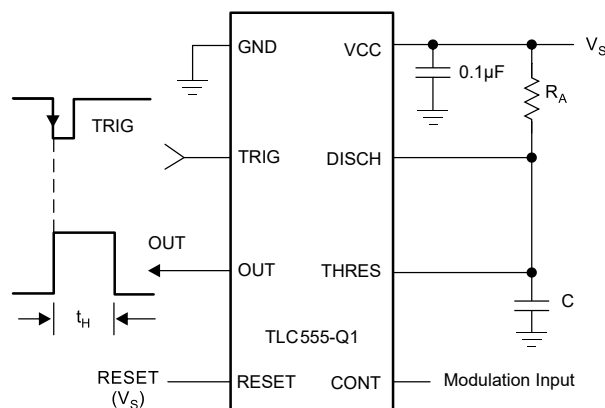# TLC555-Q1 Automotive CMOS Timer

1 Features

- AEC-Q100 qualified for automotive applications:
  - Temperature grade 1: –40°C to +125°C, T_A
- Functional Safety-Capable
  - Documentation available to aid functional safety system design
- Very-low power consumption
  - 1mW (typical) at V_{DD} = 5V
- Capable of operation in astable mode
- CMOS output capable of swinging rail to rail
- High-output-current capability
  - Sink 100mA (typical)
  - Source 10mA (typical)
- Output fully compatible with CMOS, TTL, and MOS
- Low supply current reduces spikes during output transitions
- Single-supply operation from 2V to 15V
- Temperature range: –40°C to +125°C
- Functionally interchangeable with the NE555; has same pinout

2 Applications

- Automotive lighting
- Traction Inverter
- Precision timing
- Pulse generation
- Sequential timing
- Time delay generation
- Pulse width modulation
- Pulse position modulation
- Linear ramp generators
- Telematics

3 Description

The TLC555-Q1 is a CMOS monolithic timing circuit. The timer is fully compatible with CMOS, TTL, and MOS logic and operates at frequencies up to 2MHz. As a result of the high input impedance, this device supports smaller timing capacitors than capacitors used by the NE555. Thus, more accurate time delays and oscillations are possible. Power consumption is low across the full power-supply voltage range.
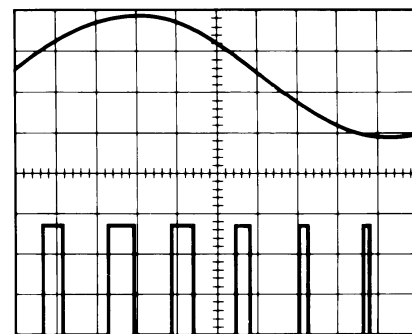
Like the NE555, the TLC555-Q1 has a trigger level equal to approximately one-third of the supply voltage, and a threshold level equal to approximately two-thirds of the supply voltage. These levels can be altered by using the control voltage pin (CONT). When the trigger input (TRIG) falls below the trigger level, the flip-flop is set, and the output goes high. If TRIG is greater than the trigger level and the threshold input (THRES) is greater than the threshold level, the flip-flop is reset and the output goes low. The reset input (RESET) can override all other inputs and is used to initiate a new timing cycle. If RESET is low, the flip-flop is reset and the output goes low. Whenever the output is low, a low-impedance path is provided between the discharge pin (DISCH) and GND. Tie all unused inputs to an appropriate logic level to prevent false triggering.

Package Information

PART NUMBER	PACKAGE[1]	PACKAGE SIZE[2]
TLC555-Q1	SOIC (8)	4.9mm × 6.0mm

(1) For more information, see Section 10.
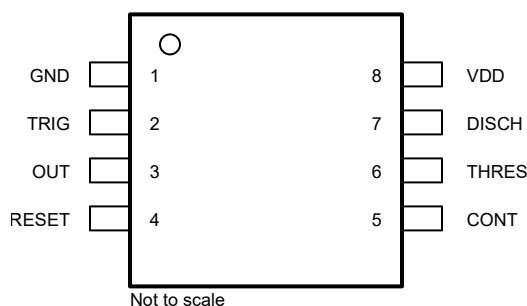(2) The package size (length × width) is a nominal value and includes pins, where applicable.

Pulse Width Modulator

**Pulse Width Modulator Waveform:
Top Waveform - Modulation
Bottom Waveform - Output Voltage**

Table of Contents

4 Pin Configuration and Functions

Figure 4-1. D Package, 8-Pin SOIC, (Top View)

Table 4-1. Pin Functions

PIN		TYPE	DESCRIPTION
NAME	NO.		
CONT	5	Input/Output	Controls comparator thresholds. Outputs 2/3V_{DD}, allows bypass capacitor connection.
DISCH	7	Output	Open collector output to discharge timing capacitor
GND	1	—	Ground
OUT	3	Output	High current timer output signal
RESET	4	Input	Active low reset input forces output and discharge low
THRES	6	Input	End of timing input. THRES > CONT sets output low and discharge low.
TRIG	2	Input	Start of timing input. TRIG < ½ CONT sets output high and discharge open.
VDD	8	—	Input supply voltage, 2V to 15V

5 Specifications

5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)[1]

			MIN	MAX	UNIT
V_{DD}	Supply voltage[2]			18	V
V_I	Input voltage, any input		−0.3	V_{DD}	V
	Sink current, discharge or output			150	mA
I_O	Source current, output			15	mA
	Continuous total power rating[3]	$T_A \leq 25°C$		900	mW
		$T_A = 125°C$		180	
	Continuous total power dissipation derating factor[3], $T_A \geq 25°C$			7.2	mW/°C
T_A	Operating free-air temperature		−40	125	°C
T_{stg}	Storage temperature		−65	150	°C

(1)   Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
(2)   All voltage values are with respect to network GND.
(3)   See *Thermal Information*.

5.2 ESD Ratings

				VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per AEC Q100-002[1]		±2000	V
		Charged-device model (CDM), per AEC Q100-011	All pins	±500	
			Corner pins (1, 4, 5, and 8)	±750	

(1)   AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

5.3 Recommended Operating Conditions

		MIN	MAX	UNIT
V_{DD}	Supply voltage	2	15	V
T_A	Operating free-air temperature	−40	125	°C

5.4 Thermal Information

	THERMAL METRIC[1]	TLC555-Q1 D (SOIC) 8 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	138.9	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	78.8	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	87.9	°C/W
ψ_{JT}	Junction-to-top characterization parameter	23.2	°C/W
ψ_{JB}	Junction-to-board characterization parameter	86.9	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1)   For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application note.

