Very large FFT for TMS320C6678 processors

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Introduction

This white paper discusses the very large FFT (VLFFT) demo, which implements one-dimensional complex single-precision floating-point FFTs of size 16K to 1024K samples on 1, 2, 4 and 8 DSP cores of TI’s TMS320C6678 8-core fixed- and floating-point DSP in order to demonstrate the capabilities of the C66x DSP core as well as the capability of the architecture to accommodate parallelization across multiple cores with performance boosts proportional to the number of cores added. The FFT was chosen as the algorithm for this demo as FFTs are common signal processing building blocks used in applications such as medical imaging, communications, and military and commercial radars, and electronic warfare (jammers, anti-jammers). The 1024K sample FFT is shown to take only 6.4 ms when the algorithm is run on all eight DSP cores of the TMS320C6678 device at 1 GHz.

TMS320C6678 SoC

The TMS320C6678 device is an eight-core DSP based on TI’s C66x fixed- and floating-point DSP core and built on TI’s innovative KeyStone™ architecture which enables full multicore entitlement. It is capable of operating at up to 1.25 GHz, at which speed it can produce 160 GFLOPS and consumes less than 10 W in typical use cases. It also features 512 KB of L2 memory per DSP core and 4 MB of shared memory for a total of 8 MB of on-chip memory, all with ECC. The DDR3 interface is capable of running up to 1600 MTPS, can access up to 8 GB of external memory and is a 64-bit + 8-bit ECC interface. Peripherals include PCIe, Serial RapidIO® and Gigabit Ethernet, as well as TI’s HyperLink interface which provides up to 50-Gbps connection to other TI DSP, ARM®, and ARM+DSP processors, as well as to FPGAs though third-party IP blocks.

In the VLFFT demo, the TMS320C6678 device operates at 1 GHz, using DDR3 transfers at 1333 MHz.

VLFFT demo

The VLFFT algorithm requires input data to be placed in the device’s external memory. During the demo, data is accessed, distributed to and processed by the DSP cores, and then the output is placed into external memory. The cycle counts and times measured incorporate this entire process. The software can be configured to use different numbers
of cores (1, 2, 4, or 8) to do the computation on FFTs of the following sizes:

- 16K
- 32K
- 64K
- 128K
- 256K
- 512K
- 1024K

The FFT implementation is designed to achieve maximum performance by distributing the computational load across multiple cores, and by fully utilizing the high-performance computational power of the C66x DSP cores. The basic decimation-in-time approach is used to formulate a one-dimensional very large FFT computation into a form similar to a two-dimensional FFT computation. For very large \( N \), it can be factored into \( N = N_1 \times N_2 \). If it is very large, a one-dimensional input array can be represented as a two-dimensional array of \( N_1 \) rows and \( N_2 \) columns and then the following steps can be taken to compute a one-dimensional very large FFT from this representation:

1. Compute \( N_2 \) FFTs of \( N_1 \) size in the column directions
2. Multiply by twiddle factor
3. Store \( N_2 \) FFTs of \( N_1 \) size in row directions to form a \( N_2 \) by \( N_1 \) two-dimensional array
4. Compute \( N_1 \) FFTs of \( N_2 \) size in the column direction
5. Store data in column direction to form a \( N_2 \) by \( N_1 \) two-dimensional array

This algorithm is described fully by Takahashi in “High-performance parallel FFT algorithms for the Hitachi SR8000.”[1]

In multicore implementation, step one is accomplished by computing \( N_2/(\text{number of cores}) \) FFTs of size \( N_2 \) on each core. Core 0 is used as a master core and is responsible for synchronizing all the cores, and the rest of the cores are used as slave cores. On each core, depending on the sizes of \( N_1 \) and \( N_2 \), the total number of FFTs on each core is divided into several smaller blocks in order to accommodate the size of the L2 SRAM per core. Each block of data is prefetched by DMA from external memory into L2 SRAM and the FFT results are written back to external memory by DDR. Two DMA channels are used by each core to transfer input and output samples between external memory (DDR3) and internal memory (L2 SRAM).

## Results

The results from running the FFT code on a TMS320C6678 evaluation board (TMDSEVM6678LE) are listed in Table 1 on the following page in both DSP cycles and in milliseconds. Ideally when the number of cores used for the calculation is doubled, the cycle count should be cut in half, but this is rarely achieved in real-world situations due to overhead from data movement, memory block sizing, and non-infinite bandwidths of data input mechanisms (here, external memory). In this example, when two cores are used instead of one the time to run the FFT is reduced on average by 49.3 percent (1.97×), nearly reaching the ideal halving of cycle count. When four cores are used instead of one the time to run the FFT is reduced on average by 72.5 percent (3.67×), and when eight cores are used the time is reduced on average by 81.6 percent (5.7×).
Table 1: Results of FFT on one, two, four and eight DSP cores in cycles and milliseconds

It can be seen that the time reduction improves as FFT size increases from 16K to 256K for both the two- and the four-core use cases, and even more dramatically in the eight-core use case. This is because for these smaller FFTs, as more cores are added, the penalty from parallelizing the code is small relative to the improvement from adding the extra cores. Past 256K size FFTs, the improvement is either flat, having reached the 2× or 4× improvement for the two- and four-core use cases, or decreases in the case of eight cores being used. This decrease in improvement is due to a memory boundary being reached as the 8 cores are consuming data faster than they can be supplied with data from external memory. The time to calculate a 1024K FFT, a million point FFT, is shown to be 6.4 ms when using all eight DSP cores at 1 GHz.

Conclusions

It is shown that a million point FFT can be executed by the TMS320C6678 device in as little as 6.4 ms when all eight cores are operating on the data in parallel, at 1 GHz. With these speeds, the DSP can be used for real-time operations in applications such as radar, electronic warfare, medical imaging, and more. Execution time could be improved even further by running the TMS320C6678 device at the maximum speed possible, 1.25 GHz, and using higher bandwidth DDR3, 1600 MTPS.
References

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