDS110 debug probe is compatible with Code Composer Studio development environment version 6.1.0 and later.
- 3. Why can't I connect to the LaunchPad in Code Composer Studio™ IDE?
 - a. Are shunts present on J101 for TCK and TMS?
 - b. Is the XDS110 and the F2800157 MCU powered? Are LED0 and LED1 illuminated? For further details on powering the LaunchPad, see Section 3.1.2.
 - i. If JP1 shunts are disconnected, the power provided through the USB is isolated from the rest of the board. Make sure that 3.3 V is supplied to any of the available connectors on the target side of the isolation.
 - c. Is the USB-C cable connected to the PCB and is the USB region receiving power? Is LED7 illuminated?
 - i. The USB region must be powered with the 5 V from the USB cable. LED7 illuminates when 5-V USB power is connected. The USB isolation chip requires 5 V on the USB side to operate and pass the signals across the isolation barrier.
 - d. Make sure that the target configuration is set up to use cJTAG in 2-pin advanced mode. Open the Target Configuration file (.ccxml) in Code Composer Studio IDE. Click on the Advanced tab and select cJTAG (1149.7) 2-pin advanced modes from the drop-down labeled JTAG/SWD/cJTAG Mode. Leave the Target Scan Format as OSCAN2 format. Alternately, a working Target configuration file is included in the launchxl_ex1_f2800157_demo project "TMS320F2800157_LaunchPad.ccxml". You can use this without modifications.

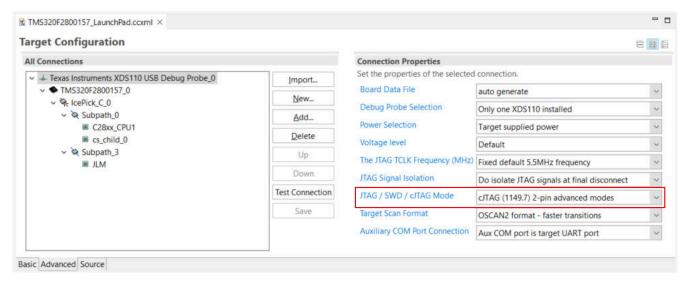


Figure 5-1. Target Configuration Advanced Options

www.ti.com References

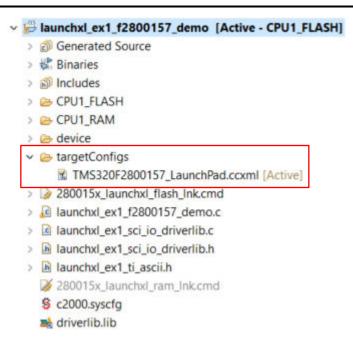


Figure 5-2. Target Configuration Included in the Demo Project

- 4. Why is the serial connection not working?
 - a. Are shunts present on J101 for TXD and RXD?
 - b. Are you using the correct COM port?
 - i. Right click on My Computer and select Properties. Navigate to the Hardware tab in the dialog box and open the device manager. Scroll to Ports (COM and LPT) and expand this entry. Is XDS110 Class Application/User UART listed? If so, read the COM number to the right of the entry; this is the COM number you should be using.
 - c. Are you using the correct baud rate? Most, if not all, of the examples are configured for a baud rate of 115200 when the CPU is running at 120 MHz. If you have changed the PLL settings or developed your own code, you can recalculate the baud rate for your specific application. For information on how to do this, see the TMS320F280015x Real-Time Microcontrollers Technical Reference Manual.
 - d. Does the UART channel wired to the debug probe match the UART channel configured in software?
 - i. The F280015x LaunchPad provides an option for one of two possible UART channels to be routed to the debug probe through J101. Make sure that S2 is configured to the appropriate UART channel for the application software. For details, see Section 3.3.2.

6 References

6.1 Reference Documents

In addition to this document, the following references are available for download at www.ti.com.