5.5 Electrical Characteristics: V_{DD} = 5V

V_{DD} = 5V, at specified free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS [1]		MIN	TYP	MAX	UNIT
V_{IT}	Threshold voltage	25°C		2.8	3.3	3.8	V
		Full range		2.7		3.9	
I_{IT}	Threshold current	25°C			10		pA
		Full range			5000		
$V_{I(TRIG)}$	Trigger voltage	25°C		1.36	1.66	1.96	V
		Full range		1.26		2.06	
$I_{I(TRIG)}$	Trigger current	25°C			10		pA
		Full range			5000		
$V_{I(RESET)}$	Reset voltage	25°C		0.4	1.1	1.5	V
		Full range		0.3		1.8	
$I_{I(RESET)}$	Reset current	25°C			10		pA
		Full range			5000		
	Control voltage (open-circuit) as a percentage of supply voltage	Full range			66.7%		
	Discharge-switch on-state voltage	I_{OL} = 10mA	25°C		0.06	0.5	V
			Full range			0.6	
	Discharge-switch off-state current	25°C			0.3		nA
		Full range			275		
V_{OH}	High-level output voltage	I_{OH} = −1mA	25°C	4.1	4.8		V
			Full range	4.1			
V_{OL}	Low-level output voltage	I_{OL} = 8mA	25°C		0.21	0.4	V
			Full range			0.6	
		I_{OL} = 5mA	25°C		0.13	0.3	
			Full range			0.45	
		I_{OL} = 3.2mA	25°C		0.08	0.3	
			Full range			0.4	
I_{DD}	Supply current[2]	25°C			180	350	µA
		Full range				700	

(1)   Full-range T_A is –40°C to 125°C.
(2)   These values apply for the expected operating configurations in which THRES is connected directly to DISCH or TRIG.
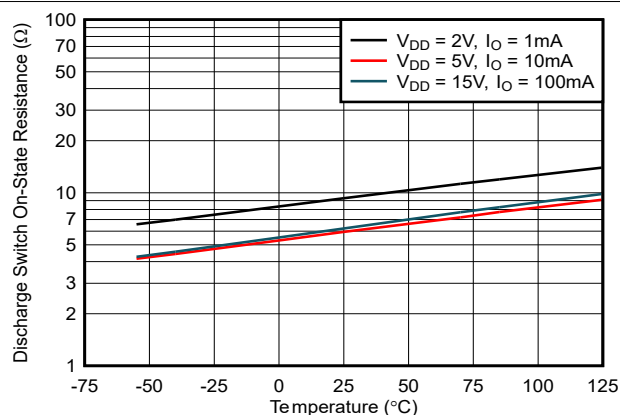
Product Folder Links: *TLC555-Q1*

5.6 Electrical Characteristics: V$_{DD}$ = 15V

V$_{DD}$ = 15V, at specified free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS [1]		MIN	TYP	MAX	UNIT
V$_{IT}$	Threshold voltage	25°C		9.45	10	10.55	V
		Full range		9.35		10.65	
I$_{IT}$	Threshold current	25°C			10		pA
		Full range			5000		
V$_{I(TRIG)}$	Trigger voltage	25°C		4.65	5	5.35	V
		Full range		4.55		5.45	
I$_{I(TRIG)}$	Trigger current	25°C			10		pA
		Full range			5000		
V$_{I(RESET)}$	Reset voltage	25°C		0.4	1.1	1.5	V
		Full range		0.3		1.8	
I$_{I(RESET)}$	Reset current	25°C			10		pA
		Full range			5000		
	Control voltage (open-circuit) as a percentage of supply voltage	Full range			66.7%		
	Discharge-switch on-state voltage	I$_{OL}$ = 100mA	25°C		0.77	1.7	V
			Full range			1.8	
	Discharge switch off-state current	25°C			0.75		nA
		Full range			280		
V$_{OH}$	High-level output voltage	I$_{OH}$ = −10mA	25°C	12.5	14.2		V
			Full range	12.5			
		I$_{OH}$ = −5mA	25°C	13.5	14.6		
			Full range	13.5			
		I$_{OH}$ = −1mA	25°C	14.2	14.9		
			Full range	14.2			
V$_{OL}$	Low-level output voltage	I$_{OL}$ = 100mA	25°C		1.28	3.2	V
			Full range			3.8	
		I$_{OL}$ = 50mA	25°C		0.63	1	
			Full range			1.5	
		I$_{OL}$ = 10mA	25°C		0.12	0.3	
			Full range			0.45	
I$_{DD}$	Supply current[2]	25°C			235	600	µA
		Full range				1000	

(1)   Full-range T$_A$ is –40°C to 125°C.
(2)   These values apply for the expected operating configurations in which THRES is connected directly to DISCH or TRIG.

5.7 Switching Characteristics

at V_{DD} = 5V, T_A = 25°C (unless otherwise noted); characteristic values are specified by design, characterization, or both
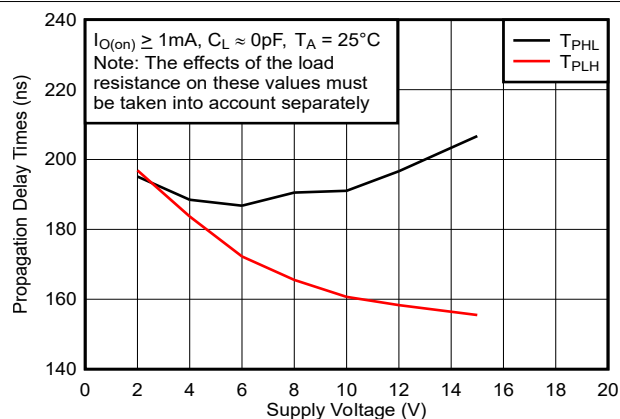
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Supply voltage sensitivity of timing interval	V_{DD} = 5V to 15V, C_T = 0.1µF R_A = R_B = 1kΩ to 100kΩ [1]		0.1	0.5	%/V
t_r	Output pulse rise time	R_L = 10MΩ, C_L = 10pF		20	75	ns
t_f	Output pulse fall time	R_L = 10MΩ, C_L = 10pF		15	60	ns
f_{max}	Maximum frequency in astable mode	R_A = 470Ω, C_T = 200pF R_B = 200Ω [1]	1.2	2.1		MHz

(1) R_A, R_B, and C_T are as defined in Typical Characteristics.

5.8 Typical Characteristics

Figure 5-1. Discharge Switch On-State Resistance vs Free-Air Temperature

Figure 5-2. Propagation Delay Times to Discharge Output From Trigger and Threshold Shorted Together vs Supply Voltage
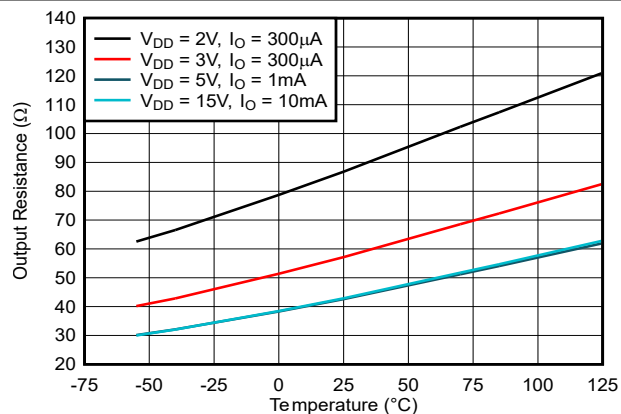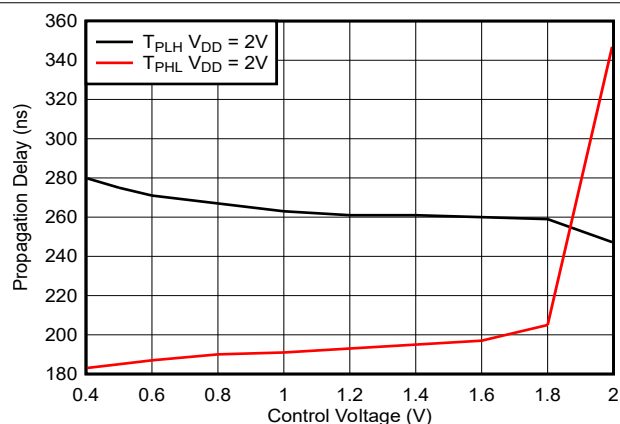

Figure 5-3. Supply Current vs Supply Voltage

Figure 5-4. Control Impedance vs Temperature
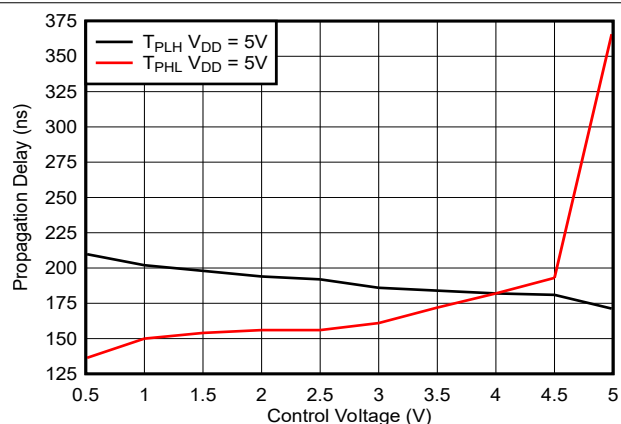
Product Folder Links: *TLC555-Q1*

Figure 5-5. Output Low Resistance vs Temperature

Figure 5-6. Output High Resistance vs Temperature
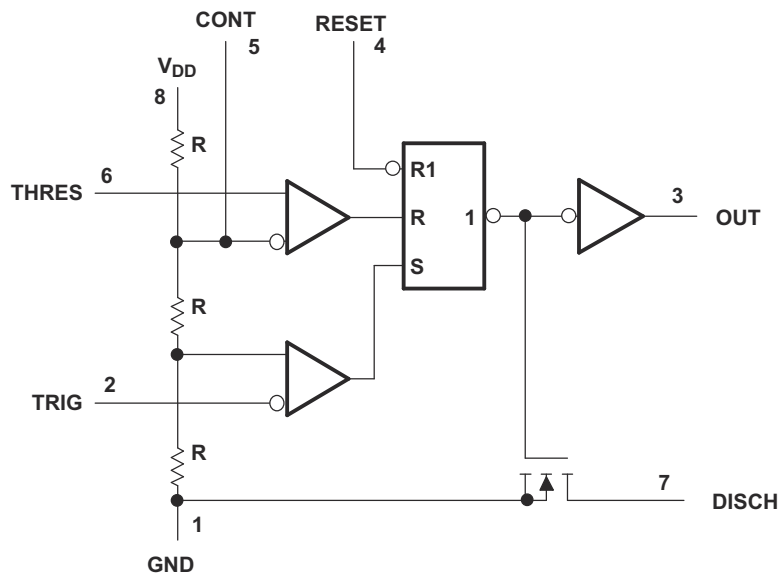

Figure 5-7. Propagation Delay vs Control Voltage

Figure 5-8. Propagation Delay vs Control Voltage

Product Folder Links: *TLC555-Q1*

6 Detailed Description

6.1 Overview

The TLC555-Q1 timer is used for general-purpose timing applications from 476ns to hours or from < 1MHz to 2.1MHz. All inputs are level sensitive, and not edge-triggered.
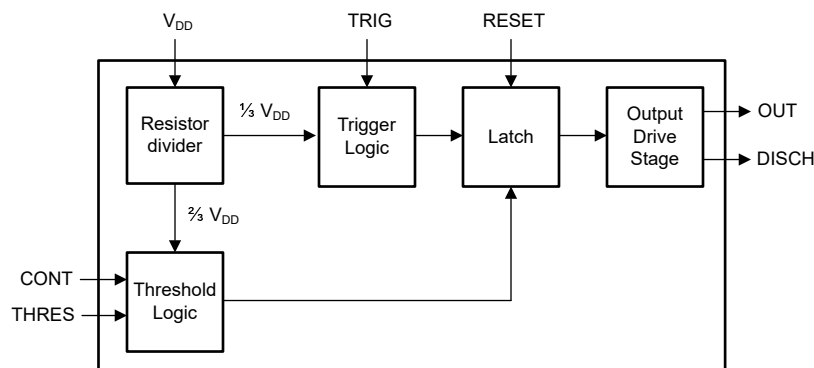

Copyright © 2017, Texas Instruments Incorporated

Note: RESET can override TRIG, which can override THRES.