- TMS320F280015 Real-Time Microcontrollers
- TMS320F280015x Real-Time Microcontrollers Data Sheet
- TMS320F280015x Real-Time Microcontrollers Technical Reference Manual
- Getting Started With C2000™ Real-Time Control Microcontrollers (MCUs)
- The Essential Guide for Developing with C2000™ Real-Time Microcontrollers
- TMS320F280015x Real-Time Microcontrollers Silicon Errata
- LAUNCHXL-F2800157 LaunchPad Kit Pinout Map
- C2000Ware for C2000 MCUs
- C2000WARE Quick Start Guide
- C2000 SysConfig
- Texas Instruments Code Composer Studio™ integrated development environment (IDE)
- Texas Instruments LaunchPad Development Environment

References Www.ti.com

6.2 Other TI Components Used in This Design

This LaunchPad uses various other TI components for the functions. A consolidated list of these components with links to their TI product pages is shown below.

- MSP432E401Y SimpleLink™ 32-bit Arm Cortex-M4F MCU
- TCAN332 3.3 V CAN Transceiver
- SN74LV4053A Triple 2-Channel Analog Multiplexer/Demultiplexer IC
- SN74LVC2G07 Dual Buffer/Driver With Open-Drain Output
- TPD4E004 4-Channel ESD Protection Array for High-Speed Data Interfaces
- TPD4E05U06 4-Channel ESD Protection Array for USB, HDMI & High Speed Interfaces
- TPS3702 High-Accuracy, Fixed-Threshold OV/UV Monitor
- TPS7A37 1-A, high-accuracy, ultra-low-dropout voltage regulator with reverse current protection & enable
- SN74LVC8T245 8-Bit Dual-Supply Bus Transceiver with Configurable Voltage-Level Shifting and Three-State
 Outputs
- TS5A23157 5-V, 2:1 (SPDT), 2-channel analog switch
- SN74LVC2G34 2-ch, 1.65-V to 5.5-V buffers
- ISOUSB111 Low emissions, full and low speed isolated USB repeater

7 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision * (June 2023) to Revision A (July 2023)			
•	Added Section 1.3.1		

STANDARD TERMS FOR EVALUATION MODULES

- Delivery: TI delivers TI evaluation boards, kits, or modules, including any accompanying demonstration software, components, and/or
 documentation which may be provided together or separately (collectively, an "EVM" or "EVMs") to the User ("User") in accordance
 with the terms set forth herein. User's acceptance of the EVM is expressly subject to the following terms.
 - 1.1 EVMs are intended solely for product or software developers for use in a research and development setting to facilitate feasibility evaluation, experimentation, or scientific analysis of TI semiconductors products. EVMs have no direct function and are not finished products. EVMs shall not be directly or indirectly assembled as a part or subassembly in any finished product. For clarification, any software or software tools provided with the EVM ("Software") shall not be subject to the terms and conditions set forth herein but rather shall be subject to the applicable terms that accompany such Software
 - 1.2 EVMs are not intended for consumer or household use. EVMs may not be sold, sublicensed, leased, rented, loaned, assigned, or otherwise distributed for commercial purposes by Users, in whole or in part, or used in any finished product or production system.
- 2 Limited Warranty and Related Remedies/Disclaimers:
 - 2.1 These terms do not apply to Software. The warranty, if any, for Software is covered in the applicable Software License Agreement.
 - 2.2 TI warrants that the TI EVM will conform to TI's published specifications for ninety (90) days after the date TI delivers such EVM to User. Notwithstanding the foregoing, TI shall not be liable for a nonconforming EVM if (a) the nonconformity was caused by neglect, misuse or mistreatment by an entity other than TI, including improper installation or testing, or for any EVMs that have been altered or modified in any way by an entity other than TI, (b) the nonconformity resulted from User's design, specifications or instructions for such EVMs or improper system design, or (c) User has not paid on time. Testing and other quality control techniques are used to the extent TI deems necessary. TI does not test all parameters of each EVM. User's claims against TI under this Section 2 are void if User fails to notify TI of any apparent defects in the EVMs within ten (10) business days after the defect has been detected.
 - 2.3 Tl's sole liability shall be at its option to repair or replace EVMs that fail to conform to the warranty set forth above, or credit User's account for such EVM. Tl's liability under this warranty shall be limited to EVMs that are returned during the warranty period to the address designated by Tl and that are determined by Tl not to conform to such warranty. If Tl elects to repair or replace such EVM, Tl shall have a reasonable time to repair such EVM or provide replacements. Repaired EVMs shall be warranted for the remainder of the original warranty period. Replaced EVMs shall be warranted for a new full ninety (90) day warranty period.

WARNING

Evaluation Kits are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems.

User shall operate the Evaluation Kit within TI's recommended guidelines and any applicable legal or environmental requirements as well as reasonable and customary safeguards. Failure to set up and/or operate the Evaluation Kit within TI's recommended guidelines may result in personal injury or death or property damage. Proper set up entails following TI's instructions for electrical ratings of interface circuits such as input, output and electrical loads.

NOTE:

EXPOSURE TO ELECTROSTATIC DISCHARGE (ESD) MAY CAUSE DEGREDATION OR FAILURE OF THE EVALUATION KIT; TI RECOMMENDS STORAGE OF THE EVALUATION KIT IN A PROTECTIVE ESD BAG.

3 Regulatory Notices:

3.1 United States

3.1.1 Notice applicable to EVMs not FCC-Approved:

FCC NOTICE: This kit is designed to allow product developers to evaluate electronic components, circuitry, or software associated with the kit to determine whether to incorporate such items in a finished product and software developers to write software applications for use with the end product. This kit is not a finished product and when assembled may not be resold or otherwise marketed unless all required FCC equipment authorizations are first obtained. Operation is subject to the condition that this product not cause harmful interference to licensed radio stations and that this product accept harmful interference. Unless the assembled kit is designed to operate under part 15, part 18 or part 95 of this chapter, the operator of the kit must operate under the authority of an FCC license holder or must secure an experimental authorization under part 5 of this chapter.

3.1.2 For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant:

CAUTION

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

FCC Interference Statement for Class A EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- · Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210 or RSS-247

Concerning EVMs Including Radio Transmitters:

This device complies with Industry Canada license-exempt RSSs. Operation is subject to the following two conditions:

(1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Concerning EVMs Including Detachable Antennas:

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types lated in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur

3.3 Japan

- 3.3.1 Notice for EVMs delivered in Japan: Please see http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_01.page 日本国内に輸入される評価用キット、ボードについては、次のところをご覧ください。
 - https://www.ti.com/ja-jp/legal/notice-for-evaluation-kits-delivered-in-japan.html
- 3.3.2 Notice for Users of EVMs Considered "Radio Frequency Products" in Japan: EVMs entering Japan may not be certified by TI as conforming to Technical Regulations of Radio Law of Japan.

If User uses EVMs in Japan, not certified to Technical Regulations of Radio Law of Japan, User is required to follow the instructions set forth by Radio Law of Japan, which includes, but is not limited to, the instructions below with respect to EVMs (which for the avoidance of doubt are stated strictly for convenience and should be verified by User):

- 1. Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
- 2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
- 3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above. User will be subject to penalties of Radio Law of Japan.

【無線電波を送信する製品の開発キットをお使いになる際の注意事項】 開発キットの中には技術基準適合証明を受けていないものがあります。 技術適合証明を受けていないもののご使用に際しては、電波法遵守のため、以下のいずれかの 措置を取っていただく必要がありますのでご注意ください。

- 1. 電波法施行規則第6条第1項第1号に基づく平成18年3月28日総務省告示第173号で定められた電波暗室等の試験設備でご使用 いただく。
- 2. 実験局の免許を取得後ご使用いただく。
- 3. 技術基準適合証明を取得後ご使用いただく。
- なお、本製品は、上記の「ご使用にあたっての注意」を譲渡先、移転先に通知しない限り、譲渡、移転できないものとします。 上記を遵守頂けない場合は、電波法の罰則が適用される可能性があることをご留意ください。 日本テキサス・イ

ンスツルメンツ株式会社

東京都新宿区西新宿6丁目24番1号

西新宿三井ビル

- 3.3.3 Notice for EVMs for Power Line Communication: Please see http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_02.page 電力線搬送波通信についての開発キットをお使いになる際の注意事項については、次のところをご覧ください。https://www.ti.com/ja-jp/legal/notice-for-evaluation-kits-for-power-line-communication.html
- 3.4 European Union
 - 3.4.1 For EVMs subject to EU Directive 2014/30/EU (Electromagnetic Compatibility Directive):