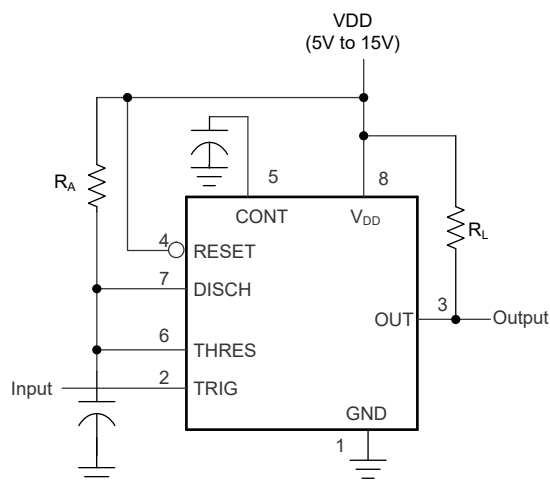**Figure 6-1. Simplified Schematic**

6.2 Functional Block Diagram

6.3 Feature Description

6.3.1 Monostable Operation

For monostable operation, Figure 6-2 shows how any of these timers can be connected. If the output is low, application of a negative-going pulse to the trigger (TRIG) sets the flip-flop ($\overline{Q}$ goes low), drives the output high, and turns off Q1. Capacitor C charges through R_A until the voltage across the capacitor reaches the threshold voltage of the threshold (THRES) input. If TRIG returns to a high level, the output of the threshold comparator resets the flip-flop ($\overline{Q}$ goes high), drives the output low, and discharges C through Q1.
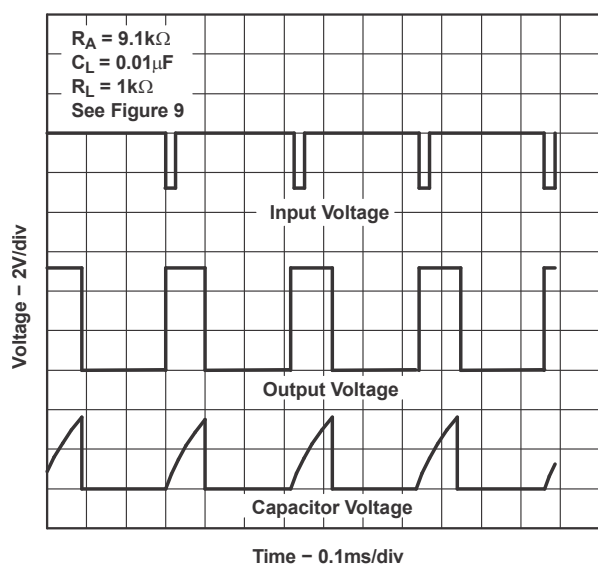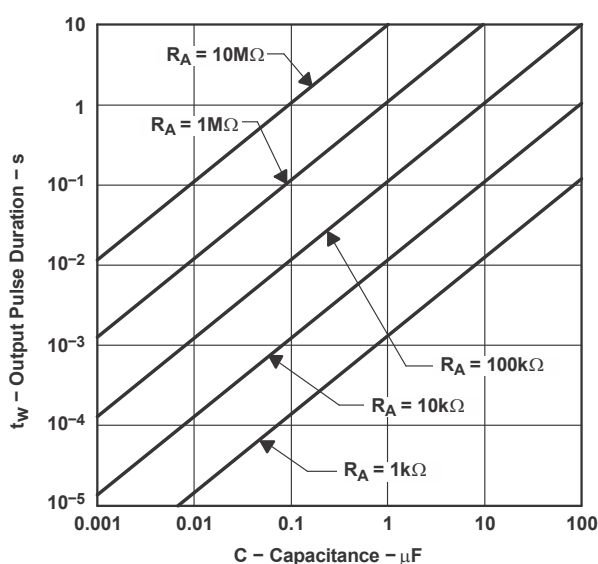
VDD
(5V to 15V)

Figure 6-2. Circuit for Monostable Operation

Monostable operation is initiated when TRIG voltage falls below the trigger threshold. When initiated, the sequence ends only if TRIG is high for at least 10µs before the end of the timing interval. When the trigger is grounded, the comparator storage time can be as long as 10µs, which limits the minimum monostable pulse duration to 10µs. Because of the threshold level and saturation voltage of Q1, the output pulse duration is approximately t_w = 1.1R_AC. Figure 6-3 is a plot of the time constant for various values of R_A and C. The threshold levels and charge rates are directly proportional to the supply voltage (V_{DD}). As a result, the timing interval is independent of the supply voltage if the supply voltage is constant during the time interval.

Applying a negative-going trigger pulse simultaneously to RESET and TRIG during the timing interval discharges C and re-initiates the cycle, commencing on the positive edge of the reset pulse. The output is held low as long as the reset pulse is low. To prevent false triggering, connect RESET to V_{DD} when RESET is not being used. If the RESET function is required and the pin is driven by external logic or a microcontroller, use a pullup resistor to V_{DD} (such as 10kΩ) to prevent the RESET pin from floating. If the RESET function is not required, short the RESET pin directly to the V_{DD} pin.

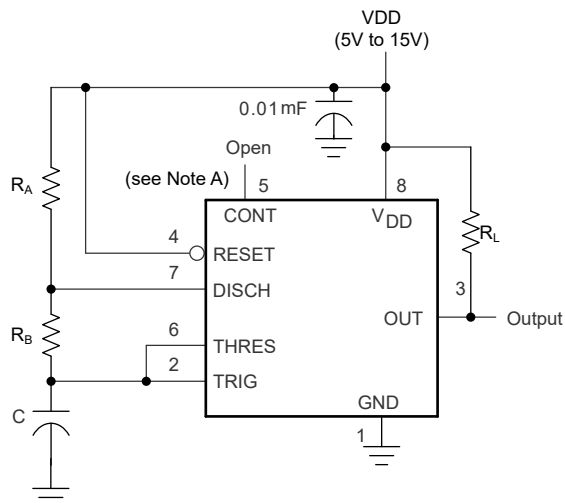**Figure 6-3. Typical Monostable Waveforms**

Figure 6-4. Output Pulse Duration vs Capacitance

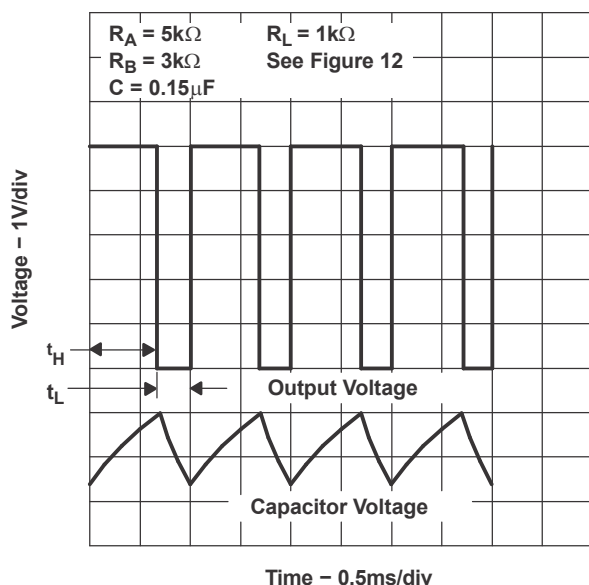Product Folder Links: *TLC555-Q1*

6.3.2 Astable Operation

Figure 6-5 shows that adding a second resistor (R_B) to the circuit and connecting the trigger input to the threshold input causes the timer to self-trigger and run as a multivibrator. The C capacitor charges through R_A and R_B and then only discharges through R_B. As a result, the values of R_A and R_B control the duty cycle.