This is a class A product intended for use in environments other than domestic environments that are connected to a low-voltage power-supply network that supplies buildings used for domestic purposes. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

- 4 EVM Use Restrictions and Warnings:
 - 4.1 EVMS ARE NOT FOR USE IN FUNCTIONAL SAFETY AND/OR SAFETY CRITICAL EVALUATIONS, INCLUDING BUT NOT LIMITED TO EVALUATIONS OF LIFE SUPPORT APPLICATIONS.
 - 4.2 User must read and apply the user guide and other available documentation provided by TI regarding the EVM prior to handling or using the EVM, including without limitation any warning or restriction notices. The notices contain important safety information related to, for example, temperatures and voltages.
 - 4.3 Safety-Related Warnings and Restrictions:
 - 4.3.1 User shall operate the EVM within TI's recommended specifications and environmental considerations stated in the user guide, other available documentation provided by TI, and any other applicable requirements and employ reasonable and customary safeguards. Exceeding the specified performance ratings and specifications (including but not limited to input and output voltage, current, power, and environmental ranges) for the EVM may cause personal injury or death, or property damage. If there are questions concerning performance ratings and specifications, User should contact a TI field representative prior to connecting interface electronics including input power and intended loads. Any loads applied outside of the specified output range may also result in unintended and/or inaccurate operation and/or possible permanent damage to the EVM and/or interface electronics. Please consult the EVM user guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative. During normal operation, even with the inputs and outputs kept within the specified allowable ranges, some circuit components may have elevated case temperatures. These components include but are not limited to linear regulators, switching transistors, pass transistors, current sense resistors, and heat sinks, which can be identified using the information in the associated documentation. When working with the EVM, please be aware that the EVM may become very warm.
 - 4.3.2 EVMs are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems. User assumes all responsibility and liability for proper and safe handling and use of the EVM by User or its employees, affiliates, contractors or designees. User assumes all responsibility and liability to ensure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard. User assumes all responsibility and liability for any improper or unsafe handling or use of the EVM by User or its employees, affiliates, contractors or designees.
 - 4.4 User assumes all responsibility and liability to determine whether the EVM is subject to any applicable international, federal, state, or local laws and regulations related to User's handling and use of the EVM and, if applicable, User assumes all responsibility and liability for compliance in all respects with such laws and regulations. User assumes all responsibility and liability for proper disposal and recycling of the EVM consistent with all applicable international, federal, state, and local requirements.
- 5. Accuracy of Information: To the extent TI provides information on the availability and function of EVMs, TI attempts to be as accurate as possible. However, TI does not warrant the accuracy of EVM descriptions, EVM availability or other information on its websites as accurate, complete, reliable, current, or error-free.

6. Disclaimers:

- 6.1 EXCEPT AS SET FORTH ABOVE, EVMS AND ANY MATERIALS PROVIDED WITH THE EVM (INCLUDING, BUT NOT LIMITED TO, REFERENCE DESIGNS AND THE DESIGN OF THE EVM ITSELF) ARE PROVIDED "AS IS" AND "WITH ALL FAULTS." TI DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED, REGARDING SUCH ITEMS, INCLUDING BUT NOT LIMITED TO ANY EPIDEMIC FAILURE WARRANTY OR IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF ANY THIRD PARTY PATENTS, COPYRIGHTS, TRADE SECRETS OR OTHER INTELLECTUAL PROPERTY RIGHTS.
- 6.2 EXCEPT FOR THE LIMITED RIGHT TO USE THE EVM SET FORTH HEREIN, NOTHING IN THESE TERMS SHALL BE CONSTRUED AS GRANTING OR CONFERRING ANY RIGHTS BY LICENSE, PATENT, OR ANY OTHER INDUSTRIAL OR INTELLECTUAL PROPERTY RIGHT OF TI, ITS SUPPLIERS/LICENSORS OR ANY OTHER THIRD PARTY, TO USE THE EVM IN ANY FINISHED END-USER OR READY-TO-USE FINAL PRODUCT, OR FOR ANY INVENTION, DISCOVERY OR IMPROVEMENT, REGARDLESS OF WHEN MADE, CONCEIVED OR ACQUIRED.
- 7. USER'S INDEMNITY OBLIGATIONS AND REPRESENTATIONS. USER WILL DEFEND, INDEMNIFY AND HOLD TI, ITS LICENSORS AND THEIR REPRESENTATIVES HARMLESS FROM AND AGAINST ANY AND ALL CLAIMS, DAMAGES, LOSSES, EXPENSES, COSTS AND LIABILITIES (COLLECTIVELY, "CLAIMS") ARISING OUT OF OR IN CONNECTION WITH ANY HANDLING OR USE OF THE EVM THAT IS NOT IN ACCORDANCE WITH THESE TERMS. THIS OBLIGATION SHALL APPLY WHETHER CLAIMS ARISE UNDER STATUTE, REGULATION, OR THE LAW OF TORT, CONTRACT OR ANY OTHER LEGAL THEORY, AND EVEN IF THE EVM FAILS TO PERFORM AS DESCRIBED OR EXPECTED.