This astable connection results in the C capacitor charging and discharging between the threshold-voltage level ($\approx 0.67 \times V_{DD}$) and the trigger-voltage level ($\approx 0.33 \times V_{DD}$). As in the monostable circuit, charge and discharge times (and as a result, the frequency and duty cycle) are independent of the supply voltage.
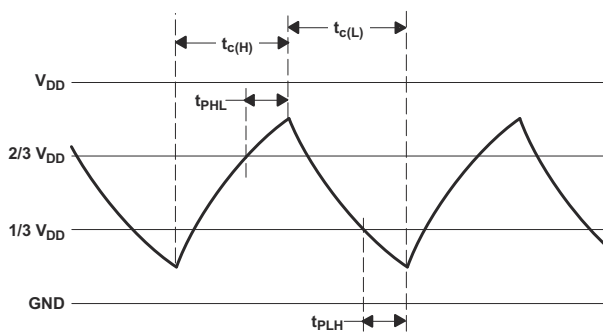

A.   Decoupling CONT voltage to ground with a capacitor can improve operation. This must be evaluated for individual applications.

Figure 6-5. Circuit for Astable Operation

Figure 6-6. Typical Astable Waveforms

Figure 6-7. Trigger and Threshold Voltage Waveform

Product Folder Links: *TLC555-Q1*

Figure 6-7 shows typical waveforms generated during astable operation. Calculate the output high-level duration (t_H) and low-level duration t_L for frequencies less than or equal to 100kHz as follows:

$$t_H = 0.693 (R_A + R_B) C \tag{1}$$

$$t_L = 0.693 (R_B) C \tag{2}$$

Other useful relationships are shown as follows:

$$\text{period} = t_H + t_L = 0.693 (R_A + 2R_B) C \tag{3}$$

$$\text{frequency} \approx \frac{1.44}{(R_A + 2R_B) C} \tag{4}$$

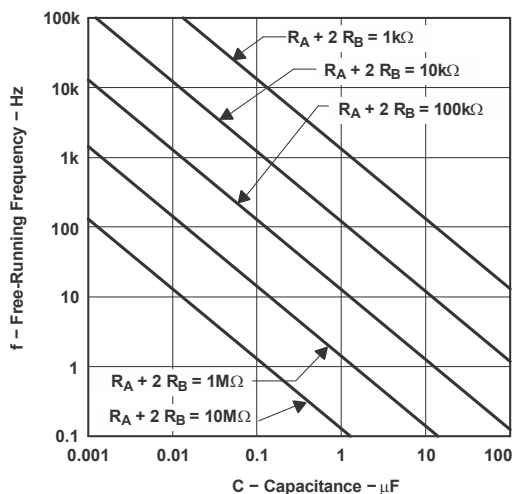$$\text{Output driver duty cycle} = \frac{t_L}{t_H + t_L} = \frac{R_B}{R_A + 2R_B} \tag{5}$$

$$\text{Output waveform duty cycle} = \frac{t_H}{t_H + t_L} = 1 - \frac{R_B}{R_A + 2R_B} \tag{6}$$

$$\text{Low-to-high ratio} = \frac{t_L}{t_H} = \frac{R_B}{R_A + R_B} \tag{7}$$

Equation 1 to Equation 7 do not account for any propagation delay times from the TRIG and THRES inputs to DISCH output. These delay times add directly to the period and overcharge the capacitor, which creates differences between calculated and actual values that increase with frequency. In addition, the internal on-state resistance r_{on} during discharge adds to R_B to provide another source of timing error in the calculation when R_B is very low. The following equations provide better agreement with measured values. The formulas in Equation 8 represent the actual low and high times when used at higher frequencies (beyond 100 kHz) because propagation delay and discharge on resistance is added to the formulas. The value of C_T includes both the nominal or deliberate timing capacitance, as well as parasitic capacitance on the PCB. Decoupling capacitance on CONT also affects the duty cycle, with an error contribution that depends on the capacitor leakage resistance. For additional discussion, see the *Design low-duty-cycle timer circuits* article.

$$t_{c(H)} = C_T (R_A + R_B) \ln \left[3 - \exp \left(\frac{-t_{PLH}}{C_T (R_B + r_{on})} \right) \right] + t_{PHL}$$

$$t_{c(L)} = C_T (R_B + r_{on}) \ln \left[3 - \exp \left(\frac{-t_{PHL}}{C_T (R_A + R_B)} \right) \right] + t_{PLH} \tag{8}$$
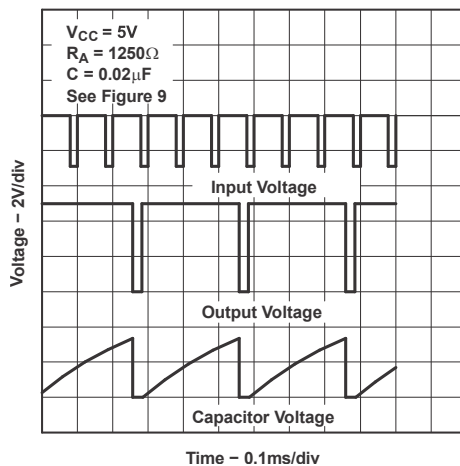
These equations and those given earlier are similar in that a time constant is multiplied by the logarithm of a number or function. The limit values of the logarithmic terms must be between ln(2) at low frequencies, and ln(3) at extremely high frequencies. For a duty cycle close to 50%, an appropriate constant for the logarithmic terms can be substituted with good results. Output waveform duty cycles less than 50% require that $t_{c(H)} / t_{c(L)} < 1$ and possibly that $R_A \leq r_{on}$. These conditions can be difficult to obtain. Figure 6-8 shows the nominal free-running frequency associated with various combinations of C_T and $R_A + 2 \times R_B$.

Figure 6-8. Free-Running Frequency

6.3.3 Frequency Divider

By adjusting the length of the timing cycle, the basic circuit of the TLC555-Q1 can operate as a frequency divider. Figure 6-9 shows a divide-by-three circuit that reinforces that re-triggering cannot occur during the timing cycle.

Figure 6-9. Divide-by-Three Circuit Waveforms

Product Folder Links: *TLC555-Q1*

6.4 Device Functional Modes

Table 6-1 lists the device functional modes. For a valid reset voltage condition, use an external pullup resistor to V_{DD} (if using the RESET functionality), or short the RESET pin directly to V_{DD} (if the RESET functionality is not used).

Table 6-1. Function Table

RESET	TRIGGER VOLTAGE[1]	THRESHOLD VOLTAGE[1]	OUTPUT	DISCHARGE SWITCH
Low	Irrelevant	Irrelevant	Low	On
High	< 1/3V_{DD}	Irrelevant	High	Off
High	> 1/3V_{DD}	> 2/3V_{DD}	Low	On
High	> 1/3V_{DD}	< 2/3V_{DD}	As previously established	

(1)   Voltage levels shown are nominal.

7 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.
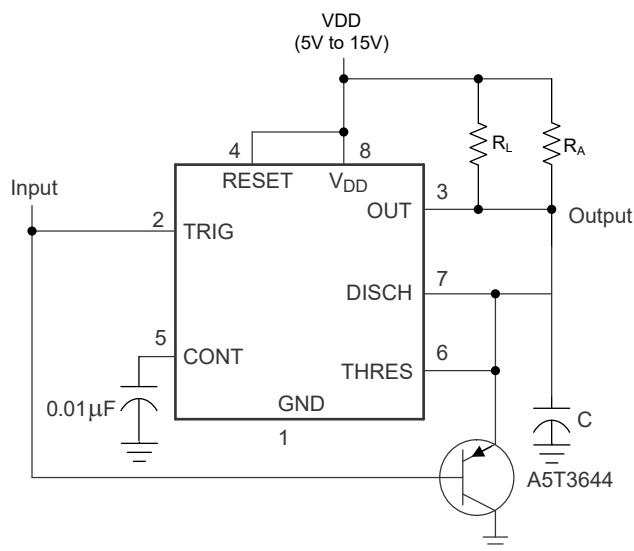

7.1 Application Information

The TLC555-Q1 timer device uses resistor and capacitor charging delay to provide a programmable time delay or operating frequency. The following section presents a simplified discussion of the design process.

7.2 Typical Applications

7.2.1 Missing-Pulse Detector

The circuit shown in Figure 7-1 can detect a missing pulse or abnormally long spacing between consecutive pulses in a train of pulses. The timing interval of the mono-stable circuit is re-triggered continuously by the input pulse train if the pulse spacing is less than the timing interval. A longer pulse spacing, missing pulse, or terminated pulse train permits the timing interval to be completed, which generates an output pulse as shown in Figure 7-2.
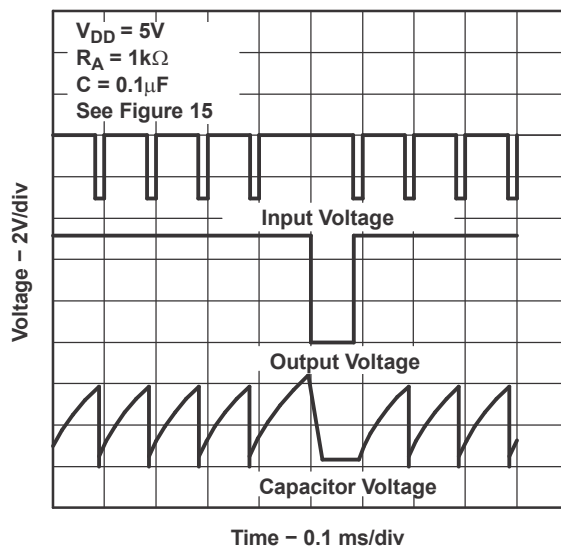

Figure 7-1. Circuit for Missing-Pulse Detector

7.2.1.1 Design Requirements

Input fault (missing pulses) must be input high. Input stuck low is not detected because timing capacitor (C) remains discharged.

7.2.1.2 Detailed Design Procedure

Select R_A and C so that $R_A \times C$ > [maximum normal input high time]. R_L improves V_{OH}, but is not required for TTL compatibility.
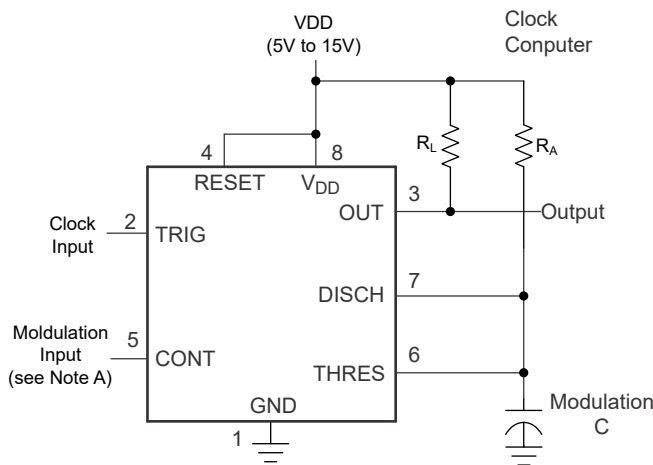
7.2.1.3 Application Curve

Figure 7-2. Completed Timing Waveforms for Missing-Pulse Detector

7.2.2 Pulse-Width Modulation

The operation of the timer can be modified by modulating the internal threshold and trigger voltages by applying an external voltage (or current) to CONT. Figure 7-3 shows a circuit for pulse-width modulation. A continuous input pulse train triggers the mono-stable circuit, and a control signal modulates the threshold voltage. Figure 7-4 shows the resulting output pulse-width modulation. While a sine-wave modulation signal is shown, any wave shape can be used.

A. The modulating signal can be direct or capacitively coupled to CONT. For direct coupling, the effects of modulation source voltage and impedance on the bias of the timer must be considered.

Figure 7-3. Circuit for Pulse-Width Modulation

7.2.2.1 Design Requirements

Clock input must have V_{OL} and V_{OH} levels that are less than and greater than 1/3 VDD. Modulation input can vary from ground to VDD. The application must be tolerant of a nonlinear transfer function; the relationship between modulation input and pulse width is not linear because the capacitor charge is based RC on an negative exponential curve.