- 8. Limitations on Damages and Liability:
 - 8.1 General Limitations. IN NO EVENT SHALL TI BE LIABLE FOR ANY SPECIAL, COLLATERAL, INDIRECT, PUNITIVE, INCIDENTAL, CONSEQUENTIAL, OR EXEMPLARY DAMAGES IN CONNECTION WITH OR ARISING OUT OF THESE TERMS OR THE USE OF THE EVMS, REGARDLESS OF WHETHER TI HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. EXCLUDED DAMAGES INCLUDE, BUT ARE NOT LIMITED TO, COST OF REMOVAL OR REINSTALLATION, ANCILLARY COSTS TO THE PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES, RETESTING, OUTSIDE COMPUTER TIME, LABOR COSTS, LOSS OF GOODWILL, LOSS OF PROFITS, LOSS OF SAVINGS, LOSS OF USE, LOSS OF DATA, OR BUSINESS INTERRUPTION. NO CLAIM, SUIT OR ACTION SHALL BE BROUGHT AGAINST TIMORE THAN TWELVE (12) MONTHS AFTER THE EVENT THAT GAVE RISE TO THE CAUSE OF ACTION HAS OCCURRED.
 - 8.2 Specific Limitations. IN NO EVENT SHALL TI'S AGGREGATE LIABILITY FROM ANY USE OF AN EVM PROVIDED HEREUNDER, INCLUDING FROM ANY WARRANTY, INDEMITY OR OTHER OBLIGATION ARISING OUT OF OR IN CONNECTION WITH THESE TERMS, , EXCEED THE TOTAL AMOUNT PAID TO TI BY USER FOR THE PARTICULAR EVM(S) AT ISSUE DURING THE PRIOR TWELVE (12) MONTHS WITH RESPECT TO WHICH LOSSES OR DAMAGES ARE CLAIMED. THE EXISTENCE OF MORE THAN ONE CLAIM SHALL NOT ENLARGE OR EXTEND THIS LIMIT.
- 9. Return Policy. Except as otherwise provided, TI does not offer any refunds, returns, or exchanges. Furthermore, no return of EVM(s) will be accepted if the package has been opened and no return of the EVM(s) will be accepted if they are damaged or otherwise not in a resalable condition. If User feels it has been incorrectly charged for the EVM(s) it ordered or that delivery violates the applicable order, User should contact TI. All refunds will be made in full within thirty (30) working days from the return of the components(s), excluding any postage or packaging costs.
- 10. Governing Law: These terms and conditions shall be governed by and interpreted in accordance with the laws of the State of Texas, without reference to conflict-of-laws principles. User agrees that non-exclusive jurisdiction for any dispute arising out of or relating to these terms and conditions lies within courts located in the State of Texas and consents to venue in Dallas County, Texas. Notwithstanding the foregoing, any judgment may be enforced in any United States or foreign court, and TI may seek injunctive relief in any United States or foreign court.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2023, Texas Instruments Incorporated

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2023, Texas Instruments Incorporated