7.2.2.2 Detailed Design Procedure

Select R_A and C so that $R_A \times C = 1/4$ [clock input period]. R_L improves V_{OH}, but is not required for TTL compatibility.
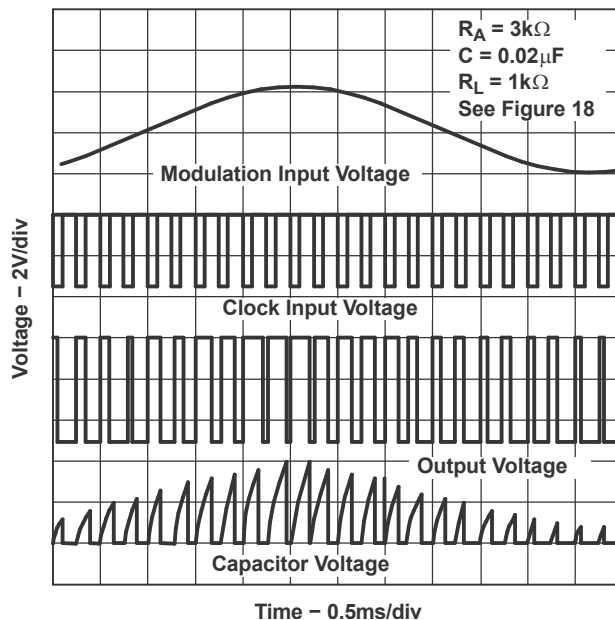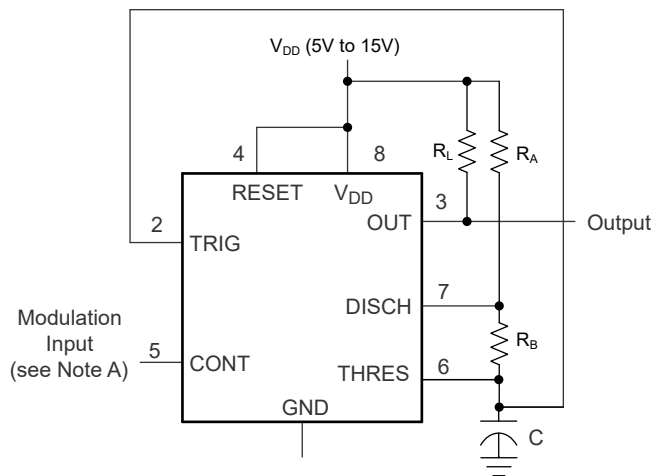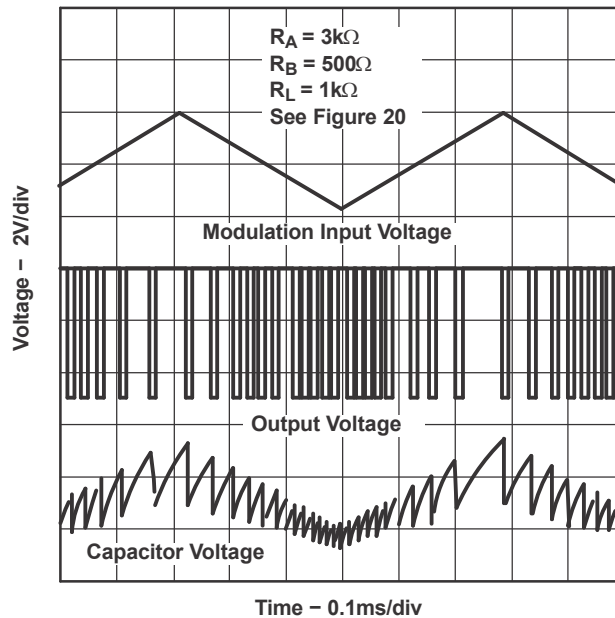
7.2.2.3 Application Curve

Figure 7-4. Pulse-Width-Modulation Waveforms

7.2.3 Pulse-Position Modulation

As shown in Figure 7-5, any of these timers can be used as a pulse-position modulator. This application modulates the threshold voltage and the time delay of a free-running oscillator. Figure 7-6 shows a triangular-wave modulation signal for this type of circuit; however, any wave shape can be used.

A. The modulating signal can be direct or capacitively coupled to CONT. For direct coupling, the effects of modulation source voltage and impedance on the bias of the timer must be considered.

Figure 7-5. Circuit for Pulse-Position Modulation

7.2.3.1 Design Requirements

Both DC and AC coupled modulation inputs change the upper and lower voltage thresholds for the timing capacitor. Both frequency and duty cycle vary with the modulation voltage.

7.2.3.2 Detailed Design Procedure

The nominal output frequency and duty cycle can be determined using formulas in *Section 6.3.2*. R_L improves V_{OH}, but is not required for TTL compatibility.
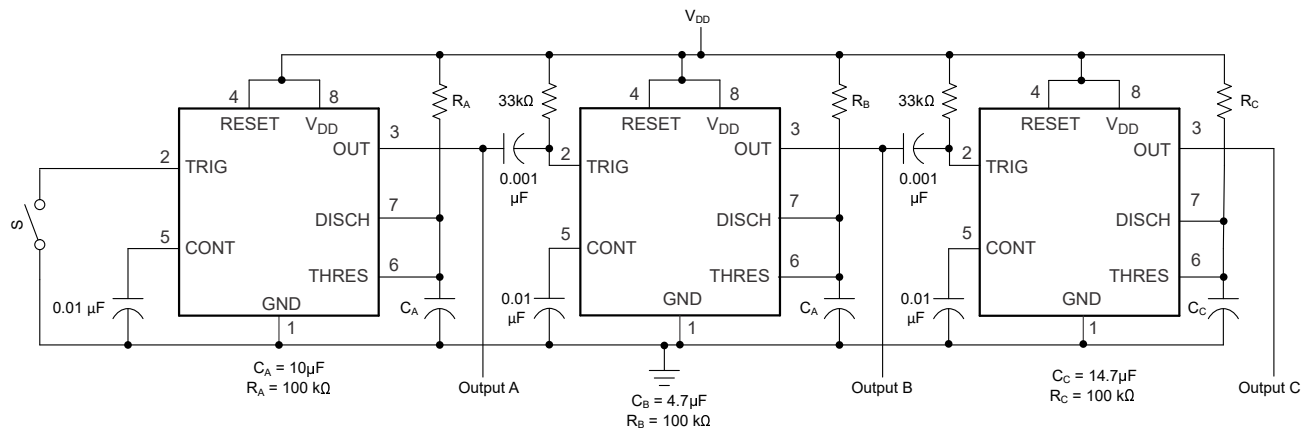
7.2.3.3 Application Curve

Figure 7-6. Pulse-Position-Modulation Waveforms

7.2.4 Sequential Timer

Many applications (such as computers) require signals for initializing conditions during start-up. Other applications (such as test equipment) require activation of test signals in sequence. These timing circuits can connect to provide sequential control. The timers can be used in various combinations of a-stable or mono-stable circuit connections with or without modulation for extremely flexible waveform control. Figure 7-7 shows a sequencer circuit with possible applications in many systems; Figure 7-8 shows the output waveforms.

NOTE A: S closes momentarily at t=0.
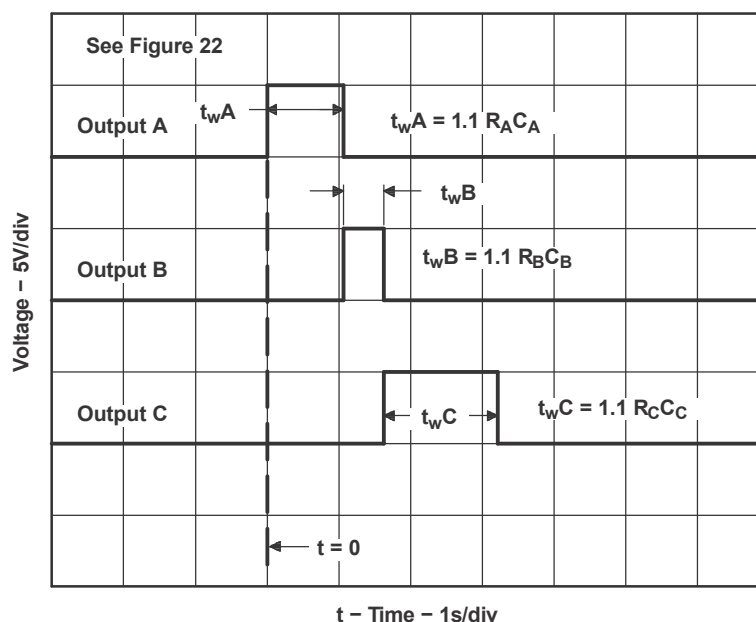
Figure 7-7. Sequential Timer Circuit

7.2.4.1 Design Requirements

The sequential timer application chains together multiple mono-stable timers. The joining components are 33kΩ resistors and 0.001µF capacitors. The output high to low edge passes a 10µs start pulse to the next mono-stable.

7.2.4.2 Detailed Design Procedure

The timing resistors and capacitors can be selected using this formula: $t_w = 1.1 \times R \times C$.

7.2.4.3 Application Curve

Figure 7-8. Sequential Timer Waveforms

7.3 Power Supply Recommendations

The TLC555-Q1 requires a voltage supply within 4.5V to 15V. Adequate power supply bypassing is required to protect associated circuitry. The minimum recommended value is 0.1µF in parallel with a 1µF electrolytic. Place the bypass capacitors as close as possible to the TLC555-Q1 and minimize the trace length.

7.4 Layout

7.4.1 Layout Guidelines

Standard PCB rules apply to routing the TLC555-Q1. The 0.1µF in parallel with a 1µF electrolytic capacitor must be as close as possible to the TLC555-Q1. The capacitor used for the time delay must be placed as close to the discharge pin. A ground plane on the bottom layer can provide better noise immunity and signal integrity.

7.4.2 Layout Example

Figure 7-9 shows the basic layout for various applications.
- C1 – based on time delay calculations
- C2 – 0.01µF bypass capacitor for control voltage pin
- C3 – 0.1µF bypass ceramic capacitor
- C4 – 1µF electrolytic bypass capacitor
- R1 – based on time delay calculations

Figure 7-9. Recommended Layout

8 Device and Documentation Support

8.1 Documentation Support

8.1.1 Related Documentation

For related documentation see the following:
- Texas Instruments, *TLC555-Q1 Used as a Positive and Negative Charge Pump* application note
- Texas Instruments, *EMC Compatible Automotive LED Rear Lamp With Sequential-Turn Animation Reference Design*

8.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

8.3 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

8.4 Trademarks

TI E2E™ is a trademark of Texas Instruments.
All trademarks are the property of their respective owners.

8.5 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

8.6 Glossary

TI Glossary   This glossary lists and explains terms, acronyms, and definitions.

9 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

Product Folder Links: *TLC555-Q1*

PACKAGE OPTION ADDENDUM

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TLC555QDRQ1	Active	Production	SOIC (D) | 8	2500 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	TL555Q
TLC555QDRQ1.A	Active	Production	SOIC (D) | 8	2500 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	TL555Q

(1) Status: For more details on status, see our product life cycle.

(2) Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF TLC555-Q1 :

• Catalog : TLC555

● Military : TLC555M

NOTE: Qualified Version Definitions:

  ● Catalog - TI's standard catalog product

  ● Military - QML certified for Military and Defense Applications

![Texas Instruments logo]

PACKAGE MATERIALS INFORMATION

TAPE AND REEL INFORMATION

REEL DIMENSIONS

Reel Diameter

Reel Width (W1)

TAPE DIMENSIONS

K0 | P1

B0 | W

Cavity | A0

A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

Sprocket Holes

| Q1 | Q2 |
| Q3 | Q4 |

| Q1 | Q2 |
| Q3 | Q4 |

User Direction of Feed

Pocket Quadrants

*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TLC555QDRQ1	SOIC	D	8	2500	330.0	12.5	6.4	5.2	2.1	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS

*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TLC555QDRQ1	SOIC	D	8	2500	353.0	353.0	32.0

PACKAGE MATERIALS INFORMATION

TUBE

T - Tube height

L - Tube length

W - Tube width

B - Alignment groove width

*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
TLC555QDRQ1	D	SOIC	8	2500	506.6	8	3940	4.32
TLC555QDRQ1.A	D	SOIC	8	2500	506.6	8	3940	4.32

.228-.244 TYP
[5.80-6.19]

PIN 1 ID AREA

A

.189-.197
[4.81-5.00]
NOTE 3

1

4

B

.150-.157
[3.81-3.98]
NOTE 4

6X .050
[1.27]

8

2X

.150
[3.81]

5

8X .012-.020
[0.31-0.51]

⊕ | .010 [0.25]Ⓜ | C | A | B

C

SEATING PLANE

⌒ | .004 [0.1] | C

4X (0°-15°)

.069 MAX
[1.75]

SEE DETAIL A

4X (0°-15°)

.005-.010 TYP
[0.13-0.25]

.010
[0.25]

0°- 8°

.016-.050
[0.41-1.27]

(.041)
[1.04]

.004-.010
[0.11-0.25]

DETAIL A
TYPICAL

4214825/C   02/2019

NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches.
   Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
   exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

8X (.061)
[1.55]

SYMM
℄

SEE
DETAILS

1

8

8X (.024)
[0.6]

SYMM
℄

(R.002) TYP
[0.05]

4

5

6X (.050)
[1.27]

(.213)
[5.4]

LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:8X

METAL

SOLDER MASK
OPENING

SOLDER MASK
OPENING

METAL UNDER
SOLDER MASK

EXPOSED
METAL

EXPOSED
METAL

.0028 MAX
[0.07]
ALL AROUND

.0028 MIN
[0.07]
ALL AROUND

NON SOLDER MASK
DEFINED

SOLDER MASK
DEFINED

SOLDER MASK DETAILS

4214825/C   02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

8X (.061)
[1.55]

1

8X (.024)
[0.6]

SYMM
℄

SYMM
℄

8

(R.002) TYP
[0.05]

6X (.050)
[1.27]

4

5

(.213)
[5.4]

SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE:8X

4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you fully indemnify TI and its representatives against any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale, TI's General Quality Guidelines, or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products. Unless TI explicitly designates a product as custom or customer-specified, TI products are standard, catalog, general purpose devices.

TI objects to and rejects any additional or different terms you may propose.